Joint error distribution after calibration R ANKL R R ANKL P R KNEE P R HIP P R HIP R R_HIP_YP 를 L_ANKL_P L_KNEE_P -L_HIP_P -00000 L_HIP_R -L HIP YP HEAD_P -HEAD Y -8 -7 -6 -5 -4 -3 -2 -1Error distribution (°)