



BITS Pilani
Pilani Campus

Course Name : Data Structures & Algorithms Design

A Baskar
Computer Science & Information Systems

Outline



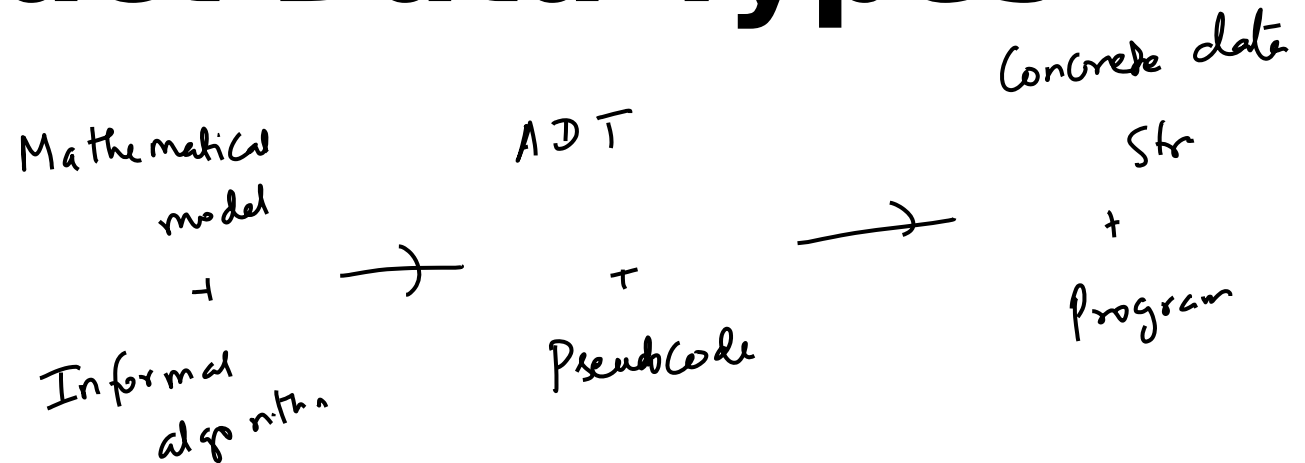
- Abstract Data Types
- Stacks
- Queues

Recap



- Pseudocode
- Primitive operations
- Worst case vs best case
- Asymptotic Analysis, Order notation
- Correctness of Algorithms
- Recursion, Recurrence relations

Abstract Data Types



Abstract Data Type



- An **abstract data type (ADT)** is a mathematical model for a certain class of data structures that have similar behavior.

Abstract Data Types (ADTs)



- A method for achieving abstraction for data structures and algorithms
- ADT = model + operations
- Describes what each operation does, but not how it does it
- An ADT is independent of its implementation

Abstract Data Types

- Typical operations on data
 - Add data to a data collection
 - Remove data from a data collection
 - Ask questions about the data in a data collection

Abstract Data Types

- Data abstraction
 - Asks you to think *what* you can do to a collection of data independently of *how* you do it
 - Allows you to develop each data structure in relative isolation from the rest of the solution
 - A natural extension of procedural abstraction

Examples



- Simple ADTs

- *Stack*✓
- *Queue*✓
- Vector
- Lists ✓
- Sequences
- Iterators

All these are called Linear Data Structures

Stacks

Stacks

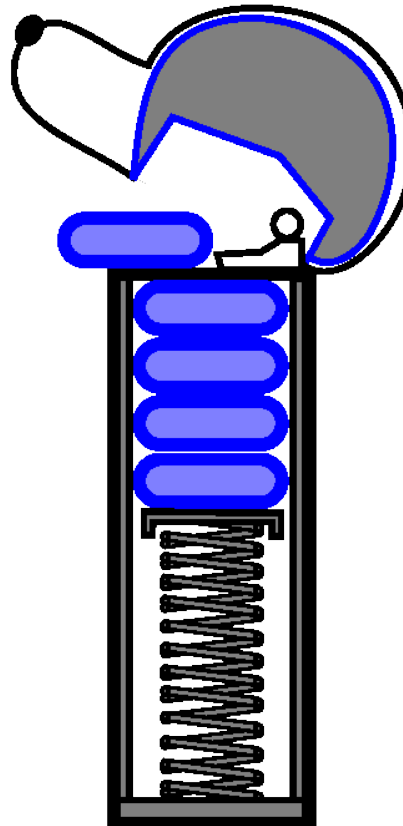


- A **stack** is a container of objects that are inserted and removed according to the last-in-first-out (**LIFO**) principle.
- Objects can be inserted at any time, but only the last (the most-recently inserted) object can be removed.
- Inserting an item is known as “**pushing**” onto the stack.
“**Popping**” off the stack is synonymous with removing an item.

Stacks



- A coin dispenser as an analogy:



Push (e)

Pop () removes the top element

Size ()

Is empty ()

top () doesn't remove the top element

Stacks: An Array Implementation



- Create a stack using an array by specifying a maximum size N for our stack.
- The stack consists of an N -element array S and an integer variable t , the index of the top element in array S .

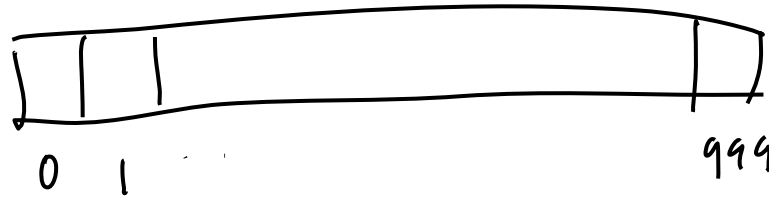


- Array indices start at 0, so we initialize t to -1

$N = 1000$

New ()

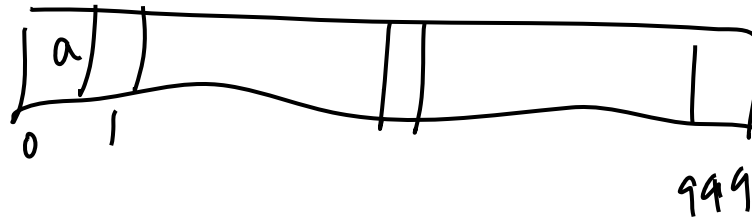
$t = -1$



creates
an array S

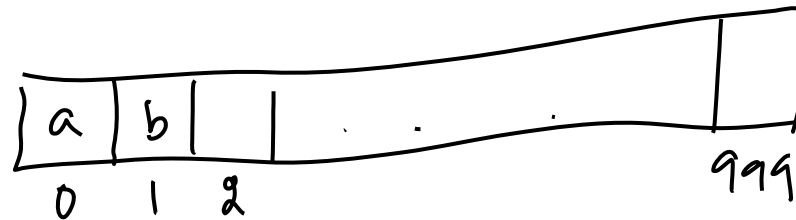
Push (a)

t

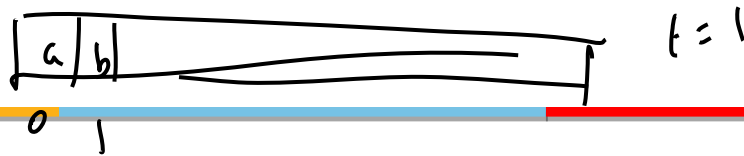


$t = 0$

Push (b)



$t = 1$



Pop ()

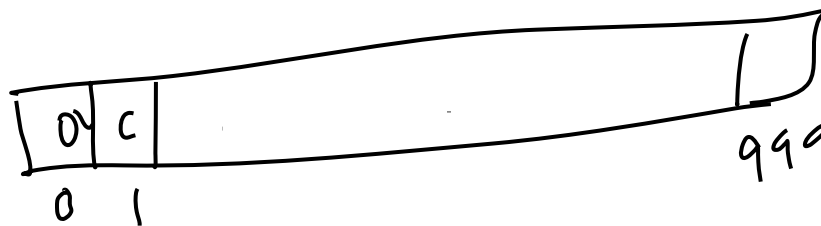


$t=0$

size () return 1

won't access it

Push (c)



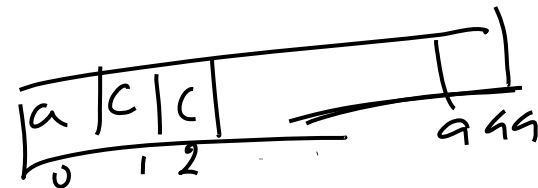
$t=1$

size () return 2

$t+1$

Push (c)

size = N
~~t = N~~
 $t \leftarrow t+1$
~~t = t+1~~ $t=2$



Stacks: An Array Implementation



- **Pseudo code**

```
Algorithm size()  
return t+1
```

```
Algorithm isEmpty()  
return (t < 0)
```

```
Algorithm top()  
if isEmpty() then  
    return Error  
return S[t]
```

```
Algorithm push(o)  
if size() == N then  
    return Error - overflow
```

```
t ← t+1  
S[t] ← o
```

```
Algorithm pop()  
if isEmpty() then  
    return Error
```

```
t ← t-1  
return S[t+1]
```

Handwritten notes:
} return ~~S[t]~~ }
t ← t-1
won't be evaluated



Stack - Array Implementation

Push()	$O(1)$	$O(N)$ Size
Pop()	$O(1)$	
Size()	$O(1)$	
isEmpty()	$O(1)$	
top()	$O(1)$	

Constant operation

Si

Stacks: An Array Implementation



The array implementation is simple and efficient

(methods performed in $O(1)$).

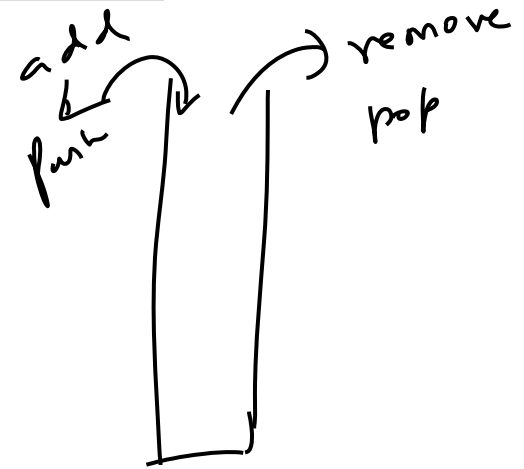
Disadvantage

There is an upper bound, N , on the size of the stack.

The arbitrary value N may be too small for a given application **OR** a waste of memory.

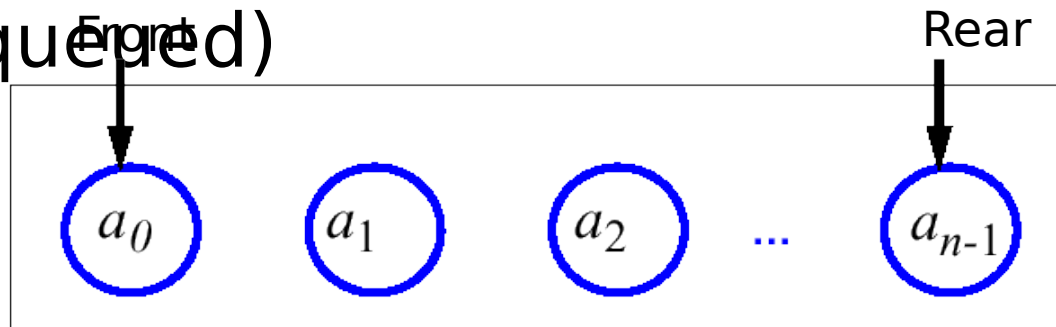
$N = 1 \text{ million}$
 100

QUEUES



Queues

- A queue differs from a stack in that its insertion and removal routines follow the **first-in-first-out** (FIFO) principle.
- Elements may be inserted at any time, but only the element which has been in the queue the longest may be removed.
- Elements are inserted at the **rear** (enqueued) and removed from the **front** (dequeued).



Queues

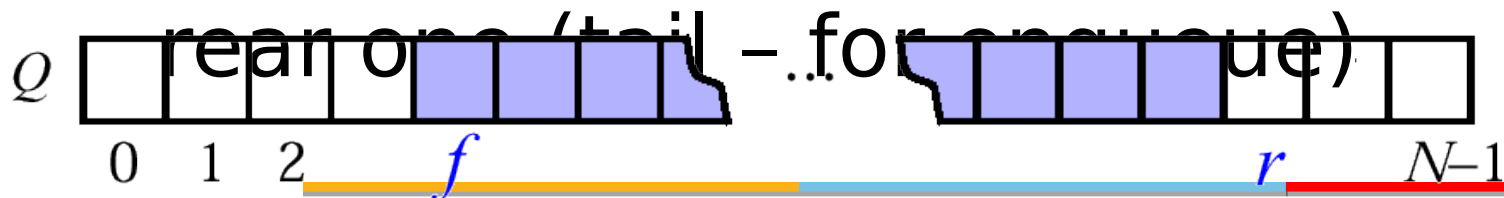


- The **queue** supports the following methods:
 - **New()** – *Creates an empty queue*
 - **Enqueue(S, o)** – Inserts object *o* at the rear of the queue
 - **Dequeue(S)** – Removes the front element from the queue; an error occurs if **S** is empty
 - **Front(S)** – Returns, but does not remove, the front element; an error occurs if **S** is empty

Queues: Array Implementation

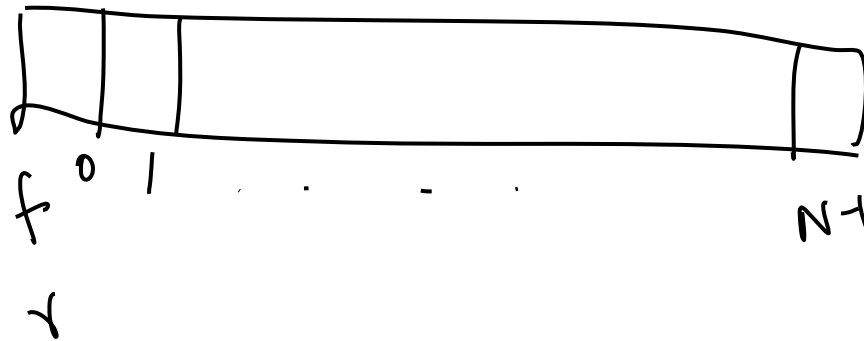


- Create a queue using an array
- A maximum size N is specified.
- The queue consists of an N -element array Q and two integer variables:
 - f , index of the front element (head – for dequeue)
 - r , index of the element after the rear one (tail – for enqueue)



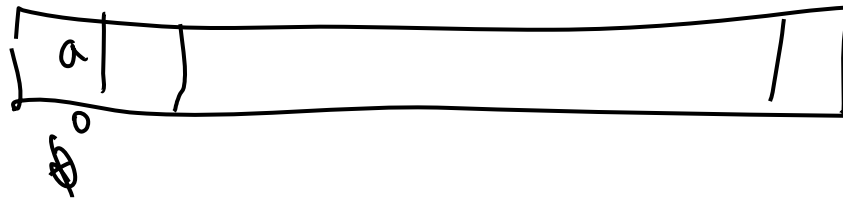
Naive Implementation

New



$$f = r = 0$$

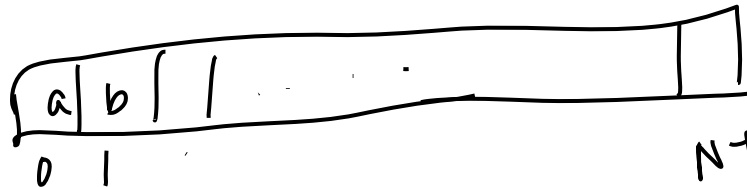
enqueue(a)



$$f = 0$$

$$r = 1$$

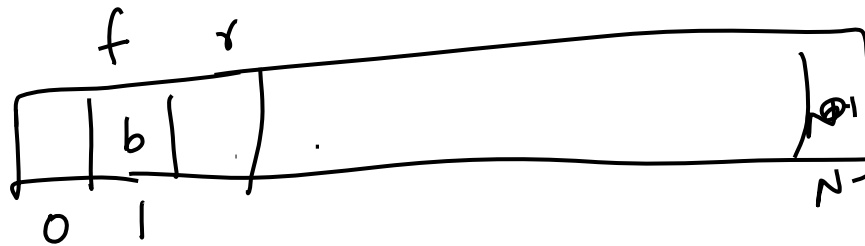
enqueue



$$f = 0$$

$$r = 2$$

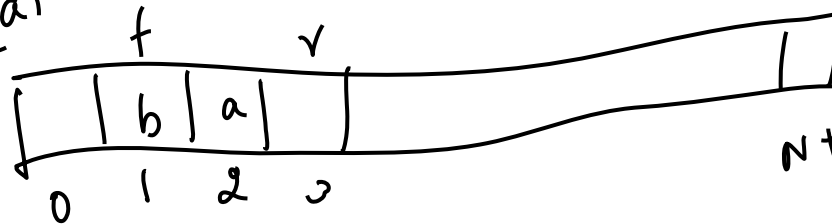
dequeue



$$f = 1$$

$$r = 2$$

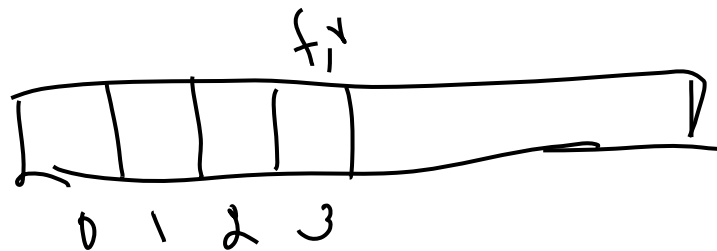
~~dequeue~~
enqueue(a)



$$f = 1$$

$$r = 3$$

dequeue
dequeue



$$f = 3$$

$$r = 3$$

Queue is empty
When $f = r$

Queues: Array implementation



- Initially, $f=r=0$
- The queue is empty if $f=r$

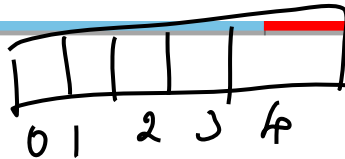


Disadvantage of this implementation



- Repeatedly enqueue and dequeue a single element N times
- Finally, $f=r=N$
- No more elements can be added to the queue, though there is space in the queue

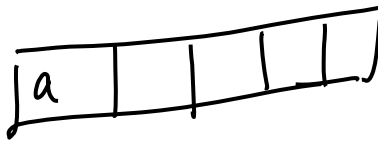
$N = 5$



$f = 0$

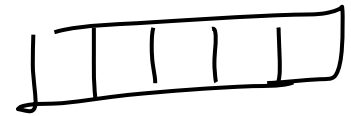
$r = 0$

After the 5^{th} round



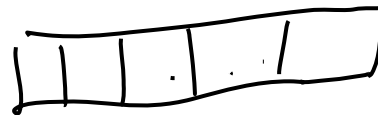
$f = 0$

$r = 1$



$f = 5$

$r = 5$



$f = 1$

$r = 1$

enqueue (a)

↓
Overflow

there is a
space



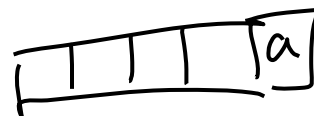
$f = 1$

$r = 2$



$f = 2$

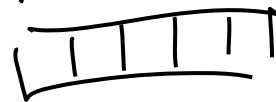
$r = 2$



$f = 4$

$r = 5$

$f' = 5, r' = 5$



1st round { enqueue (a)
dequeue (a)

2nd round { enqueue (a)
dequeue (a)

5th round

enqueue (a)
dequeue (a)

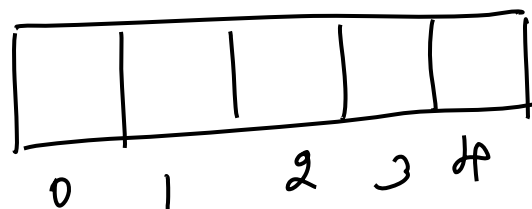
Wrapped Around Implementation



- Let f and r wrap around the end of queue
- Each time r or f is incremented, compute this increment as $(r+1) \bmod N$ or $(f+1) \bmod N$



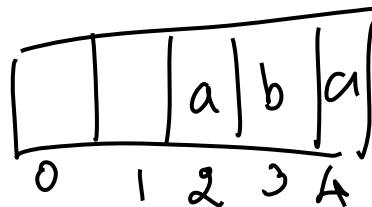
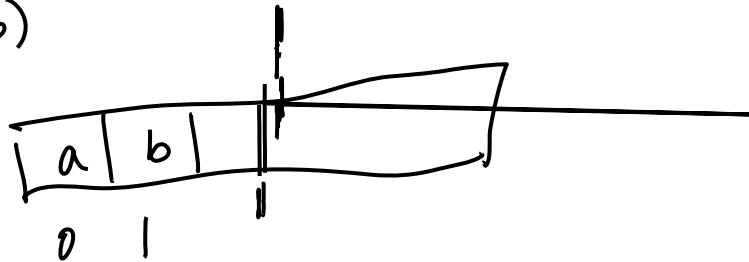
Circular Queue



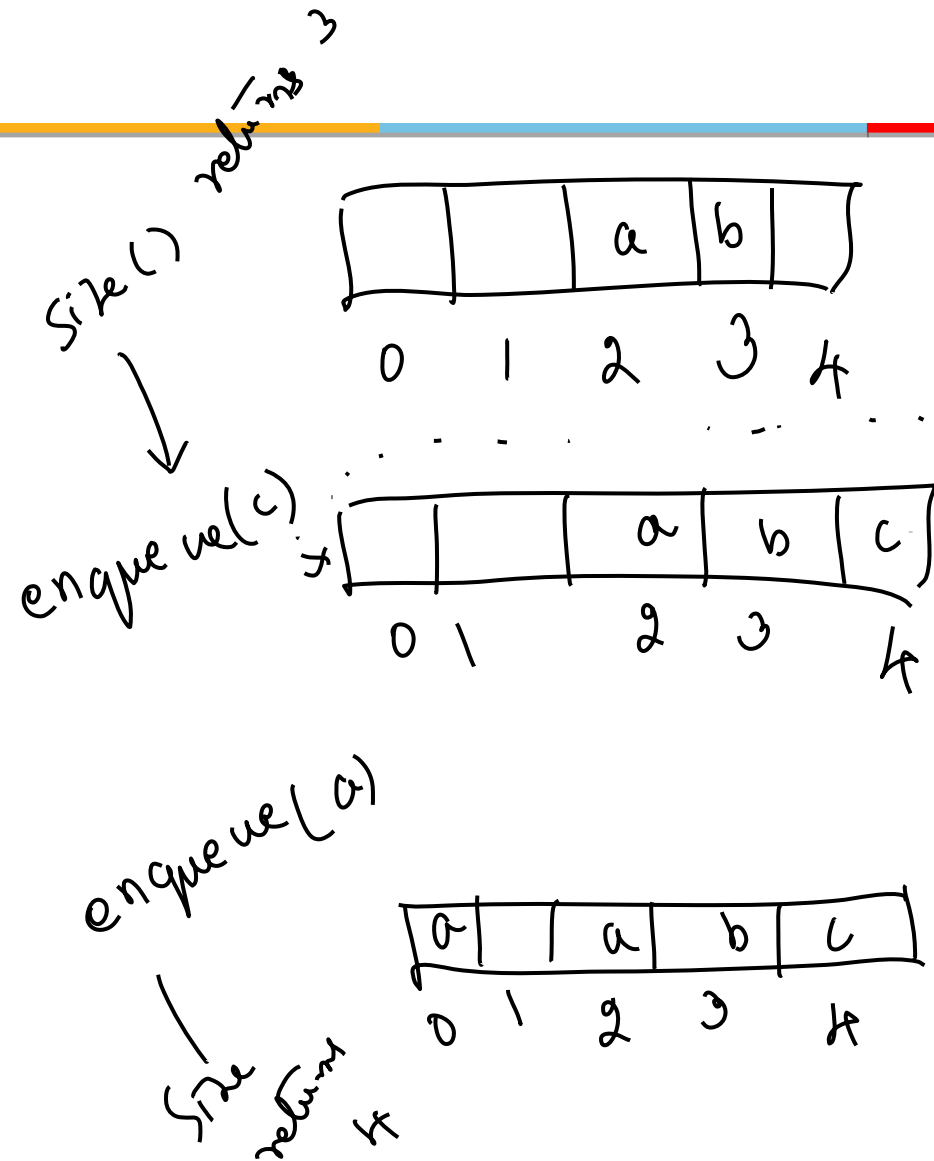
$$f = 0$$

$$r = 0$$

enqueue (a)
enqueue (b)



$f = 2$
 $r = 5$ } Still there
is a space.
checking $f = N$ and
 $r = N$ is not
enough!



$$f = 2$$
$$r = 4$$

$$N = 5$$

$$5 - 2 + 4 = 7 \bmod N$$
$$= 2$$

$$f = 2 \bmod 5$$

$$r = 5 \bmod 5$$
$$= 0$$

to wrap
around the
queue.

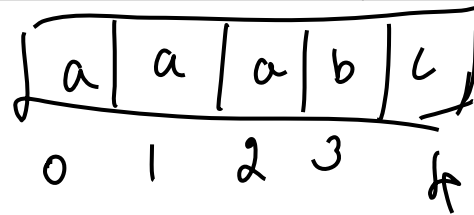
$$\left. \begin{array}{l} f = 2 \\ r = 1 \end{array} \right\}$$

$$N = 5$$

$$N - f + r$$

$$5 - 2 + 1$$
$$\bmod 5$$
$$= 3$$

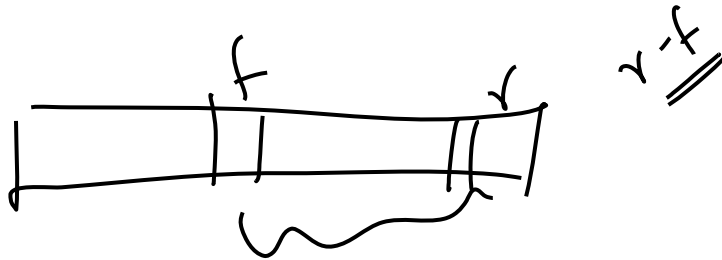
enqueue (a)



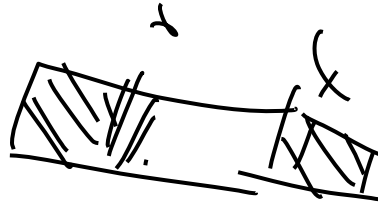
$$f = 2$$

$$r = 2$$

f and r are equal but the queue is not empty.



$$N - f + r$$



To avoid this problem we store at most $(N-1)$ elements in the queue.

Queues: Array Implementation



- Pseudo code

```
Algorithm size()  
return  $(N - f + r) \bmod N$ 
```

```
Algorithm isEmpty()  
return  $(f = r)$ 
```

```
Algorithm front()  
if isEmpty() then  
    return Error  
return Q[f]
```

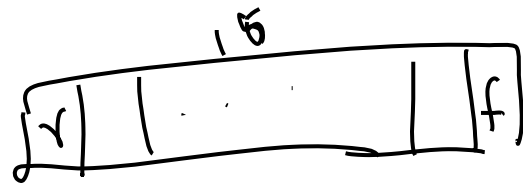

Queues: Array Implementation



- Algorithm **dequeue()**
if isEmpty() **then**
 return Error
Q[f]=null
f=(f+1)modN
- Algorithm **enqueue(o)**
if size = N - 1 **then**
 return Error
Q[r]=o
r=(r + 1)modN

* $O(1)$ time
Queue operations

* $O(N)$ size.

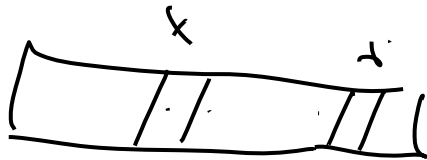


$$\text{Size} = 10$$

$$|r - f| = 10$$

$$m \bmod n$$

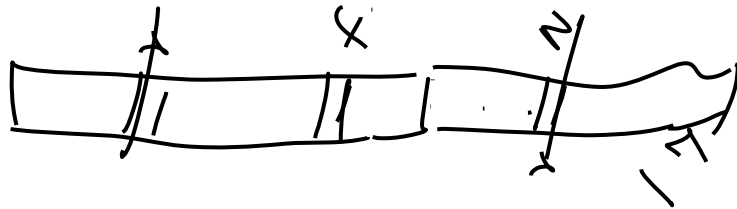
divide m by n and take the remainder.



$$15 - 7 = 8$$

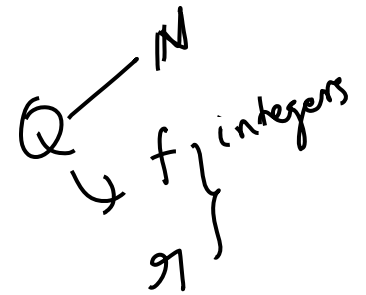
$$15 \bmod 7 = 1$$

$$15 = 2 \cdot 7 + 1$$



$$15 \bmod 7 = 1$$

$$3 \bmod 7 = 3$$



$$5 - 2 + 2 = 5$$

$$= 5 \bmod 5$$

$$= 0$$

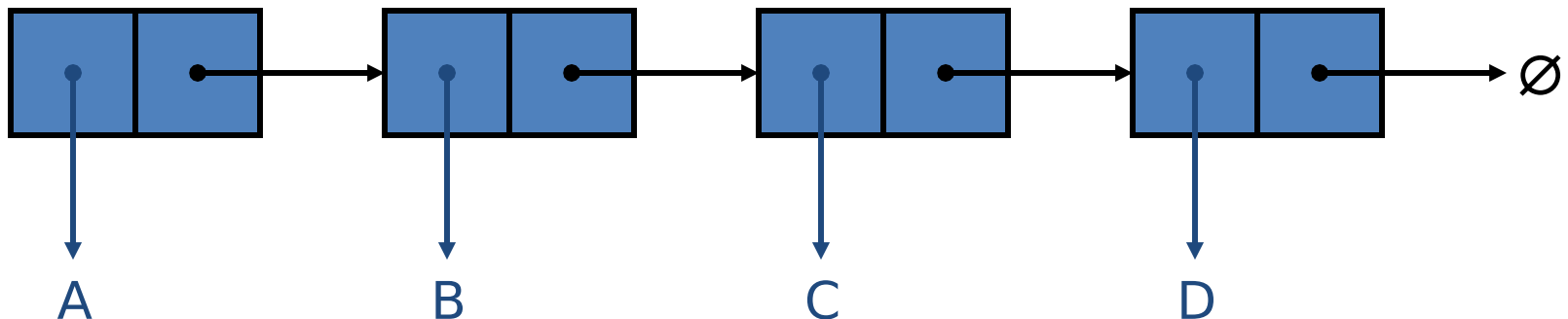
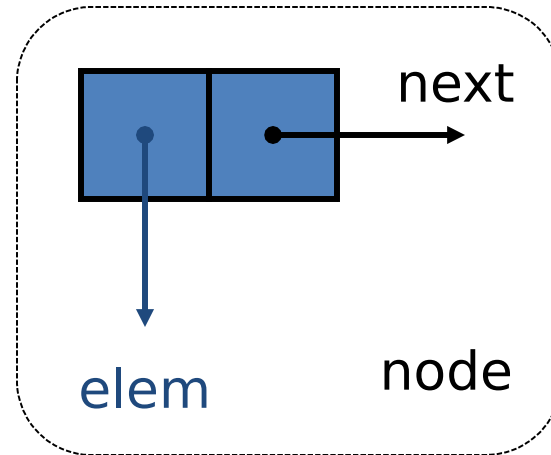
Arrays: pluses and minuses



- + Fast element access.
- Impossible to resize.
- Many applications require resizing!
- Required size not always immediately available.

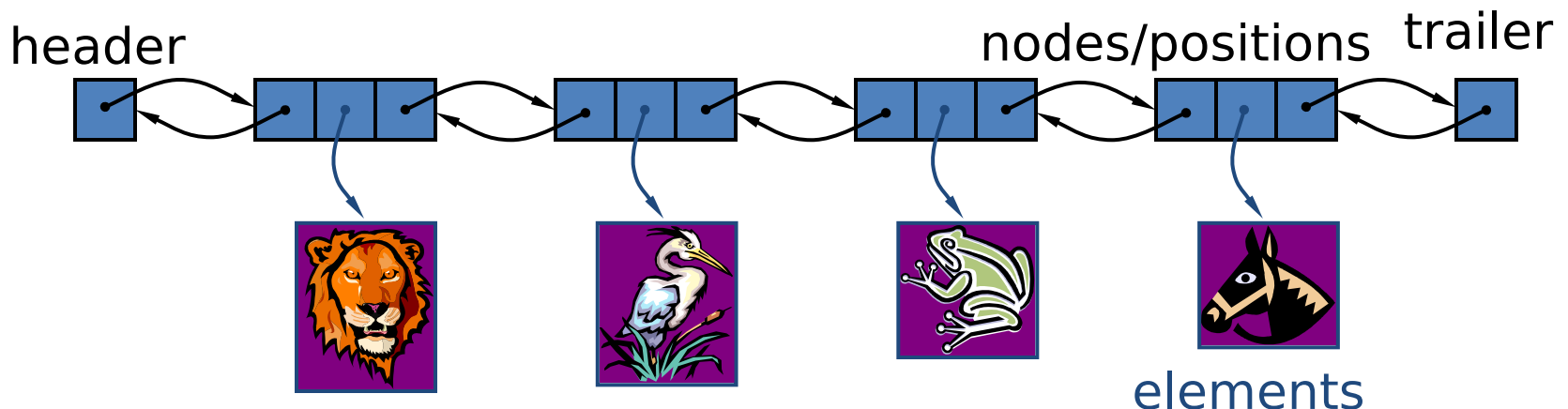
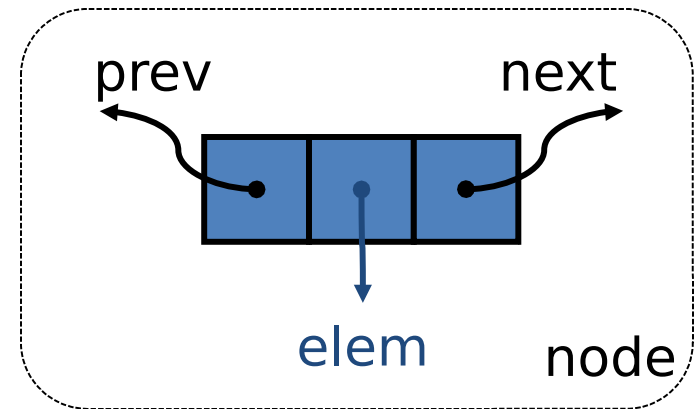
Singly Linked Lists

- A singly linked list is a concrete data structure consisting of a sequence of nodes
- Each node stores
 - element
 - link to the next node



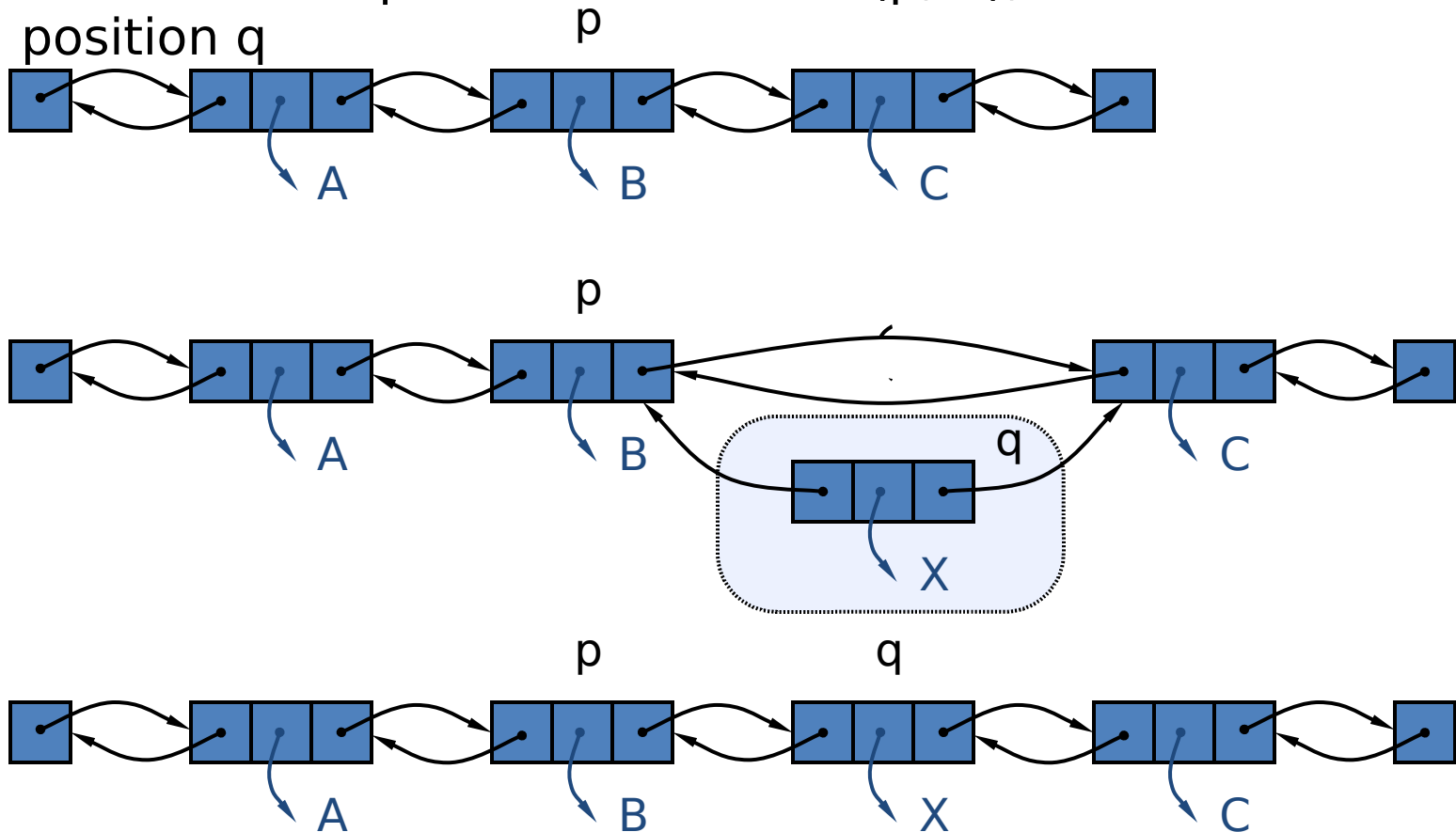
Doubly Linked List

- A doubly linked list is often more convenient!
- Nodes store:
 - element
 - link to the previous node
 - link to the next node
- Special trailer and header nodes



Insertion

- We visualize operation `insertAfter(p, X)`, which returns position `q`



Insertion Algorithm

Algorithm insertAfter(p, e):

Create a new node v

$v.setElement(e)$

$v.setPrev(p)$ {link v to its predecessor}

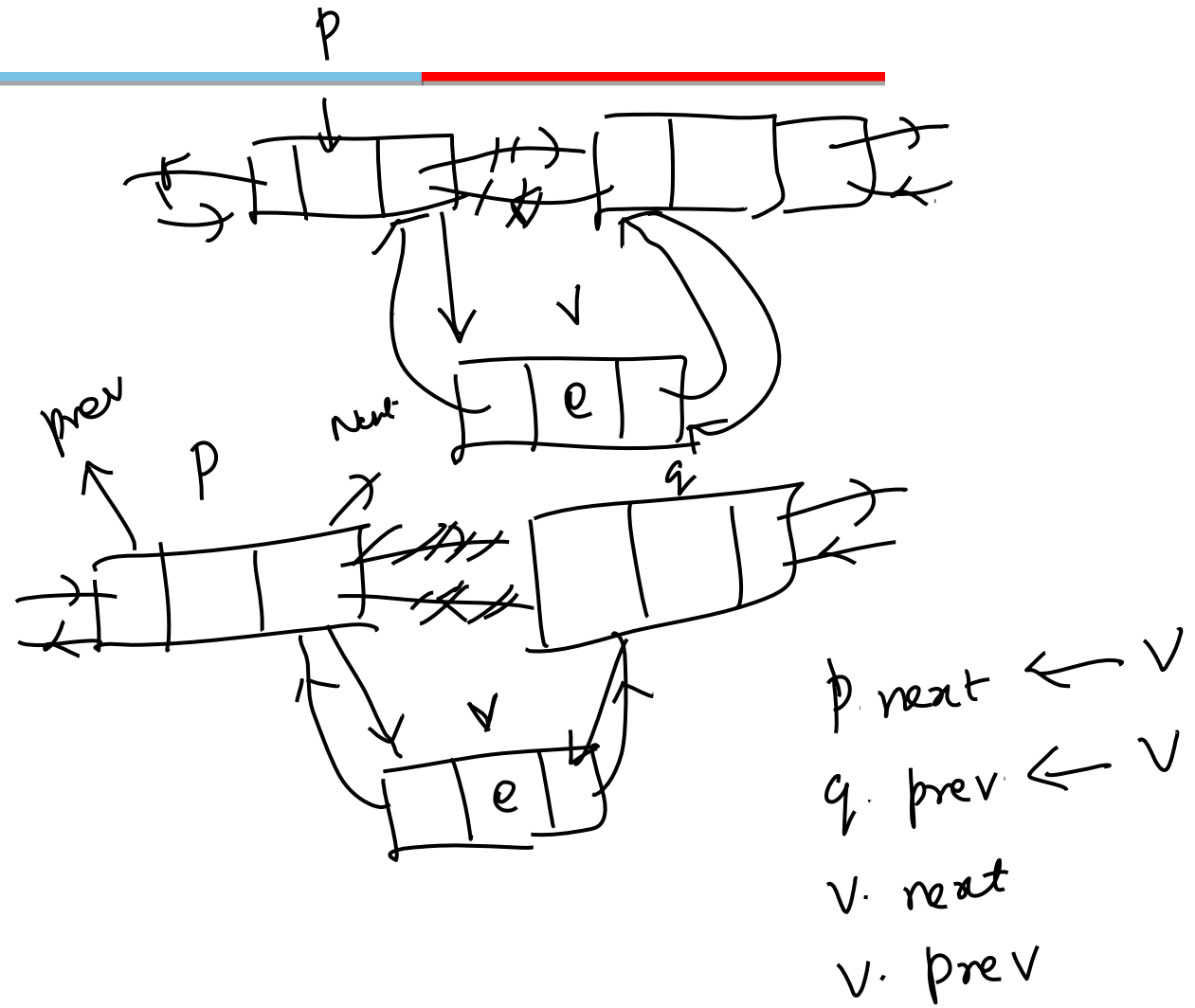
$v.setNext(p.getNext())$ {link v to its
successor}

$(p.getNext()).setPrev(v)$ {link p 's old
successor to v }

$p.setNext(v)$ {link p to its new successor, v }

return v {the position for the element e }

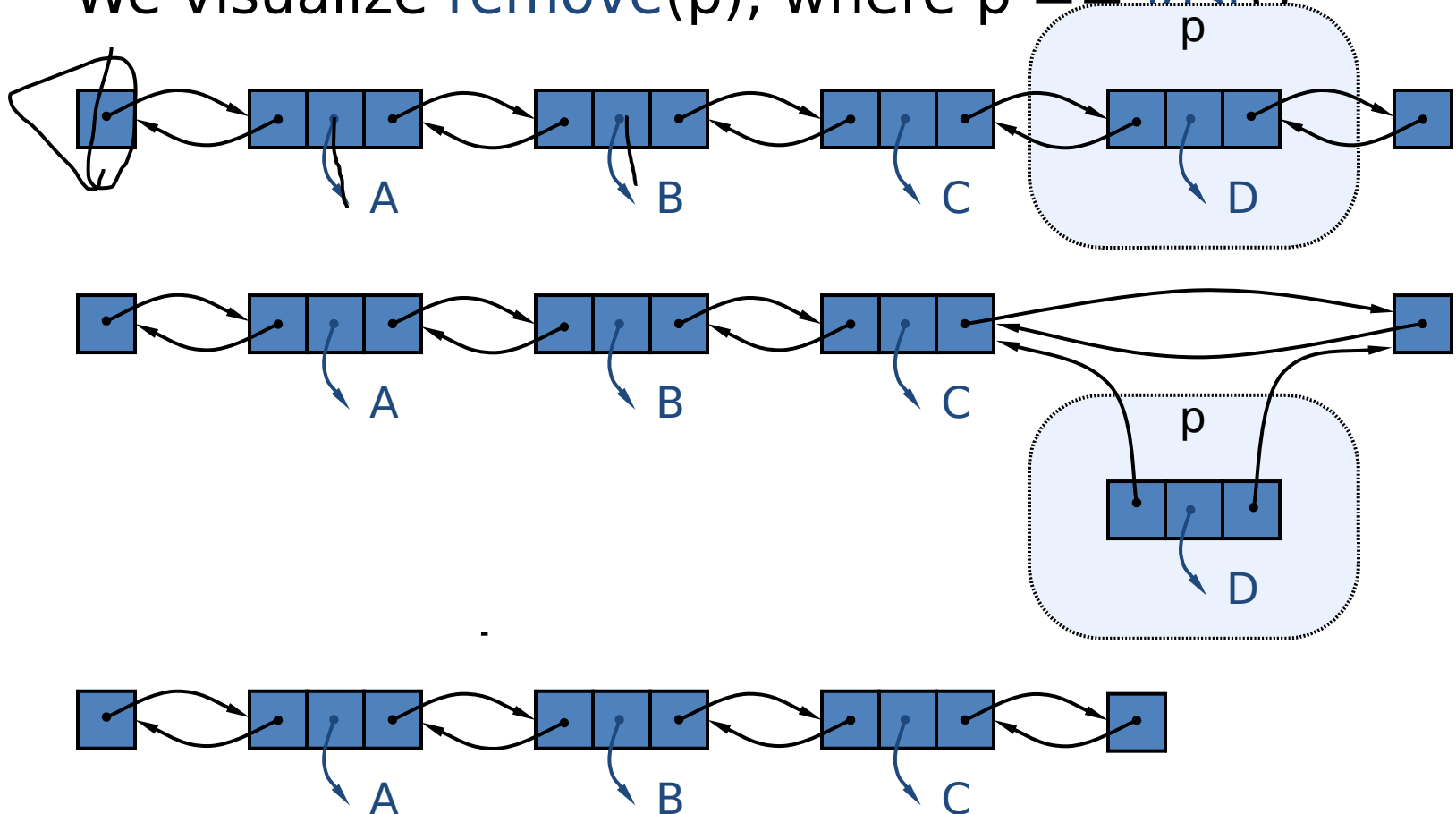
Order
is important



Deletion



- We visualize `remove(p)`, where `p == last()`



Deletion Algorithm

Algorithm remove(p):

$t = p.\text{element}$ {a temporary variable to hold
the return value}

$(p.\text{getPrev}()).\text{setNext}(p.\text{getNext}())$ {linking out
 p }

$(p.\text{getNext}()).\text{setPrev}(p.\text{getPrev}())$

$p.\text{setPrev}(\text{null})$ {invalidating the position p }

$p.\text{setNext}(\text{null})$

return t



Worst-case running time

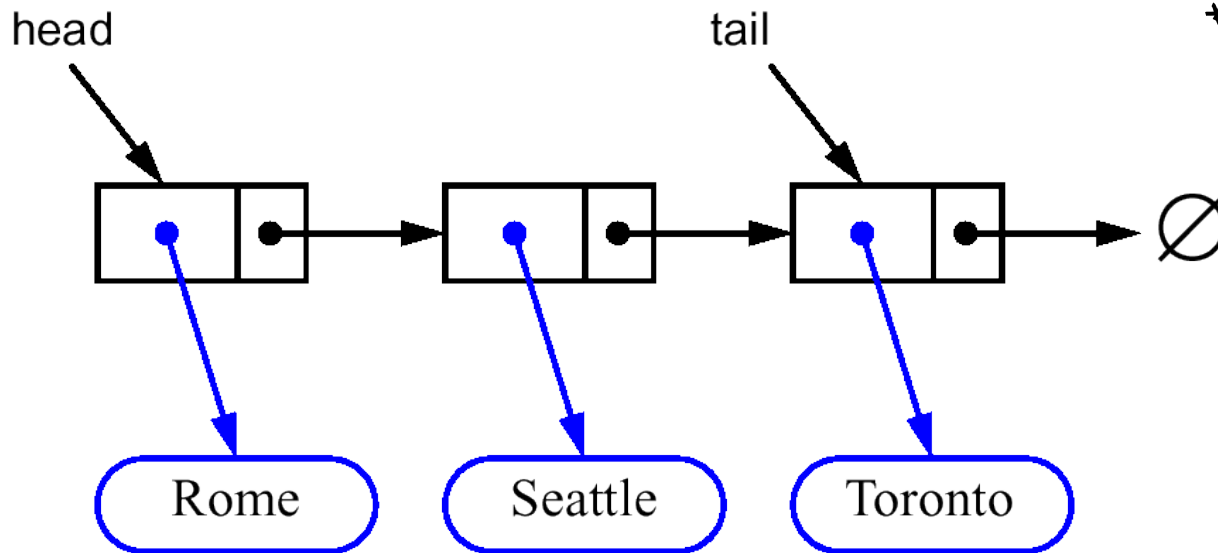
- In a doubly linked list
 - + insertion at head or tail is in $O(1)$
 - + deletion at either end is on $O(1)$
 - element access is still in $O(n)$

Know the position inserting or deleting anywhere
will be $O(1)$
^

Stacks: Singly Linked List implementation



- Nodes (*data, pointer*) connected in a chain by links

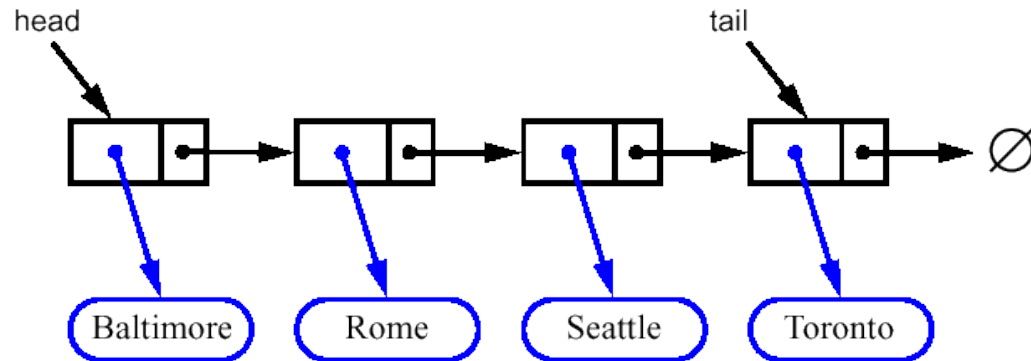


* $O(1)$ time operation

* $O(n)$ where n is the no of elements

- the head or the tail of the list could serve as the top of the stack

Queues: Linked List Implementation



$O(1)$ time operation

$O(n)$ size

- Dequeue - advance head reference

