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Textbook reference for lectures 1-13 is . Applied Nonlinear Control, Slotine and Li, Prentice-Hall 1991. Main references for lectures 14-20 are . R1 Lohmiller, W., and Slotine, J.J.E.,"On Contraction Analysis for Nonlinear Systems," Automatica, 34(6), 1998 R2 Slotine, J.J.E., "Modular Stability Tools for Distributed Computation and Control," Int. J. Adaptive Control and Signal Processing, 17(6 ...

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Analysis and Control" (Asada and Slotine, Wiley, 1986), and "Applied Nonlinear Control" (Slotine and Li, Prentice-Hall, 1991) and is one of the most cited researcher in both systems science and robotics.

JEAN-JACQUES SLOTINE - Mechanical Engineering

Constructive nonlinear control - Sepulchre et al. - Springer, 1997 More focused on passivity and recursive approaches Nonlinear control systems - A. Isidori - Springer Verlag, 1995 A reference for geometric approach Applied Nonlinear control - J.J. Slotine and W. Li - Prentice-Hall, 1991 An interesting reference in particular for sliding mode

Control of Nonlinear Systems - Gipsa-lab

However, the solution of actual nonlinear system is =?> @ A C = =D>E@ A ... Applied Nonlinear Control, J. J. E. Slotine and W. Li, Prentice Hall 3. Nonlinear System Analysis, M. Vidyasagar, Second Edition, Prentice Hall January 4, 2003 Intelligent Control Lecture Series Page 33.

Nonlinear System Analysis - IIT Kanpur

People The Nonlinear Systems Laboratory is headed by Professor Jean-Jacques Slotine.Members and affiliates are Gabriel Bousquet (g_b@mit.edu)Soon-Jo Chung (sjchung@mit.edu)Joanna Cohen (joannac@mit.edu)Khalid El-Rifai (elrifai@mit.edu)Winfried Lohmiller (wslohmil@mit.edu)Quang-Cuong Pham (cuong@mit.edu)Jonathan Soto (j_soto@mit.edu)Nicolas Tabareau (tabareau@mit.edu)

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that reasons, the nonlinear control are chosen. Nonlinear control methods also provide simplicity of the controller (Slotine & Li, 1991). There are lots of machine in industry. One of the basic one is dc machine. There are two kinds of dc machines which are brushless and brushed. Brushed type of dc machine needs

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