Contents

1	Clas	sses			4
	1.1	matrix	x - matric	es	4
		1.1.1	Matrix -	- matrices	6
			1.1.1.1	map – apply function to elements	8
			1.1.1.2	reduce – reduce elements iteratively	8
			1.1.1.3	copy – create a copy	8
			1.1.1.4	set – set compo	8
			1.1.1.5	setRow – set m-th row vector	9
			1.1.1.6	setColumn – set n-th column vector	9
			1.1.1.7	getRow – get i-th row vector	9
			1.1.1.8	getColumn – get j-th column vector	9
			1.1.1.9	swapRow – swap two row vectors	9
			1.1.1.10	swapColumn – swap two column vectors	10
			1.1.1.11	insertRow – insert row vectors	10
			1.1.1.12	insert Column – insert column vectors	10
			1.1.1.13	extendRow – extend row vectors	10
			1.1.1.14	extendColumn – extend column vectors	10
			1.1.1.15	deleteRow – delete row vector	11
			1.1.1.16	deleteColumn – delete column vector	11
			1.1.1.17	transpose – transpose matrix	11
			1.1.1.18	getBlock – block matrix	11
			1.1.1.19	subMatrix – submatrix	11
		1.1.2	SquareM	Iatrix – square matrices	13
			1.1.2.1	$is Upper Triangular Matrix-check\ upper\ triangular$	14
			1.1.2.2	isLowerTriangularMatrix – check lower triangular	14
			1.1.2.3	isDiagonalMatrix – check diagonal matrix	14
			1.1.2.4	isScalarMatrix – check scalar matrix	14
			1.1.2.5	isSymmetricMatrix - check symmetric matrix .	14
		1.1.3	RingMat	rix – matrix whose elements belong ring	16
			1.1.3.1	getCoefficientRing – get coefficient ring	17
			1.1.3.2	toFieldMatrix – set field as coefficient ring	17
			1.1.3.3	toSubspace – regard as vector space	17
			1.1.3.4	hermiteNormalForm (HNF) – Hermite Normal	
				Form	17

	1.1.3.5	exthermiteNormalForm (extHNF) - extended Her-	
		mite Normal Form algorithm	17
	1.1.3.6	kernelAsModule – kernel as Z-module	18
1.1.4	RingSqu	areMatrix – square matrix whose elements belong	
			19
	1.1.4.1	getRing – get matrix ring	20
	1.1.4.2	isOrthogonalMatrix – check orthogonal matrix .	20
	1.1.4.3	isAlternatingMatrix (isAntiSymmetricMatrix, isSke	ewSym
		metricMatrix) – check alternating matrix	20
	1.1.4.4	isSingular – check singular matrix	20
	1.1.4.5	trace - trace	20
	1.1.4.6	determinant – determinant	21
	1.1.4.7	cofactor – cofactor	21
	1.1.4.8	commutator – commutator	21
	1.1.4.9	characteristicMatrix – characteristic matrix	21
	1.1.4.10	adjugateMatrix – adjugate matrix	21
	1.1.4.11	cofactorMatrix (cofactors) – cofactor matrix	22
	1.1.4.12	smithNormalForm (SNF, elementary_divisor) -	
		Smith Normal Form (SNF)	22
	1.1.4.13	extsmithNormalForm (extSNF) - Smith Normal	
		Form (SNF)	22
1.1.5	FieldMa	trix – matrix whose elements belong field	24
	1.1.5.1	kernel – kernel	25
	1.1.5.2	image – image	25
	1.1.5.3	rank - rank	25
	1.1.5.4	inverseImage – inverse image: base solution of	
		linear system	25
	1.1.5.5	solve – solve linear system	25
	1.1.5.6	$\operatorname{columnEchelonForm} - \operatorname{column}$ echelon form	26
1.1.6	_	uareMatrix – square matrix whose elements be-	
		<u>l</u>	27
	1.1.6.1	triangulate - triangulate by elementary row op-	
		eration	28
	1.1.6.2	inverse - inverse matrix	28
	1.1.6.3	hessenbergForm - hessenberg form	28
	1.1.6.4	LUDecomposition - LU decomposition	28
1.1.7		Ring – ring of matrices	29
		unitMatrix - unit matrix	30
	1.1.7.2	zeroMatrix - zero matrix	30
	1.1.7.3	getInstance(class function) - get cached instance	31
1.1.8		e – subspace of finite dimensional vector space	32
	1.1.8.1	issubspace - check subspace of self	33
	1.1.8.2	toBasis - select basis	33
	1.1.8.3	supplementBasis - to full rank	33
	1.1.8.4	sumOfSubspaces - sum as subspace	33
	1.1.8.5	intersectionOfSubspaces - intersection as subspace	33

	1.1.8.6 fromMatrix(class function) - create subspace	35
1.1.9	createMatrix[function] – create an instance	36
1.1.10	identityMatrix(unitMatrix)[function] - unit matrix	36
1.1.11	zeroMatrix[function] – zero matrix	36

Chapter 1

Classes

1.1 matrix – matrices

- Classes
 - Matrix
 - SquareMatrix
 - RingMatrix
 - RingSquareMatrix
 - FieldMatrix
 - FieldSquareMatrix
 - MatrixRing
 - Subspace
- Functions
 - createMatrix
 - identityMatrix
 - unitMatrix
 - zeroMatrix

The module matrix has also some exception classes.

MatrixSizeError: Report contradicting given input to the matrix size.

VectorsNotIndependent: Report column vectors are not independent.

NoInverseImage: Report any inverse image does not exist.

NoInverse: Report the matrix is not invertible.

This module using following type:

 ${f compo}$: ${f compo}$ must be one of these forms below.

- concatenated row lists, such as [1,2]+[3,4]+[5,6].
- list of row lists, such as [[1,2], [3,4], [5,6]].
- list of column tuples, such as [(1, 3, 5), (2, 4, 6)].
- list of vectors whose dimension equals column, such as vector. Vector([1, 3, 5]), vector. Vector([2, 4, 6]).

The examples above represent the same matrix form as follows:

- 1 2
- 3 4
- 5 6

1.1.1 Matrix – matrices

Initialize (Constructor)

```
 \begin{array}{ll} {\rm Matrix(row:} \ integer, \ {\rm column:} \ integer, \ {\rm compo:} \ compo{=}0, \ {\rm coeff\_ring:} \\ {CommutativeRing}{=}0) \\ {\rightarrow} \ Matrix \end{array}
```

Create new matrices object.

†This constructor automatically changes the class to one of the following class: RingMatrix, RingSquareMatrix, FieldMatrix, FieldSquareMatrix.

Your input determines the class automatically by examining the matrix size and the coefficient ring. row and column must be integer, and coeff_ring must be an instance of Ring. Refer to compo for information about compo. If you abbreviate compo, it will be deemed to all zero list.

The list of expected inputs and outputs is as following:

- Matrix(row, column, compo, coeff_ring)
 → the row×column matrix whose elements are compo and coefficient ring is coeff_ring
- Matrix(row, column, compo)
 → the row×column matrix whose elements are compo (The coefficient ring is automatically determined.)
- Matrix(row, column, coeff_ring)
 → the row×column matrix whose coefficient ring is coeff_ring (All elements are 0 in coeff_ring.)
- Matrix(row, column)
 → the row×column matrix (The coefficient matrix is Integer. All elements are 0.)

Attribute

row: The row size of the matrix.

column: The column size of the matrix.

coeff ring: The coefficient ring of the matrix.

compo: The elements of the matrix.

Operations

operator	explanation
M==N	Return whether M and N are equal or not.
M[i, j]	Return the coefficient of i-th row, j-th column term of matrix M.
M[i]	Return the vector of i-th column term of matrix M.
M[i, j]=c	Replace the coefficient of i-th row, j-th column term of matrix M by c.
M[j]=c	Replace the vector of i-th column term of matrix M by vector c.
c in M	Check whether some element of M equals c .
repr(M)	Return the repr string of the matrix M.
	string represents list concatenated row vector lists.
str(M)	Return the str string of the matrix M.

```
>>> A = matrix.Matrix(2, 3, [1,0,0]+[0,0,0])
>>> A.__class__.__name__
'RingMatrix'
>>> B = matrix.Matrix(2, 3, [1,0,0,0,0,0])
>>> A == B
True
>>> B[1, 1] = 0
>>> A != B
True
>>> B == 0
True
>>> A[1, 1]
>>> print repr(A)
[1, 0, 0]+[0, 0, 0]
>>> print str(A)
1 0 0
0 0 0
```

1.1.1.1 map – apply function to elements

```
\texttt{map}(\texttt{self, function:} \textit{function}) \rightarrow \textit{Matrix}
```

Return the matrix whose elements is applied function to.

†The function map is an analogy of built-in function map.

1.1.1.2 reduce - reduce elements iteratively

```
 \begin{array}{l} \texttt{reduce}(\texttt{self, function:} \textit{function}, \texttt{initializer:} \textit{RingElement} \\ \rightarrow \textit{RingElement} \end{array}
```

Apply function from upper-left to lower-right, so as to reduce the iterable to a single value.

†The function map is an analogy of built-in function reduce.

1.1.1.3 copy - create a copy

```
\mathtt{copy}(\mathtt{self}) 	o 	extit{Matrix}
```

create a copy of self.

†The matrix generated by the function is same matrix to self, but not same as a instance.

1.1.1.4 set - set compo

```
\mathtt{set}(\mathtt{self},\,\mathtt{compo}\colon compo) 	o (None)
```

Substitute the list compo for compo.

compo must be the form of compo.

1.1.1.5 setRow – set m-th row vector

 $\mathtt{setRow}(\mathtt{self}, \mathtt{m}: integer, \mathtt{arg}: list/Vector) o (None)$

Substitute the list/Vector arg as m-th row.

The length of arg must be same to self.column.

1.1.1.6 setColumn - set n-th column vector

 $\mathtt{setColumn}(\mathtt{self}, \mathtt{n:} \ integer, \mathtt{arg:} \ list/Vector)
ightarrow (None)$

Substitute the list/Vector arg as n-th column.

The length of arg must be same to self.row.

1.1.1.7 getRow - get i-th row vector

 $\mathtt{getRow}(\mathtt{self}, \ \mathtt{i:} \ \mathit{integer}) \ o \ \mathit{Vector}$

Return i-th row in form of self.

The function returns a row vector (an instance of **Vector**).

1.1.1.8 getColumn – get j-th column vector

 $getColumn(self, j: integer) \rightarrow Vector$

Return j-th column in form of self.

1.1.1.9 swapRow – swap two row vectors

 $swapRow(self, m1: integer, m2: integer) \rightarrow (None)$

Swap self's m1-th row vector and m2-th row one.

1.1.1.10 swapColumn – swap two column vectors

```
swapColumn(self, n1: integer, n2: integer) \rightarrow (None)
```

Swap self's n1-th column vector and n2-th column one.

1.1.1.11 insertRow – insert row vectors

```
insertRow(self, i: integer, arg: list/Vector/Matrix) \rightarrow (None)
```

Insert row vectors arg to i-th row.

arg must be list, **Vector** or **Matrix**. The length (or **column**) of it should be same to the column of **self**.

1.1.1.12 insertColumn – insert column vectors

```
	ext{insertColumn(self, j: } integer, arg: list/Vector/Matrix) \ 	o (None)
```

Insert column vectors arg to j-th column.

arg must be list, **Vector** or **Matrix**. The length (or **row**) of it should be same to the row of **self**.

1.1.1.13 extendRow – extend row vectors

```
extendRow(self, arg: list/Vector/Matrix) \rightarrow (None)
```

Join self with row vectors arg (in vertical way).

The function combines self with the last row vector of self. That is, extendRow(arg) is same to insertRow(self.row+1, arg).

arg must be list, **Vector** or **Matrix**. The length (or **column**) of it should be same to the column of **self**.

1.1.1.14 extendColumn – extend column vectors

```
\operatorname{extendColumn}(\operatorname{self}, \operatorname{arg:}\ \mathit{list/Vector/Matrix}) 	o (None)
```

Join self with column vectors arg (in horizontal way).

The function combines self with the last column vector of self. That is,

extendColumn(arg) is same to insertColumn(self.column+1, arg).

arg must be list, **Vector** or **Matrix**. The length (or **row**) of it should be same to the row of **self**.

1.1.1.15 deleteRow – delete row vector

```
	ext{deleteRow(self, i: } integer) 
ightarrow (None)
```

Delete i-th row vector.

1.1.1.16 deleteColumn – delete column vector

```
deleteColumn(self, j: integer) \rightarrow (None)
```

Delete j-th column vector.

1.1.1.17 transpose – transpose matrix

```
transpose(self) \rightarrow \textit{Matrix}
```

Return the transpose of self.

$1.1.1.18 \quad getBlock-block\ matrix$

```
\begin{array}{lll} \texttt{getBlock}(\texttt{self, i:} & \textit{integer, j:} & \textit{integer, row:} & \textit{integer, column:} & \textit{integer} \\ \textit{ger} \\ = & \texttt{None}) \\ & \rightarrow \textit{Matrix} \end{array}
```

Return the rowxcolumn block matrix from the (i, j)-element.

If column is omitted, column is considered as same value to row.

1.1.1.19 subMatrix – submatrix

```
	ext{subMatrix(self, I: } integer, J: integer None) \rightarrow Matrix \\ 	ext{subMatrix(self, I: } list, J: list=None) \rightarrow Matrix \\ 	ext{}
```

The function has a twofold significance.

- I and J are integer: Return submatrix deleted I-th row and J-th column.
- I and J are list:

 Return the submatrix composed of elements from self assigned by rows
 I and columns J, respectively.

If J is omitted, J is considered as same value to I.

```
>>> A = matrix.Matrix(2, 3, [1,2,3]+[4,5,6])
>>> A
[1, 2, 3]+[4, 5, 6]
>>> A.map(complex)
[(1+0j), (2+0j), (3+0j)]+[(4+0j), (5+0j), (6+0j)]
>>> A.reduce(max)
>>> A.swapRow(1, 2)
>>> A
[4, 5, 6]+[1, 2, 3]
>>> A.extendColumn([-2, -1])
>>> A
[4, 5, 6, -2]+[1, 2, 3, -1]
>>> B = matrix.Matrix(3, 3, [1,2,3]+[4,5,6]+[7,8,9])
>>> B.subMatrix(2, 3)
[1, 2]+[7, 8]
>>> B.subMatrix([2, 3], [1, 2])
[4, 5]+[7, 8]
```

1.1.2 SquareMatrix – square matrices

Initialize (Constructor)

Create new square matrices object.

SquareMatrix is subclass of Matrix. †This constructor automatically changes the class to one of the following class: RingMatrix, RingSquareMatrix, FieldMatrix, FieldSquareMatrix.

Your input determines the class automatically by examining the matrix size and the coefficient ring. row and column must be integer, and coeff_ring must be an instance of **Ring**. Refer to **compo** for information about compo. If you abbreviate compo, it will be deemed to all zero list.

The list of expected inputs and outputs is as following:

- Matrix(row, compo, coeff_ring)
 the row square matrix whose elements are compo and coefficient ring is coeff_ring
- Matrix(row, compo)
 → the row square matrix whose elements are compo (coefficient ring is automatically determined)
- Matrix(row, coeff_ring)
 → the row square matrix whose coefficient ring is coeff_ring (All elements are 0 in coeff_ring.)
- Matrix(row)
 → the row square matrix (The coefficient ring is Integer. All elements are 0.)

†We can initialize as Matrix, but column must be same to row in the case.

 ${\bf 1.1.2.1} \quad is Upper Triangular Matrix-check\ upper\ triangular$

$$is Upper Triangular Matrix (self)
ightarrow \mathit{True}/\mathit{False}$$

Check whether self is upper triangular matrix or not.

1.1.2.2 isLowerTriangularMatrix - check lower triangular

$$isLowerTriangularMatrix(self) \rightarrow \textit{True/False}$$

Check whether self is lower triangular matrix or not.

1.1.2.3 isDiagonalMatrix - check diagonal matrix

$$isDiagonalMatrix(self) \rightarrow \mathit{True}/\mathit{False}$$

Check whether self is diagonal matrix or not.

1.1.2.4 isScalarMatrix - check scalar matrix

$$isScalarMatrix(self) \rightarrow \mathit{True}/\mathit{False}$$

Check whether self is scalar matrix or not.

1.1.2.5 isSymmetricMatrix - check symmetric matrix

$$isSymmetricMatrix(self)
ightarrow \mathit{True/False}$$

Check whether self is symmetric matrix or not.

- >>> A = matrix.SquareMatrix(3, [1,2,3]+[0,5,6]+[0,0,9])
- >>> A.isUpperTriangularMatrix()

```
True
>>> B = matrix.SquareMatrix(3, [1,0,0]+[0,-2,0]+[0,0,7])
>>> B.isDiagonalMatrix()
True
```

1.1.3 RingMatrix – matrix whose elements belong ring

```
\begin{array}{l} \mathbf{RingMatrix}(\texttt{row:} integer, \texttt{column:} integer, \texttt{compo:} compo{=}0, \texttt{coeff\_ring:} \\ CommutativeRing{=}0) \\ & \rightarrow RingMatrix \end{array}
```

Create matrix whose coefficient ring belongs ring.

RingMatrix is subclass of **Matrix**. See Matrix for getting information about the initialization.

Operations

operator	explanation
M+N	Return the sum of matrices M and N.
M-N	Return the difference of matrices M and N.
M*N	Return the product of M and N. N must be matrix, vector or scalar
M % d	Return M modulo d. d must be nonzero integer.
- M	Return the matrix whose coefficients have inverted signs of M.
+M	Return the copy of M.

```
>>> A = matrix.Matrix(2, 3, [1,2,3]+[4,5,6])
>>> B = matrix.Matrix(2, 3, [7,8,9]+[0,-1,-2])
>>> A + B
[8, 10, 12]+[4, 4, 4]
>>> A - B
[-6, -6, -6]+[4, 6, 8]
>>> A * B.transpose()
[50, -8]+[122, -17]
>>> -B * vector.Vector([1, -1, 0])
Vector([1, -1])
>>> 2 * A
[2, 4, 6]+[8, 10, 12]
>>> B % 3
[1, 2, 0]+[0, 2, 1]
```

1.1.3.1 getCoefficientRing - get coefficient ring

```
\mathtt{getCoefficientRing}(\mathtt{self}) 	o 	extit{CommutativeRing}
```

Return the coefficient ring of self.

This method checks all elements of self and set coeff_ring to the valid coefficient ring.

1.1.3.2 toFieldMatrix - set field as coefficient ring

```
	ext{toFieldMatrix(self)} 
ightarrow (None)
```

Change the class of the matrix to **FieldMatrix** or **FieldSquareMatrix**, where the coefficient ring will be the quotient field of the current domain.

1.1.3.3 toSubspace – regard as vector space

```
toSubspace(self, isbasis: True/False=None) \rightarrow (None)
```

Change the class of the matrix to Subspace, where the coefficient ring will be the quotient field of the current domain.

1.1.3.4 hermiteNormalForm (HNF) – Hermite Normal Form

```
egin{align*} \mathbf{hermiteNormalForm(self)} & 	o \mathbf{\it RingMatrix} \ \mathbf{HNF(self)} & 	o \mathbf{\it RingMatrix} \ \end{aligned}
```

Return upper triangular hermite normal form (HNF).

$\begin{array}{ll} \textbf{1.1.3.5} & \textbf{exthermiteNormalForm (extHNF)} - \textbf{extended Hermite Normal Form algorithm} \\ \end{array}$

```
	ext{exthermiteNormalForm(self)} 
ightarrow (	ext{\it RingSquareMatrix}, 	ext{\it RingMatrix}) \ = 	ext{extHNF(self)} 
ightarrow (	ext{\it RingSquareMatrix}, 	ext{\it RingMatrix})
```

Return hermite normal form M and U satisfied selfU = M.

The function returns tuple (U, M), where U is an instance of **RingSquareMatrix** and M is an instance of **RingMatrix**.

1.1.3.6 kernelAsModule – kernel as \mathbb{Z} -module

```
kernelAsModule(self) \rightarrow \textit{RingMatrix}
```

Return kernel as \mathbb{Z} -module.

The difference between the function and **kernel** is that each elements of the returned value are integer.

```
>>> A = matrix.Matrix(3, 4, [1,2,3,4,5,6,7,8,9,-1,-2,-3])
>>> print A.hermiteNormalForm()
0 36 29 28
0 0 1 0
0 0 0 1
>>> U, M = A.hermiteNormalForm()
>>> A * U == M
True
>>> B = matrix.Matrix(1, 2, [2, 1])
>>> print B.kernelAsModule()
1
-2
```

1.1.4 RingSquareMatrix – square matrix whose elements belong ring

```
\begin{array}{l} \mathbf{RingSquareMatrix(row:} \ integer, \ \mathtt{column:} \ integer{=}0, \ \mathtt{compo:} \ compo{=}0, \\ \mathtt{coeff\_ring:} \ CommutativeRing{=}0) \\ & \rightarrow RingMatrix \end{array}
```

Create square matrix whose coefficient ring belongs ring.

RingSquareMatrix is subclass of **RingMatrix** and **SquareMatrix**. See SquareMatrix for getting information about the initialization.

Operations

operator	explanation
M**c	Return the c-th power of matrices M.

```
>>> A = matrix.RingSquareMatrix(3, [1,2,3]+[4,5,6]+[7,8,9])
>>> A ** 2
[30L, 36L, 42L]+[66L, 81L, 96L]+[102L, 126L, 150L]
```

1.1.4.1 getRing – get matrix ring

```
\mathtt{getRing}(\mathtt{self}) 	o 	extit{MatrixRing}
```

Return the **MatrixRing** belonged to by self.

1.1.4.2 isOrthogonalMatrix - check orthogonal matrix

```
isOrthogonalMatrix(self) \rightarrow \mathit{True}/\mathit{False}
```

Check whether self is orthogonal matrix or not.

1.1.4.3 isAlternatingMatrix (isAntiSymmetricMatrix, isSkewSymmetricMatrix) – check alternating matrix

 $isAlternatingMatrix(self) \rightarrow True/False$

Check whether self is alternating matrix or not.

1.1.4.4 isSingular – check singular matrix

$$isSingular(self) \rightarrow True/False$$

Check whether self is singular matrix or not.

The function determines whether determinant of self is 0. Note that the the non-singular matrix does not automatically mean invertible matrix; the nature that the matrix is invertible depends on its coefficient ring.

1.1.4.5 trace – trace

 $\mathrm{trace}(\mathtt{self}) o \mathit{RingElement}$

Return the trace of self.

1.1.4.6 determinant – determinant

```
\operatorname{determinant}(\operatorname{self}) \to \mathit{RingElement}
```

Return the determinant of self.

1.1.4.7 cofactor – cofactor

```
cofactor(self, i: integer, j: integer) \rightarrow RingElement
```

Return the (i, j)-cofactor.

1.1.4.8 commutator – commutator

$commutator(self, N: RingSquareMatrix element) \rightarrow RingSquareMatrix$

Return the commutator for self and N.

The commutator for M and N, which is denoted as [M, N], is defined as [M, N] = MN - NM.

1.1.4.9 characteristicMatrix - characteristic matrix

$\operatorname{characteristicMatrix}(\operatorname{ ext{self}}) o extit{ extit{RingSquareMatrix}}$

Return the characteristic matrix of self.

1.1.4.10 adjugateMatrix – adjugate matrix

```
adjugateMatrix(self) \rightarrow \textit{RingSquareMatrix}
```

Return the adjugate matrix of self.

The adjugate matrix for M is the matrix N such that $MN = NM = (\det M)E$, where E is the identity matrix.

1.1.4.11 cofactorMatrix (cofactors) - cofactor matrix

```
egin{aligned} 	ext{cofactorMatrix}(	ext{self}) &
ightarrow RingSquareMatrix \ & 	ext{cofactors}(	ext{self}) &
ightarrow RingSquareMatrix \end{aligned}
```

Return the cofactor matrix of self.

The cofactor matrix for M is the matrix whose (i, j) element is (i, j)-cofactor of M. The cofactor matrix is same to transpose of the adjugate matrix.

1.1.4.12 smithNormalForm (SNF, elementary_divisor) – Smith Normal Form (SNF)

```
egin{align*} 	ext{smithNormalForm(self)} &
ightarrow RingSquareMatrix \ & 	ext{SNF(self)} &
ightarrow RingSquareMatrix \ & 	ext{elementary\_divisor(self)} &
ightarrow RingSquareMatrix \end{aligned}
```

Return the list of diagonal elements of the Smith Normal Form (SNF) for self.

The function assumes that self is non-singular.

1.1.4.13 extsmithNormalForm (extSNF) – Smith Normal Form (SNF)

```
{
m extsmithNormalForm(self)} 
ightarrow (RingSquareMatrix, RingSquareMatrix, RingSquareMatrix) \ {
m extSNF(self)} 
ightarrow RingSquareMatrix, RingSquareMatrix)
```

Return the Smith normal form M for self and U,V satisfied UselfV = M.

```
>>> A = matrix.RingSquareMatrix(3, [3,-5,8]+[-9,2,7]+[6,1,-4])
>>> A.trace()
1L
>>> A.determinant()
-243L
>>> B = matrix.RingSquareMatrix(3, [87,38,80]+[13,6,12]+[65,28,60])
>>> U, V, M = B.extsmithNormalForm()
>>> U * B * V == M
True
```

```
>>> print M
4 0 0
0 2 0
0 0 1
>>> B.smithNormalForm()
[4L, 2L, 1L]
```

1.1.5 FieldMatrix - matrix whose elements belong field

```
 \begin{aligned} & \textbf{FieldMatrix}(\texttt{row:} integer, \texttt{column:} integer, \texttt{compo:} compo{=}0, \texttt{coeff\_ring:} \\ & CommutativeRing{=}0) \\ & & \rightarrow \textit{RingMatrix} \end{aligned}
```

Create matrix whose coefficient ring belongs field.

FieldMatrix is subclass of **RingMatrix**. See **Matrix** for getting information about the initialization.

Operations

operator	explanation
M/d	Return the division of M by d.d must be scalar.
M//d	Return the division of M by d.d must be scalar.

```
>>> A = matrix.FieldMatrix(3, 3, [1,2,3,4,5,6,7,8,9])
>>> A / 210
1/210 1/105 1/70
2/105 1/42 1/35
1/30 4/105 3/70
```

1.1.5.1 kernel – kernel

```
kernel(self) \rightarrow FieldMatrix
```

Return the kernel of self.

The output is the matrix whose column vectors form basis of the kernel. The function returns None if the kernel do not exist.

1.1.5.2 image – image

```
image(self) \rightarrow \textit{FieldMatrix}
```

Return the image of self.

The output is the matrix whose column vectors form basis of the image. The function returns None if the kernel do not exist.

1.1.5.3 rank – rank

```
{
m rank}({
m self}) 
ightarrow integer
```

Return the rank of self.

1.1.5.4 inverseImage – inverse image: base solution of linear system

```
inverseImage(self, V: Vector/RingMatrix) \rightarrow RingMatrix
```

Return an inverse image of V by self.

The function returns one solution of the linear equation self X = V.

1.1.5.5 solve – solve linear system

```
solve(self, B: Vector/RingMatrix) \rightarrow (RingMatrix, RingMatrix)
```

Solve self X = B.

The function returns a particular solution sol and the kernel of self as a

matrix. If you only have to obtain the particular solution, use inverseImage.

${\bf 1.1.5.6} \quad {\bf column Echelon Form-column\ echelon\ form}$

$columnEchelonForm(self) \rightarrow \textit{RingMatrix}$

Return the column reduced echelon form.

```
>>> A = matrix.FieldMatrix(2, 3, [1,2,3]+[4,5,6])
>>> print A.kernel
1/1
-2/1
   1
>>> print A.image()
1 2
4 5
>>> C = matrix.FieldMatrix(4, 3, [1,2,3]+[4,5,6]+[7,8,9]+[-1,-2,-3])
>>> D = matrix.FieldMatrix(4, 2, [1,0]+[7,6]+[13,12]+[-1,0])
>>> print C.inverseImage(D)
 3/1 4/1
-1/1 -2/1
0/1 0/1
>>> sol, ker = C.solve(D)
>>> C * (sol + ker[0]) == D
True
>>> AA = matrix.FieldMatrix(3, 3, [1,2,3]+[4,5,6]+[7,8,9])
>>> print AA.columnEchelonForm()
0/1 2/1 -1/1
0/1 1/1 0/1
0/1 0/1 1/1
```

${\bf 1.1.6} \quad {\bf FieldSquare Matrix-square\ matrix\ whose\ elements} \\ {\bf belong\ field}$

```
 \begin{aligned} & \textbf{FieldSquareMatrix(row: } integer, \text{ column: } integer = 0, \text{ compo: } compo = 0, \\ & \texttt{coeff\_ring: } CommutativeRing = 0) \\ & \rightarrow & FieldSquareMatrix \end{aligned}
```

Create square matrix whose coefficient ring belongs field.

FieldSquareMatrix is subclass of **FieldMatrix** and **SquareMatrix**. †The function **RingSquareMatrix**determinant is overridden and use different algorithm from one used in **RingSquareMatrix**determinant;the function calls **FieldSquareMatrix**triangulate. See **SquareMatrix** for getting information about the initialization.

1.1.6.1 triangulate - triangulate by elementary row operation

Return an upper triangulated matrix obtained by elementary row operations.

1.1.6.2 inverse - inverse matrix

```
egin{align*} 	ext{inverse(self V: } Vector/RingMatrix=& None) \ &
ightarrow FieldSquareMatrix \end{aligned}
```

Return the inverse of self. If V is given, then return self(-1)V.

†If the matrix is not invertible, then raise **NoInverse**.

1.1.6.3 hessenbergForm - hessenberg form

Return the hessenberg form of self.

1.1.6.4 LUDecomposition - LU decomposition

```
\begin{array}{c} \textbf{LUDecomposition(self)} \\ & \rightarrow \textit{(FieldSquareMatrix, FieldSquareMatrix)} \end{array}
```

Return the lower triangular matrix L and the upper triangular matrix U such that $\mathtt{self} == LU$.

1.1.7 †MatrixRing – ring of matrices

 ${f MatrixRing(size: integer, scalars: CommutativeRing)} \
ightarrow MatrixRing$

Create a ring of matrices with given size and coefficient ring scalars.

MatrixRing is subclass of **Ring**.

1.1.7.1 unitMatrix - unit matrix

```
egin{aligned} 	ext{unitMatrix(self)} \ & 	o 	ext{\it RingSquareMatrix} \end{aligned}
```

Return the unit matrix.

1.1.7.2 zeroMatrix - zero matrix

```
zeroMatrix(self) \rightarrow RingSquareMatrix
```

Return the zero matrix.

```
>>> M = matrix.MatrixRing(3, rational.theIntegerRing)
>>> print M
M_3(Z)
>>> M.unitMatrix()
[1L, OL, OL]+[OL, 1L, OL]+[OL, OL, 1L]
>>> M.zero
[OL, OL, OL]+[OL, OL, OL]+[OL, OL, OL]
```

1.1.7.3 getInstance(class function) - get cached instance

```
\texttt{getInstance(cls, size:} \ integer, \texttt{scalars:} \ CommutativeRing) \\ \rightarrow RingSquareMatrix
```

Return an instance of MatrixRing of given size and ring of scalars.

The merit of using the method instead of the constructor is that the instances created by the method are cached and reused for efficiency.

Examples

>>> print MatrixRing.getInstance(3, rational.theIntegerRing)
M 3(Z)

1.1.8 Subspace – subspace of finite dimensional vector space

```
\begin{array}{l} \textbf{Subspace(row:} \ integer, \ \texttt{column:} \ integer{=}0, \ \texttt{compo:} \ compo{=}0, \ \texttt{coeff\_ring:} \\ CommutativeRing{=}0, \ \texttt{isbasis:} \ True/False{=} \textbf{None)} \\ \rightarrow Subspace \end{array}
```

Create subspace of some finite dimensional vector space over a field.

Subspace is subclass of **FieldMatrix**.

See Matrix for getting information about the initialization. The subspace expresses the space generated by column vectors of self.

If isbasis is True, we assume that column vectors are linearly independent.

Attribute

isbasis The attribute indicates the linear independence of column vectors, i.e., if they form a basis of the space then isbasis should be True, otherwise False.

1.1.8.1 issubspace - check subspace of self

```
egin{aligned} 	ext{Subspace}(	ext{self, other: } Subspace) \ &
ightarrow 	ext{True}/False \end{aligned}
```

Return True if the subspace instance is a subspace of the other, or False otherwise.

1.1.8.2 toBasis - select basis

```
egin{aligned} 	ext{toBasis(self)} \ &
ightarrow (None) \end{aligned}
```

Rewrite self so that its column vectors form a basis, and set True to its isbasis.

The function does nothing if isbasis is already True.

1.1.8.3 supplementBasis - to full rank

```
egin{aligned} 	ext{supplementBasis(self)} \ &
ightarrow Subspace \end{aligned}
```

Return full rank matrix by supplementing bases for self.

1.1.8.4 sumOfSubspaces - sum as subspace

```
egin{aligned} \mathbf{sumOfSubspaces(self,\,other:} \ \mathit{Subspace}) \ &
ightarrow \ \mathit{Subspace} \end{aligned}
```

Return a matrix whose columns form a basis for sum of two subspaces.

1.1.8.5 intersectionOfSubspaces - intersection as subspace

```
intersectionOfSubspaces(self, other: Subspace) \ 
ightarrow Subspace
```

Return a matrix whose columns form a basis for intersection of two subspaces.

```
>>> A = matrix.Subspace(4, 3, [1,2,3]+[4,5,6]+[7,8,9]+[10,11,12])
>>> A.toBasis()
>>> print A
 1 2
 4 5
7 8
10 11
>>> B = matrix.Subspace(3, 2, [1,2]+[3,4]+[5,7])
>>> print B.supplementBasis()
1 2 0
3 4 0
5 7 1
>>> C = matrix.Subspace(4, 1, [1,2,3,4])
>>> D = matrix.Subspace(4, 2, [2,-4]+[4,-3]+[6,-2]+[8,-1])
>>> print C.intersectionOfSubspaces(D)
-2/1
-4/1
-6/1
-8/1
```

1.1.8.6 fromMatrix(class function) - create subspace

Create a Subspace instance from a matrix instance mat, whose class can be any of subclasses of Matrix.

Please use this method if you want a Subspace instance for sure.

1.1.9 createMatrix[function] - create an instance

Create an instance of $\mathbf{RingMatrix}$, $\mathbf{RingSquareMatrix}$, $\mathbf{FieldMatrix}$ or $\mathbf{FieldSquareMatrix}$.

Your input determines the class automatically by examining the matrix size and the coefficient ring. See **Matrix** or **SquareMatrix** for getting information about the initialization.

1.1.10 identityMatrix(unitMatrix)[function] - unit matrix

```
\begin{array}{lll} \textbf{identityMatrix(size:} & \textit{integer}, & \texttt{coeff:} & \textit{CommutativeR-ing/CommutativeRingElement} = \texttt{None}) \\ & \rightarrow \texttt{RingMatrix} \\ \\ \textbf{unitMatrix(size:} & \textit{integer}, & \texttt{coeff:} & \textit{CommutativeR-ing/CommutativeRingElement} = \texttt{None}) \\ & \rightarrow \texttt{RingMatrix} \end{array}
```

Return size-dimensional unit matrix.

coeff enables us to create matrix not only in integer but in coefficient ring which is determined by coeff.

coeff must be an instance of Ring or a multiplicative unit (one).

1.1.11 zeroMatrix[function] – zero matrix

Return row × column zero matrix.

coeff enables us to create matrix not only in integer but in coefficient ring which is determined by coeff.

coeff must be an instance of Ring or a additive unit (zero). If column is abbreviated, column is set same to row.

```
>>> M = matrix.createMatrix(3, [1,2,3]+[4,5,6]+[7,8,9])
>>> print M
1 2 3
4 5 6
7 8 9
>>> 0 = matrix.zeroMatrix(2, 3, imaginary.ComplexField())
>>> print 0
0 + 0j 0 + 0j 0 + 0j
0 + 0j 0 + 0j 0 + 0j
```

Bibliography