

Lecture 8: February 9, 2015
cs 573: Probabilistic Reasoning
Professor Nevatia
Spring 2015

Review

- Assignment #2 due today
- Last lecture:
 - Conversions between BN and MN
 - Properties of chordal graphs
 - Energy functions and Log-linear models
 - Some simple models
 - Pairwise MRFs
 - Conditional random fields (CRFs)
 - Ising energy model
- Today's objective
 - Inference in graphical models
 - Variable elimination algorithm

Inference in Probabilistic Graphs

- Types of Queries
 - **Conditional probability** query $P(\mathbf{Y} | \mathbf{E} = \mathbf{e})$
 - **MAP** query, $\text{MAP}(\mathbf{W} | \mathbf{e}) = \arg \max_{\mathbf{w}} P(\mathbf{w}, \mathbf{e})$
 - We focus on the former first
- $P(\mathbf{Y} | \mathbf{E} = \mathbf{e}) = P(\mathbf{Y}, \mathbf{e}) / P(\mathbf{e})$
- $P(\mathbf{y}, \mathbf{e}) = \sum_{\mathbf{w}} P(\mathbf{y}, \mathbf{e}, \mathbf{w})$ where $\mathbf{W} = \mathbf{X} - \mathbf{Y} - \mathbf{E}$
 - Note that the quantity inside summation is just an entry in the joint distribution (may not be given explicitly but can be computed by using the chain rule)
- $P(\mathbf{e}) = \sum_{\mathbf{Y}} P(\mathbf{y}, \mathbf{e})$
 - Compute by summing out the joint distribution or from the calculation above
- Compute $P(\mathbf{y}, \mathbf{e})$ for various values of \mathbf{Y} and then normalize to add to one (don't need to compute $P(\mathbf{e})$ explicitly)

Worst-Case Complexity

- Solving by enumeration is exponential in the number of variables
- To decide whether $P(X = x) > 0$ is NP-hard
 - Shown by equivalence to satisfiability of a propositional logic formula
- To decide whether $P(X = x)$ is #P hard (harder than NP unless $P=NP$)
- Even *approximate* inference, with a ***guaranteed bound*** on the *relative error* (precise definition in the book) is NP-hard
- In practice, for moderate size networks, many queries can be answered exactly in reasonable time. Also, good approximate algorithms for larger networks.
 - Chapters 9 and 10 are about exact inference, chapters 11 and 12 about approximations

Inference on a Chain

- Study a chain first $A \rightarrow B \rightarrow C \rightarrow D$; assume CPDs are given
- First compute $P(B) = \sum_a P(a) P(B|a)$
 - Note, we compute the entire distribution of B
 - Let A have k values, B have m values. Consider computing probability of one value of B , say $P(b^1)$
 - Need k multiplications and $k-1$ additions to compute
 - Repeat for each value of B , m times
 - Total complexity is $O(k \times m)$
- Next compute $P(C) = \sum_b P(b) P(C|b)$
- Then, $P(D) = \sum_c P(c) P(D|c)$
- Method generalizes to chain of n variables.
 - If each variable is k -valued, complexity is $O(nk^2)$
 - Joint distribution has k^n entries
- How about computing $P(C|d^1)$?

Another Cut: Expand the Formula

- $P(A, B, C, D) = P(A) P(B|A)P(C|B)P(D|C)$, by chain rule
- Sum over A, B & C, to get:

$$P(D) = \sum_C \sum_B \sum_A P(A) P(B|A)P(C|B)P(D|C);$$

- Compute for $D = d^1$ and $D = d^2$

$$P(d^1) = \sum_C \sum_B \sum_A P(A) P(B|A)P(C|B)P(d^1|C) ;$$

$$P(d^2) = \sum_C \sum_B \sum_A P(A) P(B|A)P(C|B)P(d^2|C);$$

- Now, sum over A: consider $A = a^1$ and $A = a^2$
- $$P(d^1) = \sum_C \sum_B P(a^1) P(B|a^1)P(C|B) P(d^1|C) + \sum_C \sum_B P(a^2) P(B|a^2)P(C|B)P(d^1|C)$$

Similar expression for $P(d^2)$

Expanded Formulas

$$\begin{aligned}
 P(d^1) = & P(a^1) P(b^1 | a^1) P(c^1 | b^1) P(d^1 | c^1) \\
 & + P(a^2) P(b^1 | a^2) P(c^1 | b^1) P(d^1 | c^1) \\
 & + P(a^1) P(b^2 | a^1) P(c^1 | b^2) P(d^1 | c^1) \\
 & + P(a^2) P(b^2 | a^2) P(c^1 | b^2) P(d^1 | c^1) \\
 & + P(a^1) P(b^1 | a^1) P(c^2 | b^1) P(d^1 | c^2) \\
 & + P(a^2) P(b^1 | a^2) P(c^2 | b^1) P(d^1 | c^2) \\
 & + P(a^1) P(b^2 | a^1) P(c^2 | b^2) P(d^1 | c^2) \\
 & + P(a^2) P(b^2 | a^2) P(c^2 | b^2) P(d^1 | c^2)
 \end{aligned}$$

Note that the first two lines have common terms (third and fourth entries), so we do not need to compute twice; see below for factorized form.

$$\begin{aligned}
 & (P(a^1)P(b^1 | a^1) + P(a^2)P(b^1 | a^2)) P(c^1 | b^1) P(d^1 | c^1) \\
 + & (P(a^1)P(b^2 | a^1) + P(a^2)P(b^2 | a^2)) P(c^1 | b^2) P(d^1 | c^1) \\
 + & (P(a^1)P(b^1 | a^1) + P(a^2)P(b^1 | a^2)) P(c^2 | b^1) P(d^1 | c^2) \\
 + & (P(a^1)P(b^2 | a^1) + P(a^2)P(b^2 | a^2)) P(c^2 | b^2) P(d^1 | c^2)
 \end{aligned}$$

Similar expression for $P(d^2)$

Factorized Expressions

$P(d^1)=$

$$\begin{aligned}
 & (P(a^1)P(b^1 | a^1) + P(a^2)P(b^1 | a^2)) \quad P(c^1 | b^1) \quad P(d^1 | c^1) \\
 + & (P(a^1)P(b^2 | a^1) + P(a^2)P(b^2 | a^2)) \quad P(c^1 | b^2) \quad P(d^1 | c^1) \\
 + & (P(a^1)P(b^1 | a^1) + P(a^2)P(b^1 | a^2)) \quad P(c^2 | b^1) \quad P(d^1 | c^2) \\
 + & (P(a^1)P(b^2 | a^1) + P(a^2)P(b^2 | a^2)) \quad P(c^2 | b^2) \quad P(d^1 | c^2)
 \end{aligned}$$

$P(d^2)=$

$$\begin{aligned}
 & (P(a^1)P(b^1 | a^1) + P(a^2)P(b^1 | a^2)) \quad P(c^1 | b^1) \quad P(d^2 | c^1) \\
 + & (P(a^1)P(b^2 | a^1) + P(a^2)P(b^2 | a^2)) \quad P(c^1 | b^2) \quad P(d^2 | c^1) \\
 + & (P(a^1)P(b^1 | a^1) + P(a^2)P(b^1 | a^2)) \quad P(c^2 | b^1) \quad P(d^2 | c^2) \\
 + & (P(a^1)P(b^2 | a^1) + P(a^2)P(b^2 | a^2)) \quad P(c^2 | b^2) \quad P(d^2 | c^2)
 \end{aligned}$$

Note that sums are repeated several times: call the first sum, row 1 above $\tau_1(b^1)$, second row $\tau_1(b^2)$; together $\tau_1(B)$; note that each is repeated four times. Rewritten on next slide.

In terms of τ_1 (B)

$P(d^1)=$

$$\begin{array}{rclcl}
 & \tau_1(b^1) & P(c^1 | b^1) & P(d^1 | c^1) \\
 + & \tau_1(b^2) & P(c^1 | b^2) & P(d^1 | c^1) \\
 + & \tau_1(b^1) & P(c^2 | b^1) & P(d^1 | c^2) \\
 + & \tau_1(b^2) & P(c^2 | b^2) & P(d^1 | c^2)
 \end{array}$$

$P(d^2)=$

$$\begin{array}{rclcl}
 & \tau_1(b^1) & P(c^1 | b^1) & P(d^2 | c^1) \\
 + & \tau_1(b^2) & P(c^1 | b^2) & P(d^2 | c^1) \\
 + & \tau_1(b^1) & P(c^2 | b^1) & P(d^2 | c^2) \\
 + & \tau_1(b^2) & P(c^2 | b^2) & P(d^2 | c^2)
 \end{array}$$

Now, factorize $P(d^1|c^1)$, $P(d^1|c^2)$, $P(d^2|c^1)$, $P(d^2|c^2)$

Factorize Again

$$P(d^1) = \frac{(\tau_1(b^1)P(c^1 | b^1) + \tau_1(b^2)P(c^1 | b^2))}{(\tau_1(b^1)P(c^2 | b^1) + \tau_1(b^2)P(c^2 | b^2))} \frac{P(d^1 | c^1)}{P(d^1 | c^2)}$$

$$P(d^2) = \frac{(\tau_1(b^1)P(c^1 | b^1) + \tau_1(b^2)P(c^1 | b^2))}{(\tau_1(b^1)P(c^2 | b^1) + \tau_1(b^2)P(c^2 | b^2))} \frac{P(d^2 | c^1)}{P(d^2 | c^2)}$$

Note repeated sums again; define $\tau_2(C)$ to simplify and avoid repeated computations

$$\begin{aligned}\tau_2(c^1) &= \tau_1(b^1)P(c^1 | b^1) + \tau_1(b^2)P(c^1 | b^2) \\ \tau_2(c^2) &= \tau_1(b^1)P(c^2 | b^1) + \tau_1(b^2)P(c^2 | b^2)\end{aligned}$$

In terms of τ_2 (C)

$P(d^1)=$

$$\begin{aligned} & \tau_2(c^1) \quad P(d^1 \mid c^1) \\ + & \tau_2(c^2) \quad P(d^1 \mid c^2) \end{aligned}$$

$P(d^2)=$

$$\begin{aligned} & \tau_2(c^1) \quad P(d^2 \mid c^1) \\ + & \tau_2(c^2) \quad P(d^2 \mid c^2) \end{aligned}$$

Note: total number of operations (for binary variables) is 18:
4 multiplies and 2 adds for each of $\tau_1(B)$, for $\tau_2(C)$, and for $P(D)$;
computation of joint distribution requires 48 multiplies and 14 adds.

A Numerical Example

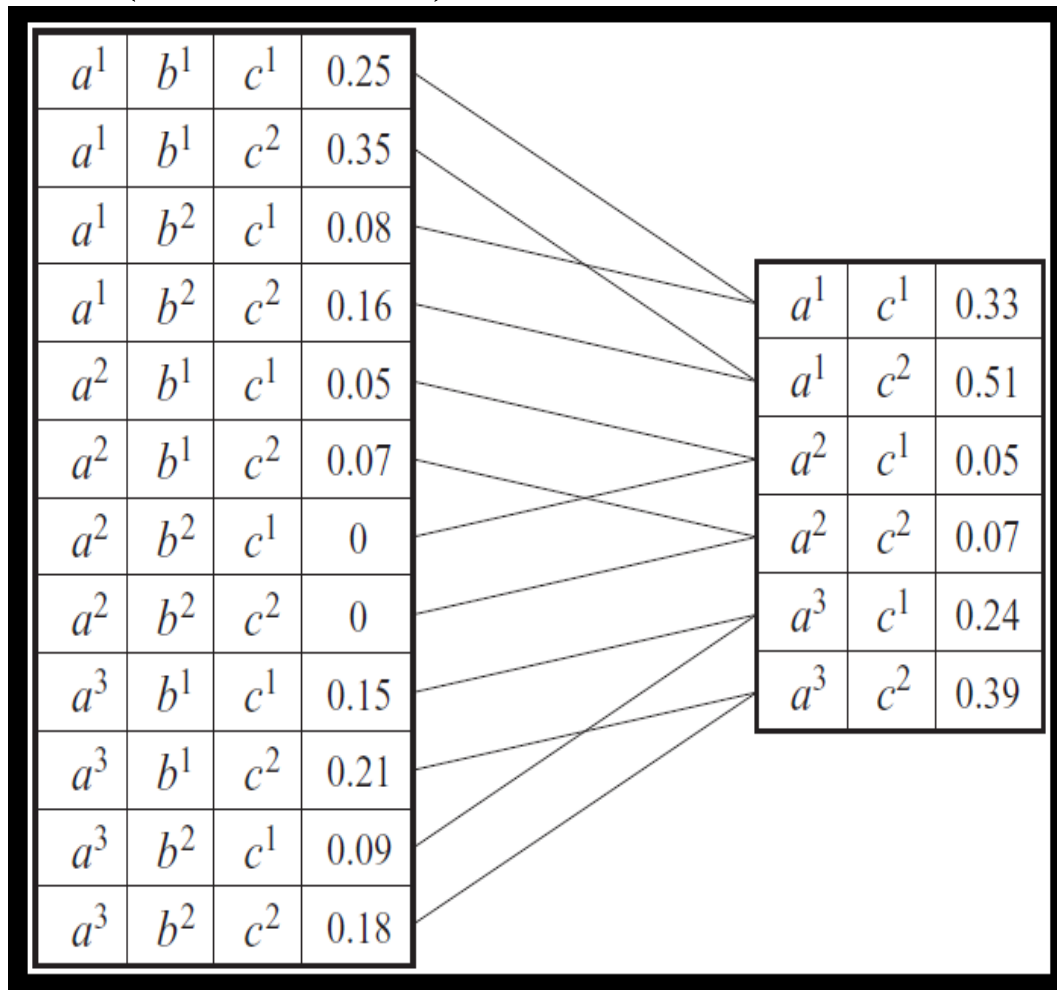
- Let $P(A) = \langle .6, .4 \rangle$, $P(B|A) = \langle .8, .2 \rangle, \langle .3, .7 \rangle$,
 $P(C|B) = \langle .9, .1 \rangle, \langle .2, .8 \rangle$, $P(D|C) = \langle .6, .4 \rangle, \langle .1, .9 \rangle$
- $\tau_1(b^1) = .6 \times .8 + .4 \times .3 = .6$, $\tau_1(b^2) = .4$
- $\tau_2(c^1) = .6 \times .9 + .4 \times .2 = .62$, $\tau_2(c^2) = .38$
- *etc.*

VE Algorithm on a Chain: Compact Form

- $P(D) = \sum_C \sum_B \sum_A P(A) P(B|A)P(C|B)P(D|C)$
- Rewrite as $\sum_C P(D|C) \sum_B P(C|B) \sum_A P(A) P(B|A)$
- Let $\psi_1(A,B) = P(A) P(B|A)$, $\tau_1(B) = \sum_A \psi_1(A,B)$
- $\psi_2(B,C) = \tau_1(B) P(C|B)$, $\tau_2(C) = \sum_B \psi_2(B,C)$
- $\psi_3(C,D) = \tau_2(C) P(D|C)$, $P(D) = \sum_C \psi_3(C,D)$
- Dynamic programming: computes inner expressions first, “inside out”

Factor Marginalization

- $\psi(\mathbf{X}) = \sum_Y \phi(\mathbf{X}, Y)$; \mathbf{X} is set of variables, Y is a single variable (not in set \mathbf{X})



Add terms that “match up”

Factor Operations

- $\phi_1 \cdot \phi_2 = \phi_2 \cdot \phi_1$
- $\sum_X \sum_Y \phi = \sum_Y \sum_X \phi$
- $(\phi_1 \cdot \phi_2) \cdot \phi_3 = \phi_1 \cdot (\phi_2 \cdot \phi_3)$
- $\sum_X (\phi_1 \cdot \phi_2) = \phi_1 \cdot \sum_X \phi_2$, if X is not in $\text{scope}[\phi_1]$

VE Algorithm (General Version)

- $P(A,B,C,D) = \phi_A \cdot \phi_B \cdot \phi_C \cdot \phi_D$;
nodes are not necessarily arranged in a chain
- $P(D) = \sum_C \sum_B \sum_A P(A, B,C,D)$; marginalize the joint distribution
 $= \sum_C \sum_B \sum_A \phi_A \cdot \phi_B \cdot \phi_C \cdot \phi_D$; express joint as a factor product
 $= \sum_C \sum_B \phi_C \cdot \phi_D (\sum_A \phi_A \cdot \phi_B)$; sum out A
 $= \sum_C \phi_D \cdot (\sum_B \phi_C \cdot (\sum_A \phi_A \cdot \phi_B))$; sum out B then C

Note: any order of variable elimination gives correct answer.

In general, compute $\sum_Z \prod_{\phi \in \Phi} \phi$; Z is the set of variables to be eliminated

Sum-Product algorithm (we have reversed the order of product and sum from the original definition)

Sum Product VE Algorithm (9.1)

Algorithm 9.1 Sum-product variable elimination algorithm

Procedure Sum-Product-VE (
 Φ , // Set of factors
 Z , // Set of variables to be eliminated
 \prec // Ordering on Z
)

1 Let Z_1, \dots, Z_k be an ordering of Z such that
2 $Z_i \prec Z_j$ if and only if $i < j$
3 **for** $i = 1, \dots, k$
4 $\Phi \leftarrow \text{Sum-Product-Eliminate-Var}(\Phi, Z_i)$
5 $\phi^* \leftarrow \prod_{\phi \in \Phi} \phi$
6 **return** ϕ^*

Procedure Sum-Product-Eliminate-Var (
 Φ , // Set of factors
 Z // Variable to be eliminated
)

1 $\Phi' \leftarrow \{\phi \in \Phi : Z \in \text{Scope}[\phi]\}$
2 $\Phi'' \leftarrow \Phi - \Phi'$
3 $\psi \leftarrow \prod_{\phi \in \Phi'} \phi$
4 $\tau \leftarrow \sum_Z \psi$
5 **return** $\Phi'' \cup \{\tau\}$

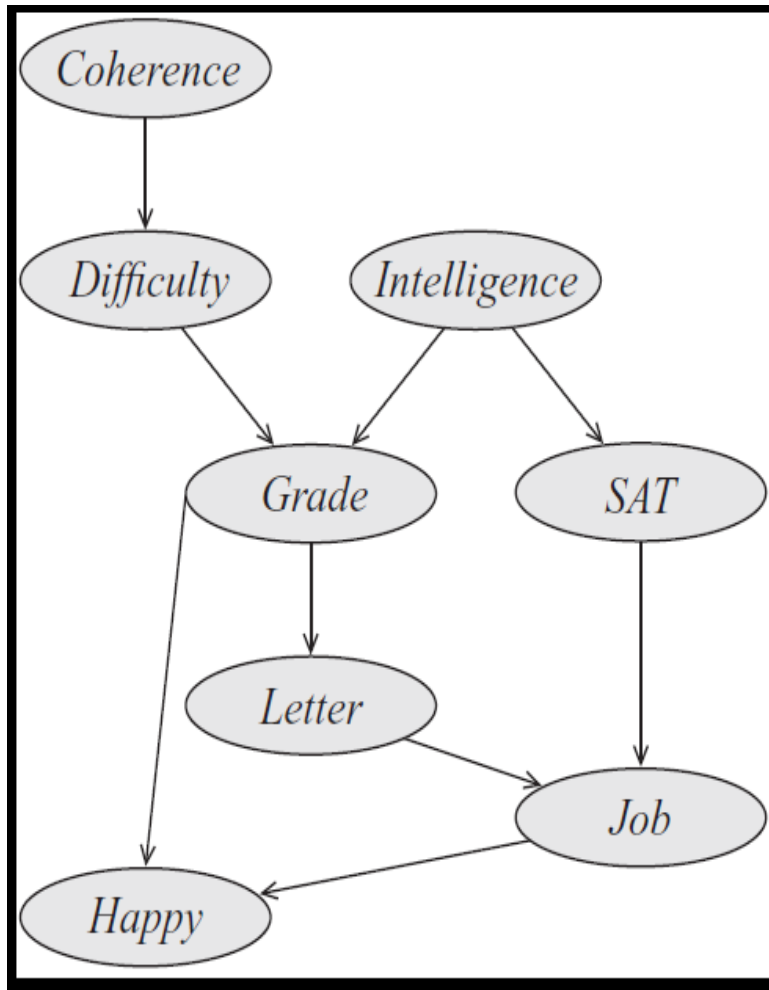
Note: A factor is used
only once

Theorem 9.5

- VE Algorithm can also be applied to general graphs
 - Example to follow
- \mathbf{X} is a set of variables, Φ is a set of factors whose scope is $\subseteq \mathbf{X}$
- Let $\mathbf{Y} \subset \mathbf{X}$ be a set of query variables
- Let $\mathbf{Z} = \mathbf{X} - \mathbf{Y}$ (set of other variables, to be eliminated)
- For any ordering \prec over \mathbf{Z} , Sum-Product-VE (Φ, \prec, \mathbf{Z}) returns
$$\phi^*(\mathbf{Y}) = \sum_{\mathbf{Z}} \prod_{\phi \in \Phi} \phi$$
- If Φ is the set of all factors (one factor associated with each variable X_i , derived from the CPD of X_i) then above gives $P(\mathbf{Y})$.
- Same algorithm also applies to Markov Networks
 - Initial factors are clique potentials
 - If original factors are not normalized, we also need to compute a partition function.

VE Applied to General Graph (Ex 9.1)

Goal is to compute $P(J)$



$$\begin{aligned} P(C, D, I, G, S, L, J, H) &= P(C)P(D | C)P(I)P(G | I, D)P(S | I) \\ &\quad P(L | G)P(J | L, S)P(H | G, J) \\ &= \phi_C(C)\phi_D(D, C)\phi_I(I)\phi_G(G, I, D)\phi_S(S, I) \\ &\quad \phi_L(L, G)\phi_J(J, L, S)\phi_H(H, G, J). \end{aligned}$$

Elimination Steps

- Use elimination ordering C, D, I, H, G, S, L
- 1. Eliminate C

$$\begin{aligned}\psi_1(C, D) &= \phi_C(C) \cdot \phi_D(D, C) \\ \tau_1(D) &= \sum_C \psi_1.\end{aligned}$$

- 2. Eliminate D: Note $\phi_D(D, C)$ already eliminated

$$\begin{aligned}\psi_2(G, I, D) &= \phi_G(G, I, D) \cdot \tau_1(D) \\ \tau_2(G, I) &= \sum_D \psi_2(G, I, D).\end{aligned}$$

- 3. Eliminate I:

$$\begin{aligned}\psi_3(G, I, S) &= \phi_I(I) \cdot \phi_S(S, I) \cdot \tau_2(G, I) \\ \tau_3(G, S) &= \sum_I \psi_3(G, I, S).\end{aligned}$$

Elimination Steps

- 4. Eliminate H

$$\begin{aligned}\psi_4(G, J, H) &= \phi_H(H, G, J) \\ \tau_4(G, J) &= \sum_H \psi_4(G, J, H).\end{aligned}$$

Note: that τ_4 is $\equiv 1$ as we are just computing $\sum_H P(H|G, J)$ so this step serves little purpose but complicates the next elimination

- 5. Eliminate G

$$\begin{aligned}\psi_5(G, J, L, S) &= \tau_4(G, J) \cdot \tau_3(G, S) \cdot \phi_L(L, G) \\ \tau_5(J, L, S) &= \sum_G \psi_5(G, J, L, S).\end{aligned}$$

- 6. Eliminate S

$$\begin{aligned}\psi_6(J, L, S) &= \tau_5(J, L, S) \cdot \phi_J(J, L, S) \\ \tau_6(J, L) &= \sum_S \psi_6(J, L, S).\end{aligned}$$

- 7. Eliminate L

$$\begin{aligned}\psi_7(J, L) &= \tau_6(J, L) \\ \tau_7(J) &= \sum_L \psi_7(J, L).\end{aligned}$$

Table Summarizing Elimination for $P(J)$

| Step | Variable eliminated | Factors used | Variables involved | New factor |
|------|---------------------|--|--------------------|-------------------|
| 1 | C | $\phi_C(C), \phi_D(D, C)$ | C, D | $\tau_1(D)$ |
| 2 | D | $\phi_G(G, I, D), \tau_1(D)$ | G, I, D | $\tau_2(G, I)$ |
| 3 | I | $\phi_I(I), \phi_S(S, I), \tau_2(G, I)$ | G, S, I | $\tau_3(G, S)$ |
| 4 | H | $\phi_H(H, G, J)$ | H, G, J | $\tau_4(G, J)$ |
| 5 | G | $\tau_4(G, J), \tau_3(G, S), \phi_L(L, G)$ | G, J, L, S | $\tau_5(J, L, S)$ |
| 6 | S | $\tau_5(J, L, S), \phi_J(J, L, S)$ | J, L, S | $\tau_6(J, L)$ |
| 7 | L | $\tau_6(J, L)$ | J, L | $\tau_7(J)$ |

Table 9.1 A run of variable elimination for the query $P(J)$

Another Elimination Order

- Note: order affects the size of factors generated, and hence the complexity of the computation.

| Step | Variable eliminated | Factors used | Variables involved | New factor |
|------|---------------------|---|--------------------|-------------------------|
| 1 | G | $\phi_G(G, I, D), \phi_L(L, G), \phi_H(H, G, J)$ | G, I, D, L, J, H | $\tau_1(I, D, L, J, H)$ |
| 2 | I | $\phi_I(I), \phi_S(S, I), \tau_1(I, D, L, S, J, H)$ | S, I, D, L, J, H | $\tau_2(D, L, S, J, H)$ |
| 3 | S | $\phi_J(J, L, S), \tau_2(D, L, S, J, H)$ | D, L, S, J, H | $\tau_3(D, L, J, H)$ |
| 4 | L | $\tau_3(D, L, J, H)$ | D, L, J, H | $\tau_4(D, J, H)$ |
| 5 | H | $\tau_4(D, J, H)$ | D, J, H | $\tau_5(D, J)$ |
| 6 | C | $\tau_5(D, J), \phi_C(C), \phi_D(D, C)$ | D, J, C | $\tau_6(D, J)$ |
| 7 | D | $\tau_6(D, J)$ | D, J | $\tau_7(J)$ |

Table 9.2 A different run of variable elimination for the query $P(J)$

Complexity and how to choose elimination order will be discussed a bit later.

Next Class

- Read sections 9.3.2, 9.4, 10.1 of the KF book

Just for formatting

- Message from \mathbf{C}_i to \mathbf{C}_j is given by
 - V_T vertices of T be ε_T the edges
 - If X is in \mathbf{C}_i and also in \mathbf{C}_j then X is also in every cluster in the path between \mathbf{C}_i and \mathbf{C}_j .
 - Implies that $\mathbf{S}_{i,j} = \mathbf{C}_i \cap \mathbf{C}_j$.
 - **Family preserving:** Each factor ϕ must be associated with some cluster, say \mathbf{C}_i , called $\alpha(\phi)$. $\text{scope}[\phi] \subseteq \mathbf{C}_i$
 - Each edge between two nodes, say \mathbf{C}_i and \mathbf{C}_j , is associated with a set of nodes, called a sepset, $\mathbf{S}_{i,j}$, $\mathbf{S}_{i,j} \subseteq \mathbf{C}_i \cap \mathbf{C}_j$.
- $\delta_{i \rightarrow j}^\Sigma$
- $P(D) = \sum_C \sum_B \sum_A P(A, B, C, D)$
- $D \perp J$
- ϕ