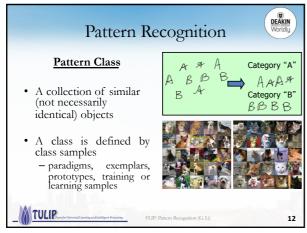
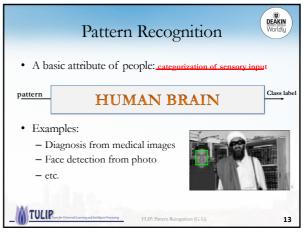


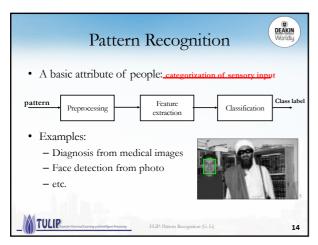
DEAKIN Worldly Pattern Recognition Recognition Category "A" BB AAAA · Identification of a В Category "B" pattern as a member of BBBB a category we already Classification know, or we are familiar with Classification (known categories) Clustering (learning categories) Clustering

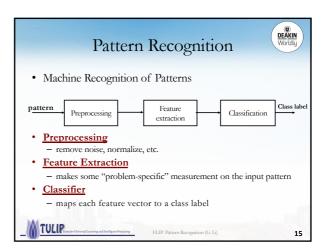
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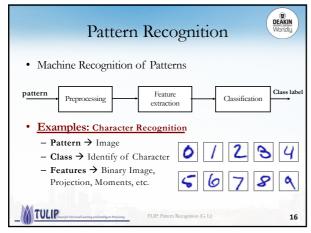


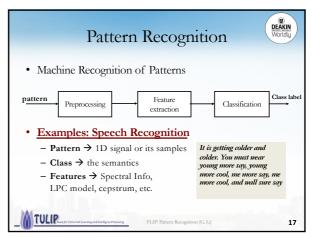


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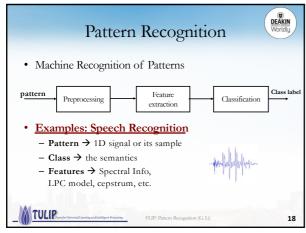


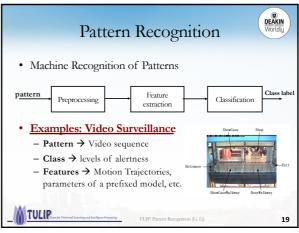




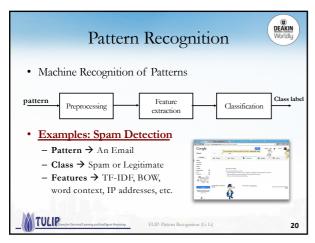


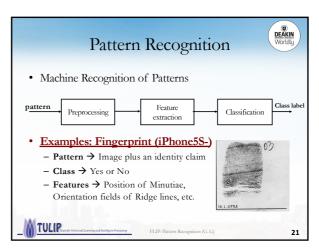
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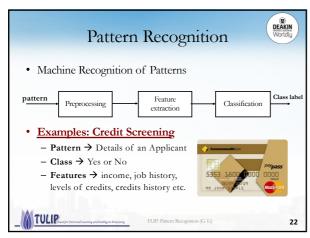


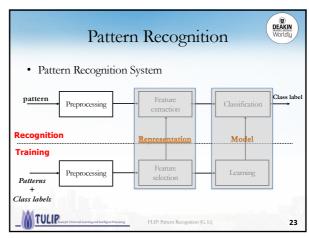


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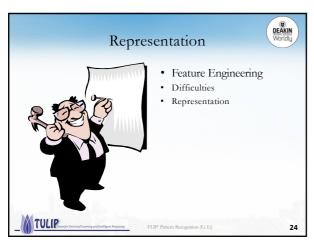


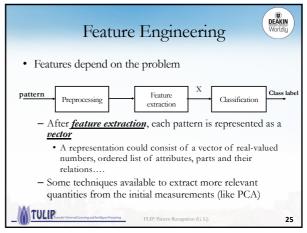




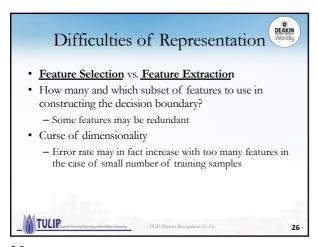


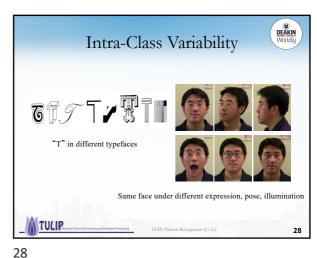
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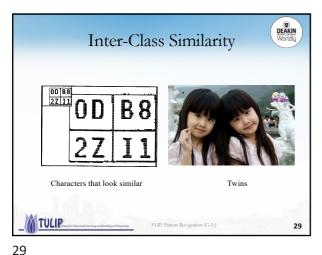




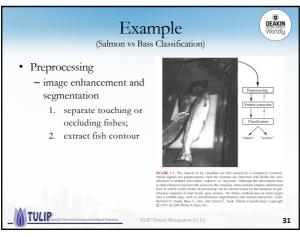
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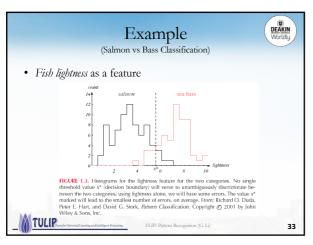


DEAKIN Worldly Good Representation Account for <u>intra-class variations</u> Ability to discriminate pattern classes of interest; - low inter-class similarity • Should have some *invariant* properties - e.g., w.r.t. rotation, translation, scale... Robustness to noise, occlusion,.. Lead to simple matching or decision-making strategies (e.g., linear decision boundary) Low measurement cost; real-time



Example (Salmon vs Bass Classification) • Fish length as a feature

32 31



Example
(Salmon vs Bass Classification)

• There are two possible classification errors.

1. Deciding the fish was a sea bass when it was a salmon.

2. Deciding the fish was a salmon when it was a sea bass.

• Which error is more important?

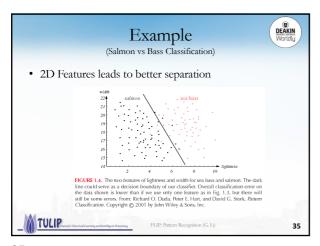
— It depends; e.g., if the fish packing company knows that:

• Customers who buy salmon will object vigorously if they see sea bass in their cans.

• Customers who buy sea bass will not be unhappy if they occasionally see some expensive salmon in their cans.

• How does this knowledge affect our decision?

33 34



How Many Features

• Does adding more features always improve the results?

- Correlated features do not improve performance.

- It might be difficult to extract certain features.

- It might be computationally expensive to extract many features.

- "Curse" of dimensionality ...

35 36

How Many Features

 Adding too many features can, paradoxically, lead to a worsening of performance.

 Divide each of the input features into a number of intervals, so that the value of a feature can be specified approximately by saying in which interval it lies.

 If each input feature is divided into M divisions, then the total number of cells is M^d (d: # of features) which grows exponentially with d.

 Since each cell must contain at least one point, the number of training data grows exponentially!

| TULL | Particular Recognition (C.1.) | 37

Representation

• Each pattern is represented as a point in d-dimensional feature space

- Choice of features and their invariance properties are domain-specific

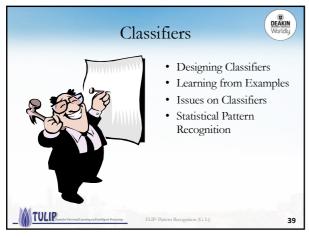
• Good representation implies

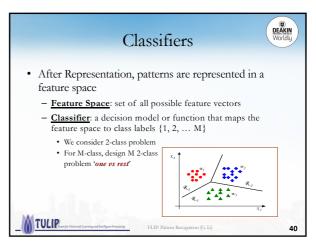
1. small intra-class variation,

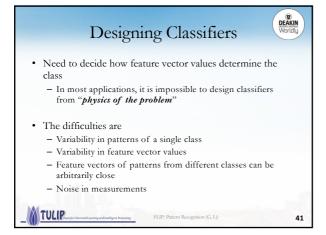
2. large inter-class separation and

3. simple decision boundary

37 38







• Often the only information available for the design is a training set of example patterns

• Training Set: {(X_i, Y_i), I = 1, ..., n}

• Take representative patterns of known category and obtain the feature vectors

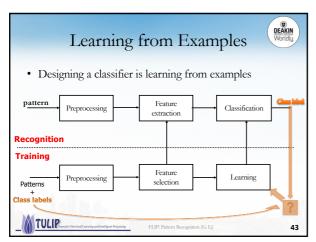
• Now learn an appropriate function h as classifier

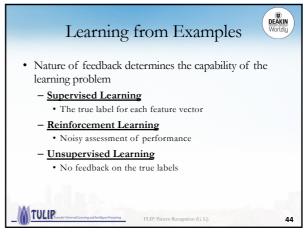
• Model Choice

• Test and validate the classifier on more data

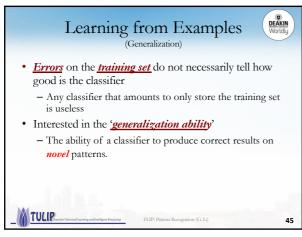
• Noise in measurements

41





43 44



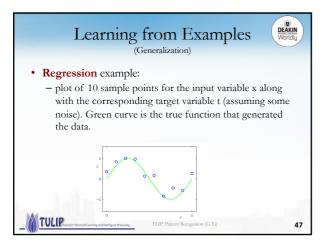
Learning from Examples
(Generalization)

• How can we improve generalization ability?

- More training examples
• i.e., better model estimates

- Simpler models usually yield better performance.
• Occam's Razor

45 46



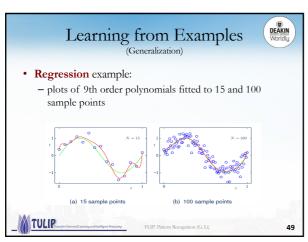
Learning from Examples
(Generalization)

• Regression example:

- plots of polynomials having various orders, shown as red curves, fitted to the set of 10 sample points.

(a) 0'th order polynomial
(b) 1'st order polynomial
(c) 3'rd order polynomial
(d) 9'th order polynomial

47 48



(Salmon vs Bass Classification)

• 2D Features leads to better separation

**Vertility*

**PLIP: Pattern Recognition (C. L.)

(Salmon vs Bass Classification)

• 2D Features leads to better separation

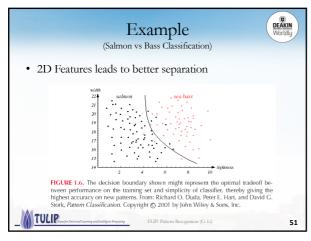
**Vertility*

**PLIP: Pattern Recognition (C. L.)

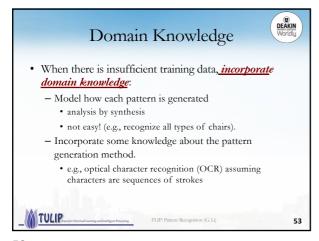
**PLIP: Pattern Recognition (C. L.)

**PLIP: Pattern Recognition (C. L.)

49 50



51 52



Context

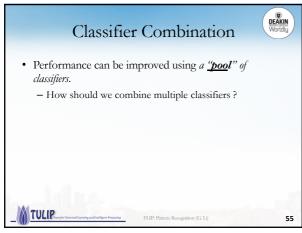
• Utilizing Side Information

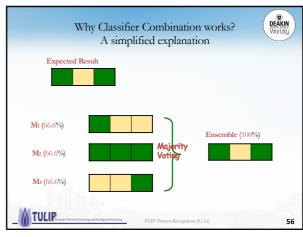
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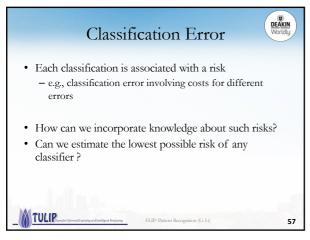
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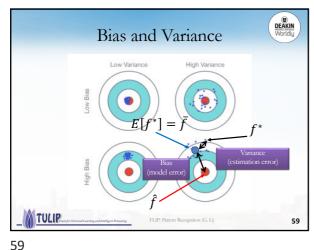


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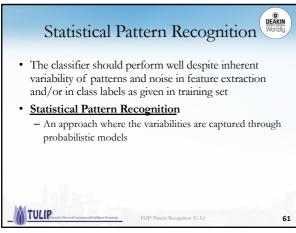


Main Sources of Error in Classifier Design $\sum_{i} p(\mathbf{x}/\omega_{i}, D_{i}) P(\omega_{i})$ Bayes error – The error due to overlapping densities $p(x \mid \omega_i)$ - The error due to choosing an incorrect model. **Estimation error** - The error due to incorrectly estimated parameters - Inadequate training samples TULIP 58

57 58



DEAKIN Worldlu Computational Complexity · How does an algorithm scale with - the number of feature dimensions - the number of patterns - the number of categories Brute-force approaches might lead to perfect classifications results but usually have impractical time and memory requirements. · Consider tradeoffs between computational complexity and performance.



Statistical Pattern Recognition Prior Information COMPLETE (K-NN,MLP) (Hard, Fuzzy)

