

# THARUN V PUTHANVEETIL

240-791-1188 | [tvpian@umd.edu](mailto:tvpian@umd.edu) | [tvpian.github.io](https://github.com/tvpian) | [linkedin.com/in/tvpian](https://www.linkedin.com/in/tvpian) | [github.com/tvpian](https://github.com/tvpian)

**Research Interest** : Pattern Recognition | Human-Robot Interaction | Multi-Modal Networks | Machine Vision | Cognitive Science

## EDUCATION

### University of Maryland

Master of Engineering in Robotics (GPA:3.88/4.0)

Aug. 2022 – May 2024

Maryland, USA

### Vellore Institute of Technology

Bachelor of Technology in Electronics and Communication (GPA:8.59/10.0)

Jul. 2014 – Apr 2018

Vellore, India

## EXPERIENCE

### Robotics Intern | Multi-Modal Networks, Robotics, Deep Learning, Security, Representation Learning

Feb 2023 – Present

CATT Labs

Maryland, USA

- Formulating functional and behavioral attacks to model the baseline behavior of the ROS1 autonomy stack.
- Developing Multi-Modal anomaly detectors for robots, enabling the ability to identify injections causing abnormalities.
- Creating a standardized metric to measure and parameterize the safety of robots and cyber-physical systems.
- Designed targetted Data Flooding & Man In The Middle attacks with 40%-60% stealth rate, on ROS1 navigation stack.
- Achieved 91% accuracy with LSTM-based sequential models in detecting anomalies from temporal robot system call data.
- Modelled an 86% accurate GCN+LSTM+Autoencoder-based anomaly detector for spatiotemporal robot sensor data.
- Developed a responsive web interface for live robot tracking and control, facilitating device-agnostic robot operation.
- Built a Flask-powered web app for robot waypoint navigation, enabling twofold acceleration in the data collection pipeline.

### Graduate Research Assistant | Deep Learning, Robotics, Human-Robot Interaction

Nov 2022 – Jan 2023

Perception and Robotics Group, UMD

Maryland, USA

- Worked on "Human-Robot Interaction using Multi-Modal interaction schemes" under Dr. Snehash Shrestha .
- Implemented an Imitation Learning-based policy to teach robot, actions from human demonstration, speech & gestures.

### Robotics Research Intern | Deep Learning, Human-Robot Interaction, Computer Vision

June 2021 – Dec 2021

Indian Institute of Science

Bangalore, India

- Implemented a robotic manipulator based Precision Weeding Robot to optimize pesticide usage in indoor farms.
- Developed YoloR-based crack detection algorithm with 94% accuracy for asset inspection challenge at IROS21.
- Developed a UNet-based Monocular Depth Estimation model using the NYU Dataset with 94% accuracy.
- Conceptualized a poster on "Event-based Dynamic Obstacle Avoidance in Outdoor Environments" for IROS21.

### Project Engineer | Deep Learning, HCI, Computer Vision, Recommendation Engine, Pattern Recognition

Jul. 2018 – May 2021

CTO Office, Wipro Digital

Bangalore, India

- Led as the AI Project Lead at the Innovation team, orchestrating the quarterly project lineup.
- Developed a 2D CNN-based tool tracking system using Leap Motion controller, enhancing hardware assembly pipelines.
- Engineered a mobile-centric insurance solution with a Transfer Learning-based car model detector(96% acc.)with Tflite.
- Implemented Generative AI and learning-based algorithms for my Style, Wipro's top 2 retail solutions for the year 2020.
- Designed a Robotics solution for the 'Smart Airport' product improving customer traction by 20%.

## PUBLICATIONS

- [1] "ASTROD: Multimodal Anomaly Detection for Autonomous Cyber-Physical Systems Empowering Real-World Evaluation". IROS 2024 [pre-print]
- [2] "Pose Fusion: Multi-View Pose Integration for Comprehensive Action Recognition". [pre-published print]
- [3] "Striking the Balance: Human Pose Estimation based Optimal Fall Recognition". [pre-published print]
- [4] "Application of Mobile Collaborative Robot using Deep Learning in Precision Weed Control of Large Farms". Elsevier 2021 [manuscript]
- [5] "A Univariate Data Analysis Approach for Rainfall Forecasting". ICCIS 2020 [manuscript] [link]
- [6] "Prediction of Rainfall Using Data Mining Techniques". ICICCT 2018 [link]
- [7] "Wall climbing robot using soft robotics". ICPCSI 2017 [link]

## PATENTS

### AGGRIP (In Progress) [link]

Oct 2021 – Present

- Engineered a manipulator gripper for precision weeding (plucking and spraying) tailored to identified weed types.
- The unique design ensures minimal contact with non-weeds using an adaptive vision-based control mechanism.

## TECHNICAL STACK

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**Programming:** Python, C/C++, SQL (MySQL), JavaScript, HTML/CSS, Matlab, Labview, Docker  
**AI/ML/Data Science Libraries:** Tensorflow, Pytorch, OpenCV, Keras, Scikit-Learn, Tableau  
**AI/ML Algorithms:** Reinforcement Learning, Imitation Learning, Graph Analysis, TSA, NLP, Gen AI, Federated Learning  
**UI/UX/AR/VR/MR/Simulation:** Unity, Three.js, A-frame, AR.js, Flask, Vuforia, Gazebo, Rviz  
**Embedded/IOT/Robotics:** ROS, ROS2, MQTT, HTTP, Socket, Softrobotics  
**Robotic Platforms:** Turtlebot 2, Turtlebot 3, Delta, OpenManipulator-X, Husky, M500 Drone  
**S/W Development:** Agile Development, Jira, GIT, Gitlab, Bitbucket, Pair Programming, Test-Driven Development, UML

## PROJECTS

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- PoseFusion - Multi-view Action Recognition** | *Python, Pytorch, OpenCV* [link] Nov 2023 – Dec 2023
- Developed a pipeline for view-based pose aggregation for action recognition in partial/no occlusion scenarios.
  - GCN+Transformer multi-view aggregation model** achieved an accuracy of 96% for multi-class action recognition.
  - Implemented a custom data loader to enable batch training for graph data that improved training speed by 4 times.
- Human Pose Estimation based Fall Recognition** | *Python, Tensorflow* [link] Nov 2023 – Dec 2023
- Developed a **Human Pose Estimation** keypoints based Fall Detection model. Identified optimal framerate for fall detection.
  - Quantified the potency of each keypoints in improving the detection accuracy. Analyzed the relevance of camera-angle.
  - Custom **Graph CNN + Transformer**-based Fall Detection model achieved 95%(avg.) accuracy on both UR & NTU dataset.
- Maze Runner** | *C++, ROS2, Gazebo, RViz* [link1] [link2] Nov 2023 – Dec 2023
- Implemented autonomous navigation in a maze, based on dynamic cues received from **Aruco** markers in Gazebo world.
  - Implemented a **ROS2 Action-Client** server to utilize the **NAV2** to perform visual feed-based waypoint navigation.
- Leonardo - Autonomous Retrieval UGV** | *Python, Arduino, OpenCV* [video] Feb 2023 – May 2023
- Constructed a Barron robot equipped with an IMU, Encoder, Rpi camera, and servo-based arm.
  - Implemented a **Visual Servoing**-based low-level controller for object 'Pick and Place' using the attached arm.
  - Developed an algorithm through **sensor fusion** of IMU, Encoder, & Range sensor for rapid localization in confined zones.
- Auto Platoon** | *Python, OpenCV, Pytorch* [video] [link] Apr 2023 – May 2023
- Deployed a bio-inspired multi-agent leader-follower system for modular & energy-efficient transportation.
  - Created a **YoloV7** and **Kalman Filter**-based agent tracking algorithm incorporating dynamic obstacle avoidance.
  - Developed a **Socket** communication-based connected-vehicle communication strategy.
  - Implemented a **Visual Servoing**-based motion planner and low-level controller for agent tracking and obstacle avoidance.
- ACO-RRT\* - Bio-Inspired Path Planning** | *Python, Numpy* [link] May 2023 – Jun 2023
- Implemented a Bio-Inspired path planning algorithm for quickly exploring random trees by foraging behavior of ants.
  - Improvise the sampling strategy of Traditional **RRT\*** with the **Ant Colony Optimization technique**.
  - Achieved 1.4 times and 3.54 times faster convergence (than **RRT\***) in finding the 'first path' and 'ideal path' respectively.
- Autonomous Weeding Robot** | *Python, Matlab, OpenCV, Tensorflow, Pytorch* [video] June 2021 – Present
- Implemented a robotic manipulator-based precision weeding robot for optimizing pesticide usage in indoor farms.
  - Created a **YoloR** object detection model trained on augmented synthetic data for weed localization with 98% accuracy.
  - Implemented an Inverse Kinematics solver based on supervised **Behavioral Cloning** for precise manipulation.
- my Style** | *Python, OpenCV, Tensorflow, Pytorch, Mysql, Flask* [link1] [link2] [video] Jun 2019 – Sep 2019
- An end-to-end AI-powered shopping app to reduce trial room drops and improve scope for apparel customization.
  - Implemented a human body measurement extraction module based on **2D photogrammetry & Body Pose Estimation**
  - Developed a **RASA** framework-based **chatbot** that can give personalized dress recommendations based on the user's body measurements, shape, color preference, and occasion of interest.
  - Modelled a **Content-based recommendation engine** for apparel recommendation.
  - Developed a **GAN**-based product customization model for dynamic apparel styling.
  - Engineered a supervised **Fit Analyzer** model that evaluates the fit of the chosen apparel in terms of a 'Fit %' metric.
- Other Robotics Projects:** | [A\* Planner] | [Dijkstra Planner] | [Irona] | [Robobutler] Aug 2022 – May 2023
- Other AI/ML Projects:** | [SLIC] | [Image Outpainting] | [Virtual Try-On] | [RL Cricket] July 2018 – Dec 2023

## ACHIEVEMENTS

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- RAMI Cascade Campaign - IEEE/RSJ IROS 2021** [link]
- Secured 3rd place for providing an aerial robotic solution for asset Inspection and Management (I&M).
- Late Breaking Results - IEEE/RSJ IROS 2021** [link]
- Poster on "Event-based Dynamic Obstacle Avoidance in Outdoor Environments" accepted as the top 25 posters.
- Winter School Projects - IEEE RAS 2021** [link]
- Finished as Top 2 teams to complete 4/4 tasks with a presentation for a challenge on "SLAM in Deformable Environments"