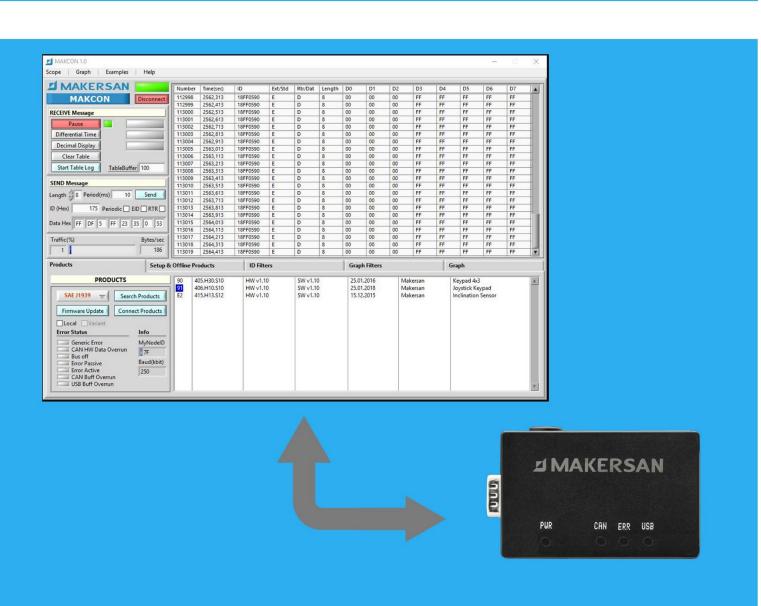


# **User Manual**

# Makcon IDE **790.01.S001**

# **Makcon IDE**





# **Revision History**

Date	Changed	Rev.
December 2018	Updated the new features	1.1
April 2018	First edition	1.0



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# 1 Introduction

This document contains information on how to install, configure and operate the device "MO 79X USB to CAN Converter" via MakCon software is MO 795.S1. It describes product functions and parameters used for the operation.

Read through this document and related documents before use to become familiar with the device.

The following symbols may appear throughout this document.



This symbol indicates a warning that may cause personal injury, death or damage to the machine by means other than electrical if the symbol is omitted.

The information contained herein is subject to change. Makersan reserves the right to make corrections, enhancements, improvements and other changes to its products at any time and without notice.



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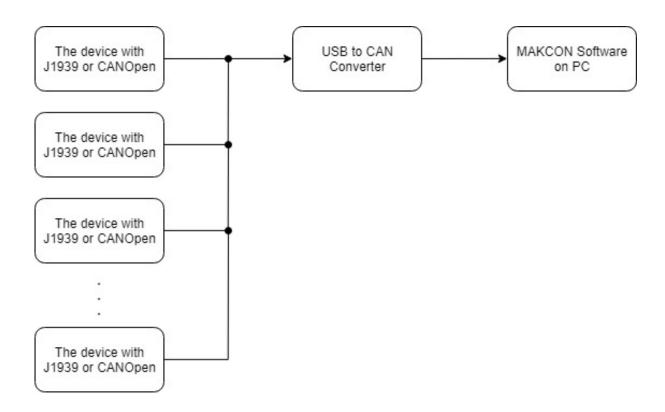
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## 2 Overview

The "MO 799 USB to CAN converter" is a communication module to provide an interface between PC and CAN bus devices. It's used to monitor the bus via MakCon software. MakCon is a software configuration tool that has been developed by Makersan and runs on a PC, also provides to monitor a J1939 bus or CANopen bus via the USB to CAN Converter.

Upon being connected to the bus, MakCon will find all devices manufactured by Makersan. The users can access easily to all the variable parameters of them and change.



Some of the specifications of the USB to CAN Converter are listed below:

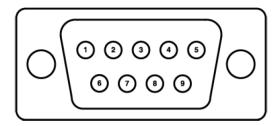
- USB socket: USB 1.1 or 2.0 full speed
- CAN socket: 9 pole DSUB male (DSUB-9)
- CAN Interface: Electrically isolated up to 1Mbit/s
- Supply Voltage: It's powered directly from the USB port 5V
- External Power: It's optional for the devices
- LED Indicators:
- Power Orange
- Error Red (represents that there is an error)
- USB Green (blinking means that USB is sending/receiving data.)
- CAN Blue (blinking means that CAN is sending/receiving data.)



# 3 Installation

#### 3.1 Electrical Connection

The USB cable is generic USB A to B cable and the CAN connector is 9 pole DSUB male(DSUB-9) as shown below;



Pin	Signal	Wires Marking
2	CAN_L	Green
7	CAN_H	Yellow
3	CAN_GND	White
9	VCC_BAT (optional)	Red
6	GND_BAT (optinal)	Black

#### 3.2 Bus Termination

CAN bus must be terminated at both ends by a resistor of 120  $\Omega$  in order to prevent signal reflections. The device doesn't have an internal termination resistor. Therefore termination must be done externally if the device is connected at one end.

#### 3.3 Software and Driver Installation

Using the provided download link, install the MakCon software by running MAKCONInstaller.exe. After that, the USB to CAN converter driver will be automatically run in order to install. Since the installer wizard installs the 64bit driver automatically, if your PC is x86, you get an error during installation. Therefore you shall install it using the file located at C:\Program Files(x86)\Makcon\Drivers\dpinst\_x86.exe manually for x86 PCs after installed the MakCon software.

## 3.4 System Requirements

Operating System: Windows 7 32/64bit and later.

Port: USB(1.1 or 2.0 full speed)

Display: VGA – 1024x768 and later recommended for MakCon software



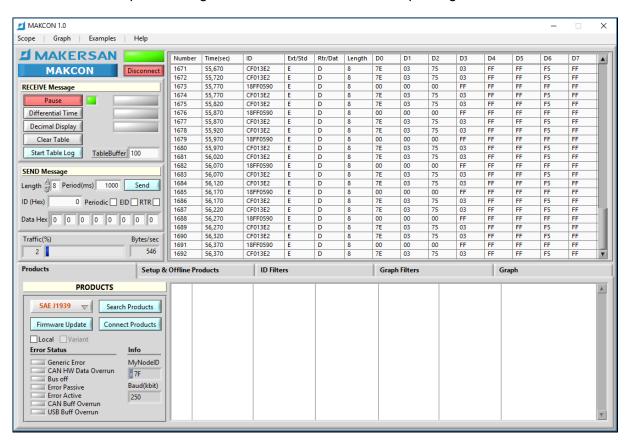
### 4 MakCon Software

#### 4.1 Overview

The MakCon is a software configuration tool that has been developed by Makersan and runs on a PC, also provides to monitor a J1939 bus or CANopen bus via the USB to CAN Converter. The ID, time, data and data length which transferring on the bus can be monitored with it. Furthermore, the users can access easily to all the variable parameters of the devices and also change.

There are four menus which are; scope, graph, examples and help in the MakCon software.

- Scope: Setting/Monitoring the parameters and status of CAN bus, received data, sending data and searching products has been manufactured by Makersan.
- Graph: Plotting the filtered data in which set the graph filter in scope menu.
- Examples: The examples application of products has been providing from Makersan.
- Help: Providing the manual how to run it and updating MakCon.





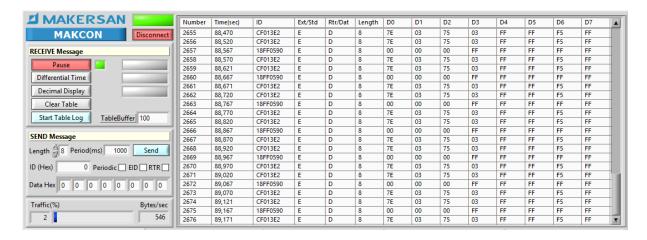
#### 4.2 Scope Menu

The scope menu provides to set parameters of the CAN, send a message, monitor the bus and find the calculated the traffic ratio.

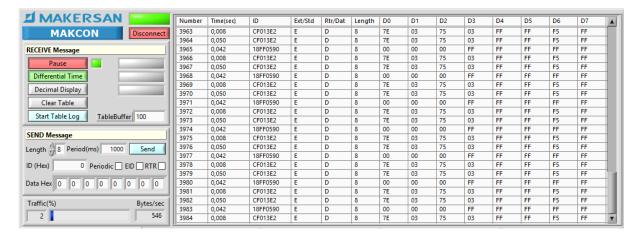
 The Connect Button: Provides to connect or disconnect the bus. Once the connect button is clicked, the software will find the USB/CAN converter automatically and connect if has been plugged to any USB port. Whether the connecting is successful can be seen through an indicator where is above the connect button. If it's green, the connecting is successful.

#### 4.2.1 Receive Message

Play/Pause Button: Provides to insert the new message which has just received from
the bus to table. If the state of this button is "play", then the table will be refreshed
automatically after received a new message. You can see which message that has just
received. If the state of this button is "pause", then the table won't be refreshed, but the
USB buffer will be read and not be an overflow.



 Differential Time Button: Displays the time as a differential. Thus the time which is between a new and before the message can be seen and found the period time of the device easily. Otherwise, it has indicated the time since connecting.



 Clear Table Button: Provides to clear the table which indicates the received and sent messages on the bus.



 Start/Stop Table Log: Provides to log the table to a text file where will be located Documents\Makcon\Log after clicked the start button. It will log the only just received message after the start to file and until is clicked again(the stop). While the logging is being active, the situation is indicating through an indicator.

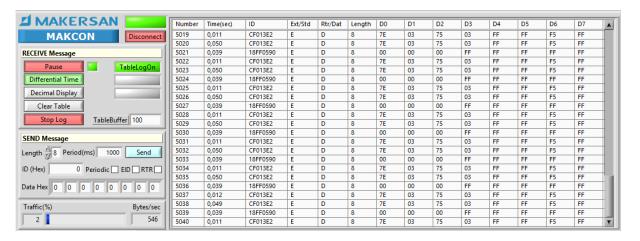
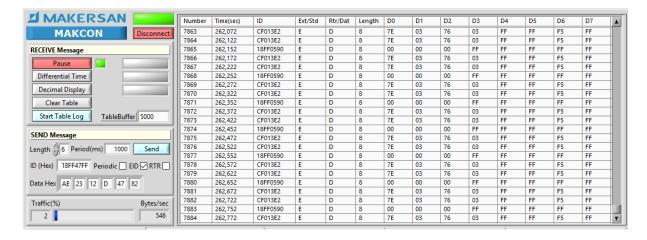


 Table Buffer: Specifies how many messages will be displayed in the table. This value may be from 1 to 5000.

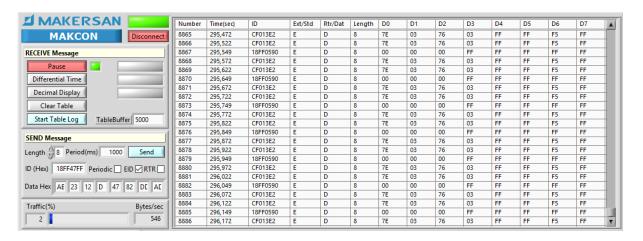
#### 4.2.2 Send Message

 Length: Specifies how many bytes will be sent via CAN. This value may be from 1 to 8 due to the feature of the CAN.

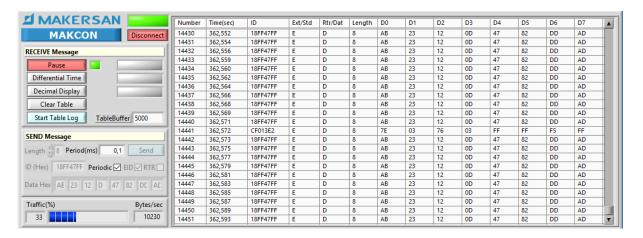


- ID(Hex): Specifies the ID which the message will be sent.
- Data Hex: Specifies the data will be sent. The first box is D0 byte and the last box is D7 byte of the CAN. Please note, these values shall be written as hexadecimal, otherwise, the wrong values will be sent.

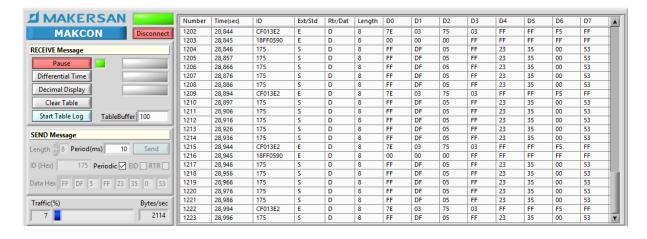




- Period(sec): When the periodic checkbox is active, this value specifies the period of the message will be sent periodically. It can be minimum 0.1 milliseconds.
- Periodic Check Box: Provides the message to send periodically as a value which specified in the box.



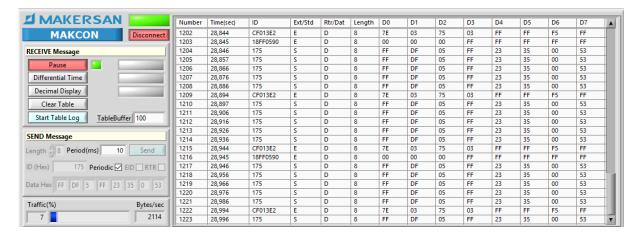
EID: Specifies whether the ID will be sent, is standard or extended. For an extended ID, the checkbox shall be selected. Otherwise, the software will assume that you select a standard ID.



RTR: Specifies whether doing a reading from an address or writing to an address.

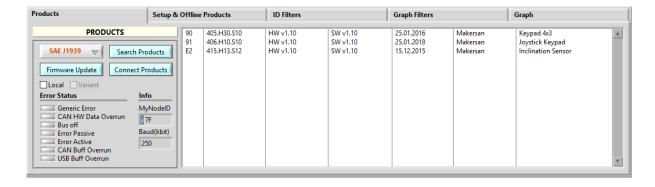


 Traffic(%) & Bytes/sec: The traffic ratio gives the ratio between the current transferring messages and capacity of the bus.



#### 4.2.3 Products

- Protocol Combobox: Provides to find all devices has been manufactured by Makersan has the selected protocol on the bus.
- Search Products: After selected the protocol and clicked the search products button, the software will find all devices on the bus.



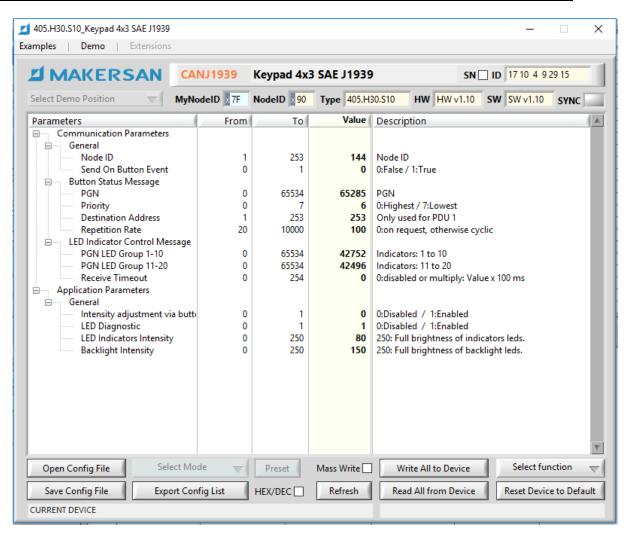
To view the parameters of any one of the listed products, please double click on it or click one connect products. After double-clicked on anyone, a new window of the selected product will be opened. Any parameter in this window can be changed easily. This window will be as follows.



While configuring the device, the machine or vehicle may react unexpectedly and may cause personal injury or death.

Ensure that man and machine in safe condition!





There are three menus which are setup, examples, demo, examples and extension in this window. The setup menu provides to set/get parameters of the device.

In title section, there is information about the device which has been connected. MyNodelD is the id of MakCon software, NodelD is the id of the device. The others which are the type, hw, sw and id are the manufacturing feature of it. The SYNC indicates whether there is a problem between the displayed values and the real values that the device has them. If it's red, this means that there is a problem.



Also, you can make your own config files the new parameters in order to upload it to a new device. To do this, you can use "save config file button". It provides these parameters to save to a specific file, also through "open config file button", these parameters can be opened. Furthermore, these parameters to save to a text file through "export config list". During saving these parameters, the default folder path is Documents\Makcon\ProgCnf to save and load.



The "write all to device" and "read all from device" buttons provides to read and write all parameters. Also, the device can be restored the default settings and parameters through "reset device to default" button. If the Mass Write option selected, it will write all parameters but this time the write data will be preserved even if the parameters in the device memory are different.

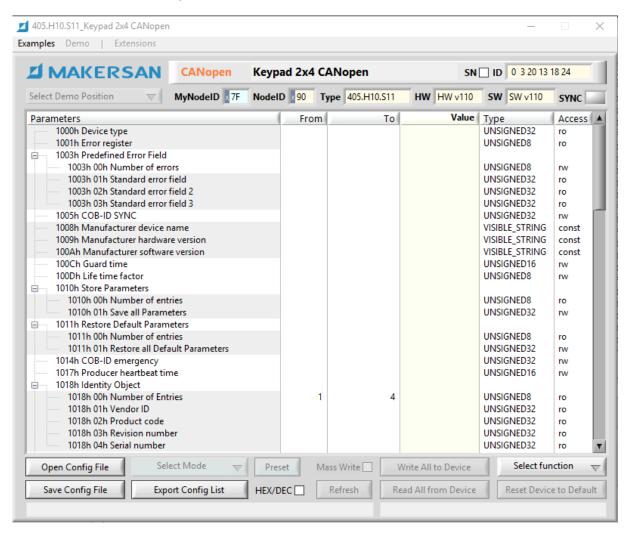
The select function combo box provides to restart the device and select whether the periodic message is sent.

The displaying of the values the can be selected as hexidecimal or decimal thanks to the HEX/DEC check box.



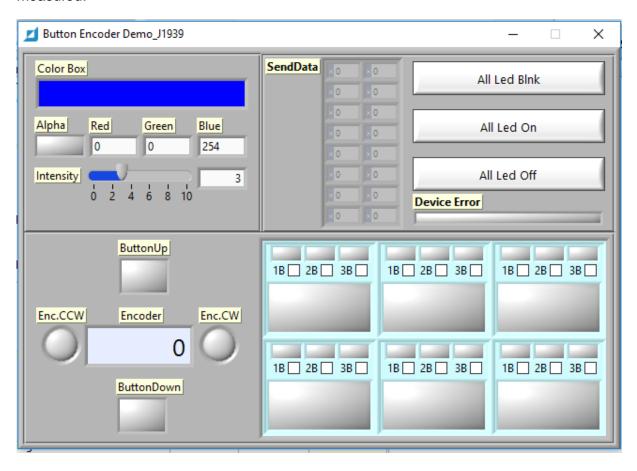
The select mode combo box and preset button are a specific feature for the products and all products may not have it.

Note: The values of having gray background rows as shown follows in the devices with CANOPEN can't be changed.





The demo menu has an application how displays the current value of the device, thus it provides the users to see the current values and make sense them which has been measured.

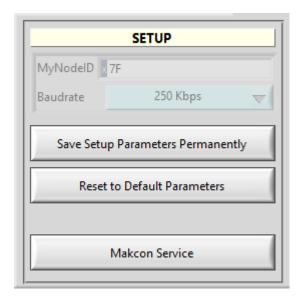


The examples menu has the example application parameters which provided by Makersan about the device. The extension menu if available means there is a module which can be used with this device.

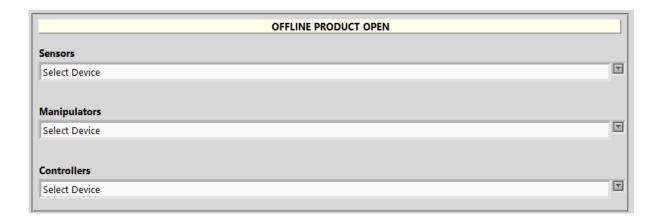
- Firmware Update: Provides to update the devices. After clicking this button, the software will connect our database and check whether there is a new software for it. If there is an available new software, it will update to the latest version. Updating can be also done with a local file which provided by Makersan. To do it, you should select the local checkbox.
- Error Status: These indicators notifies when there is a problem on the bus.
- Info: MyNodeID is the Node ID of the software and Baud(kbit) specifies the communication baud rate of the CAN. These two parameters can be changed in Setup & Offline Products menu.

#### 4.2.4 Setup & Offline Products

- MyNodelD: Specifies the node ID of the MakCon software. This value shall be a hexadecimal number. Otherwise, the wrong node id may be chosen for communication.
- Baudrate: This combo box provides to select the baud rate/speed of the CAN. It can be chosen from 10Kbps to 1000Kbps.



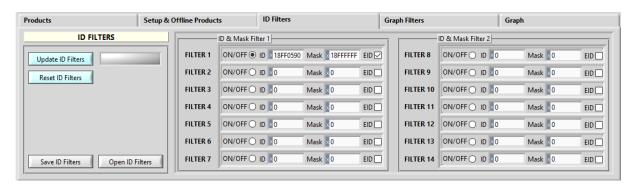
- Save Setup Parameters Permanently: Provides to save the changed settings which are node ID or baud rate for the MakCon software.
- Reset to Default Parameters: Provides to load the default setting for the MakCon software.
- Offline Product Open: Provides to review the products that manufactured by Makersan as offline.



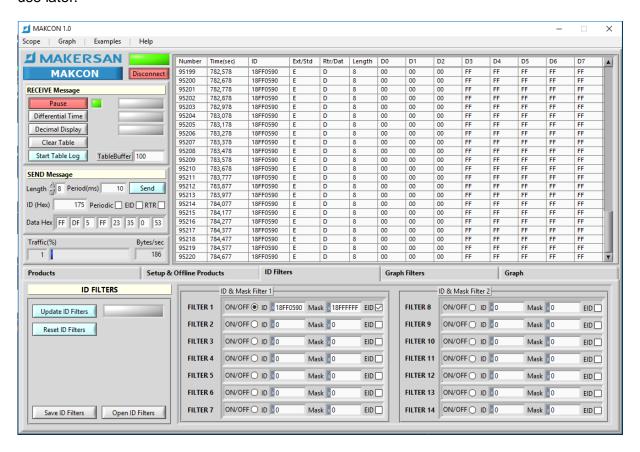
#### 4.2.5 ID Filters

The capacity of id filter of the MakCon software is 14. That's mean you can use to filter the total of 14 id filter on the bus. To enable the set filter, first the on/off radio button shall be selected and then ID filters shall be updated by clicking "Update ID Filters" button. Thus the message of the only id which has been filtered will be displayed in the table. Also, when any changing was done, an indicator warns you to update these changes.





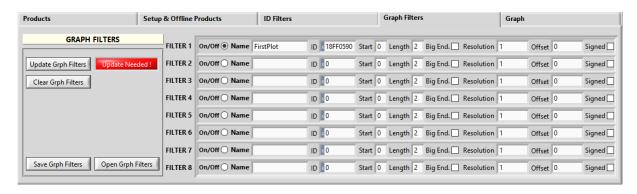
The specified filters can be saved in your documents folder and you can open them in order to use later.



#### 4.2.6 Graph Filters

The graph filters provide to plot the data which is received from the filtered id. The maximum 8 filters can be inserted. The bytes which is wanted to plot can be selected from start to the last byte easily. Through the resolution and offset box, you can add offset the data or multiply it. Furthermore, you can display the data which received the signed number and select the endian format.

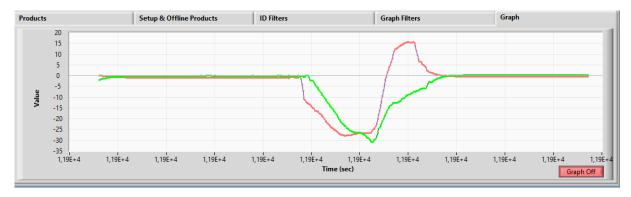




As in the id filters menu, the graph filters too need to update the plot.

#### 4.2.7 Graph

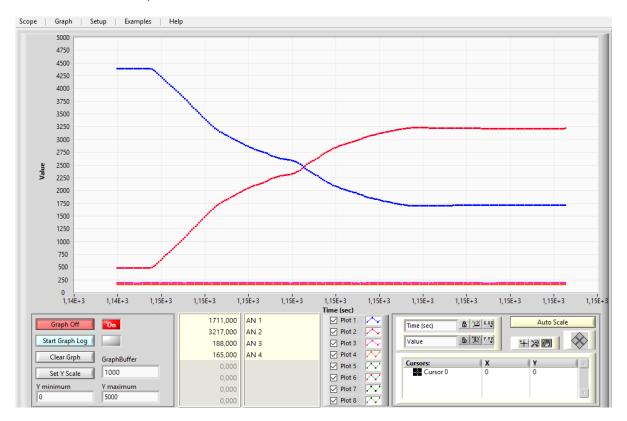
After updated the graph filters, the plotting data can be seen in this menu or another graph menu where is in the tab bar. All you need to do is click the "graph on" button.





## 4.3 Graph Menu

As the mini-graph menu in scope menu, this menu provides to plot the data which received, but this is more comprehensive.



For instance, you can log the plotted data as x and y-axis to a txt file where is located in the documents folder, set y scale axis, minimum and maximum values. Furthermore, the last value which received from the plotted data can be seen and the colour of the line changed. The graph buffer means that the plotted line will have how many points. Each line has the same point numbers.



# 4.4 Examples Menu

This menu includes the example filters which both id and graph provided by Makersan and are located in program files folder. The user can select the appropriate application for their own products and use.



# 4.5 Help Menu

The last menu of tab-bar is the help. It provides to reach the help manual and our website. Furthermore, it provides to update the MakCon software via internet.



# 5 Appendix

## **5.1 Definitions**

USB Universal Serial Bus

CAN Control Area Network

# 5.2 Disposal

Please observe the national regulations for your country when disposing of the device.