



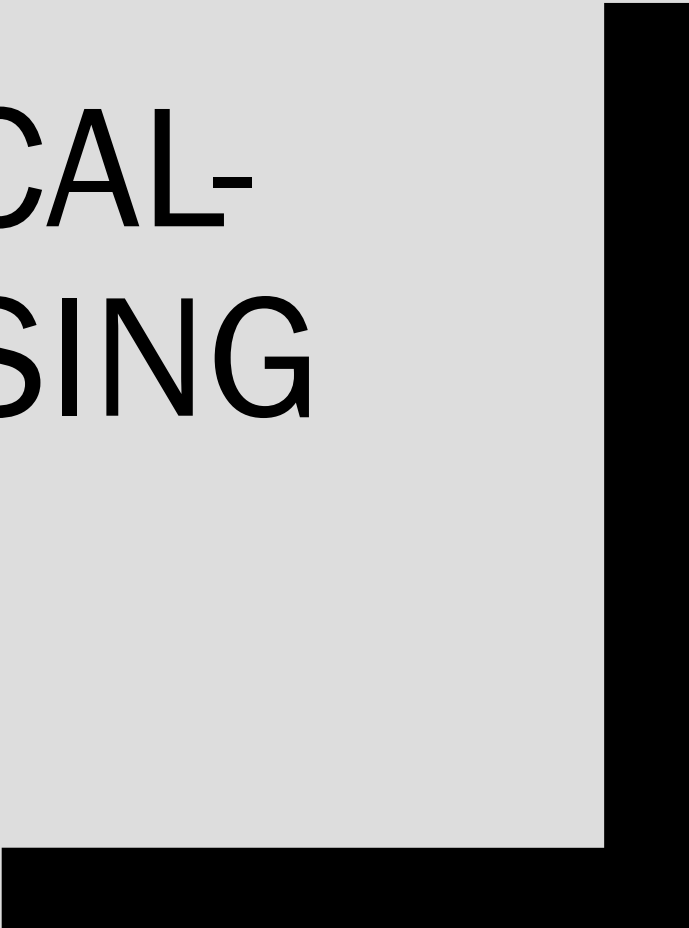
# SEAMLESS FOCAL- STACK REFOCUSING

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# Outline

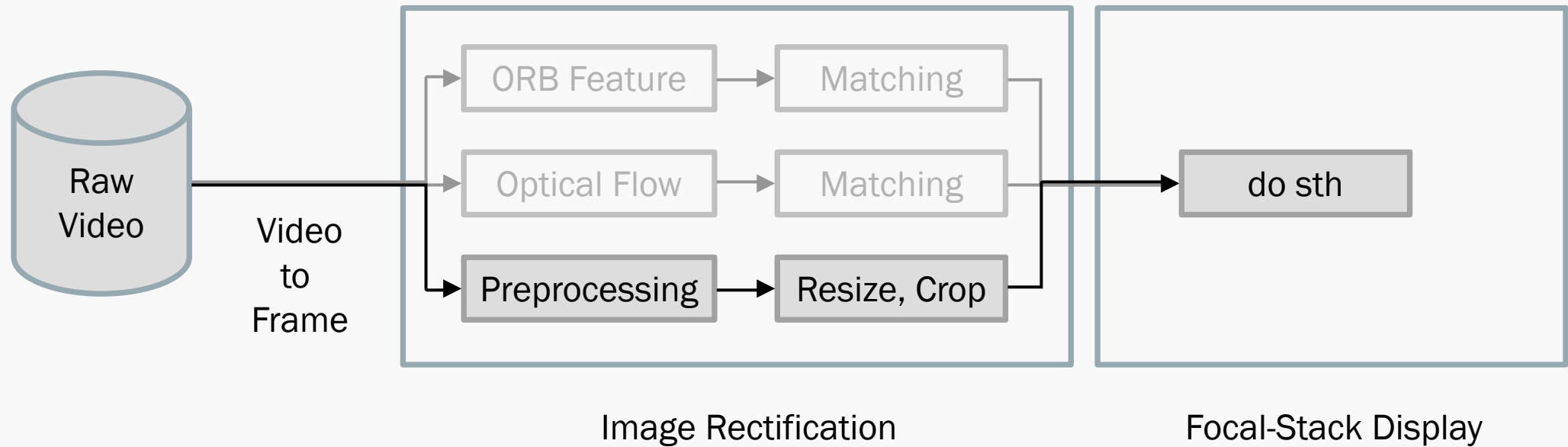
- Introduction
- Methodology
  - Image Rectification
  - Foreground and Background Differentiation (tbd)
  - Sharpness Detection (tbd)
- Experiment Results and Comparison
- Conclusion

# INTRODUCTION

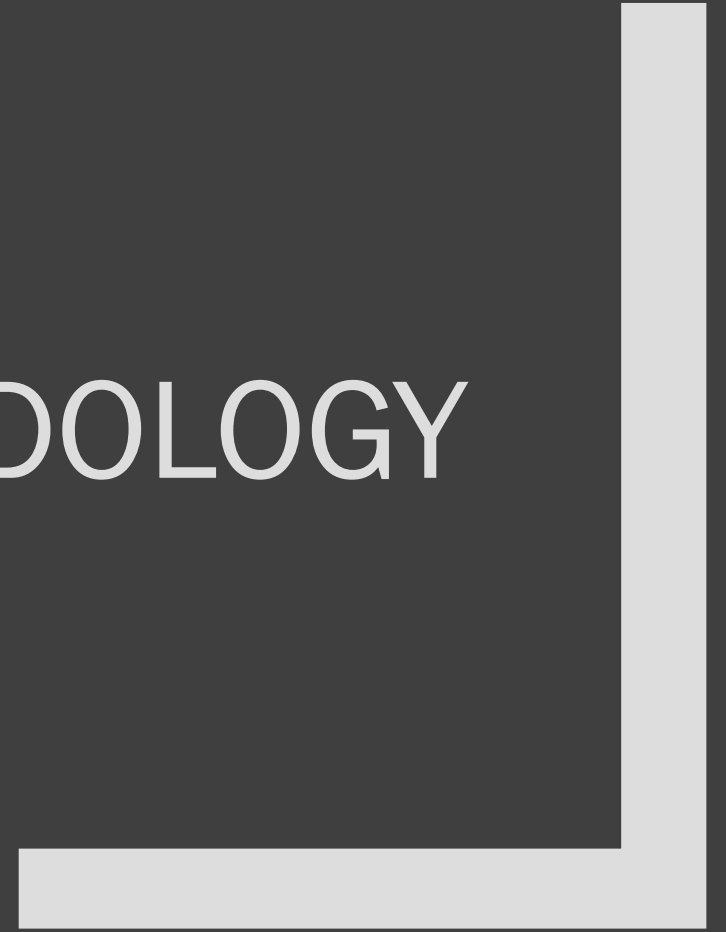


# Flow Chart

- Topic: Seamless focal-stack refocusing



# METHODOLOGY

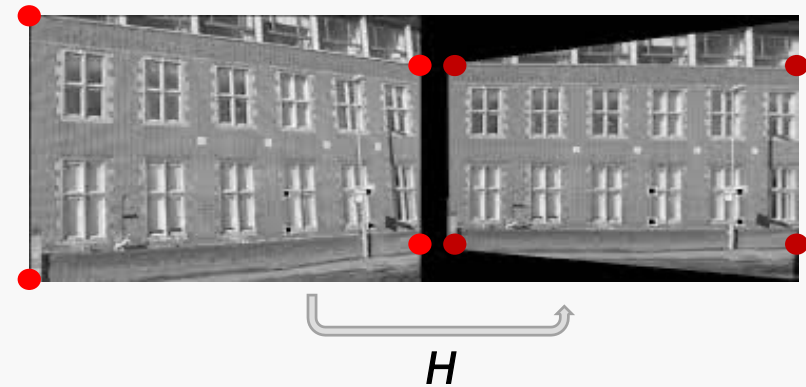


# Image Rectification

## ■ Method 1: ORB feature & brute-force matching

- Local feature: detection  $\rightarrow$  description  $\rightarrow$  matching
- ORB (Oriented FAST and Rotated BRIEF) is a fusion of FAST keypoint **detector** and BRIEF **descriptor**.
- Use matching points to find **homography**.

$$\lambda_i \begin{bmatrix} u_i' \\ v_i' \\ 1 \end{bmatrix} = \begin{bmatrix} H_{11} & H_{12} & H_{13} \\ H_{21} & H_{22} & H_{23} \\ H_{31} & H_{32} & H_{33} \end{bmatrix} \begin{bmatrix} u_i \\ v_i \\ 1 \end{bmatrix}$$



## ■ Method 2: optical flow & brute-force matching

- Optical flow is the pattern of **apparent motion** of image objects between two consecutive frames.
- Similarly, find matching points of interest and compute **homography**.

# Image Rectification

- Method 3: resizing and cropping

- Image preprocessing: Canny edge
- Find the **resize ratio** which result in the least difference between two consecutive frames by **grid search**.

$$r^* = \operatorname{argmin}_r \| \text{ResizeCrop}(\text{edge}_{k+1}, r) - \text{edge}_k \|_2$$

- To be brief, find a proper method during the demonstration.

# EXPERIMENT RESULTS & COMPARISONS





# Image Rectification Comparison

Original



Refocus



ORB Features

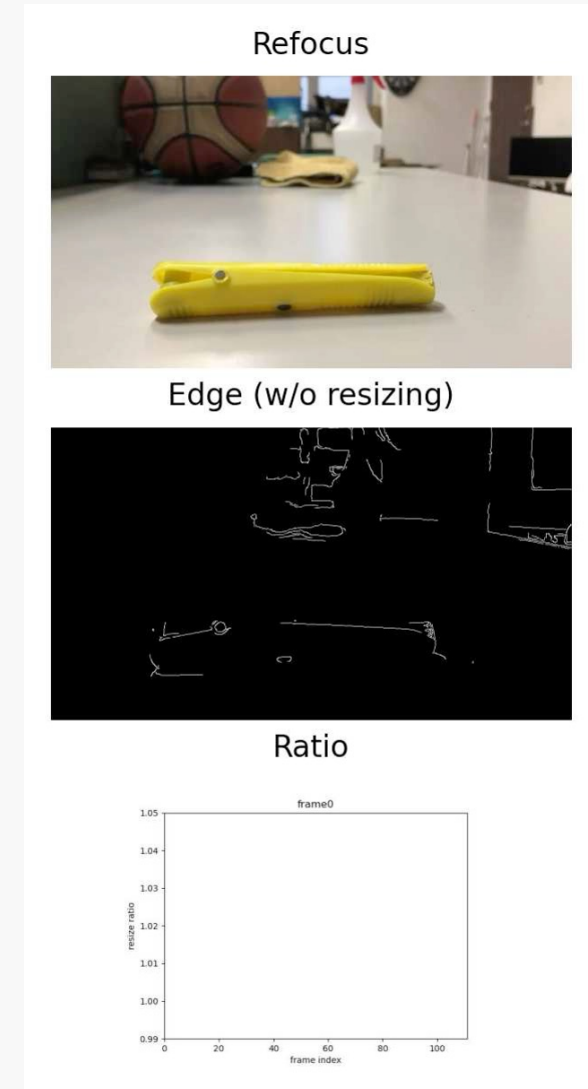
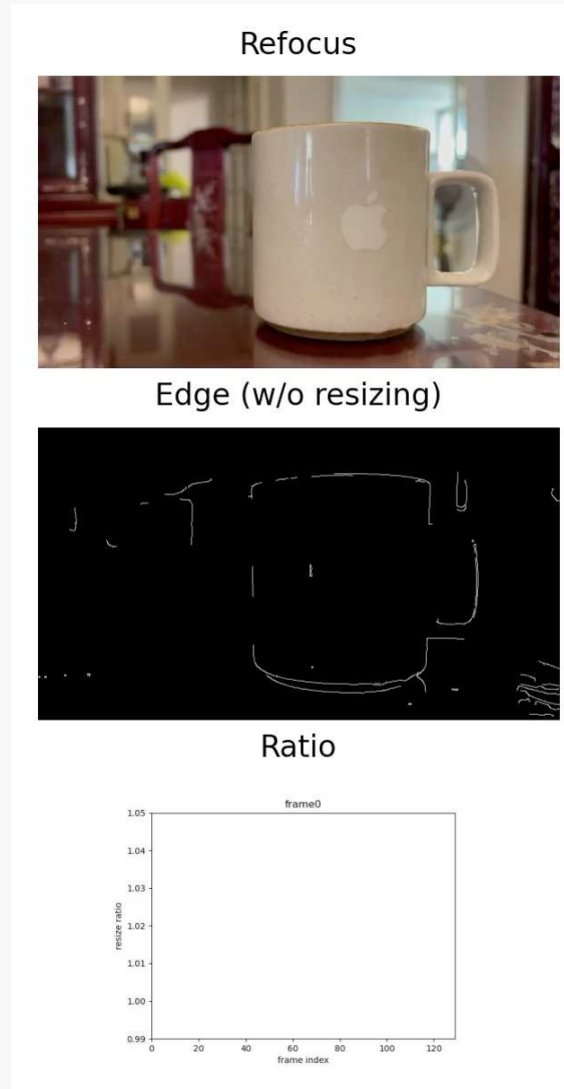
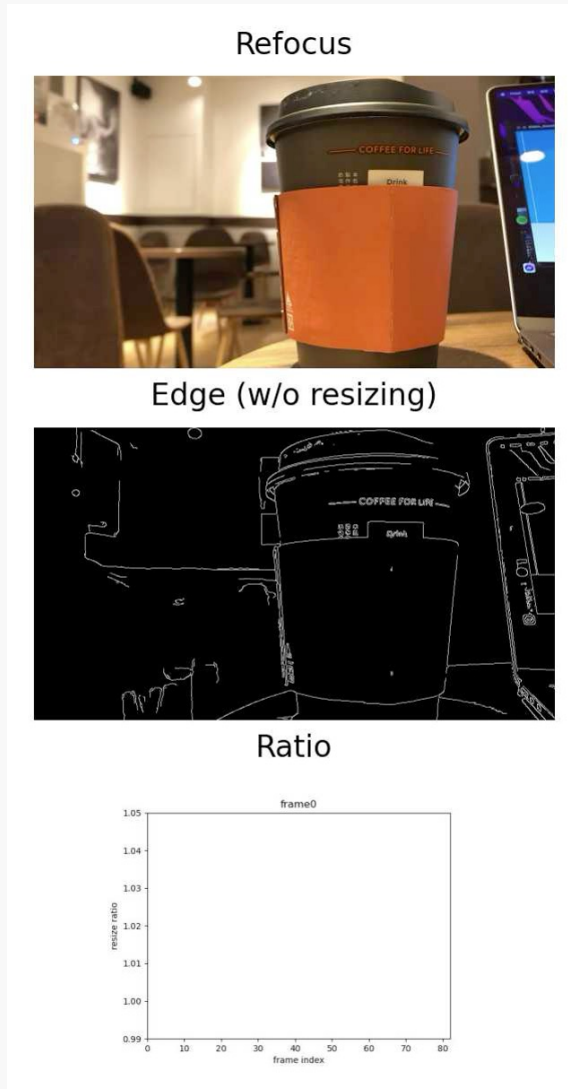


Optical Flow

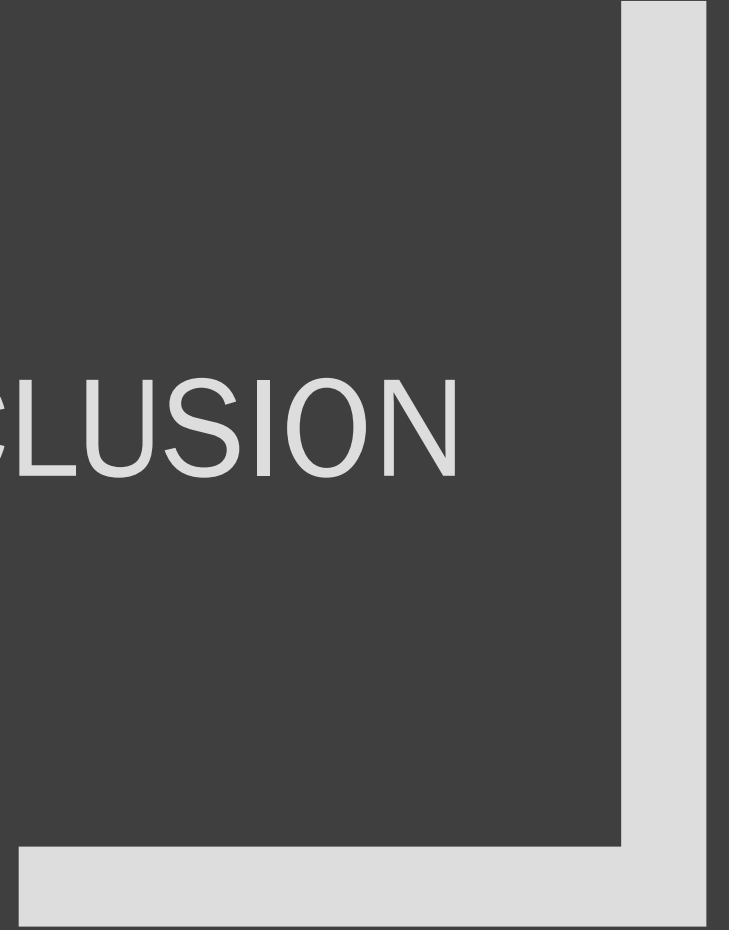


- Observation:  
ORB feature, optical flow → not stable
- In summary, we utilize resizing and cropping method as demo.

# Brief Demo: Stacks of Frame, Edge and Ratio



CONCLUSION





# THANKS!

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