DATASHEET MO 450X.H10.PXX.XX







Product Characteristics

Technology Lifetime at full stroke **Operating Temperature** Counterplug

Contactless Hall Measuring Principle (Full Redundant)

Up to 10 million -40°C ... +85°C

6 way, Delphi Packard Metric Pack 150

12162261 Metri-Pack 150 Sealed Female Connector 12124076-L Metri-Pack 150 Sealed Terminal

Sensor 1: Electrical Data

Supply Voltage

Supply Current

Output Voltage

Output Current

Output Short Circuit Current

Output Load Load Capacity **Output Resolution**

Total Error Linearity **Hysteresis** 5 VDC (±0.5V)

8 mA (typical) per channel (Total Consumption = 16mA)

Ratiometric Analog Output, Programmable 0 - 5 V / PWM (100-500 Hz - 5V)

1 mA (max.) 15 mA

10 kOhm (typical)

4.7 nF 12 bit ±1 %Vs ±1 degree 0.5 %

Sensor 2: Electrical Data

Supply Voltage

Supply Current Output Voltage

Output Current

Output Short Circuit Current

Output Load **Load Capacity**

Output Resolution Total Error Linearity **Hysteresis**

8 mA (typical) per channel (Total Consumption = 16mA)

Ratiometric Analog Output, Programmable 0 - 5 V / PWM (100-500 Hz - 5V)

1 mA (max.) 15 mA

10 kOhm (typical)

4,7 nF 12 bit ±1 %Vs ±1 degree 0.5 %

Environment / EMC

Chemical Load

Damp Heat Steady Damp Heat, Cyclic

Cold **Dry Heat**

Change of Temperature Mechanical Shock Vibration Sinusoidal Vibration Random

Free Fall Water Jet **Dust Immersion**

Salt Spray **EMC ESD**

ISO 16750-5

: Diesel, engine oil, hydraulic fluid, grease, brake fluid, antifreeze fluid, urea, windscreen washer fluid, vehicle washing chemicals, cola, coffee, NPK fertilizer.

DIN EN 60068-2-78: 40°C, 85% RH, 96h

DIN EN 60068-2-30 : Between 25 / 55°C, 95% RH, 24h/cyc, 6cyc

DIN EN 60068-2-1 : -40°C, 48h DIN EN 60068-2-2 : 85°C, 48h

DIN EN 60068-2-14 : Between -40 / 85°C, 8h/cyc, 30cyc DIN EN 60068-2-27: 40g, 6ms, 1000 times per plane x, y, z DIN EN 60068-2-6 : 40g, 0,32m/s, 8h per plane x, y ,z DIN EN 60068-2-64: 5,8g, 10-2000Hz, 8h per plane x, y,z

DIN IEC 60068-2-32: 1m free fall to concrete ground, 2 times per plane x, y, z

DIN 40050 Part 9 : Electronic IP 6K9K, Mechanical IP 54 : Electronic IP 6K9K, Mechanical IP 54 DIN 40050 Part 9

DIN 40050 Part 9 : Electronic IP 67 DIN EN 60068-2-11: 504 hours

ECE-R10 Rev.5

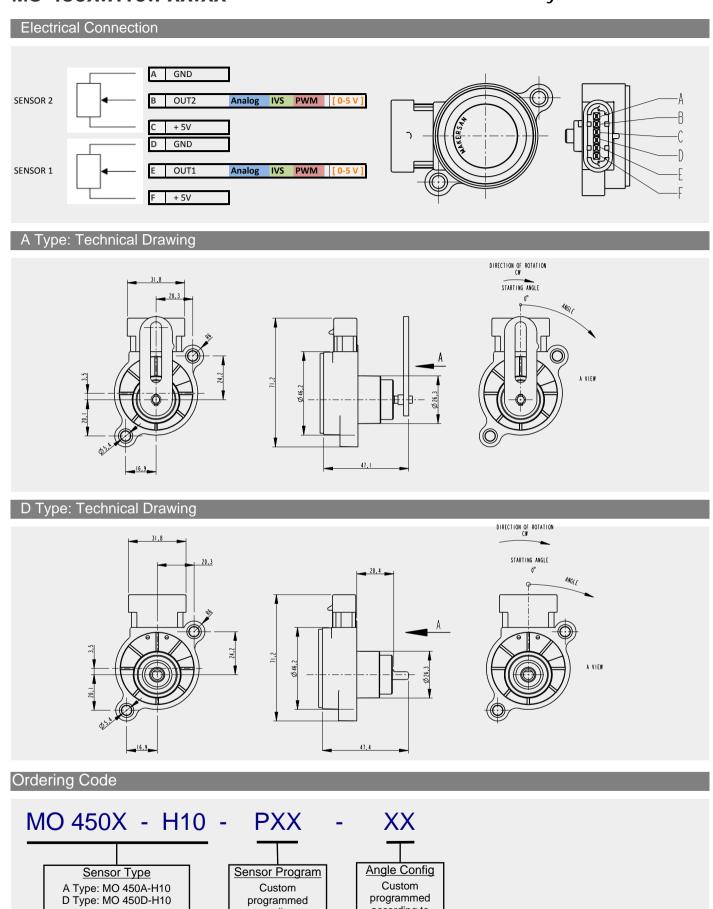
ISO 10605

All the tests specified above were performed in Makersan's in-house testing facility for the purpose of design verification except EMC. The in-house testing facility

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Rotary Position Sensor



according to

customer request

according to customer request

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Safety Instructions

- *Do not use sensor in hazardous and explosive environment.
- *Keep the sensor away from magnets and radio equipment . Hall sensors are sensitive to external magnetic fields.
- *Do not place the sensor to the direct air flow of vehicles heating cooling air duct due to the high temperature stress.
- *Screen with the vehicle's ground the electric cables connected to sensor. Far away the sensor cable from power-conducting lines.
- *Provide a clean power supply to the sensor. Otherwise voltage transients may damage the sensor.
- *Do not direct the pressure washing jet to sensor.
- *Unplug connectors from the sensor during electrical welding operations.
- *Damages which result from improper use, all warranty and liability claims with respect to the manufacturer void.
- *To perform a risk analysis of the system is customer's responsibility at use in safety-related functions of the sensor.
- *In no case Makersan will be liable or responsible for all damages and consequences resulting from the use of this device. The customer accepts all liability and risk in relation to use of this product in the final equipment.
- *All the operating conditions specified in this document must not be exceeded during product life in order to ensure part reliability.
- *These products are ESD (Electrostatic Discharge) sensitive devices. ESD may cause permanent damage. When handling these devices please observe standard ESD precautions.
- *Use outside these conditions may result in personal injury, death or damage to machine.

Fault Condition Behaviors

Test Conditions	450.H10
Sensor 1:	%Vs
Broken Ground (GND) [Pull-down load < 10 kOhm]	< 4
Broken Ground (GND) [Pull-up load > 1kOhm]	> 99
Broken Supply (Vs) [Pull-down load > 1kOhm]	< 1
Broken Supply (Vs) [Pull-up load > 1kOhm]	-
Short Sensor Signal to Supply (Vs)	> 97
Short Sensor Signal to Ground (GND)	< 1.5
Short Sensor Supply to Ground (GND)	< 1.5
Sensor 2:	%Vs
Broken Ground (GND) [Pull-down load < 10 kOhm]	< 4
Broken Ground (GND) [Pull-up load > 1kOhm]	> 99
Broken Supply (Vs) [Pull-down load > 1kOhm]	< 1
Broken Supply (Vs) [Pull-up load > 1kOhm]	-
Short Sensor Signal to Supply (Vs)	> 97
Short Sensor Signal to Ground (GND)	< 1.5
Short Sensor Supply to Ground (GND)	< 1.5

^{*} The fault conditions given above are only valid for full redundant (independent supply/ground for each sensor) operation. In any other case the product must not be used. It is customer's responsibility to ensure that the system transitions to a safe state under each fault condition in the final equipment.

Makersan reserves the right to make corrections, enhancements, improvements and other changes to its products at any time and without notice.

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