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(a) All three systems • have memory because of an integrating action performed on the input, • are causal because (in each case) the output does not appear before the input, and • are time-invariant. (b) H1 is noncausal because the output appears before the input.

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Here the input $x(t)$ is the transmitted signal and the output $y(t)$ is the received signal. Assume the message is represented in binary format and that a "1" is communicated in an interval of length T by transmitting the symbol $p(t)$ depicted in Fig. P2.41 (b) in the pertinent interval and that a "0" is communicated by transmitting $-p(t)$...

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tation in Signals and Systems, Oppenheim and Willsky with Nawab, 2nd Edition, Prentice Hall, 1997. 2.1 SIGNALS, SYSTEMS, MODELS, PROPERTIES Throughout this text we will be considering various classes of signals and systems, developing models for them and studying their properties.

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