

Make the size of the coefficients small \Rightarrow "a continuous version of sparsity".

With many thanks to Dr Giordano Scarciotti

② SHRINKAGE METHODS:

LINEAR REGRESSION (LS): Given X, \vec{y} one finds $\vec{\beta}^*$

$$\min_{\vec{\beta}} \|\vec{y} - X\vec{\beta}\|^2 = \min_{\vec{\beta}} L_{LS}(\vec{\beta}) \quad (X^T X)^{-1} X^T$$

THE SOLUTION IS:

$$\vec{\beta}^* = \text{ARGMIN} \|\vec{y} - X\vec{\beta}\|^2 = X^T X^{-1} \vec{y}$$

$$\hat{y} = \hat{f}(\vec{x}_w) = \vec{x}_w^T \vec{\beta}^*$$

2.1 RIDGE REGRESSION

$$L_{\text{RIDGE}}(\vec{\beta}) = \|\vec{y} - X\vec{\beta}\|^2 + \lambda \|\vec{\beta}\|^2$$

(THE IDEA IS TO "ELIMINATE" SOME DESCRIPTORS. IN PRACTICE WE WEIGHT THEM LOW)

$$\min_{\vec{\beta}} L_{\text{RIDGE}}(\vec{\beta}) = \min_{\vec{\beta}} \|\vec{y} - X\vec{\beta}\|^2 + \lambda \|\vec{\beta}\|^2$$

|| EQUIVALENT

Penalty term

$$\min_{\vec{\beta}} \|\vec{y} - X\vec{\beta}\|^2$$

SUBJECT TO

$$\|\vec{\beta}\|^2 \leq t$$

λ and t are inversely related

THIS PROBLEM CAN BE SOLVED EXPLICITLY:

$$L_{\text{RIDGE}}(\vec{\beta}) = \vec{y}^T \vec{y} - \vec{\beta}^T X^T \vec{y} - \vec{y}^T X \vec{\beta} + \vec{\beta}^T (X^T X + \lambda I) \vec{\beta}$$

$$\nabla_{\vec{\beta}} L_{\text{RIDGE}} = -2 X^T \vec{y} + 2 (X^T X + \lambda I) \vec{\beta}$$

$$X^T \vec{y} = (X^T X + \lambda I) \vec{\beta}^*$$

$$\vec{\beta}_{\text{RIDGE}}^* = (X^T X + \lambda I)^{-1} X^T \vec{y}$$

WE CAN CHECK THAT THE HESSIAN IS POSITIVE DEFINITE

$$\text{BIAS: } \vec{y} = X\vec{\beta} + \vec{\varepsilon} \quad E[\vec{\varepsilon}] = 0$$

$$E[\vec{\beta}_{\text{RIDGE}}^*] = E[(X^T X + \lambda I)^{-1} (X^T X) \vec{\beta} + (X^T X + \lambda I)^{-1} X^T \vec{\varepsilon}] = (X^T X + \lambda I)^{-1} (X^T X) \vec{\beta}$$

$$(X^T X) = V D V^T$$

↑
EIGEN DECOMPOSITION

$$V V^T = V^T V = I \quad (X^T X)^{-1} = V D^{-1} V^T$$

D DIAGONAL
 $\sigma(D) \equiv \sigma(X^T X)$

• V contains the eigenvectors as columns

• $D = \text{diag}(d_i)$ has the eigenvalues on the diagonal.

$$\text{BIAS} = E[\tilde{\beta}_{\text{ridge}}] - (X^T X + \lambda I)^{-1} X^T X \beta = V[(D + \lambda I)^{-1} D - I] V^T \beta$$

$$D = (D + \lambda I)^{-1} D - I \quad \leftarrow \text{everything is diagonal}$$

$$D_{ii} = \left[\frac{d_i}{d_i + \lambda} - 1 \right] = -\frac{\lambda}{d_i + \lambda}$$

$$\Rightarrow \text{BIAS} = -\lambda V[(D + \lambda I)^{-1}] V^T \beta = -\lambda (X^T X + \lambda I)^{-1} \beta$$

As expected as $\lambda \rightarrow 0$ BIAS $\rightarrow 0$ because we recover least squares

As $\lambda \rightarrow \infty$ BIAS $\rightarrow -\beta$ ($\approx 100\%$ error)

Variances:

$$\text{VAR}(\tilde{\beta}_{\text{ridge}}) = E[(\tilde{\beta}_{\text{ridge}} - E[\tilde{\beta}_{\text{ridge}}])^2]$$

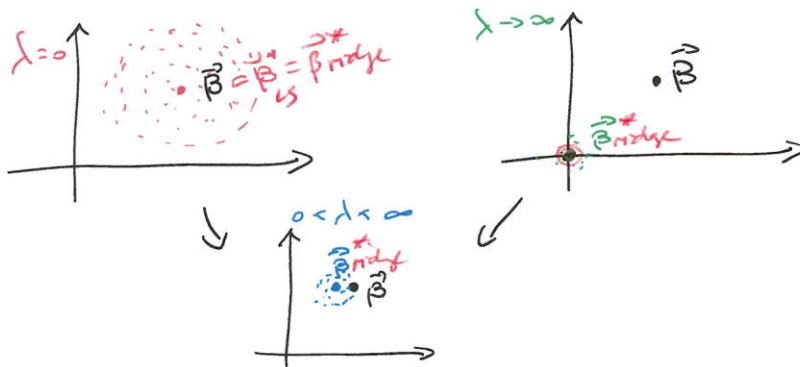
$$= E[(X^T X + \lambda I)^{-1} X^T \underbrace{\tilde{\epsilon} \tilde{\epsilon}^T}_{\sigma^2 I} X (X^T X + \lambda I)^{-1}] =$$

$$= \sigma^2 (X^T X + \lambda I)^{-1} (X^T X) (X^T X + \lambda I)^{-1} =$$

$$= \sigma^2 V \underbrace{[(D + \lambda I)^{-1} D (D + \lambda I)^{-1}]}_P V^T$$

$$P_{ii} = \frac{d_i}{(d_i + \lambda)^2}$$

As $\lambda \rightarrow \infty$ $P_{ii} \rightarrow 0$ (quadratically)



2.2 LASSO (TIBSHIRANI)

$$L_{\text{lasso}}(\tilde{\beta}) = \|\tilde{y} - X\tilde{\beta}\|^2 + \lambda \|\tilde{\beta}\|_1$$

$$\|\tilde{\beta}\|_1 = \sum_{i=1}^p |\beta_i|$$

$$\min_{\tilde{\beta}} L_{\text{lasso}}(\tilde{\beta}) \Leftrightarrow \min_{\tilde{\beta}} \|\tilde{y} - X\tilde{\beta}\|^2 \quad \text{subject to } \|\tilde{\beta}\|_1 \leq \frac{\lambda}{2}$$

~~We can't find an analytical solution but this is a convex~~

No analytical solution for LASSO (contrary to Ridge)

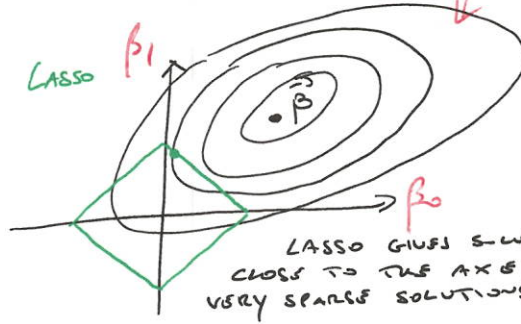
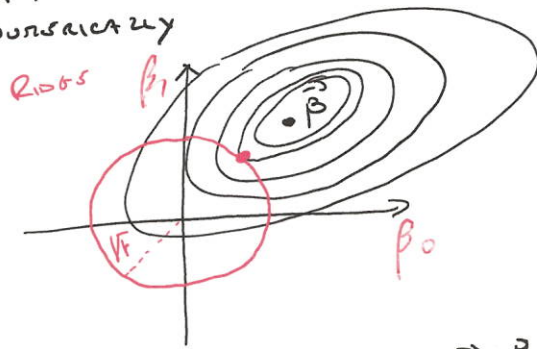
but it is a convex problem

[optimize a convex function over a convex set]

So we can use convex optimisation techniques (quadratic programming) to optimise globally.

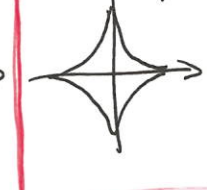
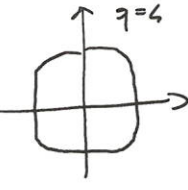
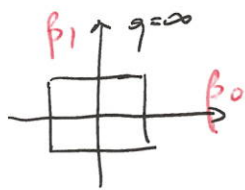
optimisation viewpoint:

WE CAN OPTIMISE PROBLEM THAT HAS A SOLUTION THAT IS NON-NEGATIVELY



level of LS: $\|y - X\beta\|^2 = k$

OTHER VARIATIONS: $\lambda \|\beta\|^q$ FOR DIFFERENT q



convex sets

optimisation is doable

non-convex sets

optimisation is difficult

$q=0$ is the " l_0 "-pseudonorm case

this whole area is called regularisation

or controlling for model complexity

where we only have solutions where some of the parameters β_i are zero \equiv Subset selection

i.e., "Sparse" models

Difficult to optimise for sparsity

Another direction is to mix the penalty terms in objective function:

Example:

Elastic net:

$$L_{EN}(\vec{\beta}) = \|\vec{y} - X\vec{\beta}\|_2^2 + \lambda \left[\alpha \|\vec{\beta}\|_1 + (1-\alpha) \|\vec{\beta}\|_2 \right]$$