1. Using Taylor series,

$$u_{1/3} = u(\frac{1}{3}h) = u(0) + \frac{1}{3}hu'(0) + \frac{1}{2}(\frac{1}{3}h)^2u''(0) + O(h^3)$$
  
$$u_{2/3} = u(\frac{2}{3}h) = u(0) + \frac{2}{3}hu'(0) + \frac{1}{2}(\frac{2}{3}h)^2u''(0) + O(h^3)$$

Eliminating u''(0) by subtracting the second equation from four times the first,

$$4u_{1/3} - u_{2/3} = 3u_0 + \frac{2}{3}hu'(0) + O(h^3)$$
 or 
$$\frac{12u_{1/3} - 3u_{2/3} - 9u_0}{2h} = u'(0) + O(h^2) .$$

**2.** As  $p = p(\rho)$ ,  $\nabla p = c^2 \nabla \rho$ , where  $c^2 = dp/d\rho$ . Thus  $\mathbf{u} \cdot \nabla p = c^2 \mathbf{u} \cdot \nabla \rho = -\rho c^2 \nabla \cdot \mathbf{u}$  using the second equation (mass conservation). Taking the scalar product of the first equation (momentum conservation) with  $\mathbf{u}$ , we have

$$0 = \mathbf{u} \cdot (\rho(\mathbf{u} \cdot \nabla)\mathbf{u} + \nabla p) = \rho(\mathbf{u} \cdot \nabla)(\frac{1}{2}\mathbf{u} \cdot \mathbf{u}) + \mathbf{u} \cdot \nabla p$$
$$= \rho(\mathbf{u} \cdot \nabla)(\frac{1}{2}\mathbf{u} \cdot \mathbf{u}) + c^{2}(-\rho\nabla \cdot \mathbf{u})$$
or  $c^{2}\nabla \cdot \mathbf{u} = \mathbf{u} \cdot \nabla(\frac{1}{2}\mathbf{u} \cdot \mathbf{u})$ .

If  $\mathbf{u} = (\phi_x, \, \phi_y, \, 0)$ , this equation becomes

$$\left(\phi_x \frac{\partial}{\partial x} + \phi_y \frac{\partial}{\partial y}\right) \left(\frac{1}{2}\phi_x^2 + \frac{1}{2}\phi_y^2\right) = c^2 \left(\phi_{xx} + \phi_{yy}\right)$$
or 
$$\phi_x^2 \phi_{xx} + \phi_x \phi_y \phi_{xy} + \phi_y \phi_x \phi_{xy} + \phi_y^2 \phi_{yy} = c^2 \left(\phi_{xx} + \phi_{yy}\right)$$
or 
$$(\phi_x^2 - c^2)\phi_{xx} + (2\phi_x \phi_y)\phi_{xy} + (\phi_y^2 - c^2)\phi_{yy} = 0.$$

This is a second order quasilinear PDE for  $\phi(x,y)$ . To classify it, we look at

$$"b^2 - 4ac" = 4\phi_x^2 \phi_y^2 - 4(\phi_x^2 - c^2)(\phi_y^2 - c^2)$$
$$= 4c^2(\phi_x^2 + \phi_y^2 - c^2) = 4c^2(|\mathbf{u}|^2 - c^2)$$

Thus the equation is hyperbolic if  $|\mathbf{u}|^2 > c^2$  (supersonic flow), elliptic for subsonic flow  $(|\mathbf{u}|^2 < c^2)$  and parabolic if  $|\mathbf{u}|^2 = c^2$ .

As the scheme is centred about (n, j), the truncation error is second order, so that  $R_n^j = O(k^2, h^2)$ . The scheme is

$$U_n^{j+1} - U_n^{j-1} = 2r(U_{n+1}^j + U_{n-1}^j - 2U_n^j)$$
.

We analyse the behaviour of a Fourier disturbance proportional to  $\exp(in\xi)$ , by seeking solutions of the form  $U_n^j = f^j \exp(in\xi)$ . Then

$$(f^{j+1} - f^{j-1})e^{in\xi} = 2r(e^{i\xi} + e^{-i\xi} - 2)e^{in\xi}$$
  
or  $f^{j+1} - f^{j-1} = -(8r\sin^2\frac{1}{2}\xi)f^j$ .

This is a second order linear recurrence relation, which has the solution  $f^j = (\lambda)^j$ , provided  $\lambda$  satisfies the equation

$$\lambda^{2} + (8r\sin^{2}\frac{1}{2}\xi)\lambda - 1 = 0$$
or  $\lambda = \lambda_{\pm} = -4r\sin^{2}\frac{1}{2}\xi \pm \sqrt{16r^{2}\sin^{4}\frac{1}{2}\xi + 1}$ .

The square root is bigger than one, and so  $\lambda_{-} < -1$  for all r > 0, and the scheme is **unconditionally unstable**; small errors grow exponentially each timestep. Although the scheme has a small truncation error, it is unstable and hence useless inpractice.

4. We have

$$u_n^{j+1} = \left(u + ku_t + \frac{1}{2}k^2u_{tt} + \frac{1}{6}k^3u_{ttt}\right)_n^j + O(k^4)$$

$$u_n^{j-1} = \left(u - ku_t + \frac{1}{2}k^2u_{tt} - \frac{1}{6}k^3u_{ttt}\right)_n^j + O(k^4)$$

$$u_n^{j+1} - u_n^{j-1} = 2k(u_t)_n^j + O(k^3)$$

 $u_n^{j+1} + u_n^{j-1} = (2u + k^2 u_{tt})_n^j + O(k^4)$ .

and so

The truncation error,  $R_n^j$ , is defined by

$$R_n^j = \frac{u_n^{j+1} - u_n^{j-1}}{2k} - \frac{1}{h^2} \left[ u_{n+1}^j + u_{n-1}^j - (u_n^{j+1} + u_n^{j-1}) \right] - (u_t - u_{xx})_n^j.$$

Using the above, we have

$$R_n^j = \frac{(2ku_t)_n^j + O(k^3)}{2k} - \frac{1}{h^2} \left[ u_{n+1}^j + u_{n-1}^j - (2u + k^2 u_{tt})_n^j \right) + O(k^4) \right] - (u_t - u_{xx})_n^j$$

$$= -\frac{1}{h^2} (u_{n+1}^j + u_{n-1}^j - 2u_n^j) + (u_{xx})_n^j + \frac{k^2}{h^2} (u_{tt})_n^j + O(k^2, k^4/h^2)$$

$$= \frac{k^2}{h^2} u_{tt} + O(k^2, h^2, k^4/h^2) \quad \text{as} \quad u_{xx} = \frac{1}{h^2} (u_{n+1}^j + u_{n-1}^j - 2u_n^j) + O(h^2) .$$

Thus the scheme is **consistent** with  $u_t = u_{xx}$  only if  $k^2/h^2 \to 0$  as  $k \to 0$  and  $h \to 0$ , i.e.  $k \to 0$  faster than  $h \to 0$ . Nevertheless, this scheme is in fact unconditionally stable (we have not shown this!)

5. The scheme is two-step, and can be written in the form  $AV^{j+1} = BV^j + CV^{j-1}$  where

$$A = (1+\theta)I \\ C = -\theta I$$
 
$$B = \begin{pmatrix} 1+2\theta-2r & r & 0 & \ddots & 0 \\ r & 1+2\theta-2r & r & \ddots & 0 \\ 0 & r & 1+2\theta-2r & \ddots & \ddots \\ \ddots & \ddots & \ddots & \ddots & r \\ 0 & 0 & \ddots & r & 1+2\theta-2r \end{pmatrix}$$

and the matrices are (say) of size  $(N-1) \times (N-1)$ . The stability criterion is that all (2N-2) solutions of

$$det(\lambda^2 A - \lambda B - C) = 0$$
 satisfy  $|\lambda| \le 1$ 

or

$$det(B - \sigma I) = 0$$
 where  $\sigma = \frac{\lambda^2(1 + \theta) + \theta}{\lambda}$ .

From lectures, the eigenvalues of B are

$$\sigma = \sigma_m = 1 + 2\theta - 2r + 2r\cos(m\pi h)$$
 for  $m = 1...N - 1$ ,  $h = \frac{1}{N}$ .

We note that  $\sigma_m \leq 1 + 2\theta$ . The corresponding values of  $\lambda$  satisfy

$$F(\lambda) = 0$$
 where  $F(\lambda) \equiv (1 + \theta)\lambda^2 - \sigma_m\lambda + \theta$ .

The product of the roots is  $\theta/(1+\theta) < 1$ , so that if the roots are complex they have the same modulus which is less than 1, giving stability. Now  $F(1) = 1 + 2\theta - \sigma_m \ge 0$  and  $F'(1) = 2 + 2\theta - \sigma_m \ge 1$ . From the graph of the quadratic function  $F(\lambda)$  is U-shaped, there will be a root with  $\lambda < -1$  if F(-1) < 0, with resulting instability. That is, the scheme is unstable if

$$(1+2\theta) + \sigma_m < 0$$
 or  $2(1+2\theta) < 2r(1-\cos m\pi h) \le 2r$ .

If F(-1) > 0, then  $F'(-1) = -2(1+\theta) - \sigma_m = -F(-1) - 1 < 0$ . By considering the graph of  $F(\lambda)$ , we see the only possible real roots lie between -1 and +1 and so we have stability. We conclude the stability condition is

$$r \sin^2(\tfrac{1}{2}(N-1)\pi/N) \leqslant \theta + \tfrac{1}{2} \qquad \text{or approximately} \quad r \leqslant \theta + \tfrac{1}{2} \ .$$

If we set  $\theta = -\frac{1}{2}$ , as in question 3, we conclude the method will be unconditionally unstable, as was indeed the case.

**6.** The equation for C(x, y) can be written

$$C_y = \frac{D}{u(x)}C_{xx} + \frac{Q}{u}$$
 with  $u = u_0(d^2 - x^2) \ge 0$ .

Since the effective diffusivity,  $D/u \ge 0$ , we must integrate in the "positive time direction" y > 0, that is we must solve downstream. We choose a steplength h = 2d/10 and a timestep k to be determined. Stability of an explicit method is guaranteed if

$$\frac{k}{h^2} \max_{grid} \left[ \frac{D}{u} \right] \leqslant \frac{1}{2} .$$

Now the maximum of D/u occurs near the boundary at  $x = \pm (d - h)$  as u is zero on the boundary. One gridpoint in,  $u = u_0 h(2d - h)$ . So we must have

$$k \leqslant \frac{1}{2}h^3(2d-h)u_0/D = 9.5 \times 10^{-4}\frac{u_0d^4}{D}.$$

This is a poor method, as we are requiring  $k = O(h^3)$  which is very small indeed.

7. Let  $U_{lmn}^j = f^j \exp(il\xi + im\eta + in\tau)$ . Then just as in question 3,  $\delta_x^2 \to -4\sin^2\frac{1}{2}\xi$  and similarly for  $\delta_y^2$  and  $\delta_z^2$ . So the equation becomes

$$f^{j+1} - f^j = -\alpha \left(\theta f^{j+1} + (1-\theta)f^j\right)$$
,

where

$$\alpha = 4k \left( \frac{\sin^2 \frac{1}{2} \xi}{h_x^2} + \frac{\sin^2 \frac{1}{2} \eta}{h_y^2} + \frac{\sin^2 \frac{1}{2} \tau}{h_z^2} \right) \geqslant 0.$$

So

$$f^{j+1} = f^j \left[ 1 - \frac{\alpha}{1 + \alpha \theta} \right] = \lambda f^j$$
, say.

For stability we need  $|\lambda| \leq 1$ . As  $\alpha \geq 0$ , we have  $\lambda \leq 1$ . Now since  $1 + \alpha \theta > 0$ ,

$$\lambda \geqslant -1 \iff 1 - \alpha(1 - \theta) \geqslant -(1 + \alpha\theta)$$
  
 $\iff \alpha(1 - 2\theta) \leqslant 2$ .

If  $\theta \geqslant \frac{1}{2}$  this is satisfied and we have unconditional stability. If  $0 \leqslant \theta < \frac{1}{2}$ , we need  $\alpha \leqslant 2/(1-2\theta)$  for stability. The worst case is the mode with  $\xi = \eta = \tau = \pi$ , so we must require for stability

$$k\left[\frac{1}{h_x^2} + \frac{1}{h_y^2} + \frac{1}{h_z^2}\right] \leqslant \frac{1}{2(1-2\theta)}$$
.