

YWEAG

Bayesian data analysis with TensorFlow Probability

www.tweag.io

Your hosts

Simeon will give the presentation



- background in computational biology
- Data Scientist at Tweag since 2019

Dorran will happily answer questions



- previous positions in geophysics
- Data Scientist at Tweag since 2019

Tweag I/O

TODO

Tweag I/O is a software innovation lab and consultancy based in Paris with employees all around the world.

We specialize in

- software engineering, with a focus on functional programming
- DevOps, with a focus on reproducible software systems and builds
- data science

What you're in for

This tutorial consists of alternating blocks of

- theory / example slides
- practical examples on either external websites or Google Colab notebooks.
 Links posted in Zoom chat

Requirements:

- a Google account (for the practical exercises)
- elementary knowledge in probability theory and statistics

Reminder: Probabilities

Probability distributions can be...

discrete: Bernoulli(k; b) =
$$b^k(1-b)^{1-k}$$

continuous:
$$\mathcal{N}(\mathbf{x};\mu,\sigma) = \frac{1}{\sqrt{2\pi\sigma^2}} \exp(-\frac{1}{2\sigma^2}(\mathbf{x}-\mu)^2)$$



Important concepts:

Conditional probability

p(A|B): probability that A is true, given B is true

Joint probability

p(A, B): probability that both A and B are true

Conditional joint probability

p(A, B|C): probability that both A and B are true, given C is true

Bayesian vs frequentist probabilities

Example: fair coin flip with (bias $b = \frac{1}{2}$)

Frequentist probability

Bayesian probability

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p("head" |b=\frac{1}{2}): measure of belief in the statement "flip results in head" given a fair coin
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Prior beliefs

Assume: unknown bias b

Prior probability

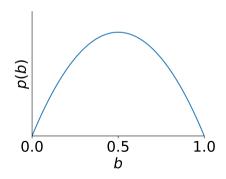
Encodes prior belief in b before flipping the coin

What is known about *b*?

- ▶ *b* is a probability: $0 \le b \le 1$
- most coins are fair
- ightarrow choose prior distribution defined between 0 and 1, with maximum at and symmetric around $b=\frac{1}{2}$

Example:

$$b \sim \text{Beta}(\alpha = 2, \beta = 2)$$

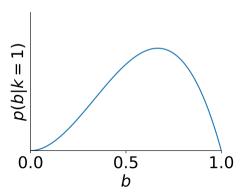


Posterior belief

Now: flip coin one time, result: head

Posterior belief

p(b|head): updated prior belief after obtaining new data



Update rule

Bayes' theorem

$$p(A|B) = \frac{p(B|A) \times p(A)}{p(B)}$$

(easily derived from rules for conditional probabilities)

In data analysis:

$$\underbrace{p(x|D,I)}_{\text{posterior}} = \underbrace{p(D|x,I)}_{\text{likelihood}} \times \underbrace{p(x|I)}_{\text{prior}} / \underbrace{p(D|I)}_{\text{evidence}}$$

x: model parameter (in our case: b)

D: data (in our case: k = 1)

I: prior information (often omitted to simplify notation)

Likelihood

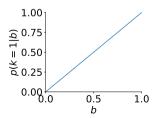
p(D|x): probability of the data given fixed model parameters \rightarrow models data-generating process

In our case:

$$p(k|b) = \text{Bernoulli}(k;b) \propto b^k (1-b)^{k-1}$$

with

$$k = \begin{cases} 0: & \text{tail} \\ 1: & \text{head} \end{cases}$$



Evidence

$$p(D) = \int dx \, p(D|x)p(x)$$
:
normalization constant (long story...)

In our case:

$$\begin{split} \rho(k=1) &= \int_0^1 \mathrm{d}b \; L(k=1|b) \rho(b) \\ &= \int_0^1 \mathrm{d}b \; \; \mathrm{Bernoulli}(k;b) \times \mathrm{Beta}(k;\alpha=2,\beta=2)|_{k=1} \\ &= \int_0^1 \mathrm{d}b \; \left. b^k (1-b)^{k-1} \frac{b(1-b)}{\frac{\Gamma(2)\Gamma(2)}{\Gamma(4)}} \right|_{k=1} \\ &\vdots \\ &= \frac{1}{2} \end{split}$$

Evidence

$$p(D) = \int dx \, p(D|x)p(x)$$
:
normalization constant (long story...)

In our case:

$$\begin{split} p(k=1) &= \int_0^1 \mathrm{d}b \ L(k=1|b) p(b) \\ &= \int_0^1 \mathrm{d}b \ \operatorname{Bernoulli}(k, \epsilon) \times \operatorname{Batc}(k; \alpha=2, \beta=2)|_{k=1} \\ &= \int_0^1 \mathrm{d}b \ b^k (1 + b) \left| \frac{b(1-b)}{\frac{\Gamma(2)\Gamma(2)}{\Gamma(4)}} \right|_{k=1} \\ &\vdots \\ &= \frac{1}{2} \end{split}$$

Update rule

In our coin flip example:

prior:
$$\begin{aligned} \textit{p}(\textit{b}) &= \mathsf{Beta}(\textit{b}; \alpha = 2, \beta = 2) \\ &\propto \textit{b}(1-\textit{b}) \end{aligned}$$

likelihood:
$$p(D|b) = Bernoulli(k = 1; b)$$

= b

posterior:
$$p(b|D) \propto p(D|b) \times p(b)/p(D)$$

= Beta $(b; \alpha = 3, \beta = 2)$
 $\propto b^2(1-b)$



no slides for interactive stuff –

Real-world Bayesian data analysis

In real problems: non-standard, difficult posterior distributions



Probabilistic programming libraries

Allow to

- programmatically define a statistical model
- sample from arbitrary posterior distributions
- run quality checks

Examples:

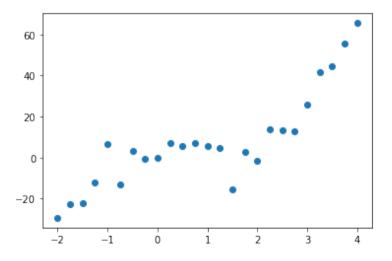
- ► PyMC3
- Stan
- ► TensorFlow Probability
- ▶ ..

Real-world Bayesian data analysis: recipe

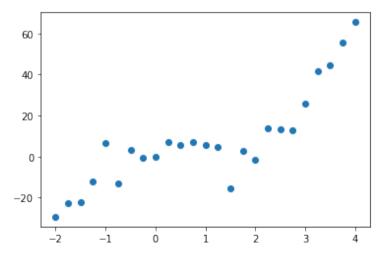
Steps to solve real-world problems:

- 0. Look at and think about data:
 - What kind of process generated data?
 - What do I want to learn: clusters? Approximating function? class labels?
- 1. formulate likelihood (statistical model for data-generating process)
- 2. formulate prior distributions for likelihood parameters
- 3. set up model in probabilistic programming library
- 4. sample from posterior distribution
- 5. perform quality checks

Step 0: formulating the problem and understanding the data

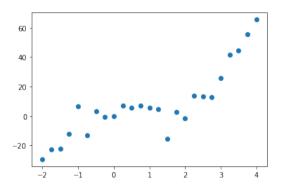


Step 0: formulating the problem and understanding the data



Let's do polynomial regression!

Step 1: formulating the likelihood



Often: measured data = idealized data + noise

idealized data:
$$\hat{f}(x) = \beta_0 + \beta_1 x + \beta_2 x^2 + \beta_3 x^3$$
 noise: normally distributed Likelihood parameters: $\vec{\beta}$, σ

Step 2: formulating prior distributions

Incorporate all available information

- previous experiments
- ballpark estimation from the data
- common sense

Noise σ :

- ▶ positive quantity $\rightarrow p(\sigma)$ with positive support
- from data: not too big

e.g.,
$$\sigma \sim \mathsf{Lognormal}(\mu = 2, \sigma = \frac{1}{2})$$

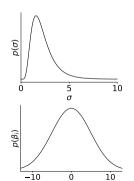
Coefficients β :

not too extreme values "_('')_/"

Something broad and "uninformative", e.g. $\mathcal{N}(0,5)$

Warning

Avoid introducing strong bias!



Step 3: code model in probabilistic programming library

- see interactive demo -

Step 4: sample with appropriate inference algorithm

Most popular and powerful class: Markov chain Monte Carlo (MCMC)

Continuous parameters:

Hamiltonian Monte Carlo (HMC) very efficient

Discrete parameters:

e.g., Metropolis-Hastings

Combination of both:

Gibbs sampling

Another popular option: variational inference (VI)

Approximation workhorse: Metropolis-Hastings

Markov chain

Random process with

$$p(x_{i+1}|x_i,x_{i-1},\ldots,x_1)=p(x_{i+1}|x_i)$$

ightarrow a Markov chain has no "memory"

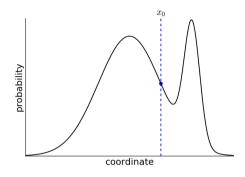
In some conditions: converges to a unique invariant distribution $\pi(x)$

Metropolis-Hastings algorithm

Construct Markov chain with invariant distribution $\pi(x) = p(x)$:

- 1. starting at state, x_i , propose a new state x_{i+1}^* from $q(x_{i+1}^*|x_i)$
- 2. calculate acceptance probability p_{acc}
- 3. draw $u \sim \mathcal{U}(0,1)$
- 4. if $u < p_{acc}$: $x_{i+1} = x_{i+1}^*$, else $x_{i+1} = x_i$

Initialize with any state x_0

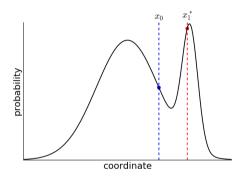


Sequence of states: (x_0)

Metropolis et al., J. Chem. Phys (1953); Hastings, Biometrika (1970)

Initial state: x_0

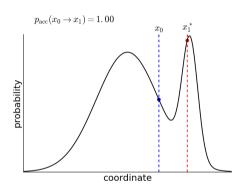
1. calculate a proposal state x_1^* by randomly perturbing x_0



Initial state: x₀

- 1. calculate a proposal state x_1^* by randomly perturbing x_0
- 2. calculate acceptance probability

$$p_{\mathsf{acc}} = \mathsf{min}\left(1, \frac{p(x_1^*)}{p(x_0)}\right)$$



Initial state: x_0

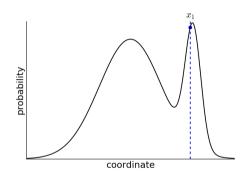
- 1. calculate a proposal state x_1^* by randomly perturbing x_0
- 2. calculate acceptance probability

$$p_{\mathsf{acc}} = \min\left(1, \frac{p(\mathbf{x}_1^*)}{p(\mathbf{x}_0)}\right)$$

3. with probability p_{acc} , accept proposal state x_1^* as the next state x_1 , else copy x_0

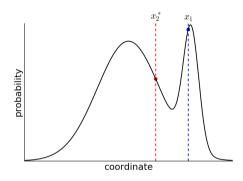
Sequence of states:

$$(x_0, x_1)$$



Current state: x₁

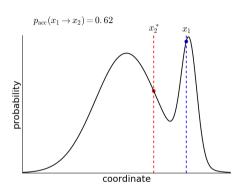
1. calculate a proposal state x_2^* by randomly perturbing x_1



Current state: x₁

- 1. calculate a proposal state x_2^* by randomly perturbing x_1
- 2. calculate acceptance probability

$$p_{\mathsf{acc}} = \min\left(1, \frac{p(x_2^*)}{p(x_1)}\right)$$



Current state: x₁

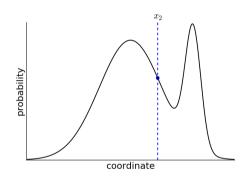
- 1. calculate a proposal state x_2^* by randomly perturbing x_1
- 2. calculate acceptance probability

$$p_{\mathsf{acc}} = \min\left(1, \frac{p(\mathbf{x}_2^*)}{p(\mathbf{x}_1)}\right)$$

3. with probability p_{acc} , accept proposal state x_2^* as the next state x_2 , else copy x_1

Sequence of states:

$$(x_0, x_1, x_2)$$



Current state: x₁

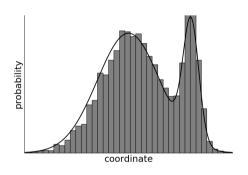
- 1. calculate a proposal state x_2^* by randomly perturbing x_1
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$$p_{\text{acc}} = \min\left(1, \frac{p(x_2^*)}{p(x_1)}\right)$$

3. with probability p_{acc} , accept proposal state x_2^* as the next state x_2 , else copy x_1

Sequence of states:

$$(\mathbf{x}_0, \mathbf{x}_1, \mathbf{x}_2, \dots, \mathbf{x}_n)$$



Step 5: quality checks

see interactive demo -