ADVISE: Evaluating Cloud Service Elasticity Behavior*

Georgiana Copil¹, Demetris Trihinas², Daniel Moldovan¹, Hong-Linh Truong¹,

George Pallis², Schahram Dustdar¹, Marios Dikaiakos²

Abstract. Complex cloud services rely on different elasticity control processes to deal with multi-dimensional elasticity control. Due to the complexity of service structures, deployment strategies, and underlying infrastructure dynamics, such processes are typically designed and applied to similar types of cloud services. However, enforcing an elasticity control process to a cloud service does not always lead to an optimal gain in terms of quality or cost. Therefore, being able, a priori, to estimate and evaluate the relation between cloud service elasticity behavior and elasticity control processes is crucial for determining which elasticity control processes are the most appropriate. In this paper we present ADVISE, a framework for estimating and evaluating cloud service elasticity behavior which can be integrated by cloud providers alongside their elasticity controllers to improve the quality of their elasticity control decisions. Experiments show that ADVISE estimates the expected elasticity behavior, in time, for different cloud services.

1 Introduction

One of the key features driving the popularity of cloud computing is elasticity, that is, the ability of cloud services to acquire and release resources on-demand in response to workloads whose requirements fluctuate over time. From the customers perspective, auto-scaling resources allows users to minimize the execution time of their tasks without exceeding a given budget. From the cloud providers perspective, elasticity provisioning contributes to maximizing their financial gain while keeping their customers satisfied and reducing administrative costs. However, although cloud services are inherently elastic, automatic elasticity provisioning is not a trivial task.

To date, a number of elasticity controllers exist. A simple approach followed by many elasticity controllers, is to monitor the cloud service and when a metric threshold is violated then (de-)provision virtual instances to the deployment. This process may be sufficient for small deployments but when considering largescale distributed cloud services with various inter-dependencies, a much deeper

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understanding of its elasticity behavior is required. For this reason, existing research [1] [2] has identified a number of elasticity control processes to improve the performance and quality of a cloud service while additionally attempting to minimize cost. However, which elasticity control processes are the most appropriate for a cloud service? Both cloud customers and providers can benefit from a service that estimates and evaluates the outcome of enforcing an elasticity control process on a given cloud service runtime snapshot by providing insights such as how the addition of a new instance to a cloud service will affect the throughput of the overall deployment and individually on each part of the cloud service. Therefore, knowing in advance the cloud service elasticity behavior towards an outside stress stimuli can be of great assistance to an elasticity controller, thus, improving the quality of the elasticity control decision.

To improve elasticity control decisions, a wide range of approaches have been proposed which rely on cloud service profiling or learning from historic information [1] [3] [4]. However, these approaches limit the decision process to evaluating only low-level VM metrics (i.e. CPU, memory utilization). Furthermore, current methods do not support multi-grain elasticity decisions where decisions are taken by studying the cloud service's behavior at multiple levels (i.e. elasticity behavior per node, tier, entire cloud service). Additionally, current approaches only evaluate resource utilization rather than considering elasticity as a multi-dimensional property [5] composed of three dimensions (cost, quality and resource elasticity) and therefore, evaluate the relations between the three dimensions. Finally, the existing approaches do not consider the outcome of a decision on the overall cloud service where in many cases, enforcing an elasticity control action to the wrong part of the cloud service, can lead to side effects, such as increasing the cost or decreasing the throughput of the overall cloud service.

In this paper, we focus on addressing the above limitations by introducing ADVISE; a learning framework for evAluating clouD serVIce elaSticity bEhavior. ADVISE can be integrated by cloud providers alongside their elasticity controllers to improve elasticity control decision quality. ADVISE is based on the elasticity control model defined in [6], which we represent at runtime as a runtime dependency graph, and continually update it with information relevant for determining cloud service elasticity behavior. Our second main focus in this paper is to evaluate the effectiveness of the proposed framework. Experiments were conducted on a public cloud platform with a testbed comprised of two different domains of cloud services. Results show that our method outputs the expected elasticity behavior, in time, for different cloud services with a low estimation error rate.

In what follows, we model in Section 2 the relevant information for determining the cloud service behavior, we describe the analysis process in Section 3, present experiments in Section 4 and conclude with Section 5.

2 Cloud Service Structural and Runtime Information

Fig. 1 shows the conceptual cloud service representation proposed in [6], with few extensions (on white background) which help us to determine cloud service

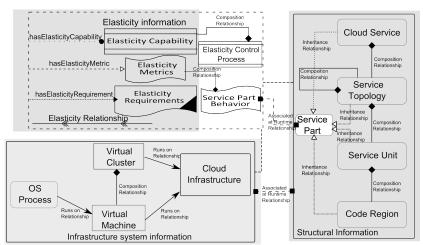


Fig. 1: Elasticity capabilities exposed by different elastic objects

behavior. The cloud service representation contains: (i) Structural Information regarding the cloud service, which describes the architectural structuring of the application to be deployed on the cloud, (ii) Infrastructure System Information, which gives runtime information regarding resources which are used by the service from cloud providers, and (iii) Elasticity Information, which can be associated with both structural information and infrastructure system information for describing elasticity metrics, requirements, and capabilities. The cloud service is composed of several service units [7], which can be grouped together into service topologies, which can at their turn be grouped into other service topologies until we reach the highest level of abstraction, the cloud service level. We refer to service units, service topologies, cloud services and code regions as Service Parts (SP).

The Elasticity Information is composed of elasticity metrics, elasticity requirements, and elasticity capabilities, each of them being associated to different service parts or infrastructure resources. The elasticity capabilities are usually grouped together as Elasticity Control Processes, as detailed in the next subsection, and produce specific elasticity behaviors upon the different SPs, which we model as Service Part Behavior. The Service Part Behavior for a defined period of time [start, end] defined in Equation 3 contains, for a specific SP, all the metrics which are being monitored for the respective SP, in time and is denoted as $Behavior_{SP_i}[start, end]$. The behavior of the cloud service over a defined period of time $Behavior_{CloudService}[start, end]$ is the set of all behaviors of all SPs of the cloud service. The above information is represented through a graph, where the nodes are the concepts shown in Fig. 1 and the edges are the relationships (e.g., Elasticity Relationship, or Associated at Runtime Relationship). This Elasticity Dependency Graph is populated with information both pre-deployment, from sources like cloud service description (e.g., through TOSCA [8]), profiling information, information from cloud

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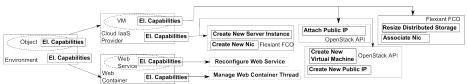


Fig. 2: Elasticity capabilities exposed by different elastic objects

providers, and *during runtime* with information regarding resources used from cloud providers, or elasticity behavior.

$$M^{a}_{SP_{i}}[start, end] = \{M^{a}(t_{j}) | SP_{i} \in ServiceParts, j = \overline{start, end}\}$$
 (1)

$$Behavior_{SP_i}[start, end] = \{M^a_{SP_i}[start, end] | M^a \in Metrics(SP_i)\}$$
 (2)

 $Behavior_{CloudService}[start,end] = \{Behavior_{SP_i}[start,end] | SP_i \in$

ServiceParts(CloudService) (3)

2.1 Elasticity control processes

From above model (Fig. 1), the concepts affecting the most $Behavior_{CloudService}$ are Elasticity Capabilities (ECs). Elasticity capabilities are the set of actions associated with a cloud service, which a cloud service stakeholder (e.g., an elasticity controller) may invoke, and affect the behavior of the cloud service. Elasticity capabilities can be exposed by: (i) different cloud service parts, (ii) cloud providers or (iii) the resources which are supplied by cloud providers. An Elasticity Capability is the abstract representation of API calls which can differ among providers and cloud services. For instance, Fig. 2 depicts the different subset of ECs provided for an exemplary web application when deployed on two different IaaS providers (Flexiant³, or Openstack⁴ private cloud), as well as the ECs exposed by the cloud service and underlying software. In each of the two mentioned providers, the cloud service needs to run, maybe on some specific environments (e.g., Tomcat web server), and all these capabilities, when enforced by an elasticity controller, will have an effect on the different parts of the cloud service (e.g., even if it is not obvious at first sight, the control actions for the web objects would have an effect on the distributed data store).

Elasticity Control Processes (ECP) are sequences of elasticity capabilities $ECP_i = [EC_{i_1} \to EC_{i_2} \to ... \to EC_{i_n}]$, which can be abstracted into higher level capabilities having predictable effects on the cloud service. The ECP causes a change into the elasticity dependency graph in the virtual infrastructure related information (e.g., change in a process properties, or change in the properties of the VM). For instance, for the case of a data end composed of multiple nodes, an ECP of increasing the amount of resources, with certain parameters, would imply both for a Cassandra and an HBase database, adding the new node, and then subscribing to the cluster. The latter two are elasticity capabilities, while

 $^{^3 {\}tt www.flexiant.com}$

 $^{^4}$ www.openstack.org

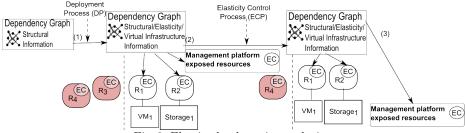


Fig. 3: Elastic cloud service evolution

the more generic increasing the amount of resources is an ECP, more abstract, which encapsulates the two elasticity capabilities.

2.2 Cloud service elasticity during runtime

In order to be able to estimate the effects of ECPs upon SPs, we describe the cloud service and its environment through the elasticity dependency graph, in order to consider as many as possible from the variables which are contributing to this evolution of the cloud service behavior. Fig. 3 shows in the left side the cloud service at a pre-deployment time, when the automatic controllers know about it only the Structural Information. After enforcing the Deployment Process DP (e.g., create machine x, configure software z, in case of error re-configure software z in configuration t), the cloud service has associated Infrastructure System Information, which describes all the resources associated with it, and Elasticity Information, showing the metrics evolution for different SPs, and the possible ECPs.

Each of the infrastructure resources have associated Elasticity Capabilities (EC in Fig. 3), that describe the change to be enforced and the mechanisms for triggering it (e.g., which API can be called for making that change). In addition, the Cloud Infrastructure (e.g., Amazon) exposes ECs in order to create new resources or instantiate new services (e.g., increasing the amount of memory can be seen as an EC exposed by a VM, while creating a new VM is an EC exposed by the Cloud Infrastructure). In this context, for being able to discover the effects that an ECP_i produces in time, for each SP, and for all the metrics which are monitored for that part of the service, taking into account correlations between metrics, we need to create our dependency graph, and analyze this information for determining the effect of ECP_i , regardless on whether ECP_i is application specific, or does not appear to influence these parts of the cloud service. In fact, as we show in Section 4, the impact of different ECPs over different cloud SPs or over the entire cloud service can be very interesting.

3 Determining Cloud Service Elasticity Behavior

As opposed to existing behavior learning solutions [3, 4], we are learning the behavior, of different sub-parts of the cloud service, not only the entire cloud

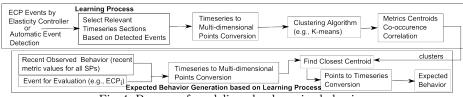


Fig. 4: Process of modeling cloud service behavior



Fig. 5: Relevant timeseries sections to points

service, and their relation to different ECPs, not only of the ones associated with the current cloud service part. Moreover, our learning process is estimating the effect of ECP in time, and considering the correlations among several metrics and among several service parts. The Learning Process executed for determining the cloud service parts behavior is depicted in Fig. 4, and is executing continuously, refining the previously gathered knowledge base.

3.1 Learning Process

Processing input data Our learning process takes as input each metric's evolution, in time, $M_{SP_i}^a[start, current]$ (see Equation 3) from the beginning of the service execution on the current cloud. For evaluating the expected evolution of metrics in response to applying a specific ECP, we select for each monitored metric, for each service part, a Relevant Timeseries Section (RTS), in order to compare it with previously encountered $M_{SP_i}^a[start, current]$. The RTS size strongly depends on the average time needed to enforcing an ECP. A RTS of a metric timeseries is a sub-sequence of the $M_{SP_i}^a$, from before enforcing an ECP until after its enforcement is over:

$$RTS_{M_a}^{SP_i} = M_{SP_i}^a \left[x - \frac{\delta + ECP_{time}}{2}, x + \frac{\delta + ECP_{time}}{2} \right], \quad (4)$$

$$\left[ECP_{startTime}, ECP_{endTime} \right] \subset \left[x - \frac{\delta + ECP_{time}}{2}, x + \frac{\delta + ECP_{time}}{2} \right]$$

, where x is the index of the event (in this case the ECP) and δ is the granularity of the relevant section.

As part of the input pre-processing phase, we represent $\delta + ECP_{time}$ as multidimensional points (see Fig. 5) in the n-dimensional Euclidian space, where the value for dimension θ is the timestamp θ of current RTS.

$$BP: M_{SP} \mapsto BehaviorPointsSpace^{\delta + ECP_{time}}$$

$$BP_{SP_i}^a(t) = (RTS_{M_a}^{SP_i}[\theta(0)], ..., RTS_{M_a}^{SP_i}[\theta(\delta + ECP_{time})])$$
(5)

Clustering process For detecting the expected behavior as a result of enforcing an ECP, we construct clusters of behavioral points $Cluster_{SP_i}$ (see Equation 7) for each service part and each ECP, not only ECPs available for the current SP, based on the distance between behavior points defined in Equation 6. Since the focus of current paper is not evaluating the quality of different clustering algorithms, we choose to use a simple K-means algorithm, following the practice of having the number of clusters equal to $\sqrt{n/2}$, n being the number of objects.

$$dist(BP[x], BP[y]) = \sqrt{\sum_{i} (BP[x][j] - BP[y][j])^{2}}$$

$$Cluster_{SP_{i}}^{a} = \{ \cup BP_{SP_{i}}^{a} | \min_{\forall x, y} dist(BP_{x}^{a}, BP_{y}^{a}) \}$$

$$(6)$$

$$Cluster_{SP_i}^a = \{ \bigcup BP_{SP_i}^a | \min_{\forall x, y} dist(BP_x^a, BP_y^a) \}$$
 (7)

After obtaining clusters of $\delta + ECP_{time}$ -dimensional points, we also create for each SP a correlation matrix, in order to know for all the metrics which clusters from different metrics are probable of appearing together (e.g., increase in data reliability is usually correlated with increase in cost). An item in the correlation matrix $CM_{SP_i}[CC_x, CC_y]$, where CC_x is the centroid of cluster x, would have as value the number of times the behavior points in clusters x respectively y were encountered together. This matrix is continuously refreshed when behavior points move from a cluster to another, or when new ECPs are enforced, increasing the knowledge base.

3.2Determining the expected behavior

In the Expected Behavior Generation based on Learning Process step from Fig. 4, we select latest metrics values for each SPs, $M_{SP}^a[current-\lambda, current]$, and the ECP which the controller is considering for enforcement, or for which the user would like to know the effects. We find the ExpectedBehavior (see Equation 8) which consists of a tuple of cluster centroids from the clusters constructed during the Learning Process which are the closest to the current metrics behavior for the part of the cloud service we are focusing on, and which have appeared together throughout the execution of the cloud service.

$$ExpectedBehavior[SP_i, Behavior_{SP_i}[current - \lambda, current], ECP_{\xi}] = \{CC_{i_{a_1}}^{M_{a_1}}, ..., CC_{i_{a_n}}^{M_{a_n}} | M_{a_n} \in Metrics(SP_i)\}$$
(8)

The above process is executed continually, as shown in Fig. 4, by refining clusters, re-computing cluster centroids with the time and with the enforcement of new ECPs. This process is highly flexible and configurable, as we can use different manners of detecting the ECP (e.g., sent by the elasticity controller), or other clustering algorithms which lead to different solutions.

4 Experiments

This section presents results obtained with the ADVISE framework which follows the details presented in the previous sections. The dependency graph (Fig. 1), is populated with various types of information, represented through existing tools:

- Structural information (e.g., TOSCA specification) from the cloud service elasticity controller and deployment tools
- Infrastructure information from monitoring tools like JCatascopia [9] and MELA [10])
- Enforced ECPs from the elasticity controller that manages the cloud service To evaluate the functionality and effectiveness of the proposed approach⁵, we have established a testbed comprised of two cloud services deployed on the Flexiant FlexiScale Cloud Platform⁶. On both of the two services, we enforce randomly ECPs exposed by their different SPs, for ensuring a good knowledge base combining different runtime information. We compute for each ECP, at different moments in time with different resources used and different workload, the expected metrics evolution, in time, for each SP of the cloud service.

4.1 Experimental Services

The first cloud service is a three-tier web application which provides video streaming services to online users. Specifically, the cloud service is comprised of: (i) an $HAProxy^7$ Load Balancer which distributes client requests (i.e., download, upload video) across multiple application servers; (ii) An Application Server Tier, where each application server is an Apache Tomcat⁸ server containing the video streaming web service; (iii) A Cassandra⁹ NoSQL Distributed Data Storage Backend from where the necessary video content is retrieved. A workload generator which produces random download/upload client requests was utilized to stress the cloud service. We have evaluated the ADVISE framework by generating client requests under a stable client request rate. It must be noted that even though a stable request rate was used, the workload imposed to the overall service varies and depends on the type of the request and the requested video.

The second service under evaluation is a Machine-to-Machine (M2M) DaaS which processes information originating from several different types of data sensors (i.e., temperature, atmospheric pressure, or pollution). Specifically, the M2M DaaS is comprised of two service topologies, an *Event Processing Service Topology* and a *Data End Service Topology*. Each service topology consists of two service units, one with a processing goal, and the other acting as the service topology balancer/controller. To stress this cloud service we generate random sensor event information which is processed by the *Event Processing Service Topology*, and stored/retrieved from the *Data End Service Topology*.

 $^{^5}$ More results and a detailed analysis, is available at <code>http://dsg.tuwien.ac.at/research/viecom/prototypes/csBehavior</code>

⁶ http://www.flexiant.com/

⁷ http://haproxy.1wt.eu/

⁸ http://tomcat.apache.org/

⁹ http://cassandra.apache.org/

Cloud		ECP Description	Action Sequence
Service			
	ECP_1		(i) select instance to remove, (ii) stop the video
Video		* *	streaming service, (iii) remove instance from
Service			HAProxy, (iv) restart HAProxy, (iv) stop JCatas-
			copia Monitoring Agent, (v) delete instance
	ECP_2		(i) create new network interface, (ii) instantiate new
		Application	instance, (ii) deploy and configure video streaming
		Server Tier	service to start accepting requests, (iv) deploy and
			start JCatascopia Monitoring Agent, (v) add instance
			IP to HAProxy, (vi) restart HAProxy
	ECP_3	Scale In	(i) select instance to remove, (ii) decommission in-
		Distributed	stance data to other nodes (using Cassandra nodetool
		Video Storage	API), (iii) stop JCatascopia Monitoring Agent, (iv)
		Backend	delete instance
	ECP_4	Scale Out	(i) create new network interface, (ii) instantiate new
		Distributed	instance, (iii) deploy and configure Cassandra (e.g.,
		Video Storage	assign token to node), (iv) deploy and start JCatas-
		Backend	copia Monitoring Agent, (v) start Cassandra
	ECP_5	Scale In Event	(i) remove service from HAProxy configuration file,
M2M		Processing	(ii) restart HAProxy, (iii) remove recursively virtual
DaaS		Service Unit	machine
	ECP_6	Scale Out Event	(i) create new network interface, (ii) create new virtual
		Processing	machine, (iii) add service IP to HAProxy configura-
		Service Unit	tion file
	ECP_7	Scale In Data	(i) decommision node (copy data from virtual machine
		Node Service	to be removed), (ii) remove recursively virtual ma-
		Unit	chine
	ECP_8	Scale Out Data	(i) create new network interface, (ii) create virtual ma-
		Node Service	chine, (iii) set ports, (iv) assign token to node, (v) set
		Unit	cluster controller, (vi) start Cassandra

Table 1: Elasticity Control Processes Available for the Two Services

The metrics which we are monitoring and analyzing for the two cloud services are presented in Table 2. Metrics are aggregated and analyzed by ADVISE framework to generate estimated values for each cloud service part. The available elasticity control processes for each cloud service are shown in Table 1, together with the lists of primary actions which compose each ECP.

4.2 Behavior Estimation

Online Video Streaming Service Figure 6 depicts both the observed and the estimated behavior for the Application Server Tier of the cloud service when a remove application server from tier ECP occurs (ECP_1) . At first, we observe that the average request throughput per application server is decreasing. This is due to two possible issues: (i) the video storage backend is under-

Cloud	SP Name	Metrics			
Service					
Video	Application Server Tier	cost, average number of active threads (busy thread			
Service		number), memory utilization, request throughput			
	Distributed Video	cost, CPU usage, memory usage, query latency			
	Storage Backend				
M2M DaaS	Cloud Service	cost per client per hour (Cost/Client/h)			
	Event Processing	cost, response time, throughput, number of clients			
	Service Topology				
	Data End Service	cost, latency, CPU usage			
	Topology				

Table 2: Elasticity metrics for different service parts

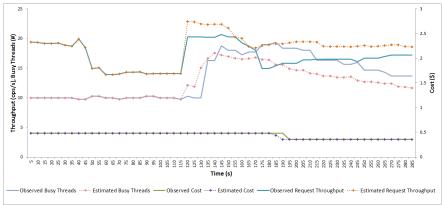


Fig. 6: Effect of ECP_1 on the application server tier

provisioned and cannot satisfy the current number of requests which, in turn, results in client requests being queued; (ii) there is, indeed, a sudden drop in client requests which indicates that application servers are not utilized efficiently. We observe that after the scale in action occurs, indeed, the average request throughput and busy thread number rises which denotes that the estimation is correct and resources are efficiently utilized.

Similarly, the charts in Figure 7 depict both the *observed* and the *estimated behavior* for the Distributed Video Storage Backend when a *scale out* action occurs (add Cassandra node to ring). We observe that after the scale out action occurs, the actual *CPU utilization* decreases to a normal value and our estimation is correct. Finally, from Figures 6 and 7, we conclude that ADVISE estimation successfully follows the actual behavior pattern and that in both cases, as time passes, the curves tend to converge.

M2M DaaS Figure 8 shows how an ECP targeting a service unit affects the entire cloud service. The Cost/Client/h is a complex metric (see Table 2) which depicts how profitable is the service deployment in comparison to the current

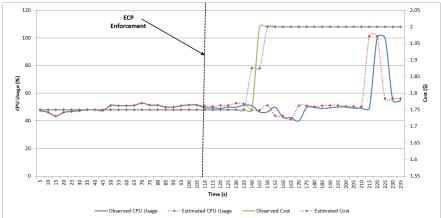


Fig. 7: Effect of ECP_4 on the entire video service

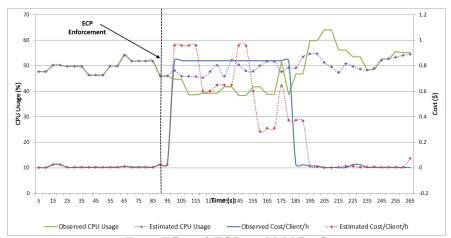


Fig. 8: Effect of ECP_7 on M2M DaaS

number of users. Although Cost/Client/h is not accurately estimated, due to the high fluctuation in number of clients, our approach estimates how the cloud service would behave in terms of expected time and expected metric fluctuations. This information is of tremendous importance for elasticity controllers, that can make informed decisions when enforcing this ECP, knowing how the Cost/Client/h, for the entire cloud service, would be affected. Although the CPU usage is not estimated perfectly, since it is a highly oscillating metric, and it depends on the CPU usage at each service unit level, knowing the baseline of this metric can also help in deciding whether this ECP is appropriate (e.g., for some applications CPU usage above 90% for a determined period of time can be considered inadmissible).

Our prototype can estimate the effect of an ECP exposed by a SP has on a different SP, even if apparently unrelated. Figure 9 shows estimations on how

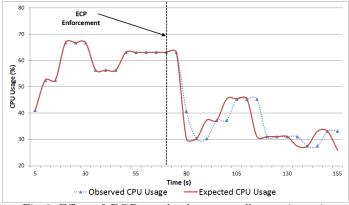


Fig. 9: Effect of ECP_8 on the data controller service unit

the data controller of the Data End Service Topology is impacted by the data transferred at the enforcement of ECP_8 . In this case, the CPU usage for the controller drops, since the new node is added to the ring, and a lot of effort in current topology goes for transferring data to the new node, then it raises due to the fact that reconfigurations are also necessary on the controller, following a slight decrease and stabilization. Therefore, even in circumstances of random workload, as is the case here, our prototype can give useful insights into how different SPs behave when enforcing ECPs exposed by various SPs.

4.3 ECP Temporal Effect

Table 3 presents the average time required for an ECP to be completed. This application-specific information is of high importance and affects the decision-making process of the elasticity controller since it is an indicator of the grace period which it should await until effects of the resizing actions are noticeable. Thus, it defines the time granularity of which resizing actions should be taken into consideration. For example, we observe that the process of adding and configuring a new instance to the video service's storage backend requires an average time interval of 150 seconds which is mainly the time required to receive and store data from other nodes of the ring. If decisions are taken in smaller intervals, the effects of the previous action will not be part of the decision process.

4.4 Quality of results

The ADVISE framework manages to estimate, in time, the elasticity behavior of different parts of a cloud service, in time, considering the correlations among metrics and the ECPs which are enforced. To evaluate the quality of results, we compute variance and standard deviations over a number of estimations. We have chosen to compute Variance and StdDeviation (Equation 9), over 100

	ECP	Standard Deviation	Average ECP Time (s)
	ECP1	0	65
Video	ECP2	0	15
Service	ECP3	0	25
	ECP4	1.414	150
	ECP1	4.5	45
M2M	ECP2	1.4	20
Service	ECP3	0	20
	ECP4	1	75

Table 3: Elasticity control processes time statistics

estimations as the result differs little from there on.

$$Variance_{metric_i} = \frac{\sum (estimatedMetric_i - obsMetric_i)^2}{nbEstimations}$$
$$StdDev_{metric_i} = \sqrt{Variance_{metric_i}}$$
(9)

Table 4 shows the accuracy of the presented results. When comparing the two cloud services, the Video Service achieves much higher accuracy (smaller variance and standard deviation), since the imposed workload is considerably stable. When focusing on the M2M DaaS estimation accuracy, we observe that it depends on the granularity at which the estimation is calculated, and on the ECP. Moreover, the standard deviation also depends on the metrics which we monitor for the different parts of the cloud service. For instance, in the case of the M2M Service, the number of clients metric can be hardly predicted, since we have sensors sending information, when issues arise or when events happen. This is evident for the Event Processing Service Topology, where we have a maximum variance of 4.9, which is the variance for the number of clients metric.

Overall, even in random cloud service load situations, ADVISE framework analyses and provides accurate information for elasticity controllers, with regard to the evolution of monitored metrics at the different cloud service levels. Without this kind of estimation, the elasticity controllers usually need to use VM-level profiling information, while they have to control complex cloud services. This information, for each cloud service part, is extremely valuable for elasticity controllers of complex cloud services, which expose complex control mechanisms.

5 Related Work

Verma et al. [1] study the impact of reconfiguration actions on system performance. They observe infrastructure level reconfiguration actions, with actions on live migration, and observe that the live migration is affected by the CPU usage of the source virtual machine, both in terms of the migration duration

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Cloud	Observed Cloud Service Part	Elasticity	Average	Maximum	Minimum
Service		Control	Standard	Variance	Variance
		Process	Deviation		
Video Service	Video Service	ECP_3	0.23	0.09	0.03
	Video Service	ECP_4	0.61	0.99	0.23
	Distributed Video Storage Backend	ECP_3	0.28	0.14	0.034
	Distributed video Storage Dackend	ECP_4	0.2	0.042	0.04
	Application Server	ECP_1	0.43	0.4	0.06
	Application Server	ECP_2	0.31	0.47	0.01
	Cloud Service	ECP_5	0.9	6.65	0.24
İ	Data End Service Topology	ECP_5	0.23	0.35	7.44E-05
	Event Processing Service Topology	ECP_7	1.1	4.9	0.046
	Event 1 rocessing betvice ropology	ECP_8	0.76	2.46	0.027
	Data Controller Service Unit	ECP_6	0.12	0.25	0
M2M	Data Controller Service Unit	ECP_8	0.22	0.41	0
Service	Data Nada Camina Hait	ECP_5	0.572	0.68	0.32
	Data Node Service Unit	ECP_6	0.573	1.4	0.07
	Event Processing Service Unit	ECP_7	1.08	3.59	0.11
	Event i focessing betvice Unit	ECP_8	0.77	1.9	0.14

Table 4: ECPs effect estimation quality statistics

and application performance. The authors conclude with a list of recommendations on dynamic resource allocation. Zhang et al. [3] propose algorithms for performance tracking of dynamic cloud applications, predicting metrics values like throughput or response time. Compared with this approach, we also take into consideration in our process the connection among different parts of the application, and we are interested of providing a prediction in time, considering metric correlations from the same part of the application, and with other different parts of the application (e.g., effect of an ECP on a completely different service topology). Kundu et al. [11] propose two algorithms, artificial neural network and support vector machine for constructing an application model correlating resource allocation with the performance obtained with the respective resource allocation.

Shen et al. [4] propose the CloudScale framework which uses resource prediction for automating resource allocation according to service level objectives (SLOs) with minimum cost. Based on resource allocation prediction, CloudScale uses predictive migration for solving scaling conflicts (i.e. there are not enough resources for accommodating scale-up requirements) and CPU voltage and frequency for saving energy with minimum SLOs impact. Compared with these research works, we construct our model considering multiple levels of metrics, depending on the application structure for which the behavior is learned. Moreover, the stress factors considered are also adapted to the application structure and the elasticity capabilities (i.e. action types) enabled for that application

⁷http://dsg.tuwien.ac.at/research/viecom/SYBL

type. Juve et al. [12] propose a system which helps at automating the provisioning process for cloud-based applications. They consider two application models, one workflow application and one data storage case, and show how for these cases the applications can be deployed and configured automatically. Li et al. [13] propose CloudProphet framework, which uses resource events and dependencies among them for predicting web application performance on the cloud. In contrast with this, our model incorporates different types of both architectural and deployment patterns of cloud computing state of the art.

To enrich existing research, our approach merges these two branches into a single dependency model, in which for estimating application's behavior we take into account both application patterns and the application expected behavior for those patterns in response to external stress factors.

6 Conclusions and Future Work

We have extended the cloud service dependency graph which is used to model both structural and runtime cloud service information. This graph plays a major role in discovering estimated cloud service behavior, in time, by taking into consideration correlation among metrics. We have incorporated this model into ADVISE framework which is able to estimate cloud service behavior, at runtime, for different cloud service structures, depending on the available ECPs. Based on results from two different cloud services, we show that the ADVISE framework is indeed able to "advise" the elasticity controller on the cloud service behavior, and therefore it can contribute to improving cloud service elasticity.

As future work, we intend to integrate the current framework with our rSYBL⁷ elasticity controller and develop new decision mechanisms that take continuous ECP effects as inputs, taking decisions based on the expected EB of each SP.

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