Joint error distribution after calibration R ANKL R R ANKL P-R KNEE P-R HIP P-R HIP R-R_HIP_YP -로 L'ANKL'B -0 coo ode L_KNEE_P - o oo L HIP P-L HIP R -ന നാല L HIP YP-HEAD_P -HEAD Y--8 -7 -6 -5 -4 -3 -2 -1

Error distribution (°)