Curriculum Vitae Thanh-Tung Ngo

# PERSONAL INFORMATION

## **Thanh-Tung Ngo**



(+84) 0386560691



https://www.linkedin.com/in/tung-ngo-hust/

tung.ngothanh.hust@gmail.com https://github.com/tungngovn

#### **EDUCATION**

10/2020 - 08/2022

## M. Sc. in Mechatronics Engineering

Hanoi University of Science and Technology (HUST), Hanoi, Vietnam

Thesis: Landmark detection and localization solution for GraphSLAM in autonomous vehicles

GPA: 3.86/4.0

09/2015 - 08/2020

## **Degree of Engineer in Mechatronics Engineering**

(Highest entrance score of the Talented Program in Mechatronics – top 1.5% university)

Hanoi University of Science and Technology, Hanoi, Vietnam

GPA: 3.25/4.0

#### **EXPERIENCE**

09/2022 - present

## College of Engineering and Computer Science, VinUniversity

## **Teaching Assistant**

Courses: Intelligent Physical Systems, Mechatronics, Mechanical Synthesis, Mechanics of Engineering Materials, Introductory Fluid Mechanics, Thermodynamics

03/2022 - 08/2022

## VinUni-Illinois Smart Health Center, VinUniversity

PI: Dr. Hieu Pham, Prof. Minh Do

#### **Research Assistant**

Project: Automatic Cranial Implant Design with Artificial Intelligence

• Proposed a method using Reinforcement Learning to design implants for varied skull defects.

05/2018 - 08/2022

### **Autonomous Intelligent Robotics Lab, HUST**

PI: Dr-Ing. Xuan-Ha Nguyen

## **Research Assistant**

**Project**: Deep Learning in Computer Vision and GraphSLAM for long-term autonomous vehicle applications Collaborator: **Autonomous Intelligent Systems Lab, University of Freiburg, Germany** 

- Researched probabilistic navigation algorithms: GMapping, EKFSLAM, and GraphSLAM;
- Finetuned object detection and instance segmentation deep learning models (YOLOv4, YOLACT++) with Cityscapes dataset for the feature extraction task;
- Customized stereo depth estimation models (AANet+, LEAStereo) with ApolloScape dataset;
- Proposed a lightweight traffic sign perception method combining object detection and depth estimation, which increased the accuracy and reduced the computational cost.

**Project**: R&D of SLAM algorithms for autonomous intelligent robots in logistics and services

- Designed software and hardware systems of an intelligent service mobile robot (AIR-HUST);
- Developed robot applications based on ROS: navigation, GUI, and speech recognition;
- Proposed a multi-layer sensor fusion (IR, LIDAR, sonar) SLAM solution;
- Implemented the proposed solution on the developed robot.

05/2018 - 07/2020

#### CMC Institute of Science and Technology, CMC Corporation, Hanoi, Vietnam

PI: Dr-Ing. Xuan-Ha Nguyen

#### **R&D Intern**

Project: CMC Intelligent Service Robot

- Developed a reception robot (C-Bot) based on TurtleBot2;
- Researched autonomous navigation algorithms: Gmapping, AMCL, and DWA;

Curriculum Vitae Thanh-Tung Ngo

#### **PUBLICATIONS**

[1] H. X. Nguyen, T. T. Ngo, and A. D. Nguyen, "Development of real-time traffic-object and traffic-sign detection models applied for autonomous intelligent vehicles," J. Sci. Technol. Smart Syst. Devices, vol. 32, pp. 17-24, Jan. 2022, doi: 10.51316/jst.155.ssad.2022.32.1.3.

- [2] H. X. Nguyen, T. T. Ngo, and H. V. Nguyen, "Development of an autonomous intelligent mobile robot based on Al and SLAM technology," in *Proc. Int. Conf. Intell. Syst. Netw. 2021*, pp. 319-326, doi: 10.1007/978-981-16-2094-2\_40.
- [3] H. X. Nguyen, H. V. Nguyen, T. T. Ngo, and A. D. Nguyen, "Improvement of Control Algorithm for mobile robot using multi-layer sensor fusion," Vietnam J. Sci. Technol., vol. 59, no. 1, pp. 110-119, Feb. 2021, doi: 10.15625/2525-2518/59/0/15301.
- [4] H. X. Nguyen, H. V. Nguyen, and T. T. Ngo, "A new landmark detection approach for SLAM algorithm applied in mobile robot," J. Sci. Technol. Tech. Univ., vol. 146, pp. 31-36, Nov. 2020, doi: 10.51316/30.7.6.
- [5] H. X. Nguyen, T. T. Ngo, T. V. Nguyen, A. D. Pham, and T. D. Nguyen, "An efficient approach for traffic sign detection, classification, and localization applied for autonomous intelligent vehicles," in *J. Mordem Phys. B* (submitted).

#### **HONORS AND AWARDS**

2021 Nominee of VEF2.0 (top 30) and Vingroup Scholarship for Overseas Study (top 20)

2020 **Domestic Master Scholarship** (full tuition fee and monthly stipend)

Vingroup Innovation Foundation, Vingroup Big Data Institute

2020 1st prize in Student Research Competition

Hanoi University of Science and Technology

2017 4<sup>th</sup> prize in the 2017 Blitz Research Competition

Vietnam Summer School of Science, Rencontres du Vietnam

2016 – 2019 Student with five good merits (morality, studying, physical training, volunteer, integration)

Vietnam National Union of Students of Hanoi University of Science and Technology

2015 – 2017 FYT Scholarship for Outstanding Students (top 25 nationwide)

FPT Center for Young Talents, FPT Corporation

# EXTRACURRICULAR ACTIVITIES

07/2019 Representative of Vietnam - NUS Enterprise Summer Program in Entrepreneurship, National University of Singapore, Singapore

- Took part in an intensive two-week introduction to the core concepts of entrepreneurship and the startup ecosystem of Southeast Asia, along with 180 students from 22 countries;
- Worked in a 6-member team to propose startup idea: "Online platform for startup mentoring".

09/2018; 03/2019 Representative of HUST – TFI Specialists' Community Action and Leadership Exchange (TFI SCALE), Temasek Polytechnic, Singapore & HUST, Vietnam

- Participated in a cross-cultural and leadership training program for 3 weeks in Singapore and 2 weeks in Vietnam:
- Proposed IT idea: "A mobile app to support intellectually disabled people".

12/2015 – 12/2017 Member of Management Board – FPT Center for Young Talents, FPT Corporation, Vietnam

• Organized seminars and networking activities for elite undergraduate students in Hanoi.

09/2015 – 08/2017 President – GSTT Group Hanoi, Hanoi, Vietnam

• Organized optional-fee Math and Physics preparation courses for candidates of the Talented Program at HUST and supported high school students in academic orientation.

#### **SKILLS**

Language IELTS 7.0 (R 8.0, L 7.5, S 6.0, W 6.5)

Programming languages Python, C/C++, Matlab, XML

Robotics ROS | 2D LiDAR, Embedded computer (Raspberry Pi) deployment

Frameworks Pytorch, Scikit-Learn, Numpy, WandB, Gym | Vim | Git | Latex