

Semiparametric robust mean estimations based on the orderliness of quantile averages

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As one of the most fundamental problems in statistics, robust location estimation has many prominent solutions, such as the trimmed mean, Winsorized mean, Hodges–Lehmann estimator, Huber M -estimator, and median of means. Recent research findings suggest that their biases concerning the mean can be quite different in asymmetric distributions, but the underlying mechanisms remain largely unclear. In this article, similar to the mean-median-mode inequality, it is proven that in the context of nearly all common unimodal distributions, there exists an orderliness of symmetric quantile averages with different breakdown points. Further deductions explain why the Winsorized mean and median of means generally have smaller biases compared to the trimmed mean. Building on the U -orderliness, the superiority of the median Hodges–Lehmann mean is discussed.

semiparametric | mean-median-mode inequality | asymptotic | unimodal
| Hodges–Lehmann estimator

In 1823, Gauss (1) proved that for any unimodal distribution with a finite second moment, $|m - \mu| \leq \sqrt{\frac{3}{4}}\omega$, where μ is the population mean, m is the population median, and ω is the root mean square deviation from the mode, M . This pioneering work revealed that despite potential bias with respect to the mean in robust estimates, the deviation remains bounded in unit of a scale parameter under certain assumptions. Bernard, Kazzi, and Vanduffel (2020) (2) further derived asymptotic bias bounds of any quantile for unimodal distributions by reducing this optimization problem to a parametric one, which can be solved analytically. They showed that the population median, m , has the smallest maximum distance to the population mean, μ , among all symmetric quantile averages (SQA_ϵ). Daniell, in 1920, (3) analyzed a class of estimators, linear combinations of order statistics, and identified that ϵ -symmetric trimmed mean (STM_ϵ) belongs to this class. Another popular choice, the ϵ -symmetric Winsorized mean (SWM_ϵ), named after Winsor and introduced by Tukey (4) and Dixon (5) in 1960, is also an L -estimator. Bieniek (2016) derived exact bias upper bounds of the Winsorized mean based on Danielak and Rychlik's work (2003) on the trimmed mean for any distribution with a finite second moment and confirmed that the former is smaller than the latter (6, 7). In 1963, Hodges and Lehmann (8) proposed a class of nonparametric location estimators based on rank tests and, from the Wilcoxon signed-rank statistic (9), deduced the median of pairwise means as a robust location estimator for a symmetric population. Both L -statistics and R -statistics achieve robustness essentially by removing a certain proportion of extreme values. In 1964, Huber (10) generalized maximum likelihood estimation to the minimization of the sum of a specific loss function, which measures the residuals between the data points and the model's parameters. Some L -statistics are also M -statistics, e.g., the sample mean is an M -estimator with a squared error loss function, while the sample median is an M -estimator with an absolute error loss function (10). The

Huber M -estimator is obtained by applying the Huber loss function that combines elements of both squared error and absolute error to achieve robustness against gross errors and high efficiency for contaminated Gaussian distributions (10). Sun, Zhou, and Fan (2020) examined the concentration bounds of Huber M -estimator (11). Mathieu (2022) (12) further derived the concentration bounds of M -statistics and demonstrated that, by selecting the tuning parameter which depends on the variance, Huber M -estimator can also be a sub-Gaussian estimator. The concept of median of means ($MoM_{k,b} = \frac{n}{k}$, k is the number of size in each block, b is the number of blocks) was implicitly introduced several times in Nemirovsky and Yudin (1983) (13), Jerrum, Valiant, and Vazirani (1986), (14) and Alon, Matias and Szegedy (1996) (15)'s works. Given its good performance even for distributions with infinite second moments, MoM has received increasing attention over the past decade (16–23). Devroye, Lerasle, Lugosi, and Oliveira (2016) showed that MoM nears the optimum of sub-Gaussian mean estimation with regards to concentration bounds when the distribution has a heavy tail (21). For a comparison of concentration bounds of trimmed mean, Huber M -estimator, median of means and other relevant estimators, readers are directed to Gobet, Lerasle, and Métivier's paper (2022) (24). Laforgue, Clemencon, and Bertail (2019) proposed the median of randomized means ($MoRM_{k,b}$) (23), wherein, rather than partitioning, an arbitrary number, b , of blocks are built independently from the sample, and showed that MoRM has better non-asymptotic sub-Gaussian property compared to MoM. In fact, asymptotically, the Hodges–Lehmann (H-L) estimator is equivalent to $MoM_{k=2,b=\frac{n}{k}}$ and $MoRM_{k=2,b}$, and they can be seen as the pairwise mean distribution is approximated by the sampling without replacement and bootstrap, respectively. For the asymptotic validity, readers are referred to the foundational works of Efron (1979) (25), Bickel and Freedman (1981, 1984) (26, 27), and Helmers, Janssen, and Veraverbeke (1990)

Significance Statement

In 1964, van Zwet introduced the convex transformation order for comparing the skewness of two distributions. This paradigm shift played a fundamental role in defining robust measures of distributions, from spread to kurtosis. Here, rather than the stochastic ordering between two distributions, the orderliness of quantile averages within a distribution is investigated. By classifying distributions through the signs of derivatives, a series of sophisticated robust mean estimators are deduced. Nearly all common nonparametric robust location estimators are found to be special cases thereof.

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72 (28).

Here, the ϵ, b -stratified mean is defined as

$$SM_{\epsilon, b, n} := \frac{b}{n} \left(\sum_{j=1}^{\lfloor \frac{b-1}{2b\epsilon} \rfloor} \sum_{i_j = \frac{(2bj-b-1)n\epsilon}{b-1}}^{\frac{(2bj-b+1)n\epsilon}{b-1}} X_{i_j} \right),$$

73 where $X_1 \leq \dots \leq X_n$ denote the order statistics of a sample
 74 of n independent and identically distributed random variables
 75 X_1, \dots, X_n . $b \in \mathbb{N}$, $b \geq 3$. The definition was further refined to
 76 guarantee the continuity of the breakdown point by incorporating
 77 an additional block in the center when $\lfloor \frac{b-1}{2b\epsilon} \rfloor \bmod 2 = 0$,
 78 or by adjusting the central block when $\lfloor \frac{b-1}{2b\epsilon} \rfloor \bmod 2 = 1$ (SI
 79 Text). If the subscript n is omitted, only the asymptotic
 80 behavior is considered. If b is omitted, $b = 3$ is assumed.
 81 $SM_{\epsilon, b=3}$ is equal to STM_{ϵ} , when $\epsilon > \frac{1}{6}$. The basic idea of
 82 the stratified mean, when $\frac{b-1}{2\epsilon} \in \mathbb{N}$, $b \bmod 2 = 1$ is to dis-
 83 tribute the data into $\frac{b-1}{2\epsilon}$ equal-sized non-overlapping blocks
 84 according to their order, then further sequentially group these
 85 blocks into b equal-sized strata and compute the mean of the
 86 middle stratum, which is the median of means of each stratum.
 87 In situations where $i \bmod 1 \neq 0$, a potential solution is to
 88 generate multiple smaller samples that satisfy the equality by
 89 sampling without replacement, and subsequently calculate the
 90 mean of all estimations, the details of determining the sample
 91 size and sampling times are included in the SI Text. Although
 92 the principle is similar to that of the median of means, with-
 93 out the random shift, the result is different from $MoM_{k=\frac{n}{b}, b}$.
 94 Additionally, the stratified mean differs from the mean of the
 95 sample obtained through stratified sampling methods, intro-
 96 duced by Neymean (1934) (29) or ranked set sampling (30),
 97 introduced by McIntyre in 1952, as these sampling methods
 98 are designed to obtain more representative samples or improve
 99 the efficiency of sample estimates, but the sample mean based
 100 on them are not robust. When $b \bmod 2 = 1$, the stratified
 101 mean can be regarded as replacing the other equal-sized strata
 102 with the middle stratum, which, in principle, is analogous to
 103 the Winsorized mean that replaces extreme values with less
 104 extreme percentiles. Furthermore, while the bounds confirm
 105 that the Winsorized mean and median of means outperform
 106 the trimmed mean (6, 7, 21, 24) in worst-case performance,
 107 the complexity of bound analysis makes it difficult to achieve a
 108 complete and intuitive understanding of these results. Also, a
 109 clear explanation for the average performance of them remains
 110 elusive. The aim of this paper is to define a series of semi-
 111 parametric models using the signs of derivatives, reveal their
 112 elegant interrelations and connections to parametric models,
 113 and show that by exploiting these models, a set of sophisti-
 114 cated robust mean estimators can be deduced, which have
 115 strong robustness to departures from assumptions.

116 Quantile average and weighted average

The symmetric trimmed mean, symmetric Winsorized mean,
 and stratified mean are all L -statistics. More specifically, they
 are symmetric weighted averages, which are defined as

$$SWA_{\epsilon, n} := \frac{\sum_{i=1}^{\lfloor \frac{n}{2} \rfloor} \frac{X_i + X_{n-i+1}}{2} w_i}{\sum_{i=1}^{\lfloor \frac{n}{2} \rfloor} w_i},$$

117 where w_i s are the weights applied to the symmetric quantile
 118 averages according to the definition of the corresponding L -
 119 statistic. For example, for the ϵ -symmetric trimmed mean,

$w_i = \begin{cases} 0, & i < n\epsilon \\ 1, & i \geq n\epsilon \end{cases}$, provided that $n\epsilon \in \mathbb{N}$. The mean and
 median are indeed two special cases of the symmetric trimmed
 mean.

To extend the symmetric quantile average to the asymmet-
 ric case, there are two possible definitions for the ϵ, γ -quantile
 average (QA(ϵ, γ, n)), i.e.,

$$\frac{1}{2}(\hat{Q}_n(\gamma\epsilon) + \hat{Q}_n(1 - \epsilon)), \quad [1]$$

and

$$\frac{1}{2}(\hat{Q}_n(\epsilon) + \hat{Q}_n(1 - \gamma\epsilon)), \quad [2]$$

where $\gamma \geq 0$ and $0 \leq \epsilon \leq \frac{1}{1+\gamma}$, $\hat{Q}_n(p)$ is the empirical quantile
 function. For trimming from both sides, [1] and [2] are equiva-
 lent. [1] is assumed in this article unless otherwise specified,
 since many common asymmetric distributions are right skewed,
 and [1] allows trimming only from the right side by setting
 $\gamma = 0$.

Analogously, the weighted average can be defined as

$$WA_{\epsilon, \gamma} := \frac{\int_{\epsilon_0=0}^{\frac{1}{1+\gamma}} QA(\epsilon_0, \gamma) w_{\epsilon_0}}{\int_{\epsilon_0=0}^{\frac{1}{1+\gamma}} w_{\epsilon_0}}.$$

For instance, the ϵ, γ -trimmed mean ($TM_{\epsilon, \gamma}$) is a weighted
 average with a left trim size of $\gamma\epsilon n$ and a right trim size of ϵn ,

$$\text{where } w_{\epsilon_0} = \begin{cases} 0, & \epsilon_0 < \epsilon \\ 1, & \epsilon_0 \geq \epsilon \end{cases}.$$

Classifying distributions by the signs of derivatives

Let \mathcal{P}_k denote the set of all distributions over \mathbb{R} whose
 moments, from the first to the k th, are all finite. With-
 out loss of generality, all classes discussed in the following
 are subclasses of the nonparametric class of distributions
 $\mathcal{P}_1^k := \{\text{All continuous distribution } P \in \mathcal{P}_k\}$. Besides fully
 and smoothly parameterizing by a Euclidean parameter or
 just assuming regularity conditions, there are many ways to
 classify distributions. In 1956, Stein initiated the problem of
 estimating parameters in the presence of an infinite dimen-
 sional nuisance shape parameter (31). A notable example
 discussed in his groundbreaking work was the estimation of
 the center of symmetry for an unknown symmetric distribution.
 In 1993, Bickel, Klaassen, Ritov, and Wellner published an
 influential semiparametrics textbook (32) and systematically
 classified many common models into three classes: paramet-
 ric, nonparametric, and semiparametric. However, there is
 another old and commonly encountered class of distributions
 that receives little attention in semiparametric literature: the
 unimodal distribution. It is a very unique semiparametric
 model because its definition is based on the signs of deriva-
 tives, i.e., assuming P is continuous, $(f'(x) > 0 \text{ for } x \leq M) \wedge$
 $(f'(x) < 0 \text{ for } x \geq M)$. Let \mathcal{P}_U denote the set of all unimodal
 distributions. Five parametric distributions in \mathcal{P}_U are detailed
 as examples here: Weibull, gamma, Pareto, lognormal and
 generalized Gaussian.

Inequalities related to weighted averages

The bias bound of the ϵ -symmetric trimmed mean is also
 monotonic for $\mathcal{P}_U \cap \mathcal{P}_2$, as proven in the SI Text using the

formulae provided in Bernard et al.'s paper (2). So far, it appears clear that the bias of an estimator is closely related to its degree of robustness. For a right-skewed unimodal distribution, often, $\mu \geq \text{STM}_\epsilon \geq m$. Then analogous to the γ -orderliness, the γ -trimming inequality is defined as $\forall \epsilon_1 \leq \epsilon_2 \leq \frac{1}{1+\gamma}$, $\text{TM}_{\epsilon_1, \gamma} \geq \text{TM}_{\epsilon_2, \gamma}$. A necessary and sufficient condition for the γ -trimming inequality is the monotonic decrease of the bias of the ϵ, γ -trimmed mean as a function of the breakdown point ϵ for a right skewed distribution, proven in the SI Text. γ -orderliness is a sufficient condition for the γ -trimming inequality, as proven in the SI Text, but it is not necessary.

Theorem .1. *For a right-skewed continuous distribution following the γ -trimming inequality, the quantile average is always greater or equal to the corresponding trimmed mean with the same ϵ and γ .*

Proof. By deducing $\frac{1}{1-\epsilon-\gamma\epsilon+2\delta} \int_{\gamma\epsilon-\delta}^{1-\epsilon+\delta} Q(u) du \geq \frac{1}{1-\epsilon-\gamma\epsilon} \int_{\gamma\epsilon}^{1-\epsilon} Q(u) du \Leftrightarrow \int_{\gamma\epsilon-\delta}^{1-\epsilon+\delta} Q(u) du - \frac{1-\epsilon-\gamma\epsilon+2\delta}{1-\epsilon-\gamma\epsilon} \int_{\gamma\epsilon}^{1-\epsilon} Q(u) du \geq 0 \Leftrightarrow \int_{\gamma\epsilon-\delta}^{1-\epsilon+\delta} Q(u) du + \frac{2\delta}{1-\epsilon-\gamma\epsilon} \int_{\gamma\epsilon}^{1-\epsilon} Q(u) du \geq 0 \Leftrightarrow \frac{1}{2\delta} \left(\int_{1-\epsilon}^{1-\epsilon+\delta} Q(u) du + \int_{\gamma\epsilon-\delta}^{\gamma\epsilon} Q(u) du \right) \geq \frac{1}{1-\epsilon-\gamma\epsilon} \int_{\gamma\epsilon}^{1-\epsilon} Q(u) du$ and noticing that $\lim_{\delta \rightarrow 0} \frac{1}{2\delta} \left(\int_{1-\epsilon}^{1-\epsilon+\delta} Q(u) du + \int_{\gamma\epsilon-\delta}^{\gamma\epsilon} Q(u) du \right) = \frac{Q(\gamma\epsilon) + Q(1-\epsilon)}{2}$, the proof is complete. \square

A similar result can be obtained in the following theorem.

Theorem .2. *For a right-skewed continuous distribution following the γ -trimming inequality, the Winsorized mean is always greater or equal to the corresponding trimmed mean with the same ϵ and γ , if $\gamma \leq 1$.*

Proof. Continue the above deduction, $\frac{Q(\gamma\epsilon) + Q(1-\epsilon)}{2} \geq \frac{1}{1-\epsilon-\gamma\epsilon} \int_{\gamma\epsilon}^{1-\epsilon} Q(u) du \Leftrightarrow \gamma\epsilon(Q(\gamma\epsilon) + Q(1-\epsilon)) \geq \left(\frac{2\gamma\epsilon}{1-\epsilon-\gamma\epsilon} \right) \int_{\gamma\epsilon}^{1-\epsilon} Q(u) du$. Then, if $\gamma \leq 1$, $\left(1 - \frac{1}{1-\epsilon-\gamma\epsilon} \right) \int_{\gamma\epsilon}^{1-\epsilon} Q(u) du + \gamma\epsilon(Q(\gamma\epsilon) + Q(1-\epsilon)) \geq 0 \Rightarrow \int_{\gamma\epsilon}^{1-\epsilon} Q(u) du + \gamma\epsilon Q(\gamma\epsilon) + \epsilon Q(1-\epsilon) \geq \int_{\gamma\epsilon}^{1-\epsilon} Q(u) du + \gamma\epsilon(Q(\gamma\epsilon) + Q(1-\epsilon)) \geq \frac{1}{1-\epsilon-\gamma\epsilon} \int_{\gamma\epsilon}^{1-\epsilon} Q(u) du$, the proof is complete. \square

Theorem .2 unequivocally establishes that, for a distribution that follows the γ -trimming inequality, the Winsorized mean is always less biased or equal to the trimmed mean, as long as $\gamma \leq 1$. If assuming γ -orderliness, the result can be extended to the $\gamma > 1$ case, as proven in the SI Text. Replacing the trimmed mean in the γ -trimming inequality with Winsorized mean forms the definition of γ -Winsorization inequality. γ -orderliness also implies the γ -Winsorization inequality, if $\gamma \leq 1$, as proven in the SI Text.

Data Availability. Data for Figure ?? are given in SI Dataset S1. All codes have been deposited in [GitHub](#).

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