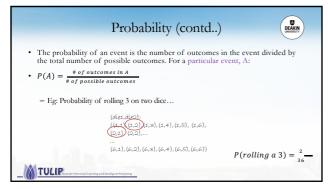
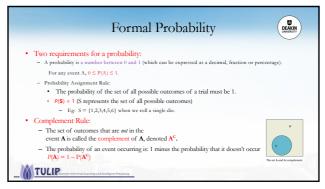
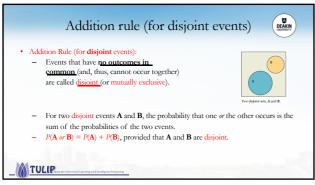


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Multiplication rule (for independent events)

• Multiplication Rule (for independent events):

- For two independent events A and B, the probability that both A and B occur is the product of the probabilities of the two events.

- P(A and B) = P(A) × P(B), provided that A and B are independent.

- Many Statistics topics require an Independence Assumption

• but assuming independence doesn't make it true.

• Always think carefully about whether that assumption is reasonable before using the Multiplication Rule.

Notation:

• In this text we use the notation P(A or B) and P(A and B).

• In or ther situations, you might see the following:

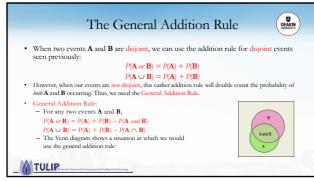
• P(A ∪ B) instead of P(A or B)

• P(A ∩ B) instead of P(A and B)

8

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7



When we want the probability of an event from a conditional distribution, we write P(B | A) and pronounce it "the probability of B given A."

— Eg, the probability that random person from the Titanic passengers surginal IBL given that they were male (A).

A probability that takes into account a given condition is called a conditional probability.

Example: If I am rolling a dice

What is the probability of getting an even number?

— What is the probability of getting a 2?

P(getting 2') = 1/6

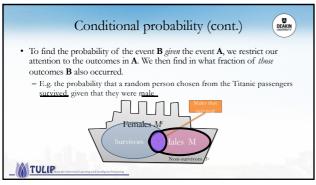
If you are half that number that I obtained is an even number, then what is the probability of getting a '2?

P(getting 2') = 1/3

Note that P(getting 2') | rew number) > P(getting 2')

That it, knowing the information that an 'trea number' has scarred, improved the probability of the event 'getting a '2'.

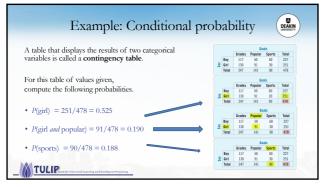
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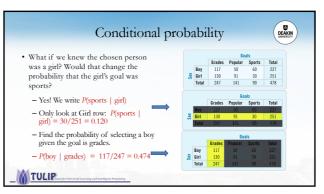


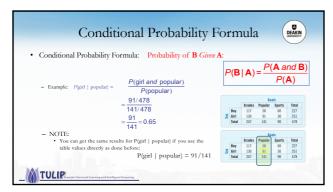
Conditional probability (cont.)

• To find the probability of the event **B** given the event **A**, we restrict our attention to the outcomes in **A**. We then find in what fraction of those outcomes **B** also occurred. $P(B/A) = \frac{P(B \text{ and } A)}{P(A)}$ • Note: P(A) cannot equal 0, since we know that **A** has occurred.

- In the Titanic example, we write $P(Survived \mid Male) = \frac{P(Survived \text{ and } Male)}{P(Male)}$







The General Multiplication Rule (cont.)

• When two events **A** and **B** are independent, we can use the multiplication rule for independent events:

• P(**A** and **B**) = P(**A**) x P(**B**)

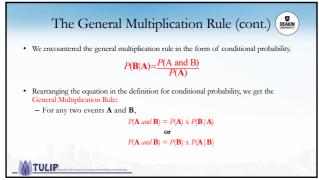
• However, when our events are not independent, this earlier multiplication rule does not work. Thus, we need the General Multiplication Rule.

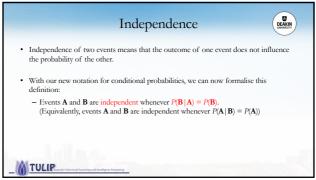
• We encountered the general multiplication rule in the form of conditional probability.

• P(**B**|**A**) = P(**A** and B)
P(**A**)

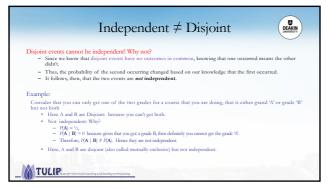
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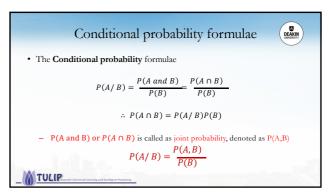
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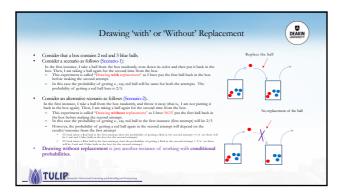


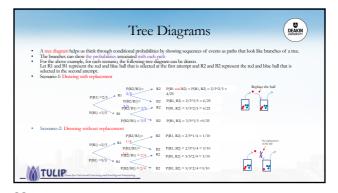


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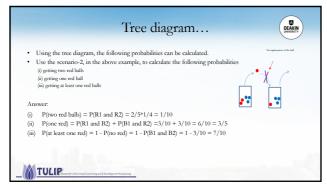


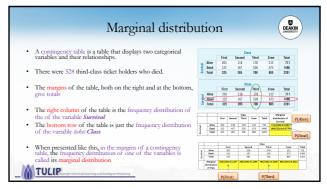




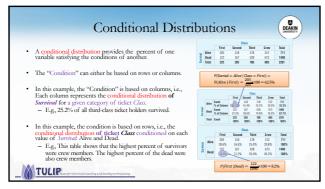


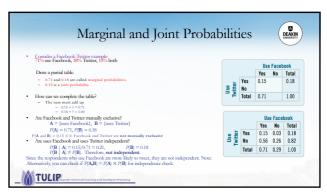
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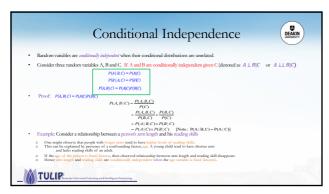


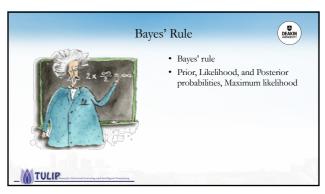


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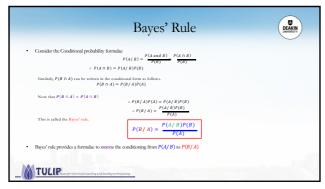


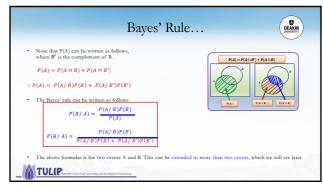




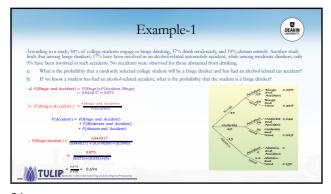


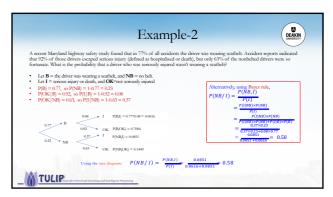
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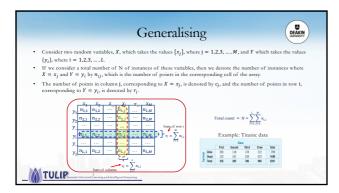


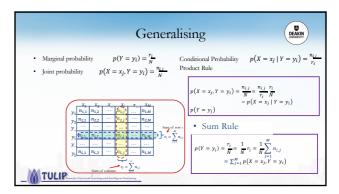


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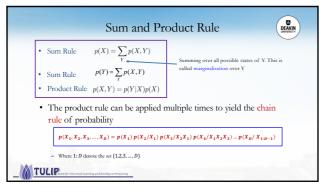


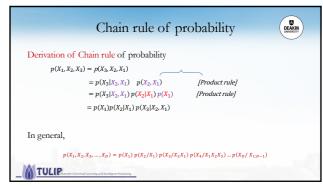




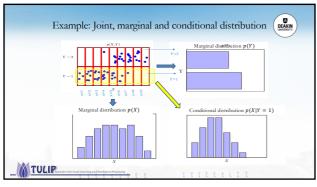


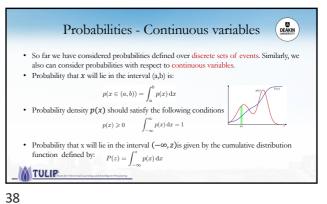
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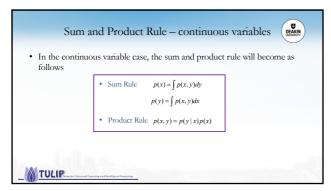


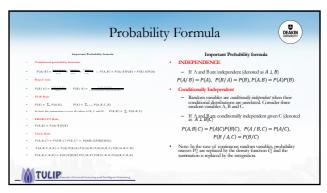


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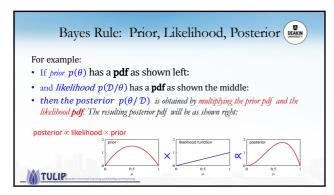


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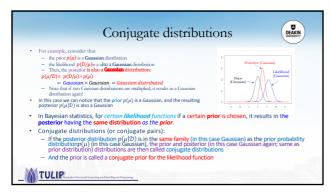




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Conjugate pairs

Recall the example with Gaussian,

- p(μ/D) ≈ p(D/p) × p(ω)

- consider that the prior p(ω) is a Gaussian distribution, the likelihood p(D/p) is distribution

- consider that the prior p(ω) is a Gaussian distribution as a Gaussian distribution.

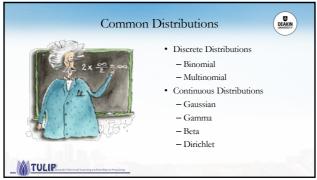
- Note that if woo Gaussian distribution are malipided, it results in another Gaussian distribution again p(μ/D) ≈ p(D/p) × p(ω)

- p(μ/D) ≈ p(D/p) × p(ω)

- p(μ/D) = Gaussian Son Sonsissian Gaussian distributed

- We can easily find the posterior distribution parameters by samply combing (as a function of) prior and likelihood distribution parameters: if Point ~ N(ω, ωⁿ) and Likelihood ~ N(ω, ωⁿ), where μ_θ and σ_φ can be Gaussian distribution parameters: if Point ~ N(ω, ωⁿ) and Likelihood ~ N(ω, ωⁿ), where μ_θ and σ_φ can be Gaussian distribution parameters: if Point ~ N(ω, ωⁿ) and Likelihood ~ N(ω, ωⁿ), where μ_θ and σ_φ can be Gaussian distribution parameters: if Point ~ N(ω, ωⁿ) and Likelihood ~ N(ω, ωⁿ), where μ_θ and σ_φ can be Gaussian distribution parameters: if Point ~ N(ω, ωⁿ) and Likelihood ~ N(ω, ωⁿ), where μ_θ and σ_φ can be Gaussian distribution parameters: if Point ~ N(ω, ωⁿ) and Likelihood ~ N(ω, ωⁿ), where μ_θ and σ_φ can be Gaussian distribution parameters: if Point ~ N(ω, ωⁿ) and Likelihood ~ N(ω, ωⁿ), where μ_θ and σ_φ are the Gaussian distribution parameters: if Point ~ N(ω, ωⁿ) and Likelihood ~ N(ω, ωⁿ) and σ_φ are the Gaussian distribution parameters: if Point ~ N(ω, ωⁿ) and Likelihood ~ N(ω, ωⁿ) and σ_φ and σ_φ can be Gaussian distribution parameters: if Point ~ N(ω, ωⁿ) and distribution parameters: if Point ~ N(ω, ωⁿ) a

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Before we learn further about the possible conjugate prior pdfs and the Frequentists and Bayesian estimation methods (next week), first we will learn about some of the useful probability distributions (both discrete distributions and continuous distributions).

In particular, we will look at

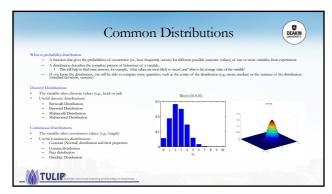
What parameters are used for each distribution

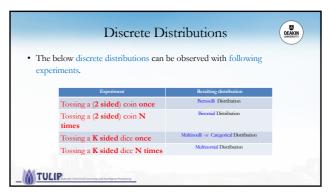
How the distribution function looks like

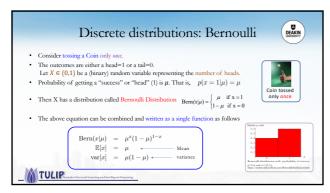
How to find (look up for) the mean and standard deviation/variance of those distributions

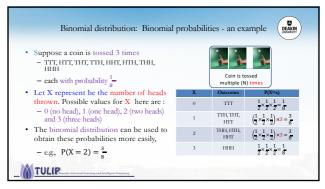
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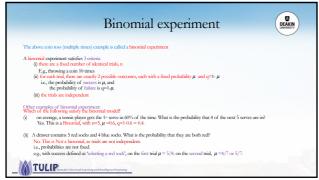


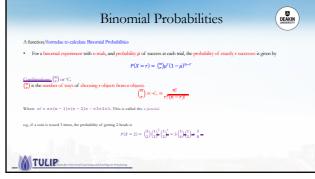




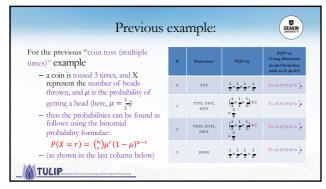


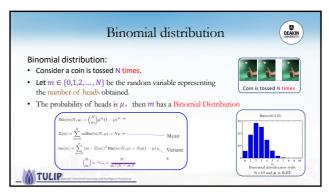
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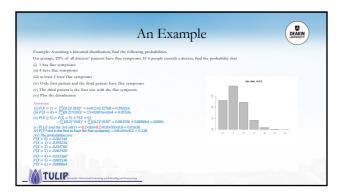


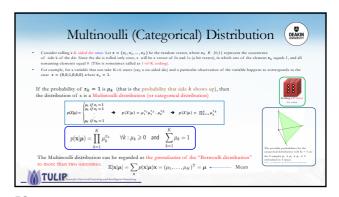


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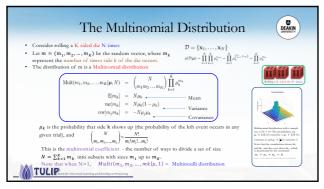


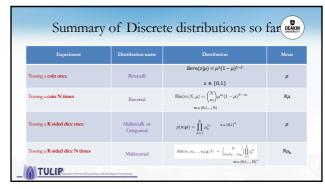




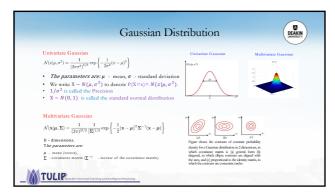


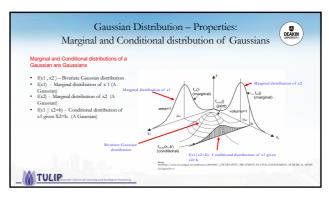
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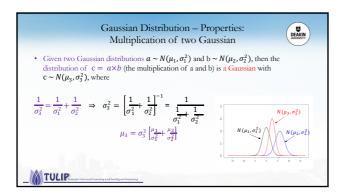


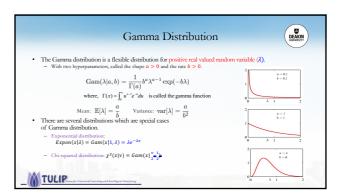


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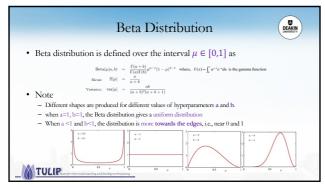


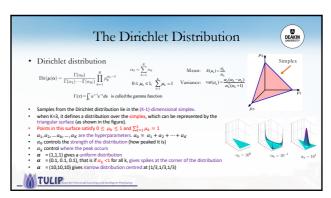


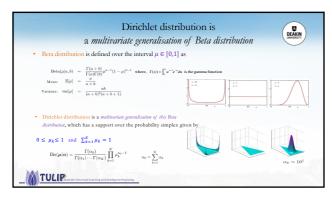


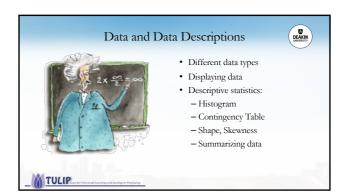


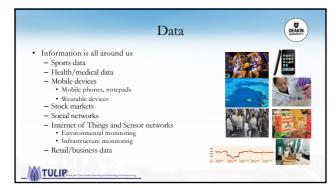
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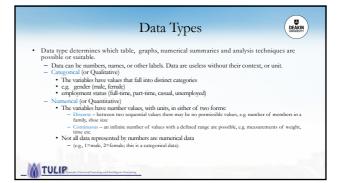






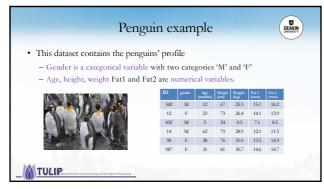






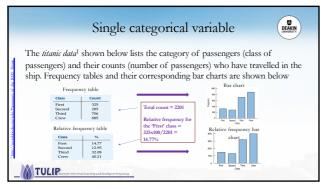
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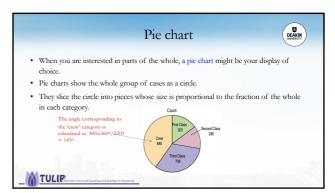
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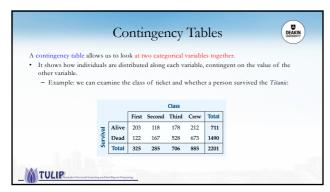




71 72







Displaying Quantitative/Numerical Data

• Summarising the data will help us when we look at large sets of quantitative data.

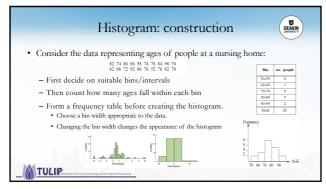
• Without summaries of the data, it's hard to grasp what the data tell us.

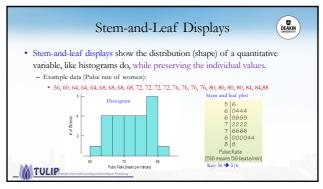
• Displaying numerical data

- Histogram

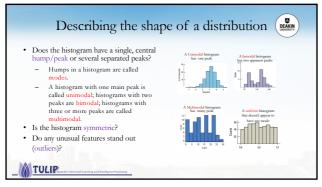
- Stem and leaf plot

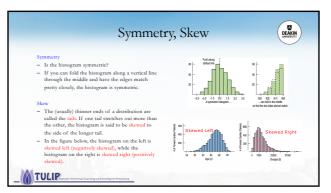
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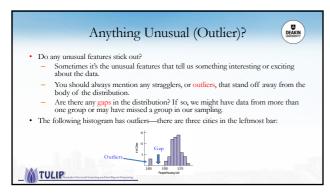


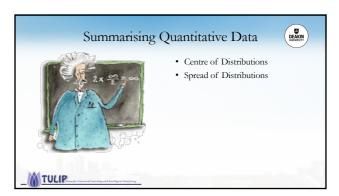


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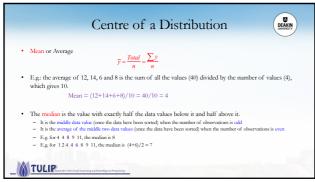






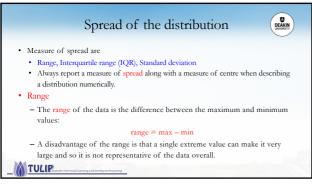


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Centre of a Distribution
In symmetric distributions, the mean and median are approximately the same in value, so either measure of centre may be used.
For skewed data, it's better to report the median than the mean as a measure of centre, as the mean is 'pulled' in the direction of the skewness.

83



Interquartile Range (IQR)

Interquartile Range (IQR)

It us ignore extreme data values and concentrate on the middle of the data.

To find the IQR, we first need to know what quartiles are...

Quartiles divide the data into four equal sections.

One quarter of the data lies below the lower quartile (first quartile), Q1

One quarter of the data lies above the upper quartile (first quartile), Q1

The quartiles can be thought of as the median of each half of the data.

E.g find the quartiles for the following data:

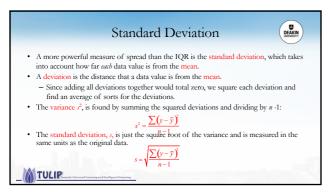
3.58 3.50 4.01 4.05 4.05 4.12 4.18 4.20 4.21

4.27 4.28 4.30 4.32 4.33 4.35 4.35 4.41 4.42 4.45

Q1 = (4.95 + 4.95)(2 = 4.95)
Q1 = (4.9

86

85



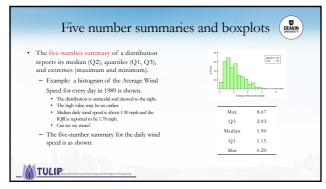
Shape, Centre and Spread

• Always report the shape of a distribution, along with a centre and a spread.

— If the shape is skewed or has outliers, report the median and IQR.

— If the shape is symmetric, report the mean and standard deviation and possibly the median and IQR as well.

87 88



A boxplot is a graphical display of the five-number summary.

Boxplos are particularly useful when comparing groups, and for a dentifying coaliers.

Steps to draw a box plot is:

1. Draw a single vertical axis spanning the range of the data. Draw short horizontal lines at the lower and upper quartile, and at the median. Then connect them with vertical lines to form a box.

2. Exect "finence" around the main part of the data. (Note that for the above example IQR = Q3 - Q1 = 293-1.15=1.78)

1.15=1.78)

1. The upper fence is 1.5 IQRs above the upper quartile, (Q3 + 1.5*IQRs) = 2.93 + 1.5*1.78 = 5.6

1. The lower fence is 1.5 IQRs below the lower quartile, (Q1 + 1.5*IQR) = 1.15 - 1.5*1.78 = 1.2

Note: the fences of are "whiskers."

1. Use the fences of are "whiskers."

1. If a data value falls outside one of the fences, we do not connect it with a whisker.

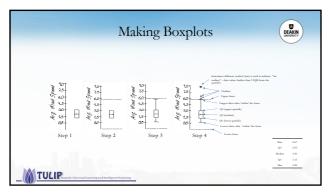
1. If a data value falls outside one of the fences, we do not connect it with a whisker.

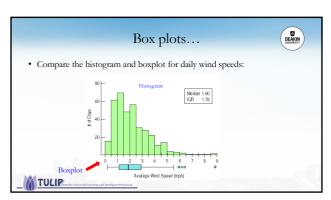
4. Add the outliers by displaying any data values beyond the fences with special symbols.

1. We often use a different symbol for "fair outliers" that are farther than 3 IQRs from the quartiles and the control of the co

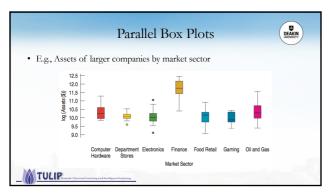
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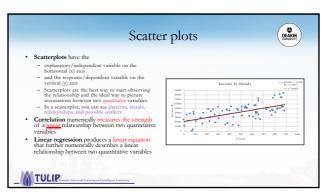
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93 94

Correlation coefficient and Coefficient of Determination

• The correlation coefficient (r) gives us a numerical measurement of the strength of the "linear relationship" between the explanatory and response variables.

• Formula $r = \frac{\sum (x - \bar{x})(y - \bar{y})}{(n - 1)s_x s_y} \qquad x, y - mean \text{ of } x \text{ and } y$ $s_x, s_y - \text{ Std. deviation of } x \text{ and } y$ • Correlation is always between -1 and +1.

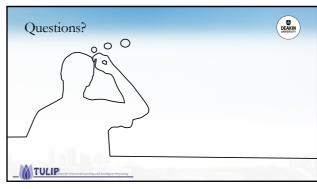
• Correlation are be exactly equal to -1 or +1, but these values are unusual in real data because they mean that all the data points fill county on a single straight line.

• A correlation care recoverseponds to a weak linear association.

• r < 0 stands for negatively correlated and r < 0 stands for positively correlated

• Coefficient of determination (r^2):

• The squared correlation, r^2 , gives the fraction of the data's variance accounted for by the model.



95 97