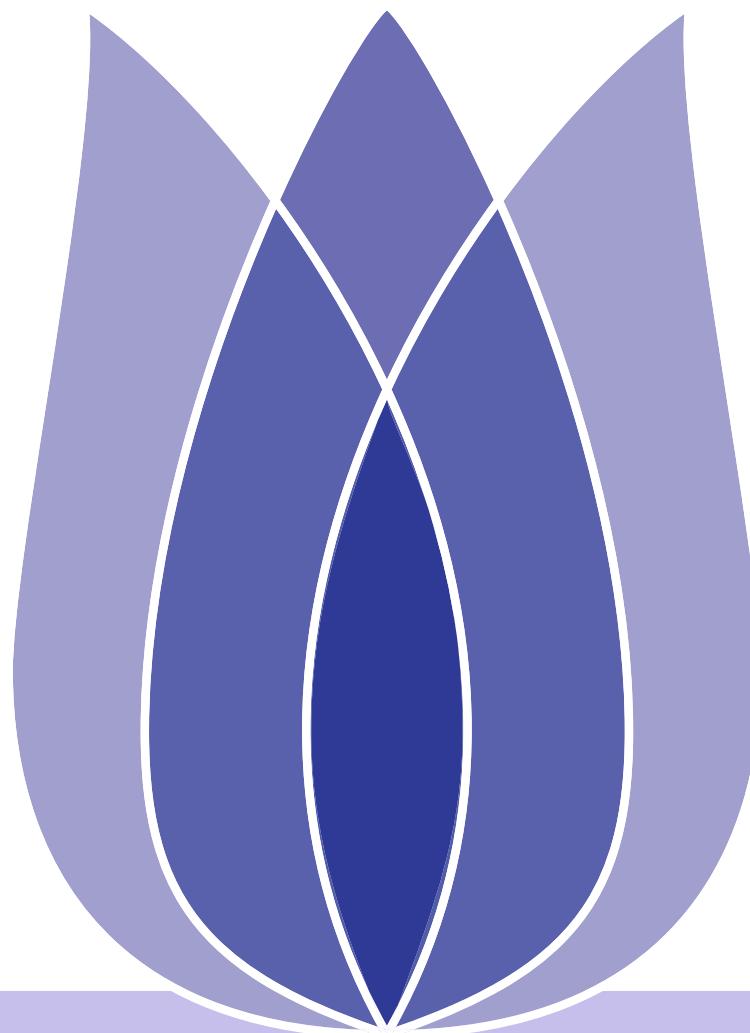




FUNDAMENTALS OF LEARNING AND INFORMATION PROCESSING

# SESSION 14: STATISTICAL MACHINE LEARNING (IV)



Gang Li

Deakin University, Australia

2021-09-19



# Table of Content

[The Fundamental Theorem of PAC Learning](#)

[Learning Beyond Classes with Finite VC Dimension](#)

[Quiz](#)

## The Fundamental Theorem of PAC Learning

The Fundamental Theorem of PAC Learning

The Fundamental Theorem of PAC Learning (Quantitative)

Proof of the Lower Bounds

The Growth Function

Sauer's Lemma

Proof of the Upper Bounds

Symmetrization

*What is Learnable and How to Learn?*

## Learning Beyond Classes with Finite VC Dimension

Nonuniform Learnability

NUL versus A-PAC

Structural Risk Minimization

Minimum Description Length

Consistency Learnability

## Quiz



The Fundamental Theorem of PAC Learning

The Fundamental Theorem of PAC Learning

The Fundamental Theorem of PAC Learning (Quantitative)

Proof of the Lower Bounds

The Growth Function

Sauer's Lemma

Proof of the Upper Bounds

Symmetrization

*What is Learnable and How to Learn?*

Learning Beyond Classes with Finite VC Dimension

---

Quiz

---

# The Fundamental Theorem of PAC Learning



# The Fundamental Theorem of PAC Learning

[The Fundamental Theorem of PAC Learning](#)

[The Fundamental Theorem of PAC Learning](#)

[The Fundamental Theorem of PAC Learning \(Quantitative\)](#)

[Proof of the Lower Bounds](#)

[The Growth Function](#)

[Sauer's Lemma](#)

[Proof of the Upper Bounds](#)

[Symmetrization](#)

[What is Learnable and How to Learn?](#)

[Learning Beyond Classes with Finite VC Dimension](#)

[Quiz](#)

Let  $\mathcal{H}$  be a hypothesis class of functions from a domain  $\mathcal{X}$  to  $\{0, 1\}$ , and let the loss function be the 0 – 1 loss. Then the following statements are equivalent:

- 1.  $\mathcal{H}$  has the **uniform convergence** property
- 2. Any ERM rule is a successful agnostic PAC learner for  $\mathcal{H}$
- 3.  $\mathcal{H}$  is agnostic PAC learnable
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- 6.  $\mathcal{H}$  has a finite VC-dimension





# The Fundamental Theorem of PAC Learning

[The Fundamental Theorem of PAC Learning](#)

[The Fundamental Theorem of PAC Learning](#)

[The Fundamental Theorem of PAC Learning \(Quantitative\)](#)

[Proof of the Lower Bounds](#)

[The Growth Function](#)

[Sauer's Lemma](#)

[Proof of the Upper Bounds](#)

[Symmetrization](#)

[What is Learnable and How to Learn?](#)

[Learning Beyond Classes with Finite VC Dimension](#)

[Quiz](#)

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*Intuition.*

- ① → ② was proved in UC property



# The Fundamental Theorem of PAC Learning

[The Fundamental Theorem of PAC Learning](#)

[The Fundamental Theorem of PAC Learning](#)

[The Fundamental Theorem of PAC Learning \(Quantitative\)](#)

[Proof of the Lower Bounds](#)

[The Growth Function](#)

[Sauer's Lemma](#)

[Proof of the Upper Bounds](#)

[Symmetrization](#)

[What is Learnable and How to Learn?](#)

[Learning Beyond Classes with Finite VC Dimension](#)

[Quiz](#)

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*Intuition.*

- ① → ② was proved in UC property
- ② → ③, ② → ⑤ and ③ → ④ are trivial



# The Fundamental Theorem of PAC Learning

[The Fundamental Theorem of PAC Learning](#)

[The Fundamental Theorem of PAC Learning](#)

[The Fundamental Theorem of PAC Learning \(Quantitative\)](#)

[Proof of the Lower Bounds](#)

[The Growth Function](#)

[Sauer's Lemma](#)

[Proof of the Upper Bounds](#)

[Symmetrization](#)

[What is Learnable and How to Learn?](#)

[Learning Beyond Classes with Finite VC Dimension](#)

[Quiz](#)

Let  $\mathcal{H}$  be a hypothesis class of functions from a domain  $\mathcal{X}$  to  $\{0, 1\}$ , and let the loss function be the 0 – 1 loss. Then the following statements are equivalent:

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*Intuition.*

- ① → ② was proved in UC property
- ② → ③, ② → ⑤ and ③ → ④ are trivial
- ④ → ⑥ and ⑤ → ⑥ follow from the NFL theorem.



# The Fundamental Theorem of PAC Learning

[The Fundamental Theorem of PAC Learning](#)

[The Fundamental Theorem of PAC Learning](#)

[The Fundamental Theorem of PAC Learning \(Quantitative\)](#)

[Proof of the Lower Bounds](#)

[The Growth Function](#)

[Sauer's Lemma](#)

[Proof of the Upper Bounds](#)

[Symmetrization](#)

[What is Learnable and How to Learn?](#)

[Learning Beyond Classes with Finite VC Dimension](#)

[Quiz](#)

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*Intuition.*

- ① → ② was proved in UC property
- ② → ③, ② → ⑤ and ③ → ④ are trivial
- ④ → ⑥ and ⑤ → ⑥ follow from the NFL theorem.
- ⑥ → ①: proven by *Vapnik and Chervonenkis* (1971), and related to PAC by *Blumer, Ehrenfeucht, Haussler and Warmuth* (1989)



# The Fundamental Theorem of PAC Learning

[The Fundamental Theorem of PAC Learning](#)

[The Fundamental Theorem of PAC Learning](#)

[The Fundamental Theorem of PAC Learning \(Quantitative\)](#)

[Proof of the Lower Bounds](#)

[The Growth Function](#)

[Sauer's Lemma](#)

[Proof of the Upper Bounds](#)

[Symmetrization](#)

[What is Learnable and How to Learn?](#)

[Learning Beyond Classes with Finite VC Dimension](#)

[Quiz](#)



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## Intuition.

- ① → ② was proved in UC property
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- ⑥ → ①: proven by *Vapnik and Chervonenkis* (1971), and related to PAC by *Blumer, Ehrenfeucht, Haussler and Warmuth* (1989)
  - ◆ If  $VC\text{Dim}(\mathcal{H}) = d$ , then even though  $\mathcal{H}$  might be infinite, when restricting to a finite set  $C \subseteq \mathcal{X}$ , the size of  $|\mathcal{H}_C|$  grows polynomially with  $|C|$



# The Fundamental Theorem of PAC Learning

The Fundamental Theorem of PAC Learning

The Fundamental Theorem of PAC Learning

The Fundamental Theorem of PAC Learning (Quantitative)

Proof of the Lower Bounds

The Growth Function

Sauer's Lemma

Proof of the Upper Bounds

Symmetrization

What is Learnable and How to Learn?

Learning Beyond Classes with Finite VC Dimension

Quiz



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## Intuition.

- ① → ② was proved in UC property
- ② → ③, ② → ⑤ and ③ → ④ are trivial
- ④ → ⑥ and ⑤ → ⑥ follow from the NFL theorem.
- ⑥ → ①: proven by *Vapnik and Chervonenkis* (1971), and related to PAC by *Blumer, Ehrenfeucht, Haussler and Warmuth* (1989)
  - ◆ If  $VC\text{Dim}(\mathcal{H}) = d$ , then even though  $\mathcal{H}$  might be infinite, when restricting to a finite set  $C \subseteq \mathcal{X}$ , the size of  $|\mathcal{H}_C|$  grows polynomially with  $|C|$
  - ◆ Uniform convergence holds for the “small effective size” class  $\mathcal{H}$ .



# The Fundamental Theorem of PAC Learning (Quantitative)

[The Fundamental Theorem of PAC Learning](#)

[The Fundamental Theorem of PAC Learning](#)

[The Fundamental Theorem of PAC Learning \(Quantitative\)](#)

[Proof of the Lower Bounds](#)

[The Growth Function](#)

[Sauer's Lemma](#)

[Proof of the Upper Bounds](#)

[Symmetrization](#)

[What is Learnable and How to Learn?](#)

[Learning Beyond Classes with Finite VC Dimension](#)

[Quiz](#)

Let  $\mathcal{H}$  be a hypothesis class of functions from a domain  $\mathcal{X}$  to  $\{0, 1\}$ , and let the loss function be the 0–1 loss. Assume that  $VC\text{Dim}(\mathcal{H}) = d < \infty$ . Then, there are absolute constants  $C_1$  and  $C_2$  such that

1.  $\mathcal{H}$  has the **uniform convergence** property with sample complexity

$$C_1 \frac{d + \log(1/\delta)}{\epsilon^2} \leq m_{\mathcal{H}}^{UC}(\epsilon, \delta) \leq C_2 \frac{d + \log(1/\delta)}{\epsilon^2}$$

2.  $\mathcal{H}$  is **agnostic PAC learnable** with sample complexity

$$C_1 \frac{d + \log(1/\delta)}{\epsilon^2} \leq m_{\mathcal{H}}^{APAC}(\epsilon, \delta) \leq C_2 \frac{d + \log(1/\delta)}{\epsilon^2}$$

3.  $\mathcal{H}$  is **PAC learnable** with sample complexity

$$C_1 \frac{d + \log(1/\delta)}{\epsilon} \leq m_{\mathcal{H}}^{PAC}(\epsilon, \delta) \leq C_2 \frac{d \log(1/\epsilon) + \log(1/\delta)}{\epsilon}$$



# The Fundamental Theorem of PAC Learning (Quantitative)

[The Fundamental Theorem of PAC Learning](#)

[The Fundamental Theorem of PAC Learning](#)

[The Fundamental Theorem of PAC Learning \(Quantitative\)](#)

[Proof of the Lower Bounds](#)

[The Growth Function](#)

[Sauer's Lemma](#)

[Proof of the Upper Bounds](#)

[Symmetrization](#)

[What is Learnable and How to Learn?](#)

[Learning Beyond Classes with Finite VC Dimension](#)

[Quiz](#)

Let  $\mathcal{H}$  be a hypothesis class of functions from a domain  $\mathcal{X}$  to  $\{0, 1\}$ , and let the loss function be the 0–1 loss. Assume that  $VC\text{Dim}(\mathcal{H}) = d < \infty$ . Then, there are absolute constants  $C_1$  and  $C_2$  such that

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$$C_1 \frac{d + \log(1/\delta)}{\epsilon^2} \leq m_{\mathcal{H}}^{UC}(\epsilon, \delta) \leq C_2 \frac{d + \log(1/\delta)}{\epsilon^2}$$

2.  $\mathcal{H}$  is **agnostic PAC learnable** with sample complexity

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3.  $\mathcal{H}$  is **PAC learnable** with sample complexity

$$C_1 \frac{d + \log(1/\delta)}{\epsilon} \leq m_{\mathcal{H}}^{PAC}(\epsilon, \delta) \leq C_2 \frac{d \log(1/\epsilon) + \log(1/\delta)}{\epsilon}$$

*Intuition.*

- *NFL* is on the lower bound; while *Hoeffding's Inequality* is on the upper bound.



# Proof of the Lower Bounds



$$C_1 \frac{d + \log(1/\delta)}{\epsilon} \leq m_{\mathcal{H}}^{PAC}(\epsilon, \delta)$$

The Fundamental Theorem of PAC Learning

The Fundamental Theorem of PAC Learning

The Fundamental Theorem of PAC Learning (Quantitative)

Proof of the Lower Bounds

The Growth Function

Sauer's Lemma

Proof of the Upper Bounds

Symmetrization

*What is Learnable and How to Learn?*

Learning Beyond Classes with Finite VC Dimension

Quiz



# Proof of the Lower Bounds

The Fundamental Theorem of PAC Learning

The Fundamental Theorem of PAC Learning

The Fundamental Theorem of PAC Learning (Quantitative)

Proof of the Lower Bounds

The Growth Function

Sauer's Lemma

Proof of the Upper Bounds

Symmetrization

What is Learnable and How to Learn?

Learning Beyond Classes with Finite VC Dimension

Quiz



$$C_1 \frac{d + \log(1/\delta)}{\epsilon} \leq m_{\mathcal{H}}^{PAC}(\epsilon, \delta)$$

*Intuition.*

- From NFL theorem, we have  $\frac{d}{2} \leq m_{\mathcal{H}}^{PAC}(1/8, 1/7)$



# Proof of the Lower Bounds

The Fundamental Theorem of PAC Learning

The Fundamental Theorem of PAC Learning

The Fundamental Theorem of PAC Learning (Quantitative)

Proof of the Lower Bounds

The Growth Function

Sauer's Lemma

Proof of the Upper Bounds

Symmetrization

*What is Learnable and How to Learn?*

Learning Beyond Classes with Finite VC Dimension

Quiz



$$C_1 \frac{d + \log(1/\delta)}{\epsilon} \leq m_{\mathcal{H}}^{PAC}(\epsilon, \delta)$$

*Intuition.*

- From NFL theorem, we have  $\frac{d}{2} \leq m_{\mathcal{H}}^{PAC}(1/8, 1/7)$
- Pick a set  $S = \{x_1, \dots, x_d\}$  of size  $d$  that is shattered by  $\mathcal{H}$ . Let  $\mathcal{D}$  be:

$$p(x_i) = \begin{cases} 1 - \epsilon & \text{if } i = 1 \\ \frac{\epsilon}{d-1} & i \in [2, d] \\ 0 & \text{otherwise} \end{cases}$$



# Proof of the Lower Bounds

The Fundamental Theorem of PAC Learning

The Fundamental Theorem of PAC Learning

The Fundamental Theorem of PAC Learning (Quantitative)

Proof of the Lower Bounds

The Growth Function

Sauer's Lemma

Proof of the Upper Bounds

Symmetrization

What is Learnable and How to Learn?

Learning Beyond Classes with Finite VC Dimension

Quiz



$$C_1 \frac{d + \log(1/\delta)}{\epsilon} \leq m_{\mathcal{H}}^{PAC}(\epsilon, \delta)$$

## Intuition.

- From NFL theorem, we have  $\frac{d}{2} \leq m_{\mathcal{H}}^{PAC}(1/8, 1/7)$
- Pick a set  $S = \{x_1, \dots, x_d\}$  of size  $d$  that is shattered by  $\mathcal{H}$ . Let  $\mathcal{D}$  be:

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- By the NFL, as long as the sample hits  $\{x_2, \dots, x_d\}$  at most  $\frac{d-1}{2}$  times, the probability of making an error over  $\{x_2, \dots, x_d\}$  is  $\geq \frac{1}{4}$ .



# Proof of the Lower Bounds

The Fundamental Theorem of PAC Learning

The Fundamental Theorem of PAC Learning

The Fundamental Theorem of PAC Learning (Quantitative)

Proof of the Lower Bounds

The Growth Function

Sauer's Lemma

Proof of the Upper Bounds

Symmetrization

What is Learnable and How to Learn?

Learning Beyond Classes with Finite VC Dimension

Quiz



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- So the overall expected error will be  $\frac{\epsilon}{4}$ .



# Proof of the Lower Bounds

The Fundamental Theorem of PAC Learning

The Fundamental Theorem of PAC Learning

The Fundamental Theorem of PAC Learning (Quantitative)

Proof of the Lower Bounds

The Growth Function

Sauer's Lemma

Proof of the Upper Bounds

Symmetrization

What is Learnable and How to Learn?

Learning Beyond Classes with Finite VC Dimension

Quiz



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- So the overall expected error will be  $\frac{\epsilon}{4}$ .
- Only roughly  $m\epsilon$  of a sample  $S$  of size  $m$  will hit  $\{x_2, \dots, x_d\}$ .



# Proof of the Lower Bounds

The Fundamental Theorem of PAC Learning

The Fundamental Theorem of PAC Learning

The Fundamental Theorem of PAC Learning (Quantitative)

Proof of the Lower Bounds

The Growth Function

Sauer's Lemma

Proof of the Upper Bounds

Symmetrization

What is Learnable and How to Learn?

Learning Beyond Classes with Finite VC Dimension

Quiz



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## Intuition.

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- So the overall expected error will be  $\frac{\epsilon}{4}$ .
- Only roughly  $m\epsilon$  of a sample  $S$  of size  $m$  will hit  $\{x_2, \dots, x_d\}$ .
- So in order to get the expected error below  $\frac{\epsilon}{4}$ , we need the  $m\epsilon > \frac{d-1}{2}$ , so  $m > \frac{d-1}{2\epsilon}$



# Proof of the Lower Bounds

The Fundamental Theorem of PAC Learning

The Fundamental Theorem of PAC Learning

The Fundamental Theorem of PAC Learning (Quantitative)

Proof of the Lower Bounds

The Growth Function

Sauer's Lemma

Proof of the Upper Bounds

Symmetrization

What is Learnable and How to Learn?

Learning Beyond Classes with Finite VC Dimension

Quiz



$$C_1 \frac{d + \log(1/\delta)}{\epsilon} \leq m_{\mathcal{H}}^{PAC}(\epsilon, \delta)$$

## Intuition.

- From NFL theorem, we have  $\frac{d}{2} \leq m_{\mathcal{H}}^{PAC}(1/8, 1/7)$
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- So the overall expected error will be  $\frac{\epsilon}{4}$ .
- Only roughly  $m\epsilon$  of a sample  $S$  of size  $m$  will hit  $\{x_2, \dots, x_d\}$ .
- So in order to get the expected error below  $\frac{\epsilon}{4}$ , we need the  $m\epsilon > \frac{d-1}{2}$ , so  $m > \frac{d-1}{2\epsilon}$
- Now we have  $\forall \epsilon, E_{S \sim \mathcal{D}^m}[L_{\mathcal{D}}(A(S))] < \frac{\epsilon}{4}$ , then  $m > \frac{d-1}{2\epsilon}$





# Proof of the Lower Bounds

The Fundamental Theorem of PAC Learning

The Fundamental Theorem of PAC Learning

The Fundamental Theorem of PAC Learning (Quantitative)

Proof of the Lower Bounds

The Growth Function

Sauer's Lemma

Proof of the Upper Bounds

Symmetrization

*What is Learnable and How to Learn?*

Learning Beyond Classes with Finite VC Dimension

Quiz



$$C_1 \frac{d + \log(1/\delta)}{\epsilon^2} \leq m_{\mathcal{H}}^{APAC}$$



# Proof of the Lower Bounds

The Fundamental Theorem of PAC Learning

The Fundamental Theorem of PAC Learning

The Fundamental Theorem of PAC Learning (Quantitative)

Proof of the Lower Bounds

The Growth Function

Sauer's Lemma

Proof of the Upper Bounds

Symmetrization

*What is Learnable and How to Learn?*

Learning Beyond Classes with Finite VC Dimension

Quiz



$$C_1 \frac{d + \log(1/\delta)}{\epsilon^2} \leq m_{\mathcal{H}}^{APAC}$$

*Intuition.*

- Why for agnostic case, we need so many more examples?



# Proof of the Lower Bounds

The Fundamental Theorem of PAC Learning

The Fundamental Theorem of PAC Learning

The Fundamental Theorem of PAC Learning (Quantitative)

Proof of the Lower Bounds

The Growth Function

Sauer's Lemma

Proof of the Upper Bounds

Symmetrization

*What is Learnable and How to Learn?*

Learning Beyond Classes with Finite VC Dimension

Quiz



$$C_1 \frac{d + \log(1/\delta)}{\epsilon^2} \leq m_{\mathcal{H}}^{APAC}$$

## Intuition.

- Why for agnostic case, we need so many more examples?
- Consider one sample with two points  $S = \{x, y\}$  both points with probability  $\frac{1}{2}$  to be selected.  $P(1|X) = P(0|Y) = \frac{1}{2} + \epsilon$  and  $P(0|X) = P(1|Y) = \frac{1}{2} - \epsilon$



# Proof of the Lower Bounds

The Fundamental Theorem of PAC Learning

The Fundamental Theorem of PAC Learning

The Fundamental Theorem of PAC Learning (Quantitative)

Proof of the Lower Bounds

The Growth Function

Sauer's Lemma

Proof of the Upper Bounds

Symmetrization

What is Learnable and How to Learn?

Learning Beyond Classes with Finite VC Dimension

Quiz



$$C_1 \frac{d + \log(1/\delta)}{\epsilon^2} \leq m_{\mathcal{H}}^{APAC}$$

## Intuition.

- Why for agnostic case, we need so many more examples?
- Consider one sample with two points  $S = \{x, y\}$  both points with probability  $\frac{1}{2}$  to be selected.  $P(1|X) = P(0|Y) = \frac{1}{2} + \epsilon$  and  $P(0|X) = P(1|Y) = \frac{1}{2} - \epsilon$
- $\mathcal{H} = \{(1, 1), (1, 0), (0, 1), (0, 0)\}$  contains all functions over  $\{x, y\}$ . Bayes predictor (best one) is  $(1, 0)$ .



# Proof of the Lower Bounds

The Fundamental Theorem of PAC Learning

The Fundamental Theorem of PAC Learning

The Fundamental Theorem of PAC Learning (Quantitative)

Proof of the Lower Bounds

The Growth Function

Sauer's Lemma

Proof of the Upper Bounds

Symmetrization

What is Learnable and How to Learn?

Learning Beyond Classes with Finite VC Dimension

Quiz



$$C_1 \frac{d + \log(1/\delta)}{\epsilon^2} \leq m_{\mathcal{H}}^{APAC}$$

## Intuition.

- Why for agnostic case, we need so many more examples?
- Consider one sample with two points  $S = \{x, y\}$  both points with probability  $\frac{1}{2}$  to be selected.  $P(1|X) = P(0|Y) = \frac{1}{2} + \epsilon$  and  $P(0|X) = P(1|Y) = \frac{1}{2} - \epsilon$
- $\mathcal{H} = \{(1, 1), (1, 0), (0, 1), (0, 0)\}$  contains all functions over  $\{x, y\}$ . Bayes predictor (best one) is  $(1, 0)$ .
- In order to detect if a coin has  $\frac{1}{2} + \epsilon$  towards tails or heads, one needs  $\frac{1}{\epsilon^2}$  coin tosses, as  $\epsilon$  gets small





# The Growth Function

[The Fundamental Theorem of PAC Learning](#)

[The Fundamental Theorem of PAC Learning](#)

[The Fundamental Theorem of PAC Learning \(Quantitative\)](#)

[Proof of the Lower Bounds](#)

[The Growth Function](#)

[Sauer's Lemma](#)

[Proof of the Upper Bounds](#)

[Symmetrization](#)

[What is Learnable and How to Learn?](#)

[Learning Beyond Classes with Finite VC Dimension](#)

[Quiz](#)

Let  $\mathcal{H}$  be a hypothesis class, then the **growth function** of  $\mathcal{H}$ , denoted  $\tau_{\mathcal{H}}: \mathcal{N} \rightarrow \mathcal{N}$ , is defined as:



$$\tau_{\mathcal{H}}(m) = \max_{C \subseteq \mathcal{X}: |C|=m} |\mathcal{H}_C|$$



# The Growth Function

[The Fundamental Theorem of PAC Learning](#)

[The Fundamental Theorem of PAC Learning](#)

[The Fundamental Theorem of PAC Learning \(Quantitative\)](#)

[Proof of the Lower Bounds](#)

**The Growth Function**

[Sauer's Lemma](#)

[Proof of the Upper Bounds](#)

[Symmetrization](#)

[What is Learnable and How to Learn?](#)

[Learning Beyond Classes with Finite VC Dimension](#)

[Quiz](#)



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## Observations.

- For every  $\mathcal{H}$  and every  $m$ ,  $\tau_{\mathcal{H}}(m) \leq 2^m$



# The Growth Function

[The Fundamental Theorem of PAC Learning](#)

[The Fundamental Theorem of PAC Learning](#)

[The Fundamental Theorem of PAC Learning \(Quantitative\)](#)

[Proof of the Lower Bounds](#)

**The Growth Function**

[Sauer's Lemma](#)

[Proof of the Upper Bounds](#)

[Symmetrization](#)

[What is Learnable and How to Learn?](#)

[Learning Beyond Classes with Finite VC Dimension](#)

[Quiz](#)



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# The Growth Function

[The Fundamental Theorem of PAC Learning](#)

[The Fundamental Theorem of PAC Learning](#)

[The Fundamental Theorem of PAC Learning \(Quantitative\)](#)

[Proof of the Lower Bounds](#)

**The Growth Function**

[Sauer's Lemma](#)

[Proof of the Upper Bounds](#)

[Symmetrization](#)

[What is Learnable and How to Learn?](#)

[Learning Beyond Classes with Finite VC Dimension](#)

[Quiz](#)



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- If  $\mathcal{H}$  shatters a set of size  $m$ , then  $\tau_{\mathcal{H}}(m) = 2^m$
- If  $VC\text{Dim}(\mathcal{H}) < m$ , then  $\tau_{\mathcal{H}}(m) < 2^m$





# The Growth Function

[The Fundamental Theorem of PAC Learning](#)

[The Fundamental Theorem of PAC Learning](#)

[The Fundamental Theorem of PAC Learning \(Quantitative\)](#)

[Proof of the Lower Bounds](#)

**The Growth Function**

[Sauer's Lemma](#)

[Proof of the Upper Bounds](#)

[Symmetrization](#)

[What is Learnable and How to Learn?](#)

[Learning Beyond Classes with Finite VC Dimension](#)

[Quiz](#)



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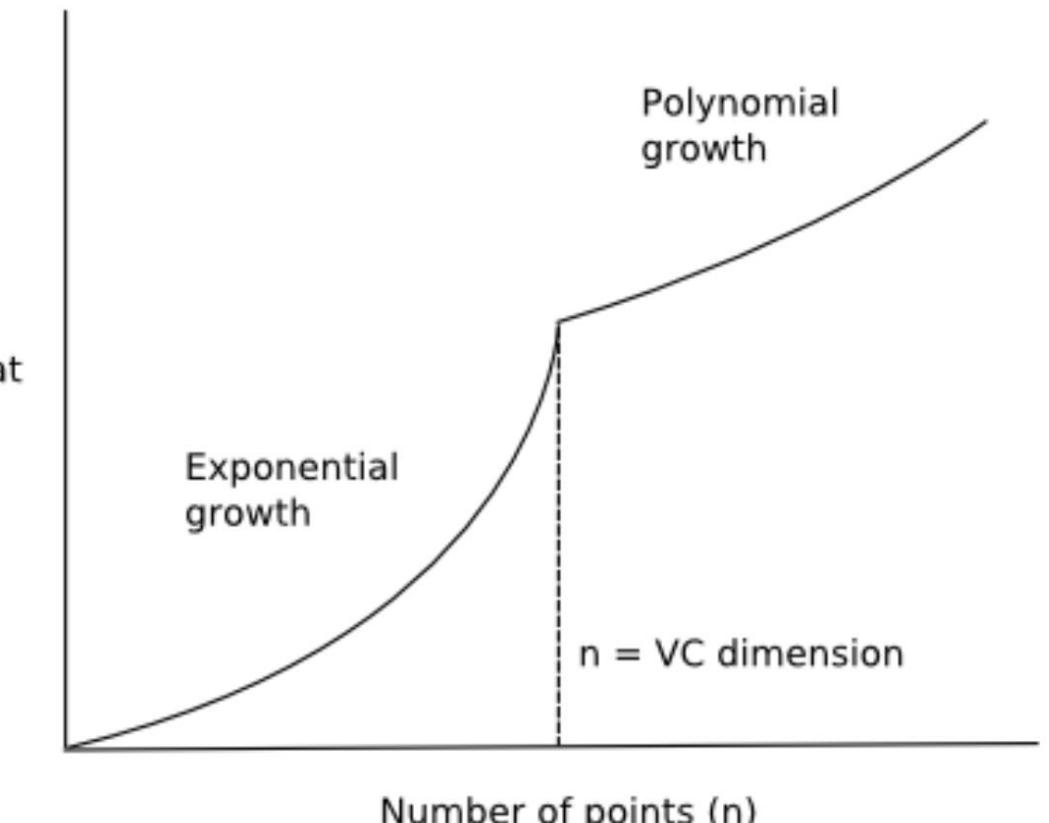
## Intuition

$$\begin{aligned}\tau_{\mathcal{H}}(m) &= \max_{|A| \leq m} |h \cap A : h \in \mathcal{H}| \\ &= |\{g : A \rightarrow \{0, 1\} : \\ &\quad \exists h \in \mathcal{H}, \forall x \in A, g(x) = h(x)\}|\end{aligned}$$

Number of distinct subsets that can be enclosed

**Exponential**  $2^m, 3^m, \dots$   
 $\dots m^{\log m}$ , etc.

**Polynomial**  $m^2, m^3, \dots$





# Sauer's Lemma

The Fundamental Theorem of PAC Learning

The Fundamental Theorem of PAC Learning

The Fundamental Theorem of PAC Learning (Quantitative)

Proof of the Lower Bounds

The Growth Function

Sauer's Lemma

Proof of the Upper Bounds

Symmetrization

*What is Learnable and How to Learn?*

Learning Beyond Classes with Finite VC Dimension

Quiz



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# Sauer's Lemma

The Fundamental Theorem of PAC Learning

The Fundamental Theorem of PAC Learning

The Fundamental Theorem of PAC Learning (Quantitative)

Proof of the Lower Bounds

The Growth Function

Sauer's Lemma

Proof of the Upper Bounds

Symmetrization

*What is Learnable and How to Learn?*

Learning Beyond Classes with Finite VC Dimension

Quiz



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- The number of partitions realizable by a linear half-space:
  - ◆  $VC\text{Dim}(\mathcal{H}_{HS^2}) = 3$



# Sauer's Lemma

The Fundamental Theorem of PAC Learning

The Fundamental Theorem of PAC Learning

The Fundamental Theorem of PAC Learning (Quantitative)

Proof of the Lower Bounds

The Growth Function

Sauer's Lemma

Proof of the Upper Bounds

Symmetrization

*What is Learnable and How to Learn?*

Learning Beyond Classes with Finite VC Dimension

Quiz



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■ The number of partitions realizable by a linear half-space:

- ◆  $VCDim(\mathcal{H}_{HS^2}) = 3$
- ◆ For 1000 points with binary labels, there are less than  $1000^3$  partitions by  $\mathcal{H}_{HS^2}$



# Sauer's Lemma

The Fundamental Theorem of PAC Learning

The Fundamental Theorem of PAC Learning

The Fundamental Theorem of PAC Learning (Quantitative)

Proof of the Lower Bounds

The Growth Function

Sauer's Lemma

Proof of the Upper Bounds

Symmetrization

*What is Learnable and How to Learn?*

Learning Beyond Classes with Finite VC Dimension

Quiz



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# Sauer's Lemma

The Fundamental Theorem of PAC Learning

The Fundamental Theorem of PAC Learning

The Fundamental Theorem of PAC Learning (Quantitative)

Proof of the Lower Bounds

The Growth Function

Sauer's Lemma

Proof of the Upper Bounds

Symmetrization

*What is Learnable and How to Learn?*

Learning Beyond Classes with Finite VC Dimension

Quiz



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# Sauer's Lemma

The Fundamental Theorem of PAC Learning

The Fundamental Theorem of PAC Learning

The Fundamental Theorem of PAC Learning (Quantitative)

Proof of the Lower Bounds

The Growth Function

**Sauer's Lemma**

Proof of the Upper Bounds

Symmetrization

*What is Learnable and How to Learn?*

Learning Beyond Classes with Finite VC Dimension

Quiz



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*Intuition.*

1. We prove a stronger claim:  $\forall C = \{c_1, \dots, c_m\}$ , we have  $\forall \mathcal{H}$ ,  $|\mathcal{H}_C| \leq |\{B \subseteq C : \mathcal{H} \text{ shatters } B\}|$ .



# Sauer's Lemma

The Fundamental Theorem of PAC Learning

The Fundamental Theorem of PAC Learning

The Fundamental Theorem of PAC Learning (Quantitative)

Proof of the Lower Bounds

The Growth Function

**Sauer's Lemma**

Proof of the Upper Bounds

Symmetrization

*What is Learnable and How to Learn?*

Learning Beyond Classes with Finite VC Dimension

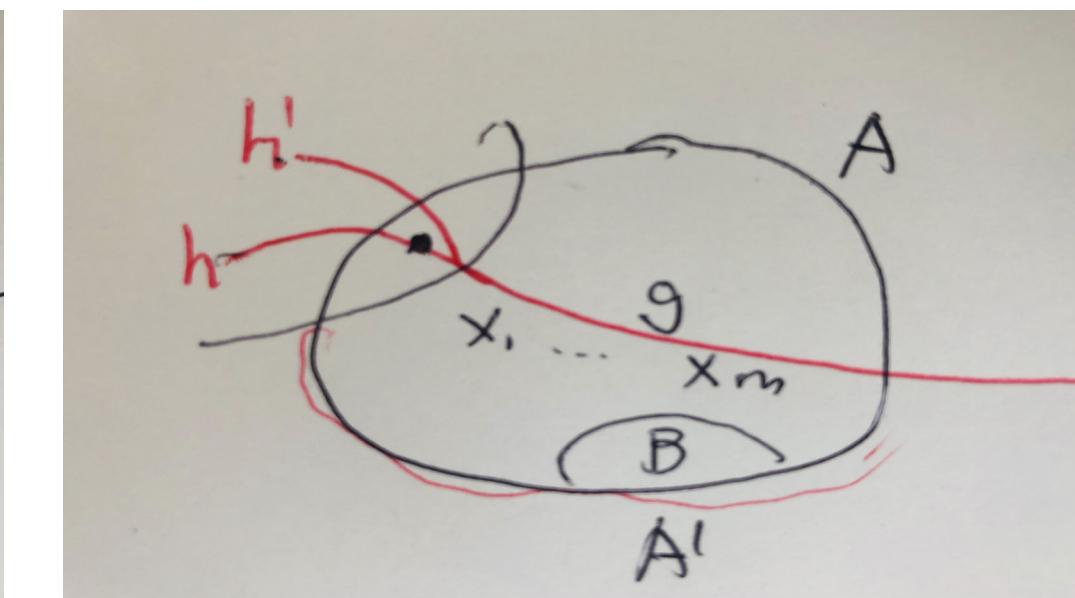
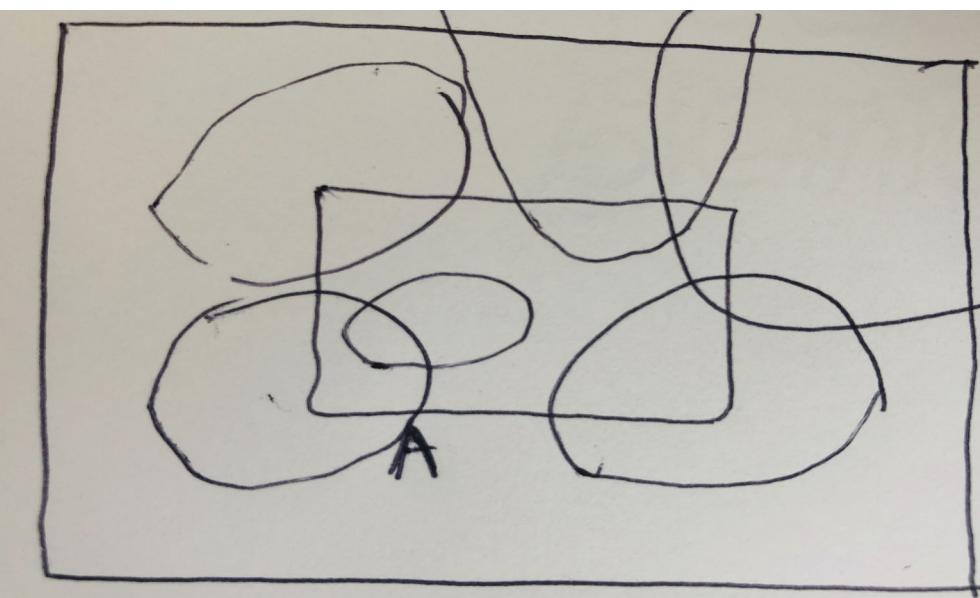
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2. If  $VC\text{Dim}(\mathcal{H}) \leq d$ , then no set with size larger than  $d$  is shattered by  $\mathcal{H}$ :  
 $|\{B \subseteq C : \mathcal{H} \text{ shatters } B\}| \leq \sum_{i=0}^d \binom{m}{i}$



□



# Sauer's Lemma

The Fundamental Theorem of PAC Learning

The Fundamental Theorem of PAC Learning

The Fundamental Theorem of PAC Learning (Quantitative)

Proof of the Lower Bounds

The Growth Function

Sauer's Lemma

Proof of the Upper Bounds

Symmetrization

What is Learnable and How to Learn?

Learning Beyond Classes with Finite VC Dimension

Quiz



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# Sauer's Lemma

The Fundamental Theorem of PAC Learning

The Fundamental Theorem of PAC Learning

The Fundamental Theorem of PAC Learning (Quantitative)

Proof of the Lower Bounds

The Growth Function

**Sauer's Lemma**

Proof of the Upper Bounds

Symmetrization

*What is Learnable and How to Learn?*

Learning Beyond Classes with Finite VC Dimension

Quiz



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1. The empty set  $\phi$  is always shattered by  $\mathcal{H}$ .
2. Assume it holds for any size  $m - 1$ , let us prove it for the size  $m$ . Denote  $C' = \{c_2, \dots, c_m\}$  and define:

$$Y_0 = \{(y_2, \dots, y_m) : (0, y_2, \dots, y_m) \in \mathcal{H}_C \vee (1, y_2, \dots, y_m) \in \mathcal{H}_C\}$$

and

$$Y_1 = \{(y_2, \dots, y_m) : (0, y_2, \dots, y_m) \in \mathcal{H}_C \wedge (1, y_2, \dots, y_m) \in \mathcal{H}_C\}$$

We have  $|\mathcal{H}_C| = |Y_0| + |Y_1|$ .



# Sauer's Lemma

The Fundamental Theorem of PAC Learning

The Fundamental Theorem of PAC Learning

The Fundamental Theorem of PAC Learning (Quantitative)

Proof of the Lower Bounds

The Growth Function

Sauer's Lemma

Proof of the Upper Bounds

Symmetrization

What is Learnable and How to Learn?

Learning Beyond Classes with Finite VC Dimension

Quiz



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We have  $|\mathcal{H}_C| = |Y_0| + |Y_1|$ .

3. Since  $Y_0 = \mathcal{H}_{C'}$ , using induction assumption, we have

$$|Y_0| = |\mathcal{H}_{C'}| \leq |\{B \subseteq C' : \mathcal{H} \text{ shatters } B\}| = |\{B \subseteq C : c_1 \notin B \wedge \mathcal{H} \text{ shatters } B\}|$$

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# Sauer's Lemma

The Fundamental Theorem of PAC Learning

The Fundamental Theorem of PAC Learning

The Fundamental Theorem of PAC Learning (Quantitative)

Proof of the Lower Bounds

The Growth Function

Sauer's Lemma

Proof of the Upper Bounds

Symmetrization

What is Learnable and How to Learn?

Learning Beyond Classes with Finite VC Dimension

Quiz



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4. Let  $\mathcal{H}' \subseteq \mathcal{H}$ ,

$$\mathcal{H}' = \{h \in \mathcal{H} : \exists h' \in \mathcal{H} (1 - h'(c_1), h'(c_2), \dots, h'(c_m)) = (h(c_1), h(c_2), \dots, h(c_m))\}$$

- $\mathcal{H}'$  contains pairs of hypotheses that agree on  $C'$  and differ on  $c_1$ .
- If  $\mathcal{H}'$  shatters a set  $B \subseteq C'$ , then it also shatters the set  $B \cup c_1$  and vice versa



# Sauer's Lemma

The Fundamental Theorem of PAC Learning

The Fundamental Theorem of PAC Learning

The Fundamental Theorem of PAC Learning (Quantitative)

Proof of the Lower Bounds

The Growth Function

**Sauer's Lemma**

Proof of the Upper Bounds

Symmetrization

*What is Learnable and How to Learn?*

Learning Beyond Classes with Finite VC Dimension

Quiz



Let  $\mathcal{H}$  be a hypothesis class with  $VC\text{Dim}(\mathcal{H}) \leq d \leq \infty$ , then  $\forall m$ ,  $\tau_{\mathcal{H}}(m) \leq \sum_{i=0}^d \binom{m}{i} \leq m^d$ . In particular, if  $m > d + 1$  then  $\tau_{\mathcal{H}}(m) \leq (em/d)^d$

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# Sauer's Lemma

The Fundamental Theorem of PAC Learning

The Fundamental Theorem of PAC Learning

The Fundamental Theorem of PAC Learning (Quantitative)

Proof of the Lower Bounds

The Growth Function

Sauer's Lemma

Proof of the Upper Bounds

Symmetrization

What is Learnable and How to Learn?

Learning Beyond Classes with Finite VC Dimension

Quiz



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6. Overall we have shown that:

$$\begin{aligned} |\mathcal{H}_C| &= |Y_0| + |Y_1| \leq |\{B \subseteq C : c_1 \notin B \wedge \mathcal{H} \text{ shatters } B\}| + |\{B \subseteq C : c_1 \in B \wedge \mathcal{H} \text{ shatters } B\}| \\ &= |\{B \subseteq C : \mathcal{H} \text{ shatters } B\}| \end{aligned}$$





# Sauer's Lemma

The Fundamental Theorem of PAC Learning

The Fundamental Theorem of PAC Learning

The Fundamental Theorem of PAC Learning (Quantitative)

Proof of the Lower Bounds

The Growth Function

**Sauer's Lemma**

Proof of the Upper Bounds

Symmetrization

*What is Learnable and How to Learn?*

Learning Beyond Classes with Finite VC Dimension

Quiz



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*Consequences of Sauer's Lemma.*

- The vast majority of partitions of a subset of  $m$  points from  $\mathbb{R}^n$  can not be realized by a linear separator:  $m^{n+1} \ll 2^m$



# Sauer's Lemma

The Fundamental Theorem of PAC Learning

The Fundamental Theorem of PAC Learning

The Fundamental Theorem of PAC Learning (Quantitative)

Proof of the Lower Bounds

The Growth Function

Sauer's Lemma

Proof of the Upper Bounds

Symmetrization

What is Learnable and How to Learn?

Learning Beyond Classes with Finite VC Dimension

Quiz



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# Sauer's Lemma

The Fundamental Theorem of PAC Learning

The Fundamental Theorem of PAC Learning

The Fundamental Theorem of PAC Learning (Quantitative)

Proof of the Lower Bounds

The Growth Function

**Sauer's Lemma**

Proof of the Upper Bounds

Symmetrization

What is Learnable and How to Learn?

Learning Beyond Classes with Finite VC Dimension

Quiz



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- Upper bounding  $m_{\mathcal{H}}^{PAC}(\epsilon, \delta)$
- Upper bounding  $VCdim(\mathcal{H}_1 \cup \mathcal{H}_2)$  by  $VCdim(\mathcal{H}_1)$  and  $VCdim(\mathcal{H}_2)$ .



# Sauer's Lemma

The Fundamental Theorem of PAC Learning

The Fundamental Theorem of PAC Learning

The Fundamental Theorem of PAC Learning (Quantitative)

Proof of the Lower Bounds

The Growth Function

**Sauer's Lemma**

Proof of the Upper Bounds

Symmetrization

What is Learnable and How to Learn?

Learning Beyond Classes with Finite VC Dimension

Quiz



Let  $\mathcal{H}$  be a hypothesis class with  $VCDim(\mathcal{H}) \leq d \leq \infty$ , then  $\forall m$ ,  $\tau_{\mathcal{H}}(m) \leq \sum_{i=0}^d \binom{m}{i} \leq m^d$ . In particular, if  $m > d + 1$  then  $\tau_{\mathcal{H}}(m) \leq (em/d)^d$

*Consequences of Sauer's Lemma.*

- The vast majority of partitions of a subset of  $m$  points from  $\mathcal{R}^n$  can not be realized by a linear separator:  $m^{n+1} \ll 2^m$
- Upper bounding  $m_{\mathcal{H}}^{PAC}(\epsilon, \delta)$
- Upper bounding  $VCdim(\mathcal{H}_1 \cup \mathcal{H}_2)$  by  $VCDim(\mathcal{H}_1)$  and  $VCDim(\mathcal{H}_2)$ .
  - ◆ Assume  $\mathcal{H}_1 \cup \mathcal{H}_2$  shatters a set  $S$  of size  $m$ ,  $|\{h \cap A : h \in \mathcal{H}_1 \vee h \in \mathcal{H}_2\}| \geq 2^m$



# Sauer's Lemma

The Fundamental Theorem of PAC Learning

The Fundamental Theorem of PAC Learning

The Fundamental Theorem of PAC Learning (Quantitative)

Proof of the Lower Bounds

The Growth Function

Sauer's Lemma

Proof of the Upper Bounds

Symmetrization

What is Learnable and How to Learn?

Learning Beyond Classes with Finite VC Dimension

Quiz



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  - ◆ On the other hand,

$$\begin{aligned} |\{h \cap A : h \in \mathcal{H}_1 \vee h \in \mathcal{H}_2\}| \\ \leq |\{h \cap A : h \in \mathcal{H}_1\}| + |\{h \cap A : h \in \mathcal{H}_2\}| \\ \leq m^{VCDim(\mathcal{H}_1)} + m^{VCDim(\mathcal{H}_2)} \end{aligned}$$



# Sauer's Lemma

The Fundamental Theorem of PAC Learning

The Fundamental Theorem of PAC Learning

The Fundamental Theorem of PAC Learning (Quantitative)

Proof of the Lower Bounds

The Growth Function

Sauer's Lemma

Proof of the Upper Bounds

Symmetrization

What is Learnable and How to Learn?

Learning Beyond Classes with Finite VC Dimension

Quiz



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- ◆  $m$  can not be too big...

□



# Proof of the Upper Bounds

The Fundamental Theorem of PAC Learning

The Fundamental Theorem of PAC Learning

The Fundamental Theorem of PAC Learning (Quantitative)

Proof of the Lower Bounds

The Growth Function

Sauer's Lemma

Proof of the Upper Bounds

Symmetrization

*What is Learnable and How to Learn?*

Learning Beyond Classes with Finite VC Dimension

Quiz



$$m_{\mathcal{H}}^{PAC} \leq C_2 \frac{d \log(1/\epsilon) + \log(1/\delta)}{\epsilon}$$



# Proof of the Upper Bounds

The Fundamental Theorem of PAC Learning

The Fundamental Theorem of PAC Learning

The Fundamental Theorem of PAC Learning (Quantitative)

Proof of the Lower Bounds

The Growth Function

Sauer's Lemma

Proof of the Upper Bounds

Symmetrization

What is Learnable and How to Learn?

Learning Beyond Classes with Finite VC Dimension

Quiz



$$m_{\mathcal{H}}^{PAC} \leq C_2 \frac{d \log(1/\epsilon) + \log(1/\delta)}{\epsilon}$$

## Intuition.

### ■ Recall our proof for the finite class $\mathcal{H}$

- ◆ For a single hypothesis  $h$ , we have shown that the probability of the event  $L_S(h) = 0$  given that  $L_{(\mathcal{D}, f)} > \epsilon$  is at most  $e^{-\epsilon m}$
- ◆ If we applied the union bound over all “bad” hypotheses, to obtain the bound on ERM failure:  $|\mathcal{H}|e^{-\epsilon m}$



# Proof of the Upper Bounds

The Fundamental Theorem of PAC Learning

The Fundamental Theorem of PAC Learning

The Fundamental Theorem of PAC Learning (Quantitative)

Proof of the Lower Bounds

The Growth Function

Sauer's Lemma

Proof of the Upper Bounds

Symmetrization

What is Learnable and How to Learn?

Learning Beyond Classes with Finite VC Dimension

Quiz



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  - ◆ If we applied the union bound over all “bad” hypotheses, to obtain the bound on ERM failure:  $|\mathcal{H}|e^{-\epsilon m}$
- If  $\mathcal{H}$  is infinite or large, the union bound yields a meaningless bound





# Proof of the Upper Bounds

The Fundamental Theorem of PAC Learning

The Fundamental Theorem of PAC Learning

The Fundamental Theorem of PAC Learning (Quantitative)

Proof of the Lower Bounds

The Growth Function

Sauer's Lemma

Proof of the Upper Bounds

Symmetrization

What is Learnable and How to Learn?

Learning Beyond Classes with Finite VC Dimension

Quiz



$$m_{\mathcal{H}}^{PAC} \leq C_2 \frac{d \log(1/\epsilon) + \log(1/\delta)}{\epsilon}$$

*Main Idea.*

**Two Samples Trick** We evaluate the error of any hypothesis  $h \in \mathcal{H}_B$  on a fresh sample  $T$ , a.k.a. the **ghost sample**.

- Since  $S$  and  $T$  are i.i.d., we can think of first sampling  $2m$  samples, and then splitting them to  $S$  and  $T$  at random
- On this evaluation, it suffices to consider  $\mathcal{H}_{S \cup T}$ , the set of possible behaviors of  $S \cup T$
- If we fix  $S \cup T$ , we can take a union bound only over  $\mathcal{H}_{S \cup T}$ :  
$$P_{S,T \sim \mathcal{D}^m} [\exists h \in \mathcal{H} : |L_S(h) - L_T(h)| > \epsilon/2] \leq (2m)^d 2e^{-2m(\frac{\epsilon}{2})^2}$$



# Proof of the Upper Bounds

The Fundamental Theorem of PAC Learning

The Fundamental Theorem of PAC Learning

The Fundamental Theorem of PAC Learning (Quantitative)

Proof of the Lower Bounds

The Growth Function

Sauer's Lemma

Proof of the Upper Bounds

Symmetrization

What is Learnable and How to Learn?

Learning Beyond Classes with Finite VC Dimension

Quiz



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**Symmetrization** For any  $\epsilon > 0$ , and  $m\epsilon^2 \geq 2$ , we have:

$$P_{S \sim \mathcal{D}^m} [\exists h \in \mathcal{H} : |L_S(h) - L_{\mathcal{D}}(h)| > \epsilon] \leq 2P_{S, T \sim \mathcal{D}^m} [\exists h \in \mathcal{H} : |L_S(h) - L_T(h)| > \epsilon/2]$$



# Proof of the Upper Bounds

The Fundamental Theorem of PAC Learning

The Fundamental Theorem of PAC Learning

The Fundamental Theorem of PAC Learning (Quantitative)

Proof of the Lower Bounds

The Growth Function

Sauer's Lemma

Proof of the Upper Bounds

Symmetrization

What is Learnable and How to Learn?

Learning Beyond Classes with Finite VC Dimension

Quiz



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**Combination** When  $m$  is sufficiently large, the probability of bad hypothesis will  $< \epsilon$ :

$$P_{S \sim \mathcal{D}^m} [\exists h \in \mathcal{H} : |L_S(h) - L_{\mathcal{D}}(h)| > \epsilon] \leq 2(2m)^d 2e^{-2m(\frac{\epsilon}{2})^2}$$



# Symmetrization

[The Fundamental Theorem of PAC Learning](#)

[The Fundamental Theorem of PAC Learning](#)

[The Fundamental Theorem of PAC Learning \(Quantitative\)](#)

[Proof of the Lower Bounds](#)

[The Growth Function](#)

[Sauer's Lemma](#)

[Proof of the Upper Bounds](#)

[Symmetrization](#)

[What is Learnable and How to Learn?](#)

[Learning Beyond Classes with Finite VC Dimension](#)

[Quiz](#)

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# Symmetrization

The Fundamental Theorem of PAC Learning

The Fundamental Theorem of PAC Learning

The Fundamental Theorem of PAC Learning (Quantitative)

Proof of the Lower Bounds

The Growth Function

Sauer's Lemma

Proof of the Upper Bounds

Symmetrization

What is Learnable and How to Learn?

Learning Beyond Classes with Finite VC Dimension

Quiz

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1. Assume the left hand side is maximized at  $h_S \in \mathcal{H}$ . Here  $h_S$  is dependent on the sample  $S$ .



# Symmetrization

The Fundamental Theorem of PAC Learning

The Fundamental Theorem of PAC Learning

The Fundamental Theorem of PAC Learning (Quantitative)

Proof of the Lower Bounds

The Growth Function

Sauer's Lemma

Proof of the Upper Bounds

Symmetrization

What is Learnable and How to Learn?

Learning Beyond Classes with Finite VC Dimension

Quiz

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# Symmetrization

The Fundamental Theorem of PAC Learning

The Fundamental Theorem of PAC Learning

The Fundamental Theorem of PAC Learning (Quantitative)

Proof of the Lower Bounds

The Growth Function

Sauer's Lemma

Proof of the Upper Bounds

Symmetrization

What is Learnable and How to Learn?

Learning Beyond Classes with Finite VC Dimension

Quiz

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3. Take the expectation on the ghost sample:

$$(|L_{\mathcal{D}}(h_S) - L_S(h_S)| > \epsilon) \wedge P(|L_{\mathcal{D}}(h_S) - L_T(h_S)| < \epsilon/2) \leq P(|L_S(h_S) - L_T(h_S)| > \epsilon/2)$$



# Symmetrization

The Fundamental Theorem of PAC Learning

The Fundamental Theorem of PAC Learning

The Fundamental Theorem of PAC Learning (Quantitative)

Proof of the Lower Bounds

The Growth Function

Sauer's Lemma

Proof of the Upper Bounds

Symmetrization

What is Learnable and How to Learn?

Learning Beyond Classes with Finite VC Dimension

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4. As  $h_S$  is independent of the ghost sample, we can use Chebyshev's Inequality:

$$P(|L_{\mathcal{D}}(h_S) - L_T(h_S)| \geq \epsilon/2) \leq \frac{4\text{var}(h_S)}{m\epsilon^2} \leq \frac{1}{m\epsilon^2}, \text{ because } \text{var}(h_S) \leq 1/4$$

$$P(|L_{\mathcal{D}}(h_S) - L_T(h_S)| < \epsilon/2) \geq 1 - \frac{1}{m\epsilon^2} \geq 1/2, \text{ when } 1 - \frac{1}{m\epsilon^2} \geq 1/2$$





# Symmetrization

The Fundamental Theorem of PAC Learning

The Fundamental Theorem of PAC Learning

The Fundamental Theorem of PAC Learning (Quantitative)

Proof of the Lower Bounds

The Growth Function

Sauer's Lemma

Proof of the Upper Bounds

Symmetrization

What is Learnable and How to Learn?

Learning Beyond Classes with Finite VC Dimension

Quiz

For any  $\epsilon > 0$ , and  $m\epsilon^2 \geq 2$ , we have:



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# Symmetrization

The Fundamental Theorem of PAC Learning

The Fundamental Theorem of PAC Learning

The Fundamental Theorem of PAC Learning (Quantitative)

Proof of the Lower Bounds

The Growth Function

Sauer's Lemma

Proof of the Upper Bounds

Symmetrization

What is Learnable and How to Learn?

Learning Beyond Classes with Finite VC Dimension

Quiz

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# Symmetrization

The Fundamental Theorem of PAC Learning

The Fundamental Theorem of PAC Learning

The Fundamental Theorem of PAC Learning (Quantitative)

Proof of the Lower Bounds

The Growth Function

Sauer's Lemma

Proof of the Upper Bounds

Symmetrization

What is Learnable and How to Learn?

Learning Beyond Classes with Finite VC Dimension

Quiz

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□

- With Symmetrization, hypothesis classes with finite VC dimension can be PAC learnable. Hence ⑥ → ① in the The Fundamental Theorem of PAC Learning.



# What is Learnable and How to Learn?

[The Fundamental Theorem of PAC Learning](#)

[The Fundamental Theorem of PAC Learning](#)

[The Fundamental Theorem of PAC Learning \(Quantitative\)](#)

[Proof of the Lower Bounds](#)

[The Growth Function](#)

[Sauer's Lemma](#)

[Proof of the Upper Bounds](#)

[Symmetrization](#)

[What is Learnable and How to Learn?](#)

[Learning Beyond Classes with Finite VC Dimension](#)

[Quiz](#)

## The fundamental theorem of statistic learning



- A class  $\mathcal{H}$  is PAC learnable if and only if it has finite **VC dimension**.
- The sample complexity is characterized by the **VC dimension**.
- The  $ERM_{\mathcal{H}}$  is a generic (near) optimal learner



# What is Learnable and How to Learn?

[The Fundamental Theorem of PAC Learning](#)

[The Fundamental Theorem of PAC Learning](#)

[The Fundamental Theorem of PAC Learning \(Quantitative\)](#)

[Proof of the Lower Bounds](#)

[The Growth Function](#)

[Sauer's Lemma](#)

[Proof of the Upper Bounds](#)

[Symmetrization](#)

[What is Learnable and How to Learn?](#)

[Learning Beyond Classes with Finite VC Dimension](#)

[Quiz](#)

## The fundamental theorem of statistic learning



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(Left to right) J. Rissanen, V. Vapnik, A. Gammerman,  
A. Chervonenkis, C. Wallace and R. Solomonoff



The Fundamental Theorem of PAC Learning

Learning Beyond Classes with Finite VC Dimension

Nonuniform Learnability

NUL versus A-PAC

Structural Risk Minimization

Minimum Description Length

Consistency Learnability

[Quiz](#)

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# Learning Beyond Classes with Finite VC Dimension



# Nonuniform Learnability

The Fundamental Theorem of PAC Learning

Learning Beyond Classes with Finite VC Dimension

Nonuniform Learnability

NUL versus A-PAC

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Consistency Learnability

Quiz

A hypothesis class  $\mathcal{H}$  is **nonuniformly learnable** (NUL) if there exist a learning algorithm  $A$ , and a function  $m_{\mathcal{H}}^{NUL} : (0, 1)^2 \times \mathcal{H} \rightarrow \mathcal{N}$  such that:

- For every  $\epsilon, \delta \in (0, 1)$ , for every  $h \in \mathcal{H}$ , if  $m \geq m_{\mathcal{H}}^{NUL}(\epsilon, \delta, h)$ , then for every distribution  $\mathcal{D}$  over  $\mathcal{X}$ , with probability of at least  $(1 - \delta)$  over the choice of  $S \sim \mathcal{D}^m$ , it holds that:

$$L_{\mathcal{D}}(A(S)) \leq L_{\mathcal{D}}(h) + \epsilon$$





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The Fundamental Theorem of PAC Learning

Learning Beyond Classes with Finite VC Dimension

Nonuniform Learnability

NUL versus A-PAC

Structural Risk Minimization

Minimum Description Length

Consistency Learnability

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A hypothesis class  $\mathcal{H}$  is **agnostically PAC learnable** if there exist a learning algorithm  $A$ , and a function  $m_{\mathcal{H}} : (0, 1)^2 \rightarrow \mathcal{N}$  such that:

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# Nonuniform Learnability

The Fundamental Theorem of PAC Learning

Learning Beyond Classes with Finite VC Dimension

Nonuniform Learnability

NUL versus A-PAC

Structural Risk Minimization

Minimum Description Length

Consistency Learnability

Quiz



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- Nonuniformly learnability (NUL) is a relaxation of agnostic PAC learnability



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The Fundamental Theorem of PAC Learning

Learning Beyond Classes with Finite VC Dimension

Nonuniform Learnability

NUL versus A-PAC

Structural Risk Minimization

Minimum Description Length

Consistency Learnability

Quiz



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- Nonuniformly learnability (NUL) is a relaxation of agnostic PAC learnability
- A class that is agnostic PAC learnable is also nonuniformly learnable



# Nonuniform Learnability

[The Fundamental Theorem of PAC Learning](#)

[Learning Beyond Classes with Finite VC Dimension](#)

**Nonuniform Learnability**

[NUL versus A-PAC](#)

[Structural Risk Minimization](#)

[Minimum Description Length](#)

[Consistency Learnability](#)

[Quiz](#)

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The Fundamental Theorem of PAC Learning

Learning Beyond Classes with Finite VC Dimension

Nonuniform Learnability

NUL versus A-PAC

Structural Risk Minimization

Minimum Description Length

Consistency Learnability

Quiz



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**Finite functions** Let  $\mathcal{X} = \mathcal{R}$ ,  $\mathcal{Y} = \{0, 1\}$ , for each  $k$ , let

$\mathcal{H}_k = \{h : h(x) = 0 \text{ for at most } k \text{ many } xs\}$

- $\mathcal{H}_1$  is the class of singletons



# Nonuniform Learnability

The Fundamental Theorem of PAC Learning

Learning Beyond Classes with Finite VC Dimension

Nonuniform Learnability

NUL versus A-PAC

Structural Risk Minimization

Minimum Description Length

Consistency Learnability

Quiz



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The Fundamental Theorem of PAC Learning

Learning Beyond Classes with Finite VC Dimension

Nonuniform Learnability

NUL versus A-PAC

Structural Risk Minimization

Minimum Description Length

Consistency Learnability

Quiz



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The Fundamental Theorem of PAC Learning

Learning Beyond Classes with Finite VC Dimension

Nonuniform Learnability

NUL versus A-PAC

Structural Risk Minimization

Minimum Description Length

Consistency Learnability

Quiz



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Two preliminary questions:

- Is there a class that is nonuniformly learnable but not PAC learnable?



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The Fundamental Theorem of PAC Learning

Learning Beyond Classes with Finite VC Dimension

Nonuniform Learnability

NUL versus A-PAC

Structural Risk Minimization

Minimum Description Length

Consistency Learnability

Quiz



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Two preliminary questions:

- Is there a class that is nonuniformly learnable but not PAC learnable?
- Is there a class that is not nonuniformly learnable?



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The Fundamental Theorem of PAC Learning

Learning Beyond Classes with Finite VC Dimension

Nonuniform Learnability

NUL versus A-PAC

Structural Risk Minimization

Minimum Description Length

Consistency Learnability

Quiz



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**Threshold Polynomial functions** Let  $\mathcal{H}$  be the class of all threshold polynomial functions: For each polynomial  $P(x) = a_0 + a_1x + \dots + a_nx^n + \dots$ ,  $h_P(x) = \text{sign}(P(x))$ . Let  $\mathcal{H} = \bigcup_{n=0}^{\infty} \mathcal{H}_n$  be the class of all such polynomial predictors  $h_P$ , where  $\mathcal{H}_n = \{h_P : P \text{ is a polynomial with degree } \leq n\}$

- Each  $\mathcal{H}_n$  is PAC learnable and has finite VC dimension, so  $\mathcal{H}$  is NUL



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The Fundamental Theorem of PAC Learning

Learning Beyond Classes with Finite VC Dimension

Nonuniform Learnability

NUL versus A-PAC

Structural Risk Minimization

Minimum Description Length

Consistency Learnability

Quiz

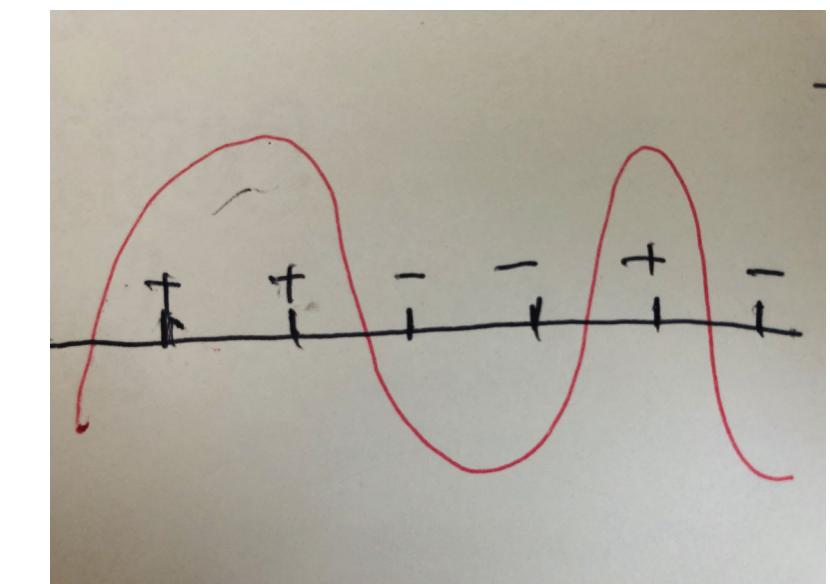


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- Each  $\mathcal{H}_n$  is PAC learnable and has finite VC dimension, so  $\mathcal{H}$  is NUL
- $\mathcal{H}$  is not PAC learnable, because it has infinite VC dimension





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The Fundamental Theorem of PAC Learning

Learning Beyond Classes with Finite VC Dimension

Nonuniform Learnability

NUL versus A-PAC

Structural Risk Minimization

Minimum Description Length

Consistency Learnability

Quiz



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**Infinite functions** For every infinite domain  $\mathcal{X}$ , the class of all binary function over  $\mathcal{X}$  can not be covered by any union of  $\bigcup_{n=0}^{\infty} \mathcal{H}_n$  where  $\mathcal{H}_n$  is with finite VC dimension.



# Nonuniform Learnability

The Fundamental Theorem of PAC Learning

Learning Beyond Classes with Finite VC Dimension

Nonuniform Learnability

NUL versus A-PAC

Structural Risk Minimization

Minimum Description Length

Consistency Learnability

Quiz



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- This implies that there exist some classes that are not NUL



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The Fundamental Theorem of PAC Learning

Learning Beyond Classes with Finite VC Dimension

Nonuniform Learnability

NUL versus A-PAC

Structural Risk Minimization

Minimum Description Length

Consistency Learnability

Quiz



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*Proof-1.* NUL  $\Rightarrow$  Countable Union

- Assume that  $\mathcal{H}$  is NUL using  $A$  with sample complexity  $m_{\mathcal{H}}^{NUL}$



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The Fundamental Theorem of PAC Learning

Learning Beyond Classes with Finite VC Dimension

Nonuniform Learnability

NUL versus A-PAC

Structural Risk Minimization

Minimum Description Length

Consistency Learnability

Quiz



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The Fundamental Theorem of PAC Learning

Learning Beyond Classes with Finite VC Dimension

Nonuniform Learnability

NUL versus A-PAC

Structural Risk Minimization

Minimum Description Length

Consistency Learnability

Quiz



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- Clearly, we have  $\mathcal{H} = \bigcup_{n \in \mathcal{N}} \mathcal{H}_n$



# Nonuniform Learnability

The Fundamental Theorem of PAC Learning

Learning Beyond Classes with Finite VC Dimension

Nonuniform Learnability

NUL versus A-PAC

Structural Risk Minimization

Minimum Description Length

Consistency Learnability

Quiz



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# Nonuniform Learnability

The Fundamental Theorem of PAC Learning

Learning Beyond Classes with Finite VC Dimension

Nonuniform Learnability

NUL versus A-PAC

Structural Risk Minimization

Minimum Description Length

Consistency Learnability

Quiz



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- For every  $n$ ,  $VCDim(\mathcal{H}_n) \leq 2n$  is finite
  - ◆ Otherwise, pick a set  $A \sim \mathcal{D}^{2n}$  such that  $\mathcal{H}_n$  shatters  $A$



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The Fundamental Theorem of PAC Learning

Learning Beyond Classes with Finite VC Dimension

Nonuniform Learnability

NUL versus A-PAC

Structural Risk Minimization

Minimum Description Length

Consistency Learnability

Quiz



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The Fundamental Theorem of PAC Learning

Learning Beyond Classes with Finite VC Dimension

Nonuniform Learnability

NUL versus A-PAC

Structural Risk Minimization

Minimum Description Length

Consistency Learnability

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# Nonuniform Learnability

The Fundamental Theorem of PAC Learning

Learning Beyond Classes with Finite VC Dimension

Nonuniform Learnability

NUL versus A-PAC

Structural Risk Minimization

Minimum Description Length

Consistency Learnability

Quiz



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  - ◆ If  $A$  is shattered by  $\mathcal{H}_n$ ,  $\mathcal{H}_n$  contains all functions over  $A$ .
  - ◆ By the definition of  $\mathcal{H}_n$ , it can be learned by  $n$  sample size.



# Nonuniform Learnability

The Fundamental Theorem of PAC Learning

Learning Beyond Classes with Finite VC Dimension

Nonuniform Learnability

NUL versus A-PAC

Structural Risk Minimization

Minimum Description Length

Consistency Learnability

Quiz



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  - ◆ If  $A$  is shattered by  $\mathcal{H}_n$ ,  $\mathcal{H}_n$  contains all functions over  $A$ .
  - ◆ By the definition of  $\mathcal{H}_n$ , it can be learned by  $n$  sample size.
  - ◆ Contradiction!





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The Fundamental Theorem of PAC Learning

Learning Beyond Classes with Finite VC Dimension

Nonuniform Learnability

NUL versus A-PAC

Structural Risk Minimization

Minimum Description Length

Consistency Learnability

Quiz



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## *Proof-2. NUL $\Leftarrow$ Countable Union*

- Assume that  $\mathcal{H} = \bigcup_{n \in \mathcal{N}} \mathcal{H}_n$ , and  $VCdim(\mathcal{H}_n) = d_n < \infty$ .



# Nonuniform Learnability

The Fundamental Theorem of PAC Learning

Learning Beyond Classes with Finite VC Dimension

Nonuniform Learnability

NUL versus A-PAC

Structural Risk Minimization

Minimum Description Length

Consistency Learnability

Quiz



A hypothesis class  $\mathcal{H}$  of binary classifiers is **nonuniformly learnable** (NUL) if and only if it is a countable union of agnostic PAC learnable hypothesis classes  $\mathcal{H}$ :

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The Fundamental Theorem of PAC Learning

Learning Beyond Classes with Finite VC Dimension

Nonuniform Learnability

NUL versus A-PAC

Structural Risk Minimization

Minimum Description Length

Consistency Learnability

Quiz



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# Nonuniform Learnability

The Fundamental Theorem of PAC Learning

Learning Beyond Classes with Finite VC Dimension

Nonuniform Learnability

NUL versus A-PAC

Structural Risk Minimization

Minimum Description Length

Consistency Learnability

Quiz



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# Nonuniform Learnability

The Fundamental Theorem of PAC Learning

Learning Beyond Classes with Finite VC Dimension

Nonuniform Learnability

NUL versus A-PAC

Structural Risk Minimization

Minimum Description Length

Consistency Learnability

Quiz



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- From the uniform convergence and  $\epsilon_n$ , it follows that for every  $m$  and  $\delta_n$ , with at most probability  $\delta_n$  over the choice of  $S \sim \mathcal{D}^m$  we have

$$\forall h \in \mathcal{H}_n, |L_{\mathcal{D}}(h) - L_S(h)| \geq \epsilon_n(m, \delta_n)$$



# Nonuniform Learnability

The Fundamental Theorem of PAC Learning

Learning Beyond Classes with Finite VC Dimension

Nonuniform Learnability

NUL versus A-PAC

Structural Risk Minimization

Minimum Description Length

Consistency Learnability

Quiz



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- Apply the union bound over  $n$ , we have at most  $\sum_n \delta_n = \delta$ ,

$$\forall h \in \mathcal{H}, |L_{\mathcal{D}}(h) - L_S(h)| \geq \min_{n: h \in \mathcal{H}_n} \epsilon_n(m, \delta_n)$$





# NUL versus A-PAC

The Fundamental Theorem of PAC Learning

Learning Beyond Classes with Finite VC Dimension

Nonuniform Learnability

NUL versus A-PAC

Structural Risk Minimization

Minimum Description Length

Consistency Learnability

Quiz

Table 1: Comparison of NUL and Agnostic PAC (I)

Learnability	Conditions
<b>Agnostic PAC</b>	$\forall h, \forall \mathcal{D}, \forall \delta$ and $\forall \epsilon$ , if $m \geq \dots$ , we have $P_{S \sim \mathcal{D}^m}[\exists h :  L_{\mathcal{D}}(h) - L_S(h)  > \epsilon] < \delta$
<b>NUL</b>	$\mathcal{H} = \cup_{n \in \mathcal{N}} \mathcal{H}_n$ , each $\mathcal{H}_n$ with $m_n^{UC}(\epsilon, \delta)$ , $\omega : \mathcal{N} \mapsto [0, 1]$ and $\sum \omega(n) \leq 1$ . $\forall \mathcal{D}, \forall \delta$ and $\forall \epsilon$ , $\forall h$ , we have $P_{S \sim \mathcal{D}^m}[\exists h :  L_{\mathcal{D}}(h) - L_S(h)  > \epsilon_{n(h)}(m, \omega(n(h))\delta)] < \delta$ <p>This implies that</p> $L_{\mathcal{D}}(h) \leq L_S(h) + \epsilon_{n(h)}(m, \omega(n(h))\delta)$

Convergence bounds on  $S$ :  $|L_S(h) - L_{\mathcal{D}}(h)|$



# NUL versus A-PAC

The Fundamental Theorem of PAC Learning

Learning Beyond Classes with Finite VC Dimension

Nonuniform Learnability

NUL versus A-PAC

Structural Risk Minimization

Minimum Description Length

Consistency Learnability

Quiz

Table 2: Comparison of NUL and Agnostic PAC (II)

Learnability	Learner
<b>Agnostic PAC</b>	<b>ERM</b> learner: $\forall h, \forall \mathcal{D}, \forall \delta$ and $\forall \epsilon$ , if $m \geq \dots$ , we have $L_{\mathcal{D}}(A(S)) \leq L_S(h) + \epsilon$ for $m \geq m_{\mathcal{H}}^{UC}(\epsilon/2, \delta)$ with probability at least $1 - \delta$ .
<b>NUL</b>	<b>SRM</b> learner: let $A(S)$ be any hypothesis $h \in \mathcal{H}$ that minimizes $L_{\mathcal{D}}(A(S)) \leq L_S(h) + \epsilon_{n(h)}(m, \omega(n(h)))\delta$

Learner bounds its error on  $S$ :  $|L_{\mathcal{D}}(A(S)) - L_{\mathcal{D}}(h)|$



# Structural Risk Minimization

[The Fundamental Theorem of PAC Learning](#)

[Learning Beyond Classes with Finite VC Dimension](#)

[Nonuniform Learnability](#)

[NUL versus A-PAC](#)

[Structural Risk Minimization](#)

[Minimum Description Length](#)

[Consistency Learnability](#)

[Quiz](#)



A Structural Risk Minimization (SRM) algorithm is given some training sample  $S$  and a confidence parameter  $\delta$ , and picks  $h$  that minimizes

$$L_S(h) + \epsilon_{n(h)}(m, \omega(n(h)))\delta$$



# Structural Risk Minimization

[The Fundamental Theorem of PAC Learning](#)

[Learning Beyond Classes with Finite VC Dimension](#)

[Nonuniform Learnability](#)

[NUL versus A-PAC](#)

[Structural Risk Minimization](#)

[Minimum Description Length](#)

[Consistency Learnability](#)

[Quiz](#)



A **Structural Risk Minimization (SRM)** algorithm is given some training sample  $S$  and a confidence parameter  $\delta$ , and picks  $h$  that minimizes

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*Prior knowledge.* In PAC learning, learner expresses prior knowledge by specifying the hypothesis class  $\mathcal{H}$ . But there are other ways to express prior knowledge:

- a union of classes of hypothesis  $\mathcal{H} = \cup_{n \in \mathcal{N}} \mathcal{H}_n$



# Structural Risk Minimization

[The Fundamental Theorem of PAC Learning](#)

[Learning Beyond Classes with Finite VC Dimension](#)

[Nonuniform Learnability](#)

[NUL versus A-PAC](#)

[Structural Risk Minimization](#)

[Minimum Description Length](#)

[Consistency Learnability](#)

[Quiz](#)



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- a union of classes of hypothesis  $\mathcal{H} = \cup_{n \in \mathcal{N}} \mathcal{H}_n$
- and prior weight  $\omega(n)$  for each  $\mathcal{H}_n$ , with  $n(h) = \min\{n : h \in \mathcal{H}_n\}$





# Structural Risk Minimization

The Fundamental Theorem of PAC Learning

Learning Beyond Classes with Finite VC Dimension

Nonuniform Learnability

NUL versus A-PAC

Structural Risk Minimization

Minimum Description Length

Consistency Learnability

Quiz



Given  $\mathcal{H} = \cup_{n \in \mathcal{N}} \mathcal{H}_n$ , where each  $\mathcal{H}_n$  satisfies the uniform convergence property with a sample complexity function  $m_{\mathcal{H}_n}^{UC}$ . Given any weight function  $\omega : \mathcal{N} \mapsto [0, 1]$  and  $\sum \omega(n) \leq 1$ . Any SRM algorithm is a successful **Non-Uniform Learner** with sample

$$m_{\mathcal{H}}^{NUL}(\epsilon, \delta, h) \leq m_{\mathcal{H}_{n(h)}}^{UC}(\epsilon/2, \omega(n(h))\delta)$$



# Structural Risk Minimization

The Fundamental Theorem of PAC Learning

Learning Beyond Classes with Finite VC Dimension

Nonuniform Learnability

NUL versus A-PAC

Structural Risk Minimization

Minimum Description Length

Consistency Learnability

Quiz



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- By the SRM algorithm, we have

$$L_{\mathcal{D}}(A(S)) \leq L_S(h) + \epsilon_{n(h)}(m, \omega(n(h))\delta)$$



# Structural Risk Minimization

The Fundamental Theorem of PAC Learning

Learning Beyond Classes with Finite VC Dimension

Nonuniform Learnability

NUL versus A-PAC

Structural Risk Minimization

Minimum Description Length

Consistency Learnability

Quiz



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*Prior knowledge.*

- By the SRM algorithm, we have

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- If  $m \geq m_{\mathcal{H}_{n(h)}}^{UC}(\epsilon/2, \omega(n(h))\delta)$ , then clearly we have  $\epsilon_{n(h)}(m, \omega(n(h))\delta) \leq \epsilon/2$ .



# Structural Risk Minimization

The Fundamental Theorem of PAC Learning

Learning Beyond Classes with Finite VC Dimension

Nonuniform Learnability

NUL versus A-PAC

Structural Risk Minimization

Minimum Description Length

Consistency Learnability

Quiz



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- From UC property of each  $\mathcal{H}_n$ , we have that with probability of at most  $\delta_n$ ,

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# Structural Risk Minimization

The Fundamental Theorem of PAC Learning

Learning Beyond Classes with Finite VC Dimension

Nonuniform Learnability

NUL versus A-PAC

Structural Risk Minimization

Minimum Description Length

Consistency Learnability

Quiz



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- From UC property of each  $\mathcal{H}_n$ , we have that with probability of at most  $\delta_n$ ,

$$L_S(h) > L_{\mathcal{D}}(h) + \epsilon/2$$

- Combining together we obtain that at most  $\delta$  we have

$$L_{\mathcal{D}}(A(S)) > L_{\mathcal{D}}(h) + \epsilon$$





# Minimum Description Length

[The Fundamental Theorem of PAC Learning](#)

[Learning Beyond Classes with Finite VC Dimension](#)

[Nonuniform Learnability](#)

[NUL versus A-PAC](#)

[Structural Risk Minimization](#)

[Minimum Description Length](#)

[Consistency Learnability](#)

[Quiz](#)

## Bias to Shorter Description:



- Let  $\mathcal{H}$  be a countable hypothesis class
- Let  $\omega : \mathcal{H} \mapsto \mathcal{R}$  be such that  $\sum_{h \in \mathcal{H}} \omega(h) \leq 1$ 
  - ◆ The function  $\omega$  reflects prior knowledge on how important  $h$  is



# Minimum Description Length

The Fundamental Theorem of PAC Learning

Learning Beyond Classes with Finite VC Dimension

Nonuniform Learnability

NUL versus A-PAC

Structural Risk Minimization

Minimum Description Length

Consistency Learnability

Quiz

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## Description Length.

- Suppose that each  $h \in \mathcal{H}$  is described by some word  $d(h) \in \{0, 1\}^*$ , such as a binary representation.



# Minimum Description Length

The Fundamental Theorem of PAC Learning

Learning Beyond Classes with Finite VC Dimension

Nonuniform Learnability

NUL versus A-PAC

Structural Risk Minimization

Minimum Description Length

Consistency Learnability

Quiz

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- Suppose that each  $h \in \mathcal{H}$  is described by some word  $d(h) \in \{0, 1\}^*$ , such as a binary representation.
- Suppose the binary representation is **prefix-free**, namely, for every  $h \neq h'$ ,  $d(h)$  is not a prefix of  $d(h')$ .



# Minimum Description Length

The Fundamental Theorem of PAC Learning

Learning Beyond Classes with Finite VC Dimension

Nonuniform Learnability

NUL versus A-PAC

Structural Risk Minimization

Minimum Description Length

Consistency Learnability

Quiz

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- Let  $|h|$  be the length of  $d(h)$ , then set  $\omega(h) = \frac{1}{2^{|h|}}$ .



# Minimum Description Length

The Fundamental Theorem of PAC Learning

Learning Beyond Classes with Finite VC Dimension

Nonuniform Learnability

NUL versus A-PAC

Structural Risk Minimization

Minimum Description Length

Consistency Learnability

Quiz



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- Suppose the binary representation is **prefix-free**, namely, for every  $h \neq h'$ ,  $d(h)$  is not a prefix of  $d(h')$ .
- Let  $|h|$  be the length of  $d(h)$ , then set  $\omega(h) = \frac{1}{2^{|h|}}$ .
- From Kraft's inequality, we have  $\sum_h \omega(h) \leq 1$ 
  - ◆ define probability over words in  $d(H)$  as follows: repeatedly toss an unbiased coin, until the sequence of outcomes is a member of  $d(H)$ , and then stop.
  - ◆ Since  $d(H)$  is prefix-free, this is a valid probability over  $d(H)$ , and the probability to get  $d(h)$  is  $\omega(h)$ .





# Minimum Description Length

[The Fundamental Theorem of PAC Learning](#)

[Learning Beyond Classes with Finite VC Dimension](#)

[Nonuniform Learnability](#)

[NUL versus A-PAC](#)

[Structural Risk Minimization](#)

[Minimum Description Length](#)

[Consistency Learnability](#)

[Quiz](#)

Let  $\omega : \mathcal{H} \rightarrow \mathcal{R}$  be such that  $\sum_{h \in \mathcal{H}} \omega(h) \leq 1$ . Then, with probability of at least  $1 - \delta$  over  $S \sim \mathcal{D}^m$ , we have  $\forall h \in \mathcal{H}$ ,



$$L_{\mathcal{D}}(h) \leq L_S(h) + \sqrt{\frac{-\log(\omega(h)) + \log(2/\delta)}{2m}}$$



# Minimum Description Length

[The Fundamental Theorem of PAC Learning](#)

[Learning Beyond Classes with Finite VC Dimension](#)

[Nonuniform Learnability](#)

[NUL versus A-PAC](#)

[Structural Risk Minimization](#)

[Minimum Description Length](#)

[Consistency Learnability](#)

[Quiz](#)

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*Proof.*

- For every  $h$ , define  $\delta_h = \omega(h) \cdot \delta$ .



# Minimum Description Length

The Fundamental Theorem of PAC Learning

Learning Beyond Classes with Finite VC Dimension

Nonuniform Learnability

NUL versus A-PAC

Structural Risk Minimization

Minimum Description Length

Consistency Learnability

Quiz

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*Proof.*

- For every  $h$ , define  $\delta_h = \omega(h) \cdot \delta$ .
- By Hoeffding's bound, for every  $h$ ,  $\mathcal{D}^m(\{S : L_{\mathcal{D}}(h) > L_S(h) + \sqrt{\frac{\log(2/\delta_h)}{2m}}\}) \leq \delta_h$



# Minimum Description Length

The Fundamental Theorem of PAC Learning

Learning Beyond Classes with Finite VC Dimension

Nonuniform Learnability

NUL versus A-PAC

Structural Risk Minimization

Minimum Description Length

Consistency Learnability

Quiz

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*Proof.*

- For every  $h$ , define  $\delta_h = \omega(h) \cdot \delta$ .
- By Hoeffding's bound, for every  $h$ ,  $\mathcal{D}^m(\{S : L_{\mathcal{D}}(h) > L_S(h) + \sqrt{\frac{\log(2/\delta_h)}{2m}}\}) \leq \delta_h$
- Applying the union bound,

$$\begin{aligned} & \mathcal{D}^m(\{S : \exists h \in \mathcal{H}, L_{\mathcal{D}}(h) > L_S(h) + \sqrt{\frac{\log(2/\delta_h)}{2m}}\}) \\ &= \mathcal{D}^m(\bigcup_{h \in \mathcal{H}} \{S : L_{\mathcal{D}}(h) > L_S(h) + \sqrt{\frac{\log(2/\delta_h)}{2m}}\}) \\ &\leq \sum_{h \in \mathcal{H}} \delta_h \leq \delta \end{aligned}$$



# Minimum Description Length

[The Fundamental Theorem of PAC Learning](#)

[Learning Beyond Classes with Finite VC Dimension](#)

[Nonuniform Learnability](#)

[NUL versus A-PAC](#)

[Structural Risk Minimization](#)

[Minimum Description Length](#)

[Consistency Learnability](#)

[Quiz](#)

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$$L_{\mathcal{D}}(h) \leq L_S(h) + \sqrt{\frac{-\log(\omega(h)) + \log(2/\delta)}{2m}}$$

*Bounds Minimization.*

**Learning Objective** to minimize  $L_{\mathcal{D}}(h)$  over  $h \in \mathcal{H}$



# Minimum Description Length

[The Fundamental Theorem of PAC Learning](#)

[Learning Beyond Classes with Finite VC Dimension](#)

[Nonuniform Learnability](#)

[NUL versus A-PAC](#)

[Structural Risk Minimization](#)

[Minimum Description Length](#)

[Consistency Learnability](#)

[Quiz](#)

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# Minimum Description Length

The Fundamental Theorem of PAC Learning

Learning Beyond Classes with Finite VC Dimension

Nonuniform Learnability

NUL versus A-PAC

Structural Risk Minimization

Minimum Description Length

Consistency Learnability

Quiz

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**Algorithms**

**ERM** minimizes the VC bound

**MDL** minimizes the MDL bound





# Consistency Learnability

[The Fundamental Theorem of PAC Learning](#)

[Learning Beyond Classes with Finite VC Dimension](#)

Nonuniform Learnability

NUL versus A-PAC

Structural Risk Minimization

Minimum Description Length

Consistency Learnability

[Quiz](#)



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# Consistency Learnability

[The Fundamental Theorem of PAC Learning](#)

[Learning Beyond Classes with Finite VC Dimension](#)

Nonuniform Learnability

NUL versus A-PAC

Structural Risk Minimization

Minimum Description Length

Consistency Learnability

[Quiz](#)



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[The Fundamental Theorem of PAC Learning](#)

[Learning Beyond Classes with Finite VC Dimension](#)

Nonuniform Learnability

NUL versus A-PAC

Structural Risk Minimization

Minimum Description Length

Consistency Learnability

[Quiz](#)

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[The Fundamental Theorem of PAC Learning](#)

[Learning Beyond Classes with Finite VC Dimension](#)

Nonuniform Learnability

NUL versus A-PAC

Structural Risk Minimization

Minimum Description Length

Consistency Learnability

[Quiz](#)

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# Consistency Learnability

[The Fundamental Theorem of PAC Learning](#)

[Learning Beyond Classes with Finite VC Dimension](#)

Nonuniform Learnability

NUL versus A-PAC

Structural Risk Minimization

Minimum Description Length

Consistency Learnability

[Quiz](#)

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The Fundamental Theorem of PAC Learning

Learning Beyond Classes with Finite VC Dimension

Nonuniform Learnability

NUL versus A-PAC

Structural Risk Minimization

Minimum Description Length

Consistency Learnability

Quiz

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  - ◆ What to do if the returned hypothesis with a large risk?



# Consistency Learnability

[The Fundamental Theorem of PAC Learning](#)

[Learning Beyond Classes with Finite VC Dimension](#)

Nonuniform Learnability

NUL versus A-PAC

Structural Risk Minimization

Minimum Description Length

Consistency Learnability

[Quiz](#)



A Memorize algorithm is universally consistent for every countable domain  $\mathcal{X}$  and a finite label set  $\mathcal{Y}$ , with respect to the zero-one loss.

*Intuition.*





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The Fundamental Theorem of PAC Learning

Learning Beyond Classes with Finite VC Dimension

Nonuniform Learnability

NUL versus A-PAC

Structural Risk Minimization

Minimum Description Length

Consistency Learnability

Quiz



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The Fundamental Theorem of PAC Learning

Learning Beyond Classes with Finite VC Dimension

Nonuniform Learnability

NUL versus A-PAC

Structural Risk Minimization

Minimum Description Length

Consistency Learnability

Quiz



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The Fundamental Theorem of PAC Learning

Learning Beyond Classes with Finite VC Dimension

Nonuniform Learnability

NUL versus A-PAC

Structural Risk Minimization

Minimum Description Length

Consistency Learnability

Quiz



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The Fundamental Theorem of PAC Learning

Learning Beyond Classes with Finite VC Dimension

Nonuniform Learnability

NUL versus A-PAC

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The Fundamental Theorem of PAC Learning

Learning Beyond Classes with Finite VC Dimension

Nonuniform Learnability

NUL versus A-PAC

Structural Risk Minimization

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Consistency Learnability

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The Fundamental Theorem of PAC Learning

Learning Beyond Classes with Finite VC Dimension

Quiz

# Quiz



# The VC Dimension

[The Fundamental Theorem of PAC Learning](#)

[Learning Beyond Classes with Finite VC Dimension](#)

[Quiz](#)



- Let  $\mathcal{H}_1, \dots, \mathcal{H}_r$  be hypothesis classes over some fixed domain set  $\mathcal{X}$ . Let  $d = \max_i VCDim(\mathcal{H}_i)$  and assume for simplicity that  $d \geq 3$ .



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[The Fundamental Theorem of PAC Learning](#)

[Learning Beyond Classes with Finite VC Dimension](#)

[Quiz](#)



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[The Fundamental Theorem of PAC Learning](#)

[Learning Beyond Classes with Finite VC Dimension](#)

[Quiz](#)



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2. Prove that

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# Non-uniform Learnability

[The Fundamental Theorem of PAC Learning](#)

[Learning Beyond Classes with Finite VC Dimension](#)

[Quiz](#)



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Learning Beyond Classes with Finite VC Dimension

Quiz



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Learning Beyond Classes with Finite VC Dimension

Quiz



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  2. The weights could be monotonically nondecreasing, namely, if  $i < j$ , then  $\omega(\mathcal{H}_i) \leq \omega(\mathcal{H}_j)$ .



# Machine Learning Project

[The Fundamental Theorem of PAC Learning](#)

[Learning Beyond Classes with Finite VC Dimension](#)

[Quiz](#)



You are free to do either of the following projects

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## References

The Fundamental Theorem of PAC Learning

Learning Beyond Classes with Finite VC Dimension

Quiz

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# Questions?

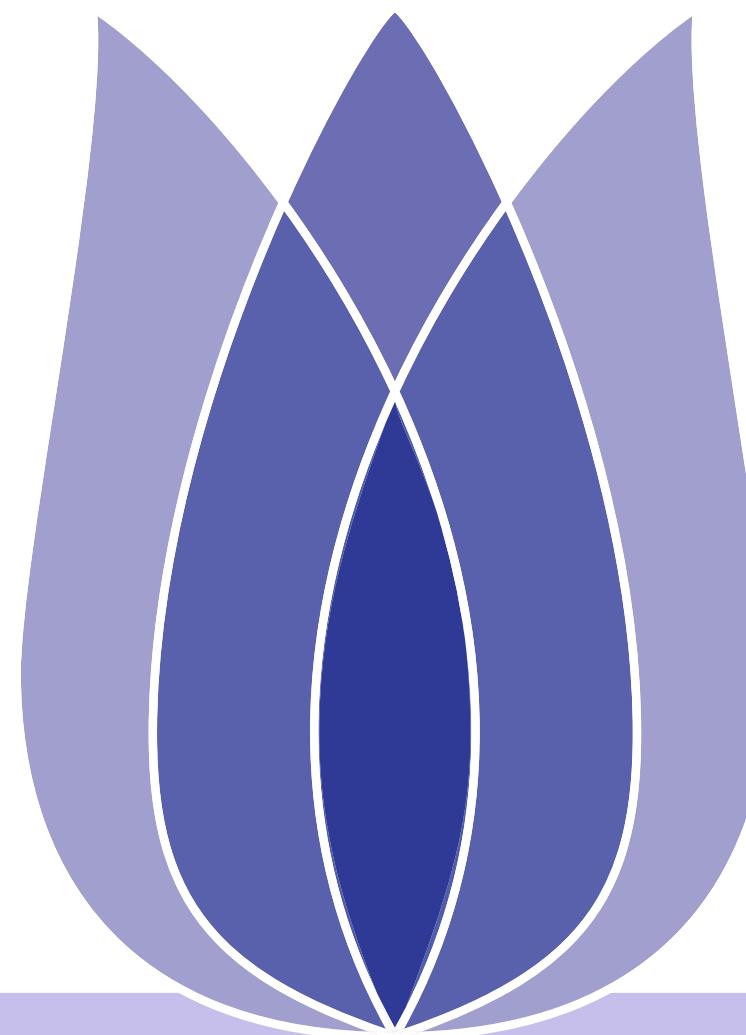
[The Fundamental Theorem of PAC Learning](#)

[Learning Beyond Classes with Finite VC Dimension](#)

[Quiz](#)



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