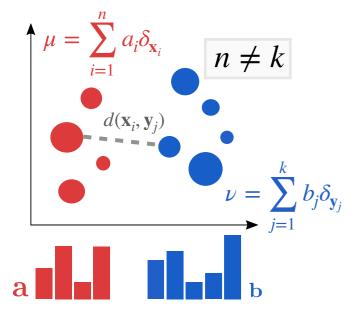
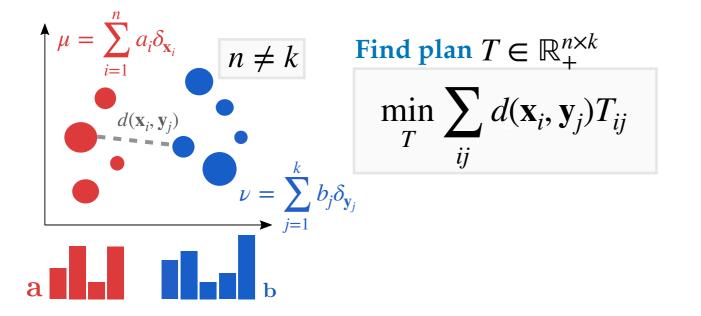
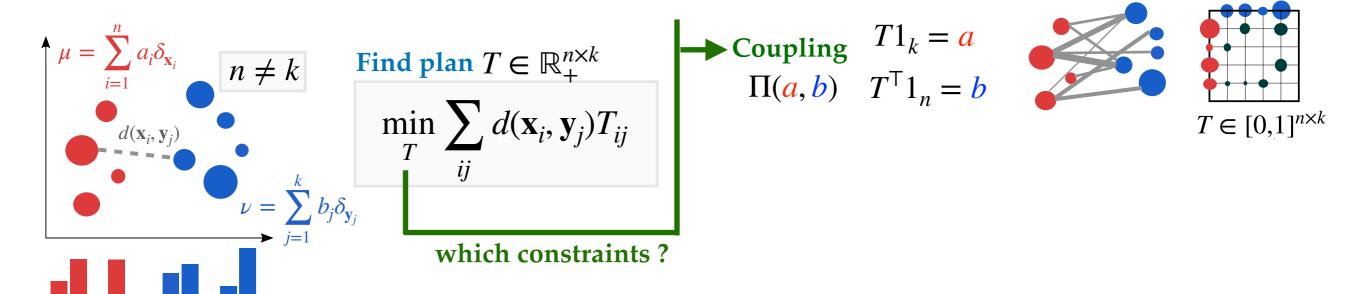
♦ Classical optimal transport (in a nutshell)



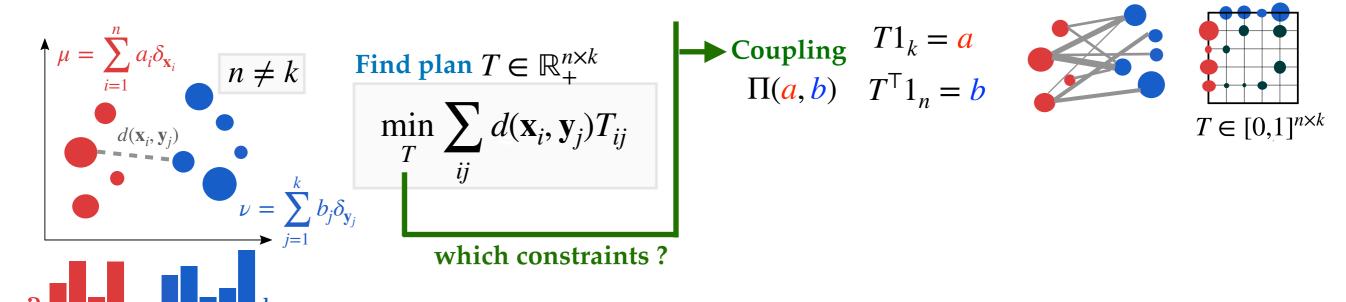
♦ Classical optimal transport (in a nutshell)



♦ Classical optimal transport (in a nutshell)



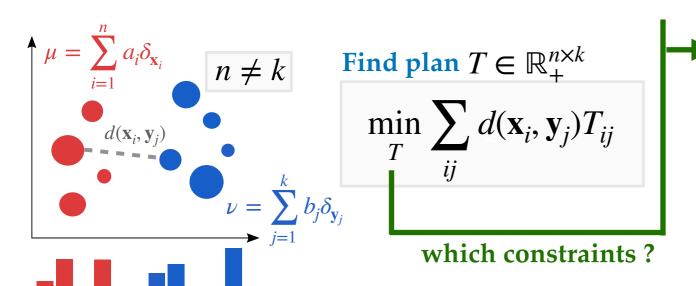
♦ Classical optimal transport (in a nutshell)

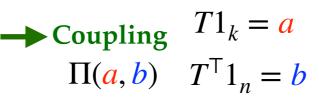


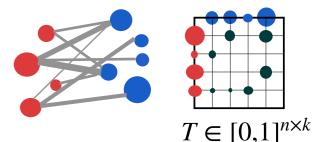
$$W_p(\mu, \nu) = \left(\min_{T} \int_{X \times X} d(x, y)^p dT(x, y)\right)^{1/p}$$

- **♦** It is always **well-defined**
- lacktriangle It is a proper distance on $\mathcal{P}(X)$
- **♦** Lifts the geometry of $X \to \mathcal{P}(X)$

♦ Classical optimal transport (in a nutshell)







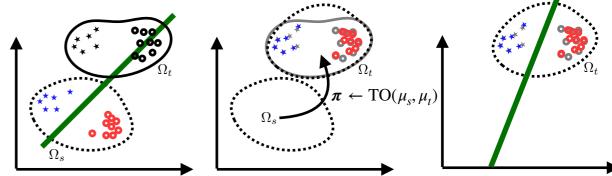
♦ Wasserstein distance

$$W_p(\mu, \nu) = \left(\min_{T} \int_{X \times X} d(x, y)^p dT(x, y)\right)^{1/p}$$

- **♦** It is always **well-defined**
- lacktriangle It is a proper distance on $\mathcal{P}(X)$
- **♦** Lifts the geometry of $X \to \mathcal{P}(X)$

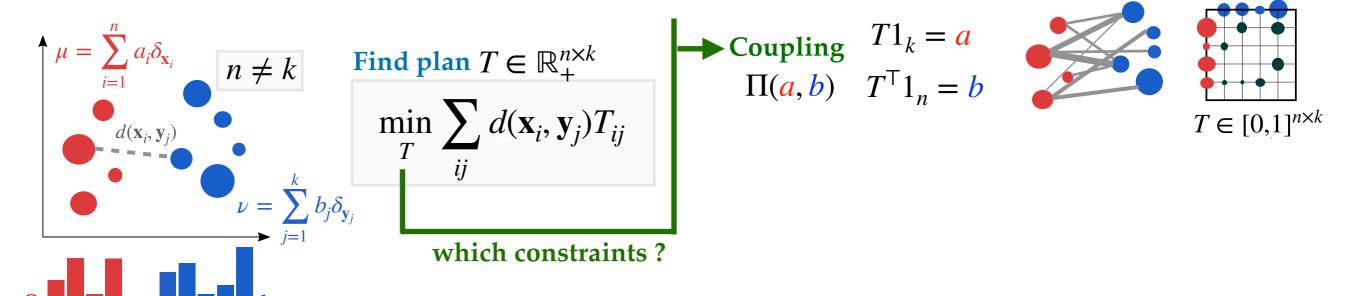
♦ In machine learning

Domain adaptation



- **♦** Generative modeling
- ♦ Analysis of NN convergence
- ♦ ML on graphs, fairness
- ◆ And many other ...

♦ Classical optimal transport (in a nutshell)



♦ Algorithmic fundations

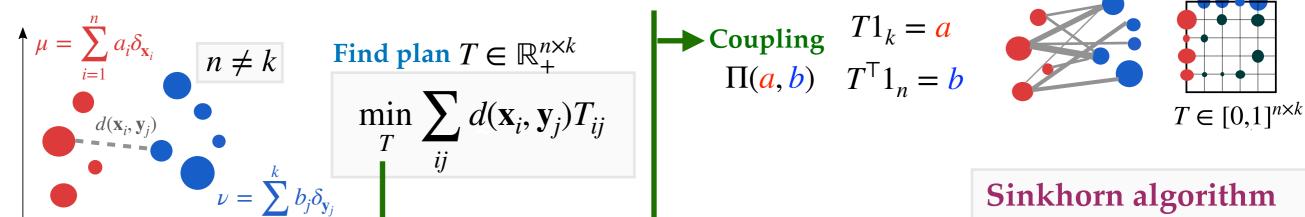
Unregularized problem

Simplex, Network flow

$$\mathcal{O}(n^3 \log(n)^2)$$

which constraints?

♦ Classical optimal transport (in a nutshell)



♦ Algorithmic fundations

Unregularized problem

Simplex, Network flow $\mathcal{O}(n^3 \log(n)^2)$

Entropic regularization

$$\min_{T} \sum_{ij} d(\mathbf{x}_i, \mathbf{y}_j) T_{ij} - \varepsilon H(T)$$

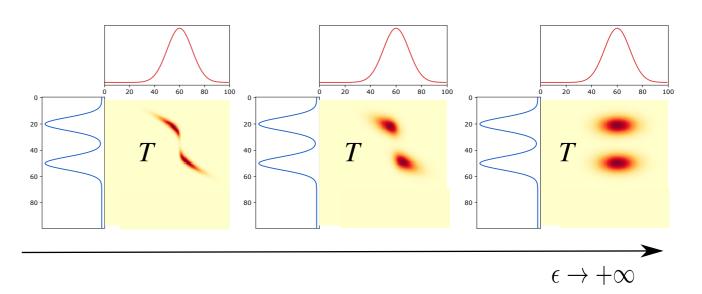
$$K := \left(e^{-d(\mathbf{x}_i, \mathbf{y}_j)/\varepsilon}\right)_{ij}$$

while not converged:

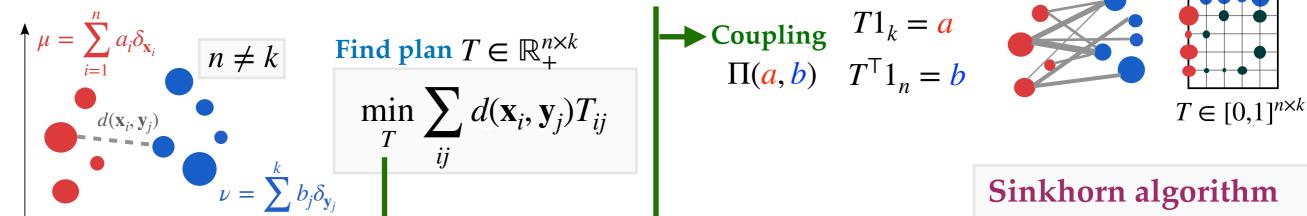
$$u = \mathbf{a} \oslash K^{\mathsf{T}} v$$
$$v = \mathbf{b} \oslash K u$$

output

$$T = diag(u)K diag(v)$$



♦ Classical optimal transport (in a nutshell)



which constraints?

♦ Algorithmic fundations

Unregularized problem

♦ Simplex, Network flow

$$\mathcal{O}(n^3 \log(n)^2)$$

Regularized problem

$$\mathcal{O}(n^2)$$

Entropic regularization

$$\min_{T} \sum_{ij} d(\mathbf{x}_i, \mathbf{y}_j) T_{ij} - \varepsilon H(T)$$

Sinkhorn algorithm

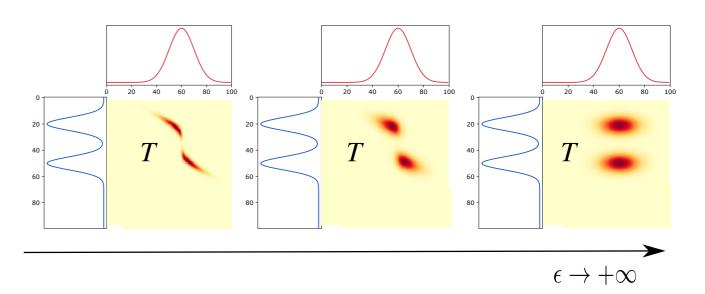
$$K := \left(e^{-d(\mathbf{x}_i, \mathbf{y}_j)/\varepsilon}\right)_{ij}$$

while not converged:

$$u = \overset{\mathbf{a}}{\circ} \oslash K^{\mathsf{T}} v$$
$$v = \overset{\mathbf{b}}{\circ} \oslash K u$$

output

$$T = \operatorname{diag}(u)K\operatorname{diag}(v)$$



♦ Goal: fast approximation of $u \rightarrow Ku$

Sinkhorn algorithm

$$K := \left(e^{-d(\mathbf{x}_i, \mathbf{y}_j)/\varepsilon}\right)_{ij}$$

while not converged:

$$u = \underset{\bullet}{a} \oslash K^{\mathsf{T}} v$$

 $v = b \oslash Ku$

output

T = diag(u)K diag(v)

lacktriangle Goal: fast approximation of $u \to Ku$

Sinkhorn algorithm

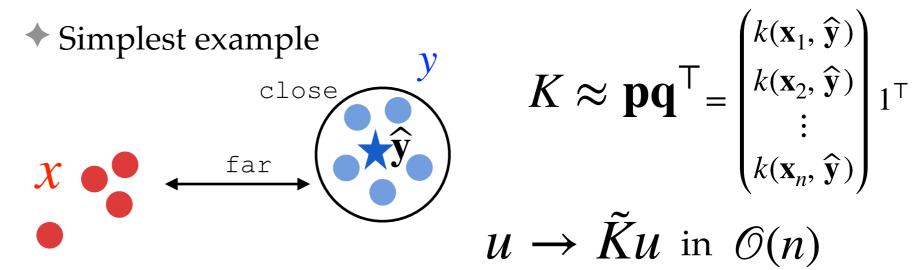
$$K := \left(e^{-d(\mathbf{x}_i, \mathbf{y}_j)/\varepsilon}\right)_{ij}$$

while not converged:

$$u = \mathbf{a} \oslash K^{\mathsf{T}} v$$
$$v = \mathbf{b} \oslash K u$$

output

$$T = diag(u)K diag(v)$$



lacktriangle Goal: fast approximation of $u \to Ku$

Sinkhorn algorithm

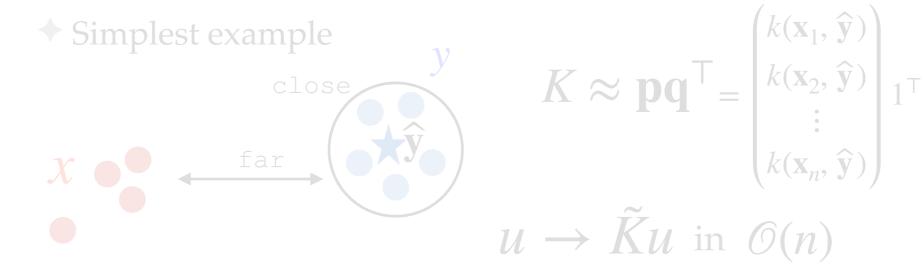
$$K := \left(e^{-d(\mathbf{x}_i, \mathbf{y}_j)/\varepsilon}\right)_{ij}$$

while not converged:

$$u = \mathbf{a} \oslash K^{\mathsf{T}} v$$
$$v = \mathbf{b} \oslash K u$$

output

$$T = diag(u)K diag(v)$$



◆ Generally if r clusters in y far enough from all the x

$$K \approx \mathbf{P}\mathbf{Q}^{\mathsf{T}} \ u \to \tilde{K}u \text{ in } \mathcal{O}(rn)$$

◆ But unknown clusters + crude approximation!

lacktriangle Goal: fast approximation of $u \to Ku$

Sinkhorn algorithm

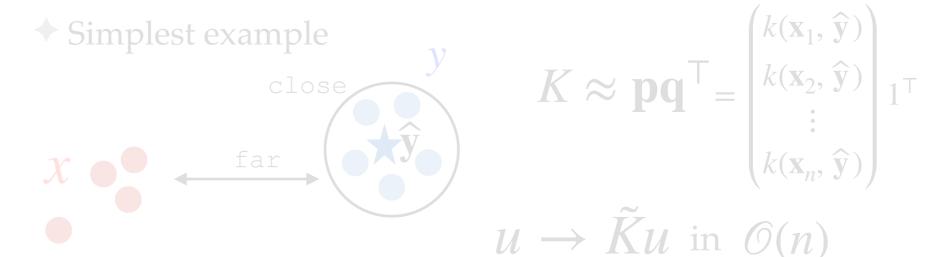
$$K := \left(e^{-d(\mathbf{x}_i, \mathbf{y}_j)/\varepsilon}\right)_{ij}$$

while not converged:

$$u = \mathbf{a} \oslash K^{\mathsf{T}} v$$
$$v = \mathbf{b} \oslash K u$$

output

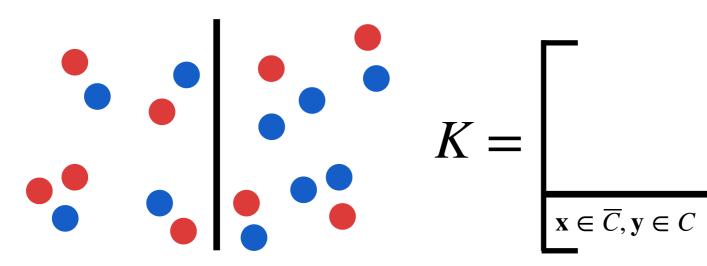
$$T = \operatorname{diag}(u)K\operatorname{diag}(v)$$



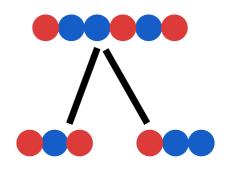
Generally if r clusters in y far enough from all the x

$$K \approx \mathbf{P}\mathbf{Q}^{\mathsf{T}} \ u \to \tilde{K}u \ \text{in } \mathcal{O}(rn)$$

♦ Idea: hierarchical clustering



$$K = \begin{bmatrix} \mathbf{x} \in C, \mathbf{y} \in \overline{C} \\ \mathbf{x} \in \overline{C}, \mathbf{y} \in C \end{bmatrix}$$



lacktriangle Goal: fast approximation of $u \to Ku$

Sinkhorn algorithm

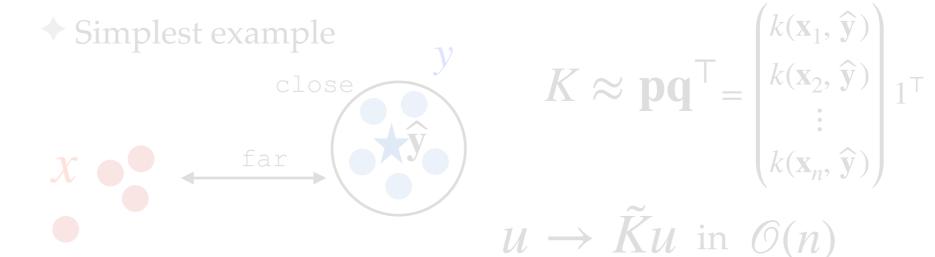
$$K := \left(e^{-d(\mathbf{x}_i, \mathbf{y}_j)/\varepsilon}\right)_{ij}$$

while not converged:

$$u = \mathbf{a} \oslash K^{\mathsf{T}} v$$
$$v = \mathbf{b} \oslash K u$$

output

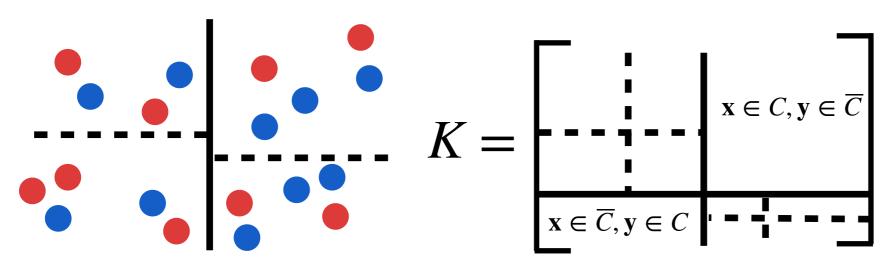
$$T = diag(u)K diag(v)$$

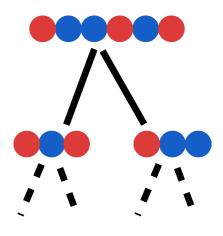


♦ Generally if r clusters in y far enough from all the x

$$K \approx \mathbf{P}\mathbf{Q}^{\mathsf{T}} \ u \to \tilde{K}u \ \text{in } \mathcal{O}(rn)$$

♦ Idea: hierarchical clustering





lacktriangle Goal: fast approximation of $u \to Ku$

Sinkhorn algorithm

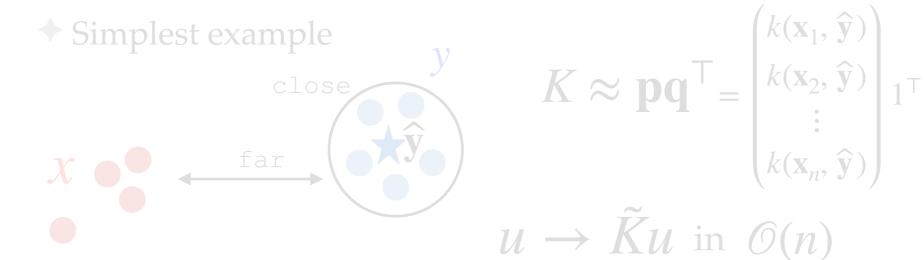
$$K := \left(e^{-d(\mathbf{x}_i, \mathbf{y}_j)/\varepsilon}\right)_{ij}$$

while not converged:

$$u = \mathbf{a} \oslash K^{\mathsf{T}} v$$
$$v = \mathbf{b} \oslash K u$$

output

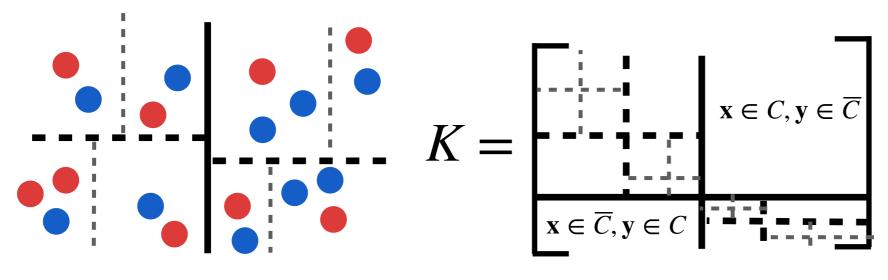
$$T = diag(u)K diag(v)$$

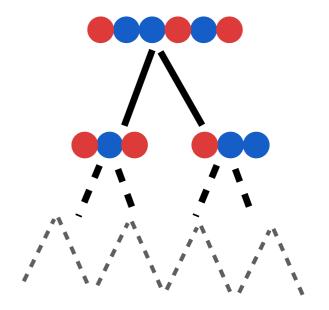


♦ Generally if r clusters in y far enough from all the x

$$K \approx \mathbf{P}\mathbf{Q}^{\mathsf{T}} \ u \to \tilde{K}u \ \text{in } \mathcal{O}(rn)$$

♦ Idea: hierarchical clustering





lacktriangle Goal: fast approximation of $u \to Ku$

Sinkhorn algorithm

$$K := \left(e^{-d(\mathbf{x}_i, \mathbf{y}_j)/\varepsilon}\right)_{ij}$$

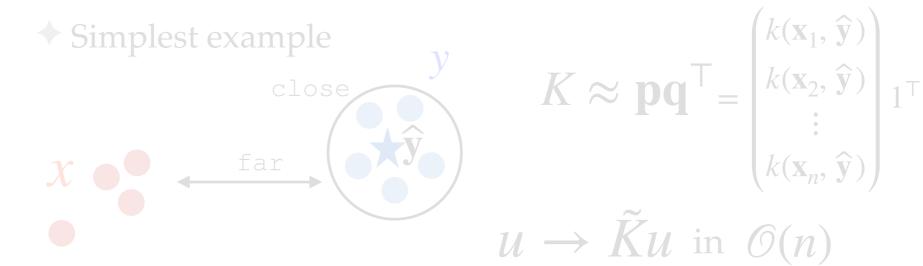
while not converged:

$$u = \underset{\bullet}{a} \oslash K^{\mathsf{T}} v$$

 $v = b \oslash Ku$

output

$$T = diag(u)K diag(v)$$



◆ Generally if r clusters in y far enough from all the x

$$K \approx \mathbf{P}\mathbf{Q}^{\mathsf{T}} \ u \to \tilde{K}u \ \text{in } \mathcal{O}(rn)$$

♦ Idea: hierarchical clustering



◆ Fast multipole methods, Barnes-Hut algorithm, H-matrices