# Ensemble methods

Course of Machine Learning Master Degree in Computer Science

University of Rome "Tor Vergata"

a.a. 2019-2020

Giorgio Gambosi

#### Ensemble methods

Improve performance by combining multiple models, in some way, instead of using a single model.

- train a committee of L different models and make predictions by averaging the predictions made by each model on dataset samplings (bagging)
- train different models in sequence: the error function used to train a model depend on the performance of previous models (boosting)

# Bagging

- Classifiers (especially some of them, such as decision trees) may have low performances due to their high variance: their behavior may largely differ in presence of slightly different training sets (or even of the same training set).
- For example, in trees, the separations made by splits are enforced at all lower levels: hence, if the data is perturbed slightly, the new tree can have a considerably different sequence of splits, leading to a different classification rule

## Bootstrap

- The bootstrap is a fundamental resampling tool in statistics. The basic underlying idea is to estimate the true distribution of data  $\mathcal F$  by the so-called empirical distribution  $\hat{\mathcal F}$
- lacksquare Given the training data  $(\mathbf{x}_i,t_i)$ ,  $i=1,\ldots,n$ , the empirical distribution function  $\hat{\mathcal{F}}$  is defined as

$$\hat{p}(\mathbf{x},t) = \begin{cases} \frac{1}{n} & \text{if } \exists i : (\mathbf{x},t) = (\mathbf{x}_i,t_i) \\ 0 & \text{otherwise} \end{cases}$$

■ This is just a discrete probability distribution, putting equal weight  $\frac{1}{n}$  on each of the observed training points

## Bootstrap

lacktriangle A bootstrap sample of size m from the training data is

$$(\mathbf{x}_i^*, t_i^*) \qquad i = 1, \dots, m$$

where each  $(\mathbf{x}_i^*, t_i^*)$  is drawn uniformly at random from  $(\mathbf{x}_1, t_1), \dots, (\mathbf{x}_n, t_n)$ , with replacement

■ This corresponds exactly to m independent draws from  $\hat{\mathcal{F}}$ . Hence it approximates what we would see if we could sample more data from the true  $\mathcal{F}$ . We often consider m=n, which is like sampling an entirely new training set

## Bagging

- Given a training set  $(\mathbf{x}_i, y_i)$ ,  $i=1,\ldots,n$ , bagging averages the predictions done by classifiers of the same type (such as decision trees) over a collection of boostrap samples. For  $b=1,\ldots,B$  (e.g., B = 100), n bootstrap items  $(\mathbf{x}_i^b, y_i^b)$ ,  $i=1,\ldots,n$  are sampled and a classifier is fit on this set.
- At the end, to classify an input x, we simply take the most commonly predicted class, among all B classifiers
- This is just choosing the class with the most votes
- $\blacksquare$  In the case of regression, the predicted value is derived as the average among the predictions returned by the B regressors

## Bagging variant

If the used classifier returns class probabilities  $\hat{p}_k^b(\mathbf{x})$ , the final bagged probabilities can be computed by averaging

$$p_k^b(\mathbf{x}) = \frac{1}{B} \sum_{b=1}^{B} \hat{p}_k^b(\mathbf{x})$$

the predicted class is, again, the one with highest probability

# Bagging classification

- Why is bagging working?
- Let us consider, for simplicity, a binary classification problem. Suppose that for a given input  $\mathbf{x}$ , we have B independent classifiers, each with a given misclassification rate e (for example, e=0.4). Assume w.l.o.g. that the true class at  $\mathbf{x}$  is 1: so the probability that the b-th classifier predicts class 0 is e=0.4
- Let  $B_0 \le B$  be the number of classifiers returning class 0 on input  $\mathbf{x}$ : the probability of  $B_0$  is clearly distributed according to a binomial (if classifiers are independent)

$$B_0 \sim \mathsf{Binomial}(B, e)$$

the misclassification rate of the bagged classifier is then

$$p\left(B_0 > \frac{B}{2}\right) = \sum_{k=\frac{B}{2}+1}^{B} {B \choose k} e^k (1-e)^{B-k}$$

which tends to 0 as B increases.

# Bagging regression

**E**xpected error of one model  $y_i(\mathbf{x})$  wrt the true function  $h(\mathbf{x})$ :

$$E_{\mathbf{x}}[(y_i(\mathbf{x}) - h(\mathbf{x}))^2] = E_{\mathbf{x}}[\varepsilon_i(\mathbf{x})^2]$$

Average expected error of the models

$$E_{av} = \frac{1}{m} \sum_{i=1}^{m} E_{\mathbf{x}} [\varepsilon_i(\mathbf{x})^2]$$

Committee expected error

$$E_c = E_{\mathbf{x}} \left[ \left( \frac{1}{m} \sum_{i=1}^m y_i(\mathbf{x}) - h(\mathbf{x}) \right)^2 \right] = E_{\mathbf{x}} \left[ \left( \frac{1}{m} \sum_{i=1}^m \varepsilon_i(\mathbf{x}) \right)^2 \right]$$

If  $E_{\mathbf{x}}[\varepsilon_i(\mathbf{x})\varepsilon_j(\mathbf{x})]=0$  if  $i\neq j$  (errors are uncorrelated) then  $E_c=\frac{1}{m}E_{av}$ .

■ This is usually not verified: errors from different models are highly correlated.

## Out-of-bag error

- Model evaluation can be performed by evaluating, for each item  $\mathbf{x}_i$  in the data set, the prediction done by the set of models trained on bootstrap samples not including  $\mathbf{x}_i$ .
- If bootstrap samples have the same size of the dataset (i.e. m=n), there is a probability .63 that an item is included in a bootstrap sample: in fact, for each sample, the probability that item  $\mathbf{x}_i$  is not selected is  $1-\frac{1}{n}$ . Hence there is a probability  $\left(1-\frac{1}{n}\right)^n$  that it is never sampled. For large enough values of n, the probability is about  $\lim_{n\to\infty}\left(1-\frac{1}{n}\right)^n=\frac{1}{e}\approx .37$
- In out-of-bag evaluation, the prediction of an item is done by using approximately a fraction .37 of all the trees. For those trees the item can be considered as a test set member.

#### Random forest

Application of bagging to a set of (random) decision trees: classification performed by voting.

- I For b=1 to B:
  - Bootstrap sample from training set
  - $\hfill \square$  Grow a decision tree  $T_b$  on such data by performing the following operations for each node:
    - $\blacksquare$  select m variables at random
    - 2 pick the best variable among them
    - 3 split the node into two children
- **2** output the collection of trees  $T_1, \ldots, T_B$

Overall prediction is performed as majority (for classification) or average (for regression) among trees predictions.

## Boosting

- Boosting is a procedure to combine the output of many weak classifiers to produce a powerful committee.
- A weak classifier is one whose error rate is only slightly better than random guessing.
- Boosting produces a sequence of weak classifiers  $y_m(x)$  for  $m=1,\ldots,m$  whose predictions are then combined through a weighted majority to produce the final prediction

$$y(\mathbf{x}) = \operatorname{sgn}\left(\sum_{j=1}^{m} \alpha_j y_j(\mathbf{x})\right)$$

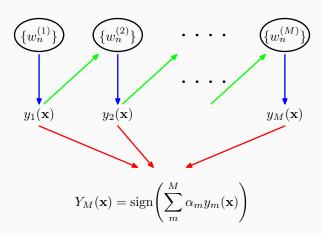
 $\blacksquare$  Each  $\alpha_j>0$  is computed by the boosting algorithm and reflects how accurately  $y_m$  classified the data.

## Boosting

#### Adaboost (adaptive boosting)

- Models are trained in sequence: each model is trained using a weighted form of the dataset
- Element weights depend on the performances of the previous models (misclassified points receive larger weights)
- Predictions are performed through a weighted majority voting scheme on all models

## Boosting



Binary classification, dataset  $(\mathbf{X}, \mathbf{t})$  of size n, with  $t_i \in \{-1, 1\}$ . The algorithm maintains a set of weights  $w(\mathbf{x}) = (w_1, \dots, w_n)$  associated to the dataset elements.

- Initialize weights as  $w_i^{(0)} = \frac{1}{n}$  for i = 1, ..., n
- For j = 1, ..., m:
  - Train a weak learner  $y_j(\mathbf{x})$  on  $\mathbf{X}$  in such a way to minimize the weighted misclassification wrt to  $w^{(j)}(\mathbf{x})$ .
  - Let

$$e^{(j)} = \frac{\sum_{\mathbf{x}_i \in \mathcal{E}^{(j)}} w_i^{(j)}}{\sum_i w_i^{(j)}}$$

where  $\mathcal{E}^{(j)}$  is the set of dataset elements misclassified by  $y_j(\mathbf{x})$ .

- lacksquare If  $e^{(j)}>rac{1}{2}$ , consider the reverse learner, which returns opposite predictions for all elements.
- $e^{(j)}$  can be interpreted as the probability that a random item from the training set is misclassified, assuming that item  $\mathbf{x}_i$  can be sampled with probability  $\frac{w_i^{(j)}}{\sum_i w_i^{(j)}}$

 $\blacksquare$  Compute the learner confidence as log odds of a random item being well classified  $(1-e^{(j)})$  vs being misclassified  $e^{(j)}$ 

$$\alpha_j = \log \frac{1 - e^{(j)}}{e^{(j)}} > 0$$

lacksquare For each  $\mathbf{x}_i$ , update the corresponding weight as follows

$$w_i^{(j+1)} = \begin{cases} w_i^{(j)} e^{\alpha_j} > w_i^{(j)} & \text{if } \mathbf{x}_i \in \mathcal{E}^{(j)} \\ w_i^{(j)} & \text{otherwise} \end{cases}$$

The overall prediction is

$$y(\mathbf{x}) = \operatorname{sgn}\left(\sum_{j=1}^{m} \alpha_j y_j(\mathbf{x})\right)$$

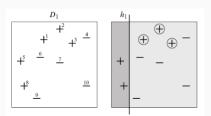
since  $y_j(\mathbf{x}) \in \{-1,1\}$ , this corresponds to a voting procedure, where each learner vote (class prediction) is weighted by the learner confidence.

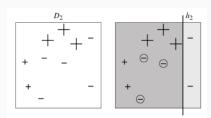
 Observe that a weak learner confidence is inversely related to the probability of misclassification. Moreover,

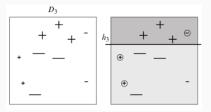
$$w_i^{(t)} = \frac{1}{n} \prod_{j \in \mathcal{B}_i} \frac{1 - e^{(j)}}{e^{(j)}}$$

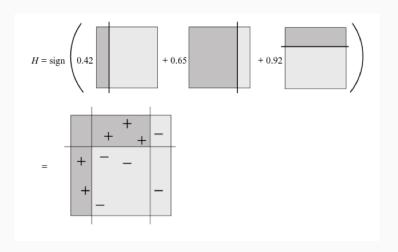
where  $\mathcal{B}_i$  is the set of indices of "bad" weak learners wrt  $\mathbf{x}_i$  (that is ones that misclassify  $\mathbf{x}_i$ )

- lacksquare Since  $1-e^{(j)}>e^{(j)}$  it derives that bad learners increase the probability of an element, while good learners decrease it.
  - As iterations proceed, observations difficult to classify correctly receive more influence.
  - Each successive classifier is forced to concentrate on training observations missed by previous ones in the sequence.









### Additive models

Additive models are defined as the additive composition of simpler "base" predictors

$$y(\mathbf{x}) = \sum_{j=1}^{m} c_j \overline{y}(\mathbf{x}; \mathbf{w}_j)$$

where  $c_j$ 's are weights and  $\overline{y}(\mathbf{x};\mathbf{w}) \in \mathbb{R}$  are simple functions of the input  $\mathbf{x}$  parameterized by  $\mathbf{w}$ 

# Fitting additive models

As usual, an additive model is fit by minimizing a loss function averaged over the training data:

$$\min_{c_j, \mathbf{w}_j} \sum_{i=1}^n L(t_i, \sum_{k=1}^m c_k \overline{y}(\mathbf{x}_i; \mathbf{w}_k))$$

 $\blacksquare$  For many loss functions L and/or predictors  $\overline{y}$  this is too hard

## Forward stagewise additive modeling

More simply, one can greedily add one basis function at a time in the following fashion.

- Set  $y_0(\mathbf{x}) = 0$
- For k = 1, ..., m:
  - Compute

$$(\hat{c}_k, \hat{\mathbf{w}}_k) = \underset{c_k, \mathbf{w}_k}{\operatorname{argmin}} \sum_{i=1}^n L(t_i, y_{k-1}(\mathbf{x}_i) + c_k \overline{y}(\mathbf{x}_i; \mathbf{w}_k))$$

• Set 
$$y_k(\mathbf{x}) = y_{k-1}(\mathbf{x}) + \hat{c}_k \overline{y}(\mathbf{x}; \hat{\mathbf{w}}_k)$$

That is, fitting is performed not modifying previously added terms

## Adaboost as additive model

Adaboost can be interpreted as fitting an additive model with exponential loss

$$L(y, f(\mathbf{x})) = e^{-tf(\mathbf{x})}$$

that is, minimizing

$$\underset{\alpha_j, \mathbf{w}_j}{\operatorname{argmin}} \ \sum_{i=1}^n e^{-t_i \sum_{k=1}^m \alpha_k \overline{y}(\mathbf{x}_i; \mathbf{w}_k)}$$

#### Adaboost as additive model

Applying forward stagewise additive modeling, at each step k it computes

$$(\hat{\alpha}_k, \hat{\mathbf{w}}_k) = \underset{\alpha_k, \mathbf{w}_k}{\operatorname{argmin}} \sum_{i=1}^n e^{-t_i(y_{k-1}(\mathbf{x}_i) + \alpha_k \overline{y}(\mathbf{x}_i; \mathbf{w}_k))}$$
$$= \underset{\alpha_k, \mathbf{w}_k}{\operatorname{argmin}} \sum_{i=1}^n p_i^{(k)} e^{-\alpha_k \overline{y}(\mathbf{x}_i; \mathbf{w}_k)}$$

where  $p_i^{(k)}=e^{-t_iy_{k-1}(\mathbf{x}_i)}=e^{-\frac{1}{2}t_i\sum_{r=1}^{k-1}\alpha_ry_r(\mathbf{x}_i)}$  is a constant wrt  $\alpha_k$  and  $\mathbf{w}_k$ 

The approach can be extended to the case of different loss functions

## Gradient boosting

#### General idea:

- Fit an additive model  $\sum_{i=1}^{m} \alpha_j y_j(\mathbf{x})$  in a forward stage-wise manner.
- At each stage, introduce a weak learner to compensate the shortcomings of existing ones.
- Shortcomings are identified by high-weight data points.

# Gradient boosting

- You are given  $(\mathbf{x}_i, t_i)$ ,  $i = 1, \dots, n$ , and the task is to fit a model  $y(\mathbf{x})$  to minimize square loss.
- Assume a model  $y^{(1)}(\mathbf{x})$  is available, with residuals  $t_i y^{(1)}(\mathbf{x}_i) = t_i y_i^{(1)}$
- A new dataset  $(\mathbf{x}_i, t_i y_i^{(1)})$ ,  $i = 1, \ldots, n$  can be defined, and a model  $\overline{y}^{(1)}(\mathbf{x})$  can be fit to minimize square loss wrt such dataset
- Clearly,  $y_2(\mathbf{x}) = y_1(\mathbf{x}) + \overline{y}_1(\mathbf{x})$  is a model which improves  $y_1(\mathbf{x})$
- $\blacksquare$  The role of  $\overline{y}_1(\mathbf{x})$  is to compensate the shortcoming of  $y(\mathbf{x})$
- If  $y_2(\mathbf{x})$  is unsatisfactory, we may define new models  $\overline{y}_2(\mathbf{x})$  and  $y_3(\mathbf{x}) = y_2(\mathbf{x}) + \overline{y}_2(\mathbf{x})$

## Gradient boosting

How is this related to gradient descent?

- Let us consider the squared loss function  $L(t,y) = \frac{1}{2}(t-y)^2$
- lacksquare We want to minimize the risk  $R = \sum_{i=1}^n L(t_i,y_i)$  by adjusting  $y_i,\dots,y_n$
- lacktriangle Consider  $y_i$  as parameters and take derivatives

$$\frac{\partial R}{\partial y_i} = y_i - t_i$$

So, we can consider residuals as negative gradients

$$t_i - y_i = -\frac{\partial R}{\partial y_i}$$

lacktriangle Model  $\overline{y}(\mathbf{x})$  can then be derived by considering the dataset

$$(\mathbf{x}_i, t_i - y_i) = \left(\mathbf{x}_i, -\frac{\partial R}{\partial y_i}\right)$$
  $i = 1, \dots, n$ 

# Gradient boosting for regression

#### The following algorithm results

- Set  $y^{(1)}(\mathbf{x}) = \frac{1}{n} \sum_{i=1}^{n} t_i$
- For k = 1, ..., m:
  - Compute negative gradients

$$-g_i^{(k)} = -\frac{\partial R}{\partial y_i}\Big|_{y_i = y^{(k)}(\mathbf{x}_i)} = -\frac{\partial}{\partial y_i} L(t_i, y_i)\Big|_{y_i = y^{(k)}(\mathbf{x}_i)} = t_i - y^{(k)}(\mathbf{x}_i)$$

- Fit a weak learner  $\overline{y}^{(k)}(\mathbf{x})$  to negative gradients, considering dataset  $(\mathbf{x}_i, -g_i^{(k)})$ ,  $i=1,\dots,n$
- $\blacksquare$  Derive the new classifier  $y^{(k+1)}(\mathbf{x}) = y^{(k)}(\mathbf{x}) + \overline{y}^{(k)}(\mathbf{x})$

## Gradient boosting for regression

- The benefit of formulating this algorithm using gradients is that it allows us to consider other loss functions and derive the corresponding algorithms in the same way.
- For example, square loss is easy to deal with mathematically, but not robust to outliers, i.e. pays too much attention to outliers.
- Different loss functions
  - Absolute loss

$$L(t,y) = |t - y|$$

$$-a = \operatorname{sgn}(t - y)$$

- $-g = \operatorname{sgn}(t y)$
- Huber loss

$$L(t,y) = \begin{cases} \frac{1}{2}(t-y)^2 & |t-y| \le \delta\\ \delta(|t-y|) - \frac{\delta}{2} & |t-y| > \delta \end{cases}$$

$$-g = \begin{cases} y - t & |t - y| \le \delta \\ \delta \cdot \operatorname{sgn}(t - y) & |t - y| > \delta \end{cases}$$

# Gradient boosting for classification

Consider a K-class framework.

Again, let  $R = \sum_{i=1}^n L(t_i, y_1(\mathbf{x}_i), \dots, y_K(\mathbf{x}_i))$  for a given loss function

- lacksquare Set  $y_j^{(1)}(\mathbf{x}) = \frac{1}{K}$ , for  $j=1,\ldots,K$
- For k = 1, ..., m:
  - Compute negative gradients

$$-g_j^{(k)}(\mathbf{x}_i) = -\frac{\partial R}{\partial y_j^{(k)}(\mathbf{x}_i)} = -\frac{\partial}{\partial y_i} L(t_i, y_1(\mathbf{x}_i), \dots, y_K(\mathbf{x}_i)) \Big|_{y_i = y^{(k)}(\mathbf{x}_i)}$$
$$= -\frac{\partial}{\partial y_j^{(k)}(\mathbf{x}_i)} L(t_i, y_1(\mathbf{x}_i), \dots, y_K(\mathbf{x}_i))$$

for  $j = 1, \ldots, K$ 

- Fit K weak learners  $\overline{y}_k^{(j)}(\mathbf{x})$   $(j=1,\ldots,K)$  to negative gradients, considering dataset  $(\mathbf{x}_i,-g(\mathbf{x}_i)),\ i=1,\ldots,n$
- $\blacksquare$  Derive the new classifiers  $y_{k+1}^{(j)}(\mathbf{x})=y_k^{(j)}(\mathbf{x})+\overline{y}_k^{(j)}(\mathbf{x})$

#### Which weak learners?

- Regression trees (special case of decision trees)
- Decision stumps (trees with only one node)