EEE302 CONTROL SYSTEMS PRE-LABORATORY REPORT

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ASSIGNMENT NUMBER : 5

OBJECTIVES OF THE LABORATORY ASSIGNMENT:

Objectives of this lab are learning parabolic, step, ramp input for the systems and calculating steady state errors and error constants by both hand and MATLAB m-file.

QUESTION-1

```
% For (a)
clc
clear all
syms s
G1 = 1/(3*s^2+4*s+1); % System Transfer Function
Kp = limit(G1,s,0) % when input is step, error constant, Kp is calculated
                  % form of steady state error, Ess for step input
Es = \frac{1}{(1+Kp)}
Kv = limit(s*G1,s,0) % when input is ramp, error constant, Kv is calculated
                 % form of steady state error, Ess for ramp input
Ka = limit(G1*s^2, s, 0) % when input is parabolic, error constant, Kp is calculated
Ep = 1/(Ka)
                % form of steady state error, Ess for step parabolic
% Command Window
Kp = 1
Es = 1/2
Kv = 0
Er = Inf
Ka = 0
Ep = Inf
```

```
% For (b)
clc
clear all
syms s
G2 = (s+1)*(s+7)/((s+2)*(s+5)); % System Transfer Function
Kp = limit(G2, s, 0) % when input is step, error constant, Kp is calculated
Es = \frac{1}{(1+Kp)}
                 % form of steady state error, Ess for step input
Kv = limit(s*G2,s,0) % when input is ramp, error constant, Kv is calculated
Er = 1/(Kv)
                % form of steady state error, Ess for ramp input
Ka = limit(G2*s^2, s, 0) % when input is parabolic, error constant, Kp is calculated
Ep = 1/(Ka)
              % form of steady state error, Ess for step parabolic
% Command Window
Kp = 7/10
Es = 10/17
Kv = 0
Er = Inf
Ka = 0
Ep = Inf
```

```
% For (c)
clc
clear all
syms s
G3 = (s^2+12*s+35)/(s^4+5*s^3+4*s^2); % System Transfer Function
Kp = limit(G3,s,0) % when input is step, error constant, Kp is calculated
                % form of steady state error, Ess for step input
Es = \frac{1}{(1+Kp)}
Kv = limit(s*G3,s,0) % when input is ramp, error constant, Kv is calculated
             % form of steady state error, Ess for ramp input
Ka = limit(G3*s^2,s,0) % when input is parabolic, error constant, Kp is calculated
             % form of steady state error, Ess for step parabolic
Ep = 1/(Ka)
% Command Window
Kp = Inf
Es = 0
Kv = Inf
Er = 0
Ka = 35/4
Ep = 4/35
```

QUESTION-2

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$$\begin{array}{l} (a) \ G(s) = \frac{1}{(s+1)(3s+1)} \\ (b) \ G(s) = \frac{(s+1)(s+2)}{(s+2)(s+5)} \\ (c) \ G(s) = \frac{(s+5)(s+2)}{s^2(s+1)(s+4)} \end{array}$$

a for given control system apply step, ramp, parabolic inputs and observe the steady state error.



+All are given unity feedback system, so H(s)=1. Therefore transfer function = 6(s) H(s)=6(s)

fer function
$$\Rightarrow 6(s) H(s) = 6(s)$$

 $A^{(3)} 6(s) H(s) = \frac{1}{(s+1)(3s+1)}$, $Kp = \lim_{S \to 0} \frac{1}{(s+1)(3s+1)} = \frac{1}{2s+1}$

* Steady state error for step input
$$\Rightarrow k_p = 1$$

$$ess = \frac{1}{1+kp} = \frac{1}{2} = 0.5$$

2)
$$kv = \lim_{S \to 0} S6(s) H(s) = \lim_{S \to 0} \frac{s}{(s+1)(3)+1} = \frac{O}{s}$$

1) $\frac{1}{s+2} = \frac{1}{s+2} = \frac{$

(3)
$$Ka = \lim_{5 \to 0} \frac{5^{2}(541)(547)}{(5+2)(5+5)} = 0$$

$$\Rightarrow ess = \frac{1}{0} = \infty$$

$$\Rightarrow Type = 0 \text{ system} \Rightarrow \frac{error}{25} \Rightarrow \frac{10}{17} \approx \infty$$

C)
$$6(s) H(s) = \frac{(s+s)(s+7)}{s^2(s+1)(s+4)}$$

$$\begin{array}{cccc}
\text{(1)} & \text{(2)} & \text{(3)} & \text$$

$$2 \text{ kv-lim} \frac{s(s+s)(s+7)}{s^2(s+1)(s+u)} = \infty$$

$$*ess = \frac{1}{100} = 0$$

3)
$$K_a = \lim_{s \to \infty} \frac{s^2(s+1)(s+1)}{s^2(s+1)(s+4)} = \frac{35}{4}$$
 parabolic

 $\frac{1}{4} = \frac{1}{1} = \frac{1}{35} = \frac{1}{35}$