

Modeling of a blow-down propulsion system

Course of Space Propulsion Academic Year 2023-2024

Lockheed Martini Group

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Contents

Co	ontents	1					
No	otation	ii					
No	otation	ii					
No	otation	iii					
1	Introduction and literature overview 1.1 Blow-down heritage	1 1 1 1					
2	Modeling of propulsion system 2.1 Input data	1 1 1 2					
3	Results analysis	4					
4	Nozzle losses	4					
5	5 Additive manufacturing influences						
6	6 Cooling analysis						
Bi	Bibliography						

Acronyms

SYM	Description of symbol	SYM	Description of symbol
SYM	Description of symbol	SYM	Description of symbol ^[1]

Symbols

а	[m/s]	Speed of sound	p	[Pa]	Pressure
\boldsymbol{A}	$[m^2]$	Area	Δp	[Pa]	Pressure loss / difference
\boldsymbol{B}	[-]	Blow-down ratio	Pr	[-]	Prandtl number
c_P	[J/kgK]	Specific heat at constant pressure	\dot{q} \dot{Q}	[W/m ²] [W]	Heat flux Heat transfer rate
c_T	[-]	Thrust coefficient	r	[-]	Recovery factor
c^*	[m/s]	Characteristic velocity	, R	[J/kgK]	Specific gas constant
C_d	[-]	Discharge coefficient	$\mathcal R$	[J/mol K]	Universal gas constant
d	[m]	Diameter	Re	[-]	Reynolds number
\boldsymbol{E}	[m/s]	Erosion rate	Re'	[-]	Modified Reynolds number
f	[-]	Darcy friction factor	t	[s]	Time
h	$[W/m^2 K]$	Convective heat transfer	Δt	[s]	Time step
п	[W/m-K]	coefficient	T	[K]	Temperature
H	[m]	Height	${\mathbb T}$	[N]	Thrust
i	[-]	First iteration index	и	[m/s]	Velocity
I_{sp}	[s]	Specific impulse	$oldsymbol{V}$	$[m^3]$	Volume
I_{tot}	[Ns]	Total impulse	ΔV	$[m^3]$	Volume change
j	[-]	Second iteration index	α_{AM}	[deg]	Deposition angle of AM
k	$[\mathrm{m}^{-1}]$	Curvature	0.		Convergent semi-aperture
K	[-]	Pressure loss coefficient	α_{con}	[deg]	angle
\boldsymbol{L}	[m]	Length			Injector pressure drop as
L^*	[m]	Characteristic length	β	[%]	percentage of initial
m	[kg]	Mass		r 3	combustion chamber pressure
ṁ	[m/s]	Mass flow rate	γ	[-]	Heat capacity ratio
M	[-]	Mach number	ε	[-]	Area ratio
\mathbb{M}	[kg/mol]	Molar mass	λ	[-]	Nozzle losses coefficient
N	[-]	Number of	μ	[Pas]	Dynamic viscosity
O/F	[-]	Oxidizer to fuel ratio	ho	$[kg/m^3]$	Density
$\overline{O/F}$	[-]	Mean O/F ratio	σ	[-]	Correction factor across boundary layer

Subscripts

aw Adiabatic wall

c Combustion chamber

cea From CEAM software

con Convergent

e Nozzle exit

eff Effective

f Final

fd Feeding lines

fu Fuel

i Initial

id Ideal

inj Injector

max Maximum

min Minimum

ox Oxidizer

p Propellants

pr Pressurizer gas

r Real

t Nozzle throat

tc Thrust chamber

tk Tank

tot Total

wg Gas side wall

1 Introduction and literature overview

- 1.1 Blow-down heritage
- 1.2 Additive manufacturing state of art
- 1.3 Analysis of losses
- 2 Modeling of propulsion system

Introduction

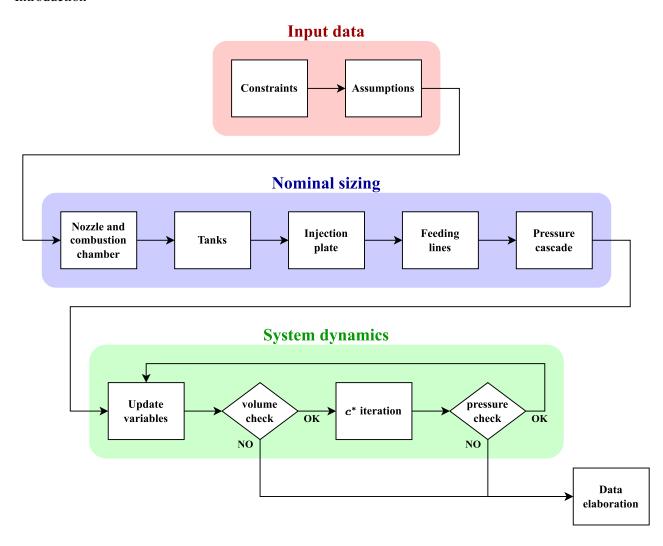


Figure 1: Flowchart of the simulation model

- 2.1 Input data
- 2.2 Nominal sizing

2.3 **System dynamics**

From the nominal sizing of the engine, it is necessary to simulate the real dynamics of the system in order to:

- retrieve the performance of the designed system in time;
- check the compliance of the system with the constraints;
- test other designs through iteration to select the best one based on the simulated data of interest.

For this reasons, a numerical method was implemented. An high level explanation for the functioning of the algorithm can be appreciated in Figure 2.

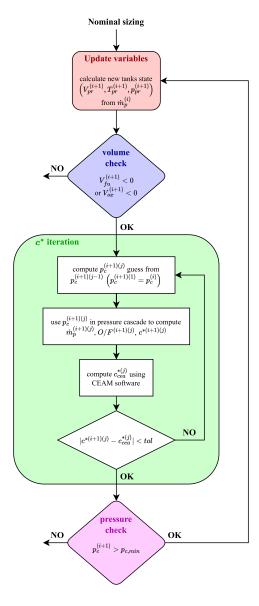


Figure 2: Flowchart of dynamics of the model

The first step of the time cycle is to update the state of the two tanks based on the previous iteration. Assuming a constant propellants flow rate during the time step Δt , the volume of the remaining liquid is decreased by a quantity $\Delta V^{(i+1)}$. Accordingly, the volume of the pressurizer will increase by the same amount.

$$\Delta V^{(i+1)} = \frac{\dot{m}_p^{(i)} \Delta t}{\rho_p}$$
 (1)

$$V_p^{(i+1)} = V_p^{(i)} - \Delta V^{(i+1)}$$
 (2)

$$V_p^{(i+1)} = V_p^{(i)} - \Delta V^{(i+1)} \tag{2}$$

$$V_{pr}^{(i+1)} = V_{pr}^{(i)} + \Delta V^{(i+1)} \tag{3}$$

From the change of volume, the new pressure and temperature of the pressurizer gas are computed assuming an adiabatic expansion in the tank:

$$p_{pr}^{(i+1)} = p_{pr}^{(i)} \left(\frac{V_{pr}^{(i)}}{V_{pr}^{(i+1)}} \right)^{\gamma_{pr}} \tag{4}$$

$$T_{pr}^{(i+1)} = T_{pr}^{(i)} \left(\frac{V_{pr}^{(i)}}{V_{pr}^{(i+1)}} \right)^{\gamma_{pr}-1}$$
 (5)

A check must be performed on the remaining volume of propellants in the tanks at current iteration: if the volume of fuel is negative it means that the combustion is over so the simulation stops (the same for oxidizer). If there is some more propellant to use, the iteration goes on with the calculation of the new chamber pressure. This step is complex because it introduces another cycle of iterations inside each time step. The mass flow rate of the propellants depends on the pressure cascade in the feeding lines, hence on the chamber pressure. These two variables are bounded and both unknown, but there's only one configuration that can match the boundary condition imposed by the critical condition in the throat, so the problem is well-posed.

From literature, the c^* of the chamber has the following expression:

$$c^* = \frac{p_c A_t}{\dot{m}_{fu} + \dot{m}_{ox}} \tag{6}$$

It correlates the chamber pressure with the propellants flow rate in the throat. Moreover, it only depends on the thermodynamics of the combustion process in the chamber, which changes over time due to the architecture of blow-down system. By imposing the critical conditions in the throat, it can be rewritten as:

$$c^* = \sqrt{\frac{\mathcal{R}}{M}} \frac{T_c}{\gamma} \left(\frac{\gamma + 1}{2}\right)^{\frac{\gamma + 1}{\gamma - 1}} \tag{7}$$

The system is coherent only if the two expressions give the same result. A system of equations could be created

and numerically solved to match both the pressure cascade and c^* . A reasonable initial guess for chamber pressure $p_c^{(i+1)(1)}$ is taken as the pressure at previous time step $p_c^{(i)}$. The next steps $p_c^{(i+1)(j)}$ will converge progressively towards the real current pressure $p_c^{(i+1)}$ (for increasing j). From $p_c^{(i+1)(j)}$ the $c^{*(i+1)(j)}$ is computed from the pressure cascade as described in Equation 6:

$$u_{fd,p}^{(i+1)(j)} = \sqrt{\frac{2(p_{pr}^{(i+1)} - p_c^{(i+1)(j)})}{\rho_p K_p}}$$
 (8)

$$m_p^{(i+1)(j)} = \rho_p A_{fd,p} u_{fd,p}^{(i+1)(j)}$$
(9)

$$O/F^{(i+1)(j)} = \frac{m_{ox}^{(i+1)(j)}}{m_{fu}^{(i+1)(j)}}$$
(10)

$$c^{*(i+1)(j)} = \frac{A_t p_c^{(i+1)(j)}}{\dot{m}_{fu}^{(i+1)(j)} + \dot{m}_{ox}^{(i+1)(j)}}$$
(11)

Equation 7 is solved directly using CEAM software, which takes as input $p_c^{(i+1)(j)}$ and $O/F^{(i+1)(j)}$ to return $c_{cea}^{*(j)}$. The two computed c^* are then compared: if their difference satisfies a certain tolerance, then the cycle stops and returns the new values for the current time step. Else, the inner cycle continues the refinement by guessing a new $p_c^{(i+1)(j+1)}$ from $p_c^{(i+1)(j)}$.

Finally, a check on the new combustion pressure $p_c^{(i+1)}$ is performed in order to stay above the minimum design pressure $p_{c,min}$, as mentioned in **REFERENCE**. Similarly to the previous check, if the pressure drops below the limit the simulation stops and returns the results, else it continues with the next time step.

The same general algorithm is used to refine the initial assumptions of O/F and B, which influence the nominal design of the whole engine (as described in subsection 2.2). In this case, the initial c^* value from design is assumed constant to reduce the computational burden, since the algorithm is applied over a wide range of combinations of O/F and B. This assumption is reasonable because the O/F (and as consequence the thermodynamics of the combustion) hardly varies during the whole burn, as can be noticed in **REFERENCE**.

- 3 Results analysis
- 4 Nozzle losses
- 5 Additive manufacturing influences
- 6 Cooling analysis

Bibliography

[1] Richard Grammier. *Overview of the Juno Mission to Jupiter*. Site: https://www.jpl.nasa.gov/missions/juno. 2006.