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Applications of vector analysis to dynamics and physics are the focus of the final chapter, including such topics as moving rigid bodies, energy of a moving rigid system, central forces, equipotential surfaces, Gauss's theorem, and vector flow.

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CHAPTER 1. VECTOR ANALYSIS 8 describes position of a point (x,y,z) relative to the origin (whose co-ordinates are (0,0,0)). Its magnitude is $r = |\vec{r}| = \sqrt{x^2 + y^2 + z^2}$ (1.32) and unit vector in the direction of \vec{r} is $\hat{r} = \frac{\vec{r}}{r} = \frac{x\hat{x} + y\hat{y} + z\hat{z}}{\sqrt{x^2 + y^2 + z^2}}$. (1.33)

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6 Chapter 1 Vector Analysis Exercises 1.1.1 Show how to find A and B, given $A + B$ and $A - B$. 1.1.2 The vector A whose magnitude is 1.732 units makes equal angles with the coordinate axes. Find A_x, A_y , and A_z . 1.1.3 Calculate the components of a unit vector that lies in the xy-plane and makes equal angles with the positive directions of the x- and y-axes. 1.1.4 The velocity of sailboat A relative ...

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CHAPTER 3. VECTOR ANALYSIS 3.1.3 Position and Distance Vectors $z_2, y_2, z_1, y_1, x_1, x_2, x, y, R_1, R_2, z$ $P_1 = (x_1, y_1, z_1)$ $P_2 = (x_2, y_2, z_2)$ O Figure 3-4 Distance vector $R_{12} = P_1P_2 = R_2 - R_1$, where R_1 and R_2 are the position vectors of points P_1 and P_2 , respectively. Figure 3.3: The notion of the position vector to a point, P

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Vector analysis, which had its beginnings in the middle of the 19th century, has in recent years become an essential part of the mathematical background required of engineers, physicists, mathematicians and other scientists.

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MATH 550, VECTOR ANALYSIS, EXTRA HOMEWORK 3 AND SOLUTIONS Problem 0. Suppose $a, b, c \in \mathbb{R}^3$. Show that $(a \cdot b) \cdot c = \dots$ Suppose \hat{u} is a unit vector in the abstract vector space V , and $2 \in \mathbb{R}$. For every vector r in V define: $R(\hat{u})r = r \cos \theta + \hat{u}(\hat{u} \cdot r)(1 - \cos \theta)$...

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