

Exercise 6: tracking camera motions

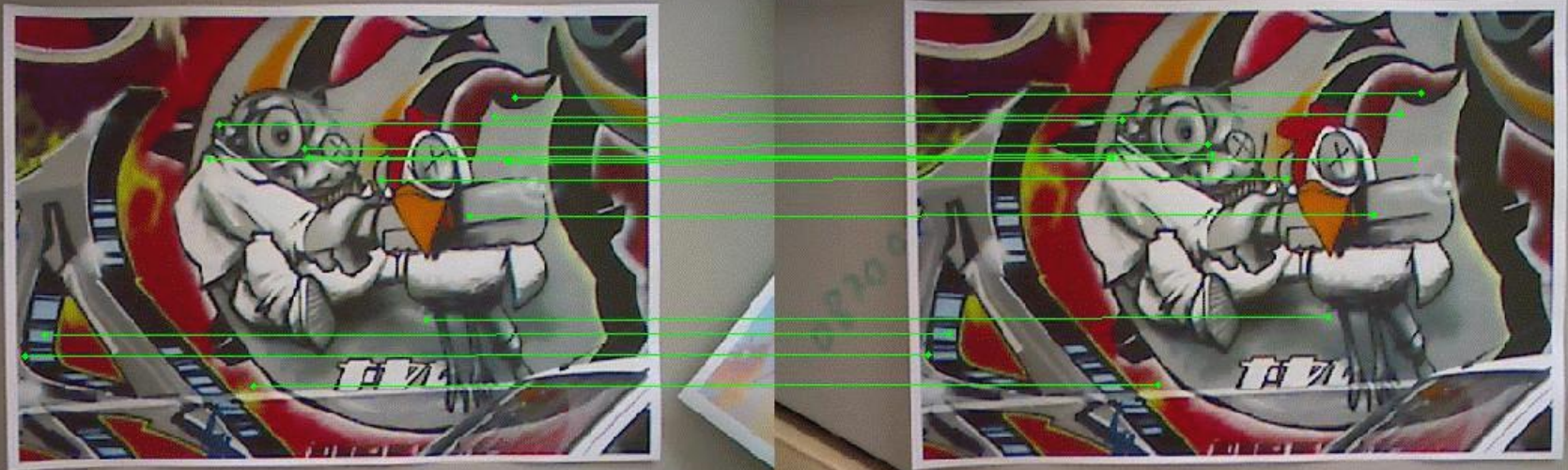


15 fps

What's the corresponding camera movement in the above sequences ?

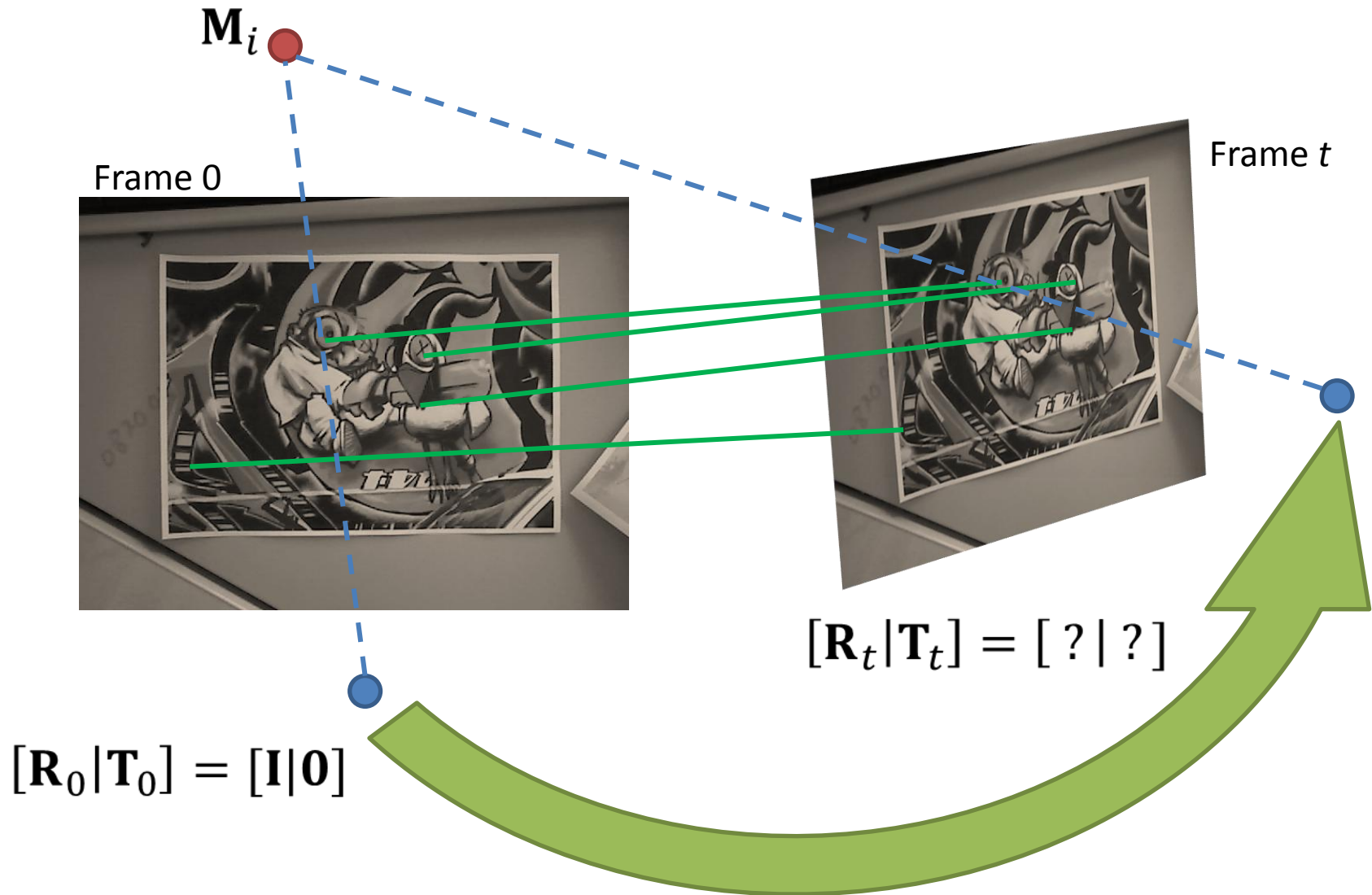
Finding correspondences

frame 1

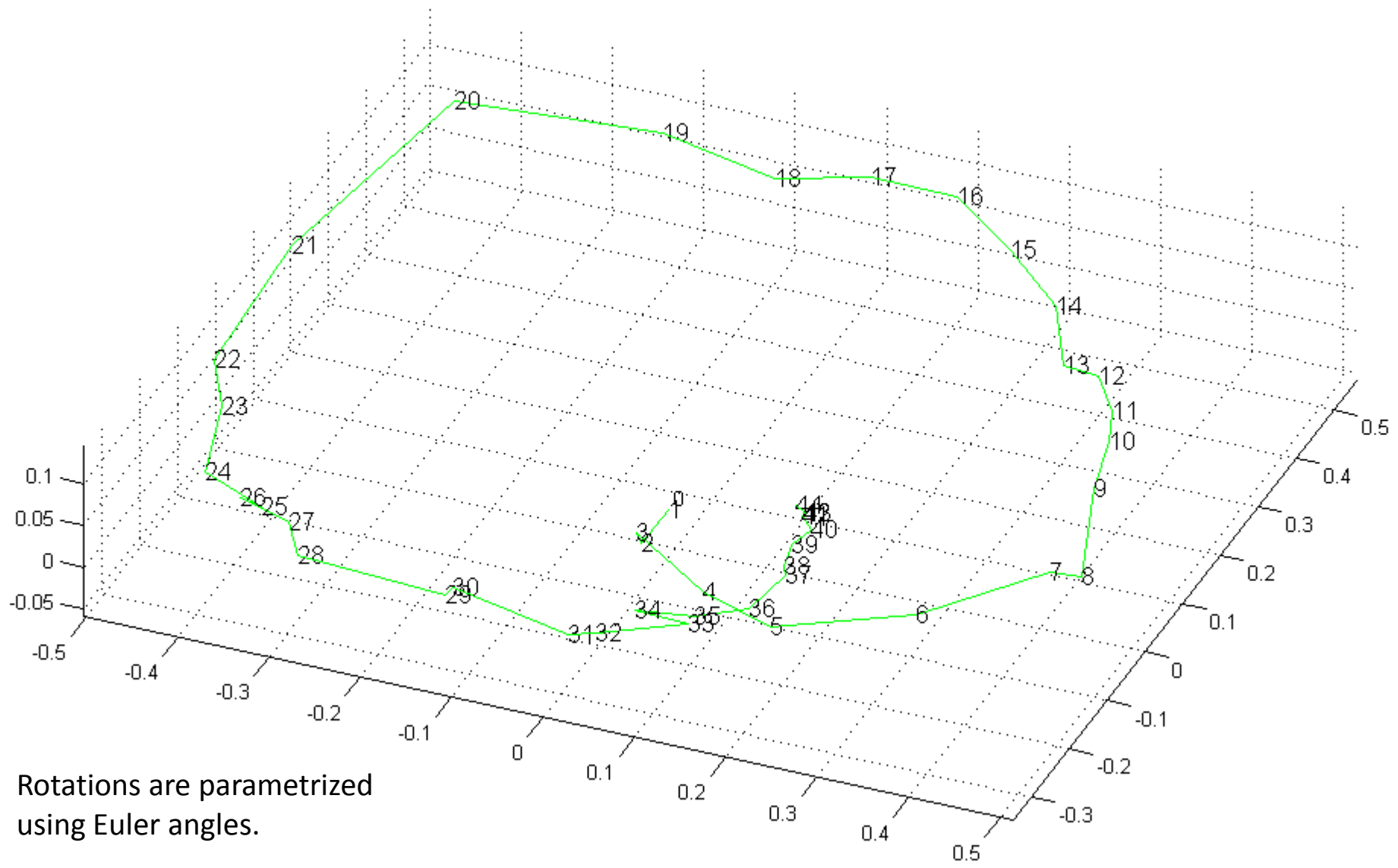


similar to exercise sheet 5: SIFT, DLT, RANSAC, etc.

Estimating camera poses



Example result



Rotations are parametrized
using Euler angles.