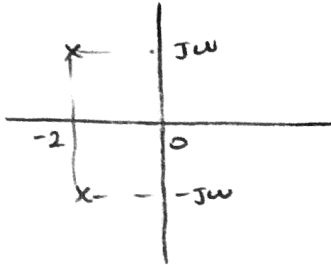


Problem 1)

a) It is a second order system.

$$\text{General Form} = \frac{\omega_n^2}{s^2 + 2\zeta\omega_n s + \omega_n^2}$$



$$P_1 = -2 + j\omega$$

$$P_2 = -2 - j\omega$$

$$G(s) = \frac{K}{(s - P_1)(s - P_2)} = \frac{K}{(s + 2 + j\omega)(s + 2 - j\omega)}$$

$$= \frac{K}{s^2 + 4s + 4 + \omega^2}$$

$$\frac{K}{s^2 + 4s + 4 + \pi^2} \longleftrightarrow \frac{K}{s^2 + 2\zeta\omega_n s + \omega_n^2}$$

$$\omega_n = \sqrt{4 + \pi^2}$$

$$\omega_n = 3.92 \text{ rad/s}$$

$$2\zeta\omega_n = 4$$

$$\zeta = \frac{2}{\omega_n} = \frac{2}{3.92} = 0.537$$

$0 < \zeta < 1 \rightarrow$ It is an underdamped system.

b) $\omega_n = 3.92 \text{ rad/s}$

$$\zeta = 0.537$$

$$\omega_d = \omega_n \sqrt{1 - \zeta^2} = 3.92 \sqrt{1 - 0.537^2} = (3.92)(0.68)$$

$$\omega_d = 2.53 \text{ rad/s}$$

$$T_p = \frac{\pi}{\omega_d} = \frac{\pi}{2.53} = 1.24 \text{ s}$$

$$T_s = \frac{4}{\zeta\omega_n} = \frac{4}{2} = 2 \text{ s}$$

c)

$$C_{ss} = \lim_{s \rightarrow 0} s \cdot \frac{K}{s \cdot (s^2 + 2\zeta\omega_n s + \omega_n^2)}$$

$$C_{ss} = 10 = \frac{K}{\omega_n^2}$$

$$K = 10\omega_n^2$$

$$K = 10 \cdot K \cdot (3.92)^2$$

$$\boxed{K = 138.384}$$

$$\text{System T.F. } T(s) = \frac{C(s)}{D(s)} = \frac{138.384}{s^2 + 4s + 138.384}$$

d) peak values (C_{max})

$$1 + m_p \rightarrow m_p = e^{-\zeta\pi / \sqrt{1-\zeta^2}}$$

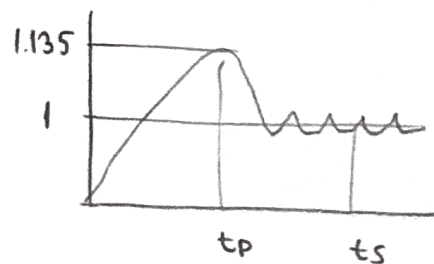
$$m_p = e^{-0.537\pi / \sqrt{1-0.537^2}}$$

$$m_p = 0.135$$

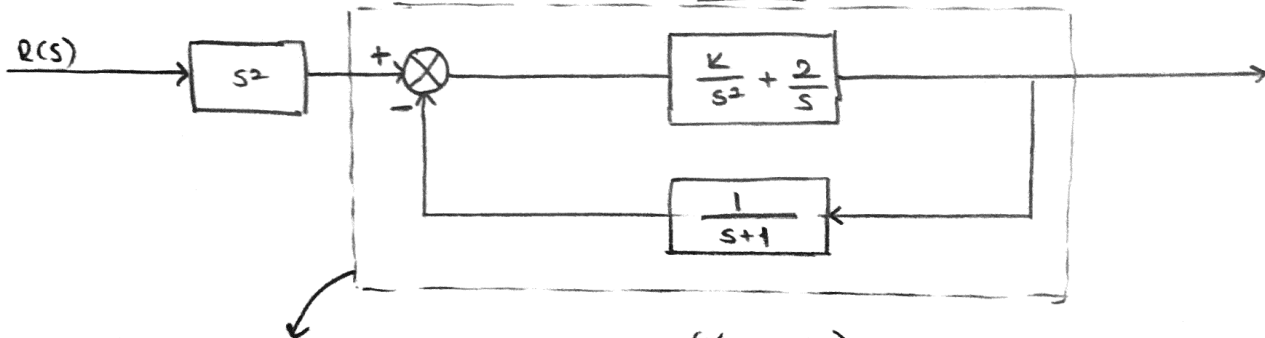
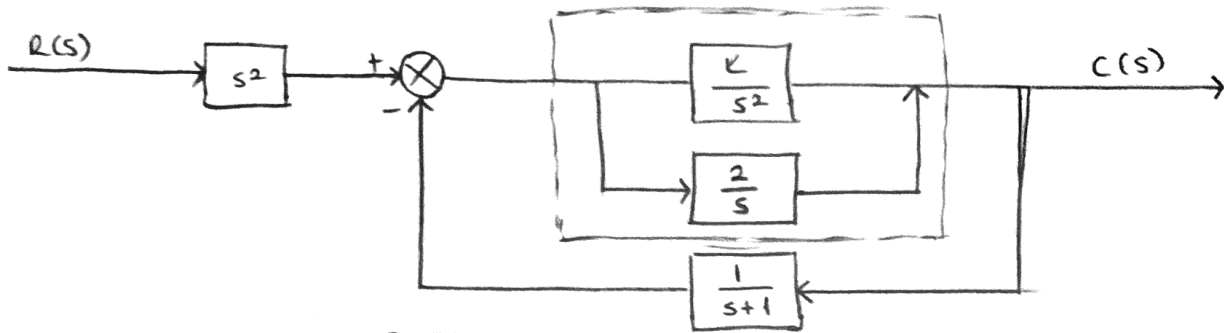
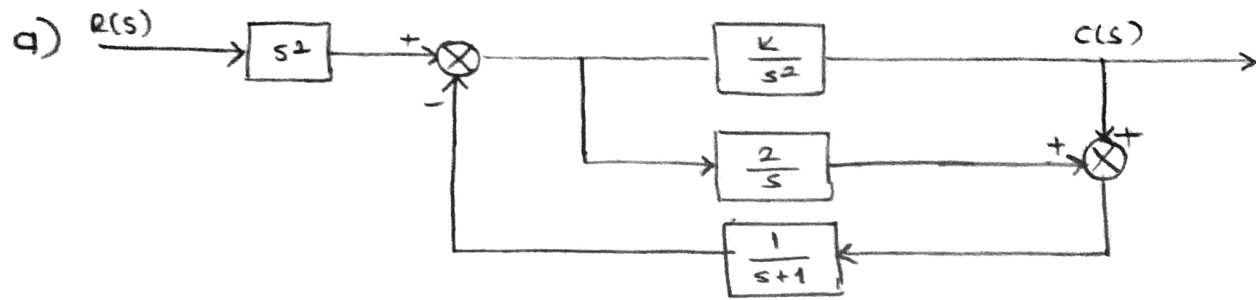
$$\% \text{ overshoot} = 13.5\%$$

$$\text{Peak value } (C_{max}) \rightarrow 1 + 0.135 = 1.135$$

$$C_{max} = 1.135$$



Problem 2)



$$T(s) = \frac{G(s)}{1 + G(s) \cdot H(s)} = \frac{\left(\frac{K}{s^2} + \frac{2}{s}\right)}{1 + \left(\frac{K}{s^2} + \frac{2}{s}\right) \cdot \frac{1}{s+1}}$$

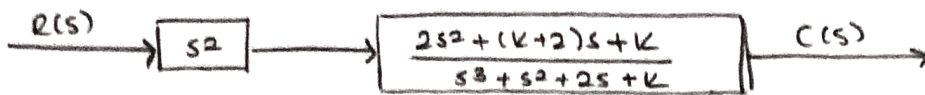
$$= \frac{\frac{K+2s}{s^2}}{1 + \frac{K}{s^2(s+1)} + \frac{2}{s(s+1)}}$$

$$= \frac{\frac{K+2s}{s^2}}{\frac{s^2(s+1) + K + 2s}{s^2(s+1)}}$$

$$= \frac{\frac{K+2s}{s^2}}{\frac{s^3 + s^2 + K + 2s}{s^2(s+1)}}$$

$$T(s) = \frac{(K+2s) \cdot (s+1)}{s^3 + s^2 + K + 2s} = \frac{2s^2 + (K+2)s + K}{s^3 + s^2 + 2s + K}$$

(4)



We are going to multiply these two;

$$\frac{C(s)}{R(s)} = T(s) = \frac{2s^4 + (k+2)s^3 + ks^2}{s^3 + s^2 + 2s + k} = \frac{(k+2s)(s+1)(s^2)}{s^3 + s^2 + 2s + k}$$

b) Applying Routh-Hurwitz criteria.

s^3	1	2
s^2	1	k
s^1	$\frac{2-k}{1}$	0
s^0	k	0

For stability; $2-k > 0$

$k < 2$ and $k > 0$

Thus, the range of k will be $0 < k < 2$

c) From above, there are two poles in $j\omega$ axis. These two poles obtained by s^2 , if s^1 is row of zeros.

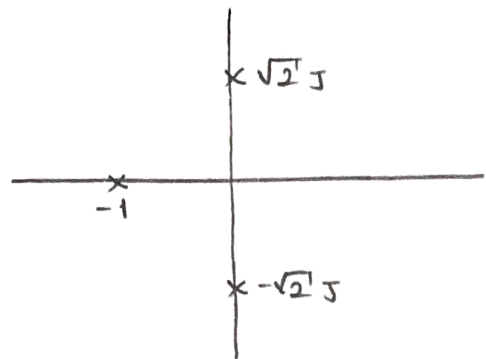
If $k=2$, then s^1 row gets zero.

$$s^2 + k = 0 \quad (\text{Substitute 2 for } k.)$$

$$s^2 + 2 = 0$$

$$s^2 = -2$$

$$s = \pm j\sqrt{2}$$



d) For oscillating system, the system should be marginally stable and for that from part (b) using Routh-Hurwitz table;

$$2-k = 0$$

$$k_{\text{critical}} = 2$$

Now, from even equation (from the table)

$$s^2 + k = 0 \quad (\text{putting } s = j\omega)$$

$$(j\omega)^2 + k = 0 \quad (\text{putting } k = k_{\text{critical}} = 2)$$

$$-\omega^2 + k = 0$$

$$\omega = \sqrt{2} \text{ rad/sec.}$$

This is the frequency value that system oscillates.

Problem 3)

a)

$$G(s) = \frac{K \cdot (s^2 - 2s + 2)}{s(s+1)(s+2)}$$

i) Poles are ; 0, -1, -2

Zeros are ; $s^2 - 2s + 2 = 0$
 $(s-1)^2 + 1 = 0 \rightarrow s = 1 \pm j$

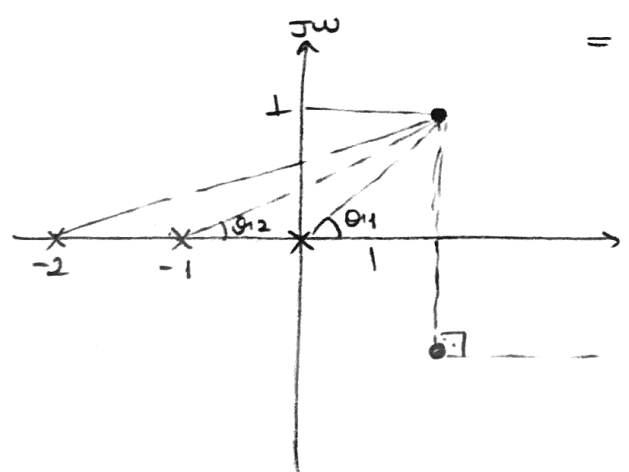
ii) Number of root locus Branch max (Pole, zero)
 $= \max(3, 2)$
 $= 3$

iii) Number of asymptotes = $P - Z = 3 - 2 = 1$

iv.) Centroid = $\frac{\sum P - \sum Z}{P - Z} = \frac{-3 - 2}{1} = (-5, 0)$

v.) Angle of asymptotes = 180°

vi.) Angle of arrival of the root locus at zero
 $= \pm [180 - \phi_p]$



s plane

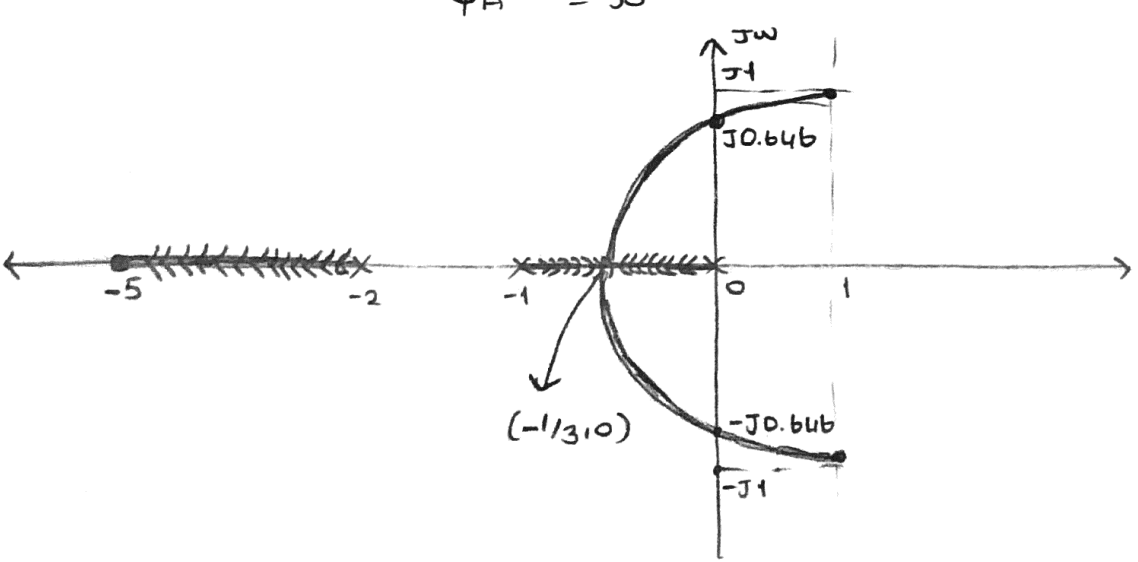
$$\theta_1 = \tan^{-1}(1/1) = 45^\circ$$

$$\theta_2 = \tan^{-1}(1/2) = 26.56^\circ$$

$$\theta_3 = \tan^{-1}(1/3) = 18.43^\circ$$

Arrival Angle = $\pm [180 - (90 - 45 - 26.56 + 18.43)]$

$\phi_A = \pm 90^\circ$



(6)

b) Characteristic Equation

$$1 + G(s) = 0$$

$$s \cdot (s^2 + 3s + 2) + K s^2 - 2sK + 2K = 0$$

$$s^3 + (K+3)s^2 + (2-2K)s + 2K = 0$$

Routh-Hurwitz Table

s^3	1	$2-2K$	
s^2	$K+3$	$2K$	
s^1	$\frac{(K+3)(2-2K)-2K}{K+3}$	0	
s^0	$2K$		

For JW intersection $s^1 = 0$.

$$(K+3)(2-2K) = 2K$$

$$(K+3) \cdot (1-K) = K$$

$$K - K^2 + 3 - 3K = K$$

$$K^2 + 3K - 3 = 0$$

$$K = 0.791, -3.792$$

c) K can not be negative, so $K = 0.791$ Thus, system is stable for $0 < K < 0.791$ Answer for (c)

$$\text{JW points: } -(0.791+3)\omega^2 + 2 \cdot (0.791) = 0$$

$$\omega = 0.64599 \text{ rad/sec}$$

Answer for (b)