Exercise – Understanding the confidence interval (CI) using simulation

1. Aim of the exercise

The rationale behind a CI is based on the concept of repeated sampling from the population. However, in practical scenarios, we cannot repeatedly sample from the population, which makes the concept somewhat abstract and challenging to teach and learn. Consequently, students often struggle to interpret a CI. Through a simulation exercise, we can mimic the process of repeatedly sampling from the population, thereby concretely demonstrating what a CI represents.

2. Theory

Assume that the OLS estimator $\hat{\beta}_k$ follows a normal distribution with mean β_k and variance $\sigma_{\hat{\beta}_k}^2$:

$$\hat{\beta}_k \sim N \left[\beta_k, \sigma_{\hat{\beta}_k}^2 \right].$$

We can standardize $\hat{\beta}_k$ so that it has a standard normal distribution:

$$\hat{\beta}_k - \beta_k / \sigma_{\hat{\beta}_k} \sim N[0, 1]$$
.

 $\sigma_{\hat{\beta}_k}$ is an unobserved population parameter. Replace it with its unbiased estimator $s_{\hat{\beta}_k}$ which gives

$$\hat{\beta}_k - \beta_k / s_{\hat{\beta}_k} \sim t \left[n - K \right]$$

where n - K is the degrees of freedom of the t distribution. For a n - K equal to, for example, 999, we can state that

Prob
$$\left(-1.9623 < \hat{\beta}_k - \beta_k / s_{\hat{\beta}_k} < 1.9623\right) = 0.95.$$

The interpretation of this expression is that the probability that the random variable $\hat{\beta}_k - \beta_k / s_{\hat{\beta}_k}$ is between the stated boundaries is 95%. The stated probability is equivalent to

$$\text{Prob}\left(\hat{\beta}_k - 1.9657s_{\hat{\beta}_k} < \beta_k < \hat{\beta}_k + 1.9657s_{\hat{\beta}_k}\right) = 0.95.$$

At this instance the interpretation changes. The interpretation is for the unique nonrandom population parameter β_k . The end points of the interval

$$\left[\hat{\beta}_{k} - 1.9657s_{\hat{\beta}_{k}}, \hat{\beta}_{k} + 1.9657s_{\hat{\beta}_{k}}\right]$$

are random! The interval does not take one value but a different value from one sample to another. Suppose that we randomly collect an infinite number of samples (repeated sampling, or sampling in the long run), and construct a particular interval using each sample. The stated probability tells that 95 percent of these intervals will include β_k . This is where the probabilistic interpretation comes from. Given the single sample data at hand, we could calculate only one interval estimate. Once we construct this interval using the sample data at hand, the end points of the interval are not random anymore. Therefore, the probability that β_k is in this interval is either 0 or 1. Hence, it is incorrect to say that the probability that β_k is in the

interval we estimate is 95%. The interval we computed is just an estimate of one of those intervals that result from repeated sampling that contain β_k 95 percent of the times. The correct interpretation is the following: In repeated sampling, the probability that intervals like the one we estimate will contain the true β_k is 95%. The probability that this particular non-random interval includes the true β_k is either 0 or 1.

The CI is also called the "interval estimate" because it provides a range of the possible estimates of the population coefficient, whereas, for example, the OLS estimate is a point estimate of the population coefficient. The CI can be seen as a possible measure of the precision of the point estimate. That is, once we obtain a point estimate, for example $\hat{\beta}_k$, we ask how precise we expect this estimate to be.

A test and a CI are closely related. We reject a null of the t test that $\beta_k = 0$ because it lies outside the CI we calculate.

- 3. Coefficient and standard error estimates (SEE) from repeated samples
- 3.1. Clear the memory

Clear the memory from possible calculations from an earlier session.

```
% 3.1. Clear the memory clear;
```

3.2. Set the sample size

Assume that the model of interest is a simple linear regression model that contains an independent variable and, for simplicity, no constant term. We assume that there are N_obs observations available for this independent variable and for the dependent variable of the regression. In our simulation exercise below, we will draw samples from the population. Setting the number of observations to N_obs means that we keep the sample size fixed at N_obs each time we draw a sample from the population.

```
\frac{14}{15} % 3.2. Set the sample size N_obs = 1000;
```

3.3. Generate data for the independent variable

The code presented in this section draws N_{obs} theoretical observations from the uniform distribution to create an artificial dataset for the independent variable X. In our simulation exercise below, we will generate new data for y repeatedly. Here we generate data for X and we will keep it fixed in the simulation exercise. That is, as we will be taking repeated samples from the population, we will be doing this only for y and not for X. This means that we will keep the random data of X fixed in repeated sampling. Keeping X fixed in repeated sampling is indeed an assumption we make. Note, however, that this is the classical assumption we make while we derive the basic econometric theory. That is, we condition on the values of a regressor while we make econometric derivations. We do this because it simplifies the derivations, and the basics of econometric theory does not change.

```
_{7} \mid% 3.3. Generate data for the only independent variable
```

```
18 | X = random('Uniform',-1,1,[N_obs 1]);
```

3.4. Define the number of coefficients to be estimated

Define the number of coefficients to be estimated and assign it to the scalar array N_par. We will use N_par in few occasions in our code below.

```
% 3.4. Define the number of coefficients to be estimated N_par = size(X,2);
```

3.5. Set a (hypothesized) value for the population coefficient

Assume that the population coefficient of the only independent variable β is equal to 0.5. This is an assumption of the simulation exercise below. We need this to generate values for y. In principle we do not observe β .

```
^{23} \% 3.5. Set a (hypothesized) value for the population coefficient ^{24} B_{-}true = 0.5;
```

3.6. Set the number of simulations

In this exercise a simulation refers to taking a random sample from the population. Since we want to take samples from the population repeatedly, we will be repeating the simulation multiple times. Here we define the number of simulations or samples.

```
\frac{26}{N_sim} = 300;
```

3.7. Preallocate a matrix for storing OLS estimates from all samples

Create an empty matrix that will store the OLS coefficient estimates of β . Since we will draw N_sim samples from the population, we will obtain N_sim coefficient estimates based on these samples. Since we have only one coefficient to estimate, that is since N_par is 1, the matrix in this case is in fact a column vector.

```
% 3.7. Preallocate a matrix for storing OLS estimates from all samples B_hat_sim = NaN(N_sim, N_par);
```

3.8. Preallocate a matrix for storing SSEs from repeated samples

Create an empty column vector that will store the N_sim standard error estimates of the OLS coefficient estimates of β from repeated samples.

```
% 3.8. Preallocate a matrix for storing SSEs from repeated samples
B_hat_SEE_sim = NaN(N_sim, N_par);
```

3.9. Create the sampling distribution of OLS estimates and their SSEs

Here we draw N_sim random samples from the population as if we could do this in reality. Each sample leads to an estimate of β . This leads to a distribution of the OLS estimate, referred to as the sampling distribution of the OLS estimate of β .

```
3.9. Create the sampling distribution of OLS estimates and their SSEs
35
  for i = 1:N_sim
36
       % Generate new error for each sample
37
       u = random('Normal',0,1,[N_obs 1]);
38
        Generate values for the dependent variable
39
        = X*B_true+u; % The data generating process (DGP)
40
       % Obtain OLS statistics using the external function
41
       LSS = exercisefunctionlss(y,X);
42
       \% Store OLS estimates and their SSEs
43
       B_hat_sim(i,1) = LSS.B_hat(1,1); % B_hat is a random variable
44
       B_{hat\_SEE\_sim(i,1)} = LSS.B_{hat\_SEE(1,1)};
45
  end
46
```

4. Construct random intervals (RIs) from repeated samples from the population

We want to construct RIs. This requires to specify the significance level as 5%. Calculate the degrees of freedom given the number of observations and parameters to estimate. Using these, calculate the critical value from the t distribution. Next, construct the confidence intervals. Note that the dimension of RIs is N_sim by 2. That is, there are N_sim intervals resulting from N_sim samples. 2 is for the lower and upper bounds of the intervals. In a real life scenario, however, we typically have only one sample and hence we can estimate only one CI. In line 64 we extract such a CI from RIs we estimated.

```
%% 4. Construct RIs from repeated samples from the population

49

50 % 4.1. Define the significance level
alpha = 0.05; % For 95% CI. Change to 0.10 for 90% CI.

52

53 % 4.2. Calculate the degrees of freedom for the t distribution
54 df = N_obs-N_par;
55
```

```
% 4.3. Calculate the critical value from the t distribution
t_c = tinv(1-alpha/2,df);

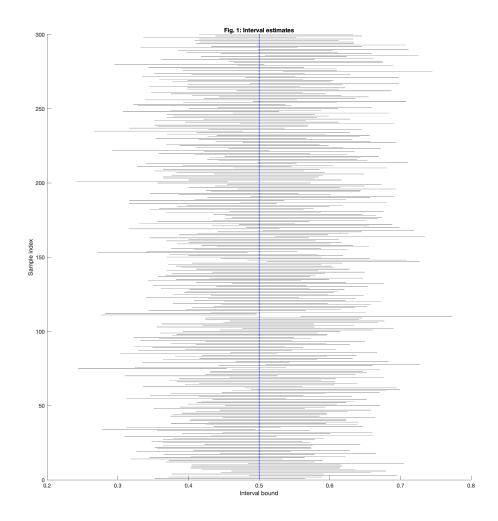
% 4.4. Construct the RIs for B_true using its estimates from all
% samples
RIs = [B_hat_sim-t_c*B_hat_SEE_sim,B_hat_sim+t_c*B_hat_SEE_sim];

% 4.5. Construct the CI for B_true when there is one sample available
CI = RIs(1,:);
```

5. Plot the RIs from all samples and the population coefficient

Here we plot the RIs we have estimated using the samples we have drawn from the population. We also plot the population coefficient.

```
\%\% 5. Plot the RIs from all samples and the population coefficient
66
  \% 5.1. Adjust the plot position and size for better visualization
67
   set(gcf, 'Position', [100,100,1000,1000]); % [left, bottom, width, height]
68
69
   \% 5.2. Draw the plot
70
  hold on
71
  for i = 1:N_sim
72
       plot(RIs(i,:),[i,i],'k-','LineWidth',0.5);
73
       plot(B_true,i,'bo','MarkerSize',1.5,'MarkerFaceColor','b');
74
   end
75
   title('Interval estimates');
76
  xlabel('Interval bound');
  ylabel('Sample index');
78
  hold off
79
```



6. Interpret the CI

Figure 1 shows all the RIs we estimated using repeated sampling, and the population coefficient. We can calculate the proportion of the times the population coefficient falls into these intervals. In line 84 we create a dummy variable that takes a value of 1 if the population coefficient falls within the intervals. In line 87 we calculate the proportion of the times the population coefficient falls into the intervals constructed using the repeated samples. The proportion we obtain is approximately 95%. It is not exactly 95% due to simulation noise.

We can now interpret the CI. In repeated sampling, the probability that intervals, like the one estimated using only one sample in line 64, contains the population coefficient β is 95%. The CI we have is called "confidence" interval because we use this one interval to be "confident" about the population coefficient with some probability.

```
%% 6. Interpret the CI

% 6.1. Create a dummy indicating if B_true is within the RIs

B_true_is_within_RIs = B_true > RIs(:,1) & B_true < RIs(:,2);
```

```
% 6.2. Calculate the proportion of times B_true is within the RIs
Proportion_B_true_is_within_RIs = mean(B_true_is_within_RIs); % App.

% 0.95
```

7. Final notes

This file is prepared and copyrighted by Renata-Maria Istrătescu and Tunga Kantarcı. This file and the accompanying MATLAB files are available on GitHub. They can be accessed via this link.