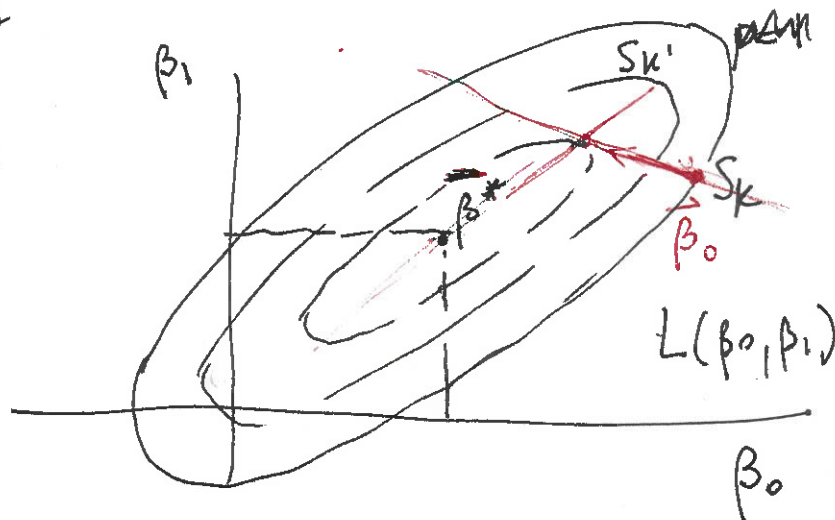


$p=1$



$$\vec{\beta} = (\beta_0, \beta_1)$$

$$S_k = \left\{ \vec{\beta} \mid L(\vec{\beta}) = k \right\}$$

$$L(\vec{\beta}) = \frac{1}{N} \left[ (\vec{y} - X\vec{\beta})^T (\vec{y} - X\vec{\beta}) \right] \quad \textcircled{*}$$

a couple of steps : ~~many~~

$$L(\vec{\beta}) = L(\vec{\beta}^*) + \frac{1}{2} (\vec{\beta} - \vec{\beta}^*)^T \underbrace{H}_{\frac{2}{N} X^T X} (\vec{\beta} - \vec{\beta}^*)$$

$$\begin{aligned} \textcircled{*} L(\vec{\beta}) &= \frac{1}{N} \left[ (\vec{y} - X\vec{\beta}^* + X\vec{\beta}^* - X\vec{\beta})^T (\vec{y} - X\vec{\beta}^* + X\vec{\beta}^* - X\vec{\beta}) \right] = \\ &= \frac{1}{N} \left[ (\vec{y} - X\vec{\beta}^*)^T (\vec{y} - X\vec{\beta}^*) + \cancel{(\vec{y} - X\vec{\beta}^*)^T X (\vec{\beta}^* - \vec{\beta})} + \right. \\ &\quad \left. + \cancel{[X (\vec{\beta}^* - \vec{\beta})]^T (\vec{y} - X\vec{\beta}^*)} + (\vec{\beta}^* - \vec{\beta})^T X^T X (\vec{\beta}^* - \vec{\beta}) \right] \end{aligned}$$

Normal equations:  $X^T \vec{y} - X^T X \vec{\beta}^* = 0 \Rightarrow X^T [\vec{y} - X\vec{\beta}] = 0$

see next page →

Convexity  $\Rightarrow$  local minimum is always ~~equivalent to~~ a global minimum

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This loss function can be minimised with gradient methods.

$\nabla_{\beta} L$  marks the direction of maximum change of  $L$

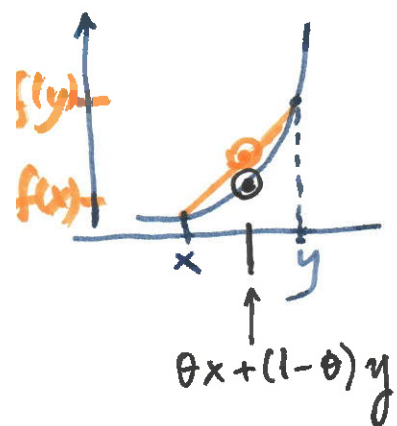
Algorithm: Iteratively follow the direction of  $-\nabla_{\beta} L$

1st order

$$\vec{\beta}_{k+1} = \vec{\beta}_k - \boxed{\eta_k} \nabla_{\beta} L(\vec{\beta}_k)$$

- Line search
  - Back tracking
  - Conjugate gradient
- ← Gradient methods.

## Convexity:



$f: \mathbb{R}^n \rightarrow \mathbb{R}$  is convex if

$\vec{x}, \vec{y} \in \mathbb{R}^n$  and  $\theta \in (0, 1)$

$$\theta f(\vec{x}) + (1-\theta) f(\vec{y}) \geq f(\theta \vec{x} + (1-\theta) \vec{y})$$

---

If  $f$  is convex, a local minimum is always a global minimum

Let  $\vec{x}_{\text{local}}, \vec{x}_{\text{global}} \in \mathbb{R}^n$ ,  $f(\vec{x}_{\text{global}}) < f(\vec{x}_{\text{local}})$

By contradiction:

• If  $\vec{x}_{\text{local}}$  is a local minimum then:

$$f(\vec{x}_{\text{local}}) \leq f(\vec{x}), \quad \|\vec{x} - \vec{x}_{\text{local}}\| < \gamma$$

• If  $f$  is convex,

$$\exists \theta, \quad \theta \vec{x}_{\text{local}} + (1-\theta) \vec{x}_{\text{global}} = \vec{x}_\theta$$

$$\|\vec{x}_\theta - \vec{x}_{\text{local}}\| < \gamma$$

But then:

$$\Rightarrow f(\vec{x}_{\text{local}}) \leq f(\vec{x}_\theta)$$

$$\leq \theta f(\vec{x}_{\text{local}}) + (1-\theta) f(\vec{x}_{\text{global}})$$

$$< \theta f(\vec{x}_{\text{local}}) + (1-\theta) f(\vec{x}_{\text{local}})$$

$$= f(\vec{x}_{\text{local}})$$

$$\cancel{f(\vec{x}_{\text{local}}) < f(\vec{x}_{\text{local}})}$$

Another way is using  
Newton's method:

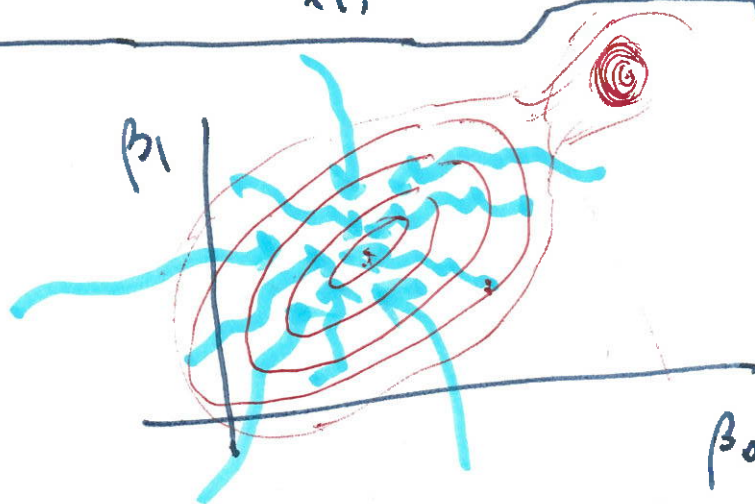
2nd order

$$L \approx L(\vec{\theta}_k) + \nabla L|_{\vec{\theta}_k} (\vec{\theta} - \vec{\theta}_k) + \frac{1}{2} (\vec{\theta} - \vec{\theta}_k)^T H(\vec{\theta}_k) (\vec{\theta} - \vec{\theta}_k)$$

$$\nabla L \approx \nabla L|_{\vec{\theta}_k} + H(\vec{\theta}_k) (\vec{\theta} - \vec{\theta}_k)$$

$$\nabla L(\vec{\theta}_k) + H(\vec{\theta}_k) (\vec{\theta}_{k+1} - \vec{\theta}_k) = 0$$

$$\vec{\theta}_{k+1} = \vec{\theta}_k - H(\vec{\theta}_k)^{-1} \nabla L(\vec{\theta}_k)$$



Non-convex.

Global minimum can be  
difficult to find

The same formulation applies for  
 $p > 1$ .

$$\left\{ \begin{matrix} x_1^{(i)} & x_2^{(i)} & \dots & x_p^{(i)} \\ \vdots & \vdots & & \vdots \end{matrix} \right\}_{i=1}^N, \quad y^{(i)} \Big\}_{i=1}^N$$

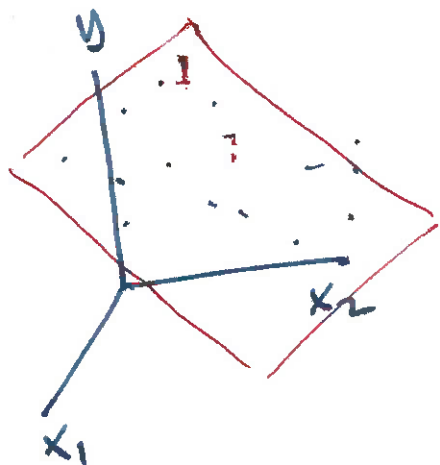
$$\beta_0 + \beta_1 x_1^{(i)} + \dots + \beta_p x_p^{(i)} = f(\vec{x}^{(i)}) \Rightarrow \hat{y}^{(i)}$$

$$\vec{\beta} = \begin{pmatrix} \beta_0 \\ \vdots \\ \beta_p \end{pmatrix} \in \mathbb{R}^{(p+1)}$$

$(p+1) \times 1$

$$X = \begin{bmatrix} 1 & x_1^{(1)} & \dots & x_p^{(1)} \\ \vdots & \vdots & & \vdots \\ 1 & x_1^{(N)} & \dots & x_p^{(N)} \end{bmatrix}_{N \times (p+1)}$$

$$\vec{y} = \begin{bmatrix} y^{(1)} \\ \vdots \\ y^{(N)} \end{bmatrix}_{N \times 1}$$



$$X\vec{\beta} = \vec{y} ? \quad \text{No solution}$$

$$\vec{e} = \vec{y} - X\vec{\beta}$$

$$\vec{\beta}_{LS}^* = (X^T X)^{-1} X^T \vec{y}$$

Linear  
regression  
model

Least squares  
solution

$$\min_{\vec{\beta}} \|\vec{y} - X\vec{\beta}\|^2$$

## Bias vs Variance

Hastie, ESL, Chapter 3

$$\mathbb{E}[\vec{\beta}^*] = \mathbb{E}[(X^T X)^{-1} X^T \vec{y}] = \vec{\beta} + \mathbb{E}[(X^T X)^{-1} X^T \vec{\epsilon}] = \vec{\beta}$$

$$\vec{y} = X \vec{\beta} + \vec{\epsilon} \quad \epsilon \sim \mathcal{N}(0, \sigma^2)$$