

CharacterDevice Drivers

Praktikum „Kernel Programming“

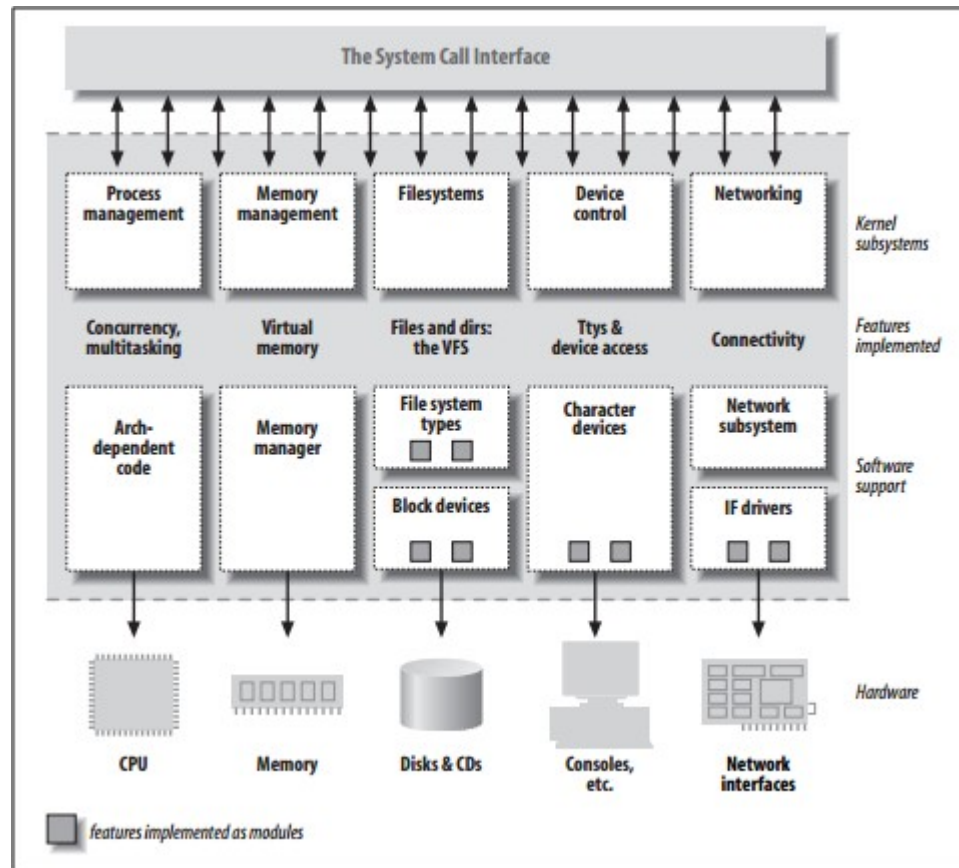
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Outline

- What are character device drivers
- Example of the connection between application and character
- Major and minor numbers
- File operations
- ioctl(Input/Output control)
- Blocking I/O
- Access control

What are character device drivers



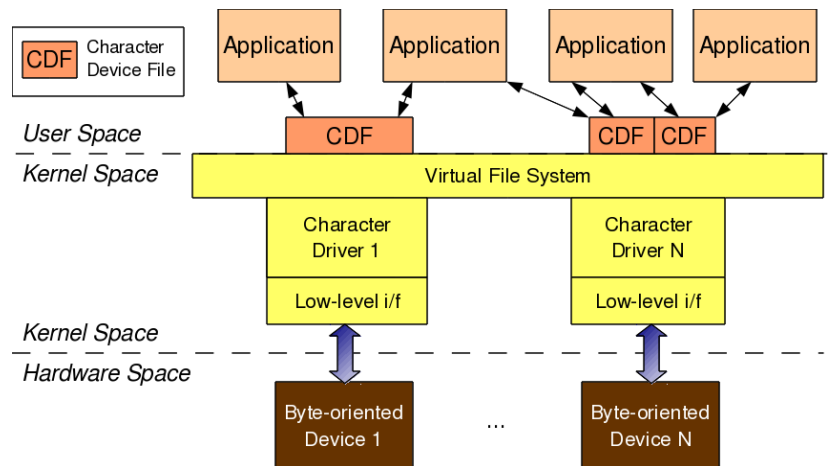
What are character device drivers

- Character devices can be accessed as a stream of bytes
- Character device drivers implement *open*, *close*, *read* and *write* of the time and grant access to the data stream for the user space
- Examples for character devices:
 - Serial Ports (/dev/ttyS0)
 - Console (/dev/console)
 - Mouse (/dev/input/mouse0)
 - (all devices that are neither storage nor network devices)

What are character device drivers

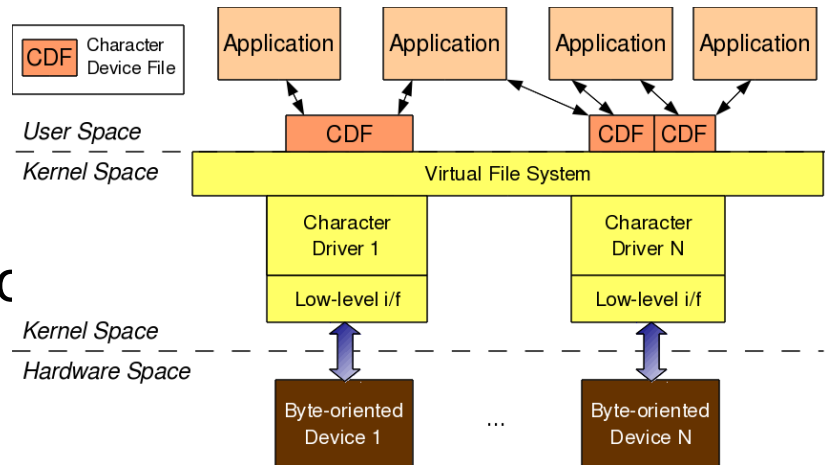
□ Connection between application and the device in 4 steps:

- Application
- Character device file
- Character device driver
- Character device



Example of the connection between application and character device

- The music player writes the music to play into the CDF
- The character device driver takes the music from the CDF and sends it as a byte stream to the character device



Major and minor numbers

- Access to device driver from user space through device file
- Kernel needs to know to which driver and which device the device file belongs
- Device files mapped by the kernel to a major and a minor number
 - Major number refers to the driver, each driver has its own
 - Minor number refers to the device which is managed by the driver

Major and minor numbers

- Limit of 255 major and 255 minor numbers
- Each combination of major and minor number is unique and mapped to a device file
- Some functions need to know the major number
- In the Kernel the type `dev_t` contains major and minor number of device

Major and minor numbers

□ To get the major or minor number from a `dev_t`:

□ `MAJOR(dev_t dev);`

□ `MINOR(dev_t dev);`

□ To get a `dev_t` from the major and the minor number:

□ `MKDEV(int major, int minor);`

Major and minor numbers

□ Two types of major and minor number region allocation:

□ `int register_chrdev_region(dev_t first, unsigned int count, char *name);`

□ Static allocation where it's not sure if you'll get the requested region

□ If the minor numbers exceed the 255 it will automatically assign the next major too, if it's free

□ `int alloc_chrdev_region(dev_t *dev, unsigned int first minor, unsigned int count, char *name);`

□ Dynamic allocation of the device numbers by the kernel

□ You will definitely get a free major number assigned

□ To free the assigned major and minor numbers in the exit function:

□ `void unregister_chrdev_region(dev_t first, unsigned int count);`

Major and minor numbers

□ Allocating only a major number with it's full 256 minor numbers

```
int register_chrdev(unsigned int major, const char *  
name, const struct file_operations * fops);
```

□ Will try to allocate the given major

□ Setting major to 0 will change the functions behavior to dynamically allocate a number

□ Free the assigned major number:

```
void unregister_chrdev(unsigned int major, const char *  
name);
```

File Operations

```
struct file_operations {
    struct module *owner;
    loff_t (*llseek) (struct file *, loff_t, int);
    ssize_t (*read) (struct file *, char __user *, size_t, loff_t *);
    ssize_t (*write) (struct file *, const char __user *, size_t, loff_t *);
    ssize_t (*read_iter) (struct kiocb *, struct iov_iter *);
    ssize_t (*write_iter) (struct kiocb *, struct iov_iter *);
    int (*iterate) (struct file *, struct dir_context *);
    unsigned int (*poll) (struct file *, struct poll_table_struct *);
    long (*unlocked_ioctl) (struct file *, unsigned int, unsigned long);
    long (*compat_ioctl) (struct file *, unsigned int, unsigned long);
    int (*mmap) (struct file *, struct vm_area_struct *);
    int (*open) (struct inode *, struct file *);
    int (*flush) (struct file *, fl_owner_t id);
    int (*release) (struct inode *, struct file *);
    int (*fsync) (struct file *, loff_t, loff_t, int datasync);
    int (*aio_fsync) (struct kiocb *, int datasync);
    int (*fasync) (int, struct file *, int);
    int (*lock) (struct file *, int, struct file_lock *);
    ssize_t (*sendpage) (struct file *, struct page *, int, size_t, loff_t *, int);
    unsigned long (*get_unmapped_area)(struct file *, unsigned long, unsigned long, unsigned long, unsigned long);
    int (*check_flags)(int);
    int (*flock) (struct file *, int, struct file_lock *);
    ssize_t (*splice_write)(struct pipe_inode_info *, struct file *, loff_t *, size_t, unsigned int);
    ssize_t (*splice_read)(struct file *, loff_t *, struct pipe_inode_info *, size_t, unsigned int);
    int (*setlease)(struct file *, long, struct file_lock **, void **);
    long (*fallocate)(struct file *file, int mode, loff_t offset,
        loff_t len);
    void (*show_fdinfo)(struct seq_file *m, struct file *f);
#ifdef CONFIG_MMU
    unsigned (*mmap_capabilities)(struct file *);
#endif
};
```

File Operations

- Structure defined in linux/fs.h
- Contains pointers to the common file operations by the driver
- Usage:

```
struct file_operations fops = {  
    .read = device_read,  
    .write = device_write,  
    .open = device_open,  
    .release = device_release  
};
```

File Operations–open/release

```
int(*open) (structinode*, structfile *);
```

```
int(*release) (structinode*, structfile *);
```

Return value: 0 for success, negative numbers for failure

Structinode* is a structdefined in linux/fs.hand includes information about the device

Structfile * is a structdefined in linux/fs.hand references to the device file

File Operations-read/write

```
□ ssize_t(*read) (struct file *, char __user *, size_t, loff_t*);
```

```
□ ssize_t(*write) (struct file *, const char __user *, size_t,  
    loff_t*);
```

□ Return value: the size read or written

□ Struct file * is a struct defined in linux/fs.h and references to the device file

□ Char __user * is the buffer we receive from user space

□ Size_t is the size of the requested transfer

□ Loff_t is the long offset type indicating the position in the file the user is accessing

File Operations-lseek

```
□ lseek(*lseek) (structfile *, lseek, int);
```

□ Return value: New position in the file

□ Structfile * is a struct defined in linux/fs.h and reference to the device file

□ Loff_t is the value defining how much the position will be changed

□ Int defines where it should start (0 from beginning, 1 at current position, 2 at end)

ioctl(Input/Output control)

- Used for device control of the driver
- Can include software commands like receiving error logs
- Can also include hardware commands like opening a CD drive
- Some command-oriented character devices like terminals use commands instead of ioctl
 - It's also possible to use only ioctl instead of read and write, you just have to implement the read and write operations as ioctl commands

ioctl(Input/Output control)

- Prototype definition:

- `int ioctl(int fd, unsigned long cmd, ...);`

- ... stands for an optional argument

- Each ioctlcommand is defined by one 8 bit Type number for the driver and an additional 8 bit Number for the actual command

- Should return -ENOTTY when an undefined ioctlcommand is called

ioctl(Input/Output control)

- Each module can define its own ioctlcommands
- The ioctlcommands should be defined in a header file in combination with the major number
 - Most of the time static major number allocation, when working with i
- The header file should be referenced by any programs using t commands

ioctl(Input/Output control)

- Usually with a switch-case
- Selecting in switch case which command was sent to him
- Default should just return -ENOTTY
- On success of one command 0 or an answer to the user space program should be returned
- Arguments can be given as a pointer or value and can be received as a return value or pointer

Blocking I/O

- If the driver gets a request which can't handle right now he puts the process to sleep
- Reasons for the driver to be not able to handle the request:
 - Receiving a read request when there is no data to read available
 - Receiving a write request when the buffer is already full

Blocking I/O

- To send a process to sleep, we need a wait queue

- Static initialized wait queue; initialized at compile time:

- `DECLARE_WAIT_QUEUE_HEAD (m y_queue);`

- Dynamic initialized wait queue; initialized at runtime

- `wait_queue_head_t m y_queue;`

- `init_waitqueue_head(&m y_queue);`

Blocking I/O

□ Several ways to send a process to sleep:

□ `sleep_on(wait_queue_head_t*queue);`

□ `interruptible_sleep_on(wait_queue_head_t*queue);`

□ `sleep_on_timeout(wait_queue_head_t*queue, long timeout);`

□ `interruptible_sleep_on_timeout(wait_queue_head_t*queue, long timeout);`

□ `void wait_event(wait_queue_head_t*queue, int condition);`

□ `int wait_event_interruptible(wait_queue_head_t*queue, int condition);`

Blocking I/O

□ All variants of `sleep_on` can be woken up using these commands

□ `wake_up(wait_queue_head_t*queue);`

□ `wake_up_interruptible(wait_queue_head_t*queue);`

□ `wake_up_sync(wait_queue_head_t*queue);`

□ `wake_up_interruptible_sync(wait_queue_head_t*queue);`

□ The `wait_event` variants don't need a `wake_up` call, but wake up automatically on the condition

Access Control

□ Single-open lock:

- Device file can only be opened by one process at the same time
- Usually implemented with an Integer which is 0 when no process is using the driver and 1 when it's busy

□ Single-user lock:

- Device file can be opened by all processes owned by one user
- Usually implemented using a field saving the owner of the first process opening the file

Access Control

□ „Blocking-open“:

- Device file can be opened by any process at any time but if another process is using the device, the calling process will have to wait
- Usually implemented with a wait queue

□ Cloning the device

- When open is called by a process, it gets its own copy of the device virtual device file

Literature

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