

# Guangyuan Weng

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177 Huntington Ave, FL 2, Boston, MA 02115

## EDUCATION

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### Northeastern University

Sept. 2021 - Present

Ph.D., Computer and Information Sciences

*Boston, MA*

- Advisor: Prof. Esteban Moro
- Research Interests: Computational Social Science, Data Mining, Artificial Intelligence

### ShanghaiTech University

Sept. 2017 - July 2021

B.E., Computer Science and Technology

*Shanghai, China*

- Advisors: Prof. David J. Crandall (Indiana University Bloomington), Prof. Haipeng Zhang

## RESEARCH EXPERIENCE

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### Social Urban Networks Lab, Network Science Institute

Jan. 2024 - Present

*Research Assistant* (Advisor: Prof. Esteban Moro)

*Boston, MA*

- Introduced an empirical method to identify mobility borders in US cities by analyzing neural embeddings of human mobility trajectories
- Validated the effectiveness of the word2vec model in modeling and embedding human mobility patterns
- Quantitatively evaluated the contributions of physical barriers, points of interest (POI), and demographic factors in shaping mobility borders

### Wormpex AI Research

May 2023 - Aug. 2023

*Research Intern* (Advisor, Mentors: Prof. Gang Hua, Dr. Bo Liu, Dr. Haoxiang Li)

*Bellevue, WA*

- Explored an innovative memory structure that merges conventional retrieval and classification methods, focusing on long-tail image recognition
- Developed an importance module based on a self-attention mechanism for the retrieved K-Nearest Neighbors
- Extended the applicability to real-world scenarios, achieving State-of-the-Art performance in ImageNet-LT datasets

### IU Computer Vision Lab, Indiana University

July 2020 - June 2021

*Research Intern* (Advisor: Prof. David J. Crandall)

*Bloomington, IN*

- Focused on recognizing human actions in videos captured from *egocentric cameras* (e.g., Google Glass)
- Discovered how action-object associations in datasets influence the generalization ability of action recognition models
- Modeling the positions and sizes of hands and objects in the videos utilizing *graph convolutional neural network*

### Mobile Autonomous Robotic Systems Lab (MARS Lab)

Sept. 2018 - Jan. 2020

*Undergraduate Research Assistant* (Advisor: Prof. Sören Schwertfeger)

*Shanghai, China*

- Built a mapping/SLAM robot with super-precise timing and localization with hardware synchronization
- Designed a *printed circuit board* (PCB) mounted on a field robotics research platform to produce synchronized signal for all sensors (e.g., IMUs and lidars) and reduce noise of trigger signal
- Generated three high-resolution and sensor-dense datasets to evaluate the performance of SLAM algorithms

## PUBLICATIONS

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*Beyond Distance: Mobility Neural Embeddings Reveal Visible and Invisible Barriers in Urban Space*

- Weng, Guangyuan, Kim, Minsuk, Ahn, Yong-Yeol, Moro, Esteban
- Under Review

### *Action Recognition based on Cross-Situational Action-object Statistics*

- Tsutsui, Satoshi, Wang, Xizi, **Weng, Guangyuan**, Zhang, Yayun, Crandall, David, Yu, Chen
- *12th IEEE International Conference on Development and Learning (ICDL 2022)*

### *Advanced Mapping Robot and High-Resolution Dataset*

- Chen, H., Yang, Z., Zhao, X., **Weng, G.**, Wan, H., Luo, J., Ye, X., Zhao, Z., He, Z., Dong, T., Schwertfeger, S.
- *Journal of Robotics and Autonomous Systems*

### *Towards Generation and Evaluation of Comprehensive Mapping Robot Datasets*

- Chen, H., Zhao, X., Luo, J., Yang, Z., Zhao, Z., Wan, H., Ye, X., **Weng, G.**, He, Z., Dong, T., Schwertfeger S.
- Workshop on Dataset Generation and Benchmarking of SLAM Algorithms for Robotics and VR/AR of the *2019 IEEE International Conference on Robotics and Automation (ICRAW 2019)*

## PEER-REVIEWED CONFERENCE PRESENTATIONS (NON-ARCHIVAL)

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### *Revealing Invisible Barriers in US Cities through Human Mobility and Unsupervised Learning*

- **Weng, Guangyuan**, Kim, Minsuk, Ahn, Yong-Yeol, Moro, Esteban
- *11th International Conference on Computational Social Science (IC2S2 2025)*, **Plenary Talks (1.5%)**

## ACTIVITIES

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<b>The Summer Institutes in Computational Social Science (SICSS-Penn)</b>	June 2024
University of Pennsylvania	<i>Philadelphia, PA</i>
<b>2018 IEEE ComSoc Summer School on Fog Computing</b>	June 2018
IEEE ComSoc, OpenFog Consortium	<i>Shanghai, China</i>

## TEACHING

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<b>CS5100 Foundations of Artificial Intelligence (25 Fall)</b>	Sept. 2025
Head Teaching Assistant, Northeastern University	<i>Boston, MA</i>
<b>CS5520 Mobile Application Development (24 Spring, 24 Fall, 25 Spring, 25 Summer)</b>	May 2025
Head Teaching Assistant, Northeastern University	<i>Boston, MA</i>
<b>CS4520 Mobile Application Development (24 Summer 1)</b>	May 2024
Teaching Assistant, Northeastern University	<i>Boston, MA</i>
<b>CS5330 Pattern Recognition and Computer Vision (21 Fall, 22 Fall)</b>	Sept. 2022
Teaching Assistant, Northeastern University	<i>Boston, MA</i>

## HONORS

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<b>ShanghaiTech Merit Students (2019-2020, Top 5%)</b>	Dec. 2020
ShanghaiTech University	
<b>ShanghaiTech Scholarship for Outstanding Undergraduate Students (RMB 30,000)</b>	Dec. 2020
ShanghaiTech University	
<b>Global Talent Attraction Program, International Summer Research Fellowship (\$ 4,000)</b>	Feb. 2020
Indiana University Bloomington	

## SKILLS

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<b>Languages</b>	Chinese (Native), English (TOEFL-iBT 112)
<b>Computer Languages</b>	Python, R, SQL, C++, C, Rust, MATLAB, AWK
<b>Protocols &amp; APIs</b>	PyTorch, scikit-learn, Robot Operating System (ROS), Processing (Java), L <sup>A</sup> T <sub>E</sub> X