

## 1 Question 1

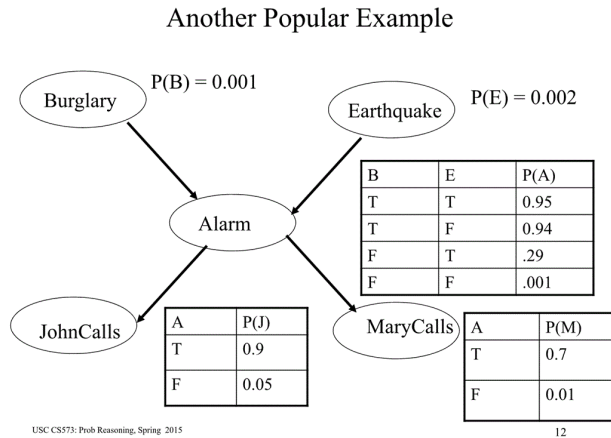
Exercise 3.5 from KF book; parts b,d,f,h only

Solution:

1. b)  $P(d^1|t^0) > P(d^1)$ . The interaction is through the active trail  $D \rightarrow C \rightarrow T$ . Intuitively, a good diet is more likely if we know that the person has good cholesterol levels.
2. d)  $P(c^1|f^0) = P(c^1)$ . No active trails between  $C$  and  $F$  given  $f^0$ . ( $F \perp C$ ).
3. f)  $P(c^1|h^0, f^0) = P(c^1|h^0)$ . No active trails. ( $F \perp C|H$ ).
4. h)  $P(d^1|e^1, f^0, w^1) > P(d^1|e^1, f^0)$ . Active trail of interaction between  $W$  and  $D$  by  $D \rightarrow W$ . Intuitively, a good diet is more likely given that we know the person's weight is healthy.

## 2 Question 2

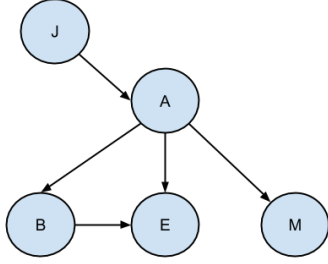
Consider the "Alarm" network given in Lecture 3. Derive a minimal I-map for this network if we choose ordering J,A,B,M,E.



Solution:

Independencies encoded in the graph:

Notice that the edge  $B \rightarrow E$  is necessary because otherwise  $(B \perp E|A)$ , which does not hold.



### 3 Question 3

We define the following properties for a set of independencies:

- **Strong Union:**

$$(\mathbf{X} \perp \mathbf{Y}|\mathbf{Z}) \implies (\mathbf{X} \perp \mathbf{Y}|\mathbf{Z}, \mathbf{W}) \quad (1)$$

- **Transitivity:**

$$\neg(\mathbf{X} \perp \mathbf{A}|\mathbf{Z}) \wedge \neg(\mathbf{A} \perp \mathbf{Y}|\mathbf{Z}) \implies \neg(\mathbf{X} \perp \mathbf{Y}|\mathbf{Z}) \quad (2)$$

Prove that if  $\mathcal{I} = \mathcal{I}(\mathcal{H})$  for some Markov network  $\mathcal{H}$ , then  $\mathcal{I}$  satisfies strong union and transitivity.

Solution:

*Proof. Strong Union:* Since  $\mathcal{I} = \mathcal{I}(\mathcal{H})$ , separation in  $\mathcal{H}$  is equivalent to independence statements in distribution  $P$ . In other words, if  $\mathcal{I}$  is the set of independencies that hold in distribution  $P$ , and we know  $\mathcal{I}(\mathcal{H}) = \{sep_{\mathcal{H}}(\mathbf{X}; \mathbf{Y}|\mathbf{Z})\}$ , we have that  $\{sep_{\mathcal{H}}(\mathbf{X}; \mathbf{Y}|\mathbf{Z})\} = \mathcal{I}$ . Notice that we are given  $(\mathbf{X} \perp \mathbf{Y}|\mathbf{Z})$ . This implies that there are no active trails between  $\mathbf{X}$  and  $\mathbf{Y}$  given  $\mathbf{Z}$  in  $\mathcal{H}$ . Since the definition of separation in a Markov network is monotonic in  $\mathbf{Z}$ , we know that, if  $sep_{\mathcal{H}}(\mathbf{X}; \mathbf{Y}|\mathbf{Z})$  holds, then  $sep_{\mathcal{H}}(\mathbf{X}; \mathbf{Y}|\mathbf{Z}')$  holds for any  $\mathbf{Z}' \supset \mathbf{Z}$ .  $\{\mathbf{Z}, \mathbf{W}\} \supset \mathbf{Z}$ , and the result follows. Intuitively, observing extra evidence in Markov networks can only cause more trails to

be blocked. It cannot unblock trails already blocked. Since  $\mathbf{X}$  and  $\mathbf{Y}$  were already separated given  $\mathbf{Z}$ , observing  $\mathbf{W}$  as well can't un-separate them. Notice that since separation is exactly equivalent to  $\mathcal{I}$ , this result holds in  $\mathcal{I}$ .  $\square$

*Proof. Transitivity:*  $\neg(\mathbf{X} \perp A|\mathbf{Z})$  means that there exists an active trail between some  $X \in \mathbf{X}$  and  $A$  in  $\mathcal{H}$ .  $\neg(A \perp \mathbf{Y}|\mathbf{Z})$  means that there exists an active trail between  $A$  and some  $Y \in \mathbf{Y}$  in  $\mathcal{H}$ . Since  $A$  is not in  $\mathbf{Z}$ , there must exist an active trail from some  $X \in \mathbf{X}$  to some  $Y \in \mathbf{Y}$  given evidence  $\mathbf{Z}$  that goes through variable  $A$ , which directly implies  $\neg(\mathbf{X} \perp \mathbf{Y}|\mathbf{Z})$ . Since separation is again equivalent to  $\mathcal{I}$ , we have shown the desired transitivity result.  $\square$

## 4 Question 4

Show that we can represent any Gibbs distribution as a log-linear model, as defined in definition 4.15. Solution:

A Gibbs distribution can be written as:

$P(X_1, \dots, X_m) = \frac{1}{Z} \prod_{i=1}^m \phi_i(\mathbf{D}_i)$ . If we let  $\epsilon_i(\mathbf{D}_i) = -\ln(\phi_i(\mathbf{D}_i))$ , and  $\phi_i(\mathbf{D}_i) = \exp(-\epsilon_i(\mathbf{D}_i))$ , we see that

$P(X_1, \dots, X_m) = \frac{1}{Z} \exp(-\sum_{i=1}^m \epsilon_i(\mathbf{D}_i))$ . We are given that a feature is a function  $f_i(\mathbf{D}_i)$  is a function from  $Val(\mathbf{D}) \rightarrow \mathbb{R}$ . If we let  $w_i = 1$  and let  $f_i(\mathbf{D}_i) = \epsilon_i(\mathbf{D}_i)$  for all  $i$ , we have shown that any Gibbs distribution can be converted into a log-linear model. Notice that this substitution is valid since  $\epsilon_i(\mathbf{D}_i)$  is also a function from  $Val(\mathbf{D}_i) \rightarrow \mathbb{R}$ . An alternative solution would be to create one weight/feature pair for each table entry  $\mathbf{d}_i$  in each factor. The weight would be equal to  $-\ln(\phi_i(\mathbf{d}_i))$ , and the feature would be an indicator function in the form  $\mathbf{1}\{\mathbf{D}_i = \mathbf{d}_i\}$ . Once such indicator feature/weight pair would exist for every possible  $\mathbf{d}_i$  in each factor. Thus, we could represent any Gibbs distribution as a log-linear model.

## 5 Question 5

This question is a simplified version of Exercise 5.13 in KF book. It starts with simplified BN20 model as in Fig. 5.1.C; for simplicity, we consider a case with only two parent and two child nodes as shown below. Now suppose that we have the observation that  $F_1 = 0$ , but result of  $F_2$  are still pending. We can encode this situation in a modified BN20 network  $B'$  that

has same structure as  $B$ , except  $F_1$  is omitted from the network. Show that the posterior distribution  $P(D_1, D_2 | F_2, F_1 = 0)$  can be encoded using  $B'$  and specify parameters of  $B'$  in terms of parameters of  $B$ .

*Hint: you can make use of proposition 5.3 without proof. For re-parameterization of  $B'$ , consider changing the prior distributions of disease nodes, or the  $\lambda$  values on the links, or both.*

Solution:

$$\begin{aligned} P(D_1, D_2 | F_1, F_2) &= P(D_1, D_2, F_1, F_2) / P(F_1, F_2) \\ &= (P(F_1, F_2 | D_1, D_2) P(D_1) P(D_2)) / P(F_1, F_2) \\ &= (P(F_1 = 0 | D_1, D_2) P(F_2 | D_1, D_2) P(D_1) P(D_2)) / P(F_1, F_2) \end{aligned}$$

$$\begin{aligned} \text{In } B', P(D_1, D_2 | F'_2) &= (P(F'_2 | D_1, D_2) P(D_1) P(D_2)) / P(F'_2) \\ \text{Let } P(F'_2 | D_1, D_2) &= P(F_1 = 0 | D_1, D_2) P(F_2 | D_1, D_2) \\ &= (1 - \lambda_{1,0})(1 - \lambda_{1,1})^{d_1} (1 - \lambda_{1,2})^{d_2} P(F_2 | D_1, D_2) \\ P(F'_2 = 0 | D_1, D_2) &= \\ &= (1 - \lambda_{1,0})(1 - \lambda_{1,1})^{d_1} (1 - \lambda_{1,2})^{d_2} \\ &= (1 - \lambda_{2,0})(1 - \lambda_{2,1})^{d_1} (1 - \lambda_{2,2})^{d_2} \\ &= (1 - (\lambda_{1,0} + \lambda_{2,0} - \lambda_{1,0}\lambda_{2,0}))(1 - (\lambda_{1,1} + \lambda_{2,1} - \lambda_{1,1}\lambda_{2,1}))^{d_1} \\ &= (1 - (\lambda_{1,2} + \lambda_{2,2} - \lambda_{1,2}\lambda_{2,2}))^{d_2} \end{aligned}$$

$$\begin{aligned} \lambda'_0 &= \lambda_{1,0} + \lambda_{2,0} - \lambda_{1,0}\lambda_{2,0} \\ \lambda'_1 &= \lambda_{1,1} + \lambda_{2,1} - \lambda_{1,1}\lambda_{2,1} \\ \lambda'_2 &= \lambda_{1,2} + \lambda_{2,2} - \lambda_{1,2}\lambda_{2,2} \end{aligned}$$

Here we have re-parameterized the network  $B'$  in terms of the parameters of  $B$  and have shown the given posterior can be encoded in terms of  $B'$ .