

# EEEN 322

# Communication Engineering

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Spring 2019

Week 4

# Last Week

- Fourier Series for periodic signals
- Fourier Transform for aperiodic signals (also for periodic signals)
- Some Fourier Transform pairs
- Properties of Fourier Transform
  - If the signal is real: magnitude spectrum is even, phase spectrum is odd
  - Time delay in the signal causes a linear phase shift in the frequency spectrum
  - Multiplication of the signal by a cosine with  $\omega_0$  causes a frequency shift in the frequency spectrum to  $\pm\omega_0$  (magnitude halved)
- Signal transmission through a linear system
  - Distortionless transmission
  - Linear distortion due to multipath effects
- Nonlinear distortion
- Ideal versus practical filters - Butterworth filter as a good approximation to ideal low pass filter
- Energy spectral density (ESD), relationship between ESDs of input and output of an LTI system

# WEEK 4

## Energy Spectral Density (ESD)

Energy

$$E_g = \int_{-\infty}^{\infty} |g(t)|^2 dt = \frac{1}{2\pi} \int_{-\infty}^{\infty} |G(w)|^2 dw \quad (\text{Parseval})$$

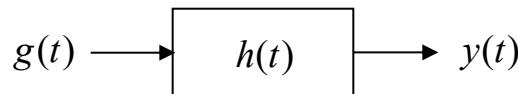
This is called "Energy Spectral Density" (ESD)

Energy Spectral Density (ESD)

$$\Psi_g(w) = |G(w)|^2$$

Note that you may also write:  $E_g = \frac{1}{2\pi} \int_{-\infty}^{\infty} \Psi_g(w) dw$

ESD of input / output:



$$Y(w) = H(w)G(w) \implies |Y(w)|^2 = |H(w)|^2|G(w)|^2$$

$$\Psi_y(w) = |H(w)|^2\Psi_g(w)$$

## Energy Spectral Density (ESD) of $x(t)=g(t)\cos\omega_0t$

$$x(t) = g(t)\cos\omega_0 t$$

$$\Rightarrow X(w) = \frac{1}{2}[G(w - w_0) + G(w + w_0)]$$

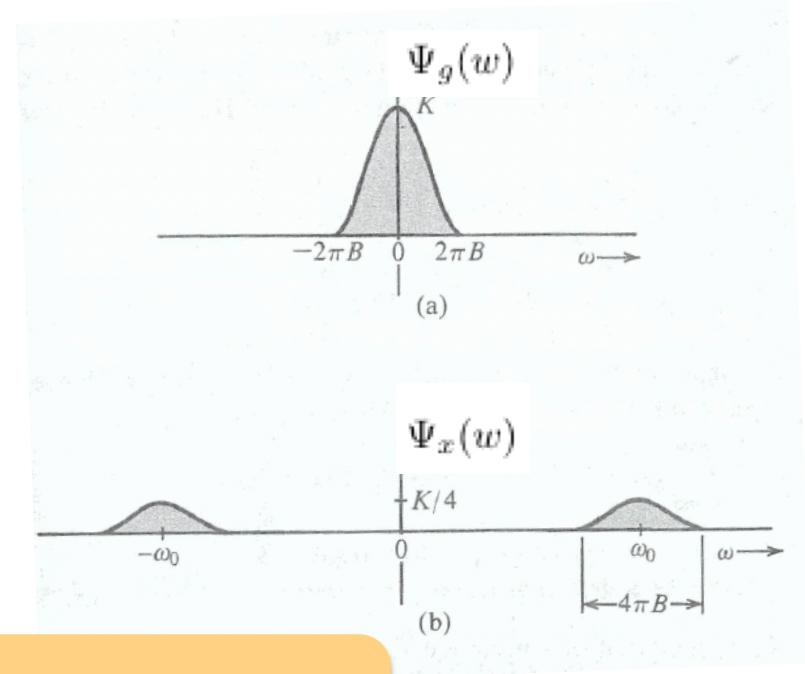
$$\Rightarrow |X(w)|^2 = \frac{1}{4}[|G(w - w_0)|^2 + |G(w + w_0)|^2]$$

$$\Rightarrow \Psi_x(w) = \frac{1}{4}[\Psi_g(w - w_0) + \Psi_g(w + w_0)]$$

Note that:  $E_x = \frac{1}{2}E_g$

because...

$$\begin{aligned}
 E_x &= \frac{1}{2\pi} \int_{-\infty}^{\infty} \Psi_x(w) dw \\
 &= \frac{1}{2\pi} \int_{-\infty}^{\infty} \left\{ \frac{1}{4} [\Psi_g(w - w_0) + \Psi_g(w + w_0)] \right\} dw \\
 &= \frac{1}{8\pi} \int_{-\infty}^{\infty} \Psi_g(w - w_0) dw + \frac{1}{8\pi} \int_{-\infty}^{\infty} \Psi_g(w + w_0) dw \\
 &= \frac{1}{4}E_g + \frac{1}{4}E_g \\
 &= \frac{1}{2}E_g
 \end{aligned}$$



$$E_g = \frac{1}{2\pi} \int_{-\infty}^{\infty} \Psi_g(w) dw$$

# Energy Spectral Density (ESD) and Power Spectral Density (PSD)

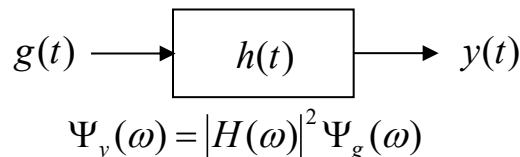
## Energy

$$E_g = \int_{-\infty}^{+\infty} |g(t)|^2 dt = \frac{1}{2\pi} \int_{-\infty}^{+\infty} |G(\omega)|^2 d\omega \quad (\text{Parseval})$$

## Energy Spectral Density (ESD)

$$\begin{aligned}\Psi_g(\omega) &= |G(\omega)|^2 \\ \Rightarrow E_g &= \frac{1}{2\pi} \int_{-\infty}^{+\infty} \Psi_g(\omega) d\omega\end{aligned}$$

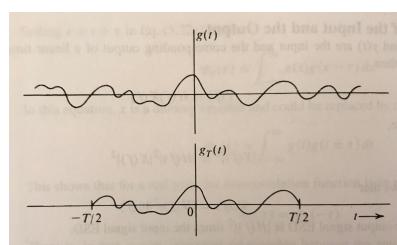
## ESD of Input / Output



## Energy Spectrum of $x(t)=g(t)\cos\omega_0 t$

$$\Psi_x(\omega) = \frac{1}{4} [\Psi_g(\omega + \omega_0) + \Psi_g(\omega - \omega_0)]$$

$$E_x = \frac{1}{2} E_g$$



## Power

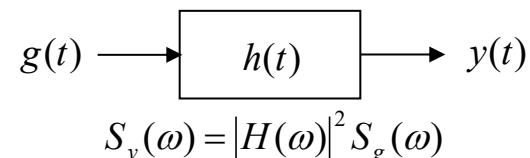
$$P_g = \lim_{T \rightarrow \infty} \frac{1}{T} \int_{-T/2}^{+T/2} |g(t)|^2 dt$$

## Power Spectral Density (PSD)

$$\begin{aligned}S_g(\omega) &= \lim_{T \rightarrow \infty} \frac{|G_T(\omega)|^2}{T} \quad (*) \\ \Rightarrow P_g &= \frac{1}{2\pi} \int_{-\infty}^{+\infty} S_g(\omega) d\omega\end{aligned}$$

The power spectrum can be computed this way as long as the limit exists

## PSD of Input / Output



## Power Spectrum of $x(t)=g(t)\cos\omega_0 t$

$$S_x(\omega) = \frac{1}{4} [S_g(\omega + \omega_0) + S_g(\omega - \omega_0)]$$

$$P_x = \frac{1}{2} P_g$$

(\*)  $g_T(t)$  is  $g(t)$  truncated to  $\left[-\frac{T}{2}, \frac{T}{2}\right]$

# Essential Bandwidth of a Signal

- Because the energy of a practical signal is finite, the signal spectrum must approach zero as the frequency goes to infinity
- Most of the signal energy is contained within a certain band of  $B$  Hz, and the energy content of the higher frequencies can be negligible
- The bandwidth  $B$  is called the **essential bandwidth** of the signal
- The criterion for selecting  $B$  depends on the error tolerance in a particular application (examples are, 90%, 95%, 99%, etc)

**Example: Rectangular pulse**

$$g(t) = \text{rect} \frac{t}{T}$$

$$\text{rect} \frac{t}{T} \leftrightarrow T \text{sinc} \frac{\omega T}{2}$$

→ Energy spectrum:  $\Psi_g(\omega) = |G(\omega)|^2 = T^2 \text{sinc}^2 \frac{\omega T}{2}$

$$\text{Energy within a bandwidth of } W: E_W = \frac{1}{2\pi} \int_{-W}^W \Psi_g(\omega) d\omega = \frac{T^2}{2\pi} \int_{-W}^W \text{sinc}^2 \frac{\omega T}{2} d\omega$$

$$\frac{E_W}{E_g} = \frac{T}{2\pi} \int_{-W}^W \text{sinc}^2 \frac{\omega T}{2} d\omega$$

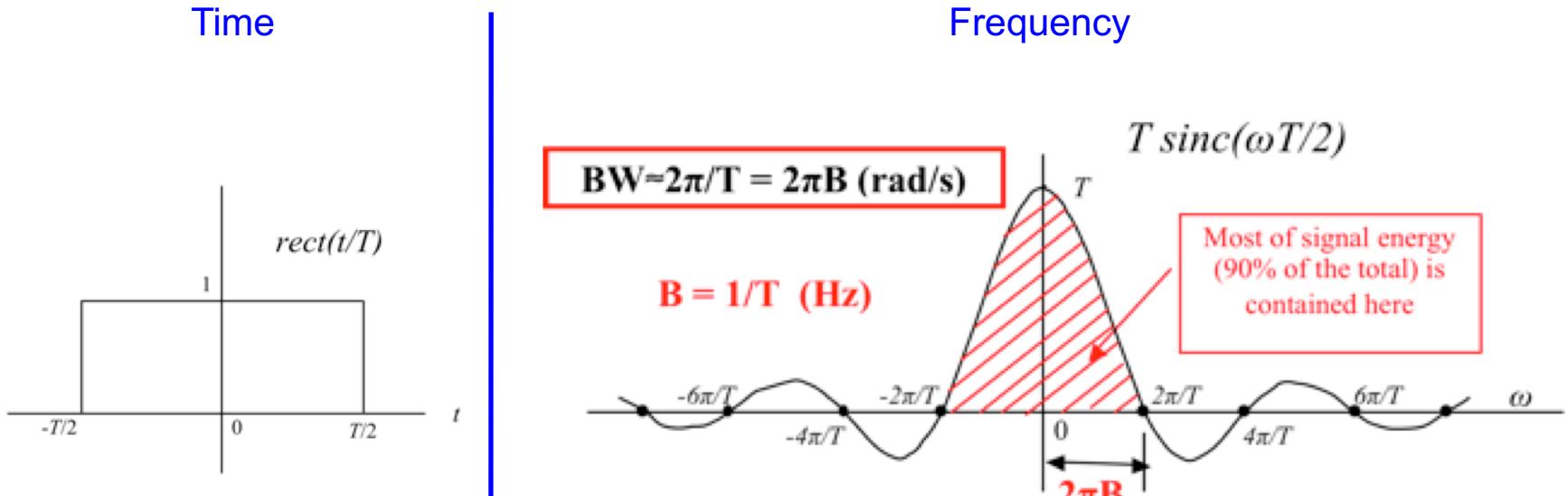
Compute numerically

$$\Rightarrow \frac{E_W}{E_g} = 90\% \text{ if } W = \frac{2\pi}{T}$$

90% of signal energy is contained within the bandwidth of  $B = 1 / T$

# Essential bandwidth of a rectangular pulse

(by the 90% criterion)



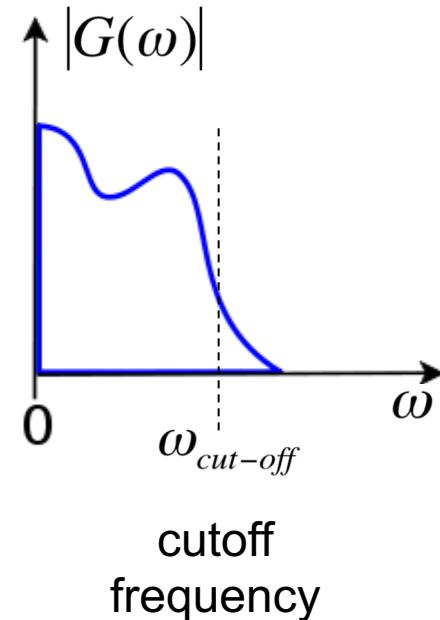
We define bandwidth ( $B$ )  
considering positive  
frequencies only.

## Baseband Signal

A **baseband signal** is a signal that can include frequencies that are very near zero, by comparison with its highest frequency

A **signal at baseband** is usually considered to include frequencies from near 0 Hz up to the highest (cut-off) frequency in the signal (with significant energy/power)

**Baseband communication:** no shift of the spectrum of the signal to be transmitted (the baseband signal) to the higher frequencies by modulation



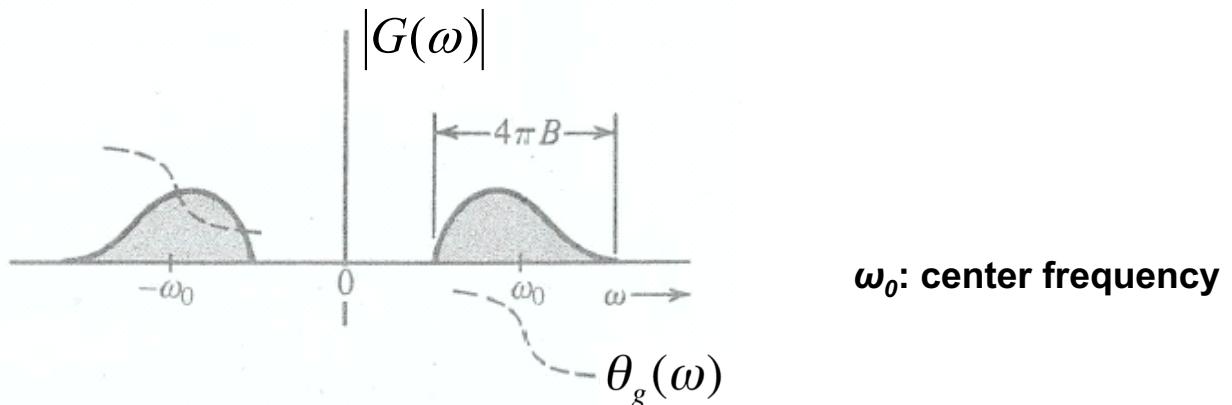
Note:  $G(0)$  is the "DC content" of the signal

## Bandpass Signal

A **bandpass signal** is a signal  $g(t)$  whose frequency domain representation  $G(\omega)$  is nonzero for frequencies in a usually small neighborhood of some high frequency  $\omega_0$ , that is:

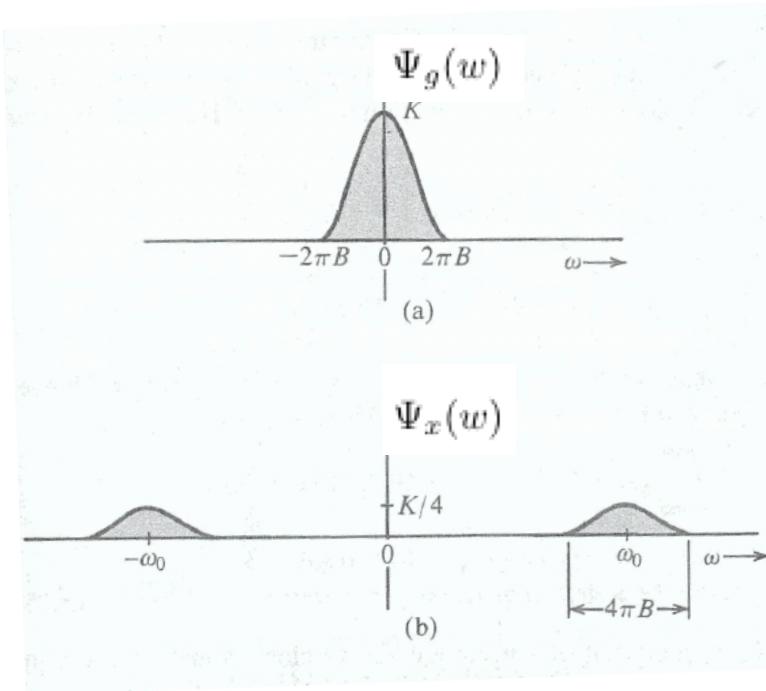
$$G(\omega) \equiv 0 \quad \text{for} \quad |\omega - \omega_0| > 2\pi B \quad (\omega_0 \gg 2\pi B)$$

$$G(\omega) = |G(\omega)| e^{j\theta_g(\omega)}$$



$\omega_0$ : center frequency

$$x(t) = g(t) \cos \omega_0 t \Leftrightarrow X(\omega) = \left( \frac{1}{2} \right) \left[ G(\omega - \omega_0) + G(\omega + \omega_0) \right]$$



*g(t)* (the message signal to be modulated) is a baseband signal

Bandwidth:  $2\pi B$  rad/s ( $B$  Hz)

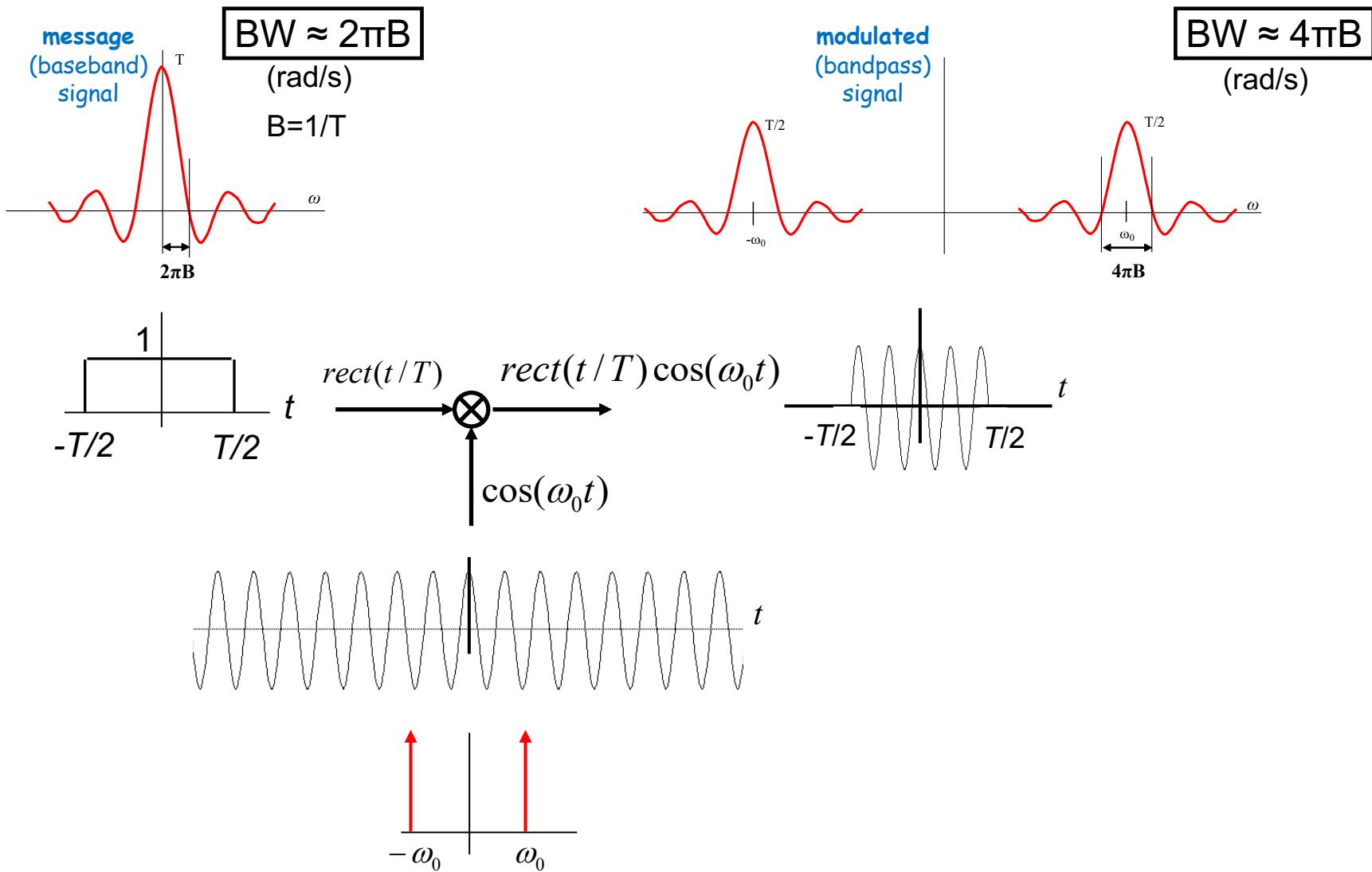
*x(t)* (the modulated signal to be sent via the antenna) is a bandpass signal

Bandwidth:  $4\pi B$  rad/s ( $2B$  Hz)

- $\omega_0$ : center frequency
- In this context it may also be called “carrier frequency”

The modulation example shown here is **DSB-SC** modulation.

Example:  $g(t) \cos \omega_0 t \leftrightarrow \frac{1}{2} [G(\omega - \omega_0) + G(\omega + \omega_0)]$  where  $g(t)$  is a rectangular function



The modulation example shown here is **DSB-SC** modulation.

# Communication System with Signal Modulation & Demodulation

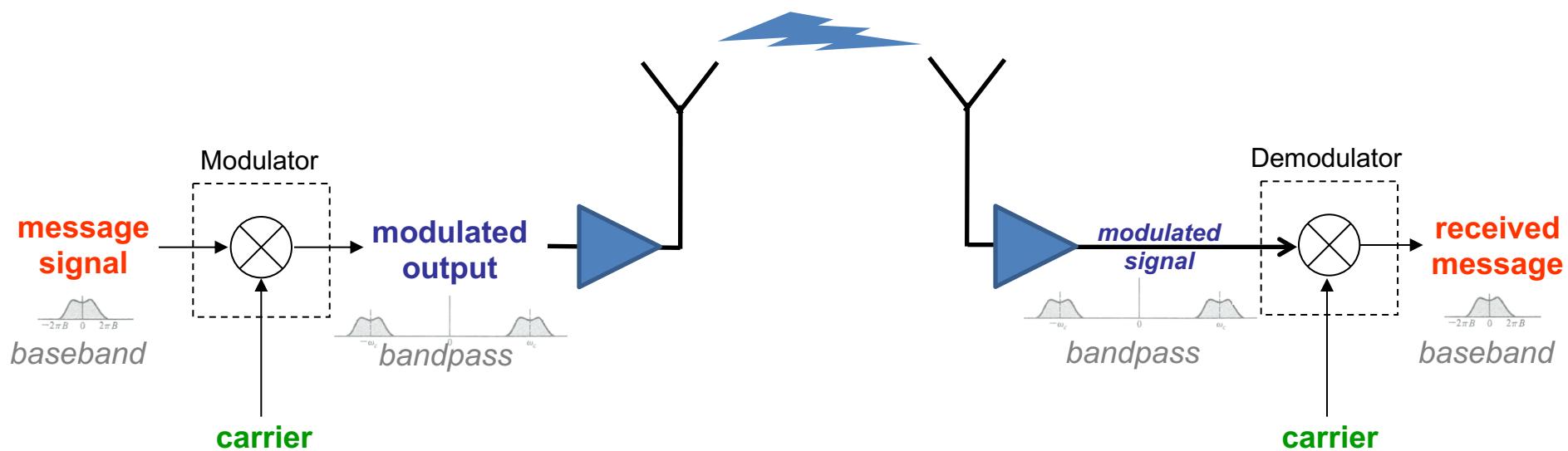


Illustration is for the case of **DSB-SC** modulation with **coherent** demodulation.

# Modulation and Demodulation

**Modulation:** process of impressing an analog signal on the amplitude, frequency or phase of a sinusoidal carrier.

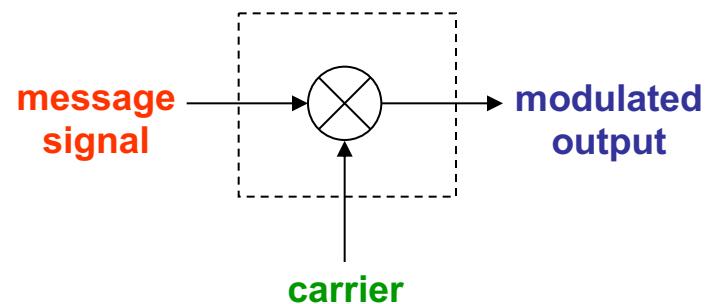
Amplitude Modulation (AM)  
Frequency Modulation (FM)  
Phase Modulation (PM)

**Demodulation:** process of recovering the signal that was impressed on the sinusoidal carrier.

# Amplitude Modulation (AM)

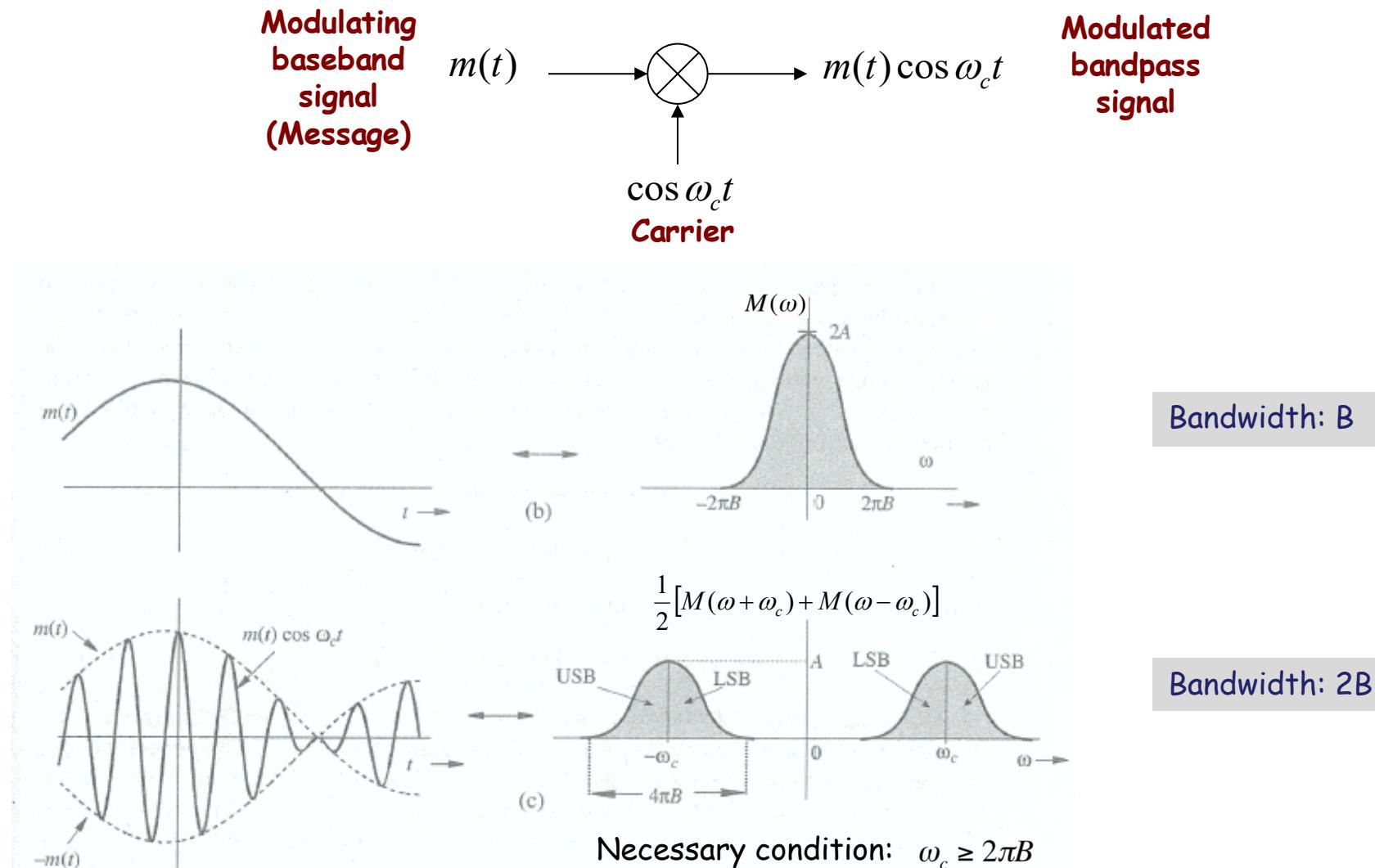
	Suppressed Carrier	With Carrier
Double Sideband (DSB)	DSB-SC	DSB+C (a.k.a. AM)
Single Sideband (SSB)	SSB-SC	SSB+C
Vestigial Sideband (VSB)	VSB-SC	VSB+C

In general: The **amplitude** of the **carrier** is changed by the **message signal**

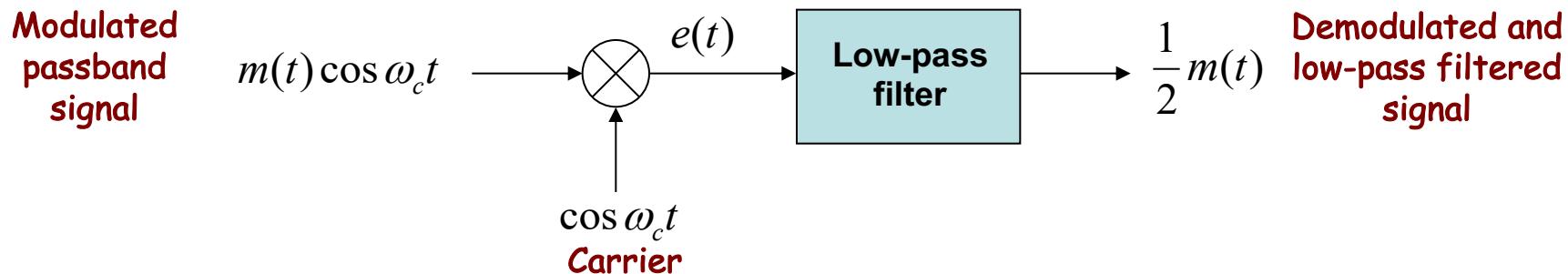


$$\varphi_{DSB-SC}(t) = m(t) \cos \omega_c t$$

## Double Sideband Suppressed Carrier (DSB-SC) Modulation

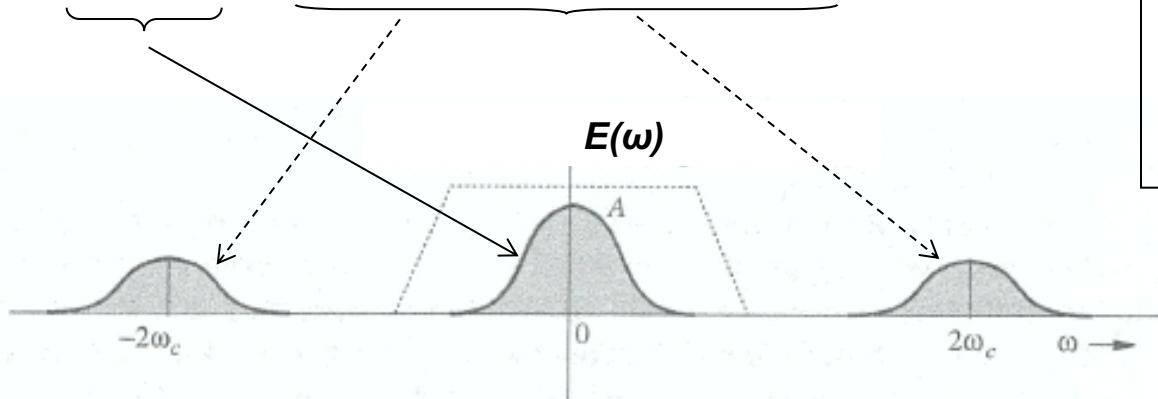


## Double Sideband Suppressed Carrier (DSB-SC) Demodulation



$$e(t) = m(t) \cos^2 \omega_c t = m(t) \left[ \frac{1 + \cos 2\omega_c t}{2} \right] = \frac{1}{2} m(t) + \frac{1}{2} m(t) \cos 2\omega_c t$$

$$\Rightarrow E(\omega) = \underbrace{\frac{1}{2} M(\omega)}_{\text{DC component}} + \underbrace{\frac{1}{4} [M(\omega + 2\omega_c) + M(\omega - 2\omega_c)]}_{\text{Sidebands}}$$

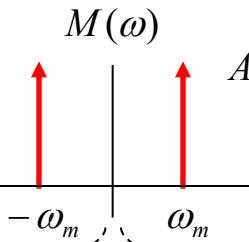


**Coherent demodulation** uses a carrier of the *same* frequency and phase (homodyne) as that for modulation

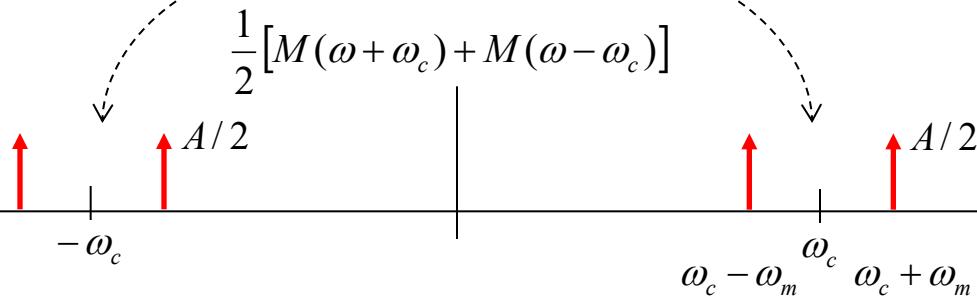
## DSB-SC Tone Modulation-Demodulation

when  $m(t)$  itself is a cosine as well (with angular frequency  $\omega_m$ )

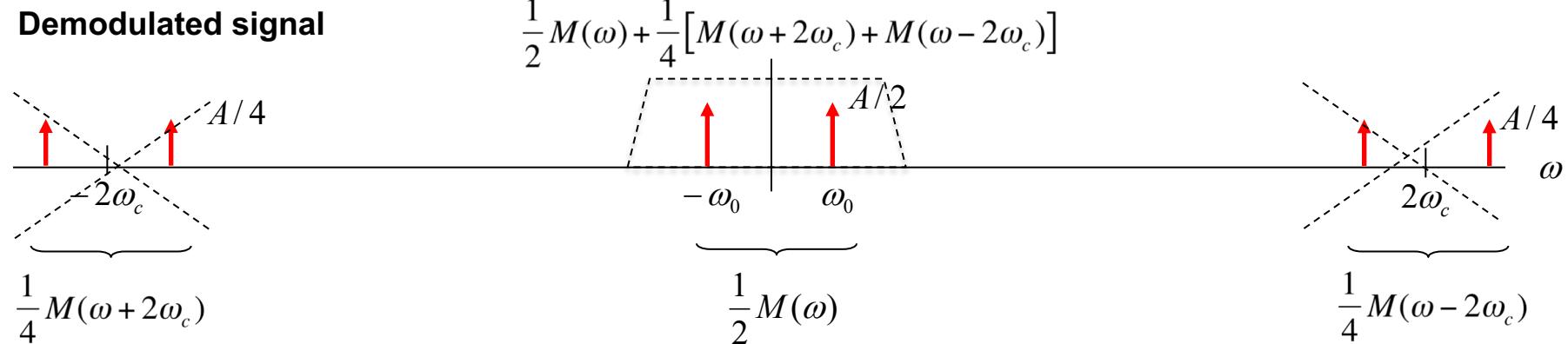
**Modulating signal**



**Modulated signal**



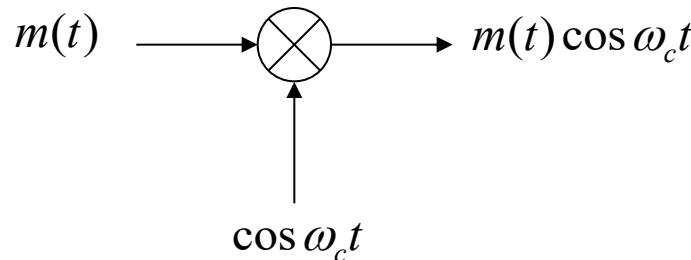
**Demodulated signal**



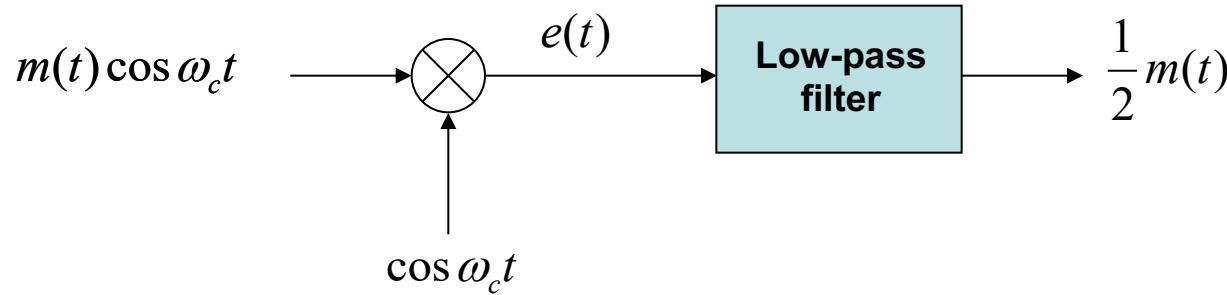
Dashed lines depict the low-pass filtering operation

# Modulation - Demodulation Circuits for DSB-SC Modulation

## Modulation



## Demodulation



→All the modulators discussed can also be used as demodulators  
(provided that proper output filtering is performed)

# **Modulation - Demodulation Circuits for DSB-SC Modulation**

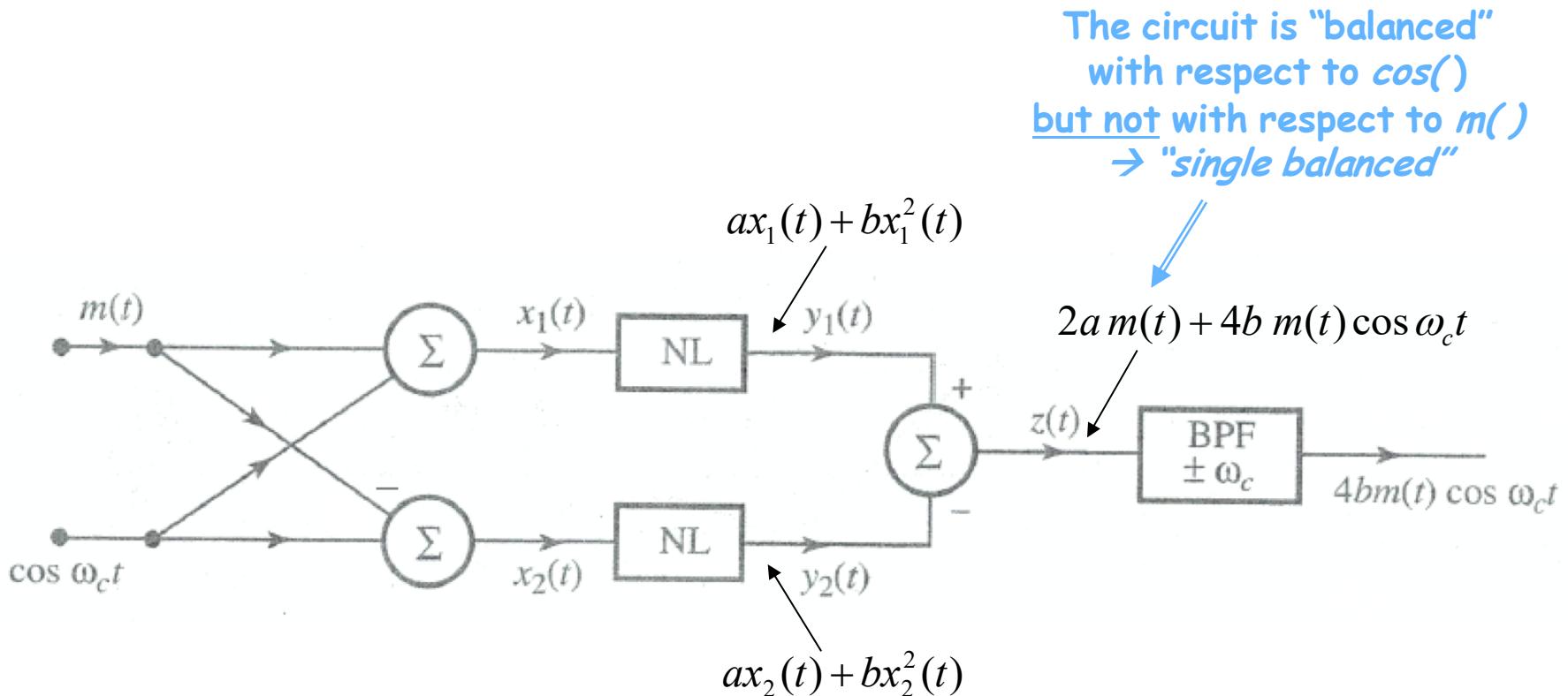
- **Modulation:**
  - Multiplier modulator
  - Nonlinear modulator
  - Switching modulator
    - Diode-bridge modulator
    - Ring modulator
- **Demodulation**
  - All the modulators above

## Multiplier Modulator for DSB-SC Modulation

- Modulation is achieved directly by multiplying  $m(t)$  by  $\cos\omega_c t$  using an analog multiplier
  - Rather difficult to maintain linearity
  - Rather expensive

→ Best to avoid them if possible

# Nonlinear Modulator for DSB-SC Modulation



# Switching Modulator for DSB-SC Modulation

