

Guangyuan Weng

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177 Huntington Ave, FL 2, Boston, MA 02115

EDUCATION

- Northeastern University** Sept. 2021 - Present
Ph.D., Computer and Information Sciences *Boston, MA*
- Advisor: Prof. Esteban Moro
 - Research Interests: Computational Social Science, Data Mining, Artificial Intelligence
- ShanghaiTech University** Sept. 2017 - July 2021
B.E., Computer Science and Technology *Shanghai, China*
- Advisors: Prof. David J. Crandall (Indiana University Bloomington), Prof. Haipeng Zhang

RESEARCH EXPERIENCE

- Social Urban Networks Lab, Network Science Institute** Jan. 2024 - Present
Research Assistant (Advisor: Prof. Esteban Moro) *Boston, MA*
- Introduced an empirical method to identify mobility borders in US cities by analyzing neural embeddings of human mobility trajectories
 - Validated the effectiveness of the word2vec model in modeling and embedding human mobility patterns
 - Quantitatively evaluated the contributions of physical barriers, points of interest (POI), and demographic factors in shaping mobility borders
- Wormpex AI Research** May 2023 - Aug. 2023
Research Intern (Advisor, Mentors: Prof. Gang Hua, Dr. Bo Liu, Dr. Haoxiang Li) *Bellevue, WA*
- Explored an innovative memory structure that merges conventional retrieval and classification methods, focusing on long-tail image recognition
 - Developed an importance module based on an self-attention mechanism for the retrieved K-Nearest Neighbors
 - Extended the applicability to real-world scenarios, achieving State-of-the-Art performance in ImageNet-LT datasets
- IU Computer Vision Lab, Indiana University** July 2020 - June 2021
Research Intern (Advisor: Prof. David J. Crandall) *Bloomington, IN*
- Focused on recognizing human actions in videos captured from *egocentric cameras* (e.g., Google Glass)
 - Discovered how action-object associations in datasets influence the generalization ability of action recognition models
 - Modeling the positions and sizes of hands and objects in the videos utilizing *graph convolutional neural network*
- Mobile Autonomous Robotic Systems Lab (MARS Lab)** Sept. 2018 - Jan. 2020
Undergraduate Research Assistant (Advisor: Prof. Sören Schwertfeger) *Shanghai, China*
- Built a mapping/SLAM robot with super-precise timing and localization with hardware synchronization
 - Designed a *printed circuit board* (PCB) mounted on a field robotics research platform to produce synchronized signal for all sensors (e.g., IMUs and lidars) and reduce noise of trigger signal
 - Generated three high-resolution and sensor-dense datasets to evaluate the performance of SLAM algorithms

PUBLICATIONS

- Beyond Distance: Mobility Neural Embeddings Reveal Visible and Invisible Barriers in Urban Space***
- **Weng, Guangyuan**, Kim, Minsuk, Ahn, Yong-Yeol, Moro, Esteban
 - Under Review

Action Recognition based on Cross-Situational Action-object Statistics

- Tsutsui, Satoshi, Wang, Xizi, **Weng, Guangyuan**, Zhang, Yayun, Crandall, David, Yu, Chen
- 12th IEEE International Conference on Development and Learning (ICDL 2022)

Advanced Mapping Robot and High-Resolution Dataset

- Chen, H., Yang, Z., Zhao, X., **Weng, G.**, Wan, H., Luo, J., Ye, X., Zhao, Z., He, Z., Dong, T., Schwertfeger, S.
- Journal of Robotics and Autonomous Systems

Towards Generation and Evaluation of Comprehensive Mapping Robot Datasets

- Chen, H., Zhao, X., Luo, J., Yang, Z., Zhao, Z., Wan, H., Ye, X., **Weng, G.**, He, Z., Dong, T., Schwertfeger S.
- Workshop on Dataset Generation and Benchmarking of SLAM Algorithms for Robotics and VR/AR of the 2019 IEEE International Conference on Robotics and Automation (ICRAW 2019)

PEER-REVIEWED CONFERENCE PRESENTATIONS (NON-ARCHIVAL)

Revealing Invisible Barriers in US Cities through Human Mobility and Unsupervised Learning

- **Weng, Guangyuan**, Kim, Minsuk, Ahn, Yong-Yeol, Moro, Esteban
- 11th International Conference on Computational Social Science (IC2S2 2025), Plenary Talks (1.5%)

ACTIVITIES

The Summer Institutes in Computational Social Science (SICSS-Penn)	June 2024
University of Pennsylvania	<i>Philadelphia, PA</i>
2018 IEEE ComSoc Summer School on Fog Computing	June 2018
IEEE ComSoc, OpenFog Consortium	<i>Shanghai, China</i>

TEACHING

CS5100 Foundations of Artificial Intelligence (25 Fall)	Sept. 2025
Head Teaching Assistant, Northeastern University	<i>Boston, MA</i>
CS5520 Mobile Application Development (24 Spring, 24 Fall, 25 Spring, 25 Summer)	May 2025
Head Teaching Assistant, Northeastern University	<i>Boston, MA</i>
CS4520 Mobile Application Development (24 Summer 1)	May 2024
Teaching Assistant, Northeastern University	<i>Boston, MA</i>
CS5330 Pattern Recognition and Computer Vision (21 Fall, 22 Fall)	Sept. 2022
Teaching Assistant, Northeastern University	<i>Boston, MA</i>

HONORS

ShanghaiTech Merit Students (2019-2020, Top 5%)	Dec. 2020
ShanghaiTech University	
ShanghaiTech Scholarship for Outstanding Undergraduate Students (RMB 30,000)	Dec. 2020
ShanghaiTech University	
Global Talent Attraction Program, International Summer Research Fellowship (\$ 4,000)	Feb. 2020
Indiana University Bloomington	

SKILLS

Languages	Chinese (Native), English (TOEFL-iBT 112)
Computer Languages	Python, R, SQL, C++, C, Rust, MATLAB, AWK
Protocols & APIs	PyTorch, scikit-learn, Robot Operating System (ROS), Processing (Java), L ^A T _E X