

Data Structures and Algorithms Design

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Recap

- Sorting problem
- Insertion sort, Selection sort
- Priority Queue ADT

Outline

- Heaps
- Heap-sort
- Dictionary ADT

Sorting Problem

- Input : A sequence of n numbers $\langle a_1, a_2, \dots, a_n \rangle$
- Output : A permutation (reordering) $\langle a'_1, a'_2, \dots, a'_n \rangle$ of the input sequence such that $a'_1 \leq a'_2 \leq \dots \leq a'_n$

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- Solutions : Many!
- First Solution : Selection Sort

Priority Queue ADT

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- removeMin, removeFirst, insert

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- In selection sort we use removeMin and insert
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- removeMin, removeFirst, insert
- In selection sort we use removeMin and insert
- In insertion sort we use removeFirst and insert
- Priority queue supports these methods

Sorting using Priority Queue ADT

- We have collection C of n items and we want to sort them.
- First insert each into the priority queue Q using the insert method
- Now remove the minimum element from P and add into C until there are no elements left in Q .

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- n insert operations and n removeMin operations are used.

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Priority Queue Implementation: Heap

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- Can we use some nonlinear data structure to implement the priority queue in an efficient way?
- In heap implementation insert and removeMin methods take $O(\log n)$ time
- From a given collection C insert element into the Priority Queue Q
- Use removeMin on Q and store it in C
- This is known as heap sort and it takes $O(n \log n)$ time

Heaps

- Storing elements and keys in internal nodes of binary tree
- External nodes will not have any element
- Heap-order property and complete binary tree property

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- Keys on path from root node to an external node are in nondecreasing order
- The root node will have the minimum key

Complete binary tree

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- There is a special node called last node
- A heap storing n keys has height $\lceil \log(n + 1) \rceil$

Array representation of a heap

- We can use array to represent heap and index of last node is equal to n
- If there are n keys to be stored, there will be $2n + 1$ nodes in the tree
- But it is not necessary to store all of them in the array representation

Insertion in a heap

- If we want to insert a key k in the heap, first we have to identify the correct external node z .
- Then we perform an `expandExternal(z)` operation: replaces z with an internal node (which has two external nodes)
- Then insert e at the newly created internal node.

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- Then we perform an `expandExternal(z)` operation: replaces z with an internal node (which has two external nodes)
- Then insert e at the newly created internal node.
- It might violate the heap-order property
- Up-heap bubbling to resolve this issue
- Insert method takes $O(\log n)$ time

removeMin in a heap

- First copy the key in the last node to root node
- Now change the last node as external node
- Reassign the last node

removeMin in a heap

- First copy the key in the last node to root node
- Now change the last node as external node
- Reassign the last node
- It might violate the heap-order property
- Down-heap bubbling to resolve this issue
- removeMin method takes $O(\log n)$ time

Heap-sort

- First we have to insert n items and it will take $O(n \log n)$ time
- Then we have to removeMin n times and it will take $O(n \log n)$ time
- So overall running time for heap-sort is $O(n \log n)$

Dictionary ADT

- Store items (k, e)
- `search(k)`, `insert(k,e)`, `remove(k)`
- `size()`, `isEmpty()`

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- Store items in an array, lists
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- Space requirement is $\Theta(n)$

Direct Address Table

- Uses an array to store items
- item (k,e) will be stored in the cell $A[k]$
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- Drawback: Space requirement

Ordered Dictionary ADT

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- Store items (k, e)
- $\text{search}(k)$, $\text{insert}(k, e)$, $\text{remove}(k)$
- $\text{size}()$, $\text{isEmpty}()$
- $\text{successor}(k)$, $\text{predecessor}(k)$
- $\text{maximum}(k)$, $\text{minimum}(k)$

Look-up table

- Store items in an array but with ordering
- Size of look-up table is $\Theta(n)$

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- Store items in an array but with ordering
- Size of look-up table is $\Theta(n)$
- Use the order to find an element efficiently
- Search takes $O(\log n)$ time
- insert and delete take $O(n)$ time

Binary Search Tree

A Binary Search Tree (BST) is a binary tree with the following properties:

- The key of a node is always greater than the keys of the nodes in its left subtree
- The key of a node is always smaller than the keys of the nodes in its right subtree