



Lecture 19

# **GPIO**

## **General Purpose Input/Output**

Assignment Project Exam Help

<https://tutorcs.com>

WeChat: cstutorcs

**Bad joke of the day:**

**Why are assembly programmers always wet?**

**Because they work below C-level**

# Solution to Quiz 5



**Task:** Write a subroutine that checks whether a given integer  $n$  is prime

```
-----  
; Subroutine: is_prime  
; Inputs: unsigned word n in R6 -- returned unchanged  
;  
; Output: binary value in R13 -- R13 = 1 if n is prime  
;         R13 = 0 if n is composite  
;  
; All other core registers in R4-R15 unchanged  
; Subroutine does not access addressed memory locations  
-----
```

Assignment Project Exam Help

<https://tutorcs.com>

WeChat: cstutorcs

## Approach:

- Check if  $n$  is divisible by 2, 3, 4, ...,  $n-1$
- If it is divisible by any of these numbers, the number is composite
- If not divisible, the number is prime
- Works only if  $n > 3$ , the cases  $n = 0, 1, 2$  need separate logic

# Solution to Quiz 5 v.1



**is\_prime\_1:**

```
push    R5
push    R12

clr.w   R13

cmp.w   #2, R6
jlo     ret_from_is_prime_1    ; if n<2 not prime
jne     larger_than_two       ; if (n>=2 and n!= 2) check n
mov.w   #1, R13                ; n=2 is prime
jmp     ret_from_is_prime_1
```

**larger\_than\_two:**

```
mov.w   #2, R5                ; start checking for divisibility by 2
```

**check\_divisibility\_1:**

```
call    #is_divisible
tst.w   R12                    ; if divisible, then R12==1, n is composite
jnz     ret_from_is_prime_1

inc.w   R5                     ; check divisibility by next integer
cmp.w   R6, R5                 ; until n-1
jne     check_divisibility_1
```

```
; We land here only if the number is prime
mov.w   #1, R13
```

**ret\_from\_is\_prime\_1:**

```
pop     R12
pop     R5
ret
```

Assignment Project Exam Help

<https://tutorcs.com>

WeChat: cstutorcs

**Note:** is\_divisible modifies R12  
Need to push/pop R12!!

# Solution to Quiz 5



**What about algorithmic complexity?** How many calls to `is_divisible`?

Depends on the nature of the number:

- If  $n$  is even, then only one call:  $n$  is divisible by 2
- If  $n$  is an odd multiple of 3, then two calls: check for divisibility by 2 and 3
- ...
- If  $n$  is prime, then  $n-2$  calls to `is_divisible` with 2, 3, ...,  $n-1$

Assignment Project Exam Help

<https://tutorcs.com>

How can we speed things up?

WeChat: cstutorcs

- No need to check  $n > 2$  if it is an even number `bit.w #BIT0, R6`
- For odd  $n$ , it suffices to check divisibility by odd numbers  $\{3, 5, \dots, n-2\}$
- For  $n > 4$ , no need to check for factors  $> n/2$  check only  $\{3, 5, \dots, \text{floor}(n/2)\}$
- Actually no need to check for factors  $> \text{sqrt}(n)$

# Solution to Quiz 5 v.2



```
;  
; Somewhat improved efficiency  
; Test only odd n for divisibility by odd integers in {3, 5, ..., (n-1)/2}  
; Note (n+1)/2 > sqrt(n) for all n>=3  
; takes quite some time to run  
is_prime_2:
```

```
push    R5  
push    R7  
push    R12
```

```
;  
; n is more likely not prime: Pr(n is prime) ~ 1/ln(n)  
clr.w    R13
```

```
cmp.w    #3, R6                ; n=3 is prime  
jeq       found_prime  
cmp.w    #2, R6                ; n=2 is prime  
jeq       found_prime
```

```
jlo       ret_from_is_prime_2    ; if n<2 not prime  
jne       larger_than_two_2      ; if (n>=2 and n!= 2) check n
```

```
mov.w    #1, R13  
jmp       ret_from_is_prime_2
```

```
larger_than_two_2:
```

```
;  
; if n>2 is even it is not prime  
bit.w    #BIT0, R6  
jnc       ret_from_is_prime_2
```

Assignment Project Exam Help

<https://tutorcs.com>

WeChat: cstutorcs

# Solution to Quiz 5 v.2



```
; test divisibility by odd numbers only
mov.w  #3, R5
mov.w  R6, R7          ; R7=n
inc.w  R7              ; R7=n+1
clrc                   ; unsigned divide by 2 using cleared carry bit
rrc.w  R7              ; R7=(n+1)/2
```

check\_divisibility:

```
; check if n is divisible by 3, 5, 7, 9, ..., n-1
call   #is_divisible
tst.w  R12
jnz    ret_from_is_prime_2 ; found a factor, n is composite

incd.w R5              ; next odd number
cmp.w  R7, R5          ; will stop checking at R7 = (n+1)/2
; this works because both R5 and R6 are odd
jlo    check_divisibility
```

; We land here only if the number is prime

found\_prime:

```
mov.w  #1, R13
```

ret\_from\_is\_prime\_2:

```
pop    R12
pop    R7
pop    R5
ret
```

~4 times faster for prime numbers

# Learning From Quiz 4



How can we *improve* following code?

Logic is correct

```
69 is_divisible:
70     push    R5
71     push    R6
72
73     clr.w   R12
74
75 check:
76     cmp.w   R5, R6
77     jlo     found_remainder
78     sub.w   R5, R6
79     jhs     check
80
81 found_remainder:
82     tst.w   R6
83     jnz     ret_from_is_divisib
84
85     mov.w   #1, R12
86
87 ret_from_is_divisible:
88     pop     R6
89     pop     R5
90     ret
91
```

Assignment Project Exam Help

<https://tutorcs.com>

WeChat: cstutorcs

No need to push/pop R5  
since it is not modified

# Learning From Quiz 4



How can we *improve* following code?

Logic is correct

```
67 is_divisible:
68     push    R6
69     clr.w   R12
70
71 check_R6:
72     tst.w   R6
73     jz      yes_divisible
74
75     sub.w   R5, R6
76     cmp.w   R5, R6
77     jlo     ret_is_divisible
78     jz      yes_divisible
79     jhs     check_R6
80
81 yes_divisible:
82     add.w   #1, R12
83     jmp     ret_is_divisible
84
85 ret_is_divisible:
86     pop     R6
87     ret
```

Assignment Project Exam Help

<https://tutorcs.com>

WeChat: cstutorcs

**No need:** sub.w already sets the status bits!!

**No need to jump**  
ret\_is\_divisible is the next line already!!!



# Learning From Quiz 4



How can we *improve* following code?

```
81 not_divisible:
82     add.w    #0, R12
83     pop      R6
84     jmp      ret_to_main
85
86 divisible:
87     add.w    #1, R12
88     pop      R6
89     jmp      ret_to_main
90
91 ret_to_main:
92     ret
93
```

← No need:  $x + 0 = x$

Assignment Project Exam Help

<https://tutorcs.com>

WeChat: cstutorcs

← No need to jump to the next line

No need to repeat lines 83-84

```
divisible:
    add.w    #1, R12

not_divisible:
    pop      R6
    ret
```

# Learning From Quiz 4



What is the issue with this code?

```
65 is_divisible:
66     push        R6
67     clr.w       R12
68
69     cmp.w       R5, R6
70     jlo         test
71
72 subtract:
73     sub.w       R5, R6
74     jmp         is_divisible
75
76 test:
77     cmp.w       #0, R6
78     jne         subtract
79
80     mov.w       #1, R12
81
82 ret_main:
83     pop         R6
84     ret
85
--
```

← Pushes to stack with each iteration!!!

Assignment Project Exam Help

<https://tutorcs.com>

WeChat: cstutorcs

← Pops only once  
(R6) -> PC -> crash

# This is a Mistake



How do we fix it?

```
65 is_divisible:
66     push    R6
67     clr.w   R12
68
69     cmp.w   R6, R5
70     jlo     test
71
72 subtract:
73     sub.w   R5, R6
74     jmp     is_divisible
75
76 test:
77     cmp.w   #0, R6
78     jne     subtract
79
80     mov.w   #1, R12
81
82 ret_main:
83     pop     R6
84     ret
85
--
```

```
65 is_divisible:
66     push    R6
67     clr.w   R12
68
69     compare R6, R5
70     cmp.w   R6, R5
71     jlo     test
72
73 subtract:
74     sub.w   R5, R6
75     jmp     compare
76
77 test:
78     cmp.w   #0, R6
79     jne     subtract
80
81     mov.w   #1, R12
82
83 ret_main:
84     pop     R6
85     ret
```

Assignment Project Exam Help

<https://tutorcs.com>

WeChat: cstutorcs

# How MCUs are used in the Real-World



Not the way we have used them so far: we have only used the CPU and memory (RAM/FRAM) of our MCU to do basic data manipulations

When treated like this, the MCU is a very limited computer:

- No real input or interaction with the user/environment
- We defined (hardcoded) data in RAM/FRAM as input to some logic
- Output is limited too: we peek into registers using CCS to view the input

Assignment Project Exam Help

<https://tutorcs.com>

An MCU is intended to do much more

WeChat: cstutorcs

- Interact with the user / environment / other MCUs
- **Input** from buttons, sensors, other MCUs
- **Output** via displays, motors (motor drivers), actuators, control circuitry ...

All input / output to the MCU is through **Input/Output Pins**

# The MSP430FR6989 Launchpad



This part enables interface to a PC and enables debugging

eZ-FET emulator

**Headers** with access to selected pins connect I/O devices e.g., sensors, motors, logic analyzer...

Assignment Project Exam Help

<https://tutorsof.com>

Web content

MSP430FR6989IPZ

100 Pins

More headers

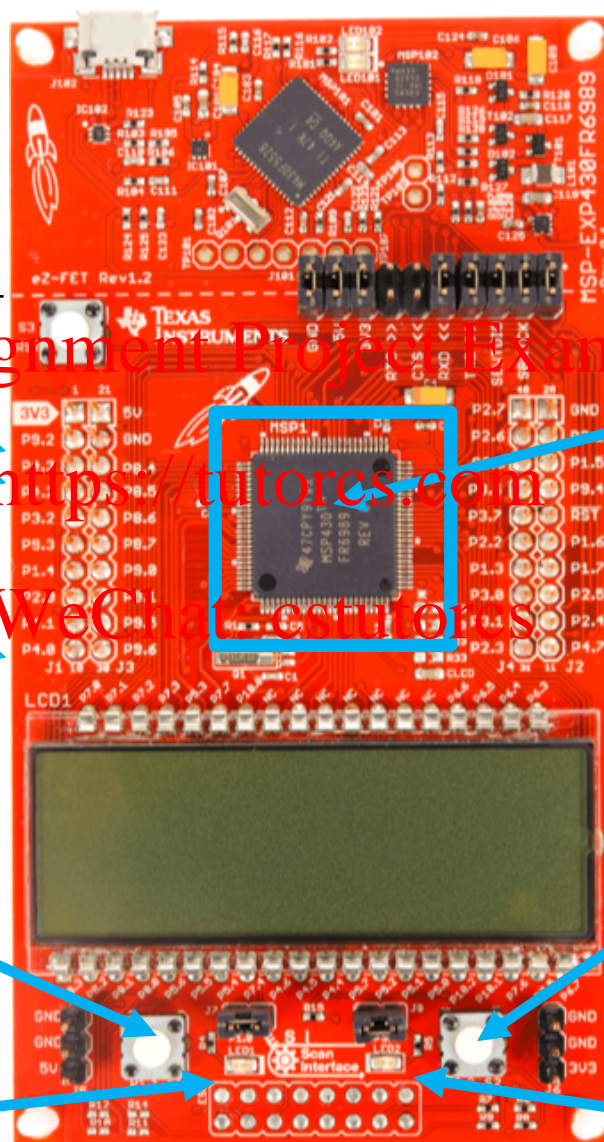
Only I/O we will use

Push Button S1

Push Button S2

Red LED

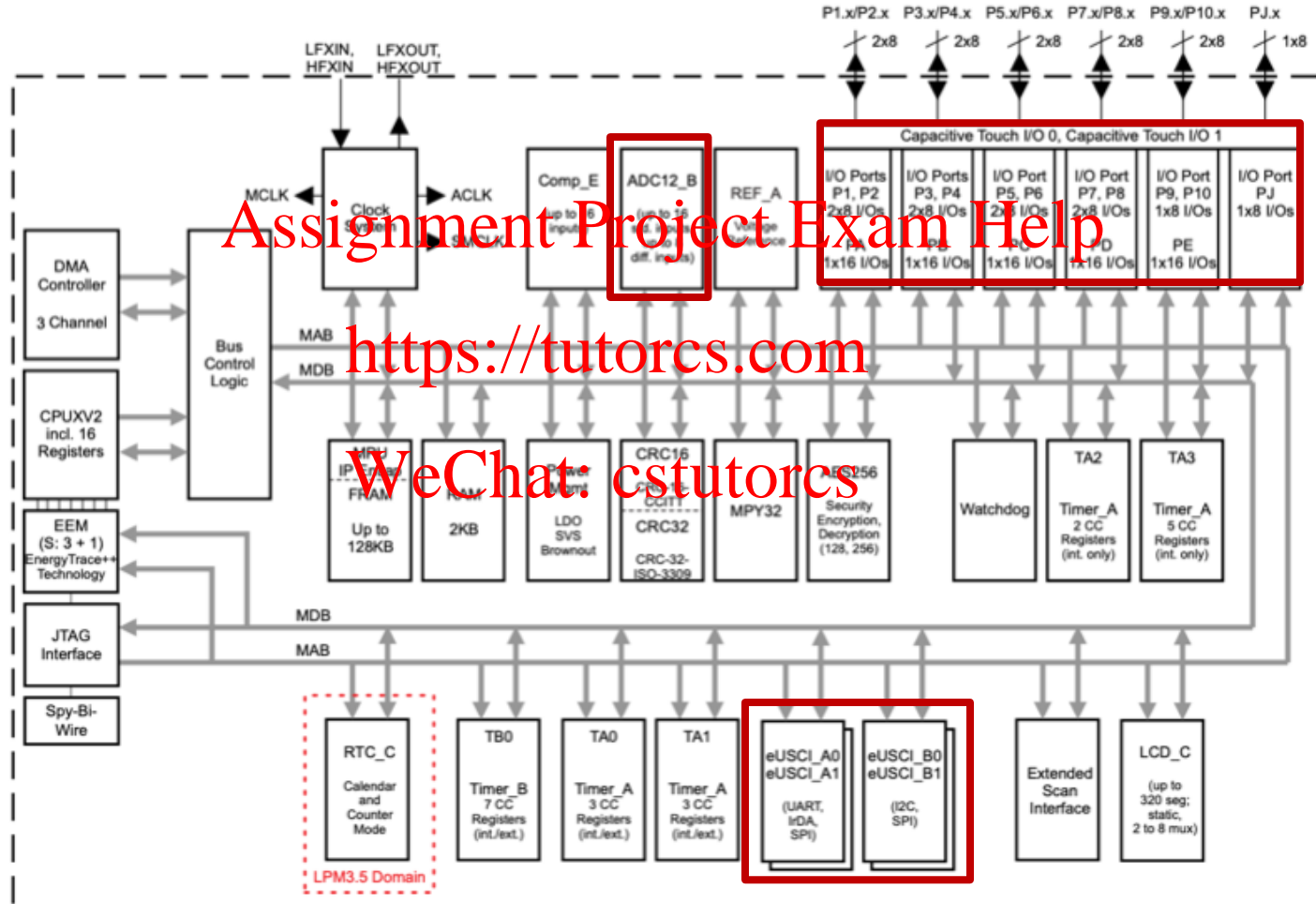
Green LED





# MSP430FR6989 I/O Options

## Ports for GPIO



Copyright © 2016, Texas Instruments Incorporated

# I/O Through Standard Protocols



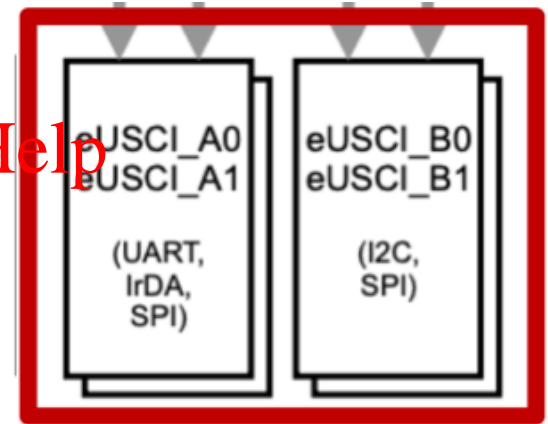
The **enhanced Universal Serial Communication Interfaces** (**eUSCI\_A** and **eUSCI\_B**) support several standard protocols for I/O

- **Serial Peripheral Interface (SPI)**
- **Inter Integrated Circuit (I<sup>2</sup>C, I2C, IIC)**
- **Universal Asynchronous Receiver Transmitter (UART)**

Assignment Project Exam Help

<https://tutorcs.com>

WeChat: cstutorcs



How to use?

- Dedicated pins for I/O
  - Registers for configuration
  - Devices that use these protocols
  - e.g., SPI sensors, I<sup>2</sup>C sensors, I<sup>2</sup>C motor drivers etc.
- All the details in **slau367p.pdf**  
Posted to Carmen under Resources

# GPIO Ports P1 – P10



Our MCU has 10 **General Purpose Input Output (GPIO) Ports P1 – P10**  
TI refers to these as **Digital I/O ports** (or PA – PJ)

- Each port has **8 pins**
- Pins are labeled as **Px.y** – **x** is the port number, **y** is the pin number

**Assignment Project Exam Help**

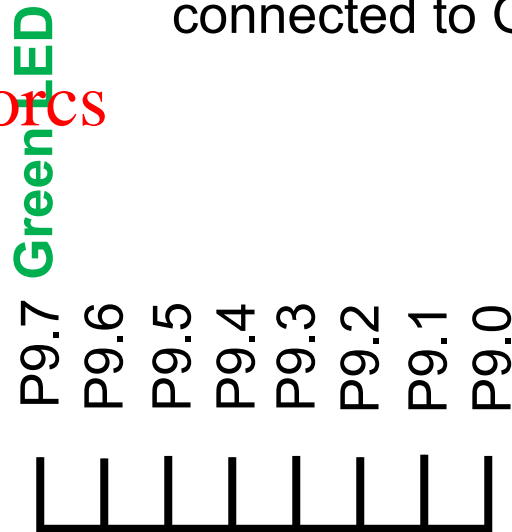
<https://tutorcs.com>

WhatsApp: [tutorcs](https://tutorcs.com)

Push buttons and LEDs are connected to GPIO pins



Pins of Port 1



Pins of Port 9



## 80 pins connected to GPIO Ports



# MSP430FR6989IPZ Pinout



Pins are **multiplexed**  
many are connected to  
multiple peripherals and need  
to be configured by selecting  
one functionality

Assignment Project Exam Help

<https://tutorcs.com>

Green LED

WeChat: cstutorcs

Red LED

Push Buttons S1 & S2

<input type="checkbox"/> P10.0/SMCLK/S4	<input type="checkbox"/> P9.7/ESIC3/A15/C15
<input type="checkbox"/> P4.7/UCB1SOMI/UCB1SCL/TA1.2/S5	<input type="checkbox"/> P9.6/ESIC2/A14/C14
<input type="checkbox"/> P4.6/UCB1SIMO/UCB1SDA/TA1.1/S6	<input type="checkbox"/> P9.5/ESIC1/A13/C13
<input type="checkbox"/> P4.5/UCB1CLK/TA1.0/S7	<input type="checkbox"/> P9.4/ESIC0/A12/C12
<input type="checkbox"/> P4.4/UCB1STE/TA1CLK/S8	<input type="checkbox"/> P9.3/ESICH3/ESITEST3/A11/C11
<input type="checkbox"/> P5.7/UCA1STE/TB0CLK/S9	<input type="checkbox"/> P9.2/ESICH2/ESITEST2/A10/C10
<input type="checkbox"/> P5.6/UCA1CLK/S10	<input type="checkbox"/> P9.1/ESICH1/ESITEST1/A9/C9
<input type="checkbox"/> P5.5/UCA1SOMI/UCA1RXD/S11	<input type="checkbox"/> P9.0/ESICH0/ESITEST0/A8/C8
<input type="checkbox"/> P5.4/UCA1SIMO/UCA1TXD/S12	<input type="checkbox"/> P1.0/TA0.1/DMAE0/RTCCLK/A0/C0/VREF-/VREF-
<input type="checkbox"/> AVSS2	<input type="checkbox"/> P1.1/TA0.2/TA1CLK/COUT/A1/C1/VREF+/VREF+
<input type="checkbox"/> PJ.5/LFXOUT	<input type="checkbox"/> P1.2/TA1.1/TA0CLK/COUT/A2/C2
<input type="checkbox"/> PJ.4/LFXIN	<input type="checkbox"/> P1.3/TA1.2/ESITEST4/A3/C3
<input type="checkbox"/> AVSS1	<input type="checkbox"/> P8.7/A4/C4
<input type="checkbox"/> PJ.6/HFXIN	<input type="checkbox"/> P8.6/A5/C5
<input type="checkbox"/> PJ.7/HFXOUT	<input type="checkbox"/> P8.5/A6/C6
<input type="checkbox"/> AVSS3	<input type="checkbox"/> P8.4/A7/C7
<input type="checkbox"/> AVCC1	<input type="checkbox"/> DVCC2
<input type="checkbox"/> ESIC0	<input type="checkbox"/> DVSS2
<input type="checkbox"/> ESIC1	
<input type="checkbox"/> ESIDVSS	

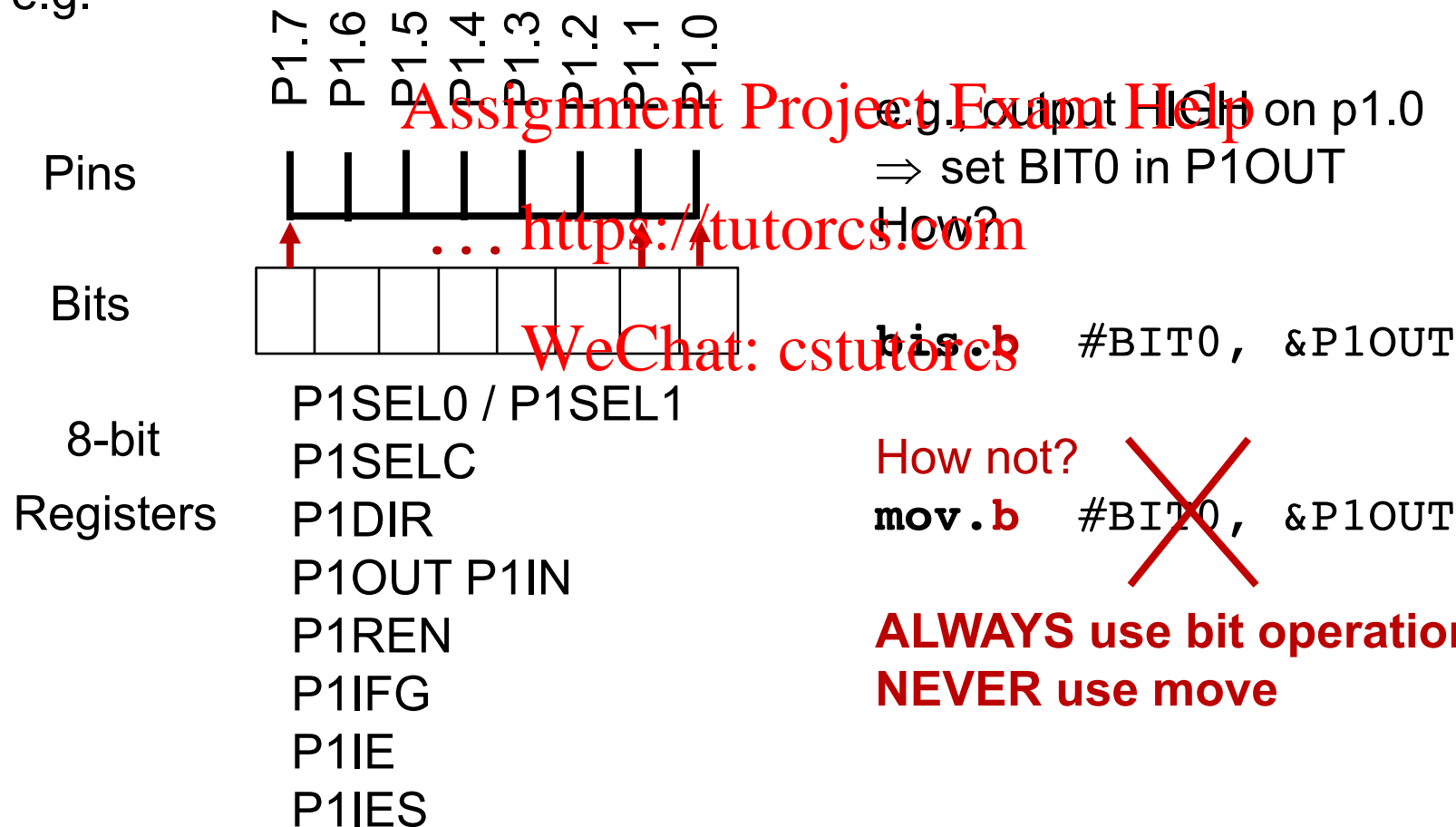
# Registers Controlling GPIO Ports



Each port is configured and controlled by a set of **8-bit registers**

**Px.y** is controlled by **bit y** in the register corresponding to **port x**

e.g.



# Addressing GPIO Port Registers



`bic.b` `#BIT0,` `&P1OUT`  
`bis.b` `#BIT0,` `&P1OUT`

byte immediate absolute (rather than symbolic mode)

Assignment Project Exam Help

<https://tutorcs.com>

All addresses are defined in the header file `msp430fr69891.h`

WeChat: [cstutorcs](#)

```
#define P1IN      (PAIN_L)      /* Port 1 Input */
#define P1OUT     (PAOUT_L)     /* Port 1 Output */
#define P1DIR     (PADIR_L)     /* Port 1 Direction */
#define P1REN     (PAREN_L)     /* Port 1 Resistor Enable */
#define P1SEL0    (PASEL0_L)    /* Port 1 Selection 0 */
#define P1SEL1    (PASEL1_L)    /* Port 1 Selection 1 */
#define P1SELC    (PASELC_L)    /* Port 1 Complement Selection */
#define P1IES     (PAIES_L)     /* Port 1 Interrupt Edge Select */
#define P1IE      (PAIE_L)      /* Port 1 Interrupt Enable */
#define P1IFG     (PAIFG_L)     /* Port 1 Interrupt Flag */
```

Registers are replicated for all 10 ports: `P2IN`, ..., `P3IN`, ..., `P10IN`,...

# Configuring Px.y: PxSEL0/ PxSEL1



## Function Select Registers: PxSEL0, PxSEL1

Pins are multiplexed

66 ☐ P1.0/TA0.1/DMAE0/RTCCLK/A0/C0/VREF-/VeREF-  
65 ☐ P1.1/TA0.2/TA1CLK/COUT/A1/C1/VREF+/VeREF+

**PxSEL0 and PxSEL1 determine the pin function**

(PxSELC is a helper register to complement between 00 and 11)

Table 12-2. I/O Function Selection

PxSEL1	PxSEL0	I/O Function
0	0	General purpose I/O is selected
0	1	Primary module function is selected
1	0	Secondary module function is selected
1	1	Tertiary module function is selected

Default values are **PxSEL0.y = 0** and **PxSEL1.y = 0**

⇒ the default function for each pin **Px.y** is **GPIO / Digital I/O**

# Configuring Px.y: PxDIR



## Direction Register: PxDIR

Selects the **direction** of the corresponding I/O pin: i.e., input or output

**PxDIR.y = 0:** Pin **Px.y** is switched to **input** direction (Default)

**PxDIR.y = 1:** Pin **Px.y** is switched to **output** direction

Assignment Project Exam Help

<https://tutorcs.com>

**Shorthand notation:** WeChat: cstutorcs

**PxDIR.y** refers to bit  $y \in \{0, 1, \dots, 7\}$  of register controlling port  $x \in \{1, \dots, 10\}$

**Px.y** refers to pin  $y \in \{0, 1, \dots, 7\}$  of port  $x \in \{1, \dots, 10\}$

# Configuring Px.y: PxIN



## Input Register: PxIN

Bit **PxIN.y** reflects the value of the input signal at pin **Px.y**

**PxIN.y = 0:** Input at pin **Px.y** is LOW

**PxIN.y = 1:** Input at pin **Px.y** is HIGH

Assignment Project Exam Help

<https://tutorcs.com>

**Note: PxIN is a read-only register**

You cannot write to it, attempting to write only results in increased current consumption while the write attempt is active

WeChat: estutorcs

# Configuring Px.y: PxOUT – Role 1



## Output Register: PxOUT

Bit **PxOUT.y** is the value of the output signal at pin **Px.y** when the pin is configured as I/O function, **output** direction

**PxOUT.y = 0:** Output at pin **Px.y** is LOW

**PxOUT.y = 1:** Output at pin **Px.y** is HIGH

## How to write to output?

The red LED is connected to **P1.0**

**P1DIR.0 = 1** selects the pin as **output**

First set the desired output value, then change the direction  
Otherwise, the initial output may be random

~~**bis.b** #BIT0, &P1DIR  
**bis.b** #BIT0, &P1OUT~~

Option 1

**bis.b** #BIT0, &P1OUT  
**bis.b** #BIT0, &P1DIR

Option 2