

## Categorical Definition of Requirements

### To-do

- ✓ Define the set of requirements  $R$ . ✓ 2025-11-28
- ✓ Add cat theory elements - products, limits, composed morphisms. ✓ 2025-12-02
- ✓ Make the definitions below more cat-theory-like. ✓ 2025-11-28

### Preliminary Definitions

Let  $E$  be a category.

$Objs(E)$  is the set of Electro-mechanical devices plus  $\{\mathbb{R}, \mathbb{B}\}$ .

Let  $F$  be the object representing the Flashlight,  $F \in Objs(E)$ .

Let  $\mathbb{R}$  be the real numbers (measurements), and  $\mathbb{B}$  be the Boolean object  $\{true, false\}$ .

### FR-001: White Light

Colour temperature measurement in  $^{\circ}\text{K}$  using a colour meter device  $cmeter$ :

Given  $I = \{Dark, Dim, Bright\}$  representing the torch output.

$$\begin{aligned} cmeter : I &\rightarrow \mathbb{R} \\ cmeter(Dark) &= 0 \\ cmeter(Dim) &\in [5000, 6000] \\ cmeter(Bright) &\in [5000, 6000] \end{aligned}$$

### FR-002 & FR-003: Controls

Let  $S = \{Off, Low, High\}$  be the set of internal states of  $F$ .

Let  $\Phi = Sy^S \rightarrow Iy^A$  be the dynamic system representing the behaviour of  $F$ .

$A = \{next!\}$  representing the user input -  $next!$  represent the input from a single switch.

Initial State:  $\Phi_0 : S \times A \rightarrow S = (-, -) \rightarrow Off$

Inspect State:

$$\begin{aligned} \Phi_1 : S &\rightarrow I = \\ Off &= Dark \\ Low &= Dim \\ High &= Bright \end{aligned}$$

Next State:

$$\begin{aligned} \Phi^\# : S \times A &\rightarrow S = (Off, next!) = Low \\ (Low, next!) &= High \\ (High, next!) &= Off \end{aligned}$$

### FR-004: Replaceable Battery

See IR-002

## **PR-001 & PR-002: Lumen Output**

Let  $lmeter$  be a Lux meter with an integrating sphere producing a Lumens measurement  $\mathbb{R}$ .  
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$lmeter : I \rightarrow \mathbb{R}$   
 $lmeter(Dark) = 0$   
 $lmeter(Dim) \in [50, 60]$   
 $lmeter(Bright) \in [500, 550]$

500 Lumens is Approximately 5250 Candelas.

## **PR-003: Beam Distance**

Let  $lmeter$  be a Lux meter *without* an integrating sphere, producing a Lux measurement  $\mathbb{R}$  at distance  $d$  metres from  $F$ .

$lmeter : I \times \mathbb{R} \rightarrow \mathbb{R}$   
 $lmeter(Bright, 400) \geq 0.25$

Rule of thumb: the usable distance is approximately 25% of the distance where the lux value drops off to 0.25, so measuring at 400m should give a usable distance of 100m.

## **PR-004 & PR-005: Run Time**

$I$  is the current consumption in mA.  
 $C$  is the battery capacity in mAh.

$$T = \frac{C}{I}$$

$$T_{high} = \frac{C}{I_{high}} \wedge T_{high} \geq 2$$
$$T_{low} = \frac{C}{I_{low}} \wedge T_{low} \geq 10$$

## **PhR-001: Power Source**

See FR-004

## **Phr-002: Material and Durability**

$housing : F \rightarrow H$  where  $H$  is the torch housing.  
 $H \subset \text{Aluminium} \wedge H \subset \text{Anodised}$

For normal usage:

$Y$  is the years of life,  $H$  is the hours of use,  $C$  number of operational cycles.  
Batteries excluded from durability.

Constraints:

$$Y \geq 5$$
$$H \geq 2000$$
$$C \geq 100000$$

## **PhR-003: Weight**

$scale : F \rightarrow \mathbb{R}$  is a weight measurement function returning a weight in grams.  
 $scale(f) \leq 200$

## **PhR-004: Dimensions**

Let  $length : F \rightarrow \mathbb{R}$  be a function that returns the length of  $F$  in units of cm.

Let  $width : F \rightarrow \mathbb{R}$  be a function that returns the width of  $F$  in units of cm.

Let  $height : F \rightarrow \mathbb{R}$  be a function that returns the height of  $F$  in units of cm.

$$length(f) \leq 15 \wedge length(f) \geq 8$$

$$width(f) \leq 3 \wedge width(f) \geq 0.5$$

$$height(f) \leq 3 \wedge height(f) \geq 0.5$$

### PhR-005: IPX4

Let  $water : F \rightarrow \mathbb{R}$  be a function that measures the amount of liquid water inside the torch.

Let  $spray : F \rightarrow F'$  be a water spray from all directions for 10 minutes.

$$water(spray(F)) = 0$$

### IR-001: User Interface

Let  $tail : H \rightarrow T$  be a function that returns the tail cap  $T$  from the housing  $H$

Let  $switch : T \rightarrow S$  be a function that returns the switch  $S$  from the tail cap  $T$ .

$s = switch(tail(housing(f))) \wedge s \in P$  where  $P$  is the set of momentary action push button switches.

The sets  $A$  and  $I$  from FR-002 and FR-003 also form part of the interface.

The switch  $s \in S$  implements  $A$  and the light source  $l \in L$ , where  $L$  is the set of LEDs, implements  $I$ .

### IR-002: Battery Access

Also FR-004.

Let  $case : F \rightarrow C \times T$  be a function that returns the case  $C$  and the tail cap  $T$  from a torch  $F$ .

Let  $battery : C \rightarrow B$  be a function that returns the battery  $B$  from a case  $C$ .

$$replace_{batt} : F \times B \rightarrow F' \times B' : replace_{batt}(f, b_{new}) = (f', b_{old})$$

and

$$battery(case(f)) = b_{old}$$

$$battery(case(f')) = b_{new}$$

### ER-001: Operating Temperature Range

Let  $F$  be a torch that satisfies the requirements  $R$ , i.e.  $F \vdash R$ .

Let  $cold : F \rightarrow F$  be a function that cools  $F$  to  $-10^\circ\text{C}$ .

Let  $hot : F \rightarrow F$  be a function that heats  $F$  to  $40^\circ\text{C}$ .

$$F \vdash R \wedge cold(F) \vdash R \wedge hot(F) \vdash R$$

### ER-002: Drop Resistance

Let  $drop : F \times \mathbb{R} \rightarrow F$  be a function that drops a torch  $F$  from a height  $\mathbb{R}$  in metres onto a concrete surface.

$$F \vdash R \wedge drop(F, 1) \vdash R$$

$F \vdash R \wedge \text{drop}(F, 1), 1 \vdash R$  is not necessarily true.

### **SR-001: Non-Incendive**

Let  $\text{heat\_test}: F \times \mathbb{R} \times \mathbb{R} \times S \rightarrow \mathbb{B}$  be a function that tests a torch  $f \in F$  at a temperature  $\mathbb{R}$  in °C for a duration  $\mathbb{R}$  minutes, in state  $S$ , and returns *true* if fire is detected, and *false* if it is not.

$\text{heat\_test}(f, 40, 180, \text{High}) = \text{false}$

I.e. the highest output for the longest duration in the hottest expected environment should not cause a fire.

### **FR-005: Beam Width/Angle**

Let  $\text{beam\_width}: F \times \mathbb{R} \rightarrow \mathbb{R}$  be a function that measures the minimum beam width in metres of a torch  $F$  at distance  $\mathbb{R}$  in metres.

$w = \text{beam\_width}(f, 3) \wedge w \geq 1 \wedge w \leq 3$  (constraint  $C_1$ )

Let  $\alpha$  be the beam angle measured in degrees at the light source, then:

$C_1 \Rightarrow \alpha \in [18, 53]$

### **BR-001: Costs, Profit, Etc**

$\text{Revenue} = \text{Price} \times \text{Sales}$

$\text{Costs} = \text{Fixed} + \text{Variable}$

$\text{Fixed} = \text{Design} + \text{Salaries} + \text{Rent}$

$\text{Variable} = \text{Sales} \times (\text{Materials} + \text{Labour} + \text{Shipping})$

$\text{Profit} = \text{Revenue} - \text{Costs}$

$\text{Sales} \geq 5000 \wedge \text{Price} \geq 15 \Rightarrow \text{Revenue} \geq 75000$

$\text{Profit} = 0.2 \times \text{Revenue} \Rightarrow \text{Profit} \geq 15000 \Rightarrow \text{Costs} \leq 0.8 \times \text{Revenue}$

**Finally**

✓ Don't forget the To-do list ✓ 2025-11-27

### **Notes/Observations**

- A measurable requirement can be constrained – the measurement is produced by an activity which can be modelled in HQDM.