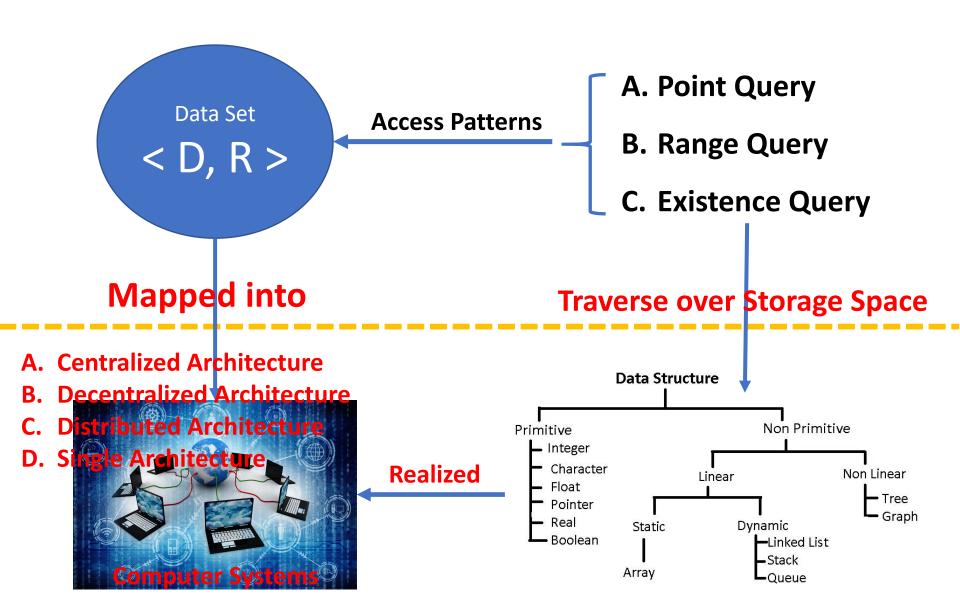
Zhihong Chong

https://cs.seu.edu.cn/chongzhihong

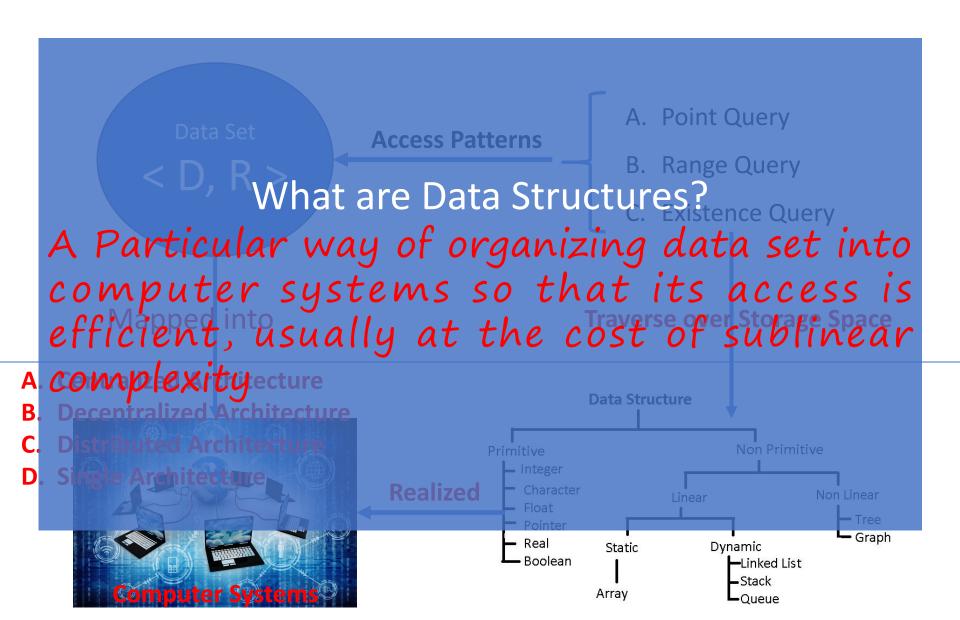
Outline

- Why Augmenting Data Structures
 - Access Pattern: Ranked Query
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- Applications and Problems

Framework of Data Structures



Framework of Data Structures



Retrieval for knowledge-intensive NLP tasks

Representative tasks: open-domain QA, fact checking, entity linking, ...

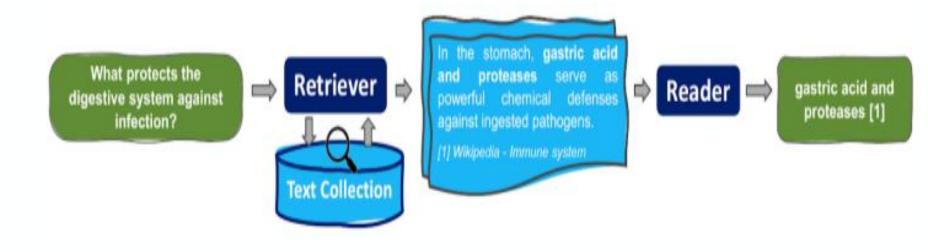
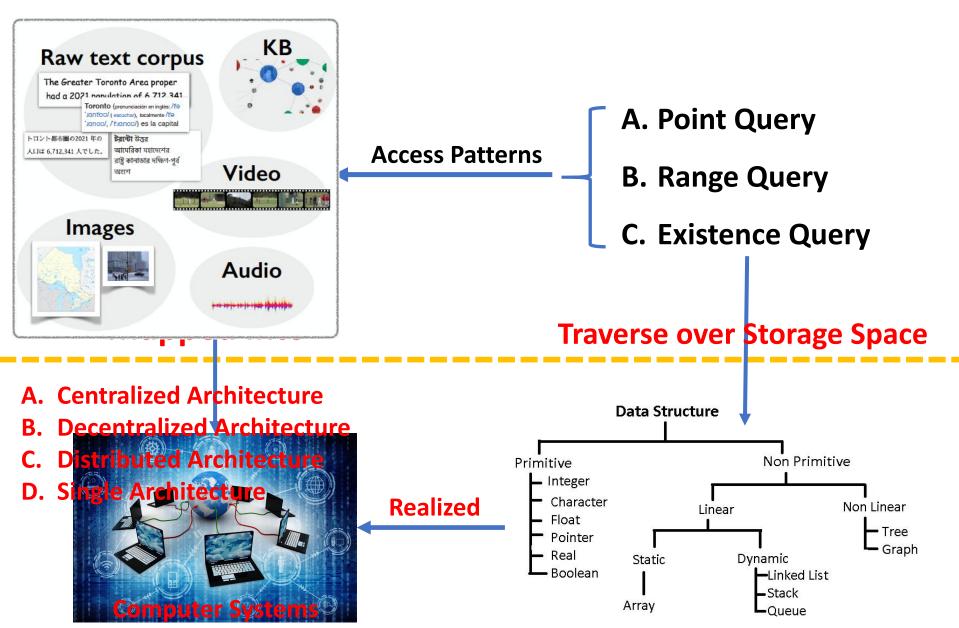


Image: http://ai.stanford.edu/blog/retrieval-based-NLP/

Drives a lot of research on better algorithms for dense retrieval, e.g., DPR (Karpukhin et al., 2020), ColBERT (Khattab and Zaharia, 2020), ANCE (Xiong et al., 2021), Contriever (Izacard et al., 2022), ...

Why retrieval \rightarrow LMs?

Framework of Data Structures



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Dynamic order statistics

OS-SELECT(i, S): returns the *i*th smallest element

in the dynamic set S.

OS-RANK(x, S): returns the rank of $x \in S$ in the

sorted order of S's elements.

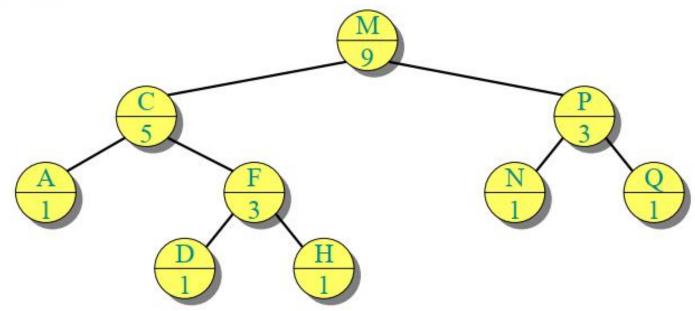
IDEA: Use a red-black tree for the set S, but keep subtree sizes in the nodes.

Notation for nodes:





Example of an OS-tree



size[x] = size[left[x]] + size[right[x]] + 1



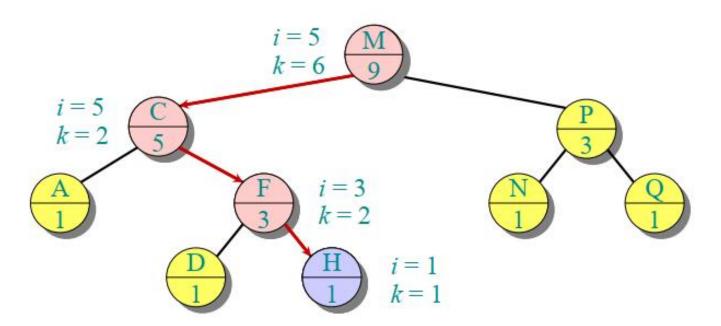
```
Implementation trick: Use a sentinel
(dummy record) for NIL such that size[NIL] = 0.
OS-SELECT(x, i) > ith smallest element in the
                    subtree rooted at x
  k \leftarrow size[left[x]] + 1 \triangleright k = rank(x)
  if i = k then return x
  if i < k
      then return OS-SELECT(left[x], i)
      else return OS-SELECT(right[x], i-k)
```

(OS-RANK is in the textbook.)



Example

OS-SELECT(root, 5)



Running time = $O(h) = O(\lg n)$ for red-black trees.



Data structure maintenance

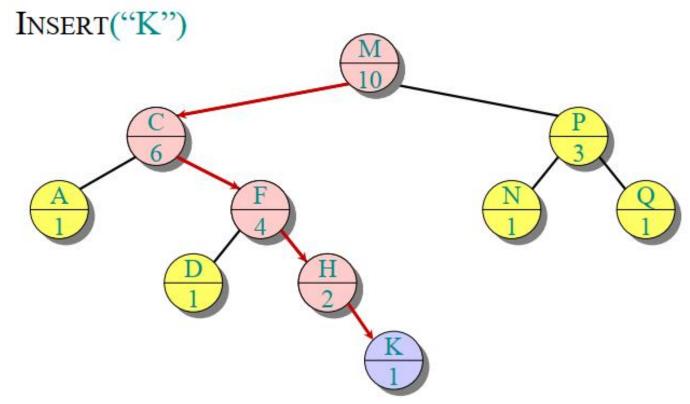
- Q. Why not keep the ranks themselves in the nodes instead of subtree sizes?
- A. They are hard to maintain when the red-black tree is modified.

Modifying operations: INSERT and DELETE.

Strategy: Update subtree sizes when inserting or deleting.



Example of insertion

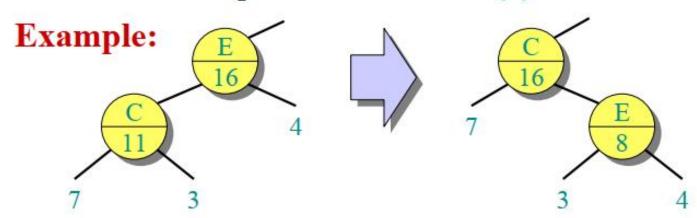




Handling rebalancing

Don't forget that RB-INSERT and RB-DELETE may also need to modify the red-black tree in order to maintain balance.

- *Recolorings*: no effect on subtree sizes.
- Rotations: fix up subtree sizes in O(1) time.



 \therefore RB-Insert and RB-Delete still run in $O(\lg n)$ time.



Data-structure augmentation

Methodology: (e.g., order-statistics trees)

- 1. Choose an underlying data structure (red-black trees).
- 2. Determine additional information to be stored in the data structure (*subtree sizes*).
- 3. Verify that this information can be maintained for modifying operations (*RB-INSERT*, *RB-DELETE don't forget rotations*).
- 4. Develop new dynamic-set operations that use the information (*OS-SELECT and OS-RANK*).

These steps are guidelines, not rigid rules.



Interval trees

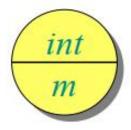
Goal: To maintain a dynamic set of intervals, such as time intervals.

Query: For a given query interval *i*, find an interval in the set that overlaps *i*.



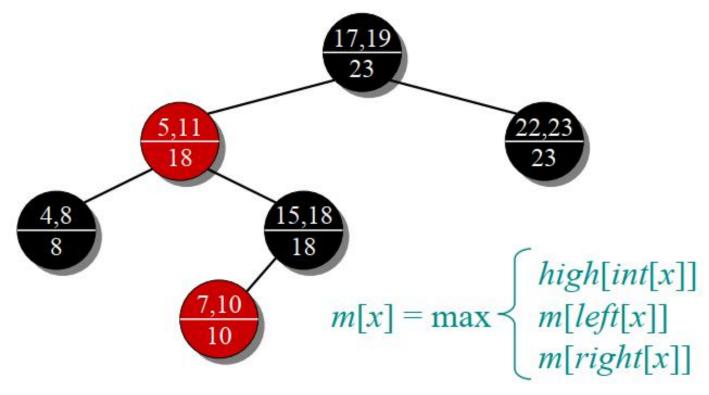
Following the methodology

- 1. Choose an underlying data structure.
 - Red-black tree keyed on low (left) endpoint.
- 2. Determine additional information to be stored in the data structure.
 - Store in each node x the largest value m[x] in the subtree rooted at x, as well as the interval int[x] corresponding to the key.





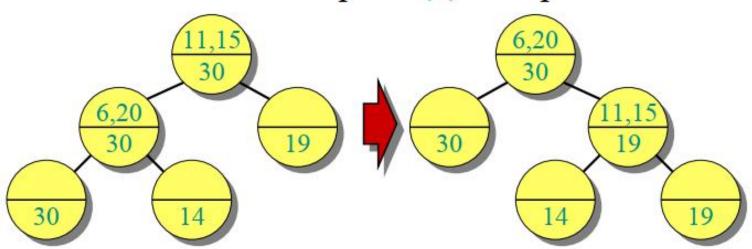
Example interval tree



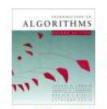


Modifying operations

- 3. Verify that this information can be maintained for modifying operations.
 - INSERT: Fix m's on the way down.
 - Rotations Fixup = O(1) time per rotation:



Total Insert time = $O(\lg n)$; Delete similar.



New operations

4. Develop new dynamic-set operations that use the information.

```
INTERVAL-SEARCH(i)

x \leftarrow root

while x \neq NIL and (low[i] > high[int[x]]

or low[int[x]] > high[i])

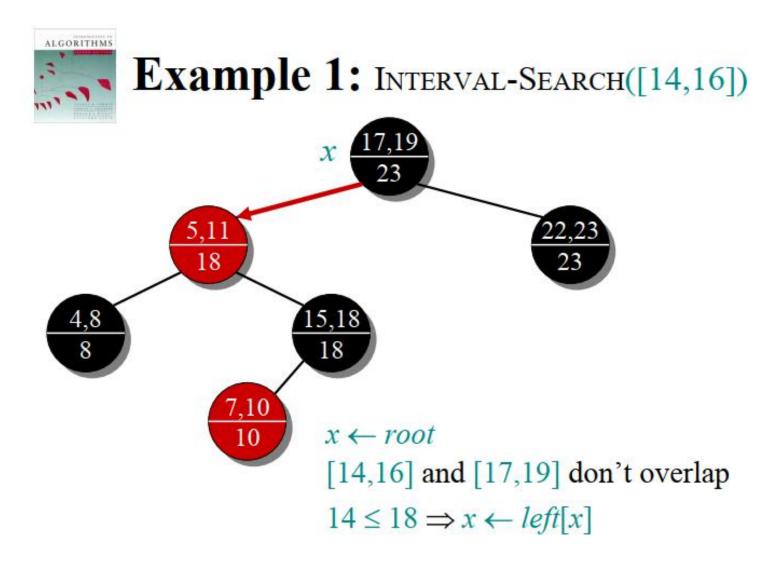
do \triangleright i and int[x] don't overlap

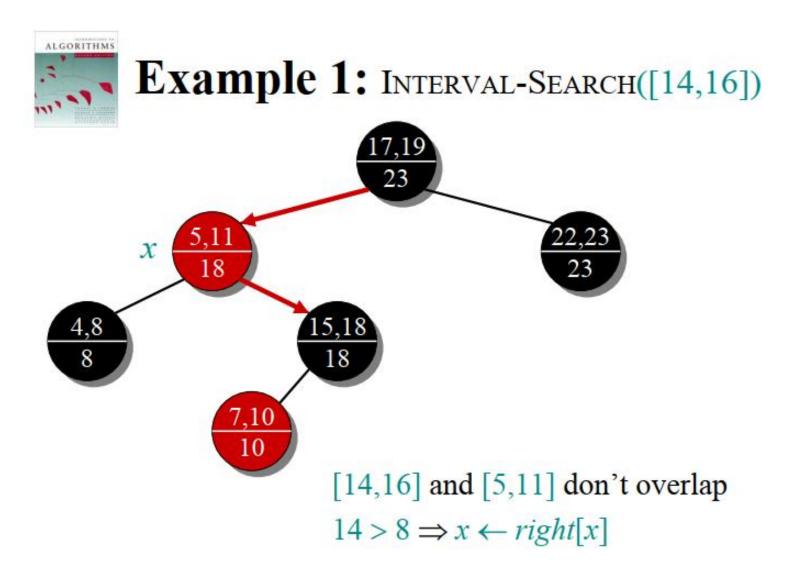
if left[x] \neq NIL and low[i] \leq m[left[x]]

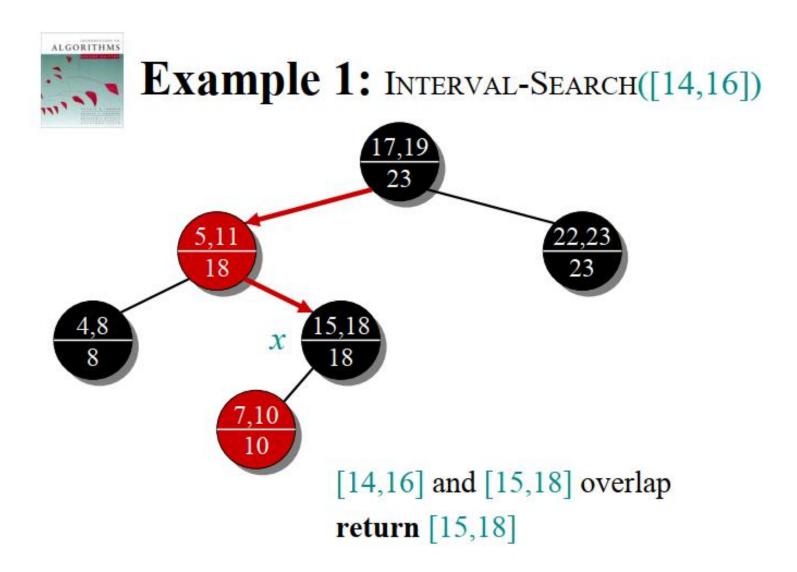
then x \leftarrow left[x]

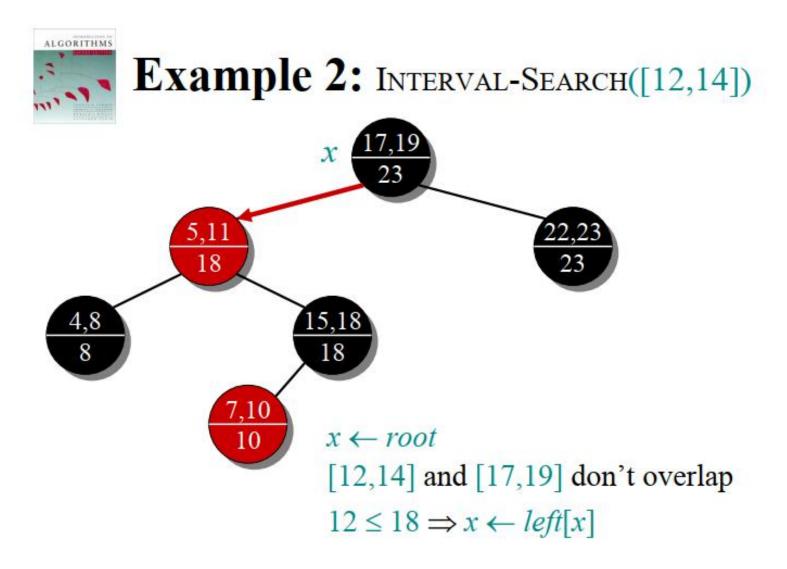
else x \leftarrow right[x]

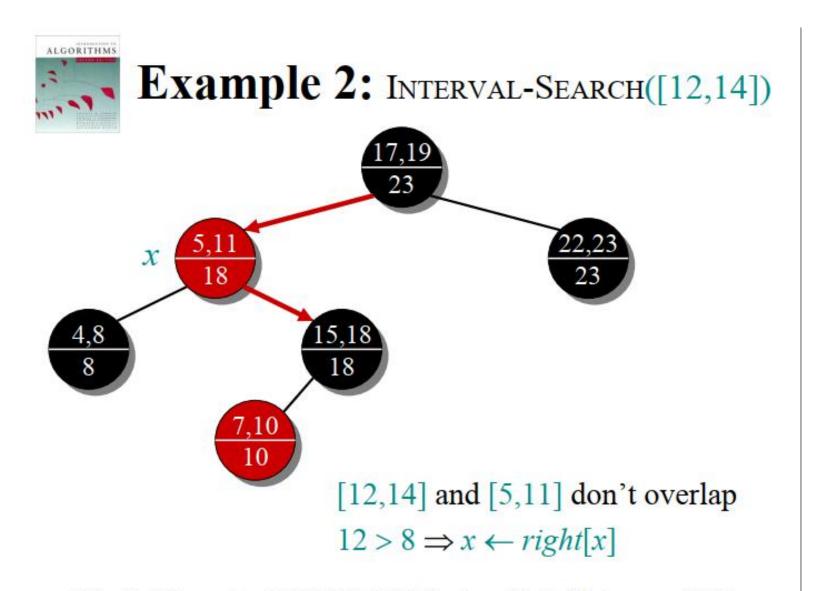
return x
```

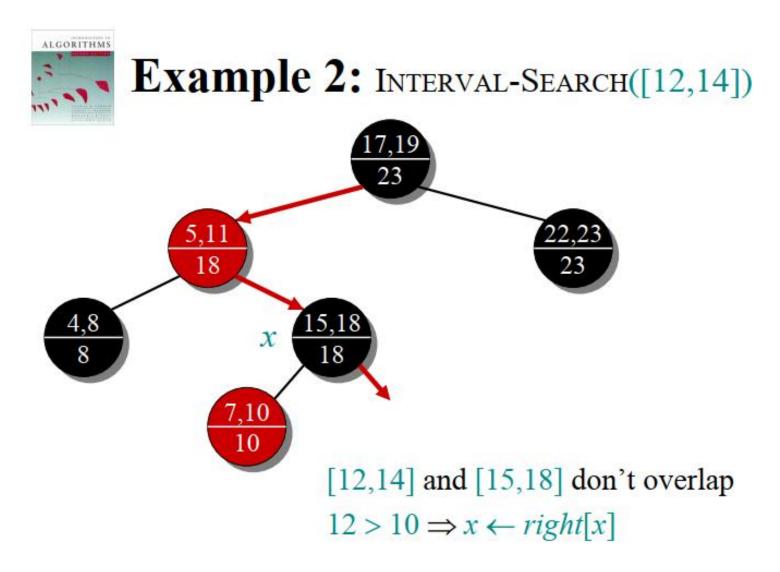


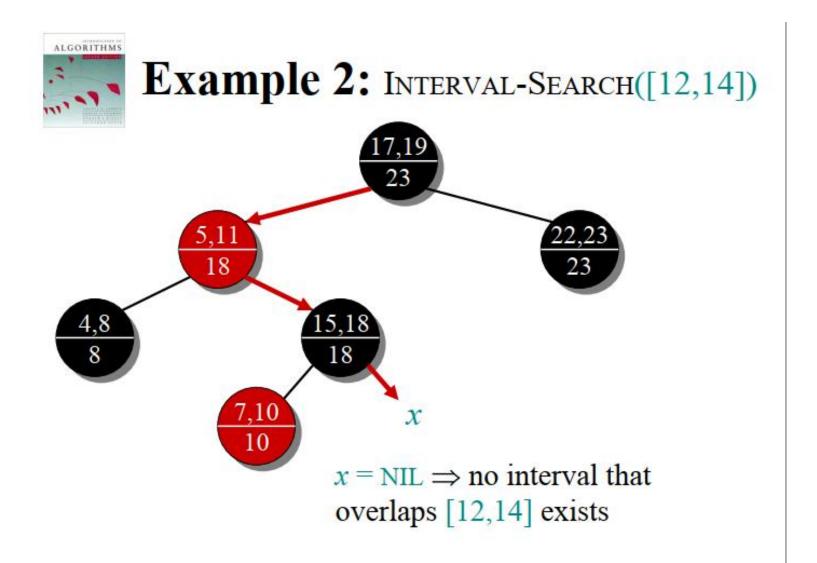








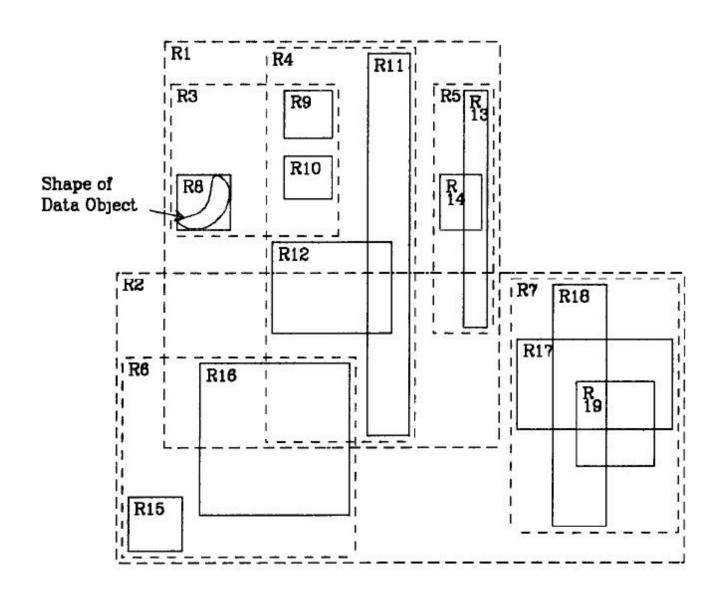


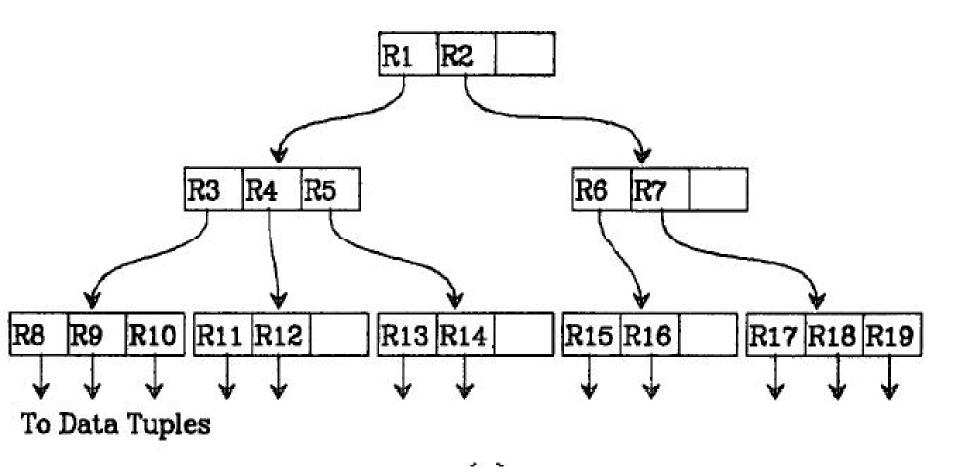


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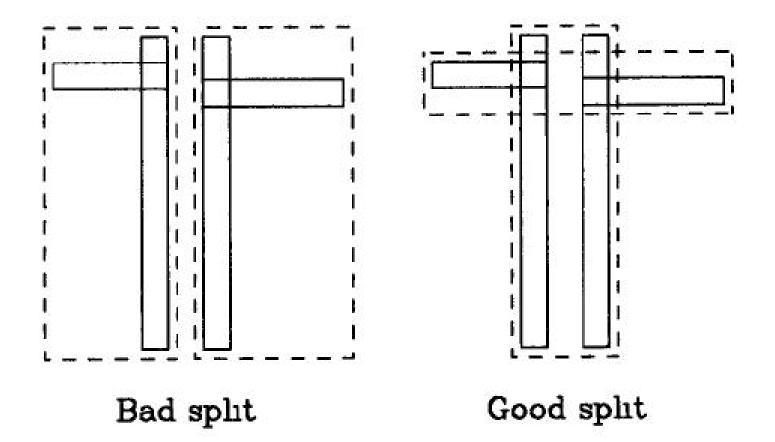
And R-tree





R-TREES: A DYNAMIC INDEX STRUCTURE FOR SPATIAL SEARCHING

Antonin Guttman University of California Berkeley



And Hilbert R-tree

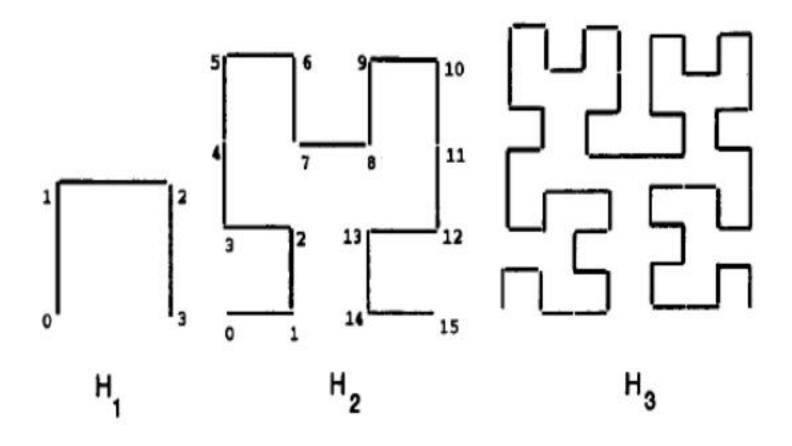
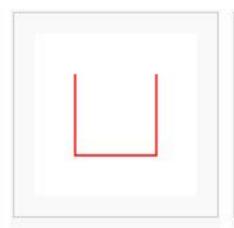
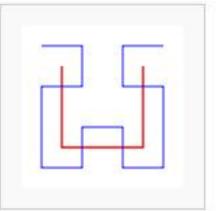


Figure 1: Hilbert Curves of order 1, 2 and 3

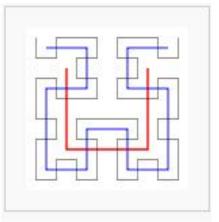
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Hilbert curve, first order



Hilbert curves, first and second orders



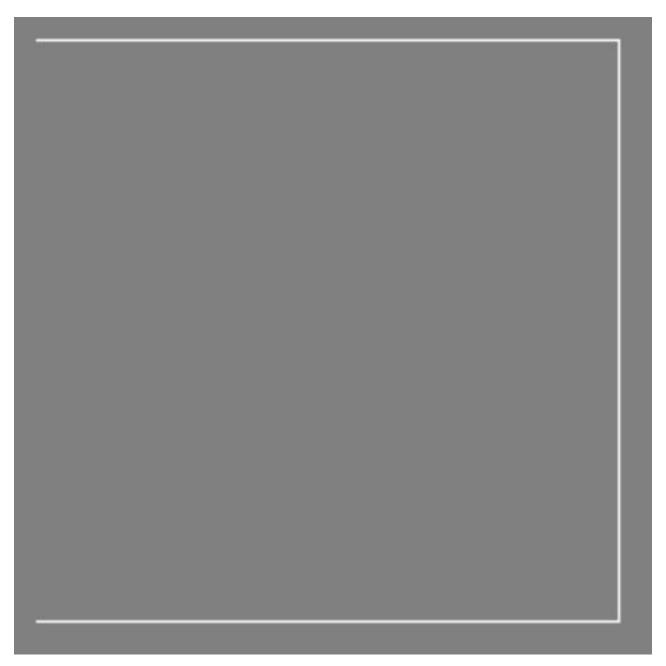
Hilbert curves, first to third orders



Hilbert curve in three dimensions



3-D Hilbert curve with color showing progression



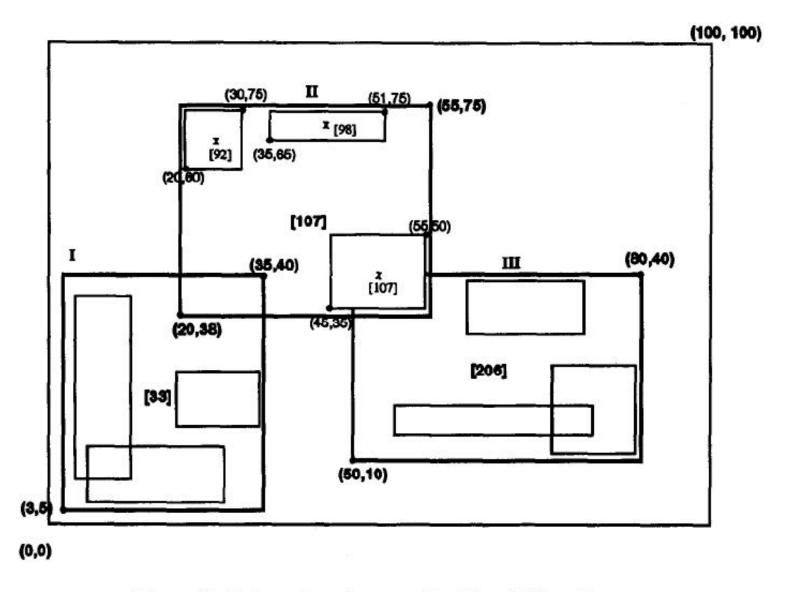


Figure 2: Data rectangles organized in a Hilbert R-tree

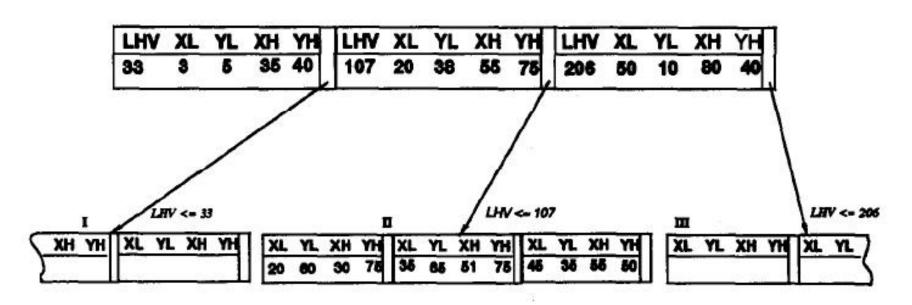


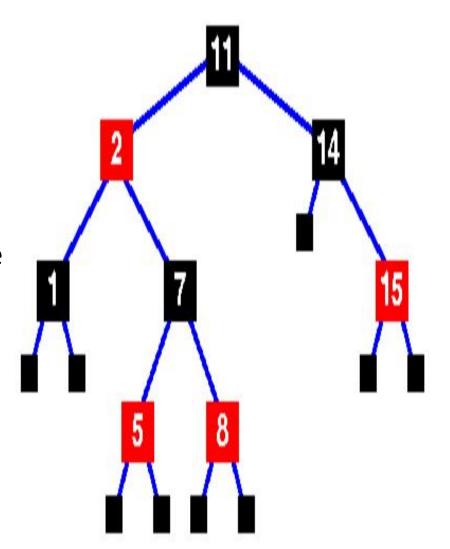
Figure 3: The file structure for the previous Hilbert R-tree

Outline

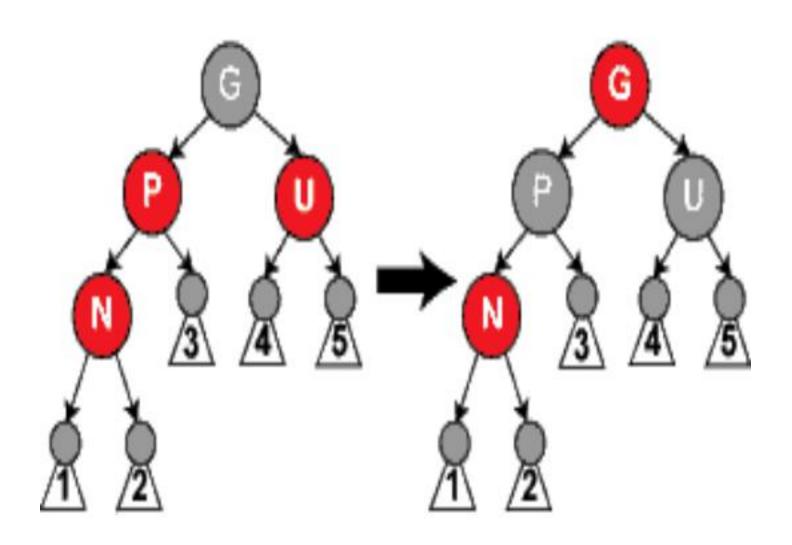
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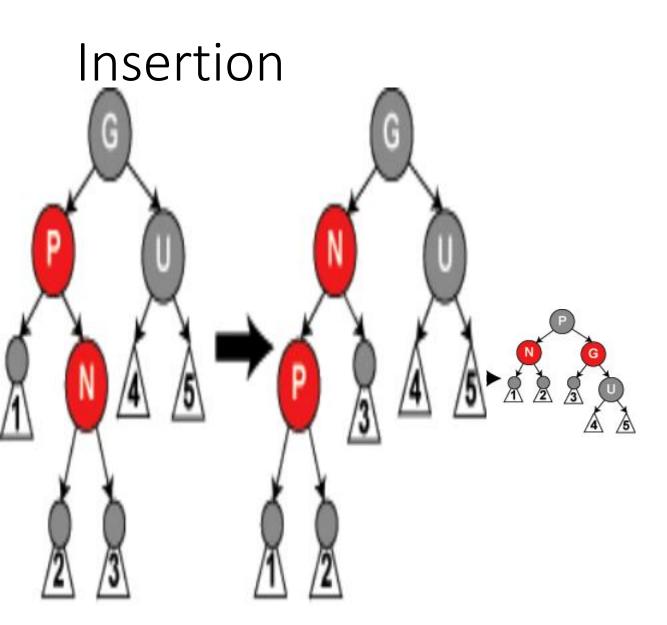
And Red Black-tree

- 1. A node is either red or black.
- 2. The root is black
- All leaves are black.
- Both children of every red node are black.
- 5. Every <u>simple path</u> from a given node to any of its descendant leaves contains **the same number of black nodes.**



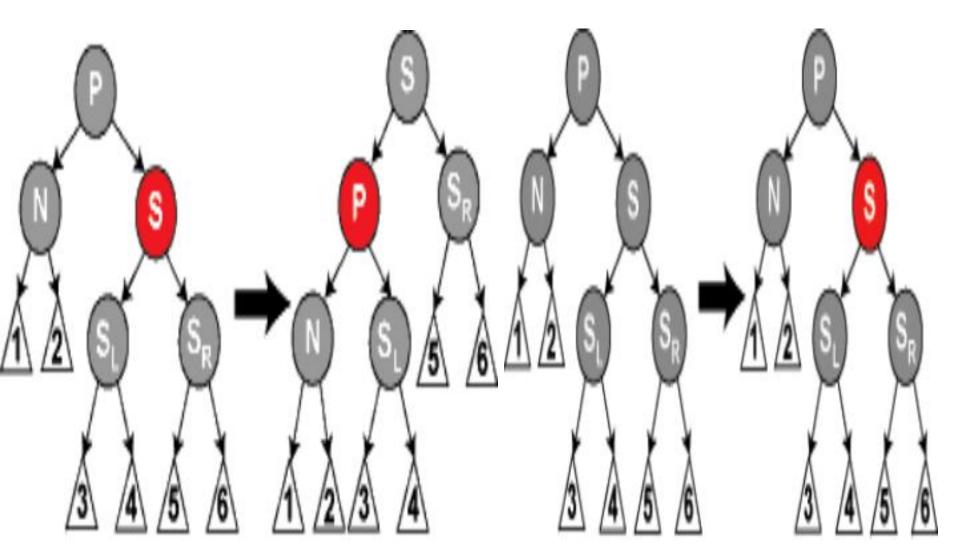
Insertion



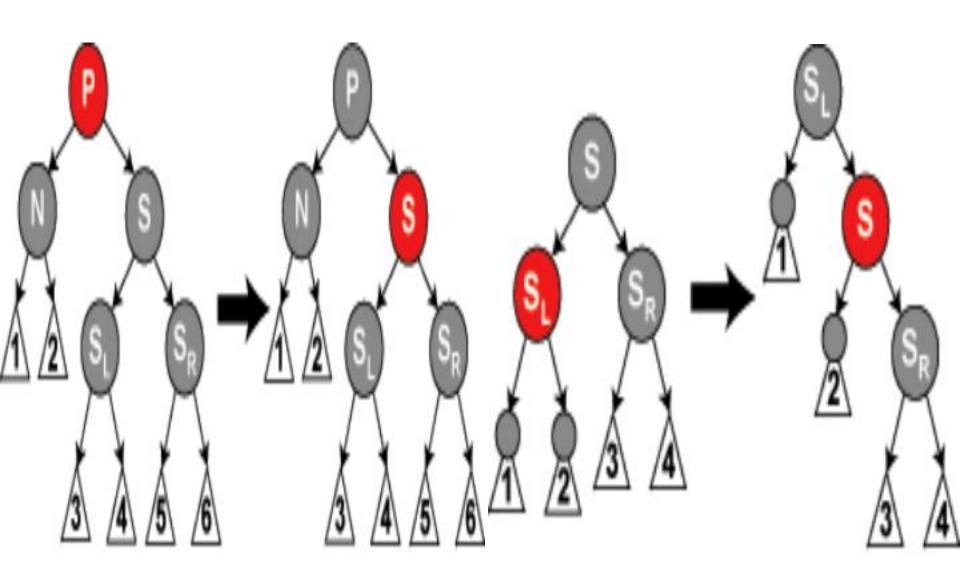


Deletion

- 1. this reduces to the problem of deleting a node with at most one non-leaf child.
 - deleting a red node
 - the deleted node is black and its child is red
 - both the node to be deleted and its child are black



东南大学数据科学与智能实验室(D&Intel Lab)



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