### Destination $\lambda$ -calculus

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## 1 Term and value syntax

```
Term-level variable name
var, x, y
k
                Index for ranges
hvar, h
                                                                                                    Hole or destination name (\mathbb{N})
                                h+h'
                                                                                            Μ
                                h[H \pm h']
                                                                                            Μ
                                                                                                        Shift by h' if h \in H
                                                                                                        Maximum of a set of holes
                                max(H)
                                                                                            Μ
                                                                                                    Set of hole names
hvars, H
                                \{\mathbf{h}_1, \dots, \mathbf{h}_k\}
                                H_1 \cup H_2
                                                                                            Μ
                                                                                                        Union of sets
                                \mathtt{H} \dot{=} \mathtt{h'}
                                                                                                        Shift all names from H by h'.
                                                                                            Μ
                                \mathtt{hvars}(\Gamma)
                                                                                                        Hole names of a context (requires \mathtt{ctx\_NoVar}(\Gamma))
                                                                                            Μ
                                hvars(C)
                                                                                            Μ
                                                                                                        Hole names of an evaluation context
                                                                                                    Term
term, t, u
                                                                                                        Value
                                V
                                                                                                        Variable
                                t \succ t^\prime
                                                                                                        Application
                                                                                                        Pattern-match on unit
                                \mathsf{t} \succ \mathsf{case}_m \left\{ \, \mathsf{Inl} \, \mathsf{x}_1 \mapsto \mathsf{u}_1 \,, \, \, \mathsf{Inr} \, \mathsf{x}_2 \mapsto \mathsf{u}_2 \, \right\}
                                                                                                        Pattern-match on sum
                                \mathsf{t} \succ \mathsf{case}_m \left( \mathsf{x}_1 \,,\, \mathsf{x}_2 \right) \mapsto \mathsf{u}
                                                                                                        Pattern-match on product
                                \mathsf{t} \succ \mathsf{case}_m \, \mathsf{E}^n \, \mathsf{x} \mapsto \mathsf{u}
                                                                                                        Pattern-match on exponential
                                t \succ map \times \mapsto t'
                                                                                                        Map over the right side of ampar t
                                                                                                        Wrap u into a trivial ampar
                                to<sub>⋉</sub> u
                                from<sub>k</sub> t
                                                                                                        Extract value from trivial ampar
                                                                                                        Fill destination with unit
                                t ⊲ ()
                                t \mathrel{\triangleleft} \mathsf{InI}
                                                                                                        Fill destination with left variant
                                t ⊲ Inr
                                                                                                        Fill destination with right variant
                                t \triangleleft E^{m}
                                                                                                        Fill destination with exponential constructor
                                t ⊲ (,)
                                                                                                        Fill destination with product constructor
                                                                                                        Fill destination with function
                                t \triangleleft (\lambda \times_m \mapsto u)
                                t \mathrel{\triangleleft} \bullet t'
                                                                                                        Fill destination with root of ampar t'
                                t[x := v]
                                                                                            Μ
val, v
                                                                                                    Term value
                                                                                                        Hole
                                -h
                                                                                                        Destination
                                +h
                                                                                                        Unit
                                                                                                        Lambda abstraction
                                                                                                        Left variant for sum
                                Inl v
                                                                                                        Right variant for sum
                                Inr v
                                E^{\color{red} m} V
                                                                                                        Exponential
                                                                                                        Product
                                (v_1, v_2)
                                _{\mathbf{H}}\!\!\left\langle \mathsf{v}_{2}\,_{\mathsf{9}}\,\,\mathsf{v}_{1}\right
angle
                                                                                                        Ampar
                                v[H \pm h']
                                                                                            Μ
                                                                                                        Shift hole names inside v by \mathbf{h}' if they belong to \mathbf{H}.
```

```
Evaluation context component
ectx, c
                               \square \succ \mathsf{t}'
                                                                                                              Application
                                                                                                              Application
                               V \succ \square
                                                                                                              Pattern-match on unit
                               \square \succ \mathsf{case}_m \left\{ \, \mathsf{Inl} \, \mathsf{x}_1 \mapsto \mathsf{u}_1 \, , \, \, \mathsf{Inr} \, \mathsf{x}_2 \mapsto \mathsf{u}_2 \, \right\}
                                                                                                              Pattern-match on sum
                               \square \succ \mathsf{case}_m (\mathsf{x}_1 \,,\, \mathsf{x}_2) \mapsto \mathsf{u}
                                                                                                              Pattern-match on product
                               \square \succ \mathsf{case}_m \, \mathsf{E}^n \, \mathsf{x} \mapsto \mathsf{u}
                                                                                                              Pattern-match on exponential
                               \square \succ \mathsf{map} \times \mathsf{t}'
                                                                                                              Map over the right side of ampar
                               to<sub>⋉</sub> □
                                                                                                              Wrap into a trivial ampar
                               from_{\ltimes} \square
                                                                                                              Extract value from trivial ampar
                               \Box \triangleleft ()
                                                                                                              Fill destination with unit
                               \square \triangleleft \mathsf{InI}
                                                                                                              Fill destination with left variant
                               □ ⊲ Inr
                                                                                                              Fill destination with right variant
                               \square \triangleleft E^{m}
                                                                                                              Fill destination with exponential constructor
                               \Box \triangleleft (,)
                                                                                                              Fill destination with product constructor
                               \Box \triangleleft (\lambda \times_m \mapsto \mathsf{u})
                                                                                                              Fill destination with function
                               \square \triangleleft \bullet \mathsf{t}'
                                                                                                              Fill destination with root of ampar
                               v ⊲• □
                                                                                                              Fill destination with root of ampar
                               _{{\scriptscriptstyle \mathbf{H}}}^{\mathrm{op}}\langle\mathsf{v}_{2}\,\mathsf{\scriptsize{9}}\;\Box
                                                                                                              Open ampar. Only new addition to term shapes
ectxs, C
                                                                                                          Evaluation context stack
                               Represent the empty stack / "identity" evaluation context
                               C \circ c
                                                                                                              Push c on top of C
                               C[\mathbf{h} :=_{\mathbf{H}} \mathbf{v}]
                                                                                                 Μ
                                                                                                              Fill h in C with value v (that may contain holes)
```

### 2 Type system

```
type, T, U
                                                           Type
                               1
                                                               Unit
                               \mathsf{T}_1 \oplus \mathsf{T}_2
                                                               Sum
                               T_1 \otimes T_2
                                                               Product
                               !^m\mathsf{T}
                                                              Exponential
                               \textbf{U} \ltimes \textbf{T}
                                                               Ampar type (consuming \mathsf{T} yields \mathsf{U})
                               \mathbf{T}_{m}\!\!\rightarrow\!\mathbf{U}
                                                               Function
                               |\mathsf{T}|^m
                                                               Destination
                                                           Mode (Semiring)
mode, m, n
                                                              Pair of a multiplicity and age
                               pa
                                                               Error case (incompatible types, multiplicities, or ages)
                                                    Μ
                                                               Semiring product
                               m_1 \cdot \ldots \cdot m_k
mul, p
                                                           Multiplicity (first component of modality)
                               1
                                                               Linear. Neutral element of the product
                                                               Non-linear. Absorbing for the product
                                                    Μ
                                                               Semiring product
                               p_1, \ldots, p_k
age, a
                                                           Age (second component of modality)
                                                               Born now. Neutral element of the product
                               \uparrow
                                                               One scope older
                                                               Infinitely old / static. Absorbing for the product
                               \infty
                                                               Semiring product
                                                    Μ
                               a_1 \cdot \ldots \cdot a_k
ctx, \Gamma, \Delta, \Pi
                                                           Typing context
                               \{\mathbf{x}: {}_{m}\mathsf{T}\}
                               \{+h: {}_{m}|T|^{n}\}
                               \{-h:T^n\}
                               m \cdot \Gamma
                                                    Μ
                                                              Multiply each binding by m
                               \Gamma_1 + \Gamma_2
                                                    M
                                                              Sum contexts \Gamma_1 and \Gamma_2. Duplicate keys with incompatible values will be tagged
                               \Gamma_1, \Gamma_2
                                                    Μ
                                                               Disjoint sum/union of contexts \Gamma_1 and \Gamma_2.
                                                               Transforms dest bindings into a hole bindings (requires ctx_DestOnly \Gamma and ctx
                                                    Μ
```

```
--1\Gamma
                                                                                                           Transforms hole bindings into dest bindings with left mode 1\nu (requires ctx_HoleOnly \Gamma)
                                    \Gamma[H\pmh^{\prime}]
                                                                         Μ
                                                                                                           Shift hole/dest names by h' if they belong to H
\Gamma \Vdash \mathsf{v} : \mathsf{T}
                                                                                                                                                                                                                                                                                                                                                                                                           (Typing of values (raw))
                                                                                                                                                                                                                                                                                                     TyR-val-F
                                                                                                                                                                                                                                                                                                   \frac{\Delta + \{\mathsf{x} : {}_{m}\mathsf{T}\} \vdash \mathsf{u} : \mathsf{U}}{\Delta \Vdash \lambda^{\mathsf{v}}\mathsf{x}_{m} \mapsto \mathsf{u} : \mathsf{T}_{m} \rightarrow \mathsf{U}} \qquad \frac{\Gamma \sqcap \mathsf{v}_{1} : \mathsf{T}_{1}}{\Gamma \Vdash \mathsf{Inl}\,\mathsf{v}_{1} : \mathsf{T}_{1} \oplus \mathsf{T}_{2}}
TyR-val-H
                                                                                                    TyR-val-D
                                                                                                                                                                                                                                  TyR-val-U
\overline{\{-\mathbf{h}:\mathsf{T}^{\mathit{1}\nu}\}\Vdash -\mathbf{h}:\mathsf{T}} \qquad \overline{\{+\mathbf{h}:{}_{\mathit{1}\nu}[\mathsf{T}]^{\mathit{n}}\}\Vdash +\mathbf{h}:[\mathsf{T}]^{\mathit{n}}} \qquad \overline{\{\}\Vdash ():\mathsf{1}}
                                                                                                                                                                                                                                                                                                                                                  TyR-val-A
                                                                                                                                                                                                                                                                                                                                                  \begin{array}{c} \mathtt{LinOnly} \ \Delta_3 & \mathtt{FinAgeOnly} \ \Delta_3 \\ & \ 1\!\!\uparrow\!\!\cdot\!\Delta_1, \Delta_3 \ \!\Vdash\! \ \mathsf{v}_1 : \mathsf{T} \end{array}
      \frac{ \begin{array}{c} \text{TyR-val-R} \\ \Gamma \Vdash \mathsf{v}_2 : \mathsf{T}_2 \\ \hline \Gamma \Vdash \mathsf{Inr} \mathsf{v}_2 : \mathsf{T}_1 \oplus \mathsf{T}_2 \end{array}}{ \begin{array}{c} \Gamma \mathsf{yR-val-P} \\ \Gamma_1 \Vdash \mathsf{v}_1 : \mathsf{T}_1 & \Gamma_2 \Vdash \mathsf{v}_2 : \mathsf{T}_2 \\ \hline \Gamma_1 + \Gamma_2 \Vdash (\mathsf{v}_1 \,,\, \mathsf{v}_2) : \mathsf{T}_1 \otimes \mathsf{T}_2 \end{array}}
                                                                                                                                                                                                                                \frac{\Gamma_{\mathsf{YR-VAL-E}}}{\Gamma \Vdash \mathsf{v}' : \mathsf{T}}
\frac{\Gamma \Vdash \mathsf{E}^n \mathsf{v}' : !^n \mathsf{T}}{n \cdot \Gamma \Vdash \mathsf{E}^n \mathsf{v}' : !^n \mathsf{T}}
                                                                                                                                                                                                                                                                                                                                                    \frac{\Delta_2, (-\Delta_3) \Vdash \mathsf{v}_2 : \mathsf{U}}{\Delta_1, \Delta_2 \Vdash_{\mathsf{hvars}(-\Delta_3)} \langle \mathsf{v}_2, \mathsf{v}_1 \rangle : \mathsf{U} \ltimes \mathsf{T}}
 \Pi \, \vdash \, t : {\color{red}\mathsf{T}}
                                                                                                                                                                                                                                                                                                                                                                                                                                    (Typing of terms)
                                                                                                                                                                                                                Ty-Term-Var
                                                                                                                                                                                                                 DisposableOnly \Pi
                                Ty-Term-Val
                                                                                                                                                                                                                                                                                                                                        Ty-term-App
                                 DisposableOnly \Pi \Delta \Vdash \mathsf{v}: \mathsf{T}
                                                                                                                                                                                                                                                                                                                                        \Pi_1 \, \vdash \, \mathsf{t} : \mathsf{T} \qquad \Pi_2 \, \vdash \, \mathsf{t}' : \mathsf{T}_{\mathit{m}} \!\! \to \! \mathsf{U}
                                                                                                                                                                                                                                  m <: 1\nu
                                                                                                                                                                                                                                                                                                                                                        m \cdot \Pi_1 + \Pi_2 \vdash \mathsf{t} \succ \mathsf{t}' : \mathsf{U}
                                                                            \Pi, \Delta \vdash \vee : \mathsf{T}
                                                                                                                                                                                                                   \Pi, \{x : {}_m\mathsf{T}\} \vdash x : \mathsf{T}
                                                                                                                                                                                                                    Ty-term-PatS
                                                                                                                                                                                                                                                                                               \Pi_1 \vdash t : \mathsf{T}_1 \oplus \mathsf{T}_2
                                                                                                                                                                                                                                                                               \Pi_2, \{\mathbf{x}_1: {}_m\mathbf{T}_1\} \vdash \mathbf{u}_1: \mathbf{U}
                                                             Ty-term-PatU
                                                             \frac{\Pi_1 \ \vdash \ t : 1 \qquad \Pi_2 \ \vdash \ u : \textbf{U}}{\Pi_1 + \Pi_2 \ \vdash \ t \ ; \ u : \textbf{U}}
                                                                                                                                                                                                                    \frac{\Pi_2, \{\mathsf{x}_2: {}_m\mathsf{T}_2\} \vdash \mathsf{u}_2: \mathsf{U}}{m \cdot \Pi_1 + \Pi_2 \vdash \mathsf{t} \succ \mathsf{case}_m \left\{ \mathsf{Inl} \, \mathsf{x}_1 \mapsto \mathsf{u}_1 \, , \, \mathsf{Inr} \, \mathsf{x}_2 \mapsto \mathsf{u}_2 \right\}: \mathsf{U}}
   Ty-term-PatP
                                                                                                                                                                                     Ty-term-PatE
                                                                                                                                                                                     \begin{array}{ll} \text{TY-TERM-PATE} & \Pi_1 \vdash \textbf{t} : !^n \textbf{T} \\ \Pi_2, \{\textbf{x}: \underline{m \cdot n} \textbf{T}\} \vdash \textbf{u} : \textbf{U} \\ \hline m \cdot \Pi_1 + \Pi_2 \vdash \textbf{t} \succ \textbf{case}_m \ \textbf{E}^n \textbf{x} \mapsto \textbf{u} : \textbf{U} \end{array} \qquad \begin{array}{l} \text{TY-TERM-MAP} \\ \Pi_1 \vdash \textbf{t} : \textbf{U} \ltimes \textbf{T} \\ \hline 1 \uparrow \cdot \Pi_2, \{\textbf{x}: \underline{\imath_{\nu}} \textbf{T}\} \vdash \textbf{t}' : \textbf{T}' \\ \hline \Pi_1 + \Pi_2 \vdash \textbf{t} \succ \textbf{map} \ \textbf{x} \mapsto \textbf{t}' : \textbf{U} \ltimes \textbf{T}' \end{array}
                                                 \Pi_1 \vdash \mathsf{t} : \mathsf{T}_1 \otimes \mathsf{T}_2
     \frac{\Pi_2, \{\mathsf{x}_1: {}_m\mathsf{T}_1\}, \{\mathsf{x}_2: {}_m\mathsf{T}_2\} \, \vdash \, \mathsf{u}: \mathsf{U}}{m{\cdot}\Pi_1 + \Pi_2 \, \vdash \, \mathsf{t} \, \succ \mathsf{case}_m \, (\mathsf{x}_1 \, , \, \mathsf{x}_2) \mapsto \mathsf{u}: \mathsf{U}}
                                                                                                                                                                                                                                                                                                     \begin{array}{ll} \text{TY-TERM-FILLL} & \text{TY-TERM-FILLR} \\ \Pi \vdash \mathsf{t} : \lfloor \mathsf{T}_1 \oplus \mathsf{T}_2 \rfloor^n \\ \Pi \vdash \mathsf{t} \triangleleft \mathsf{Inl} : \lfloor \mathsf{T}_1 \rfloor^n & \Pi \vdash \mathsf{t} \triangleleft \mathsf{Inr} : \lfloor \mathsf{T}_2 \rfloor^n \end{array}
                           Π ⊢ u : U
                                                                                                                                                                                                            \frac{\text{TY-TERM-FILLU}}{\prod \vdash \mathsf{t} : \lfloor \mathsf{1} \rfloor^n} \\ \overline{\prod \vdash \mathsf{t} \triangleleft () : \mathsf{1}}
              Ty-term-ToA
                                                                                                          Ty-term-FromA
                                                                                                                                                                                                             Ty-term-FillU
                                                                                                              \Pi \vdash \mathsf{t} : \mathsf{U} \ltimes \mathsf{1}
               \overline{\Pi \vdash \mathsf{to}_{\ltimes} \mathsf{u} : \mathsf{U} \ltimes \mathsf{1}}
                                                                                                       \Pi \vdash \mathsf{from}_{\mathsf{k}} \, \mathsf{t} : \mathsf{U}
                                                                                                                                                                                                                                                                                                                 Ty-term-FillF
                                                                                                                                                                                                                                                                                                                                              \Pi_1 \vdash \mathsf{t} : \lfloor \mathsf{T}_m \!\!\! \to \mathsf{U} \rfloor^n
                                                                                                                                                                                       Ty-term-FillE
                                         Ty-term-FillP
                                                                                                                                                                                        \frac{\boldsymbol{\Pi} \, \vdash \, \mathsf{t} : \lfloor !^{n'} \, \mathsf{T} \rfloor^n}{\boldsymbol{\Pi} \, \vdash \, \mathsf{t} \triangleleft \, \mathsf{E}^{n'} \, : \lfloor \mathsf{T} \rfloor^{n' \cdot n}}
                                                                                                                                                                                                                                                                                                                                            \Pi_2, \{\mathsf{x}: {}_m\mathsf{T}\} \vdash \mathsf{u}: \mathsf{U}
                                                        \Pi \vdash \mathsf{t} : [\mathsf{T}_1 {\otimes} \mathsf{T}_2]^n
                                                                                                                                                                                                                                                                                                                 \overline{\Pi_1 + (1 \uparrow \cdot n) \cdot \Pi_2} \vdash \mathsf{t} \triangleleft (\lambda \mathsf{x}_m \mapsto \mathsf{u}) : \mathbf{1}
                                         \overline{\Pi \vdash \mathsf{t} \triangleleft (,) : |\mathsf{T}_1|^n \otimes |\mathsf{T}_2|^n}
                                                                                                                                                                                 TY-TERM-FILLC
                                                                                                                                                                                 \frac{\Pi_1 \vdash \mathsf{t} : \lfloor \mathsf{U} \rfloor^n \qquad \Pi_2 \vdash \mathsf{t}' : \mathsf{U} \ltimes \mathsf{T}}{\Pi_1 + (1 \!\!\uparrow \!\!\cdot \!\! n) \cdot \! \Pi_2 \vdash \mathsf{t} \triangleleft \!\!\bullet \!\! \mathsf{t}' : \mathsf{T}}
  \Delta \dashv \mathsf{C} : \mathsf{T} {\rightarrowtail} \mathsf{U}_0
                                                                                                                                                                                                                                                                                                                                                                                 (Typing of evaluation contexts)
                                                                                                                                                                                                                                                                                                                Ty-ectxs-AppFoc2
                                                                                                                                                         TY-ECTXS-APPFOC1
                                                                                                                                                                                                                                                                                                                \frac{m \cdot \Delta_{1}, \Delta_{2} \dashv \mathsf{C} : \mathsf{U} \!\!\!\! \rightarrow \!\!\! \mathsf{U}_{0}}{\Delta_{1} \vdash \mathsf{v} : \mathsf{T}} \\ \frac{\Delta_{2} \dashv \mathsf{C} \circ (\mathsf{v} \succ \square) : (\mathsf{T}_{m} \!\!\!\! \rightarrow \!\!\! \mathsf{U}) \!\!\!\! \rightarrow \!\!\! \mathsf{U}_{0}}{\Delta_{2} \dashv \mathsf{C} \circ (\mathsf{v} \succ \square) : (\mathsf{T}_{m} \!\!\!\! \rightarrow \!\!\! \mathsf{U}) \!\!\!\! \rightarrow \!\!\! \mathsf{U}_{0}}
                                                                                                                                                         \frac{m \cdot \Delta_{1}, \Delta_{2} \dashv \mathsf{C} : \mathsf{U} \rightarrowtail \mathsf{U}_{0}}{\Delta_{2} \vdash \mathsf{t}' : \mathsf{T}_{m} \rightarrowtail \mathsf{U}}
\frac{\Delta_{1} \dashv \mathsf{C} \circ (\Box \succ \mathsf{t}') : \mathsf{T} \rightarrowtail \mathsf{U}_{0}}{\Delta_{1} \dashv \mathsf{C} \circ (\Box \succ \mathsf{t}') : \mathsf{T} \rightarrowtail \mathsf{U}_{0}}
                                           Ty-ectxs-Id
                                            \overline{\{\}} \dashv \Box : \mathbf{U}_0 \rightarrow \mathbf{U}_0
                                                                                                                                                                                                          TY-ECTXS-PATSFOC
                                                                                                                                                                                                                                                                                              m \cdot \Delta_1, \Delta_2 \dashv \mathsf{C} : \mathbf{U} \rightarrowtail \mathbf{U}_0
                                                                                                                                                                                                                                                                                            \Delta_2, \{\mathsf{x}_1: {}_m\mathsf{T}_1\} \vdash \mathsf{u}_1: \mathsf{U}
                           Ty-ectxs-PatUFoc
                            \frac{\Delta_1, \Delta_2 \dashv \mathsf{C} : \mathsf{U} {\rightarrowtail} \mathsf{U}_0 \qquad \Delta_2 \vdash \mathsf{u} : \mathsf{U}}{\Delta_1 \dashv \mathsf{C} \circ (\Box \; ; \mathsf{u}) : 1 {\rightarrowtail} \mathsf{U}_0}
                                                                                                                                                                                                                                                                                         \Delta_2, \{ \mathbf{x}_2 : {}_m \mathbf{T}_2 \} \vdash \mathbf{u}_2 : \mathbf{U}
                                                                                                                                                                          \overline{\Delta_1 \dashv \mathsf{C} \circ (\Box \succ \mathsf{case}_m \, \{ \, \mathsf{Inl} \, \mathsf{x}_1 \mapsto \mathsf{u}_1 \, , \, \, \mathsf{Inr} \, \mathsf{x}_2 \mapsto \mathsf{u}_2 \, \}) : (\mathsf{T}_1 \oplus \mathsf{T}_2) \mapsto \mathsf{U}_0}
                                                                                                                                                                                                                                                                                TY-ECTXS-PATEFOC
                                   Ty-ectxs-PatPFoc
                                                                                                                                                                                                                                                                                                                            m \cdot \Delta_1, \Delta_2 \dashv \mathsf{C} : \mathsf{U} \rightarrow \mathsf{U}_0
                                                                                          m \cdot \Delta_1, \Delta_2 \dashv C : \mathbf{U} \rightarrow \mathbf{U}_0
                                                                                                                                                                                                                                                                                                                           \Delta_2, \{\mathbf{x}: {}_{m \cdot m'}\mathbf{T}\} \vdash \mathbf{u}: \mathbf{U}
                                    \frac{\Delta_2, \{\mathbf{x}_1: {}_m \mathbf{T}_1\}, \{\mathbf{x}_2: {}_m \mathbf{T}_2\} \vdash \mathbf{u}: \mathbf{U}}{\Delta_1 \dashv \mathsf{C} \mathrel{\circ} (\square \succ \mathsf{case}_m \left(\mathbf{x}_1 \,, \, \mathbf{x}_2\right) \mapsto \mathbf{u}) : (\mathbf{T}_1 \otimes \mathbf{T}_2) \mapsto \mathbf{U}_0}
                                                                                                                                                                                                                                                                                 \Delta_1 \dashv \mathsf{C} \circ (\Box \succ \mathsf{case}_m \, \mathsf{E}^{m'} \times \mapsto \mathsf{u}) : !^{m'} \, \mathsf{T} \mapsto \mathsf{U}_0
```

```
TY-ECTXS-MAPFOC
                                          \Delta_1, \Delta_2 \dashv \mathsf{C} : \mathsf{U} \ltimes \mathsf{T}' \rightarrowtail \mathsf{U}_0
                                                                                                                                                                              Ty-ectxs-ToAFoc
                                                                                                                                                                                                                                                                                          Ty-ectxs-FromAfoc
             \frac{1\!\!\uparrow\!\!\cdot\!\Delta_2,\{\times:{}_{1\!\nu}\mathsf{T}\}\vdash\mathsf{t}':\mathsf{T}'}{\Delta_1\,\dashv\,\mathsf{C}\,\circ\,(\Box\,\succ\,\mathsf{map}\,\times\!\mapsto\!\mathsf{t}'):(\mathsf{U}\,\times\,\mathsf{T})\!\!\mapsto\!\!\mathsf{U}_0}
                                                                                                                                                                                                                                                                                            \Delta \dashv \mathsf{C} : \mathsf{U} {\rightarrowtail} \mathsf{U}_0
                                                                                                                                                                               \Delta \dashv \mathsf{C} : (\mathsf{U} \ltimes \mathsf{1}) {\rightarrowtail} \mathsf{U}_0
                                                                                                                                                                               \Delta \dashv \mathsf{C} \circ (\mathsf{to}_{\bowtie} \square) : \mathsf{U} \rightarrow \mathsf{U}_0
                                                                                                                                                                                                                                                                                           \Delta \dashv \mathsf{C} \circ (\mathsf{from}_{\bowtie} \square) : (\mathsf{U} \bowtie \mathsf{1}) \rightarrowtail \mathsf{U}_0
              TY-ECTXS-FILLUFOC
                                                                                                                                                                                                                                                                                  Ty-ectxs-FillRfoc
                                                                                                                                     Ty-ectxs-FillLFoc
                                                                                                                                       \Delta \dashv C: [\mathsf{T}_1]^n \mapsto \mathsf{U}_0
                                                                                                                                                                                                                                                                                                          \Delta \dashv C: [\mathsf{T}_2]^n \mapsto \mathsf{U}_0
                                     \Delta \dashv C : 1 \rightarrow U_0
                \overbrace{\Delta \dashv \mathsf{C} \circ (\Box \triangleleft ()) : [\mathbf{1}]^n \rightarrowtail \mathbf{U}_0}^{\circ}
                                                                                                                                     \Delta \dashv \mathsf{C} \circ (\Box \triangleleft \mathsf{Inl}) : |\mathsf{T}_1 \oplus \mathsf{T}_2|^n \rightarrowtail \mathsf{U}_0
                                                                                                                                                                                                                                                                                  \Delta \dashv \mathsf{C} \circ (\Box \triangleleft \mathsf{Inr}) : |\mathsf{T}_1 \oplus \mathsf{T}_2|^n \mapsto \mathsf{U}_0
                                                                                                                                                                                                                                                                Ty-ectxs-fillffoc
                                                                                                                                                                                                                                                                                                \Delta_1, (1\!\!\uparrow\!\!\cdot\! n){\cdot}\Delta_2 \dashv \mathsf{C}: 1\!\!\rightarrowtail\!\!\mathsf{U}_0
Ty-ectxs-fillPfoc
                                                                                                                                   TY-ECTXS-FILLEFOC
                                                                                                                                                       \Delta \dashv C : [T]^{m \cdot n} \rightarrow U_0
         \Delta \dashv \mathsf{C} : \overline{([\mathsf{T}_1]^n \otimes [\mathsf{T}_2]^n)} \rightarrow \mathsf{U}_0
                                                                                                                                                                                                                                                                 \frac{\Delta_2, \{\mathbf{x}: {}_m\mathbf{T}\} \vdash \mathbf{u}: \mathbf{U}}{\Delta_1 \dashv \mathbf{C} \circ (\Box \triangleleft (\lambda \mathbf{x}_m \mapsto \mathbf{u})) : [\mathbf{T}_m \!\!\rightarrow\! \mathbf{U}]^n \!\!\mapsto\! \mathbf{U}_0}
\overline{\Delta \dashv \mathsf{C} \circ (\Box \triangleleft (,)) : [\mathsf{T}_1 \otimes \mathsf{T}_2]^n \rightarrowtail \mathsf{U}_0}
                                                                                                                                   \overline{\Delta + \mathsf{C} \circ (\Box \triangleleft \mathsf{E}^m) : |!^m \mathsf{T}|^n \rightarrowtail \mathsf{U}_0}
                                                                                                                                                                                                                                                             TY-ECTXS-AOPENFOC
                                                                                                                                                                                                                                                                                       hvars(C) ## hvars(-\Delta_3)
                                                                                                                                                                                                                                                                          \begin{array}{ccc} \mathtt{LinOnly} \ \Delta_3 & \mathtt{FinAgeOnly} \ \Delta_3 \\ \Delta_1, \Delta_2 \dashv \mathsf{C} : (\mathsf{U} \ltimes \mathsf{T}') {\rightarrowtail} \mathsf{U}_0 \end{array}
        Ty-ectxs-FillCFoc1
                                                                                                                                  Ty-ectxs-FillCFoc2
                \Delta_1, (1 \uparrow \cdot n) \cdot \Delta_2 \dashv \mathsf{C} : \mathsf{T} \rightarrowtail \mathsf{U}_0
                                                                                                                                         \Delta_1, (1 \uparrow \cdot n) \cdot \Delta_2 \dashv \mathsf{C} : \mathsf{T} \rightarrow \mathsf{U}_0
                                                                                                                                                                                                                                                            \frac{\Delta_2, -\Delta_3 \Vdash \mathsf{v}_2 : \mathsf{U}}{\cancel{t} \uparrow \cdot \Delta_1, \Delta_3 \dashv \mathsf{C} \circ \binom{\mathsf{op}}{\mathsf{hvars}(-\Delta_3)} \langle \mathsf{v}_2, \square) : \mathsf{T}' \rightarrowtail \mathsf{U}_0}
                                                                                                                                  \frac{\Delta_1 \, \vdash \, \mathbf{v} : \lfloor \mathbf{U} \rfloor^n}{\Delta_2 \, \dashv \, \mathbf{C} \, \circ \, (\mathbf{v} \, \sphericalangle \bullet \, \square) : \mathbf{U} \, \bowtie \, \mathbf{T} \rightarrowtail \mathbf{U}_0}
                     \Delta_2 \, \vdash \, \mathsf{t}' : \mathsf{U} \ltimes \mathsf{T}
         \overline{\Delta_1 \dashv \mathsf{C} \circ (\Box \triangleleft \bullet \mathsf{t}') : |\mathsf{U}|^n \rightarrowtail \mathsf{U}_0}
```

 $\vdash C[t] : T$ 

(Typing of extended terms (pair of evaluation context and term))

$$\frac{\Delta \dashv C: \textbf{T} {\longmapsto} \textbf{U}_0 \qquad \Delta \vdash \textbf{t}: \textbf{T}}{\vdash C[\textbf{t}]: \textbf{U}_0}$$

## 3 Small-step semantics

 $C[t] \longrightarrow C'[t']$ (Small-step evaluation of terms using evaluation contexts) Sem-eterm-AppFoc1 SEM-ETERM-APPFOC2 SEM-ETERM-APPUNFOC1 NotVal t  $\frac{}{\mathsf{C}[\mathsf{t} \succ \mathsf{t}'] \longrightarrow (\mathsf{C} \circ (\square \succ \mathsf{t}'))[\mathsf{t}]}$  $C[v \succ t'] \longrightarrow (C \circ (v \succ \Box))[t']$  $\frac{(\mathsf{C} \circ (\Box \succ \mathsf{t}'))[\mathsf{v}] \longrightarrow \mathsf{C}[\mathsf{v} \succ \mathsf{t}']}{}$ SEM-ETERM-PATUFOC SEM-ETERM-APPUNFOC2 SEM-ETERM-APPRED NotVal t  $\overline{C[v \succ (\lambda^{v} \times_{m} \mapsto u)] \longrightarrow C[u[x \coloneqq v]]}$  $\overline{(\mathsf{C} \circ (\mathsf{v} \succ \Box))[\mathsf{v}'] \longrightarrow \mathsf{C}[\mathsf{v} \succ \mathsf{v}']}$  $\overline{\mathsf{C}[\mathsf{t}\;;\mathsf{u}]\;\longrightarrow\;(\mathsf{C}\;\circ\;(\Box\;;\mathsf{u}))[\mathsf{t}]}$ SEM-ETERM-PATUUNFOC SEM-ETERM-PATURED  $C[();u] \longrightarrow C[u]$  $(C \circ (\Box ; u))[v] \longrightarrow C[v ; u]$ SEM-ETERM-PATSFOC NotVal t  $\overline{\mathsf{C}[\mathsf{t} \succ \mathsf{case}_m \, \{\, \mathsf{Inl} \, \mathsf{x}_1 \mapsto \mathsf{u}_1 \,, \,\, \mathsf{Inr} \, \mathsf{x}_2 \mapsto \mathsf{u}_2 \, \}]} \,\, \longrightarrow \,\, (\mathsf{C} \, \circ \, (\Box \, \succ \mathsf{case}_m \, \{\, \mathsf{Inl} \, \mathsf{x}_1 \mapsto \mathsf{u}_1 \,, \,\, \mathsf{Inr} \, \mathsf{x}_2 \mapsto \mathsf{u}_2 \, \}))[\mathsf{t}]$ SEM-ETERM-PATSUNFOC  $(C \circ (\Box \succ \mathsf{case}_m \{ \mathsf{Inl} \, \mathsf{x}_1 \mapsto \mathsf{u}_1 \,, \, \mathsf{Inr} \, \mathsf{x}_2 \mapsto \mathsf{u}_2 \}))[\mathsf{v}] \longrightarrow C[\mathsf{v} \succ \mathsf{case}_m \{ \, \mathsf{Inl} \, \mathsf{x}_1 \mapsto \mathsf{u}_1 \,, \, \, \mathsf{Inr} \, \mathsf{x}_2 \mapsto \mathsf{u}_2 \, \}]$ SEM-ETERM-PATLRED  $C[(Inl v_1) \succ case_m \{ Inl x_1 \mapsto u_1, Inr x_2 \mapsto u_2 \}] \longrightarrow C[u_1[x_1 \coloneqq v_1]]$ SEM-ETERM-PATRRED  $C[(\operatorname{Inr} \mathsf{v}_2) \succ \mathsf{case}_m \{ \operatorname{Inl} \mathsf{x}_1 \mapsto \mathsf{u}_1, \operatorname{Inr} \mathsf{x}_2 \mapsto \mathsf{u}_2 \}] \longrightarrow C[\mathsf{u}_2[\mathsf{x}_2 \coloneqq \mathsf{v}_2]]$ SEM-ETERM-PATPFOC  $\frac{\Box}{\mathsf{C}[\mathsf{t} \succ \mathsf{case}_m \, (\mathsf{x}_1 \,,\, \mathsf{x}_2) \mapsto \mathsf{u}] \,\, \longrightarrow \,\, (\mathsf{C} \circ (\Box \succ \mathsf{case}_m \, (\mathsf{x}_1 \,,\, \mathsf{x}_2) \mapsto \mathsf{u}))[\mathsf{t}]}$ SEM-ETERM-PATPUNFOC  $(\mathsf{C} \circ (\Box \succ \mathsf{case}_m(\mathsf{x}_1, \mathsf{x}_2) \mapsto \mathsf{u}))[\mathsf{v}] \longrightarrow \mathsf{C}[\mathsf{v} \succ \mathsf{case}_m(\mathsf{x}_1, \mathsf{x}_2) \mapsto \mathsf{u}]$ SEM-ETERM-PATEFOC SEM-ETERM-PATPRED  $\overline{\mathsf{C}[(\mathsf{v}_1\,,\,\mathsf{v}_2)\succ\mathsf{case}_m\,(\mathsf{x}_1\,,\,\mathsf{x}_2)\mapsto\mathsf{u}]}\ \longrightarrow\ \overline{\mathsf{C}[\mathsf{u}[\mathsf{x}_1\coloneqq\mathsf{v}_1][\mathsf{x}_2\coloneqq\mathsf{v}_2]]}\ \overline{\mathsf{C}[\mathsf{t}\succ\mathsf{case}_m\,\mathsf{E}^n\,\mathsf{x}\mapsto\mathsf{u}]\ \longrightarrow\ (\mathsf{C}\circ(\Box\succ\mathsf{case}_m\,\mathsf{E}^n\,\mathsf{x}\mapsto\mathsf{u}))[\mathsf{t}]}$ SEM-ETERM-PATEUNFOC SEM-ETERM-PATERED  $\overline{\mathsf{C}[\mathtt{E}^n\,\mathsf{v}'\,\succ\mathsf{case}_m\,\mathtt{E}^n\,\mathsf{x}\mapsto\mathsf{u}]}\,\,\longrightarrow\,\,\mathsf{C}[\mathsf{u}[\mathsf{x}\coloneqq\mathsf{v}']]$  $(\mathsf{C} \circ (\Box \succ \mathsf{case}_m \, \mathsf{E}^n \mathsf{x} \mapsto \mathsf{u}))[\mathsf{v}] \longrightarrow \mathsf{C}[\mathsf{v} \succ \mathsf{case}_m \, \mathsf{E}^n \mathsf{x} \mapsto \mathsf{u}]$ SEM-ETERM-MAPFOC SEM-ETERM-MAPUNFOC NotVal t  $\frac{}{\mathsf{C}[\mathsf{t}\succ\mathsf{map}\;\mathsf{x}\mapsto\mathsf{t}']\;\longrightarrow\;(\mathsf{C}\circ(\Box\succ\mathsf{map}\;\mathsf{x}\mapsto\mathsf{t}'))[\mathsf{t}]}}\frac{}{(\mathsf{C}\circ(\Box\succ\mathsf{map}\;\mathsf{x}\mapsto\mathsf{t}'))[\mathsf{v}]\;\longrightarrow\;\mathsf{C}[\mathsf{v}\succ\mathsf{map}\;\mathsf{x}\mapsto\mathsf{t}']}$ SEM-ETERM-MAPREDAOPENFOC SEM-ETERM-AOPENUNFOC h' = max(hvars(C))+1 $\overline{\mathsf{C}_{[\mathtt{H}}\!\langle \mathsf{v}_2\,,\,\mathsf{v}_1\rangle \,\succ\, \mathsf{map}\,\,\mathsf{x}\!\mapsto\! \mathsf{t}']} \,\longrightarrow\, \big(\mathsf{C}\,\circ\, \big(\begin{smallmatrix} \mathsf{op} \\ \mathsf{H} \!\succeq\! \mathsf{h}' \end{smallmatrix}\big/\mathsf{v}_2\big[\mathtt{H} \!\succeq\! \mathsf{h}'\big]\,,\, \square\big)\big)[\mathsf{t}'[\mathsf{x} \coloneqq \mathsf{v}_1\big[\mathtt{H} \!\succeq\! \mathsf{h}'\big]]]} \qquad \qquad \overline{\big(\mathsf{C}\,\circ\, \begin{smallmatrix} \mathsf{op} \\ \mathsf{H} \end{smallmatrix}\big/\mathsf{v}_2\,,\, \square\big)[\mathsf{v}_1]} \,\longrightarrow\, \mathsf{C}_{[\mathtt{H}}\!\langle \mathsf{v}_2\,,\, \mathsf{v}_1\rangle\big]}$ SEM-ETERM-TOAFOC SEM-ETERM-TOAUNFOC SEM-ETERM-TOARED NotVal u  $\overline{(\mathsf{C} \, \circ \, (\mathbf{to}_{\ltimes} \, \square))[\mathsf{v}_2] \, \longrightarrow \, \mathsf{C}[\mathbf{to}_{\ltimes} \, \mathsf{v}_2]}$  $C[\mathbf{to}_{\bowtie} \ \mathsf{u}] \longrightarrow (C \circ (\mathbf{to}_{\bowtie} \square))[\mathsf{u}]$  $C[\mathbf{to}_{\ltimes} \mathsf{v}_2] \longrightarrow C[\{\{\{\mathsf{v}_2,\mathsf{v}()\}\}]$ SEM-ETERM-FROMAFOC SEM-ETERM-FROMAUNFOC SEM-ETERM-FROMARED  $(\mathsf{C} \circ (\mathsf{from}_{\ltimes} \square))[\mathsf{v}] \longrightarrow \mathsf{C}[\mathsf{from}_{\ltimes} \mathsf{v}]$  $C[from_{\times} \{ \} \langle v_2, () \rangle] \longrightarrow C[v_2]$  $C[from_{\ltimes} t] \longrightarrow (C \circ (from_{\ltimes} \square))[t]$ SEM-ETERM-FILLUFOC SEM-ETERM-FILLUUNFOC SEM-ETERM-FILLURED NotVal t  $\frac{\mathsf{C}[\mathsf{t} \triangleleft ()] \longrightarrow (\mathsf{C} \circ (\square \triangleleft ()))[\mathsf{t}]}{\mathsf{c}[\mathsf{t} \triangleleft ()]}$  $(C \circ (\Box \triangleleft ()))[v] \longrightarrow C[v \triangleleft ()]$  $C[+h \triangleleft ()] \longrightarrow C[h:=_{\{\}} ()][()]$ 

```
SEM-ETERM-FILLLFOC
                                                                                                                                                                   Sem-eterm-FillLRed
                                                                                Sem-eterm-fillLunfoc
                                                                                                                                                                  \frac{\mathbf{h}' = \max(\mathbf{h} \vee \mathbf{vars}(\mathsf{C}) \cup \{\mathbf{h}\}) + 1}{\mathsf{C}[+\mathbf{h} \triangleleft \mathsf{InI}] \longrightarrow \mathsf{C}[\mathbf{h} :=_{\{\mathbf{h}'+1\}} \mathsf{InI} - (\mathbf{h}'+1)][+(\mathbf{h}'+1)]}
                      NotVal t
\overline{\mathsf{C}[\mathsf{t} \triangleleft \mathsf{Inl}] \ \longrightarrow \ (\mathsf{C} \circ (\Box \triangleleft \mathsf{Inl}))}[\mathsf{t}]
                                                                        \overline{(\mathsf{C} \circ (\Box \triangleleft \mathsf{InI}))[\mathsf{v}] \longrightarrow \mathsf{C}[\mathsf{v} \triangleleft \mathsf{InI}]}
                                               SEM-ETERM-FILLRFOC
                                                                                                                                                         SEM-ETERM-FILLRUNFOC
                                                                     NotVal t
                                               \overline{\mathsf{C}[\mathsf{t} \triangleleft \mathsf{Inr}] \ \longrightarrow \ (\mathsf{C} \circ (\square \triangleleft \mathsf{Inr}))[\mathsf{t}]}
                                                                                                                                                         (C \circ (\Box \triangleleft Inr))[v] \longrightarrow C[v \triangleleft Inr]
                               Sem-eterm-FillRred
                                                                                                                                                                         SEM-ETERM-FILLEFOC
                                                     h' = \max(hvars(C) \cup \{h\}) + 1
                                                                                                                                                                         \frac{\text{NotVal t}}{\mathsf{C}[\mathsf{t} \triangleleft \mathsf{E}^m \,] \, \longrightarrow \, (\mathsf{C} \circ (\Box \triangleleft \mathsf{E}^m))[\mathsf{t}]}
                               \overline{C[+h \triangleleft Inr] \longrightarrow C[h :=_{\{h'+1\}} Inr - (h'+1)][+(h'+1)]}
                                                                                                                                  Sem-eterm-fillEred
                             SEM-ETERM-FILLEUNFOC
                                                                                                                                  \frac{\mathbf{h}' = \max(\mathbf{h} \mathbf{vars}(\mathsf{C}) \cup \{\mathbf{h}\}) + 1}{\mathsf{C}[+\mathbf{h} \triangleleft \mathbf{E}^m] \longrightarrow \mathsf{C}[\mathbf{h} :=_{\{\mathbf{h}'+1\}} \mathbf{E}^m - (\mathbf{h}'+1)][+(\mathbf{h}'+1)]}
                              (\mathsf{C} \circ (\Box \triangleleft \mathsf{E}^m))[\mathsf{v}] \longrightarrow \mathsf{C}[\mathsf{v} \triangleleft \mathsf{E}^m]
                                                 SEM-ETERM-FILLPFOC
                                                                                                                                                         SEM-ETERM-FILLPUNFOC
                                                                       NotVal t
                                                  \overline{\mathsf{C}[\mathsf{t} \triangleleft (,)]} \longrightarrow (\mathsf{C} \circ (\square \triangleleft (,)))[\mathsf{t}]
                                                                                                                                                          (C \circ (\Box \triangleleft (,)))[v] \longrightarrow C[v \triangleleft (,)]
                                                     \frac{h' = \max(hvars(C) \cup \{h\}) + 1}{C[+h \triangleleft (,)] \longrightarrow C[h :=_{\{h'+1,h'+2\}} (-(h'+1), -(h'+2))][(+(h'+1), +(h'+2))]}
                  SEM-ETERM-FILLFFOC
                                                                                                                                                  SEM-ETERM-FILLFUNFOC
                                                           NotVal t
                  \overline{\mathbb{C}[\mathsf{t} \triangleleft (\lambda \times_m \mapsto \mathsf{u})] \ \longrightarrow \ (\mathbb{C} \circ (\square \triangleleft (\lambda \times_m \mapsto \mathsf{u})))[\mathsf{t}]}
                                                                                                                                                 (\mathsf{C} \circ (\Box \triangleleft (\lambda \times_m \mapsto \mathsf{u})))[\mathsf{v}] \longrightarrow \mathsf{C}[\mathsf{v} \triangleleft (\lambda \times_m \mapsto \mathsf{u})]
                                                                                                                         SEM-ETERM-FILLCFOC1
  SEM-ETERM-FILLFRED
                                                                                                                                                                                                         SEM-ETERM-FILLCUNFOC1
                                                                                                                                             NotVal t
  \overline{\mathsf{C}[+\mathtt{h} \triangleleft (\lambda \mathsf{x}_m \mapsto \mathsf{u})] \ \longrightarrow \ \mathsf{C}[\mathtt{h} \coloneqq_{\{\,\}} \ \lambda^{\mathsf{v}} \mathsf{x}_m \mapsto \mathsf{u}][()]}
                                                                                                                        \overline{C[t \triangleleft \bullet t'] \ \longrightarrow \ (C \circ (\Box \triangleleft \bullet t'))[t]} \qquad \overline{(C \circ (\Box \triangleleft \bullet t'))[v] \ \longrightarrow \ C[v \triangleleft \bullet t']}
Sem-eterm-FillCFoc2
                                                                                                                                                                 SEM-ETERM-FILLCRED
                                                                               Sem-eterm-FillCUnfoc2
                                                                                                                                                                                     h' = max(hvars(C) \cup \{h\}) + 1
                     NotVal t'
```

# 4 Remarks on the Coq proofs

- Not particularly elegant. Max number of goals observed 232 (solved by a single call to the congruence tactic). When you have a computer, brute force is a viable strategy. (in particular, no semiring formalisation, it was quicker to do directly)
- Rules generated by ott, same as in the article (up to some notational difference). Contexts are not generated purely by syntax, and are interpreted in a semantic domain (finite functions).
- Reasoning on closed terms avoids almost all complications on binder manipulation. Makes proofs tractable.
- Finite functions: making a custom library was less headache than using existing libraries (including MMap). Existing libraries don't provide some of the tools that we needed, but the most important factor ended up being the need for a modicum of dependency between key and value. There wasn't really that out there. Backed by actual functions for simplicity; cost: equality is complicated.
- Most of the proofs done by author with very little prior experience to Coq.
- Did proofs in Coq because context manipulations are tricky.
- Context sum made total by adding an extra invalid *mode* (rather than an extra context). It seems to be much simpler this way.
- It might be a good idea to provide statistics on the number of lemmas and size of Coq codebase.
- (possibly) renaming as permutation, inspired by nominal sets, make more lemmas don't require a condition (but some lemmas that wouldn't in a straight renaming do in exchange).
- (possibly) methodology: assume a lot of lemmas, prove main theorem, prove assumptions, some wrong, fix. A number of wrong lemma initially assumed, but replacing them by correct variant was always easy to fix in proofs.
- Axioms that we use and why (in particular setoid equality not very natural with ott-generated typing rules).
- Talk about the use and benefits of Copilot.