

Confidential

Version	Date	Document Owner	Changes
1.0	2-27	PanJuan	初稿
2.0	2-28	PanJuan	1、修改 openCamera 接口的参数; 2、删除 getNewFrame—和doneWithFrame—接口,同时增加回调接口postFrameFromNative 和postEventFromNative; 3、附加使用限制说明。
<mark>2. 1</mark>	03-02	<mark>PanJuan</mark>	增加待确认项1和2

1 EVC Camera

1.1 boolean initCameraService(void);

This function initializes the camera service.

Returns:

true if success , false if failure.

1.2 ArrayList<CameraDesc> getCameraList(void);

This function returns description of all cameras.

Class CameraDesc defines variables: camera id(int), camera description(string:left ,right,rear,front), width(int), height(int), format(int).

Returns:

The description of cameras.

1.3 boolean openCamera(int cameraId, CameraCallback callback);

This function will open the camera about the camera id.

Parameters:

camerald the id of camera will be opened.

callback the listener which should implement the callback functions.

Returns:

True if success, false if failure.

1.4 boolean startStream(int cameraId);

This function will start the video frame flow.



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Parameters:

camerald the id of camera will be started to transit the frame.

Returns:

true if success, false if failure.

boolean_getNewFrame(int_camerald, byte[] buffer);

This function will return the video frame pointer, the default format is yuv422.

Parameters:

camerald the id of camera.

buffer the byte array to store buffer

Returns:

true if success, false if failure.

boolean doneWithFrame (int camersId);

When you used up the frame, you must call the API, it will put the buffer back to the list.

Parameters:

camerald the id of camera which is used up.

Returns:

true if success, false if failure.

1.5 boolean stopStream(int cameraId);

This function will stop the video frame flow.

Parameters:

camerald the id of camera will be stopped to transit the frame.

Returns:

true if success, false if failure.

1.6 boolean closeCamera(int cameraId);

This function will close the camera about the camera id.

Parameters:

camerald the id of camera will be closed.

Returns:

True if success, false if failure.

2 Evs CameraCallback

2.1 void postFrameFromNative(byte[] buffer, long size, int cameraId);

The callback function in Class CameraCallback. App get the frame buffer data and size in this callback. CameraCallback is parameter of openCamera.



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Parameters:

buffer the byte array of data. size the buffer size.

camerald the id of camera which post the frame.

2.2 void postEventFromNative(int errorId, int cameraId);

The callback function in Class CameraCallback. App get the error code in this callback. CameraCallback is parameter of openCamera.

Parameters:

errorId The error code which will be defined in the manager.

cameraId the id of camera which post the error.

3 Additional Notes

3.1 使用限制:

跟 App 沟通接口后,App 表示可以保证在第二帧 Camera 数据到来之前完成对第一帧数据 buffer 的使用,所以不想调用 doneWithFrame 通知底层 buffer 使用完了,因此我们会删除这个接口不给 App 调用。App 要确保这点,以防使用超时导致出现第二帧数据把第一帧数据改写的情况。

4 待确认项

- 1. 关于跟仪表盘的接口,还需后续根据具体需求展开讨论;
- 2. 关于数据格式yuv422转yuv420的,desay会评估是否有硬件方案可以支持格式转换,如果没有的话,只能提供原始格式,由百度负责格式转换。