

# CS/CNS/EE 156a

## Homework 7

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1. Answer: [d]

The classification errors I got were:

k=3 Error: 0.3

k=4 Error: 0.5

k=5 Error: 0.2

k=6 Error: 0 (The smallest)

k=7 Error: 0.1

Please refer to the code below for derivation.

---

```
#Sung Hoon Choi
#CS/CNS/EE156a HW7 Problem 1
import numpy as np

IN_DTA_NUM = 35      # number of insample data points
OUT_DTA_NUM = 250    # number of outsample data points

def extract_data(filename):
    data_array = []
    for line in open(filename):
        data=[]
        data_entries = line.split(' ')
        data_row = [float(data_entries[1]),float(data_entries[2]),float(data_entries[3].rstrip("\n"))]
        data_array.append(data_row)
    return data_array          #return the data from given dta file.
                                # Format: (x1,x2,label)
                                #      ...
                                #      (x1,x2,label)

def nonlinear_trans(x,lineNum,k):
    nonlin_transformed_data = []
    for i in range(0,lineNum):
        nonlin_transformed_row = []
        nonlin_transformed_row.append(1)
        nonlin_transformed_row.append(x[i][0])
        nonlin_transformed_row.append(x[i][1])
        nonlin_transformed_row.append(x[i][0]**2)
        nonlin_transformed_row.append(x[i][1]**2)
        nonlin_transformed_row.append((x[i][0]*x[i][1]))
        nonlin_transformed_row.append(abs(x[i][0]-x[i][1]))
        nonlin_transformed_row.append(abs(x[i][0]+x[i][1]))
        nonlin_transformed_data.append(nonlin_transformed_row[0:k+1])
    return nonlin_transformed_data          # Format: (1,x1,x2,x1^2,x2^2,...)
                                            #      ...
                                            #      (1,x1,x2,x1^2,x2^2,...)

def calculate_weight(nonlinear_x, label):
    return np.dot(np.linalg.pinv(nonlinear_x), label)

def calculate_error(weights, nonlin_input_x, y, data_num):
    error_count = 0
    for i in range(0,data_num):
        g = np.sign(np.dot(weights.T,nonlin_input_x[i]))
        if(g != y[i]):
            error_count = error_count + 1
    print("Error: ", error_count/data_num)

for k in range(3,8):
    print("k = %d -----" % k)
```

```

insample_data = extract_data("in.dta")
insample_data_np = np.array(insample_data) # turn it into a numpy array to use numpy library functions
y = insample_data_np[:, 2] # extract y-labels from the input data
transformed_data = nonlinear_trans(insample_data, IN_DTA_NUM,k)
transformed_data = np.array(transformed_data)
weights = calculate_weight(transformed_data[:25,:],y[:25])
calculate_error(weights,transformed_data[25:,:],y[25:],10)

```

---

## 2. Answer: [e]

The out-of-sample errors I got were:

k = 3 Error: 0.42

k = 4 Error: 0.416

k = 5 Error: 0.188

k = 6 Error: 0.084

k = 7 Error: 0.072 (The smallest)

Please refer to the code below for the derivation.

---

```

#Sung Hoon Choi
#CS/CNS/EE156a HW7 Problem 2
import numpy as np

IN_DTA_NUM = 35      # number of insample data points
OUT_DTA_NUM = 250    # number of outsample data points

def extract_data(filename):
    data_array = []
    for line in open(filename):
        data=[]
        data_entries = line.split(' ')
        data_row = [float(data_entries[1]),float(data_entries[2]),float(data_entries[3].rstrip("\n"))]
        data_array.append(data_row)
    return data_array          #return the data from given dta file.
                                # Format: (x1,x2,label)
                                #
                                #      ...
                                #      (x1,x2,label)

def nonlinear_trans(x,lineNum,k):
    nonlin_transformed_data = []
    for i in range(0,lineNum):
        nonlin_transformed_row = []
        nonlin_transformed_row.append(1)
        nonlin_transformed_row.append(x[i][0])
        nonlin_transformed_row.append(x[i][1])
        nonlin_transformed_row.append(x[i][0]**2)
        nonlin_transformed_row.append(x[i][1]**2)
        nonlin_transformed_row.append((x[i][0]*x[i][1]))
        nonlin_transformed_row.append(abs(x[i][0]-x[i][1]))
        nonlin_transformed_row.append(abs(x[i][0]+x[i][1]))
        nonlin_transformed_data.append(nonlin_transformed_row[0:k+1])
    return nonlin_transformed_data          # Format: (1,x1,x2,x1^2,x2^2,...)
                                            #
                                            #      ...
                                            #      (1,x1,x2,x1^2,x2^2,...)

def calculate_weight(nonlinear_x, label):
    return np.dot(np.linalg.pinv(nonlinear_x), label)

def calculate_error(weights, nonlin_input_x, y, data_num):
    error_count = 0
    for i in range(0,data_num):
        g = np.sign(np.dot(weights.T,nonlin_input_x[i]))
        if(g != y[i]):
            error_count = error_count + 1
    print("Error: ", error_count/data_num)

for k in range(3,8):
    print("k = %d -----" % k)
    insample_data = extract_data("in.dta")
    insample_data_np = np.array(insample_data) # turn it into a numpy array to use numpy library functions
    y = insample_data_np[:, 2] # extract y-labels from the input data
    transformed_data = nonlinear_trans(insample_data, IN_DTA_NUM,k)

```

```

transformed_data = np.array(transformed_data)
weights = calculate_weight(transformed_data[:25,:],y[:25])

outsample_data = extract_data("out.dta")
outsample_data_np = np.array(outsample_data) # turn it into a numpy array to use numpy library functions
y = outsample_data_np[:, 2] # extract y-labels from the input data
transformed_data = nonlinear_trans(outsample_data, OUT_DTA_NUM, k)
calculate_error(weights, transformed_data, y, OUT_DTA_NUM) # Eout - OutSample Error

```

---

3. Answer: [d]

The errors I got were:

k = 3 Error: 0.28

k = 4 Error: 0.36

k = 5 Error: 0.2

k = 6 Error: 0.08 (The smallest)

k = 7 Error: 0.12

Please refer to the code below for derivation.

---

```

#Sung Hoon Choi
#CS/CNS/EE156a HW7 Problem 3
import numpy as np

IN_DTA_NUM = 35          # number of insample data points
OUT_DTA_NUM = 250        # number of outsample data points

def extract_data(filename):
    data_array = []
    for line in open(filename):
        data=[]
        data_entries = line.split(' ')
        data_row = [float(data_entries[1]),float(data_entries[2]),float(data_entries[3].rstrip("\n"))]
        data_array.append(data_row)
    return data_array          #return the data from given dta file.
                                # Format: (x1,x2,label)
                                #
                                #      ...
                                #      (x1,x2,label)

def nonlinear_trans(x,lineNum,k):
    nonlin_transformed_data = []
    for i in range(0,lineNum):
        nonlin_transformed_row = []
        nonlin_transformed_row.append(1)
        nonlin_transformed_row.append(x[i][0])
        nonlin_transformed_row.append(x[i][1])
        nonlin_transformed_row.append(x[i][0]**2)
        nonlin_transformed_row.append(x[i][1]**2)
        nonlin_transformed_row.append((x[i][0]*x[i][1]))
        nonlin_transformed_row.append(abs(x[i][0]-x[i][1]))
        nonlin_transformed_row.append(abs(x[i][0]+x[i][1]))
        nonlin_transformed_data.append(nonlin_transformed_row[0:k+1])
    return nonlin_transformed_data          # Format: (1,x1,x2,x1^2,x2^2,...)
                                #
                                #      ...
                                #      (1,x1,x2,x1^2,x2^2,...)

def calculate_weight(nonlinear_x, label):
    return np.dot(np.linalg.pinv(nonlinear_x), label)

def calculate_error(weights, nonlin_input_x, y, data_num):
    error_count = 0
    for i in range(0,data_num):
        g = np.sign(np.dot(weights.T,nonlin_input_x[i]))
        if(g != y[i]):
            error_count = error_count + 1
    print("Error: ", error_count/data_num)

for k in range(3,8):
    print("k = %d -----" % k)
    insample_data = extract_data("in.dta")
    insample_data_np = np.array(insample_data) # turn it into a numpy array to use numpy library functions
    y = insample_data_np[:, 2] # extract y-labels from the input data

```

```

transformed_data = nonlinear_trans(insample_data, IN_DTA_NUM,k)
transformed_data = np.array(transformed_data)
weights = calculate_weight(transformed_data[25:35,:],y[25:35])
calculate_error(weights, transformed_data[:25, :], y[:25], 25)

```

---

#### 4. Answer: [d]

The errors I got were:

k = 3 Error: 0.396

k = 4 Error: 0.388

k = 5 Error: 0.284

k = 6 Error: 0.192 (The smallest)

k = 7 Error: 0.196

Please refer to the code below for derivation.

---

```

#Sung Hoon Choi
#CS/CNS/EE156a HW7 Problem 4
import numpy as np

IN_DTA_NUM = 35      # number of insample data points
OUT_DTA_NUM = 250    # number of outsample data points

def extract_data(filename):
    data_array = []
    for line in open(filename):
        data=[]
        data_entries = line.split(' ')
        data_row = [float(data_entries[1]),float(data_entries[2]),float(data_entries[3].rstrip("\n"))]
        data_array.append(data_row)
    return data_array          #return the data from given dta file.
                                # Format: (x1,x2,label)
                                #      ...
                                #      (x1,x2,label)

def nonlinear_trans(x,lineNum,k):
    nonlin_transformed_data = []
    for i in range(0,lineNum):
        nonlin_transformed_row = []
        nonlin_transformed_row.append(1)
        nonlin_transformed_row.append(x[i][0])
        nonlin_transformed_row.append(x[i][1])
        nonlin_transformed_row.append(x[i][0]**2)
        nonlin_transformed_row.append(x[i][1]**2)
        nonlin_transformed_row.append((x[i][0]*x[i][1]))
        nonlin_transformed_row.append(abs(x[i][0]-x[i][1]))
        nonlin_transformed_row.append(abs(x[i][0]+x[i][1]))
        nonlin_transformed_data.append(nonlin_transformed_row[0:k+1])
    return nonlin_transformed_data          # Format: (1,x1,x2,x1^2,x2^2,...)
                                            #      ...
                                            #      (1,x1,x2,x1^2,x2^2,...)

def calculate_weight(nonlinear_x, label):
    return np.dot(np.linalg.pinv(nonlinear_x), label)

def calculate_error(weights, nonlin_input_x, y, data_num):
    error_count = 0
    for i in range(0,data_num):
        g = np.sign(np.dot(weights.T,nonlin_input_x[i]))
        if(g != y[i]):
            error_count = error_count + 1
    print("Error: ", error_count/data_num)

for k in range(3,8):
    print("k = %d -----" % k)
    insample_data = extract_data("in.dta")
    insample_data_np = np.array(insample_data) # turn it into a numpy array to use numpy library functions
    y = insample_data_np[:, 2] # extract y-labels from the input data
    transformed_data = nonlinear_trans(insample_data, IN_DTA_NUM,k)
    transformed_data = np.array(transformed_data)
    weights = calculate_weight(transformed_data[25:35,:],y[25:35])

```

```
outsample_data = extract_data("out.dta")
outsample_data_np = np.array(outsample_data) # turn it into a numpy array to use numpy library functions
y = outsample_data_np[:, 2] # extract y-labels from the input data
transformed_data = nonlinear_trans(outsample_data, OUT_DTA_NUM, k)
calculate_error(weights, transformed_data, y, OUT_DTA_NUM) # Eout - OutSample Error
```

---

5. Answer: [b]

In problem1, the chosen model was  $k=6$  and its out-of-sample error was 0.084.

In problem3, the chosen model was  $k=6$  and its out-of-sample error was 0.192.

Therefore, the closest values are (0.1, 0.2).

6. Answer: [d]

By generating 100000 pairs of data using Python, I got

$E[e_1] = 0.499$

$E[e_2] = 0.500$

$E[e_3] = 0.333$

Therefore, the closest value is [d].

Please refer to the code below for derivation.

---

#Sung Hoon Choi

#CS/CNS/EE156a HW7 Problem 6

```
import random
```

```
DATA_NUM = 100000
```

```
total_e1 = 0
```

```
total_e2 = 0
```

```
total_e = 0
```

```
for i in range(0, DATA_NUM):
```

```
    e1 = random.uniform(0,1)
```

```
    e2 = random.uniform(0,1)
```

```
    e = min(e1,e2)
```

```
    total_e1 = total_e1 + e1
```

```
    total_e2 = total_e2 + e2
```

```
    total_e = total_e + e
```

```
print("Expected e1: ", total_e1/DATA_NUM)
```

```
print("Expected e2: ", total_e2/DATA_NUM)
```

```
print("Expected e: ", total_e/DATA_NUM)
```

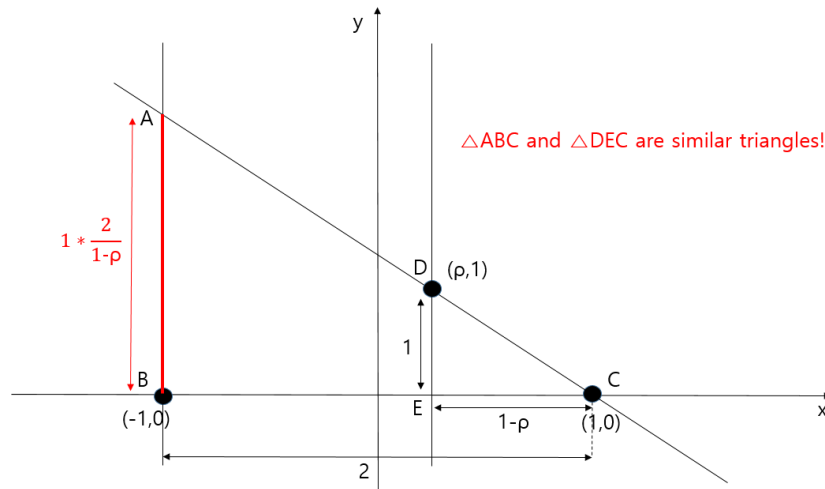
---

7. Answer: [c]

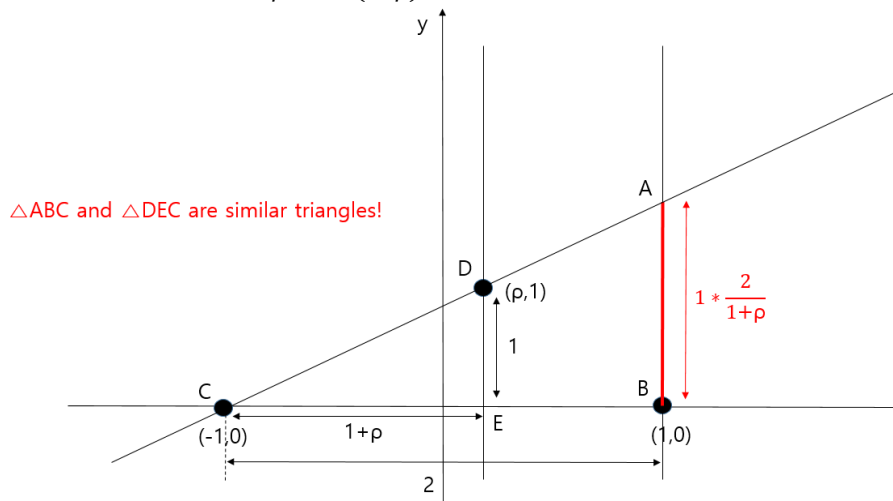
$\{h_0(x)=b\}$ : First, let's leave out  $(\rho, 1)$ . Then, the equation of the line passing through  $(-1,0)$  and  $(1,0)$  would be  $y=0$ . Thus, the validation square error from  $y=0$  to  $(\rho, 1)$  would be 1. ( $\because (1-0)^2=1$ ) Now, let's leave out  $(-1,0)$ . Then, since we have  $(1,0)$  and  $(\rho, 1)$ , the line must be located at the middle of this interval, giving the equation of  $y=\frac{1}{2}$ . Thus, the validation error from  $y=\frac{1}{2}$  to  $(-1,0)$  would be  $(\frac{1}{2} - 0)^2 = \frac{1}{4}$ . In the same way, if we leave out  $(1,0)$  for validation, we get the same validation error of  $\frac{1}{4}$  due to symmetry. Thus, the error for  $\{h_0(x)=b\}$  is

$$\frac{1}{3} * \left(1 + \frac{1}{4} + \frac{1}{4}\right) = \frac{1}{2}$$

$\{h_1(x)=ax+b\}$ : First, let's leave out  $(\rho, 1)$ . Then, it is exactly the same as what we've done for  $h_0(x)=b$  above and we already know that its validation error is 1. ( $\because (1-0)^2=1$ ) Now, for the cases of leaving out  $(-1,0)$  and  $(1,0)$ , I drew diagrams below to help explaining the geometry. If we leave out  $(-1,0)$  for validation, then we get the following estimation line:



Since  $\triangle ABC$  and  $\triangle DEC$  are similar triangles, we can find that  $\overline{AB} = \frac{2}{1-\rho}$ . Since we are using a squared-error measure, the error would be  $(\frac{2}{1-\rho})^2 = \frac{4}{(1-\rho)^2}$ . Similarly, if we leave out  $(1,0)$ , we get the following:



In this case,  $\overline{AB} = \frac{2}{1+\rho}$  and the squared-error measure is  $(\frac{2}{1+\rho})^2 = \frac{4}{(1+\rho)^2}$ .

Thus, the error for  $\{h_1(x)=ax+b\}$  is

$$\frac{1}{3} * \left(1 + \frac{4}{(1-\rho)^2} + \frac{4}{(1+\rho)^2}\right)$$

Now that we have the errors for both  $\{h_0(x)=b\}$  and  $\{h_1(x)=ax+b\}$ , let's find the  $\rho$  that makes them equal.

$$\frac{1}{2} = \frac{1}{3} * \left(1 + \frac{4}{(1-\rho)^2} + \frac{4}{(1+\rho)^2}\right)$$

The solution for this equation is  $\rho = \sqrt{9 + 4\sqrt{6}}$ . (Used WolframAlpha)

## 8. Answer: [c]

I repeated the experiment for 1000 runs, and the simulation indicated that  $g_{\text{svm}}$  did better than  $g_{\text{PLA}}$  for 573 times. Thus, the closest answer is [c].

Please refer to the code below for derivation.

---

#Sung Hoon Choi

#CS/CNS/EE156a HW7 Problem 8

```
from sklearn.svm import SVC #Used for implementing SVM.
import numpy as np
import random
```

```
def gen_target_func():
    #generate a target function(f(x)) and return the corresponding vertical coordinate
    #input: none
    #output: target_function. format: [slope, y_intercept]

    rnd_x1 = np.zeros(2)
    rnd_x2 = np.zeros(2)

    for i in range(0,2):
        rnd_x1[i] = (1 if np.random.rand(1) < 0.5 else -1) * np.random.rand(1)

    for i in range(0,2):
        rnd_x2[i] = (1 if np.random.rand(1) < 0.5 else -1) * np.random.rand(1)

    slope_target_func = (rnd_x2[1]-rnd_x1[1])/(rnd_x2[0]-rnd_x1[0]) # slope = (y2-y1)/(x2-x1)

    y_intercept = rnd_x2[1]-slope_target_func*rnd_x2[0]

    return [slope_target_func, y_intercept]

def Label_data(X_vector, target_f): #return a correct label(1 or -1) by using the input vector and target equation f.
    #inputs
    # X_vector : input point's coordinate. format: [a, b]
    # target_f : target function. format: a
    #outputs
    # y : correct label for the input vector. format: a (1 or -1)

    if(X_vector[1] > target_f): #if the input's vertical coordinate is above the target function, return 1 label
        #if the input's vertical coordinate is below the target function, return -1 label
        return 1
    else:
        return -1

def generate_random_point(): #generate random data point's coordinate
    #inputs
    # none
    #outputs
    # x: random points. format: [a,b]

    x = np.zeros(2)
    x[0] = (1 if np.random.rand(1) < 0.5 else -1) * np.random.rand(1)
    x[1] = (1 if np.random.rand(1) < 0.5 else -1) * np.random.rand(1)
    return x

#Initializing the constants which will be used for training and testing
Total_Run = 1000 #Total number of experiment runs.
Test_Data_Num = 1000 #Total number of testing data points
Total_Support_Vector_Num = 0 #Total number of support vectors. Used to find the average number of support vectors.
SVM_better_than_PLA = 0 #Counts the number of cases when SVM did better than PLA.
N=10 #Number of data points for training.

print("-----N=%d-----" % N)
for run in range(0,Total_Run):
    clf = SVC(kernel='linear', C=1e12) #Set C to a very high value for the hard margin.

    target_info = gen_target_func() #target_info = [slope_target_func, y_intercept]

    x = np.zeros([N,4]) # x - [[1, x1,x2,label(y)],
                        # [1, x1,x2,label(y)],
                        # ..
                        # [1, x1,x2,label(y)]]

    w = np.zeros([3,1]) #initializing w vector
    w = np.squeeze(w) #remove one dimension for matrix operations
```

```

# generate N random data points with their correct labels based on the current target function f(x)
for i in range (0, N):
    x[i,0] = 1 #x0 = 1
    x[i,1:3] = generate_random_point() #random data points coordinate data
    f_x = target_info[0] * x[i,1] + target_info[1] #obtaining the target equation f
    x[i,3] = Label_data(x[i,1:3],f_x) #using f, obtain the label(y) and append it to the array

sum_all_one_side = 0
for i in range (0, N):
    sum_all_one_side = sum_all_one_side + x[i,3]

if (sum_all_one_side == N or sum_all_one_side == -N):
    continue;

#Fit the SVM.
clf.fit(x[:,0:3],x[:,3])
#Get the number of support vectors.
Total_Support_Vector_Num = Total_Support_Vector_Num + len(clf.support_)

#Go through PLA until the hypothesis converges.
while (1):
    misclassified_arr = []
    for i in range (0,N):
        g_x = np.dot(w.T, x[i, 0:3]) # g(x) = dot(w,x)
        if(x[i,3] != np.sign(g_x)):
            misclassified_arr.append(i)
    if(len(misclassified_arr) == 0): #escape the loop when PLA converges.
        break
    w = w + x[random.choice(misclassified_arr), 3] * x[random.choice(misclassified_arr), 0:3] # w = w + y*X

#Testing begins
#Generate random points to examine the error rate of g(x)
test = np.zeros([Test_Data_Num, 4])
for i in range(0, Test_Data_Num):
    test[i, 0] = 1 # x0 = 1
    test[i, 1:3] = generate_random_point()
    f_x = target_info[0] * test[i, 1] + target_info[1]
    test[i, 3] = Label_data(test[i, 1:3], f_x) # y (label)

svm_wrong_counter = 0
svm_predict = clf.predict(test[:,0:3])
for i in range(0,Test_Data_Num):
    if (test[i,3] != svm_predict[i]):
        svm_wrong_counter = svm_wrong_counter + 1 #Count the data points misclassified by SVM.

#Examine the error using the generated test points
pla_wrong = 0
for i in range (0,Test_Data_Num):
    g_x = np.dot(w.T, test[i, 0:3]) # g(x) = dot(w,x)
    if (test[i, 3] != np.sign(g_x)):
        pla_wrong = pla_wrong + 1 #Count the data points misclassified by PLA.

#If SVM did better than PLA, increase the counter.
if (svm_wrong_counter < pla_wrong):
    SVM_better_than_PLA = SVM_better_than_PLA + 1

print("svm better than pla: %d times " % SVM_better_than_PLA)
print("svn better than pla: %.2f percent" % (SVM_better_than_PLA/Total_Run))

```

---

## 9. Answer: [d]

I repeated the experiment for 1000 runs, and the simulation indicated that  $g_{\text{svm}}$  did better than  $g_{\text{PLA}}$  for 621 times. Thus, the closest answer is [d].

Please refer to the code below for derivation.

---

```

#Sung Hoon Choi
#CS/CNS/EE156a HW7 Problem 9

from sklearn.svm import SVC #Used for implementing SVM.
import numpy as np
import random

def gen_target_func():
    #generate a target function(f(x)) and return the corresponding vertical coordinate

```



```

        #input: none
        #output: target_function. format: [slope, y_intercept]

rnd_x1 = np.zeros(2)
rnd_x2 = np.zeros(2)

for i in range (0,2):
    rnd_x1[i] = (1 if np.random.rand(1) < 0.5 else -1) * np.random.rand(1)

for i in range (0,2):
    rnd_x2[i] = (1 if np.random.rand(1) < 0.5 else -1) * np.random.rand(1)

slope_target_func = (rnd_x2[1]-rnd_x1[1])/(rnd_x2[0]-rnd_x1[0]) # slope = (y2-y1)/(x2-x1)

y_intercept = rnd_x2[1]-slope_target_func*rnd_x2[0]

return [slope_target_func, y_intercept]

def Label_data(X_vector, target_f): #return a correct label(1 or -1) by using the input vector and target equation f.
    #inputs
    # X_vector : input point's coordinate. format: [a, b]
    # target_f : target function. format: a
    #outputs
    # y : correct label for the input vector. format: a (1 or -1)

    if(X_vector[1] > target_f): #if the input's vertical coordinate is above the target function, return 1 label
        #if the input's vertical coordinate is below the target function, return -1 label
        return 1
    else:
        return -1

def generate_random_point(): #generate random data point's coordinate
    #inputs
    # none
    #outputs
    # x: random points. format: [a,b]

    x = np.zeros(2)
    x[0] = (1 if np.random.rand(1) < 0.5 else -1) * np.random.rand(1)
    x[1] = (1 if np.random.rand(1) < 0.5 else -1) * np.random.rand(1)
    return x

#Initializing the constants which will be used for training and testing
Total_Run = 1000 #Total number of experiment runs.
Test_Data_Num = 1000 #Total number of testing data points
Total_Support_Vector_Num = 0 #Total number of support vectors. Used to find the average number of support vectors.
SVM_better_than_PLA = 0 #Counts the number of cases when SVM did better than PLA.
N=100 #Number of data points for training.

print("-----N=%d-----" % N)
for run in range (0,Total_Run):
    clf = SVC(kernel='linear', C=1e12) #Set C to a very high value for the hard margin.

    target_info = gen_target_func() #target_info = [slope_target_func, y_intercept]

    x = np.zeros([N,4]) # x - [[1, x1,x2,label(y)],
    # [1, x1,x2,label(y)],
    # ..
    # [1, x1,x2,label(y)]]

    w = np.zeros([3,1]) #initializing w vector
    w = np.squeeze(w) #remove one dimension for matrix operations

    # generate N random data points with their correct labels based on the current target function f(x)
    for i in range (0, N):
        x[i,0] = 1 #x0 = 1
        x[i,1:3] = generate_random_point() #random data points coordinate data
        f_x = target_info[0] * x[i,1] + target_info[1] #obtaining the target equation f
        x[i,3] = Label_data(x[i,1:3],f_x) #using f, obtain the label(y) and append it to the array

    sum_all_one_side = 0
    for i in range (0, N):
        sum_all_one_side = sum_all_one_side + x[i,3]

    if (sum_all_one_side == N or sum_all_one_side == -N):
        continue;

    #Fit the SVM.

```

```

clf.fit(x[:,0:3],x[:,3])
#Get the number of support vectors.
Total_Support_Vector_Num = Total_Support_Vector_Num + len(clf.support_)

#Go through PLA until the hypothesis converges.
while (1):
    misclassified_arr = []
    for i in range (0,N):
        g_x = np.dot(w.T, x[i, 0:3]) # g(x) = dot(w,x)
        if(x[i,3] != np.sign(g_x)):
            misclassified_arr.append(i)
    if(len(misclassified_arr) == 0): #escape the loop when PLA converges.
        break
    w = w + x[random.choice(misclassified_arr), 3] * x[random.choice(misclassified_arr), 0:3] # w = w + y*X

#Testing begins
#Generate random points to examine the error rate of g(x)
test = np.zeros([Test_Data_Num, 4])
for i in range(0, Test_Data_Num):
    test[i, 0] = 1 # x0 = 1
    test[i, 1:3] = generate_random_point()
    f_x = target_info[0] * test[i, 1] + target_info[1]
    test[i, 3] = Label_data(test[i, 1:3], f_x) # y (label)

svm_wrong_counter = 0
svm_predict = clf.predict(test[:,0:3])
for i in range(0,Test_Data_Num):
    if (test[i,3] != svm_predict[i]):
        svm_wrong_counter = svm_wrong_counter + 1 #Count the data points misclassified by SVM.

#Examine the error using the generated test points
pla_wrong = 0
for i in range (0,Test_Data_Num):
    g_x = np.dot(w.T, test[i, 0:3]) # g(x) = dot(w,x)
    if (test[i, 3] != np.sign(g_x)):
        pla_wrong = pla_wrong + 1 #Count the data points misclassified by PLA.

#If SVM did better than PLA, increase the counter.
if (svm_wrong_counter < pla_wrong):
    SVM_better_than_PLA = SVM_better_than_PLA + 1

print("svm better than pla: %d times " % SVM_better_than_PLA)
print("svn better than pla: %.2f percent" % (SVM_better_than_PLA/Total_Run))

```

---

10. Answer: [b]

I repeated the experiment for 1000 runs, and the average number of support vectors was 2.998. Thus, the answer is [b].

Please refer to the code below for derivation.

---

```

#Sung Hoon Choi
#CS/CNS/EE156a HW7 Problem 10

from sklearn.svm import SVC #Used for implementing SVM.
import numpy as np
import random

def gen_target_func():
    #generate a target function(f(x)) and return the corresponding vertical coordinate
    #input: none
    #output: target_function. format: [slope, y_intercept]

    rnd_x1 = np.zeros(2)
    rnd_x2 = np.zeros(2)

    for i in range (0,2):
        rnd_x1[i] = (1 if np.random.rand(1) < 0.5 else -1) * np.random.rand(1)

    for i in range (0,2):
        rnd_x2[i] = (1 if np.random.rand(1) < 0.5 else -1) * np.random.rand(1)

    slope_target_func = (rnd_x2[1]-rnd_x1[1])/(rnd_x2[0]-rnd_x1[0]) # slope = (y2-y1)/(x2-x1)

    y_intercept = rnd_x2[1]-slope_target_func*rnd_x2[0]

```

```

    return [slope_target_func, y_intercept]

def Label_data(X_vector, target_f): #return a correct label(1 or -1) by using the input vector and target equation f.
    #inputs
    # X_vector : input point's coordinate. format: [a, b]
    # target_f : target function. format: a
    #outputs
    # y : correct label for the input vector. format: a (1 or -1)

    if(X_vector[1] > target_f):    #if the input's vertical coordinate is above the target function, return 1 label
        #if the input's vertical coordinate is below the target function, return -1 label
        return 1
    else:
        return -1

def generate_random_point():    #generate random data point's coordinate
    #inputs
    # none
    #outputs
    # x: random points. format: [a,b]

    x = np.zeros(2)
    x[0] = (1 if np.random.rand(1) < 0.5 else -1) * np.random.rand(1)
    x[1] = (1 if np.random.rand(1) < 0.5 else -1) * np.random.rand(1)
    return x

#Initializing the constants which will be used for training and testing
Total_Run = 1000    #Total number of experiment runs.
Test_Data_Num = 1000    #Total number of testing data points
Total_Support_Vector_Num = 0 #Total number of support vectors. Used to find the average number of support vectors.
SVM_better_than_PLA = 0    #Counts the number of cases when SVM did better than PLA.
N=100    #Number of data points for training.

print("-----N=%d-----" % N)
for run in range (0,Total_Run):
    clf = SVC(kernel='linear', C=1e12) #Set C to a very high value for the hard margin.

    target_info = gen_target_func()    #target_info = [slope_target_func, y_intercept]

    x = np.zeros([N,4])    # x - [[1, x1,x2,label(y)],
    # [1, x1,x2,label(y)],
    # ..
    # [1, x1,x2,label(y)]]

    w = np.zeros([3,1])    #initializing w vector
    w = np.squeeze(w)    #remove one dimension for matrix operations

    # generate N random data points with their correct labels based on the current target function f(x)
    for i in range (0, N):
        x[i,0] = 1    #x0 = 1
        x[i,1:3] = generate_random_point()    #random data points coordinate data
        f_x = target_info[0] * x[i,1] + target_info[1] #obtaining the target equation f
        x[i,3] = Label_data(x[i,1:3],f_x)    #using f, obtain the label(y) and append it to the array

    sum_all_one_side = 0
    for i in range (0, N):
        sum_all_one_side = sum_all_one_side + x[i,3]

    if (sum_all_one_side == N or sum_all_one_side == -N):
        continue;

    #Fit the SVM.
    clf.fit(x[:,0:3],x[:,3])
    #Get the number of support vectors.
    Total_Support_Vector_Num = Total_Support_Vector_Num + len(clf.support_)

    #Go through PLA until the hypothesis converges.
    while (1):
        misclassified_arr = []
        for i in range (0,N):
            g_x = np.dot(w.T, x[i, 0:3]) # g(x) = dot(w,x)
            if(x[i,3] != np.sign(g_x)):
                misclassified_arr.append(i)
        if(len(misclassified_arr) == 0):    #escape the loop when PLA converges.
            break
        w = w + x[random.choice(misclassified_arr), 3] * x[random.choice(misclassified_arr), 0:3] # w = w + y*X

```

```

#Testing begins
#Generate random points to examine the error rate of g(x)
test = np.zeros([Test_Data_Num, 4])
for i in range(0, Test_Data_Num):
    test[i, 0] = 1 # x0 = 1
    test[i, 1:3] = generate_random_point()
    f_x = target_info[0] * test[i, 1] + target_info[1]
    test[i, 3] = Label_data(test[i, 1:3], f_x) # y (label)

svm_wrong_counter = 0
svm_predict = clf.predict(test[:,0:3])
for i in range(0,Test_Data_Num):
    if (test[i,3] != svm_predict[i]):
        svm_wrong_counter = svm_wrong_counter + 1 #Count the data points misclassified by SVM.

#Examine the error using the generated test points
pla_wrong = 0
for i in range (0,Test_Data_Num):
    g_x = np.dot(w.T, test[i, 0:3]) # g(x) = dot(w,x)
    if (test[i, 3] != np.sign(g_x)):
        pla_wrong = pla_wrong + 1 #Count the data points misclassified by PLA.

#If SVM did better than PLA, increase the counter.
if (svm_wrong_counter < pla_wrong):
    SVM_better_than_PLA = SVM_better_than_PLA + 1

print("svm better than pla: %d times " % SVM_better_than_PLA)
print("svm better than pla: %.2f percent" % (SVM_better_than_PLA/Total_Run))
print('Average Number of Support Vectors: ', Total_Support_Vector_Num/Total_Run) #For Problem 10

```

---