

Information theory

Course of Machine Learning
Master Degree in Computer Science
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a.a. 2017-2018

Let X be a discrete random variable:

- define a measure $h(x)$ of the information (surprise) of observing $X = x$
- requirements:
 - likely events provide low surprise, while rare events provide high surprise:
 $h(x)$ is inversely proportional to $p(x)$
 - X, Y independent: the event $X = x, Y = y$ has probability $p(x)p(y)$. Its surprise is the sum of the surprise for $X = x$ and for $Y = y$, that is,
 $h(x, y) = h(x) + h(y)$ (information is additive)

this results into $h(x) = -\log x$ (usually base 2)

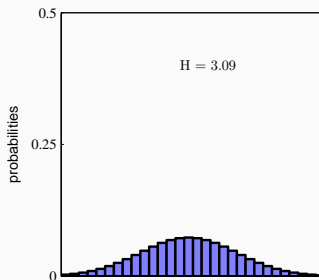
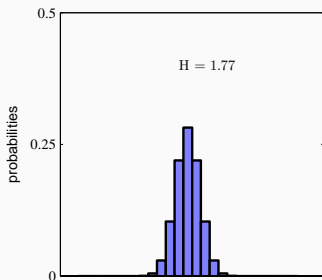
Entropy

A sender transmits the value of X to a receiver: the expected amount of information transmitted (w.r.t. $p(x)$) is the **entropy** of X

$$H(x) = - \sum_x p(x) \log_2 p(x)$$

- lower entropy results from more sharply peaked distributions
- the uniform distribution provides the highest entropy

Entropy is a measure of disorder.



Entropy, some properties

- $p(x) \in [0, 1]$ implies $p(x) \log_2 p(x) \leq 0$ and $H(X) \geq 0$
- $H(X) = 0$ if there exists x such that $p(x) = 1$

Maximum entropy

Given a fixed number k of outcomes, the distribution p_1, \dots, p_k with maximum entropy is derived by maximizing $H(X)$ under the constraint $\sum_{i=1}^k p_i = 1$. By using Lagrange multipliers, this amounts to maximizing

$$-\sum_{i=1}^k p_i \log_2 p_i + \lambda \left(\sum_{i=1}^k p_i - 1 \right)$$

Setting the derivative of each p_i to 0,

$$0 = -\log_2 p_i - \log_2 e + \lambda$$

results into $p_i = 2^{\lambda - \log_2 e}$ for each i , that is into the uniform distribution $p_i = \frac{1}{k}$ and $H(X) = \log_2 k$

$H(X)$ is a lower bound on the expected number of bits needed to encode the values of X

- trivial approach: code of length $\log_2 k$ (assuming uniform distribution of values for X)
- for non-uniform distributions, better coding schemes by associating shorter codes to likely values of X

Entropy, continuous case

Differential entropy

X is a continuous r.v.: divide the domain in bins of width Δ . Then, for each bin, there exists x_i such that

$$\int_{i\Delta}^{(i+1)\Delta} p(x)dx = p(x_i)\Delta$$

The probability of a point in the i -th bin is then $p(x_i)\Delta$, and

$$H_\Delta = - \sum_i p(x_i)\Delta \ln(p(x_i)\Delta) = - \sum_i p(x_i)\Delta \ln p(x_i) - \ln \Delta$$

The **differential entropy** is defined as

$$H(X) = \lim_{\Delta \rightarrow 0} - \sum_i p(x_i)\Delta \ln p(x_i) = - \int p(x) \ln p(x) dx$$

Maximum differential entropy

Let X be a continuous r.v. with given mean μ and variance σ^2 .

- The distribution of X with maximum entropy is the gaussian distribution $\mathcal{N}(\mu, \sigma^2)$.

Conditional entropy

Let X, Y be a continuous r.v. : for a pair of values x, y the additional information needed to specify y if x is known is $-\ln p(y|x)$.

The expected additional information needed to specify the value of Y if we assume the value of X is known is the **conditional entropy** of Y given X

$$H(Y|X) = - \int \int p(x, y) \ln p(y|x) dx dy$$

Clearly, since $\ln p(y|x) = \ln p(x, y) - \ln p(x)$

$$H(X, Y) = H(Y|X) + H(X)$$

that is, the information needed to describe (on the average) the values of X and Y is the sum of the information needed to describe the value of X plus that needed to describe the value of Y if X is known.

KL divergence

Assume the distribution $p(x)$ of X is unknown, and we have modeled it as an approximation $q(x)$.

If we use $q(x)$ to encode values of X we need an average length $-\int p(x) \ln q(x) dx$, while the minimum (known $p(x)$) is $-\int p(x) \ln p(x) dx$.

The additional amount of information needed, due to the approximation of $p(x)$ through $q(x)$ is the **Kullback-Leibler divergence**

$$\begin{aligned} KL(p||q) &= -\int p(x) \ln q(x) dx + \int p(x) \ln p(x) dx \\ &= -\int p(x) \ln \frac{q(x)}{p(x)} dx \end{aligned}$$

$KL(p||q)$ measures the difference between the distributions p and q .

- $KL(p||p) = 0$
- $KL(p||q) \neq KL(q||p)$: the function is not symmetric, it is not a distance (it would be $d(x, y) = d(y, x)$)

Applying KL divergence

- $\mathbf{x} = (x_1, \dots, x_n)$, dataset generated by a unknown distribution $p(x)$
- we want to infer the parameters of a probabilistic model $q_\theta(x|\theta)$
- approach: minimize

$$\begin{aligned} KL(p||q_\theta) &= - \int p(x) \ln \frac{q(x|\theta)}{p(x)} dx \\ &\approx - \frac{1}{n} \sum_{i=1}^n \ln \frac{q(x_i|\theta)}{p(x_i)} \\ &= \frac{1}{n} \sum_{i=1}^n (\ln p(x_i) - \ln q(x_i|\theta)) \end{aligned}$$

First term is independent of θ , while the second one is the negative log-likelihood of \mathbf{x} . The value of θ which minimizes $KL(p||q_\theta)$ also maximizes the log-likelihood.

Mutual information

- Measure of the independence between X and Y

$$I(X, Y) = KL(p(X, Y) || p(X), p(Y)) = - \int \int p(x, y) \ln \frac{p(x)p(y)}{p(x, y)} dx dy$$

additional encoding length if independence is assumed

- We have:

$$\begin{aligned} I(X, Y) &= - \int \int p(x, y) \ln \frac{p(x)p(y)}{p(x, y)} dx dy \\ &= - \int \int p(x, y) \ln \frac{p(x)p(y)}{p(x|y)p(y)} dx dy \\ &= - \int \int p(x, y) \ln \frac{p(x)}{p(x|y)} dx dy \\ &= - \int \int p(x, y) \ln p(x) dx dy + \int \int p(x, y) \ln p(x|y) dx dy \\ &= H(X) - H(X|Y) \end{aligned}$$

- Similarly, it derives $I(X, Y) = H(Y) - H(Y|X)$