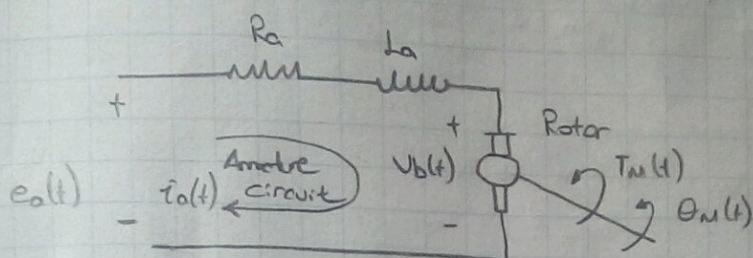


2.42)

$$v_b(t) = K_b \cdot \frac{d\theta_m(t)}{dt} \rightarrow v_b(s) = K_b \cdot s \cdot \theta_m(s) \quad (1)$$

\downarrow \downarrow \downarrow
 electromotive force ω_m angular velocity



$$R_a \cdot I_a(s) + L_a \cdot s \cdot I_a(s) + V_b(s) = E_o(s) \quad (2)$$

Armature Current

Torque developed by the motor

$$T_m(s) = K_t \cdot I_a(s)$$

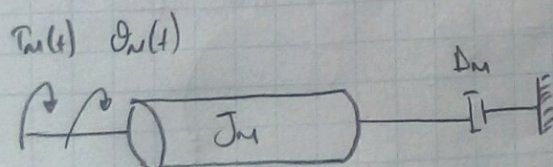
or

$$I_a(s) = \frac{1}{K_t} \cdot T_m(s) \quad (3)$$

(1) + (3) \rightarrow (2) \Rightarrow Transfer func. of the motor:

$$E_o(s) = \frac{(R_a + L_a \cdot s) T_m(s)}{K_t} + K_b \cdot s \cdot \theta_m \quad (4)$$

We need $T_m(s)$ in terms of $\theta_m(s) \sim \theta_m(s) / E_o(s)$



Typical equivalent mechanical
loading motor

$$T_m(s) = (J_m s^2 + D_m s) \cdot \theta_m(s) \quad (5)$$

$$\textcircled{5} \rightarrow \textcircled{4} \Rightarrow \frac{(R_a + L_a s) \cdot (J_m s^2 + D_m s) \cdot \Theta_m(s)}{K_t} + K_b s \Theta_m(s) = E_a(s)$$

$$\frac{\Theta_m(s)}{E_a(s)} = \frac{K_t (R_a \cdot J_m)}{s \left[s + \frac{1}{J_m} + \left(D_m + \frac{K_t K_b}{R_a} \right) \right]}$$

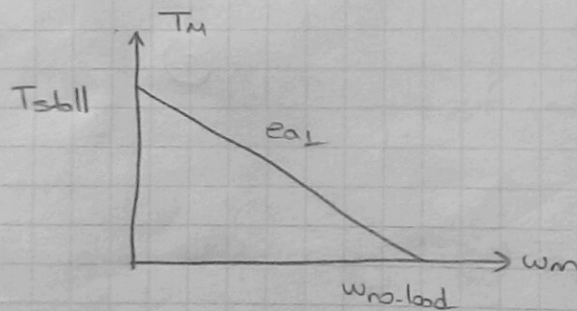
Constants

$$\text{Eq. (4)} \rightarrow (I_a = 0) \quad \frac{R_a}{K_t} \cdot T_m + K_b \cdot \omega_m = e_a$$

$$\underbrace{(\omega_m = s \Theta(s))}_{\text{angular vel.}} = \frac{d\Theta_m}{dt}$$

$$T_m = -\frac{K_b \cdot K_t}{R_a} \cdot \omega_m + \frac{K_t}{R_a} \cdot e_a \quad \textcircled{6}$$

Eq. (6) is a straight line



Torque speed curve

$$T_{stall} = \frac{K_t}{R_a} \cdot e_a$$

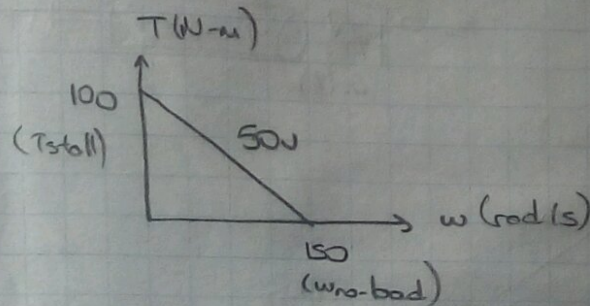
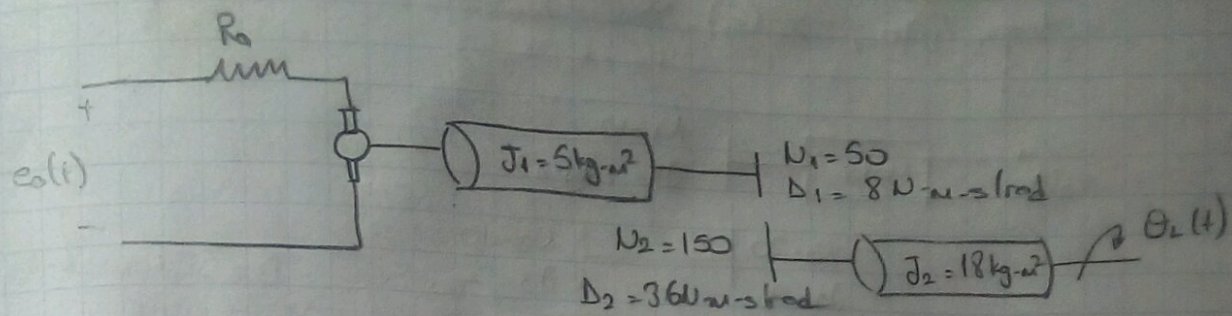
$$w_{no-load} = \frac{e_a}{K_b}$$

Electrical constants of the motor's trans. F.

$$\textcircled{1} \quad \frac{K_t}{R_a} = \frac{T_{stall}}{e_a} \quad (\omega_m = 0 @ 6)$$

$$\textcircled{2} \quad K_b = \frac{e_a}{w_{no-load}} \quad (T_m = 0 @ 6)$$

2.42) For the motor, load, and torque-speed curve, find the transfer func., $G(s) = \Theta_L(s)/E_a(s)$



$$\frac{K_t}{R_a} = \frac{T_{stall}}{E_a} = \frac{100}{50} = \underline{\underline{2}}$$

$$\frac{E_a}{\omega_{no-load}} = \frac{50}{150} = \underline{\underline{1/3}} = K_b$$

$$J_m = 5 + 18 \cdot \left(\frac{50}{150}\right)^2 = 7$$

$$D_m = 8 + 36 \cdot \left(\frac{50}{150}\right)^2 = 12$$

$$\frac{\Theta_m(s)}{E_a(s)} = \frac{K_t / (R_a \cdot J_m)}{s \left[s + \frac{1}{J_m} \cdot (D_m + K_t K_b / R_a) \right]}$$

$$= \frac{2/7}{s \left[s + \frac{1}{7} \cdot \left(12 + \frac{2}{3} \right) \right]}$$

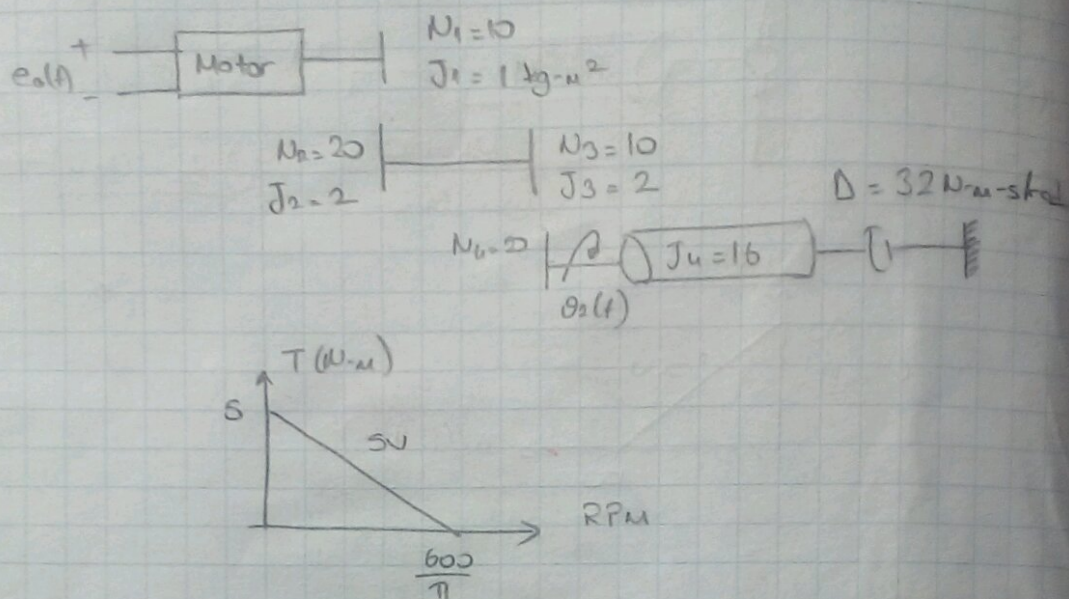
$$\frac{\Theta_m}{E_a} = \frac{2/7}{s \left(s + \frac{28}{21} \right)}$$

$$\Theta_L = \Theta_m \left(\frac{50}{150} \right)$$

$$\Theta_L = \frac{1}{3} \Theta_m$$

$$\boxed{\frac{\Theta_L}{E_a} = \frac{2/21}{s \left(s + \frac{28}{21} \right)}}$$

2.43) The motor whose torque-speed char. are shown in Fig. drives the load shown in the diagram. Find the tran. func., $G(s) = \theta_2(s)/e_a(s)$



$$\frac{K_t}{R_a} = \frac{T_{\text{stall}}}{E_a} = \frac{5}{5} = \underline{\underline{1}}$$

$$K_b = \frac{E_a}{\omega_{\text{no-load}}} = \frac{5}{\frac{600}{\pi} \cdot \frac{1}{60} \cdot 2\pi} = \underline{\underline{\frac{1}{4}}}$$

RPS \approx freq.
 $\omega = 2\pi f$

$$J_u = 1 + 2 \cdot \left(\frac{10}{20}\right)^2 + 2 \cdot \left(\frac{10}{20}\right)^2 + 16 \left(\frac{1}{2} \cdot \frac{1}{2}\right)^2 = 9$$

$$\Delta_m = 32 \left(\frac{1}{2} \cdot \frac{1}{2}\right)^2 = 2$$

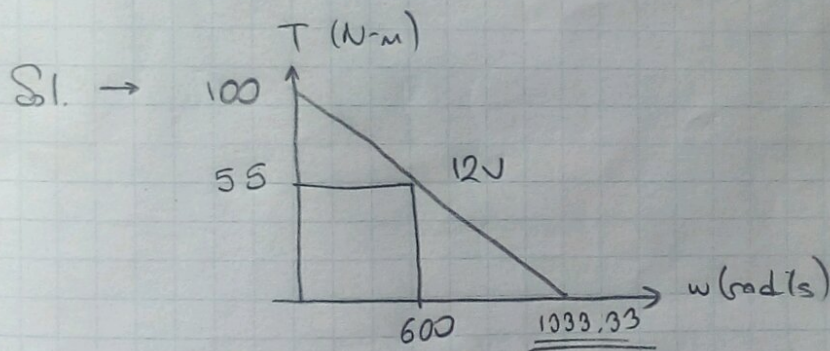
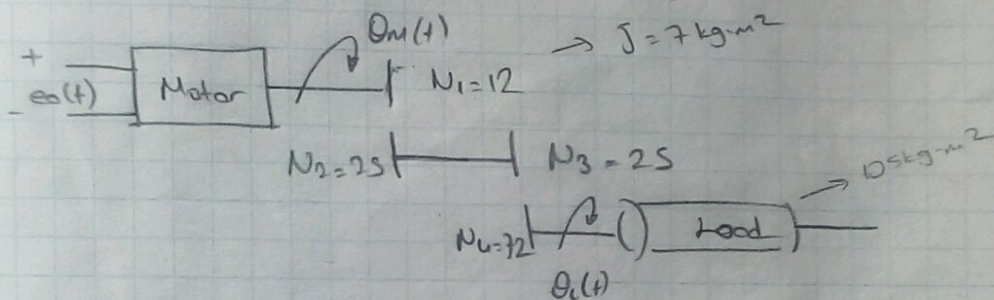
$$\frac{\theta_2(s)}{E_a(s)} = \frac{K_t / (R_a J_u)}{\left[s + \frac{1}{J_u} (\Delta_m + \frac{K_t K_b}{R_a})\right]}$$

$$= \frac{1/3}{\left[s + \frac{1}{3} \left(2 + \frac{1}{4}\right)\right]} = \underline{\underline{\frac{1/3}{s + 0.75}}}$$

$$\theta_2(s) = \frac{1}{u} \theta_2(s)$$

$$\frac{\theta_2}{E_a} = \frac{1/12}{s(s+0.75)}$$

2.45) A dc-motor develops 55 N-m of torque at a speed of 600 rad/s when 12 V are applied. It stalls ^{out} at this voltage with $\overset{T_{stall}}{100 \text{ N-m}}$ of torque. If the inertia and damping of the armature are 7 kg-m² and $\overset{D}{3 \text{ N-m/rad}}$ find the trans. f. $G(s) = \theta_1(s)/E_a(s)$ of this motor if it drives on inertia load of 105 kg-m² through a gear train.



$$\frac{K_t}{R_a} = \frac{T_{stall}}{E_a} = \frac{100}{12}$$

$$K_b = \frac{E_a}{\omega_{no-load}} = \frac{12}{1033.33}$$

$$J_M = 7 + 105 \left(\frac{25}{72} \cdot \frac{12}{25} \right)^2 = 9.92 \quad \Delta = 3$$

$$\frac{\theta_m}{E_a} = \frac{100/12 \cdot (9.92)}{s \left(s + \frac{1}{9.92} \left(3 + \frac{100}{12} \cdot \frac{12}{1033.33} \right) \right)} = \frac{0.84}{s(s+0.31)}$$

$$\theta_L = \left(\frac{2s}{72} - \frac{12}{2s} \right) \theta_M = \frac{1}{6} \theta_M$$

$$G(s) = \frac{\theta_L}{\theta_M} = \frac{0.14}{s(s+0.31)}$$