Electronics for embedded systems - Group 02

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Laboratory 1

Project 1: AND gate

In this project we designed an AND gate. The input signals are the first two switches of the board, and the output signal is displayed on the first LED.

```
file lab1_1_efes.vhd:
library ieee;
use ieee.std_logic_1164.all;
entity lab1_1_efes is
port (
    SW : in std_logic_vector(1 downto 0);
    LEDR : out std_logic_vector(0 downto 0)
);
end entity;
architecture behavior of lab1_1_efes is
    LEDR(0) \le SW(0) \text{ and } SW(1);
end architecture;
file tb.vhd:
library ieee;
use ieee.std_logic_1164.all;
entity tb is
end entity;
architecture behavior of tb is
    component lab1_1_efes
    port (
        A, B: in std_logic;
        C : out std_logic
    );
    end component;
```

```
signal A, B, C: std_logic;
begin
```

```
and_port: lab1_1_efes PORT MAP(
        A => A,
        B \Rightarrow B
        C => C
    );
    values_process: process is
        A <= '1';
        B <= '1';
        wait for 20 ns;
        A <= 'O';
        B <= '1';
        wait for 20 ns;
        A <= 'O';
        B <= '0';
        wait for 20 ns;
        A <= '1';
        B <= '0';
        wait for 20 ns;
    end process values_process;
end architecture;
```

Timing analisys: At the beginning, we didn't assign any pins or timing constraints to the project in order to let the tool make the decision itself.

The tool set the following pins:

- PIN_AH28 for signal A
- PIN_AC25 for signal B
- PIN_AD25 for signal C

It made a very smart choice since these pins are pretty close to each other; in this way, signals propagation delays through the AND gate should have been relatively small.

In fact, the resulting propagation delays were:

- signal A
 - 1. from rising edge to rising edge, RR: 5.737 ns

- 2. from falling edge to falling edge, FF: 5.835 ns
- signal B
 - 1. from rising edge to rising edge, RR: 5.965 ns
 - 2. from falling edge to falling edge, FF: 6.162 ns

Then we tried assigning timing constraints to check whether the tool would have assigned the same pins as before or if it would have changed something in order to be sure that the timing constraint would have been respected.

We assigned 10 ns as timing constraint (a pretty large one), and, as predicted, the pins assigned by the tool were closer than before:

- PIN_AB26 for signal A
- PIN AB22 for signal B
- PIN AB23 for signal C

As a result, signals propagation delays through the AND gate were smaller:

- signal A
 - 1. from rising edge to rising edge, RR: 5.660 ns
 - 2. from falling edge to falling edge, FF: 5.751 ns
- signal B
 - 1. from rising edge to rising edge, RR: 5.644 ns
 - 2. from falling edge to falling edge, FF: 5.754 ns

{Figure 1} In orange is shown the first set of pins assigned by the tool, in blue is shown the second one.

After assigning the timing constraint and letting the tool figure by itself the pin assignment, we tried doing the opposite: we assigned different sets of pins for our signals and we checked the resulting propagation delays.

A	В	C		
pin	pin	pin	Constraint $t_{pd_{MAX}}$ [ns]	Worst case t_{pd} [ns]
$\overline{\mathrm{AD27}}$	AD26	AD25	None	7.739
AE26	AD26	AD25	None	7.739
AE26	AC27	AH30	None	6.807
AK3	A3	AH30	None	9.951

{Figure 2} In green is shown the first set of pins, in purple is shown the last one.

We first assigned pins really close to each other (first row of the table) expecting to have similar values of propagation delays as the ones obtained when the tool assigned both pins and timing constraints by itself.

What we got instead were values of propagation delays higher than those:

- signal A
 - 1. from rising edge to rising edge, RR: 6.154 ns
 - 2. from falling edge to falling edge, FF: 6.385 ns
- signal B
 - 1. from rising edge to rising edge, RR: 6.845 ns
 - 2. from falling edge to falling edge, FF: 7.739 ns

We think that the reason why this happened may be the fact that:

- when the tool had to make all the decisions, it chose pins that not only are close to each other on the pin planner but whose routes are also shorter inside the FPGA
- when we chose the pins, even if they were approximately as close to each other as the ones chosen by the tool previously, their routes are longer inside the FPGA

During our second attempt, we changed only one pin, the A signals' one, and we chose a pin which was a little farther away.

As expected, the propagation delays of the A signal were a little bit higher this time:

- from rising edge to rising edge, RR: 6.319 ns
- from falling edge to falling edge, FF: 6.545 ns

In our third attempt, we changed also signals B and C pins in order to have more distance between the three of them, but still not too much (third row of the table).

While signal A propagation delays increased, according to our prediction, the ones of signal B decreased:

- signal A
 - 1. from rising edge to rising edge, RR: 6.571 ns
 - 2. from falling edge to falling edge, FF: 6.807 ns
- signal B
 - 1. from rising edge to rising edge, RR: 6.116 ns
 - 2. from falling edge to falling edge, FF: 6.173 ns

We think that the reason why this happened is probably the same we said before, regarding the routes between the pins inside the FPGA.

During our last attempt, we assigned pins really far from each other (fourth row of the table).

What we expected were propagation delays much higher than the previous ones and, in fact, we got:

- signal A
 - 1. from rising edge to rising edge, RR: 8.103 ns
 - 2. from falling edge to falling edge, FF: 8.495 ns
- signal B
 - 1. from rising edge to rising edge, RR: 9.350 ns
 - 2. from falling edge to falling edge, FF: 9.951 ns

At the end, we assigned both pins and timing constraints to our project:

A pin	B pin	C pin	Constraint $t_{pd_{MAX}}$ [ns]	Worst case t_{pd} [ns]
AK3 AK3	-	AH30 AH30		10.708 10.708

We kept the same pin assignment of the last attempt and we assigned different timing constraints, starting from a higher one and decreasing it along the way.

Since during the last attempt we didn't assign any timing constraint and the tool figured out a way to have a maximum propagation delay of 9.951 ns, we thought that with a timing constraint of 15 ns we would have had pretty much the same results, probably a little higher.

Our reasoning was proved to be true by the results:

- signal A
 - 1. from rising edge to rising edge, RR: 8.694 ns
 - 2. from falling edge to falling edge, FF: 9.185 ns
- signal B
 - 1. from rising edge to rising edge, RR: 9.989 ns
 - 2. from falling edge to falling edge, FF: 10.708 ns

At that point, we tried assigning a smaller timing constraint (9 ns) in order to see if the tool would have found a way to respect it, but we discovered that the tool couldn't do it and that probably the propagation delays that it found by itself were the best he could do. In fact, it didn't even try to get those values again, it just gave up and reported the same result we obtained for 15 ns as timing constraint.

```
Project 2: 10 bit counter
file lab1_2_efes.vhd:
library ieee;
use ieee.std_logic_1164.all;
use ieee.numeric_std.all;
entity lab1_2_efes is
port(
    CLOCK_50: in std_logic;
    GPIO_0: out std_logic_vector(2 downto 0);
    KEY: in std_logic_vector(0 DOWNTO 0)
 );
end entity;
architecture behaviour of lab1_2_efes is
signal A, B, C, resn, clk: std_logic;
component counter_10bits
port(
    cnt : buffer unsigned(9 downto 0);
    resn, enable, clk: in std_logic
);
end component;
component and_gate
port (
    A, B: in std_logic;
    C : out std_logic
);
end component;
signal cnt: unsigned(9 downto 0);
signal output: std_logic;
begin
counter_comp: counter_10bits port map(
   cnt => cnt,
   resn => resn,
    enable=>'1',
    clk=>clk
);
andgate_comp: and_gate port map(
    A = > cnt(9),
    B=>cnt(8),
```

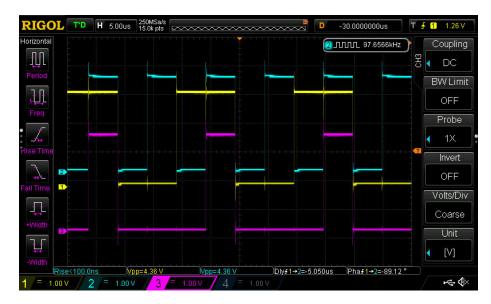
```
c=>output
);
A \leq cnt(9);
B <= cnt(8);
C <= output;</pre>
resn <= KEY(0);</pre>
GPIO_O(0) \leftarrow A;
GPIO_0(1) <= B;</pre>
GPIO_0(2) <= C;</pre>
clk <= CLOCK_50;</pre>
end architecture;
file counter_10bits.vhd:
library ieee;
use ieee.std_logic_1164.all;
use ieee.numeric_std.all;
entity counter_10bits is
 port(
    cnt : buffer unsigned(9 downto 0);
    resn,enable,clk: in std_logic
 );
end entity;
architecture behaviour of counter_10bits is
begin
    count_process: process (clk,resn) is
    begin
    if (resn = '0') then
         cnt<="0000000000";
    elsif (clk'event and clk = '1') then
      if (enable='1') then
          cnt <= cnt+1;</pre>
      end if;
    end if;
    end process;
```

```
end architecture;
file and_gate.vhd:
library ieee;
use ieee.std_logic_1164.all;
entity and_gate is
port (
    A, B: in std_logic;
    C : out std_logic
);
end entity;
architecture behavior of and_gate is
begin
    C \le A \text{ and } B;
end architecture;
file tb.vhd:
library ieee;
use ieee.std_logic_1164.all;
use ieee.numeric_std.all;
entity tb is
end entity;
architecture behaviour of tb is
component lab1_2_efes
 port(
    clk, resn: in std_logic;
    A, B, C: out std_logic
);
end component;
signal clk, A, B, C, resn: std_logic;
begin
testbench: lab1_2_efes port map(
    clk => clk,
    resn => resn,
    A => A
```

```
B \Rightarrow B,
    C \Rightarrow C
);
process is
begin
    clk <= '1';
    resn <= '0';
    wait for 20 ns;
    resn <= '1';
    wait for 20 ns;
    for i in 0 to 100 loop
         clk <= '0';
         wait for 20 ns;
         clk <= '1';
         wait for 20 ns;
    end loop;
end process;
end architecture;
```

Code explanation: we added a 10 bit counter clocked at 50 MHz, and connected the bits 8 and 9 (the slowest changing ones) to the input of the AND gate. Then we connected the inputs and the output of the gate to the GPIO pins, in order to observe the waveforms on the oscilloscope.

As we can see in the image below, the output of the AND gate (the purple one) correctly represents the logical AND of the two inputs: it is LOW always except when both inputs are HIGH.



Note: the waveforms are vertically shifted in order to better distinguish them.

Project 3: Ripple Carry Adder

```
file lab1_3_efes.vhd:
library ieee;
use ieee.std_logic_1164.all;
entity lab1_3_efes is
port (
    SW: in std_logic_vector(7 DOWNTO 0);
   LEDR : out std_logic_vector(4 DOWNTO 0);
   KEY: in std_logic_vector(0 DOWNTO 0);
   HEXO: out std_logic_vector(0 TO 6);
   CLOCK_50: in std_logic
);
end lab1_3_efes;
architecture behavior of lab1_3_efes is
SIGNAL input_decoder: std_logic_vector(3 DOWNTO 0);
COMPONENT ripple_carry_adder IS
port(a,b: in std_logic_vector(3 DOWNTO 0);
    cin: in std_logic;
    s: out std_logic_vector(3 DOWNTO 0);
    cout: out std_logic;
```

```
clk: in std_logic
);
END COMPONENT;
COMPONENT disp IS
PORT ( ing : IN STD_LOGIC_VECTOR( 3 DOWNTO 0);
usc : OUT STD_LOGIC_VECTOR(0 to 6) );
END COMPONENT;
begin
LEDR(3 DOWNTO 0) <= input_decoder;</pre>
rca: ripple_carry_adder PORT MAP(a => SW(3 DOWNTO 0), b => SW(7 DOWNTO 4), cin => not KEY(0)
display: disp PORT MAP(ing => input_decoder, usc => HEXO);
end architecture;
file ripple_carry_adder.vhd:
library ieee;
use ieee.std_logic_1164.all;
ENTITY ripple_carry_adder IS
port(a,b: in std_logic_vector(3 DOWNTO 0);
    cin: in std_logic;
    s: out std_logic_vector(3 DOWNTO 0);
     cout: out std_logic;
     clk: in std_logic
);
END ripple_carry_adder;
ARCHITECTURE structural OF ripple_carry_adder IS
SIGNAL f: std_logic_vector(0 TO 2);
SIGNAL a_ff, b_ff, s_ff: std_logic_vector(3 downto 0);
COMPONENT fulladder IS
port(a_full,b_full: in std_logic;
    cin_full: in std_logic;
    s_full: out std_logic;
     cout_full: out std_logic);
END COMPONENT;
BEGIN
   process(clk) is
    begin
        if(rising_edge(clk)) then
            a_ff <= a;
```

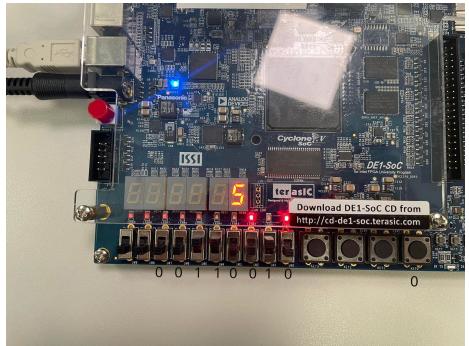
```
b_ff <= b;
            s <= s_ff;
        end if;
    end process;
fa0: fulladder PORT MAP (a_full => a_ff(0), b_full => b_ff(0), cin_full => cin, cout_full =>
fa1: fulladder PORT MAP (a_full => a_ff(1), b_full => b_ff(1), cin_full => f(0), cout_full
fa2: fulladder PORT MAP (a_full => a_ff(2), b_full => b_ff(2), cin_full => f(1), cout_full
fa3: fulladder PORT MAP (a_full => a_ff(3), b_full => b_ff(3), cin_full => f(2), cout_full
END ARCHITECTURE;
file fulladder.vhd:
library ieee;
use ieee.std_logic_1164.all;
use ieee.numeric_std.all;
ENTITY fulladder IS
port(a_full,b_full: in std_logic;
    cin_full: in std_logic;
    s_full: out std_logic;
     cout_full: out std_logic);
END fulladder;
ARCHITECTURE structural OF fulladder IS
SIGNAL a_u, b_u, c_u, out_u: unsigned(1 DOWNTO 0);
BEGIN
a_u(0) <= a_full;
b_u(0) <= b_full;
c_u(0) <= cin_full;</pre>
s_full <= out_u(0);</pre>
a_u(1) \le '0';
b_u(1) <= '0';
c_u(1) <= '0';
cout_full <= out_u(1);</pre>
out_u <= a_u+b_u+c_u;</pre>
END ARCHITECTURE;
file disp.vhd:
```

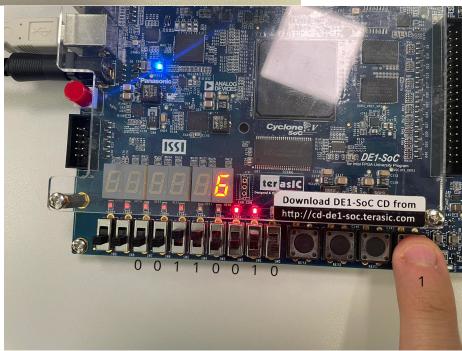
```
LIBRARY ieee;
USE ieee.std_logic_1164.all;
ENTITY disp IS
    PORT ( ing : IN STD_LOGIC_VECTOR( 3 DOWNTO 0);
     usc : OUT STD_LOGIC_VECTOR(0 to 6) );
END disp;
 ARCHITECTURE Behaviour OF disp IS -- funzioni logiche derivate dalla tabella di verità e da
     BEGIN
     usc(0) \le ((NOT ing(3)) AND (NOT ing(2)) AND (NOT ing(1)) AND ing(0)) OR ((NOT ing(3)) AND
      (ing(3) AND ing(2) AND (NOT ing(1)) AND ing(0)) OR (ing(3) AND (NOT ing(2)) AND ing(1) AND
      usc(1) <= ((NOT ing(3)) AND ing(2) AND (NOT ing(1)) AND ing(0)) OR ((NOT ing(0)) AND ing(1)
      (ing(3) AND ing(2) AND (NOT ing(0))) OR (ing(3) AND ing(2) AND ing(1)) OR (ing(3) AND ing(4))
      usc(2) \le ((NOT ing(3)) AND ing(1) AND (NOT ing(2)) AND (NOT ing(0))) OR (ing(3) AND ing(1))
      (ing(3) AND ing(2) AND (NOT ing(0)));
      usc(3) \le ((NOT ing(3)) AND (NOT ing(2)) AND (NOT ing(1)) AND ing(0)) OR ((NOT ing(3)) AND (NOT ing(3)) AND
      (ing(0) AND ing(2) AND ing(1)) OR (ing(3) AND (NOT ing(2)) AND ing(1) AND (NOT ing(0)));
      usc(4) \leftarrow ((NOT ing(2)) AND (NOT ing(1)) AND ing(0)) OR (((NOT ing(3)) AND (NOT ing(1)) AND (NOT ing(1))) AND (NOT ing(1)) A
      usc(5) \le ((NOT ing(3)) AND ing(1) AND (NOT ing(2))) OR (ing(3) AND ing(0) AND ing(2) AND (NOT ing(3)) OR (ing(3) AND ing(3)) OR (ing(3) AND ing(3)) OR (ing(3) AND ing(3)) AND ing(3) AND
      ((NOT ing(3)) AND ing(0) AND (NOT ing(2))) OR ((NOT ing(3)) AND ing(1) AND ing(0));
      usc(6) \le ((NOT ing(3)) AND (NOT ing(2)) AND (NOT ing(1))) OR ((NOT ing(3)) AND ing(1) AND
      (ing(3) AND ing(2) AND (NOT ing(0)) AND (NOT ing(1)));
 END Behaviour ;
```

Code explanation: We wrote the VHDL code for a full adder, taking two bits (a_full and b_full) as inputs. Then, we converted them to 2 bits unsigned signals, in order to sum them. We are sure that the result will fit in 2 bits because the worst case is with a_full=1, b_full=1 and cin_full=1, and the output should be 11.

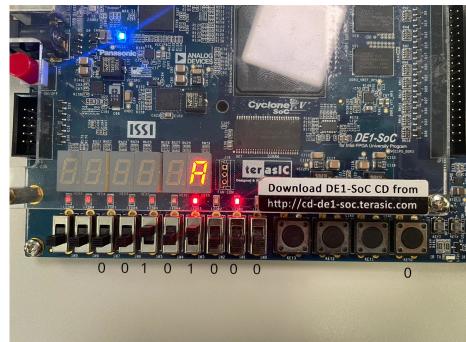
In order to obtain a 4 bits ripple carry adder, we connected 4 different full adders together, routing the carry out of each one to the carry in of the following. To make the ripple carry adder synchronous, we added filp flops at the inputs and the output, using a process sensible to the clock. Finally, we displayed on a 7 segment display the result, using a decoder whose logic function has been calculated with a Karnaugh map, and also displayed it in binary format using the LEDs

If there an overflow occurs, an LED turns on, like shown in the following pictures:

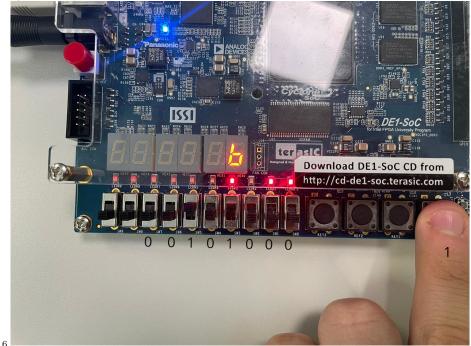




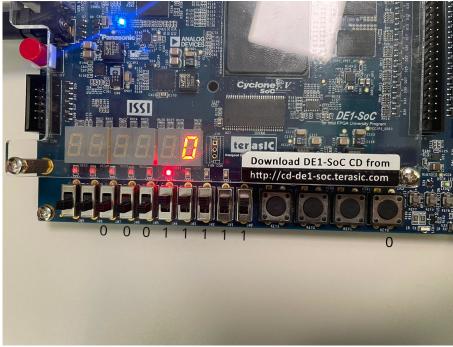
 $0010_2+0011_2=0101_2=5_{16}$ Here the KEY0 button is pressed, meaning that the carry in is equal to 1.



 $0010_2 + 0011_2 + 1 = 0110_2 = 6_{16}$



 $1000_2 + 0010_2 = 1010_2 = A_{16}$



 $1000_2 + 0010_2 + 1 = 1011_2 = B_{16}$

In this example the result cannot be represented on 4 bits, so the value displayed is wrong and the overflow LED turns on $1111_2+0001_2=10000_2=10_{16}$

```
2 . 2 2 10
```

```
Project #5: 16 bits counter
```

```
file lab1_5_efes.vhd:
    library ieee;
use ieee.std_logic_1164.all;
use ieee.numeric_std.all;
entity lab1_5_efes is
port(
        CLOCK_50: IN std_logic;
        KEY: IN std_logic_vector(0 downto 0);
        SW: IN std_logic_vector(0 downto 0);
        HEXO, HEX1, HEX2, HEX3: OUT std_logic_vector(0 to 6);
        lEDR: OUT std_logic_vector(0 downto 0)
);
end entity;
architecture behavior of lab1_5_efes is
signal count: unsigned(15 downto 0);
```

```
component counter16
port(
    clk, rstn, enable: in std_logic;
    cnt: buffer unsigned (15 downto 0);
    tc: out std_logic
);
end component;
component disp
PORT (
    ing : IN STD_LOGIC_VECTOR( 3 DOWNTO 0);
    usc : OUT STD_LOGIC_VECTOR(0 to 6)
);
END component;
begin
pippo: counter16 port map(
    clk => CLOCK_50,
    rstn => KEY(0),
    enable \Rightarrow SW(0),
    cnt => count,
    tc => LEDR(0)
);
disp0: disp port map(
    ing => std_logic_vector(count(3 downto 0)),
    usc => HEXO
);
disp1: disp port map(
    ing => std_logic_vector(count(7 downto 4)),
    usc => HEX1
);
disp2: disp port map(
    ing => std_logic_vector(count(11 downto 8)),
    usc => HEX2
);
disp3: disp port map(
    ing => std_logic_vector(count(15 downto 12)),
    usc => HEX3
);
end architecture;
```

```
file counter16.vhd:
library ieee;
use ieee.std_logic_1164.all;
use ieee.numeric_std.all;
entity counter16 is
port(
    clk, rstn, enable: in std_logic;
    cnt: buffer unsigned (15 downto 0);
    tc: out std_logic
);
end entity;
architecture behavior of counter16 is
begin
    cntpr: process(clk, rstn)
    begin
        if(rstn='0') then
            cnt <= (others=>'0'); --"000000000000000";
        elsif (clk'event and clk='1') then
            if(enable='1') then
                cnt <= cnt + 1;</pre>
            end if;
        end if;
    end process;
    tc <= '1' when (cnt = "11111111111111") else '0';
end architecture;
file disp.vhd: (same as exercise #3)
file tb.vhd:
library ieee;
use ieee.std_logic_1164.all;
use ieee.numeric_std.all;
entity tb is
end entity;
architecture behavior of tb is
```

```
signal resetn: std_logic_vector(0 downto 0);
signal enable: std_logic_vector(0 downto 0);
signal HEXO, HEX1, HEX2, HEX3: std_logic_vector(0 to 6);
signal tc: std_logic_vector(0 downto 0);
component lab1_5_efes
port(
    CLOCK_50: IN std_logic;
    KEY: IN std_logic_vector(0 downto 0);
    SW: IN std_logic_vector(0 downto 0);
    HEXO, HEX1, HEX2, HEX3: OUT std_logic_vector(0 to 6);
    lEDR: OUT std_logic_vector(0 downto 0)
);
end component;
begin
testbencho: lab1_5_efes port map(
    CLOCK_50 => CLOCK_50,
    KEY => resetn,
    SW => enable,
    HEXO => HEXO,
    HEX1 => HEX1,
   HEX2 \Rightarrow HEX2,
   HEX3 \Rightarrow HEX3,
    LEDR => tc
);
clock_process: process
begin
    CLOCK 50 <= '0';
    wait for 20 ns;
    CLOCK_50 <= '1';
    wait for 20 ns;
end process;
tb_process: process
begin
   resetn(0) <= '0';
    enable(0) <= '0';
    wait for 50 ns;
   resetn(0) <= '1';
    wait for 50 ns;
    enable(0) <= '1';
```

signal CLOCK_50: std_logic;

```
wait for 5 ms;
end process;
end architecture;
```

Code explanation: The 16 bit counter we implemented has a an asynchronous reset input (active low), a clock input, and an enable input.

If the reset signal is LOW, the counter will reset, writing 0 to cnt, no matter how the clock behaves. Otherwise, if the enable signal is high, the clock rising edge will increment by 1 the value of cnt. The terminal count signal (tc) is set to 1 when cnt arrives its maximum value, meaning that he ended counting and that at the next clock edge it will be set to 0.