On Device Machine Learning using Raspberry Pi

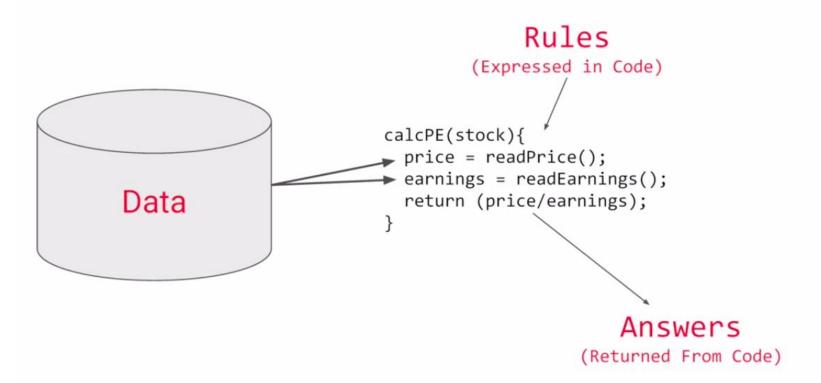
Tun Tun Win

Disclaimer

All images and Contents are from Coursera, Introduction to Tensorflow for Artificial Intelligence, Machine Learning, Instructurer Laurence Maroney, Google Al and TensorFlow

Part I

Hello World!



```
if (ball.collide(brick)){
    removeBrick();
   ball.dx=-1*(ball.dx);
   ball.dy=-1*(ball.dy);
```







Activity Recognition



```
if(speed<4){
    status=WALKING;
}</pre>
```



```
if(speed<4){
    status=WALKING;
} else {
    status=RUNNING;
}</pre>
```



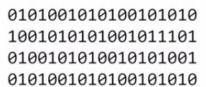
```
if(speed<4){
    status=WALKING;
} else if(speed<12){
    status=RUNNING;
} else {
    status=BIKING;
}</pre>
```



```
// Oh crap
```

Activity Recognition





Label = WALKING



Label = RUNNING



Label = BIKING



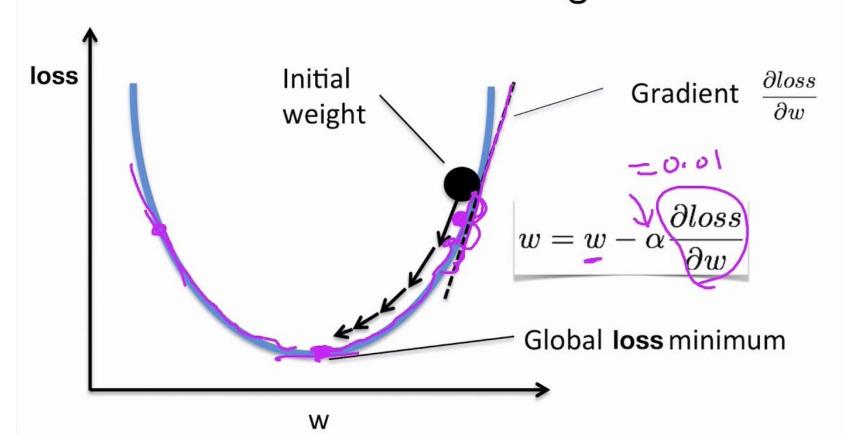
1111111111010011101 00111110101111110101 010111010101010101110 1010101010100111110

Label = GOLFING
(Sort of)

$$X = -1$$
, 0, 1, 2, 3, 4
 $Y = -3$, -1, 1, 3, 5, 7

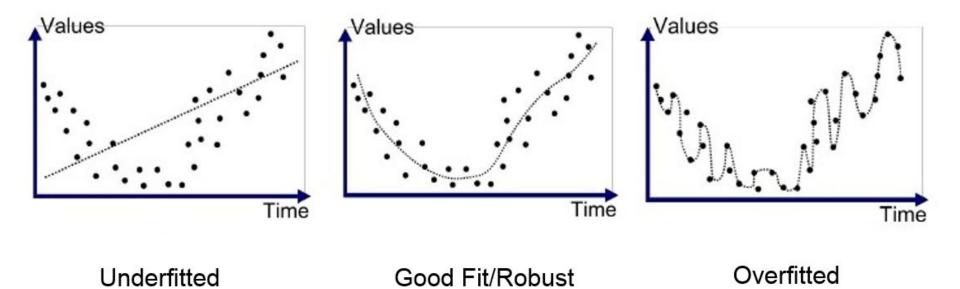
```
model = keras.Sequential([keras.layers.Dense(units=1, input_shape=[1])])
model.compile(optimizer='sgd', loss='mean_squared_error')
xs = np.array([-1.0, 0.0, 1.0, 2.0, 3.0, 4.0], dtype=float)
ys = np.array([-3.0, -1.0, 1.0, 3.0, 5.0, 7.0], dtype=float)
model.fit(xs, ys, epochs=500)
print(model.predict([10.0]))
```

Gradient descent algorithm



$MSE = \frac{1}{n} \Sigma \left(y - \widehat{y} \right)^{2}$

The square of the difference between actual and predicted



Part II

Computer Vision











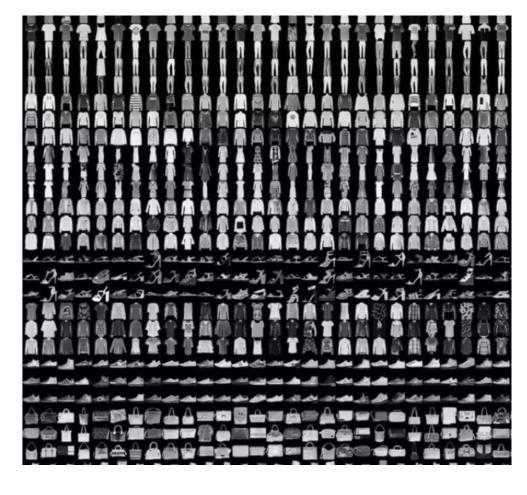






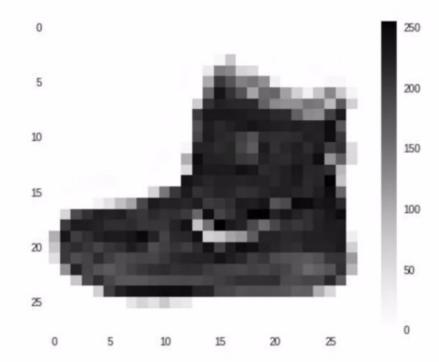
Fashion MNIST

- 70k Images
- 10 Categories
- Images are 28x28
- Can train a neural net!



Fashion MNIST

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- 10 Categories
- Images are 28x28
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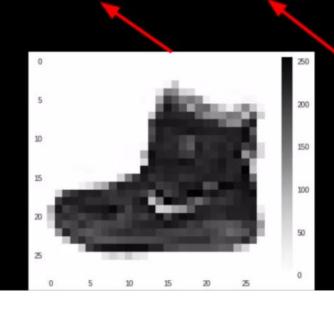


```
fashion_mnist = keras.datasets.fashion_mnist
(train_images, train_labels), (test_images, test_labels) = fashion_mnist.load_data()
```

```
Train = Test =
```

```
import tensorflow as tf
from tensorflow import keras
```

```
fashion_mnist = keras.datasets.fashion_mnist
(train_images, train_labels), (test_images, test_labels) = fashion_mnist.load_data()
```



09 = ankle boot; 踝靴; アンクルブーツ; Bróg rúitín

```
model = keras.Sequential([
    keras.layers.Flatten(input_shape=(28, 28)),
    keras.layers.Dense(128, activation=tf.nn.relu),
    keras.layers.Dense(10, activation=tf.nn.softmax)
])
```

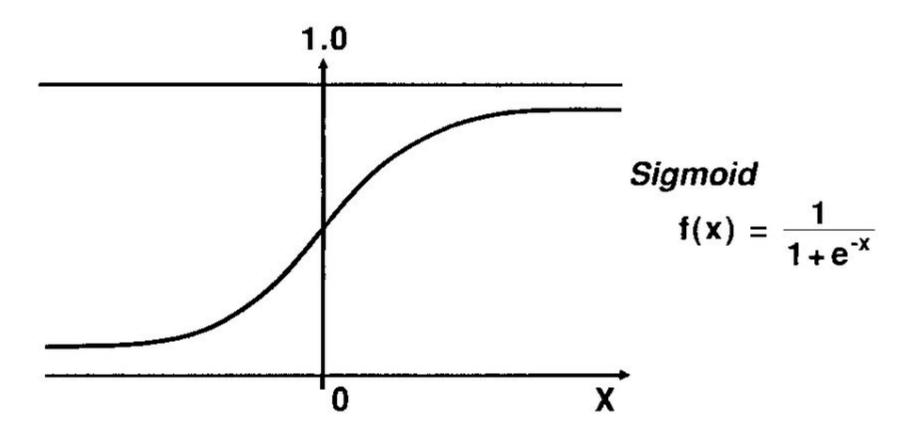
W0*X0+W1*X1+W2*X2+.....+WN*XN = 9----> Label

Confused???

Optimizer
Loss Function
Activation Function

Anythings Else??

Activation Function



Machine Learning Week 3

Andrew Ng

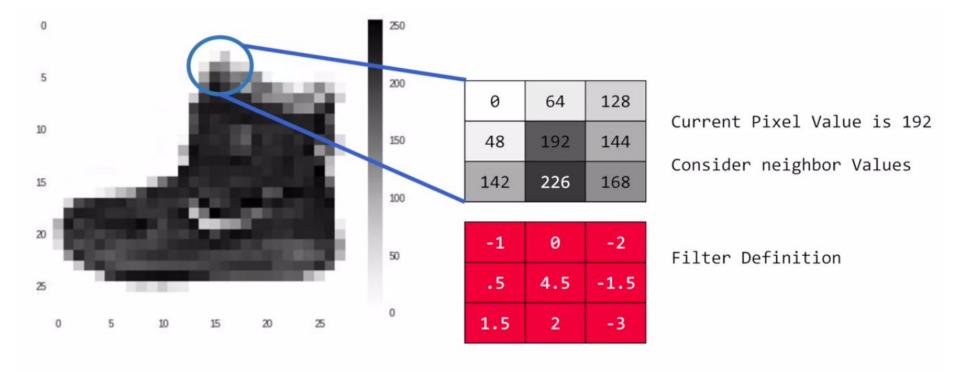
$$H_p(q) = -\frac{1}{N} \sum_{i=1}^{N} y_i \cdot log(p(y_i)) + (1 - y_i) \cdot log(1 - p(y_i))$$

Binary Cross-Entropy / Log Loss

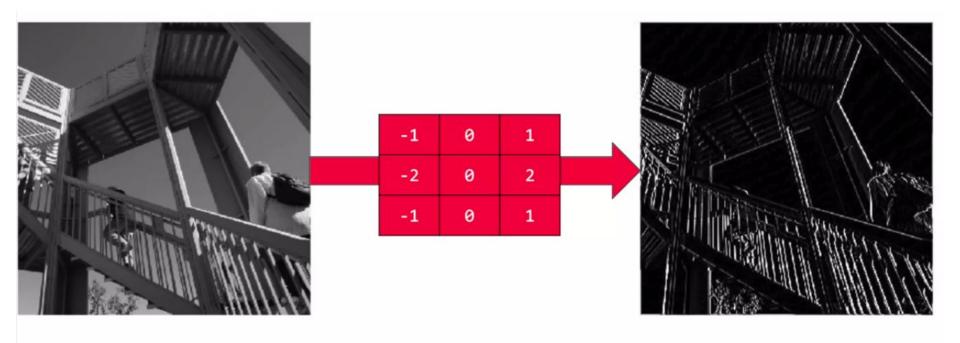
Part III

Convolutional Neural Network

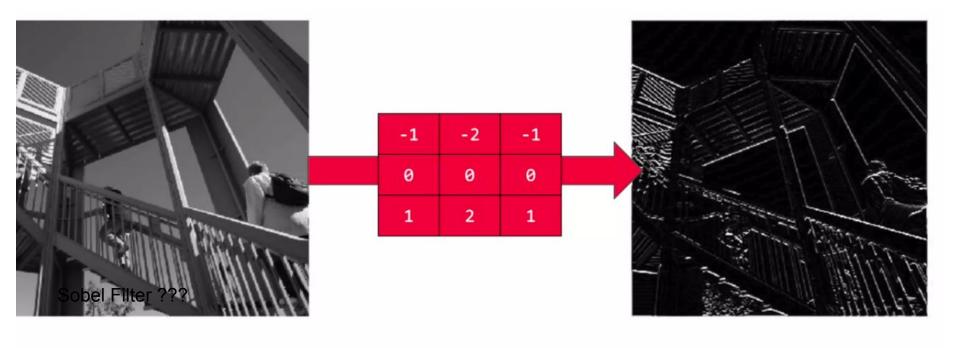
Convolution



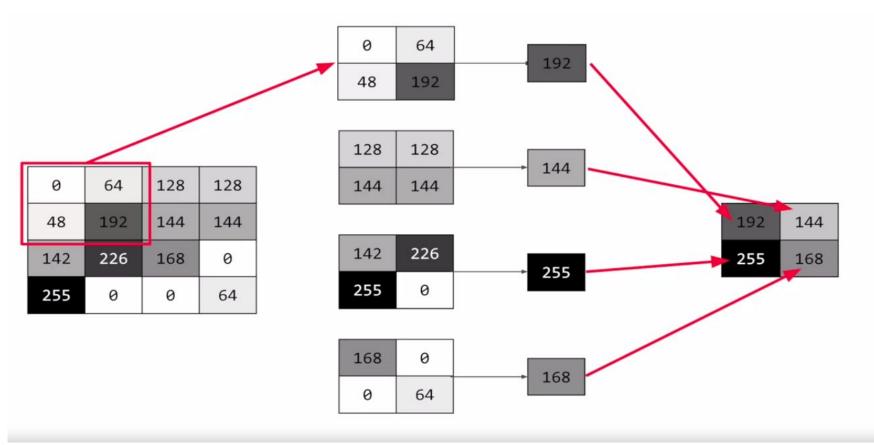
Convolution



Convolution



Pooling

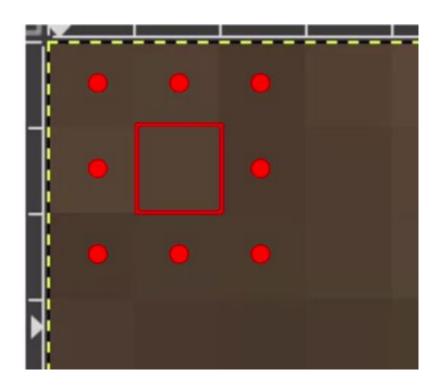


Reducing the size

```
model = tf.keras.models.Sequential(
  tf.keras.layers.Conv2D(64, (3,3), activation='relu',
                         input_shape=(28, 28, 1)),
  tf.keras.layers.MaxPooling2D(2, 2),
  tf.keras.layers.Conv2D(64, (3,3), activation='relu'),
  tf.keras.layers.MaxPooling2D(2,2),
  tf.keras.layers.Flatten(),
  tf.keras.layers.Dense(128, activation='relu'),
  tf.keras.layers.Dense(10, activation='softmax')
```

model.summary()

Layer (type)	Output		Param #
conv2d_12 (Conv2D)		26, 26, 64)	640
max_pooling2d_12 (MaxPooling	(None,	13, 13, 64)	0
conv2d_13 (Conv2D)	(None,	11, 11, 64)	36928
max_pooling2d_13 (MaxPooling	(None,	5, 5, 64)	0
flatten_5 (Flatten)	(None,	1600)	0
dense_10 (Dense)	(None,	128)	204928
dense_11 (Dense)	(None,	10) =========	1290 ======



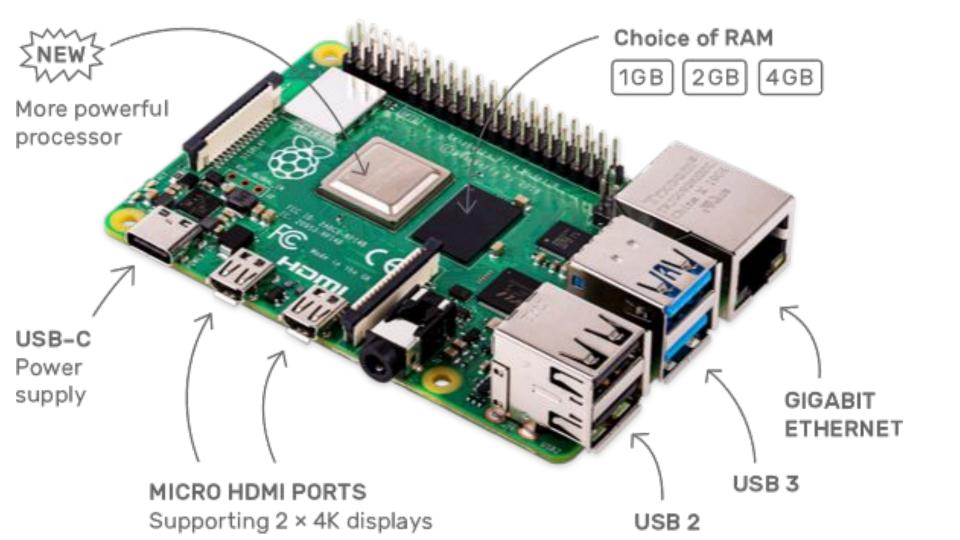
X-2 Y-2 in output

28x28, 64 filters,---> 26x26,64 filters

Original images are convolved with 64 filters, so we got 64 different images

Part IV

Raspberry Pi



sudo apt install libopenblas-dev libblas-dev m4 cmake cython python3-dev
python3-yaml python3-setuptools python3-wheel python3-pillow
python3-numpy

sudo apt install libatlas3-base

sudo pip3 install numpy

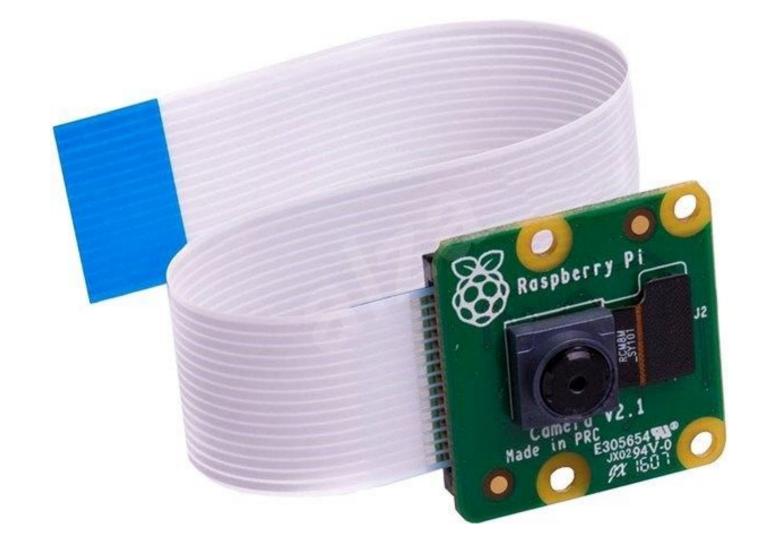
python3 -m pip install Pillow==6.1

pip3 install torch-1.3.0a0+deadc27-cp37-cp37m-linux_armv7l.whl

pip3 install torchvision-0.4.0a0+d31eafa-cp37-cp37m-linux_armv71.whl

pip3 install fastai --no-deps

- Quad Core 1.2GHz Broadcom BCM2837 64bit CPU
- 1GB RAM
- BCM43438 wireless LAN and Bluetooth Low Energy (BLE) on board
- 100 Base Ethernet
- 40-pin extended GPIO
- 4 USB 2 ports
- 4 Pole stereo output and composite video port
- Full size HDMI
- CSI camera port for connecting a Raspberry Pi camera
- DSI display port for connecting a Raspberry Pi touchscreen display
- Micro SD port for loading your operating system and storing data
- Upgraded switched Micro USB power source up to 2.5A



```
import os
from fastai.vision import *
from picamera import PiCamera
from time import sleep
path = os.getcwd()
import sys
if not sys.warnoptions:
    import warnings
    warnings.simplefilter("ignore")
print('Taking Photo')
camera = PiCamera()
camera.start_preview()
sleep(5)
camera.capture('im<mark>a</mark>ge.jpg')
camera.stop_preview()
print('Photo Taken and trying to predict it....')
image = open_image('image.jpg')
   Get Help
                Write Out Where Is
   Exit
                                          Cut Text
                Read File
                                                        Justify
                             Replace
```



File Edit Tabs Help

```
GNU nano 3.2
                               Desktop/test/testing.py
print('Taking Photo')
camera = PiCamera()
camera.start_preview()
sleep(5)
camera.capture('image.jpg')
camera.stop_preview()
print('Photo Taken and trying to predict it....')
image = open_image('image.jpg')
model = load_learner(path,'export.pkl')
print('Model Loaded')
predicted = model.predict(image)
print(predicted)
```

Thank you so much,

Faculty Members, Student Volunteers

Thanks Online Resources