A linear  $\lambda$ -calculus for pure, functional memory updates

ARNAUD SPIWACK, Modus Create, France THOMAS BAGREL, LORIA/Inria, France and Modus Create, France

We present the destination calculus, a linear  $\lambda$ -calculus for pure, functional memory updates. We introduce the syntax, type system, and operational semantics of the destination calculus, and prove type safety formally in the Coq proof assistant.

We show how the principles of the destination calculus can form a theoretical ground for destination-passing style programming in functional languages. In particular, we detail how the present work can be applied to Linear Haskell to lift the main restriction of DPS programming in Haskell as developed in [1]. We illustrate this with a range of pseudo-Haskell examples.

#### **ACM Reference Format:**

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POPL'25, January 19 – 25, 2025, Denver, Colorado

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ACM ISBN 978-x-xxxx-xxxx-x/YY/MM...\$15.00

https://doi.org/10.1145/nnnnnnn.nnnnnnn

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# 1 INTRODUCTION

Destination-passing style programming takes its root in the early days of imperative programming. In such language, the programmer is responsible for managing memory allocation and deallocation, and thus is it often unpractical for function calls to allocate memory for their results themselves. Instead, the caller allocates memory for the result of the callee, and passes the address of this output memory cell to the callee as an argument. This is called an *out parameter*, *mutable reference*, or even *destination*.

But destination-passing style is not limited to imperative settings; it can be used in functional programming as well. One example is the linear destination-based API for arrays in Haskell[?], which enables the user to build an array efficiently in a write-once fashion, without sacrificing the language identity and main guarantees. In this context, a destination points to a yet-unfilled memory slot of the array, and is said to be *consumed* as soon as the associated hole is filled. In this paper, we continue on the same line: we present a linear  $\lambda$ -calculus embedding the concept of *destinations* as first-class values, in order to provide a write-once memory scheme for pure, functional programming languages.

Why is it important to have destinations as first-class values? Because it allows the user to store them in arbitrary control or data structures, and thus to build complex data structures in arbitrary order/direction. This is a key feature of first-class DPS APIs, compared to ones in which destinations are inseparable from the structure they point to. In the latter case, the user is still forced to build the structure in its canonical order (e.g. from the leaves up to the root of the structure when using data constructors).

# 2 SYSTEM IN ACTION ON SIMPLE EXAMPLES

The idea of destination calculus is to provide a building canvas for data structures, represented as a special pair-like structure, called an *ampar*, whose left side is the structure being built, and whose right side carries destinations pointing to holes present in the left side.

A *hole*, denoted h in the language, is a memory cell that has not been written to yet. In a practical application, a *hole* would contain garbage data left by the previous use of the memory location, and thus should not be read in any circumstances (or it could lead to a segmentation fault!).

A destination, denoted  $\rightarrow$ h, is the address of a hole. It is meant to be one-use only; unlike mutable references which can often be reused.

The simplest form of ampar is a single empty cell on the left with a destination pointing to it on the right:  $\{h\}\langle h_{\Lambda} \rightarrow h\rangle$ . This ampar is highly analogous to the identity function: the final structure on the left side will correspond to what is fed in the right side.

The main operation to operate on an ampar is map, which binds the right side of the ampar to a variable, while temporarily forgetting about the left side (the incomplete structure that is being mutated behind the scenes).

```
\{h\}(h_{\wedge} \to h) \triangleright \text{map } d \mapsto d \triangleleft \text{Inl } () \text{ reduces to } \{h'\} \langle \text{Inl } h'_{\wedge} \to h' \rangle \text{ then to } \{\} \langle \text{Inl } ()_{\wedge} () \rangle \}
```

The destination-filling primitive  $\triangleleft$ Inl will in fact follow the destination on the left-hand side and write an Inl data constructor to the hole pointed by the destination. A new destination  $\rightarrow h'$  is returned to represented the (yet unspecified) payload for the Inl constructor.

This new destination  $\rightarrow h'$  is then passed to the destination-filling primitive  $\triangleleft$ (), which writes a unit value to the hole pointed by  $\rightarrow h'$ . The unit data constructor () doesn't hold any payload, so there is no new destination to return here (so () is returned by the primitive instead).

Arbitrary building order. As mentioned earlier, one key point of destination calculus is being able to build a structure in any desired order. For example, one can build a balanced binary tree of depth two by first building the skeleton, then giving values to the right leaves, then to the left leaves.

Let's build the skeleton first:

```
\begin{split} t_1 &:=_{\{h_1\}} \langle h_1 \,_{\wedge} \to h_1 \rangle \rhd \mathsf{map} \, d_1 \mapsto \\ d_1 \,_{\triangleleft} \, (,) &\rhd \mathsf{case}_{1\nu} \, (d_2 \,, d_3) \mapsto \\ d_2 \,_{\triangleleft} \, (,) &\rhd \mathsf{case}_{1\nu} \, (d_4 \,, d_5) \mapsto \\ d_3 \,_{\triangleleft} \, (,) &\rhd \mathsf{case}_{1\nu} \, (d_6 \,, d_7) \mapsto {}^s [d_4, d_5, d_6, d_7] \\ \mathsf{evaluates} \, \mathsf{to:} \\ &\{h_4, h_5, h_6, h_7\} \langle ((h_4 \,, h_5) \,, (h_6 \,, h_7)) \,_{\wedge} \,^s [\to h_4, \to h_5, \to h_6, \to h_7] \rangle \end{split}
```

We can see that the skeleton of the tree is here on the left-hand side, but leaves are unspecified yet (so are represented by holes). Let's now fill the right leaves:

```
\begin{array}{l} t_{2} \coloneqq t_{1} \rhd \mathsf{map} \, \mathsf{d} \mapsto \\ \mathsf{d} \rhd \mathsf{case}_{1\nu} \, {}^{s} [\mathsf{d}_{4}, \mathsf{d}_{5}, \mathsf{d}_{6}, \mathsf{d}_{7}] \mapsto \\ \mathsf{d}_{5} \blacktriangleleft \mathsf{Inr} \blacktriangleleft () \, ; \mathsf{d}_{7} \blacktriangleleft \mathsf{Inr} \blacktriangleleft () \, ; {}^{s} [\mathsf{d}_{4}, \mathsf{d}_{6}] \\ \mathsf{reduces} \, \mathsf{to} \\ \{\mathsf{h}_{4}, \mathsf{h}_{6}\} \langle ((\mathsf{h}_{4}, \mathsf{Inr}\, ()), (\mathsf{h}_{6}, \mathsf{Inr}\, ())) \, {}_{\Lambda} \, {}^{s} [\rightarrow \mathsf{h}_{4}, \rightarrow \mathsf{h}_{6}] \rangle \end{array}
```

Now only left leaves are left unspecified, that's why the associated destinations  $\rightarrow h_4$  and  $\rightarrow h_6$  are the only left on the right side. We can finally fill them:

```
\begin{array}{l} t_3 \coloneqq t_2 \rhd \mathsf{map} \; \mathsf{d} \mapsto \\ \mathsf{d} \; \rhd \mathsf{case}_{1\nu} \, {}^s[\mathsf{d}_4, \mathsf{d}_6] \; \mapsto \\ \mathsf{d}_4 \, \triangleleft \; \mathsf{Inl} \, \triangleleft \, () \; ; \mathsf{d}_6 \, \blacktriangleleft \; \mathsf{Inr} \, \triangleleft \, () \end{array}
```

 $t_3$  reduces to  $\{\$   $\{\$   $((Inl(), Inr()), (Inl(), Inr()))_{\land}()\}$  which is now a complete structure. There is no destination remaining on the right-hand side.

We also see that structure can in fact be built in several stages with ease, with other operations taking place in-between.

# 3 LIMITIONS OF THE PREVIOUS APPROACH

Everything described above is in fact already possible in destination-passing style for Haskell as presented in [1]. However, there is one fundamental limitation in [1]: the inability to store destinations in destination-based data structures.

Indeed, that first approach of destination-passing style for Haskell can only be used to build non-linear data structures. More precisely, the FillLeaf operator ( $\triangleleft$ ) can only take arguments with multiplicity  $\omega$ . This is in fact a much stronger restriction than necessary; the core idea is *just* to prevent any destination (which are always linear resources) to appear somewhere in the right-hand side of FillLeaf.

- 3.1 Why stored destinations are problematic
- 3.2 Breadth-first tree traversal
- 3.3 Storing linear data in destination-based data structures
- 3.4 Need for scope control
- 4 UPDATED BREADTH-FIRST TREE TRAVERSAL

# 5 LANGUAGE SYNTAX

# 5.1 Introducing the ampar

Minamide's work[3] is the earliest record we could find of a functional calculus integrating the idea of incomplete data structures (structures with holes) that exist as first class values and can be interacted with by the user.

In that paper, a structure with a hole is named *hole abstraction*. In the body of a hole abstraction, the bound *hole variable* should be used linearly (exactly once), and must only be used as a parameter of a data constructor. In other terms, the bound *hole variable* cannot be pattern-matched on or used as a parameter of a function call. A hole abstraction is thus a weak form of linear lambda abstraction, which just moves a piece of data into a bigger data structure.

In fact, the type of hole abstraction  $(T_1, T_2)$ hfun in Minamine's work shares a lot of similarity with the separating implication or *magic wand*  $T_1 * T_2$  from separation logic: given a piece of memory matching description  $T_1$ , we obtain a (complete) piece of memory matching description  $T_2$ .

Transforming the hole abstraction from its original implication form to a *par* form let us consider the type  $\lfloor T_1 \rfloor$  of *sink* or *destination* of  $T_1$  as a first class component of our calculus. We also get to see the hole abstraction aka memory par as a pair-like structure, where the two sides might be coupled together in a way that prevent using both of them simultaneously.

From memory  $par \widehat{\mathscr{Y}}$  to  $ampar \ltimes$ . In CLL, the cut rule states that given  $T_1 \mathscr{Y} T_2$ , we can free up  $T_1$  by providing an eliminator of  $T_2$ , or free up  $T_2$  by providing an eliminator of  $T_1$ . The eliminator of  $T_2$  can be  $T^{\perp}$ , or  $T^{\perp^{-1}} = T'$  if T is already of the form  $T'^{\perp}$ . In a classical setting, thanks to the involutive nature of negation  $\bullet^{\perp}$ , the two potential forms of the eliminator of T are equal.

In destination calculus though, we don't have an involutive memory negation  $\lfloor \cdot \rfloor$ . If we are provided with a destination of destination  $\rightarrow h': \lfloor \lfloor T \rfloor \rfloor$ , we know that some structure is expecting to store a destination of type  $\lfloor T \rfloor$ . If ever that structure is consumed, then the destination stored inside will have to be filled with a value (remember we are in a linear calculus). So if we allocate a new memory slot of type h:T and its linked destination  $\rightarrow h: \lfloor T \rfloor$ , and write  $\rightarrow h$  to the memory slot pointed to by  $\rightarrow h'$ , then we can get back a value of type T at h if ever the structure pointed to by  $\rightarrow h'$  is consumed. Thus, a destination of destination is only equivalent to the promise of an eventual value, not an immediate usable one.

However, we can recover a memory abstraction that is usable in practice if we know the nature of an memory par side:

 if the memory par side is a value made only of inert elements and destinations (negative polarity), then we can pattern-match/map on it, but we cannot store it away to free up the other side;

- if the memory par side is a value made only of inert elements and holes (positive polarity), then we can store it away in a bigger struct and free up the associated destinations (this is not an issue as the bigger struct will be locked by an memory par too), but we cannot pattern-match/map on it as it (may) contains holes;
- if one memory par side is only made of inert elements, we can in fact convert the memory par to a pair, as the memory par doesn't have any form of interaction between its sides.

It is important to note that the type of an memory par side is not really enough to determine the nature of the side, as a hole of type T and and inert value of type T are indistinguishable at the type level.

So we introduced a more restricted form of memory par, named *ampar* ( $\ltimes$ ), for *asymmetrical memory par*, in which:

- the left side is made of inert elements (normal values or destinations from previous scopes) and/or holes if and only if those holes are compensated by destinations on the right side;
- the right side is made of inert elements and/or destinations.

As the right side cannot contain any holes, it is always safe to pattern-match or map on it. Because the left side cannot contain destinations from the current scope, it is always safe to store it away in a bigger struct and release the right side.

Finally, it is enough to check for the absence of destinations in the right side (which we can do easily just by looking at its type) to convert an *ampar* to a pair, as any remaining hole on the left side would be compensated by a destination on the right side.

Destinations from previous scopes are inert. In destination calculus, scopes are delimited by the map operation over ampars. Anytime a map happens, we enter a new scope, and any preexisting destination or variable see its age increased by one ( $\uparrow$ ). As soon as a destination or variable is no longer of age 0 ( $\nu$ ), it cannot be used actively but only passively (e.g. it cannot be applied if it is a function, or used to store a value if it is a destination, but it can be stored away in a dest, or pattern-matched on).

This is a core feature of the language that ensures part of its safety.

# 5.2 Names and variables

The destination calculus uses two classes of names: regular (meta) variable names x, y, and hole names, h,  $h_1$ ,  $h_2$  which represents the identifier or address of a memory cell that hasn't been written to vet.

```
var, x, y, d, un, ex, st Variable names

hvar, h ::= Hole (or destination) name, represented by a natural number

\begin{vmatrix} h+h' & M \\ h[H\pm h'] & M & Shift by h' if h \in H \\ max(H) & M & Maximum of a set of hole names
```

Hole names are represented by natural numbers under the hood, so they can act both as relative offsets or absolute positions in memory. Typically, when a structure is effectively allocated, its hole names are shifted by the maximum hole name encountered so far in the program; this corresponds to finding the next unused memory cell in which to write new data.

We sometimes need to keep track of hole names bound by a particular runtime value or evaluation context, hence we also define sets of hole names  $H, H_1, H_2 \dots$ 

```
hvars, H ::= Set of hole names
```

Shifting all hole names in a set by a given offset h' is denoted H±h'. We also define a conditional shift operation [H±h'] which shifts each hole name appearing in the operand to the left of the brackets by h' if this hole name is also member of H. This conditional shift can be used on a single hole name, a value, or a typing context.

# 5.3 Term and value core syntax

 $^{\nu}\lambda_{\mathbf{X}_{\mathbf{m}}}\mapsto u$ 

Inl  $\nu$ 

Destination calculus is based on linear simply-typed  $\lambda$ -calculus, with built-in support for sums, pairs, and exponentials. The syntax of terms is quite unusual, as we need to introduce all the tooling required to manipulate destinations, which constitute the primitive way of building a data structures for the user.

In fact, the grammatical class of values v, presented as a subset of terms t, could almost be removed completely from the user syntax, and just used as a denotation for runtime data structures. We only need to keep the *ampar* value  $\{h\}\langle h_{\wedge} \rightarrow h\rangle$  as part of the user syntax as a way to spawn a fresh memory cell to be later filled using destination-filling primitives (see alloc in Section 5.4).

```
term, t, u
                                                                                                        Term
                              ν
                                                                                                            Value
                                                                                                            Variable
                              Χ
                              t \triangleright t'
                                                                                                            Application
                              t: u
                                                                                                            Pattern-match on unit
                              t \triangleright \mathsf{case}_{\mathsf{m}} \{ \mathsf{Inl} \, \mathsf{x}_1 \mapsto u_1, \, \mathsf{Inr} \, \mathsf{x}_2 \mapsto u_2 \}
                                                                                                            Pattern-match on sum
                              t \rhd \mathsf{case}_{\mathsf{m}} (\mathsf{x}_1, \mathsf{x}_2) \mapsto u
                                                                                                            Pattern-match on product
                              t \triangleright \mathsf{case}_{\mathsf{m}} \, \mathsf{E}_{\mathsf{n}} \, \mathsf{X} \mapsto u
                                                                                                            Pattern-match on exponential
                              t \triangleright \mathsf{map} \times \mapsto t'
                                                                                                            Map over the right side of ampar
                              to<sub>⋉</sub> u
                                                                                                            Wrap into a trivial ampar
                                                                                                            Convert ampar to a pair
                              from_{\kappa} t
                                                                                                            Fill destination with unit
                              t \triangleleft ()
                              t ⊲ Inl
                                                                                                            Fill destination with left variant
                              t ⊲ Inr
                                                                                                            Fill destination with right variant
                              t ⊲ E<sub>m</sub>
                                                                                                            Fill destination with exponential const
                                                                                                            Fill destination with product construct
                               t \triangleleft (,)
                                                                                                            Fill destination with function
                               t \triangleleft (\lambda \times_{m} \mapsto u)
                              t ⊲• t'
                                                                                                            Fill destination with root of other amp
                               t[\mathbf{x} \coloneqq v]
                                                                                                M
                                                                                                        Value
val, v
                      ::=
                                                                                                            Hole
                        1
                              \rightarrow h
                                                                                                            Destination
                                                                                                            Unit
```

Function with no free variable

Left variant for sum

```
| Inr \nu Right variant for sum

| E_m \nu Exponential

| (\nu_1, \nu_2) Product

| H(\nu_2, \nu_1) Ampar

| \nu[H\pm h'] M Shift hole names inside \nu by h' if they belong to H.
```

Pattern-matching on every type of structure (except unit) is parametrized by a mode m to which the scrutinee is consumed. The variables which bind the subcomponents of the scrutinee then inherit this mode. In particular, this choice crystalize the equivalence  $!_{\omega a}(T_1 \otimes T_2) \simeq (!_{\omega a}T_1) \otimes (!_{\omega a}T_2)$ , which is not part of intuitionistic linear logic, but valid in Linear Haskell[2].

map is the main primitive to operate on an ampar, which represents an incomplete data structure whose building is in progress. map binds the right-hand side of the ampar — the one containing destinations of that ampar — to a variable, allowing those destinations to be operated on by destination-filling primitives. The left-hand side of the ampar is inaccessible as it is being mutated behind the scenes by the destination-filling primitives.

 $to_{\bowtie}$  embeds an already completed structure in an *ampar* whose left side is the structure, and right side is unit. We have an operator FillComp ( $\triangleleft$ •) allowing to compose two *ampars* by writing the root of the second one to a destination of the first one, so by throwing  $to_{\bowtie}$  to the mix, we can compose an *ampar* with a normal (completed) structure (see the sugar operator FillLeaf ( $\triangleleft$ ) in Section 5.4).

from  $_{\mathbb{K}}$  is used to convert an *ampar* to a pair, when the right side of the *ampar* is an exponential of the form  $_{\mathbb{K}}$   $_{\mathbb{K}}$ . Indeed, when the right side has such form, it cannot contains destinations (as destinations always have a finite age), thus it cannot contain holes in its left side either (as holes on the left side are always compensated 1:1 by a destination on the right side). As a result, it is valid to convert an *ampar* to a pair in these circumstances. from  $_{\mathbb{K}}$  is in particular used to extract a structure from its *ampar* building shell when it is complete (see the sugar operator from  $_{\mathbb{K}}$  in Section 5.4).

The remaining term operators  $\triangleleft()$ ,  $\triangleleft$ Inl,  $\triangleleft$ Inr,  $\triangleleft \in_{\mathbb{m}}$ ,  $\triangleleft()$ ,  $\triangleleft(\lambda \times_{\mathbb{m}} \mapsto u)$  are all destination-filling primitives. They write a layer of value/constructor to the hole pointed by the destination operand, and return the potential new destinations that are created in the process (or unit if there is none).

# 5.4 Syntactic sugar for constructors and commonly used operations

As we said in section 5.3, the grammatical class of values is mostly used for runtime only; in particular, data constructors can only take other values as arguments, not terms. Thus we introduce syntactic for data constructors taking arbitrary terms as parameters (as we often find in functional programming languages) using destination-filling primitives.

 $from_{\ltimes'}$  is a simpler variant of  $from_{\ltimes}$  that allows to extract the right side of an ampar when the left side has been fully consumed. We implement it in terms of  $from_{\ltimes}$  to keep the core calculus tidier (and limit the number of typing rules, evaluation contexts, etc), but it can be implemented much more efficiently in a real-world implementation.

```
 \begin{array}{lll} & \mbox{$^s$E}_{m} & t & \mbox{$M$} & \mbox{Allocate exponential} \\ & \mbox{$^s$($t_1$, $t_2$)} & \mbox{$M$} & \mbox{Allocate product} \end{array}
```

```
alloc
                                                                                                                                    t 4 t'
                                                                                                                                                                  t \triangleleft \bullet (\mathsf{to}_{\mathsf{K}} t')
                           \{1\}\langle 1 \land \rightarrow 1 \rangle
                                                                                                                                   {}^{s}\lambda \times_{m} \mapsto u \triangleq from'_{k}
from'_{\kappa} t \triangleq
                           (from_{\mathbb{K}} (t \rhd map un \mapsto un ; E_{1\infty} ())) \rhd case_{1\nu}
                                 (st, ex) \mapsto ex \triangleright case_{1\nu}
                                                                                                                                                                         alloc \triangleright map d →
                                      E_{1\infty} un \mapsto un; st
                                                                                                                                                                              d \triangleleft (\lambda x_m \mapsto u)
^{s}Inl t
                  \triangleq
                          from' (
                                                                                                                                    ^{s}Inr t
                                                                                                                                                                from' (
                                   alloc \triangleright map d →
                                                                                                                                                                         alloc \triangleright map d →
                                       d \triangleleft Inl \triangleleft t
                                                                                                                                                                              d \triangleleft Inr \triangleleft t
                          from'<sub>⋉</sub>(
                                                                                                                                                                 from'<sub>⋉</sub>(
                                                                                                                                    s(t_1, t_2)
^{s}E<sub>m</sub> t
                                   alloc \triangleright map d \mapsto
                                                                                                                                                                         alloc \triangleright map d \mapsto
                                       d \triangleleft E_m \triangleleft t
                                                                                                                                                                              (d \triangleleft (,)) \triangleright case_{1\nu}
                           )
                                                                                                                                                                                  (d_1, d_2) \mapsto d_1 \triangleleft t_1 ; d_2 \triangleleft t_2
```

Table 1. Desugaring of syntactic sugar forms for terms

# 6 TYPE SYSTEM

# 6.1 Syntax for types, modes, and typing contexts

```
type, T, U
                   ::=
                                              Type
                        1
                                                 Unit
                        \mathsf{T}_1 \oplus \mathsf{T}_2
                                                 Sum
                    T_1 \otimes T_2
                                                 Product
                                                 Exponential
                       !<sub>m</sub>T
                    \mathsf{U} \ltimes \mathsf{T}
                                                 Ampar
                        T_m \rightarrow U
                                                 Function
                         |_{m}T|
                                                 Destination
mode, m, n
                                              Mode (Semiring)
                   ::=
                                                 Pair of a multiplicity and age
                         pa
                         .
                                                 Error case (incompatible types, multiplicities, or ages)
mul, p
                   ::=
                                              Multiplicity (Semiring, first component of modality)
                                                 Linear use
                         1
                                                 Non-linear use
                         ω
                                              Age (Semiring, second component of modality)
age, a
                                                 Born now
                                                 One scope older
                         \infty
                                                 Infinitely old / static
ctx, \Gamma, \Delta, \Theta
                                              Typing context
                                                 Variable typing binding
                         x :_m T
                         h:_nT
                                                 Hole typing binding
                                                 Destination typing binding
                    \longrightarrow h:_{m}[_{n}T]
                        \mathbf{m} \cdot \Gamma
                                                 Multiply the leftmost mode of each binding by m
                                        Μ
                                                 \Gamma_1 + \Gamma_2
                                        Μ
                        \Gamma_1, \Gamma_2
                                        Μ
                                                 Disjoint sum
                         \rightarrow-1\Gamma
                                                 Transforms dest bindings into a hole bindings
                                        Μ
                         \rightarrow \Gamma
                                                 Transforms hole bindings into dest bindings
                                        Μ
                                                 Shift hole/dest names by h' if they belong to H
                         Γ[H<sub>±</sub>h′]
                                        Μ
```

# 6.2 Typing of terms and values

 $\Gamma \Vdash \nu : \mathsf{T}$ 

(Typing judgment for values)

 $\begin{array}{c} \text{Ty-val-Ampar} \\ \text{LinOnly } \Delta_3 \\ \text{FinAgeOnly } \Delta_3 \\ \text{Ty-val-Exp} \\ \Gamma \Vdash \nu' : \mathsf{T} \\ \hline n \cdot \Gamma \Vdash \mathsf{E_n} \ \nu' : !_n \mathsf{T} \end{array}$ 

 $\Theta \, \vdash \, t : \mathsf{T}$ 

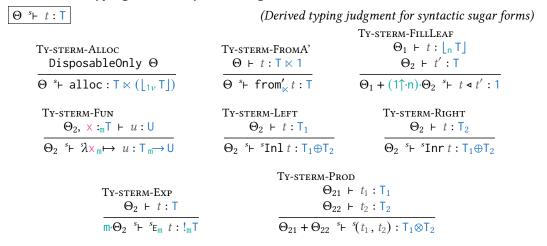
(Typing judgment for terms)

Ty-TERM-PATS

 $\begin{array}{c} \Theta_1 \vdash t : \mathsf{T}_1 \oplus \mathsf{T}_2 \\ \Theta_1 \vdash t : \mathsf{1} & \Theta_2 \vdash u : \mathsf{U} \\ \hline \Theta_1 \vdash \theta_2 \vdash t : \mathsf{u} : \mathsf{U} \\ \end{array} \qquad \begin{array}{c} \Theta_1 \vdash t : \mathsf{T}_1 \oplus \mathsf{T}_2 \\ \Theta_2, \ \mathsf{x}_1 :_{\mathsf{m}} \mathsf{T}_1 \vdash u_1 : \mathsf{U} \\ \Theta_2, \ \mathsf{x}_2 :_{\mathsf{m}} \mathsf{T}_2 \vdash u_2 : \mathsf{U} \\ \hline \mathsf{m} \cdot \Theta_1 + \Theta_2 \vdash t \vartriangleright \mathsf{case}_{\mathsf{m}} \left\{ \mathsf{Inl} \ \mathsf{x}_1 \mapsto u_1, \ \mathsf{Inr} \ \mathsf{x}_2 \mapsto u_2 \right\} : \mathsf{U} \end{array}$ 

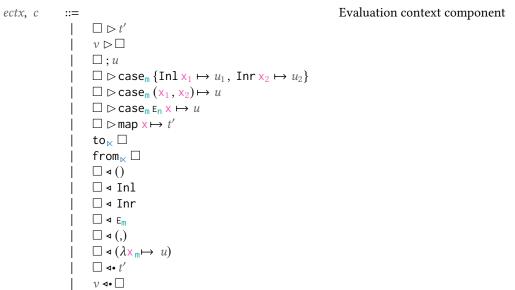
 $\begin{array}{lll} \text{Ty-term-Map} & & & & & & \\ \Theta_1 \vdash t : \mathsf{U} \ltimes \mathsf{T} & & & & & \\ 1 \uparrow \cdot \Theta_2, \; \times :_{1\nu} \mathsf{T} \vdash t' : \mathsf{T}' & & & \Theta \vdash u : \mathsf{U} & & \Theta \vdash t : \mathsf{U} \ltimes (!_{1\infty} \mathsf{T}) \\ \hline \Theta_1 + \Theta_2 \vdash t \rhd \mathsf{map} \; \times \mapsto t' : \mathsf{U} \ltimes \mathsf{T}' & & \Theta \vdash \mathsf{to}_{\aleph} \; u : \mathsf{U} \ltimes \mathsf{1} & & \Theta \vdash \mathsf{from}_{\aleph} \; t : \mathsf{U} \otimes (!_{1\infty} \mathsf{T}) \\ \end{array}$ 

# 6.3 Derived typing rules for syntactic sugar forms



# 7 EVALUATION CONTEXTS AND SEMANTICS

# 7.1 Evaluation contexts forms



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$$cctxs, C$$
 ::= Evaluation context stack |  $C \circ c$  |  $C[h:=_H v]$  |  $C$ 

$$\begin{array}{c} \text{Ty-ectxs-Fille-Foc} \\ \Delta + C : \lfloor_{\mathbb{m} \cdot \mathsf{n}} \mathsf{T} \rfloor \rightarrowtail \mathsf{U}_0 \\ \hline \Delta + C \circ (\square \triangleleft \mathsf{E}_{\mathsf{m}}) : \lfloor_{\mathsf{n}} !_{\mathsf{m}} \mathsf{T} \rfloor \rightarrowtail \mathsf{U}_0 \\ \hline \Delta_1 + C \circ (\square \triangleleft \mathsf{E}_{\mathsf{m}}) : \lfloor_{\mathsf{n}} !_{\mathsf{m}} \mathsf{T} \rfloor \rightarrowtail \mathsf{U}_0 \\ \hline \Delta_2, \ \mathbf{x} :_{\mathsf{m}} \mathsf{T} \vdash u : \mathsf{U} \\ \hline \Delta_1 + C \circ (\square \triangleleft (\lambda \mathsf{x}_{\mathsf{m}} \mapsto u)) : \lfloor_{\mathsf{n}} \mathsf{T}_{\mathsf{m}} \mapsto \mathsf{U} \rfloor \rightarrowtail \mathsf{U}_0 \\ \hline \Delta_1 + C \circ (\square \triangleleft (\lambda \mathsf{x}_{\mathsf{m}} \mapsto u)) : \lfloor_{\mathsf{n}} \mathsf{T}_{\mathsf{m}} \mapsto \mathsf{U} \rfloor \rightarrowtail \mathsf{U}_0 \\ \hline \Delta_1 + C \circ (\square \triangleleft (\lambda \mathsf{x}_{\mathsf{m}} \mapsto u)) : \lfloor_{\mathsf{n}} \mathsf{T}_{\mathsf{m}} \mapsto \mathsf{U} \rfloor \rightarrowtail \mathsf{U}_0 \\ \hline \Delta_1 + C \circ (\square \triangleleft (\lambda \mathsf{x}_{\mathsf{m}} \mapsto u)) : \lfloor_{\mathsf{n}} \mathsf{T}_{\mathsf{m}} \mapsto \mathsf{U} \rfloor \rightarrowtail \mathsf{U}_0 \\ \hline \Delta_1 + C \circ (\square \triangleleft (\lambda \mathsf{x}_{\mathsf{m}} \mapsto u)) : \lfloor_{\mathsf{n}} \mathsf{T}_{\mathsf{m}} \mapsto \mathsf{U} \rfloor \mapsto \mathsf{U}_0 \\ \hline \Delta_1 + C \circ (\square \triangleleft (\lambda \mathsf{x}_{\mathsf{m}} \mapsto u)) : \mathsf{U} \bowtie \mathsf{T}_{\mathsf{m}} \mapsto \mathsf{U}_0 \\ \hline \Delta_1 + C \circ (\square \triangleleft (\lambda \mathsf{x}_{\mathsf{m}} \mapsto u)) : \mathsf{U} \bowtie \mathsf{T}_{\mathsf{m}} \mapsto \mathsf{U}_0 \\ \hline \Delta_1 + C \circ (\square \triangleleft (\lambda \mathsf{x}_{\mathsf{m}} \mapsto u)) : \mathsf{U} \bowtie \mathsf{T}_{\mathsf{m}} \mapsto \mathsf{U}_0 \\ \hline \Delta_1 + C \circ (\square \triangleleft (\lambda \mathsf{x}_{\mathsf{m}} \mapsto u)) : \mathsf{U} \bowtie \mathsf{T}_{\mathsf{m}} \mapsto \mathsf{U}_0 \\ \hline \Delta_1 + C \circ (\square \triangleleft (\lambda \mathsf{x}_{\mathsf{m}} \mapsto u)) : \mathsf{U} \bowtie \mathsf{T}_{\mathsf{m}} \mapsto \mathsf{U}_0 \\ \hline \Delta_1 + C \circ (\square \triangleleft (\lambda \mathsf{x}_{\mathsf{m}} \mapsto u)) : \mathsf{U} \bowtie \mathsf{T}_{\mathsf{m}} \mapsto \mathsf{U}_0 \\ \hline \Delta_1 + C \circ (\square \triangleleft (\lambda \mathsf{x}_{\mathsf{m}} \mapsto u)) : \mathsf{U} \bowtie \mathsf{T}_{\mathsf{m}} \mapsto \mathsf{U}_0 \\ \hline \Delta_1 + C \circ (\square \triangleleft (\lambda \mathsf{x}_{\mathsf{m}} \mapsto u)) : \mathsf{U} \bowtie \mathsf{T}_{\mathsf{m}} \mapsto \mathsf{U}_0 \\ \hline \Delta_1 + C \circ (\square \triangleleft (\lambda \mathsf{x}_{\mathsf{m}} \mapsto u)) : \mathsf{U} \bowtie \mathsf{T}_{\mathsf{m}} \mapsto \mathsf{U}_0 \\ \hline \Delta_1 + C \circ (\square \triangleleft (\lambda \mathsf{x}_{\mathsf{m}} \mapsto u)) : \mathsf{U} \bowtie \mathsf{T}_{\mathsf{m}} \mapsto \mathsf{U}_0 \\ \hline \Delta_1 + C \circ (\square \triangleleft (\lambda \mathsf{x}_{\mathsf{m}} \mapsto u)) : \mathsf{U} \bowtie \mathsf{T}_{\mathsf{m}} \mapsto \mathsf{U}_0 \\ \hline \Delta_1 + C \circ (\square \triangleleft (\lambda \mathsf{x}_{\mathsf{m}} \mapsto u) : \mathsf{U} \bowtie \mathsf{T}_{\mathsf{m}} \mapsto \mathsf{U}_0 \\ \hline \Delta_1 + C \circ (\square \triangleleft (\lambda \mathsf{x}_{\mathsf{m}} \mapsto u) : \mathsf{U} \bowtie \mathsf{T}_{\mathsf{m}} \mapsto \mathsf{U}_0 \\ \hline \Delta_1 + C \circ (\square \triangleleft (\lambda \mathsf{x}_{\mathsf{m}} \mapsto u) : \mathsf{U} \bowtie \mathsf{T}_{\mathsf{m}} \mapsto \mathsf{U}_0 \\ \hline \Delta_1 + C \circ (\square \triangleleft (\lambda \mathsf{x}_{\mathsf{m}} \mapsto u) : \mathsf{U} \bowtie \mathsf{T}_{\mathsf{m}} \mapsto \mathsf{U}_0 \\ \hline \Delta_1 + C \circ (\square \triangleleft (\lambda \mathsf{x}_{\mathsf{m}} \mapsto u) : \mathsf{U} \bowtie \mathsf{T}_{\mathsf{m}} \mapsto \mathsf{U}_0 \\ \hline \Delta_1 + C \circ (\square \triangleleft (\lambda \mathsf{x}_{\mathsf{m}} \mapsto u) : \mathsf{U} \bowtie \mathsf{U}_0 \\ \hline \Delta_1 + C \circ (\square \triangleleft (\lambda \mathsf{x}_{\mathsf{m}} \mapsto u) : \mathsf{U} \bowtie \mathsf{U}_0 \\ \hline \Delta_1 + C \circ (\square \triangleleft (\lambda \mathsf{x}_{\mathsf{m}} \mapsto u) : \mathsf{U}_0 \mapsto \mathsf{U}_0 \\ \hline \Delta_1 + C \circ (\square \triangleleft (\lambda \mathsf{x}_{\mathsf{m}} \mapsto u) : \mathsf{U}_0 \mapsto \mathsf{U}_0 \\ \hline \Delta_1 + C \circ (\square \square (\lambda \mathsf{x}_{\mathsf{m}} \mapsto u) : \mathsf{U}_0 \mapsto \mathsf{U}_0$$

 $\begin{array}{c} \text{Ty-ectxs-OpenAmpar-Foc} \\ & \textit{hvars}(\textit{C}) \;\; \# \;\; \textit{hvars}(\rightarrow^{-1}\Delta_3) \\ & \text{LinOnly} \;\; \Delta_3 \\ & \text{FinAgeOnly} \;\; \Delta_3 \\ & \Delta_1, \;\; \Delta_2 \;\; \dashv \; \textit{C} : \; (\textbf{U} \ltimes \textbf{T}') \rightarrowtail \textbf{U}_0 \\ & \Delta_2, \;\; \rightarrow^{-1}\Delta_3 \;\; \Vdash \;\; \textit{v}_2 : \textbf{U} \\ \hline \\ \hline \textbf{1} \uparrow \cdot \Delta_1, \;\; \Delta_3 \;\; \dashv \; \textit{C} \circ \left( \stackrel{\text{op}}{\textit{hvars}(\rightarrow^{-1}\Delta_3)} \langle \textit{v}_2 \;_{\land} \Box \rangle \right) : \textbf{T}' \rightarrowtail \textbf{U}_0 \\ & \text{hvars}(\rightarrow^{-1}\Delta_3) \langle \textit{v}_2 \;_{\land} \Box \rangle \right) : \textbf{T}' \rightarrowtail \textbf{U}_0 \\ \end{array}$ 

⊢ C[t]: T

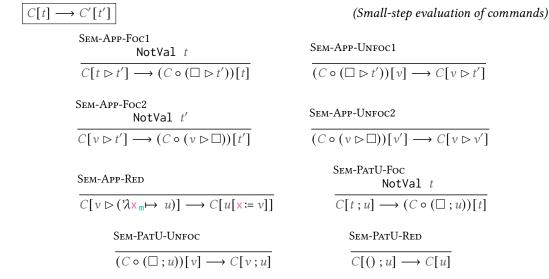
(Typing judgment for commands)

TY-CMD
$$\Delta + C : T \rightarrow U_0$$

$$\Delta \vdash t : T$$

$$\vdash C[t] : U_0$$

# 7.3 Small-step semantics



SEM-PATS-Foc

NotVal t

 $\overline{C[t\rhd \mathsf{case}_{\mathtt{m}}\left\{\mathsf{Inl}\,\mathsf{x}_1\mapsto u_1\,,\,\,\mathsf{Inr}\,\mathsf{x}_2\mapsto u_2\right\}]}\longrightarrow (C\circ (\Box\rhd \mathsf{case}_{\mathtt{m}}\left\{\mathsf{Inl}\,\mathsf{x}_1\mapsto u_1\,,\,\,\mathsf{Inr}\,\mathsf{x}_2\mapsto u_2\right\}))[t]$ 

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#### SEM-PATS-UNFOC

$$\begin{array}{c} \operatorname{SEM-TOA-UNFOC} \\ \hline (C \circ (\operatorname{to}_{\mathbb{K}} \square))[v_2] \longrightarrow C[\operatorname{to}_{\mathbb{K}} v_2] \\ \hline \\ C[\operatorname{from}_{\mathbb{K}} v_2] \longrightarrow C[\operatorname{fi}_{\mathbb{V}} v_2] \\ \hline \\ C[\operatorname{from}_{\mathbb{K}} v_2] \longrightarrow C[\operatorname{fi}_{\mathbb{V}} v_2] \\ \hline \\ C[\operatorname{from}_{\mathbb{K}} v_2] \longrightarrow C[\operatorname{fi}_{\mathbb{V}} v_2] \\ \hline \\ C[\operatorname{from}_{\mathbb{K}} v_2] \longrightarrow C[\operatorname{from}_{\mathbb{K}} v_$$

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# 8 PROOF OF TYPE SAFETY USING COQ PROOF ASSISTANT

- Not particularly elegant. Max number of goals observed 232 (solved by a single call to the congruence tactic). When you have a computer, brute force is a viable strategy. (in particular, no semiring formalisation, it was quicker to do directly)
- Rules generated by ott, same as in the article (up to some notational difference). Contexts are not generated purely by syntax, and are interpreted in a semantic domain (finite functions).
- Reasoning on closed terms avoids almost all complications on binder manipulation. Makes proofs tractable.
- Finite functions: making a custom library was less headache than using existing libraries (including MMap). Existing libraries don't provide some of the tools that we needed, but the most important factor ended up being the need for a modicum of dependency between key and value. There wasn't really that out there. Backed by actual functions for simplicity; cost: equality is complicated.
- Most of the proofs done by author with very little prior experience to Coq.
- Did proofs in Coq because context manipulations are tricky.
- Context sum made total by adding an extra invalid *mode* (rather than an extra context). It seems to be much simpler this way.
- It might be a good idea to provide statistics on the number of lemmas and size of Coq codebase.
- (possibly) renaming as permutation, inspired by nominal sets, make more lemmas don't require a condition (but some lemmas that wouldn't in a straight renaming do in exchange).
- (possibly) methodology: assume a lot of lemmas, prove main theorem, prove assumptions, some wrong, fix. A number of wrong lemma initially assumed, but replacing them by correct variant was always easy to fix in proofs.
- Axioms that we use and why (in particular setoid equality not very natural with ott-generated typing rules).
- Talk about the use and benefits of Copilot.

# 9 IMPLEMENTATION OF DESTINATION CALCULUS USING IN-PLACE MEMORY MUTATIONS

What needs to be changed (e.g. linear alloc)

- 10 RELATED WORK
- 11 CONCLUSION AND FUTURE WORK

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