Title in Progress

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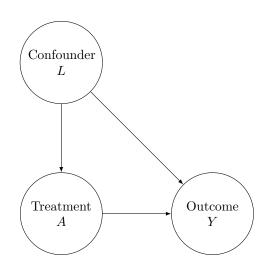
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- ▶ ... but there is no consensus on the best way to estimate standard errors when using the PSM algorithm.
- How can we assess which procedures reliably estimate standard errors?

A simulation study!

A Quick Foray into Confounding



Taking a Step Back, What is Propensity Score Matching?

A propensity score is the probability that an individual receives a treatment A; that is, P(A=1). In an RCT, treatments are randomized, and hence outcomes Y are independent of treatment A.

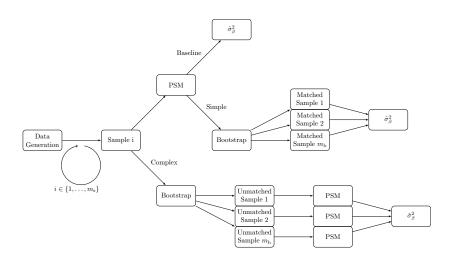
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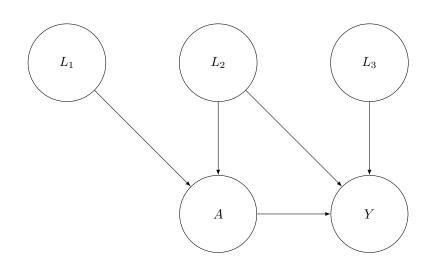
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- ► The PSM algorithm intakes an unmatched dataset and outputs a matched one.
- ▶ When do we execute the bootstrap before the match or after it?
- Let's try both!

Roadmap of the Simulation Study



Data Generation



Data Generation - Continuous Outcome

For each individual $i \in \{1, \ldots, n\}$, we consider covariates $L_{1i}, L_{2i}, L_{3i} \sim N(0,1)$. Treatments are distributed according to law $A_i \sim B(\pi_i)$, where π_i - the true propensity to be treated - is subject to the data-generating process

$$\log\left(\frac{\pi_i}{1-\pi_i}\right) = \alpha_0 + \alpha_1 L_{1i} + \alpha_2 L_{2i}.$$

Given this, we further define the data-generating process of our continuous outcome via

$$Y_i = \beta_1 A_i + \beta_2 L_{2i} + \beta_3 L_{3i} + \varepsilon_i,$$

where ε_i denotes random error. Because L_{2i} effects both A_i and Y_i , it acts as a confounder in estimating the treatment effect.

Data Generation - Binary Outcome

For each individual $i \in \{1, \ldots, n\}$, we consider covariates $L_{1i}, L_{2i}, L_{3i} \sim N(0,1)$. Treatments are distributed according to law $A_i \sim B(\pi_i)$, where π_i - the true propensity to be treated - is subject to the data-generating process

$$\log\left(\frac{\pi_i}{1-\pi_i}\right) = \alpha_0 + \alpha_1 L_{1i} + \alpha_2 L_{2i}.$$

Given this, we further define the data-generating process of our binary outcome via $Y_i \sim B(\tau_i)$ where

$$\log\left(\frac{\tau_i}{1-\tau_i}\right) = \beta_1 A_i + \beta_2 L_{2i} + \beta_3 L_{3i}.$$

Observe that we have omitted a random error term, as realizations of Y_i are innately subject to noise.

Parameters of Interest

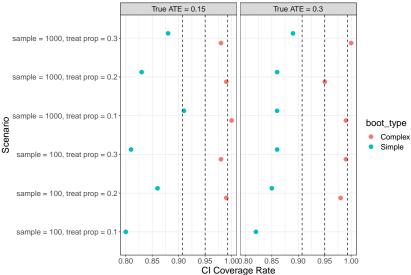
- ▶ The sample size of each dataset $n_{\mathsf{sample}} \in \{100, 1000\}$
- ▶ The population proportion of treated individuals $\pi \in \{0.113, 0.216, 0.313\}$

Other Parameters

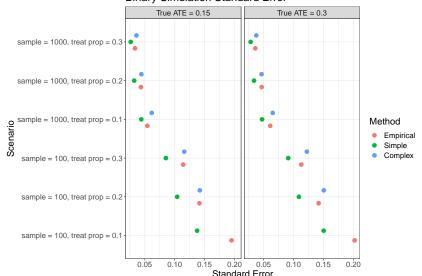
▶ The number of datasets $m_{\text{sample}} = 100$

Measures of Interest

in binary coverage plot-1.pdf
Binary Coverage Rates by Parameters of Interest

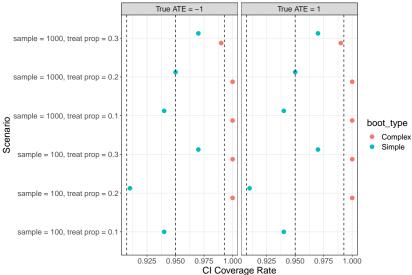


standard error plot-1.pdf
Binary Simulation Standard Error

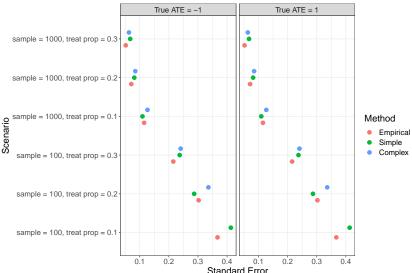


coverage plot-1.pdf





standard error plot-1.pdf
Continuous Simulation Standard Error



Summary of Results

► Sample size / treatment (or exposure) prevalence

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- ► Non-normal distributions of covariates