

ENS DE LYON

*Inria*

# **Existence of optima in sparse matrix factorization and sparse ReLU networks training**

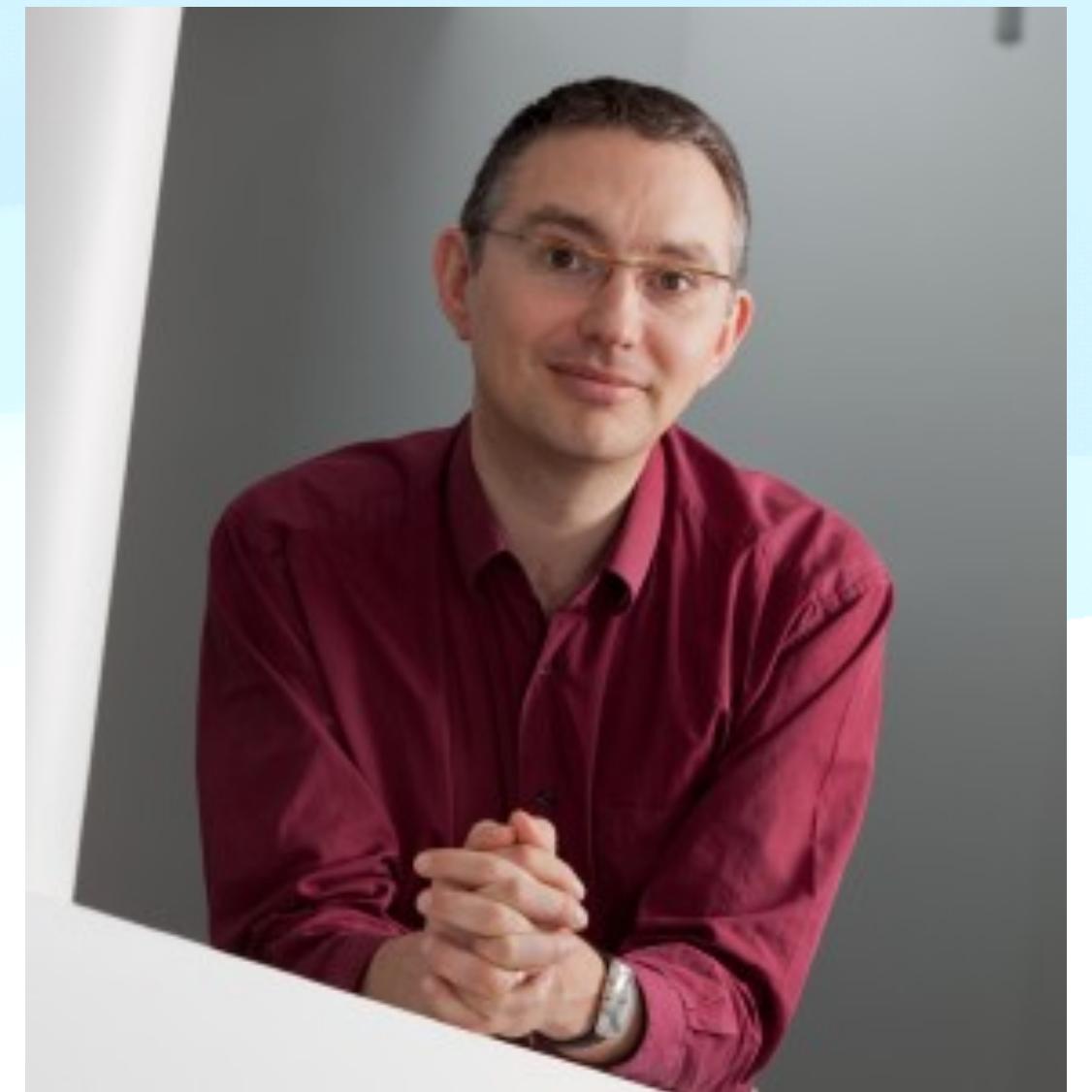
Le Quoc Tung, 27 June 2023



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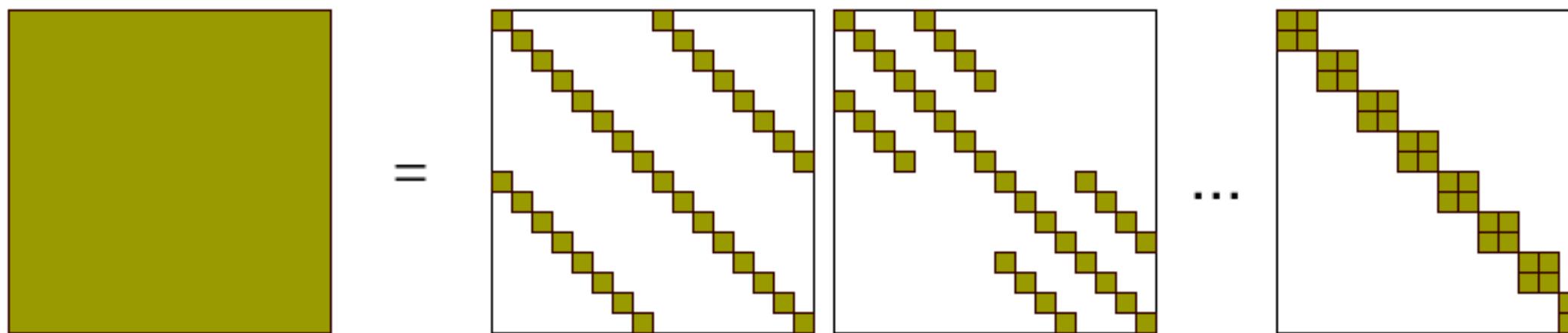
# Sparse matrix factorization

**OBJECTIVES:** Given  $A$ , find some **sparse** matrices  $X_\ell, \ell = 1, \dots, L$ , such that:

$$A \approx X_1 \dots X_L$$

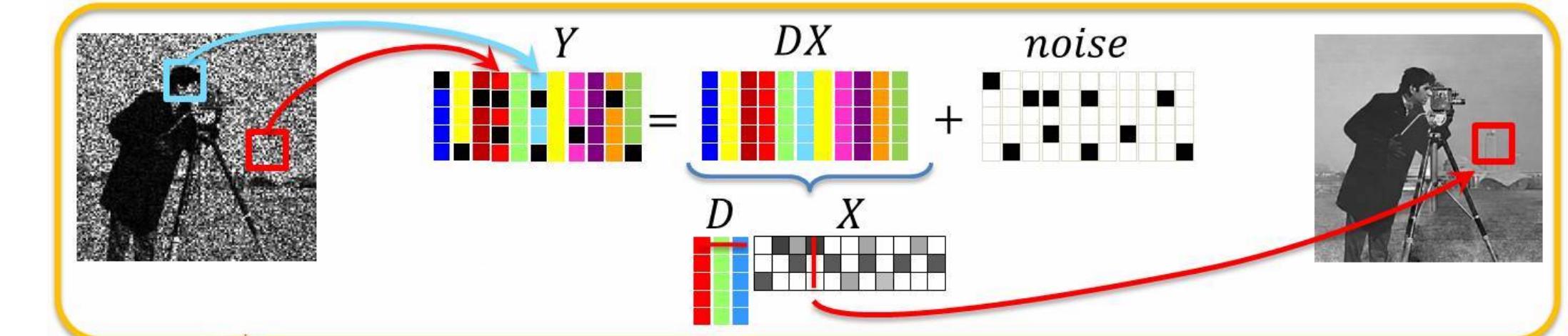
**APPLICATIONS:** Accelerating matrix-vector multiplication, data analysis, etc.

$$Ax \approx X_1(X_2 \dots (X_L x)), \forall x$$



Fast Fourier Transformation

$$Y = DX, \quad X \text{ sparse}$$



Dictionary learning

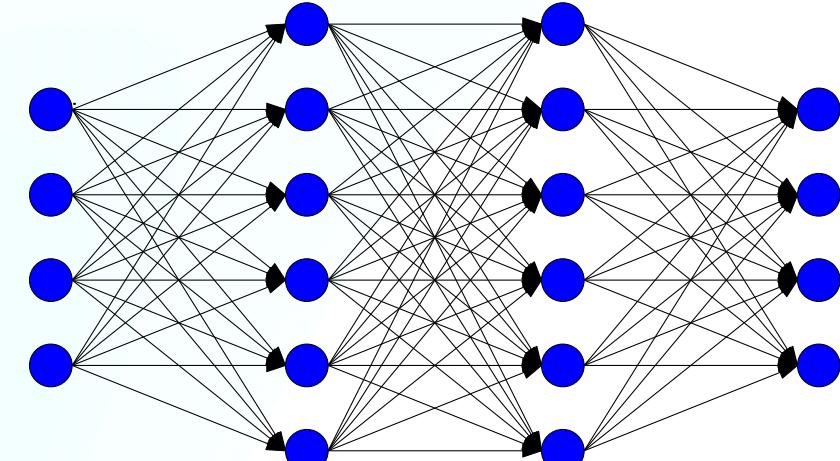
# ReLU neural networks and sparse ReLU neural networks

**DEFINITIONS:** Given **weight matrices**  $W^{(\ell)}$  and **bias vectors**  $b^{(\ell)}, \ell = 1, \dots, L$

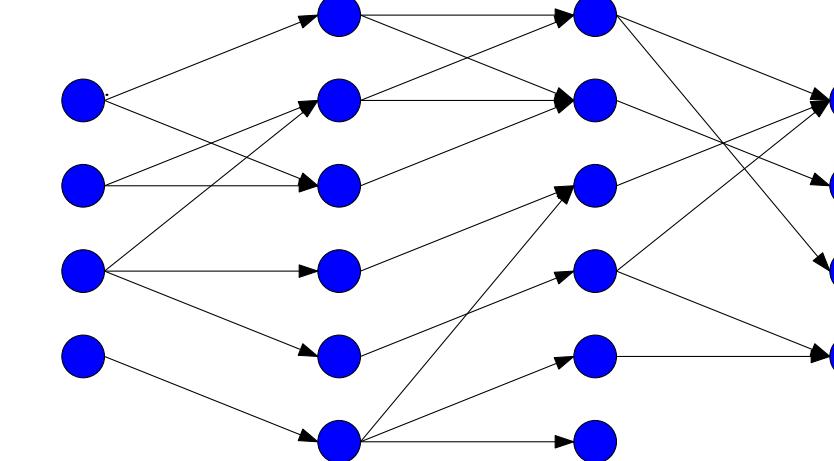
$$x \mapsto W^{(L)}\sigma(\dots\sigma(W^{(1)}x + b^{(1)}) + \dots) + b^{(L)}$$

$\sigma : \mathbb{R} \mapsto \mathbb{R} : \sigma(x) = \max(0, x)$  is the ReLU activation function

Conventional Deep Neural Networks



Sparse Deep Neural Networks



The weight matrices are dense

The weight matrices are sparse

# Sparse matrix factorization formulation

## OPTIMIZATION FORMULATIONS:

Given  $A$  and  $\mathcal{E}_j$  some sets of **sparse** matrices, solve:

$$\min_{S^{(1)}, \dots, S^{(J)}} \|A - \prod_{j=1}^L S^{(j)}\|_F^2 \text{ subject to: } S^{(j)} \in \mathcal{E}_j, \forall j \in \{1, \dots, L\}$$

Choice of sparse matrices set  $\mathcal{E}_j$

- $k$ -sparse per row,
- $k$ -sparse per column
- $k$ -sparse in total

**COMPLEXITY:** Problem is **NP-hard** in general (Malik, IPL 2017), (S.Foucart, H. Rauhut, ANNA 2013)

# Sparse ReLU neural networks (NNs) training

## OPTIMIZATION FORMULATIONS:

Given data set  $\mathcal{D} := (X, Y)$  and  $\mathcal{E}_j$  some sets of **sparse** matrices, solve:

$$\min_{W^{(j)}, b^{(j)}} \|Y - W^{(L)}\sigma(\dots\sigma(W^{(1)}X + b^{(1)}) + \dots) + b^{(L)}\|_F^2$$

subject to:  $W^{(j)} \in \mathcal{E}_j, \forall j \in \{1, \dots, L\}$

Practical choice of sparse matrices set  $\mathcal{E}_j$ :  $k$ -sparse in total

(J. Frankle, M. Carbin, ICLR 2019), (S. Han, H. Mao, W-J. Dally, ICLR 2016)

**COMPLEXITY:** Not known yet.

Expected to be difficult since training classical ReLU NNs is **NP-hard**.

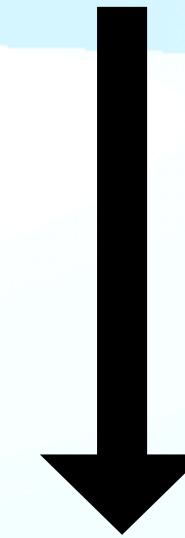
(R. Livni, S. Shalev-Shwartz, O. Shamir, NeuRIPS 2014), (D. Boob, S-S. Dey, G. Lan, Discrete Optimization 2022)

→ How to deal with these problems?

# Block ~~support~~ matrix factorization

## SPECIAL CASE OF SPARSE MATRIX FACTORISATION

SPARSE MATRIX  
FACTORISATION



$$\min_{S^{(1)}, \dots, S^{(J)}} \|A - \prod_{j=1}^L S^{(j)}\|_F^2 \text{ subject to: } S^{(j)} \in \mathcal{E}_j, \forall j \in \{1, \dots, L\}$$



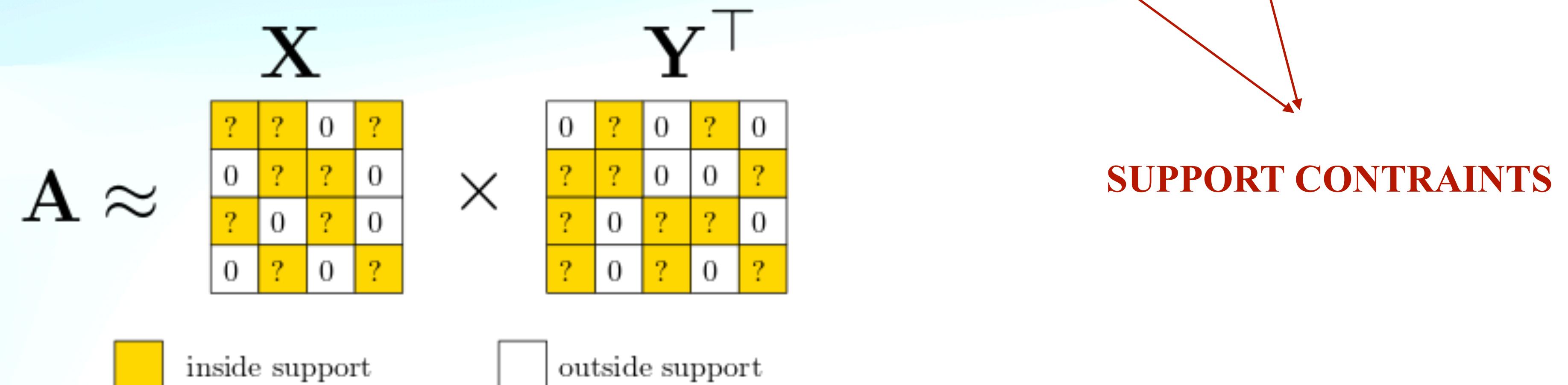
- $L = 2$
- $(\mathcal{E}_1, \mathcal{E}_2)$ : set of matrices whose **support** are included in  $I$  and  $J$

FIXED SUPPORT  
MATRIX  
FACTORISATION

$$\min_{X,Y} \|A - XY^\top\|_F^2 \text{ subject to: } \text{supp}(X) \subseteq I, \text{supp}(Y) \subseteq J$$

# Fixed support matrix factorization (FSMF)

$$\min_{X,Y} \|A - XY^\top\|_F^2 \text{ subject to: } \text{supp}(X) \subseteq I, \text{supp}(Y) \subseteq J$$



# Why Fixed Support Matrix Factorization?

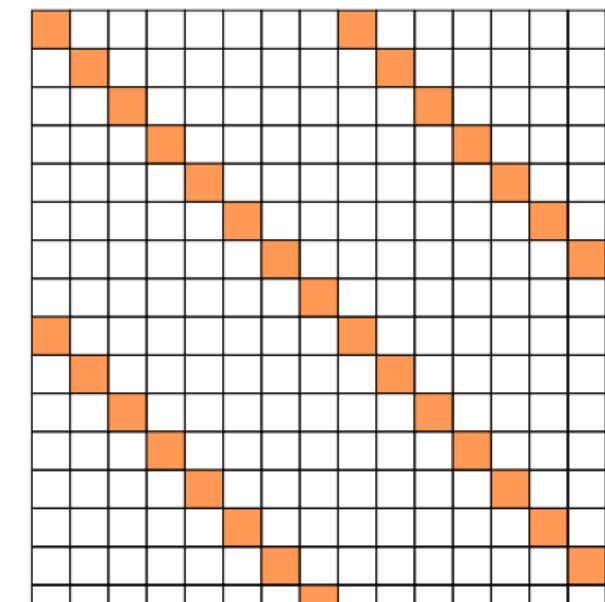
$$A = \begin{array}{c} \text{LU decomposition} \\ \times \end{array} \begin{array}{c} \text{Matrix} \\ \text{with} \\ \text{variable} \\ \text{support} \end{array}$$

$$A = \begin{array}{c} r \\ \longleftrightarrow \\ \times \end{array} \begin{array}{c} \text{Matrix} \\ \text{with} \\ \text{fixed} \\ \text{support} \end{array}$$

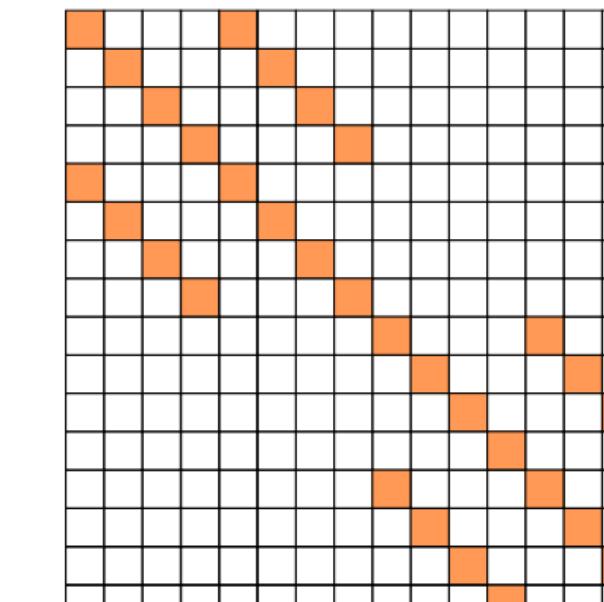
Low rank approximation



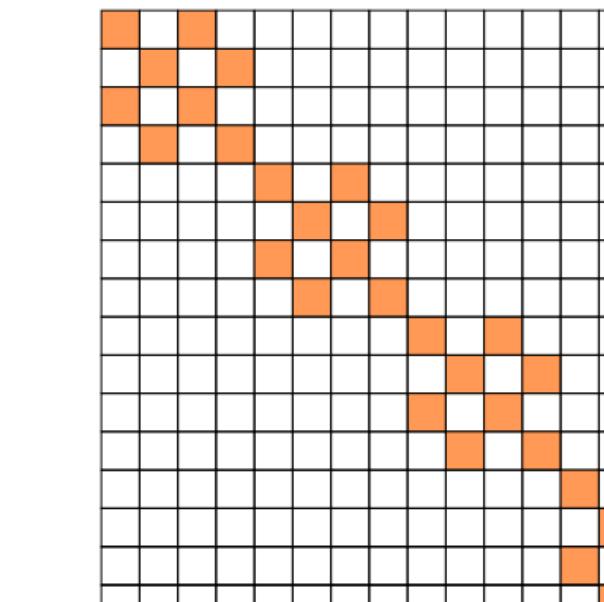
Hierarchical matrix



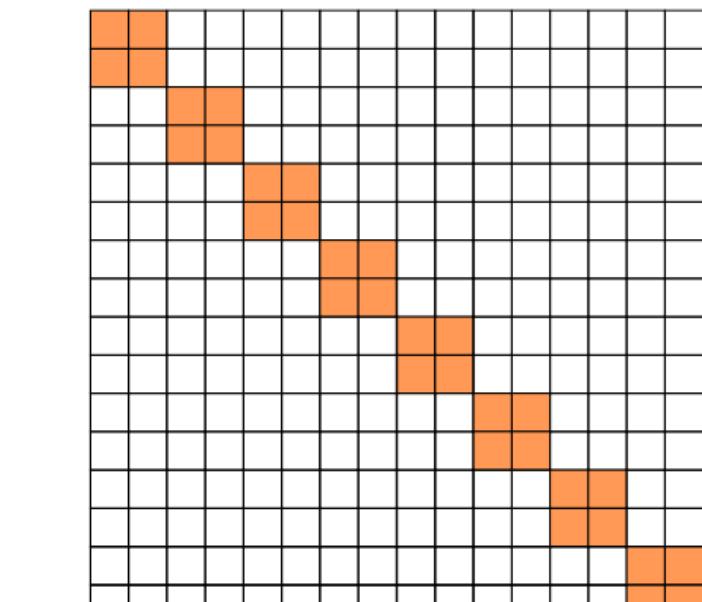
(a)  $S_{bf}^{(4)}$



(b)  $S_{bf}^{(3)}$



(c)  $S_{bf}^{(2)}$



(d)  $S_{bf}^{(1)}$

Butterfly matrix/factorization

# Known results on (FSMF)

- For arbitrary  $(I, J)$ , (FSMF) is *NP-hard* to solve.

NP-hardness

- There are instances  $(A, I, J)$  where (FSMF) has no optimal solution.

Ill-posedness

- For certain structured  $(I, J)$ , (FSMF) has a polynomial algorithm.

Tractability

- With the same family of structured  $(I, J)$ , loss function of (FSMF) has no local minima.

Benign landscape

# Existence of optimal solutions of FSMF

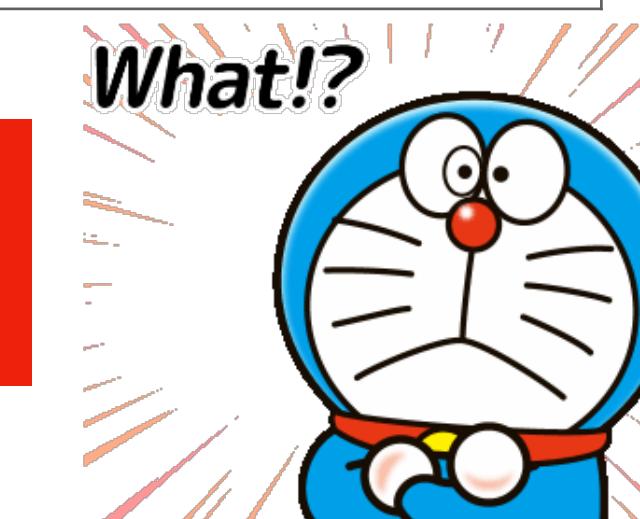
Low rank matrix approximation	LU decomposition
$A = \begin{matrix} & \xleftarrow[r]{} \\ \xleftarrow[r]{} & \end{matrix} \times \begin{matrix} & \\ & \xleftarrow[r]{} \end{matrix}$	$A = \begin{matrix} & \xleftarrow[r]{} \\ \xleftarrow[r]{} & \end{matrix} \times \begin{matrix} & \\ & \xleftarrow[r]{} \end{matrix}$

Huh...  
That's pretty good.

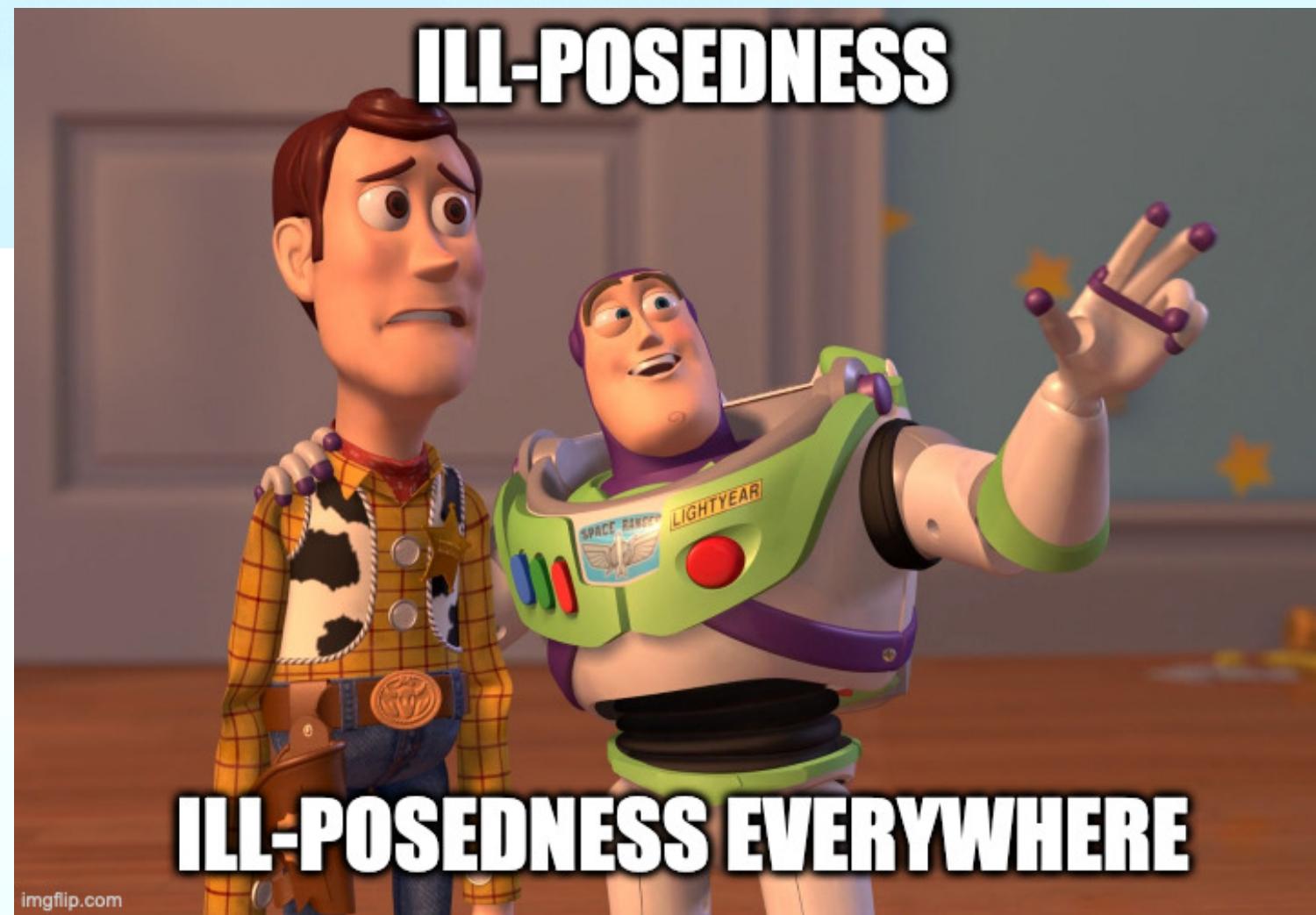


WELL-POSED

ILL-POSED



# Similar phenomenon



Tensor decomposition  
(order at least three)

TENSOR RANK AND THE ILL-POSEDNESS OF THE BEST  
LOW-RANK APPROXIMATION PROBLEM

VIN DE SILVA\* AND LEK-HENG LIM†

Matrix Completion

Low-Rank Matrix Approximation  
with Weights or Missing Data is NP-hard

Nicolas Gillis<sup>1</sup> and François Glineur<sup>1</sup>

Robust Principle  
Component Analysis

Matrix rigidity and the ill-posedness of  
Robust PCA and matrix completion\*

Jared Tanner<sup>†‡</sup> Andrew Thompson<sup>§</sup> Simon Vary<sup>†</sup>

(Classical) Neural  
Network Training

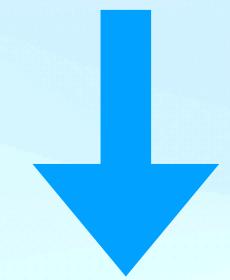
Best  $k$ -Layer Neural Network Approximations

Lek-Heng Lim<sup>1</sup> · Mateusz Michałek<sup>2,3</sup> · Yang Qi<sup>4</sup>

# Existence of optimal solutions of FSMF (cont)



Given support constraints  $(I, J)$ , is there a matrix  $A$  that makes (FSMF) have no optimal solution?



Given support constraints  $(I, J)$ , is there a data set  $\mathcal{D}$  that makes the training sparse ReLU NNs have no optimal solutions?

$$\min_{W^{(j)}, b^{(j)}}$$

subject to:

$$\|Y - W^{(L)}\sigma(\dots\sigma(W^{(1)}X + b^{(1)}) + \dots) + b^{(L)}\|_F^2$$

$$W^{(j)} \in \mathcal{E}_j, \forall j \in \{1, \dots, L\}$$

$\mathcal{E}_j$ : set of matrices whose **support** are *fixed*.

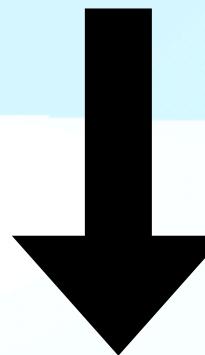
Similar assumption to (FSMF)

# Origin of ill-posedness

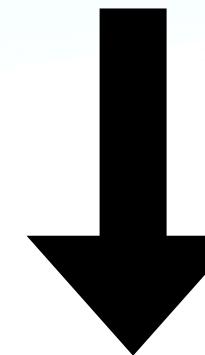
# Reformulation of (FSMF)

ORIGINAL  
FORMULATION

$$\min_{X,Y} \|A - XY^\top\|_F^2 \text{ subject to: } \text{supp}(X) \subseteq I, \text{supp}(Y) \subseteq J$$



Change of variables



NEW  
FORMULATION

$$\min_{B \in \mathcal{E}_{I,J}} \|A - B\|_F^2 \text{ where } \mathcal{E}_{I,J} := \{XY^\top \mid \text{supp}(X) \subseteq I, \text{supp}(Y) \subseteq J\}$$

**PROJECTION A ONTO THE SET  $\mathcal{E}_{I,J}$**

# Equivalence: closedness - well-posedness

A NECESSARY AND SUFFICIENT CONDITION

## THEOREM

$(I, J)$  is well-posed if and only if  $\mathcal{E}_{I,J}$  is a closed set in the usual topology of  $\mathbb{R}^{m \times n}$

## REMINDER:

**A set  $X$  is closed if the limit of any convergent sequence of elements of  $X$  is an element of  $X$ .**

# Equivalence: closedness - well-posedness

## PROOF

⇒ If  $(I, J)$  is well-posed:

By contradiction, assume that  $\mathcal{E}_{I,J}$  is not closed.

By definition, there exists  $A \notin \mathcal{E}_{I,J}$  such that there is a sequence  $\{B_n\}_{n \in \mathbb{N}}, B_n \in \mathcal{E}_{I,J}$  s.t.:

$$\lim_{n \rightarrow \infty} B_n = A.$$

Consider the (FSMF) with  $(A, I, J)$ :

- The infimum is zero (take the sequence  $\{B_n\}_{n \in \mathbb{N}}$ )
- The infimum is not attained ( $A \notin \mathcal{E}_{I,J}$ )

# Equivalence: closedness - well-posedness

## PROOF (CONT)

⇒ If  $\mathcal{E}_{I,J}$  is closed:

⇒ Since  $0 \in \mathcal{E}_{I,J}$  is closed, for any instance of (FSMF) with  $(A, I, J)$ , the infimum is at most  $C = \|A\|_F^2$ .

$$\min_B \|A - B\|_F^2 \text{ where } B \in \mathcal{E}_{I,J} \cap \mathbf{B}(A, \|A\|_F)$$

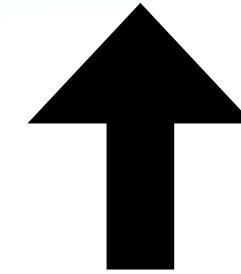
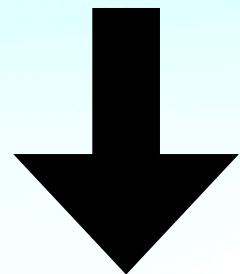
Ball centered at  $A$   
and radius  $\|A\|_F$

Important trick:  $\mathcal{E}_{I,J} \cap \mathbf{B}(A, \|A\|_F)$  is compact (bounded and closed).

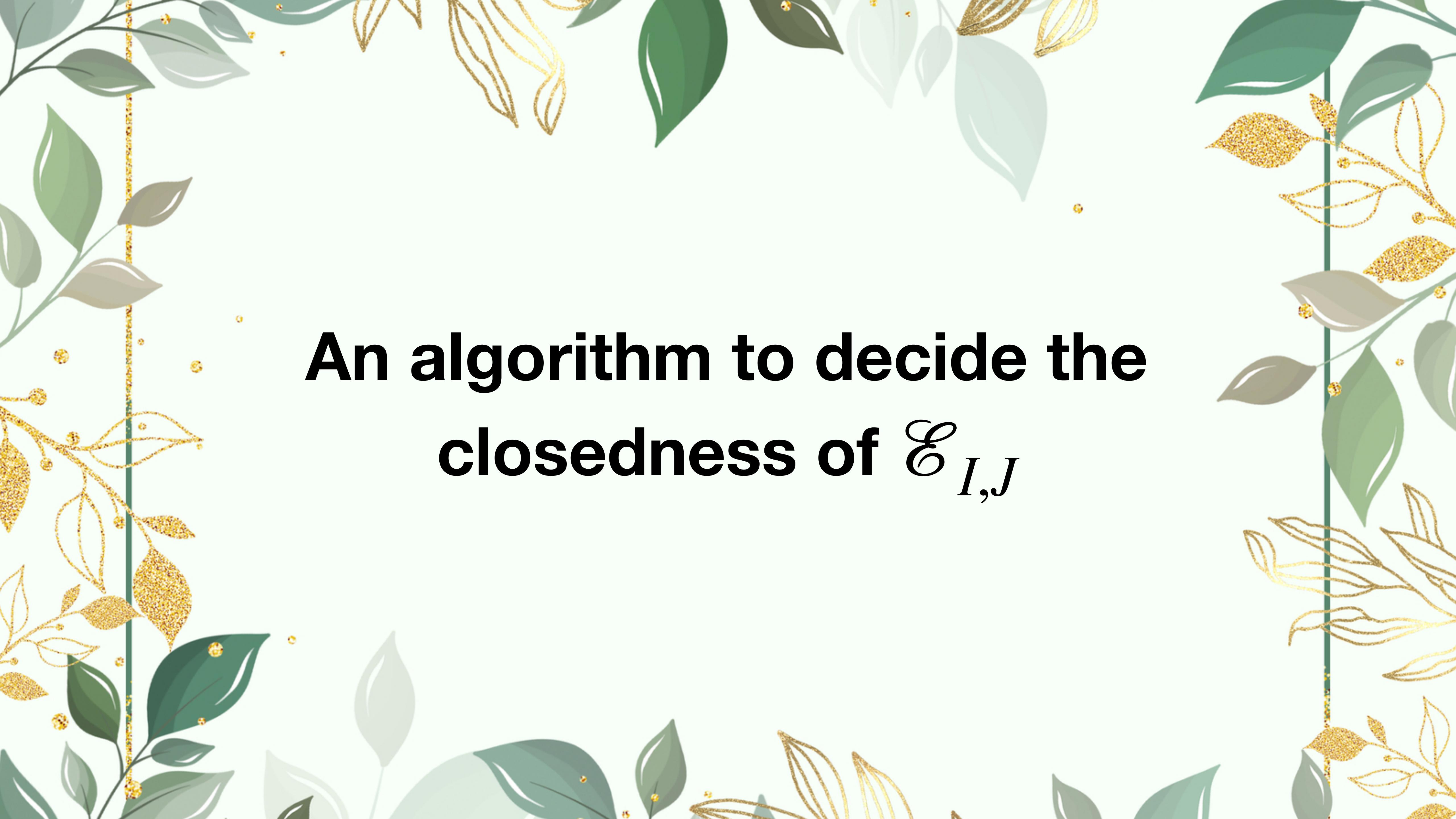
$\|A - \cdot\|_F^2$  is a continuous function.

# Conclusion

Given a support constraint  $(I, J)$ , decide whether  $(I, J)$  is **well-posed**.



Given a support constraint  $(I, J)$ , decide whether  $\mathcal{E}_{I,J}$  is **closed**.



# An algorithm to decide the closedness of $\mathcal{E}_{I,J}$

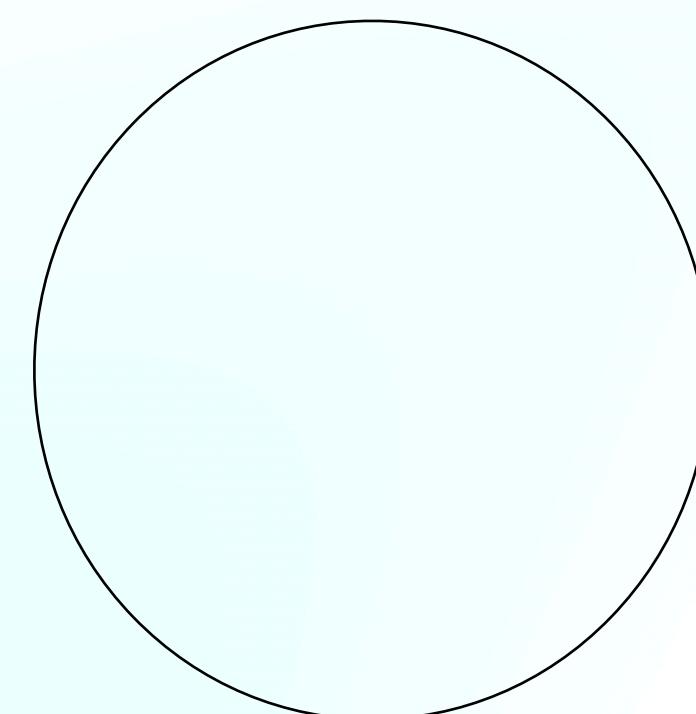
# Real algebraic geometry and its algorithm

## SEMI-ALGEBRAIC SET

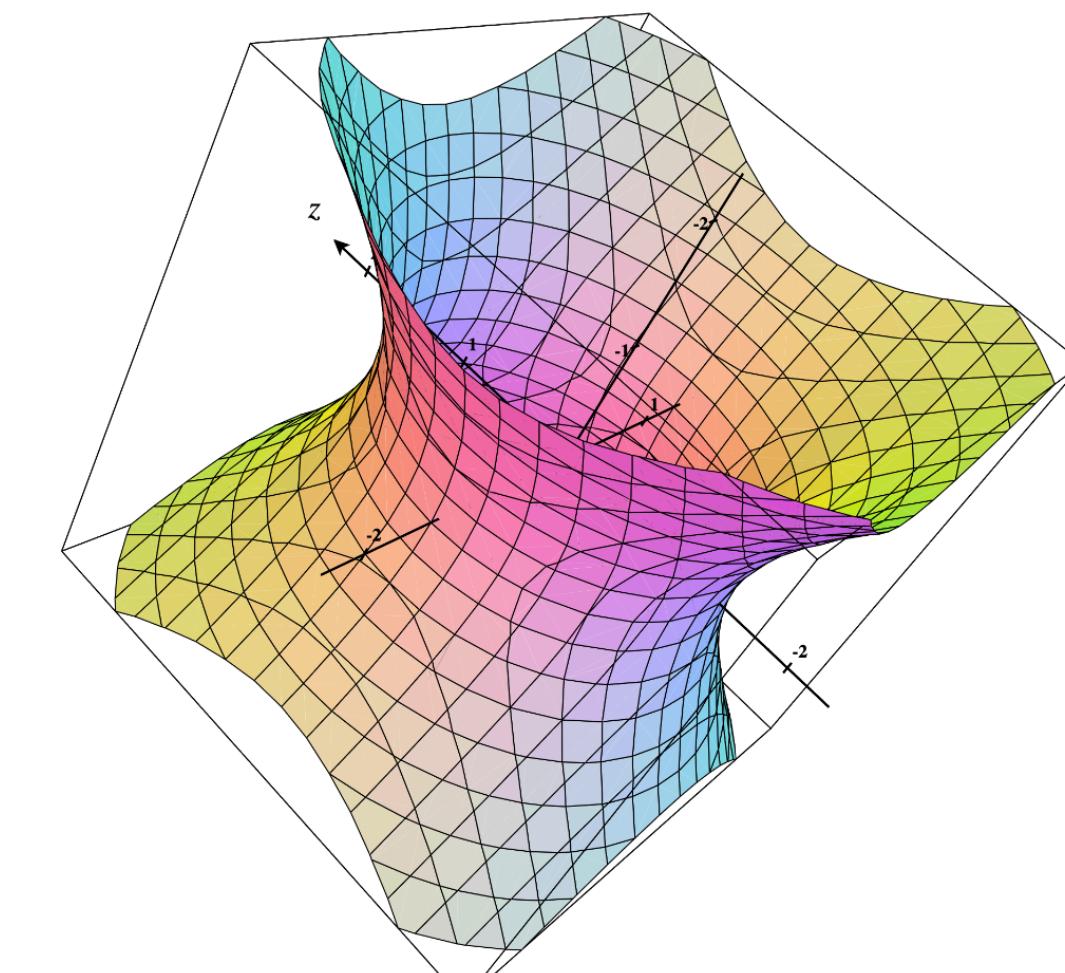
$$\bigcup_{i \in \mathcal{I}} \{x \in \mathbb{R}^n \mid P_i(x) = 0 \wedge \bigwedge_{j=1}^{\ell} Q_{i,j}(x) > 0\}, \mathcal{I} \text{ is finite}$$

where  $P_i, Q_{i,j}$  are polynomials

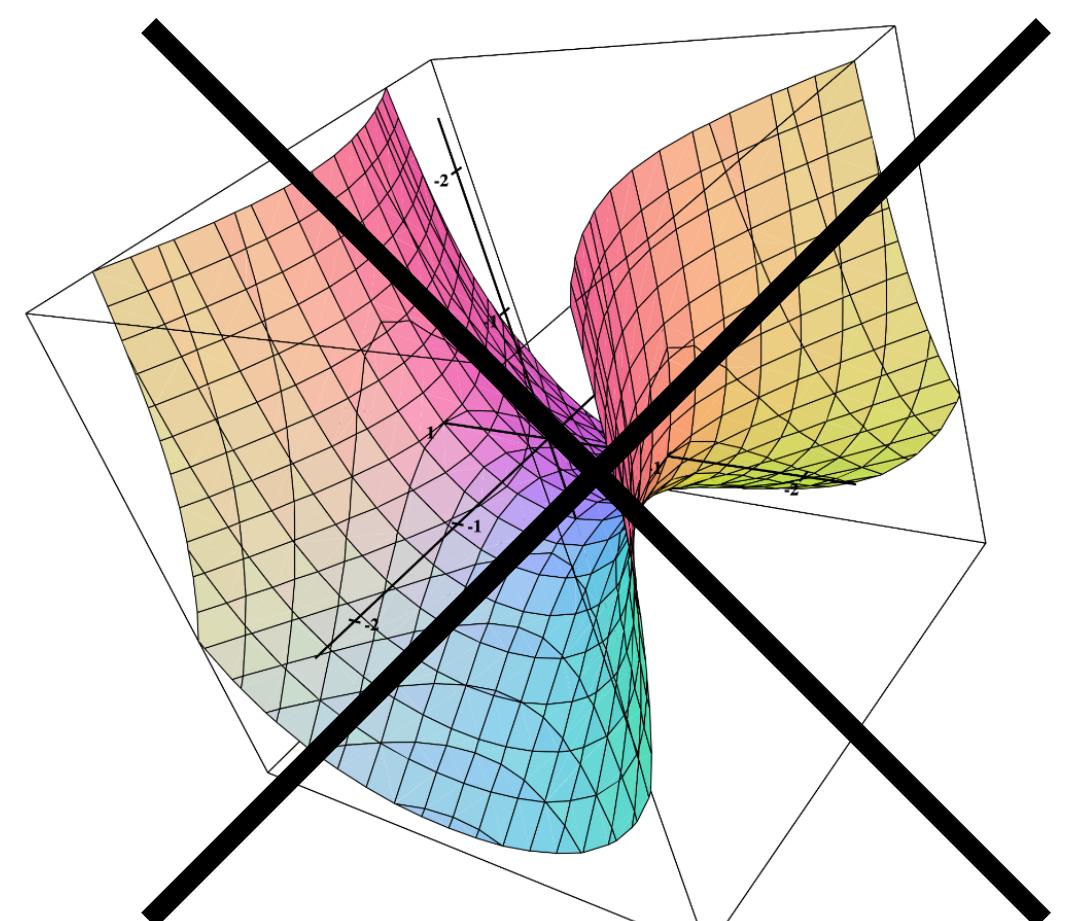
## EXAMPLE:



$$\{(x, y) \mid x^2 + y^2 = 1\}$$



$$\{(x, y, z) \mid x^2 - y^2 + z^2 = 2\}$$



$$\{(x, y, z) \mid x^2 - y^2 + e^z = 2\}$$

# $\mathcal{E}_{I,J}$ is a semi-algebraic set

## THEOREM

For any  $(I, J)$ ,  $\mathcal{E}_{I,J}$  is a semi-algebraic set

**REMINDER:**  $\mathcal{E}_{I,J} := \{XY^\top \mid \text{supp}(X) \subseteq I, \text{supp}(Y) \subseteq J\}$



How to find the set of polynomials describing  $\mathcal{E}_{I,J}$ ?

## PROJECTION THEOREM

Let  $X$  be semi-algebraic,  $Y = \{y \mid \exists x, (x, y) \in X\}$  is also semi-algebraic

# $\mathcal{E}_{I,J}$ is a semi-algebraic set (cont)

## PROJECTION THEOREM

Let  $X$  be semi-algebraic,  $Y = \{y \mid \exists x, (x, y) \in X\}$  is also semi-algebraic.

## PROOF (THAT $\mathcal{E}_{I,J}$ IS SEMI-ALGEBRAIC):

Consider  $\mathcal{A} := \{(A, X, Y) \mid \boxed{\|A - XY^T\|_F^2 = 0} \wedge \boxed{\text{supp}(X) \subseteq I} \wedge \boxed{\text{supp}(Y) \subseteq J}\}$ .

Therefore,  $\mathcal{A}$  is semi-algebraic.

polynomial

$X_{i,j} = 0, \forall (i, j) \notin I$

$Y_{i,j} = 0, \forall (i, j) \notin J$

To conclude, projection of  $\mathcal{A}$  to the first term is  $\mathcal{E}_{I,J}$  (because  $\|A - XY^T\|_F^2 \Rightarrow A = XY^T$ )

→ Therefore, we can use tools from real algebraic geometry to decide the closedness of  $\mathcal{E}_{I,J}$

# Deciding the closedness of $\mathcal{E}_{I,J}$

$\mathcal{E}_{I,J}$  is a closed set if and only if  $\overline{\mathcal{E}_{I,J}} \setminus \mathcal{E}_{I,J}$  is empty

**REMINDER:** Given a set  $\mathcal{A}$ ,  $\overline{\mathcal{A}}$  is the set of limits of sequence of  $\mathcal{A}$ .

$$\overline{\mathcal{E}_{I,J}} \setminus \mathcal{E}_{I,J} = \boxed{\{A \mid \forall X, \forall Y, \text{supp}(X) \subseteq I \wedge \text{supp}(Y) \subseteq J \wedge \|A - XY^\top\|^2 > 0\}}$$

$\mathcal{E}_{I,J}^C$

$$\bigcap \{A \mid \forall \epsilon > 0, \exists X, \exists Y, \text{supp}(X) \subseteq I \wedge \text{supp}(Y) \subseteq J \wedge \|A - XY^\top\|^2 < \epsilon\}$$

$\overline{\mathcal{E}_{I,J}}$

→ Using (generalised) projection theorem,  $\mathcal{E}_{I,J}^C, \overline{\mathcal{E}_{I,J}}, \overline{\mathcal{E}_{I,J}} \setminus \mathcal{E}_{I,J}$  are semi-algebraic sets

# Deciding the closedness of $\mathcal{E}_{I,J}$

$$\overline{\mathcal{E}_{I,J}} \setminus \mathcal{E}_{I,J} = \{A \mid \forall X, \forall Y, \text{supp}(X) \subseteq I \wedge \text{supp}(Y) \subseteq J \wedge \|A - XY^\top\|^2 > 0\}$$

$$\bigcap \{A \mid \forall \epsilon > 0, \exists X, \exists Y, \text{supp}(X) \subseteq I \wedge \text{supp}(Y) \subseteq J \wedge \|A - XY^\top\|^2 < \epsilon\}$$

- Using *quantifier elimination algorithm*, we can decide the emptiness of the semi-algebraic set  $\overline{\mathcal{E}_{I,J}} \setminus \mathcal{E}_{I,J}$ .  
(S. Basu, R. Pollack, M-F Roy, Algorithms in Real Algebraic Geometry)
- The complexity of the algorithm is  $O(4^{C^k})$ , where:

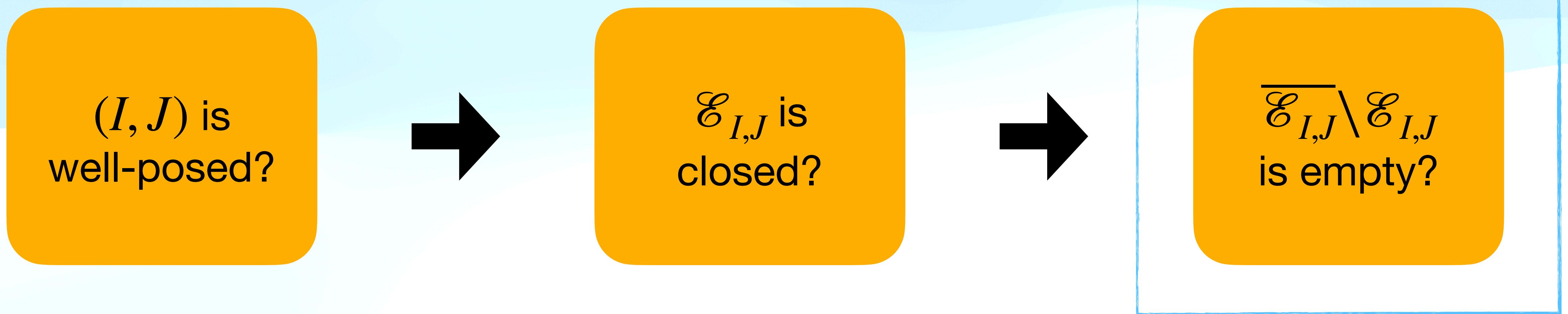
- $C$  is a universal constant.
- $k = mn + 2(|I_1| + |I_2|) + 1$



Size of the matrix product

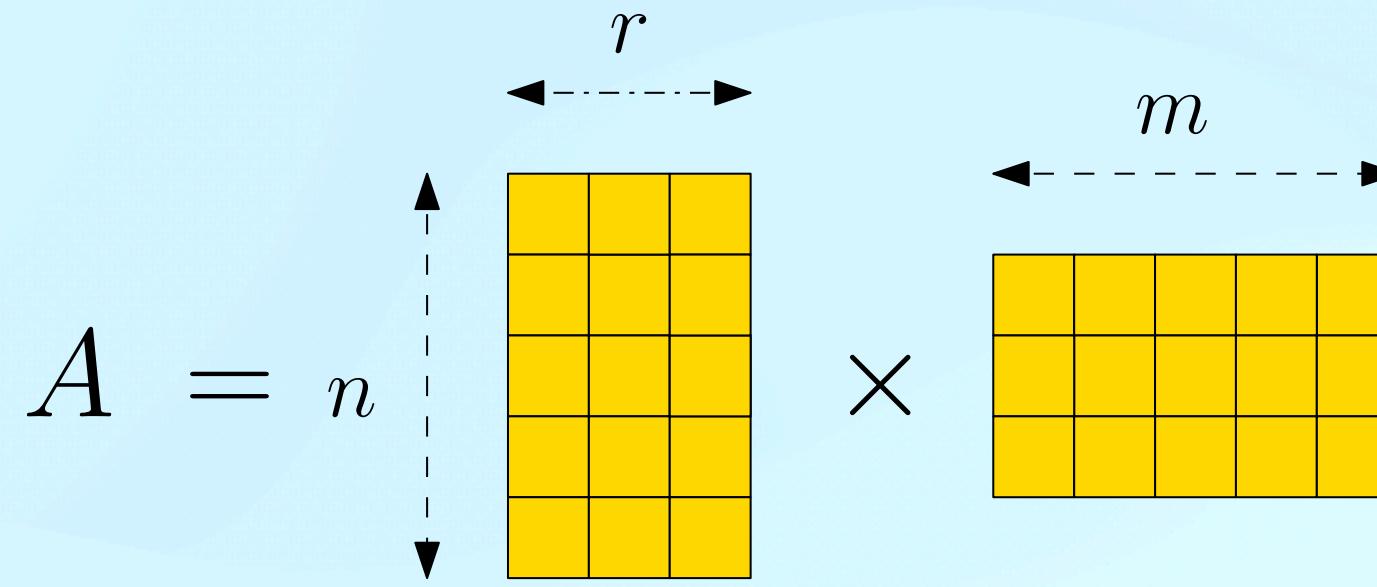
Size of the supports

# Recap of the algorithm



# How does the algorithm work in practice?

## Low rank approximation



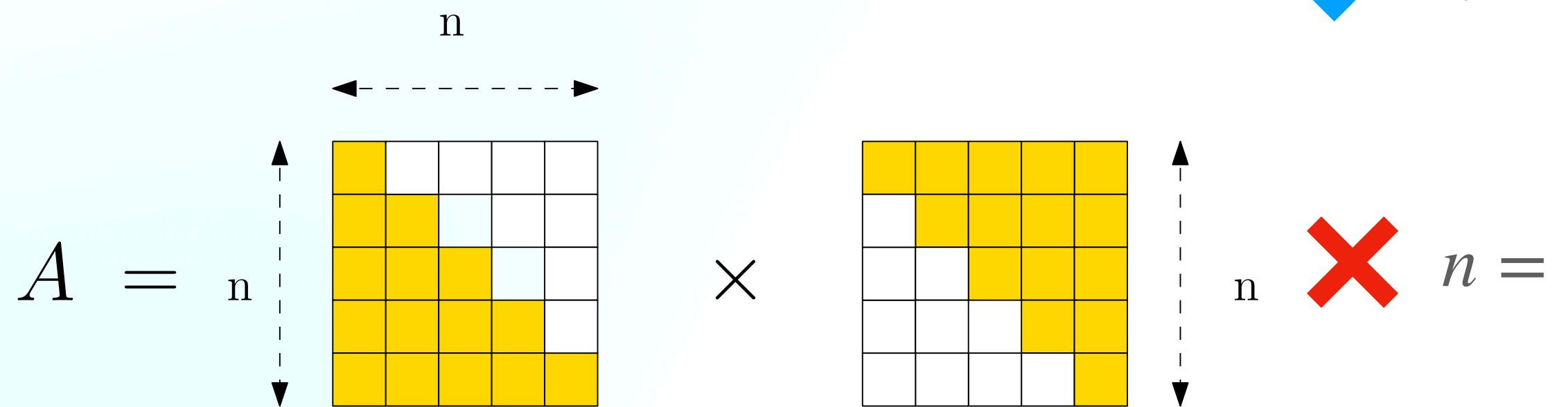
✓  $m = n = r = 2$

```
(base) tung@dhcp-67-169 quantifiersElimination % python fullsupport.py
Running time: 0.0036940574645996094
True
```

✗  $m = n = 3, r = 2$

```
(base) tung@dhcp-67-169 quantifiersElimination % python fullsupport.py
^CRunning time: 2112.0239312648773
None
```

## LU decomposition



✓  $n = 2$

```
(base) tung@dhcp-67-169 quantifiersElimination % python LU2x2.py
Running time: 0.013816118240356445
False
```

✗  $n = 3$

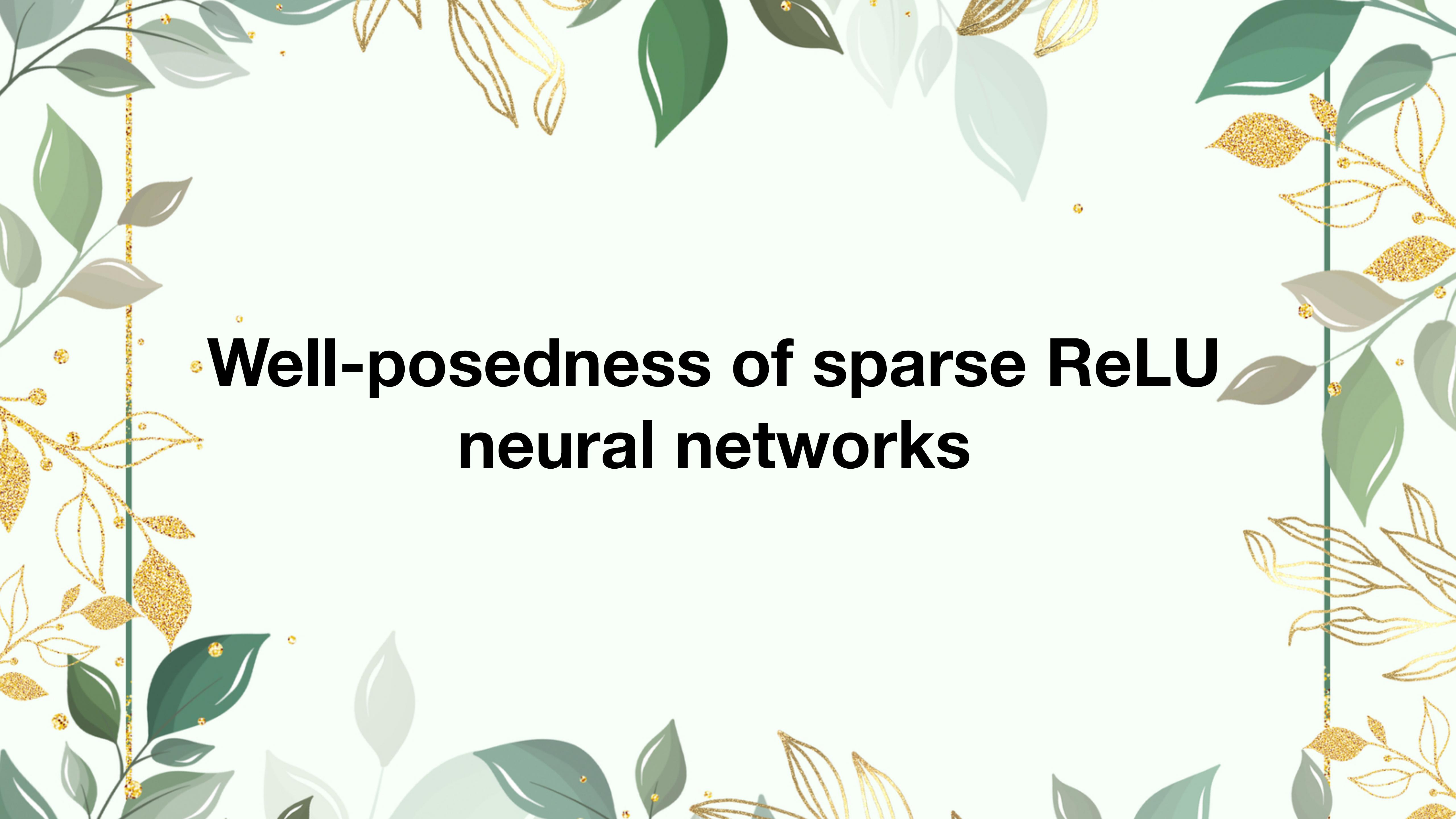
```
(base) tung@dhcp-67-169 quantifiersElimination % python LU3x3.py
^CRunning time: 3202.279525756836
None
```

# Perspectives

- ✓ Given support constraint  $(I, J)$ , its well-posedness is ***decidable***.
- ✓ The algorithm generalises easily to multi-factors ( $L > 2$ ).

But,

- ✗ The complexity for the algorithm is doubly exponential.
- ✗ Using quantifier elimination algorithm (a general algorithm) does not provide any insight properties of  $\mathcal{E}_{I,J}$ .



# **Well-posedness of sparse ReLU neural networks**

# Fixed support sparse ReLU neural networks

Given data set  $\mathcal{D} := (X, Y)$ , solve:

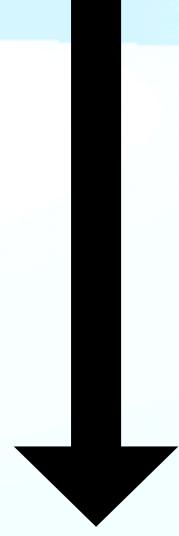
**GENERAL**

$$\min_{W^{(j)}, b^{(j)}}$$

$$\|Y - W^{(L)}\sigma(\dots\sigma(W^{(1)}X + b^{(1)}) + \dots) + b^{(L)}\|_F^2$$

subject to:

$$W^{(j)} \in \mathcal{E}_j, \forall j \in \{1, \dots, L\}$$



**FIXED SUPPORT**

$$\min_{W^{(j)}, b^{(j)}}$$

$$\|Y - W^{(L)}\sigma(\dots\sigma(W^{(1)}X + b^{(1)}) + \dots) + b^{(L)}\|_F^2$$

subject to:

$$\text{supp}(W^{(j)}) \in I_j, \forall j \in \{1, \dots, L\}$$

# DÉJÀ VU: closedness vs well-posedness



Given a support constraint  $(I_1, \dots, I_L)$ , is the training problem well-posed (i.e., **for all data set  $\mathcal{D}$** , optimal solutions always exist)?

The support constraint  $(I_1, \dots, I_L)$  make training problem **well-posed** if and only if for all input sets  $X$ , the image  $W^{(L)}\sigma(\dots\sigma(W^{(1)}X + b^{(1)}) + \dots) + b^{(L)}$  is **closed**.



# Sufficient condition for well-posedness

## THEOREM

For **two-layer** neural networks ( $L = 2$ ) with **output dimension** equal to **one**, any support constraint makes the training problem **well-posed**.

## COROLLARY

For **two-layer** neural networks ( $L = 2$ ) with **output dimension** equal to **one**, constraints  $\mathcal{E}_j := \{X \mid \|X\|_0 \leq k_j\}, j = 1, 2$  makes the training problem well-posed.

# Necessary condition for well-posedness

## THEOREM

For **two-layer** neural networks ( $L = 2$ ) with support constraint  $(I, J)$ , the **well-posedness** of training problem implies the **closedness** of  $\mathcal{E}_{I,J}$ .



this is decidable



## THEOREM

For fixed support neural networks with support constraint  $(I_1, \dots, I_L)$ , the **well-posedness** of training problem implies the **closedness** of  $\mathcal{E}_{I_1, \dots, I_L}$ .

# Necessary condition for well-posedness

## THEOREM

For **two-layer** neural networks ( $L = 2$ ) with support constraint  $(I, J)$ , the **well-posedness** of training problem implies the **closedness** of  $\mathcal{E}_{I,J}$ .

The condition is just necessary because when there is **no constraint** on the support, the training problem is ill-posed for certain data set.

(L-H. Lim, M. Michalek, Y. Qi, Constructive Approximation 2019)

# Contribution and future works

## TAKE AWAY MESSAGE

- Ill-posedness of (FSMF) is decidable, not yet tractable.
- Link between sparse matrix factorization and sparse ReLU neural networks.

## POSSIBLE IMPROVEMENT?

- Better algorithms to decide the ill-posedness of (FSMF)
- When the problem is well-posed, is there polynomial algorithm for (FSMF)
- A full characterization of ill-posedness of sparse ReLU neural networks

[\*\*https://arxiv.org/abs/2306.02666\*\*](https://arxiv.org/abs/2306.02666)

**THANK YOU**