# **Navigation Based Pilot**

# Subsystem Technology Specific Specification (STSS)

Version 1.1
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FORD CONFIDENTIAL

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# **Terms and Definitions**

Abbreviation	Description
NBP	Navigation Based Pilot
ALC	Assisted Lane Change
TJA	Traffic Jam Assist

# 1. Navigation Based Pilot

# 1.1 Functional Description

This STSS handles the functions associated with the Navigation Based Pilot feature, hereafter called NBP feature or NBP.

When a user is driving a vehicle with ALC, the user will be indicated by a lane change suggestion if it's determined to be helpful. Following a turn signal initiated by driver, the vehicle will perform a lane change.

Based on ALC, NBP will add the ability for vehicle to provide lane change suggestions according Navigation indication.

Currently, NBP scenarios are below:

- Highway Exit
- Y-shaped Road
- Lane End

Depending on the vehicle location relative to lane position and the distance to target road section and objects, this feature will:

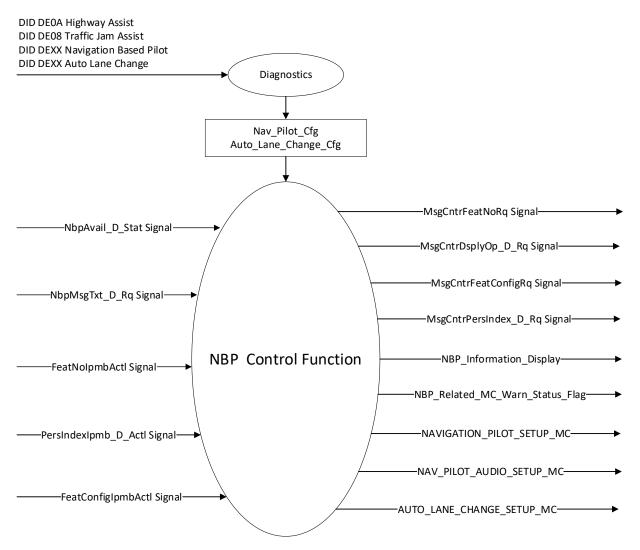
- Signal to driver for a lane change suggestion
- Signal to driver for taking over steering control

Starting with MY2024 CX771/CX821, Navigation Based Pilot (NBP) has been introduced to the suite of Highway Assist feature with the support of new introduced IPMB\_EPC module. NBP enriches the capability providing lane change suggestion against additional scenarios (means Highway Exit) compared with that supported by ALC.

Navigation Based Pilot correlates the personalization signals from the IPMB, several signals from IPMB EPC and the Operation Mode to determine when to activate additional appropriate displays.

## 1.2 Interfaces

## 1.2.1 Interface Context Diagram (I/O Block Diagram)



**Figure 2 NBP Context Diagram** 

# **1.2.2 Inputs**

## 1.2.2.1 Internal

- Hwy\_Assist\_Cfg Feature Cfg
- Traffic\_Jam\_Assist\_Cfg Feature Cfg
- Nav\_Piolot\_Cfg
- Auto\_Lane\_Change\_Cfg

# 1.2.2.2 MUX signals on the CAN Bus from IPMB (2nd ECU)

1.2.2.2.1 FeatConfigIpmbActl Signal

Signal Name	Size (bits)	Detail	Units	Res.	Offset	State Encoded	Min	Max
FeatConfigIpmbActl	16	-	Undefined	1	0		0 (0x0)	65535 (0xFFFF)

1.2.2.2.2 FeatNolpmbActl Signal

Signal Name	Size (bits)	Detail	Units	Res.	Offset	State Encoded	Min	Max
FeatNoIpmbActl	16	-	Number	1	0		0 (0x0)	65535 (0xFFFF)

1.2.2.2.3 PersIndexIpmb\_D\_Actl Signal

1.Z.Z.Z.O 1 CI SIII ackipiii	<u> </u>	. O.g.i.a.						
Signal Name	Size (bits)	Detail	Units	Res.	Offset	State Encoded	Min	Max
PersIndexIpmb_D_Actl	3		SED	1	0		0(0x0)	7 (0x7)
		PERS_1				0x0		
		PERS_2				0x1		
		PERS_3				0x2		
		PERS_4				0x3		
		Vehicle				0x4		
		Unused				0x5		
		Unused				0x6		
		Unused				0x7		

1.2.2.2.4 NbpAvail D Stat Signal

Signal Name	Size (bits)	Detail	Units	Res.	Offset	State Encoded	Min	Max
NbpAvail _D_Stat	3		SED	1	0		0 (0x0)	7 (0x7)
		Off				0x0		
		Standby				0x1		
		AvailableLnChngSuggstnOnly				0x2		
		AvailableDrvLnChng				0x3		
		AvailableVehLnChng				0x4		
		NbpFailure				0x5		
		NotUsed_1				0x6		
		NotUsed_2				0x7		

#### 1.2.2.2.5 SIG-REQ-XXXXXX/A- NbpMsgTxt\_D\_Rq Signal

Signal Name	Size (bits)	Detail	Uni ts	Res.	Offset	State Encoded	Min	Max
NbpMsgTx	4		SE	1	0		0	15
t_D_Rq	4		D	1	U		(0x0)	(0xF)
		NoMessage				0x0		
		LnChngSuggstnLeftFaterLn				0x1		
		LnChngSuggstnRightFaterLn				0x2		
		AlcOn				0x3		
		AlcOff				0x4		
		TurnOffIndicator				0x5		
		LnChngSuggstnLeftNav				0x6		
		LnChngSuggstnRightNav				0x7		
		HandOver				0x8		
		MissingExitAlert				0x9		
		LnChngSuggstnLeftManual				0xA		
		LnChngSuggstnRightManual				0xB		
		NotUsed_1				0xC		
		NotUsed_2				0xD		
		NotUsed_3				0xE		
		NotUsed_4				0xF		

#### 1.2.3 Outputs

#### 1.2.3.1 Internal

- NBP Information Display displays the Navigation Based Pilot information in the ADAS metaphor.
- NAVIGATION\_PILOT\_SETUP\_MC, controls the setting menu display output for Navigation Based Pilot.
- NAV\_PILOT\_AUDIO\_SETUP\_MC, controls the setting menu display output for Navigation Based Pilot audio selection.
- AUTO\_LANE\_CHANGE\_SETUP\_MC, controls the setting menu display output for Auto Lane Change.
- NBP\_Related\_MC\_Warn\_Status\_Flag, which is used to control the state of the text warning message including those MC\_Warn\_Status\_Flag below:
  - 1) Navigation\_Pilot\_Unavailable\_MC\_Warn\_Status\_Flag
  - 2) Lane\_Change\_Suggested\_For\_Faster\_Lane\_Left\_MC\_Warn\_Status\_Flag
  - 3) Lane\_Change\_Suggested\_For\_Faster\_Lane\_Right\_MC\_Warn\_Status\_Flag
  - 4) Lane\_Change\_Suggested\_Following Navigation Left\_MC\_Warn\_Status\_Flag
  - 5) Lane Change Suggested Following Navigation Right MC Warn Status Flag
  - 6) LnChngSuggstnLeftManual\_MC\_Warn\_Status\_Flag
  - 7) LnChngSuggstnRightManual\_MC\_Warn\_Status\_Flag
  - 8) HandOver MC Warn Status Flag
  - 9) Missing\_Exit\_Alert\_MC\_Warn\_Status\_Flag

# 1.2.3.2 MUX signals on the CAN Bus to IPMB (2nd ECU)

1.2.3.2.1 MsgCntrFeatNoRq Signal

Signal Name	Size (bits)	Detail	Units	Res.	Offset	State Encoded	Min	Max
MsgCntrFeatNoRq	16	-	Number	1	0		0 (0x0)	65535 (0xFFFF)

1.2.3.2.2 MsgCntrDsplyOp\_D\_Rq Signal

Signal Name	Size (bits)	Detail	Units	Res.	Offset	State Encoded	Min	Max
MsgCntrDsplyOp_D_Rq	3		SED	1	0		0 (0x0)	7 (0x7)
		NULL				0x0		
		QUERY				0x1		
		SET				0x2		
		UPLOAD				0x3		
		RESTORE				0x4		
		COPY				0x5		
		Unused				0x6		
		Unused				0x7		

1.2.3.2.3 MsgCntrFeatConfigRq Signal

Signal Name	Size (bits)	Detail	Units	Res.	Offset	State Encoded	Min	Max
MsgCntrFeatConfigRq	16	-	Undefined	1	0		0 (0x0)	65535 (0xFFFF)

1.2.3.2.4 MsgCntrPersIndex D Rq Signal

Signal Name	Size (bits)	Detail	Units	Res.	Offset	State Encoded	Min	Max
MsgCntrPersIndex_D_Rq	3		SED	1	0		0 (0x0)	7 (0x7)
		PERS_1				0x0		
		PERS_2				0x1		
		PERS_3				0x2		
		PERS_4				0x3		
		Vehicle				0x4		
		Unused				0x5		
		Unused				0x6		
		Unused				0x7		

## 1.3 Function/Performance

#### 1.3.1 Operational Modes

Mode	Differentiating Vehicle Conditions
Sleep Mode	NBP Control Function Text Message Disabled
Limited Mode	NBP Control Function Text Message Disabled
Normal Mode	NBP Control Function Text Message Enabled / Disabled
Crank Mode	NBP Control Function Text Message Enabled / Disabled

## 1.3.2 Voltage Levels

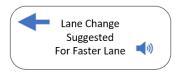
Refer to the Cluster Features table located in the Operational Modes and Voltage Range Strategies.

#### 1.3.3 Human-Machine Interface

#### 1.3.3.1 Visual

#### 1.3.3.1.1 Indicator Graphics / Display Format

Example Graphic (final graphics to be provided by HMI wallpaper)





Message Center Text Warning Message as defined in section 1.3.3.5.12 of this document. Actual wording may vary based on Program Translation table.

Please refer to the program specific menu structure for exact graphics.

**Example Menu Structure:** 

Menu level 0	Menu level 1	Menu level 2	Comments
		With Lane Centering	Traffic_Jam_Assist_Cfg = 0x1 (Enabled) Hwy_Assist_Cfg = 0x0 (Disabled) Nav_Pilot_Cfg = X (Don't Care) Auto_Lane_Change_Cfg = X (Don't Care)
	Cruise Control	With Lane Centering (Blue Cruise)	$Hwy_Assist_Cfg = 0x1$ (Enabled)
		With Smart Offerings	$Traffic\_Jam\_Assist\_Cfg = X (Don't Care)$
		Lane Biasing	$Nav_Pilot_Cfg = 0x0 (Disabled)$
		Assist Lane Change	$Auto\_Lane\_Change\_Cfg = X (Don't Care)$
		With Lane Centering (Blue Cruise)	
Driver Assist		With Smart Offerings	$Hwy\_Assist\_Cfg = 0x1$ (Enabled)
		Lane Biasing	$Traffic_Jam_Assist_Cfg = X (Don't Care)$
		Assist Lane Change	$Nav_Pilot_Cfg = 0x1$ (Enabled)
		<ul><li>Navigation Based Pilot</li><li>Audio On</li></ul>	Auto_Lane_Change_Cfg = 0x0 (Disabled)
		With Lane Centering (Blue Cruise) With Smart Offerings Lane Biasing Assist Lane Change	Hwy_Assist_Cfg = 0x1 (Enabled) Traffic_Jam_Assist_Cfg = X (Don't Care) Nav_Pilot_Cfg = 0x1 (Enabled) Auto_Lane_Change_Cfg = 0x1 (Enabled)
		<ul> <li>Navigation Based Pilot</li> </ul>	Auto_Lane_Change_Ctg = 0x1 (Enabled)

	<ul> <li>Audio On</li> </ul>	
	<ul> <li>Auto Lane Change</li> </ul>	

Menu display logic in above list:

About the menu of Lane Biasing and Assist Lane Change (Pre-condition: Hwy\_Assist\_Cfg = 0x1 (Enabled))

Menu display of Lane Biasing and Assisted Lane Change depends on the customer selection of Blue Cruise (Ford Brand)/Active Glide (Lincoln Brand) feature. LB and ALC shall appear when Blue Cruise is selected on, while disappear when Blue Cruise is selected off.

2. About the menu of Navigation Based Pilot (Pre-condition: Hwy\_Assist\_Cfg = 0x1 (Enabled))

Menu display of Navigation Based Pilot depends on the customer selection of ALC feature. Navigation Based Pilot shall appear when ALC is selected on, while disappear when ALC is selected off. And the two sub menus: Audio On and Auto Lane Change can be checked or unchecked independently.

3. IVI/SYNC+ should query Navigation Based Pilot menu every time after bootup and get response and display last remembered settings (follow HA menu strategy). Last remembered settings are saved on IPMB.

#### 1.3.3.1.2 Indicator Color Coordinates

Refer to program specific HMI requirements for styling direction.

#### 1.3.3.1.3 Indicator Characteristics

As per program specific HMI theme.

#### 1.3.3.2 Audio- 待修改

#### F-REQ-XXXXXX (NBP indication and cancellation).

Note that both Graphic and Voice indication could be provided during NBP operation while voice broadcast can be enabled/disabled by customer in the setting menu.

When both supported, voice broadcast should show synchronously with the graphic text. The voice content needs to be broadcasted once till the signal transits to a new state.

Note that considering the similarity between NBP voice broadcast and Navigation broadcast, NBP shows a higher priority. Hence, arbitration between these two should be supported.

#### 1.3.3.3 Switch Control Logic

Consumer access to NBP Module Configuration shall be as specified in the message center basic functionality display as specified in Message Center X Display\_Y Button Interface Section, where X and Y are appropriate values in this document.

#### 13.4 System Accuracy

Within 100 msec of receiving a message that results in a change of state the cluster will update the display to the proper state.

#### 1.3.5 Operation: Performance and Functional

#### 1.3.5.1 Subsystem Algorithm Flowchart / State Diagram

# 1.3.3.5.1 Highway Assist with Navigation Pilot Diagnostic Configuration Flowchart

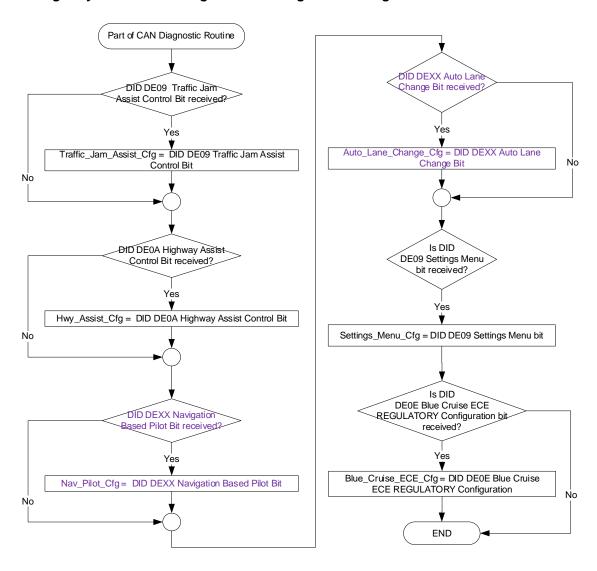


Figure 3.1 Diagnostic Configuration Flowchart

Figure 3.1 is based on F-REQ-343087/A-Highway Assist and Lane Centering Diagnostic Configuration Flowchart in < Highway Assist with Lane Centering Control Function and Warnings - FNV2.docm>. The purple content is added for NBP.

# 1.3.3.5.2 Highway Assist and Lane Centering and Navigation Based Pilot Menu Display Determination Matrix

Hwy_Assist_Cfg	Traffic_Jam_Assist_Cfg	Nav_Pilot_Cfg	"With Lane Centering" Displayed in menu?	"With Smart Offering" Displayed in menu?	"With Nav Pilot" Displayed in menu?
Enabled (0x1)	Enabled (0x1)	Enabled (0x1)	Yes	Yes	Yes
Enabled (0x1)	Enabled (0x1)	Disabled (0x0)	Yes	Yes	No
Enabled (x1)	Disabled (0x0)	Enabled (0x1)	Yes	Yes	Yes
Enabled (0x1)	Disabled (0x0)	Disabled (0x0)	Yes	Yes	No
Disabled (0x0)	Enabled (0x1)	Enabled (0x1)	Yes	No	No
Disabled (0x0)	Enabled (0x1)	Disabled (0x0)	Yes	No	No
Disabled (0x0)	Disabled (0x0)	Enabled (0x1)	No	No	No
Disabled (0x0)	Disabled (0x0)	Disabled (0x0)	No	No	No

# 1.3.3.5.3 Highway Assist with Navigation Pilot input request Flowchart

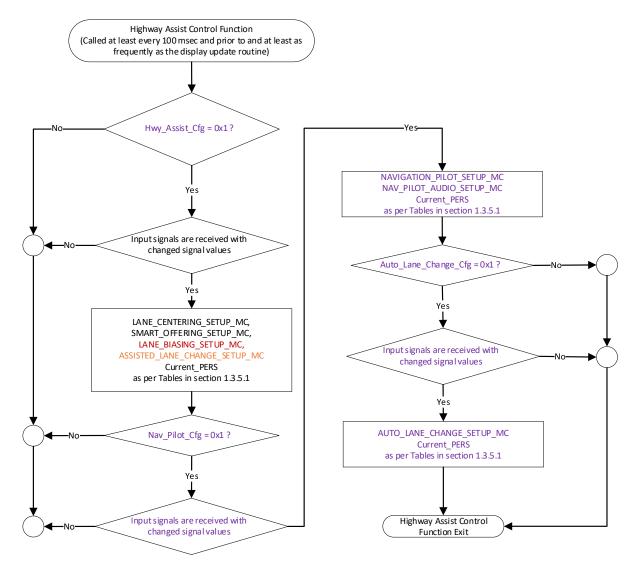


Figure 3.2 Input Request Flowchart

Figure 3.2 is based on F-REQ-343089/D-Highway Assist and Lane Centering input request Flowcharts in < Highway Assist with Lane Centering Control Function and Warnings - FNV2.docm>. The purple content is added or modified for NBP.

Input signals are received in a message from IPMB (2nd ECU), including FeatNoIpmbActl Signal, FeatConfigIpmbActl Signal, PersIndexIpmb\_D\_Actl Signal that is described in IO inputs.

# 1.3.3.5.4 Highway Assist with Navigation Pilot output SET request Flowchart

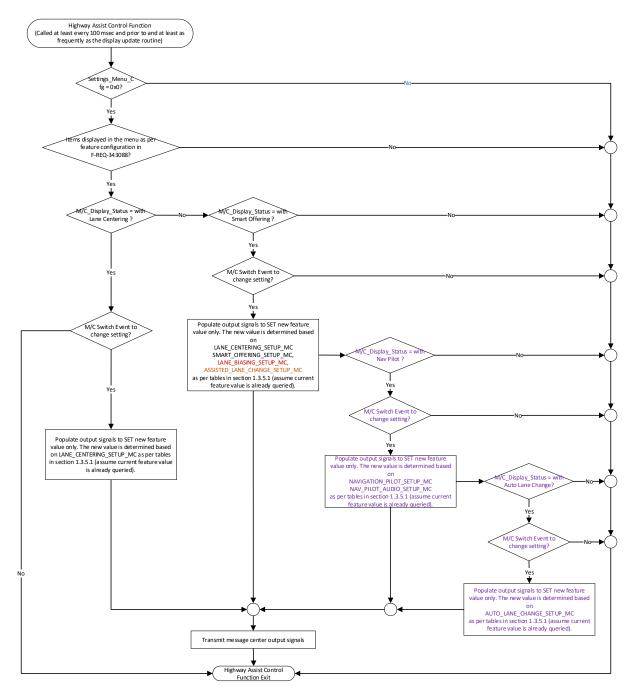


Figure 3.3 Output SET Request Flowchart

Figure 3.3 is based on F-REQ-343090/D-Highway Assist and Lane Centering Output SET request Flowchart in < Highway Assist with Lane Centering Control Function and Warnings - FNV2.docm>. The purple content is added for NBP.

Output signals are sent in a message to IPMB (2nd ECU), including MsgCntrDsplyOp\_D\_Rq Signal, MsgCntrFeatNoRq Signal, MsgCntrFeatConfigRq Signal and MsgCntrPersIndex\_D\_Rq Signal that is described in Setup Request Messages.

## 1.3.3.5.5 Navigation Based Pilot Setup State Assignment

FeatNoIpmb Actl Signal	FeatConfigIpmbActl Signal	PersIndexIpmb_D_Actl Signal	NAVIGATION_PILOT_ SETUP_MC	Current_PERS (3)	
	0x0000 (Off)	0x0 - 0x4	0x00	0x0 - 0x4	
0x0880 (1)	0x0001 (On)	0x0 - 0x4	0x01	0x0 - 0x4	
	Oth	ner (2)	Error	Last Known	
	Missing per Section	1.4.1 (2)	(0x2)		

<sup>(1)</sup> Navigation Based Pilot Feature Number. Reference is Feat Num table in "Vehicle Personalization FS"

# 1.3.3.5.6 Navigation Based Pilot Setup Request Messages based upon NAVIGATION\_PILOT\_SETUP\_MC

ASSISTED_ LANE_CHANGE_ SETUP_MC	Display Menu	M/C Switch Selection Event	MsgCntrDsplyOp_ D_Rq Signal	MsgCntrFeatNoRq Signal	MsgCntrFeatCon figRq Signal	MsgCntrPersIndex _D_Rq Signal
0x00 or 0x02	(Off)	Up/Down + OK (Select On)	SET (0x2)	0x0880	0x0001 (If On is selected)	Current_PERS
0x01	(On)	Up/Down + OK (Select Off)	SET (0x2)	0x0880	0x0000 (If Off is selected)	Current_PERS

# 1.3.3.5.7 Navigation Pilot Audio Setup State Assignment

FeatNoIpmb Actl Signal	FeatConfigIpmbActl Signal	PersIndexIpmb_D_Actl Signal	NAVIGATION_PILOT_ SETUP_MC	Current_PERS (3)	
	0x0000 (Off)	0x0 - 0x4	0x00	0x0 - 0x4	
0x0881 (1)	0x0001 (On)	0x0 - 0x4	0x01	0x0 - 0x4	
	Other (2	2)	Error		
	Missing per Section 1.4.1	(0x2)	Last Known		

<sup>(1)</sup> Navigation Pilot Audio Feature Number. Reference is Feat Num table in "Vehicle Personalization FS"

<sup>(2)</sup> Message Response is Faulted

<sup>(3)</sup> Equal to the received "PersIndex<--->" signal value. When faulted Keep last known value.

<sup>(2)</sup> Message Response is Faulted

<sup>(3)</sup> Equal to the received "PersIndex<--->" signal value. When faulted Keep last known value.

# 1.3.3.5.8 Navigation Pilot Audio Setup Request Messages based upon NAV\_PILOT\_AUDIO\_SETUP\_MC

ASSISTED_ LANE_CHANGE_ SETUP_MC	Display Menu	M/C Switch Selection Event	MsgCntrDsplyOp_ D_Rq Signal	MsgCntrFeatNoRq Signal	MsgCntrFeatConfig Rq Signal	MsgCntrPersIndex _D_Rq Signal
0x00 or 0x02	(Off)	Up/Down + OK (Select On)	SET (0x2)	0x0881	0x0001 (If On is selected)	Current_PERS
0x01	(On)	Up/Down + OK (Select Off)	SET (0x2)	0x0881	0x0000 (If Off is selected)	Current_PERS

## 1.3.3.5.9 Auto Lane Change Setup State Assignment

FeatNoIpmbActl Signal	FeatConfigIpmbActl Signal	PersIndexIpmb_D_Actl Signal	NAVIGATION_PILOT_ SETUP_MC	Current_PERS (3)
	0x0000 (Off)	0x0 - 0x4	0x00	0x0 - 0x4
0x0882 (1)	0x0001 (On)	0x0 - 0x4	0x01	0x0 - 0x4
	Oti	her (2)	Error	Last Wassess
	Missing per Section 1.4.	(0x2)	Last Known	

# 1.3.3.5.10 Auto Lane Change Setup Request Messages based upon AUTO\_LANE\_CHANGE\_SETUP\_MC

ASSISTED_ LANE_CHANGE_ SETUP_MC	Display Menu	M/C Switch Selection Event	MsgCntrDsplyOp_ D_Rq Signal	MsgCntrFeatNoRq Signal	MsgCntrFeatConfig Rq Signal	MsgCntrPersIndex_ D_Rq Signal
0x00 or 0x02	(Off)	Up/Down + OK (Select On)	SET (0x2)	0x0882	0x0001 (If On is selected)	Current_PERS
0x01	(On)	Up/Down + OK (Select Off)	SET (0x2)	0x0882	0x0000 (If Off is selected)	Current_PERS

# 1.3.3.5.11 State Matrix Update for Assisted Lane Change Information with NBP

Assisted Lane Change Information will be shown whenever Navigation Based Pilot is not available (either because Navigation Based Pilot is configured off or even if equipped but not activated due to driver deselection or without Navigation route).

Operational_Mode	Feature Config	NbpAvail_D_Stat Signal	Blue_Cruise_ECE	TjaLc_D_Stat Signal	TjaLcWarn_D_Rq Signal	TjaLcMsgTxt_D_Rq		ALC_Information_ Display (Example Graphics)	Chime Status Flag	
	cd) Don' t Care)	Traffic_Jam_Assist_Cfg = 0x1 (Enabled) OR Hwy_Assist_Cfg = 0x1 (Enabled)  AND Nav_Pilot_Cfg = X (Don' t Care) AND Auto_Lane_Change_Cfg = X (Don' t Care)  and Mary_Bilot_Cfg = X (Don' t Care)  and Mary_Assist_Cfg = 0x1 (Enabled)  AND Auto_Lane_Change_Cfg = X (Don' t Care)  and Mary_Bilot_Cfg = X (D		0x1 (Standby)		X (Don't Care)	Active	((under speed threshold or no lanes detected) chevrons have less contrast and line thickness)	None	
				0x2 (AvailableLeft)	X (Don't Care)			(Grey chevron on the left only)	None	
Nor mal or Cran k	ssist_Cfg = 0x1 ( Enab. .ane_Change_Cfg = X		X (Don't Care)	0x3 (AvailableRight)				(Gray chevron on the right only)	None	
	0x1 (Enabled) OR Hwy_Assi Don't Care) AND Auto_La		e Ox1 (Enabled) OR Hwy_As (Don't Care) AND Auto_I w Ball Ball Ball Ball Ball Ball Ball Bal	(Don't Care) AND Auto I		0x4 (AvailableLeftRigh t)				(Grey Chevron on both sides, example graphic of HA in limited mode)
	Traffic_Jam_Assist_Cfg = AND Nav_Pilot_Cfg = X			0x5 (PreparingLeft)				Preparing Lane Change READY  (Blue Chevron on the Left, none Right, example graphic of HA in extended mode)	None	

i	ī			-		1		
			0x6 (PreparingRight)				Preparing Lane Change  BLADY  (Blue Chevron on the Right, none Left)	None
			0x7 (LcActiveLeft)				(part of animation Indicating a lane change to the left, final static image is displayed as long as signal is active)	None
			0x8 (LcActiveRight)				part of animation Indicating a lane change to the right, final static image is displayed as long as signal is active)	None
		0x1 (Enabled)		0x1 (DriverCancel)			Canceled by Driver* (GML ID: A13)	
				0x2 (SystemCancel)	X (Don't Care)		Not Available (GML ID: A21)	ity_ Jag
	X (Don't Care)	X (Don't Care)	0x3 (CancelNoLane)		Active	Not Available No Lane Seen* (GML ID: A15)	TJA_Low_Priority_ Chime_Status_Flag	
				0x4 (CancelLaneBusy)			Not Available Lane Busy* (GML ID: A14)	
				0x5 (CancelSpeedToo Low)			Not Available Low Speed* (GML ID: A16)	

	_Cfg = 0x1 ( Enabled) ne_Change_Cfg = X	0x0 (Off)				0x1 (LcSugges tionLeft)		Lane Change Suggested  (above text or "Lane Change Possible, Use Left Turn Signal to make lane change" based on application HMI)	None
Nor mal or Cran k	t_Cfg = 0x1 (Enabled) OR Hwy_Assist _Cfg = X (Don't Care) AND Auto_La	(Nbp Failur e)	X (Don't Care)	X (Don't Care)	0x2 (LcSugges tionRight)	Active	(above text or "Lane Change Possible, Use Left Turn Signal to make lane change" based on application HMI Example graphic of HA in Extended mode)	None	
	Traffic_Jam_Assist_Cfg = AND Nav_Pilot_Cfg =	ng				0x5 (TurnOffIn dicator)		Turn Signal Is Stil Active (Text: Turn Signal is Still Active)	None
			All	Other Cases			Inacti ve	(No indication)	None

The ADAS controller will arbitrate and populate the 3 input signals above, cluster simply displays information based on signal states received.

Note \*: The generic "Cancelation (GML ID: A1)" notification shall be displayed only if application display does not have space to display reason text.

For Assisted Lane Change, "Not Available" (GML ID: A21) notification shall be displayed only if an application display does not have space to display reason text.

Note: The Lane\_Centering\_Assist\_Canceled\_MC\_Warn\_Status\_Flag shall have higher priority over any and all ALC cancelation messages.

Blue\_Cruise\_ECE\_Cfg – Determines if certain notifications need to be displayed on the cluster per ECE regulations. Required to be enabled on ECE regions.

Above State Matrix for Assisted Lane Change Information is based on F-REQ-438184/B-State Matrix for Assisted Lane Change Information in < Highway Assist with Lane Centering Control Function and Warnings - FNV2.docm>. The purple content is added for NBP.

# 1.3.3.5.12 State Matrix for Navigation Based Pilot Information

Navigation Based Pilot Information will only be shown when the feature is active.

Operational_Mode	Feature Config	NbpAvail_D_Stat Signal	Blue_Cruise_ECE_Cfg	TjaLc_D_Stat Signal	TjaLcWarn_D_Rq Signal	NbpLcMsgTxt_D_Rq		NBP_Information_Display (Example Graphics)	Chime Status Flag
	$\xi = 0x1$ (Enabled) Cfg = X (Don' t Care)			0x1 (Standby)				((under speed threshold or no lanes detected) chevrons have less contrast and line thickness)	None
Nor mal or	OR Hwy_Assist_Cfg Auto_Lane_Change_	0x2 (AvailableL nChngSugg stnOnly) Or 0x3 (Available		0x2 (AvailableLef t)	X	X (Don't	Activ	(Grey chevron on the left only)	None
Cran k	$\label{eq:transfer} Traffic\_Jam\_Assist\_Cfg = 0x1 \text{ (Enabled) OR Hwy\_Assist\_Cfg} = 0x1 \text{ (Enabled)} \\ AND \text{ Nav\_Pilot\_Cfg} = X \text{ (Don' t Care) AND Auto\_Lane\_Change\_Cfg} = X \text{ (Don' t Care)} \\$	DrvLnChng ) Or 0x4 (Avaialble VehLnChn g)	X (Don't Care)	0x3 (AvailableRi ght)	(Don't Care)	Care)	e	(Gray chevron on the right only)	None
	Traffic_Jam_≯ AND Nav_Pilot_Cf			0x4 (AvailableLef tRight)				(Grey Chevron on both sides, example graphic of HA in limited mode)	None

			_		_		
		0x5 (PreparingLef t)				(Blue Chevron on the Left, none Right, example graphic of HA in extended mode)	None
		0x6 (PreparingRi ght)				Preparing Lane Change  READY  (Blue Chevron on the Right, none Left)	None
		0x7 (LcActiveLef t)				(part of animation Indicating a lane change to the left, final static image is displayed as long as signal is active)	None
		0x8 (LcActiveRig ht)				part of animation Indicating a lane change to the right, final static image is displayed as long as signal is active)	None
	0x1 (Enabled)	X	0x1 (DriverCancel)	X (Don't Care)	Activ	Canceled by Driver* (GML ID: A13)	_Priority_ atus_Flag
	X (Don't Care)	(Don't Care)	0x2 (SystemCancel)		e	Not Available (GML ID: A21)	TJA_Low_Priority_ Chime_Status_Flag

					0x3 (CancelNoLane)  0x4 (CancelLaneBusy)			Not Available No Lane Seen* (GML ID: A15)  Not Available Lane Busy* (GML ID: A14)	
					(CancelSpeedTooLow			Not Available Low Speed* (GML ID: A16)	
	t Care) X				·	0x1 (LnChngSu ggstonLeft FasterLn)		Lane Change Suggested For Faster Lane	None
	_Assist_Cfg = X (Don' ito_Lane_Change_Cfg =	0x2 (AvailableL nChngSugg stnOnly)				0x2 (LnChngSu ggstonRigh tFasterLn)		Lane Change Suggested For Faster Lane	None
Nor mal or Cran k	Hwy_Assist_Cfg = 0x1 ( Enabled) OR Traffic_Jam_Assist_Cfg = X (Don't Care) AND Nav_Pilot_Cfg = 0x1 ( Enabled) AND Auto_Lane_Change_Cfg = X	Or 0x3 (Available DrvLnChng ) Or 0x4 (Avaialble	X (Don't Care)	X (Don't Care)	X (Don't Care)	0x5 (TurnOffIn dicator)	Activ e	Turn Signal Is Stil Active  (Text: Turn Signal is Still Active)	None
	vy_Assist_Cfg = 0x1 ( AND Nav_Pilot_Cfg	VehLnChn g)				0x6 (LnChngSu ggstonLeft Nav)		Lane Change Suggested Following Navigation	None
	Hv					0x7 (LnChngSu ggstonRigh tNav)		Lane Change Suggested Following Navigation	None

			0x8 (HandOver)		Handover	None
			0x9 (MissingEx itAlert)		Missing Exit Alert Change to Orange text	TJA_Low_Priority
			0xA (LnChngSu ggstnLeftM anual)		To do added	None
			0xB (LnChngSu ggstnRight Manual)		To be added	None
	All	Other Cases		Inacti ve	(No indication)	None

The ADAS controller will arbitrate and populate the 3 input signals above, cluster simply displays information based on signal states received.

Note \*: The generic "Cancelation (GML ID: A1)" notification shall be displayed only if application display does not have space to display reason text.

For Assisted Lane Change, "Not Available" (GML ID: A21) notification shall be displayed only if an application display does not have space to display reason text.

Note: The Lane\_Centering\_Assist\_Canceled\_MC\_Warn\_Status\_Flag shall have higher priority over any and all ALC cancelation messages.

Blue\_Cruise\_ECE\_Cfg – Determines if certain notifications need to be displayed on the cluster per ECE regulations. Required to be enabled on ECE regions.

# 1.3.3.5.13 State Matrix Update for Highway Assist Information Warnings with NBP

Operational_Mode	Feature Config	Driver Assist On- Demand Screen	TjaWarn_D_Rq Signal	TjaMsgTxt_D_Dsply Signal	NbpAvail_D_Stat Signal	Lane_Centering_Assis t Canceled MC War	Driver_Resume_Cont	Lane_Warning_Right	Lane_Warning_Left_ MC_Worn_Stotuc_El	Eyes On Road Ambe	Eyes_On_Road_Red_	ote   o	Lane_Centering_Assis	Hwy_Assist_Unavaila	Hwy_Assist_On_	Assist	Hwy_Assist_Press_Ac	Navigation_Pilot_Un
		Not Dis play ed	TrafficJamAs	X (Don't Care)		Ac tiv e	In act ive	In act ive	In act ive	In act ive	In act ive	In act ive	In act ive	In act ive	In act ive	In act iv e	Ina cti ve	In act iv e
		Acti vely Dis play ed	sistCancel (0x1)			Ina cti ve	In act ive	In act ive	In act ive	In act ive	In act ive	In act ive	In act ive	In act ive	In act ive	In act iv e	Ina cti ve	In act iv e
	abled $(0x1)$ Cfg = X		HardTakeOv erLevel2 (0x3)	X (Don't Care)		Ina ctiv e	A cti ve	In act ive	In act ive	In act ive	In act ive	In act ive	In act ive	In act ive	In act ive	In act iv e	Ina cti ve	In act iv e
	$\label{eq:cfg} \begin{tabular}{ll} ffic\_Jam\_Assist\_Cfg = Enabled (0x1) OR Hwy\_Assist\_Cfg = Enabled (0x1) AND Nav\_Pilot\_Cfg = 0x1 (Enabled) AND Auto\_Lane\_Change\_Cfg = X AND Nav\_Pilot\_Cfg = 0x1 (Enabled) AND Auto\_Lane\_Change\_Cfg = X AND Nav\_Pilot\_Cfg = 0x1 (Enabled) AND Auto\_Lane\_Change\_Cfg = X AND Nav\_Pilot\_Cfg = 0x1 (Enabled) AND Auto\_Lane\_Change\_Cfg = X AND Nav\_Pilot\_Cfg = 0x1 (Enabled) AND Auto\_Lane\_Change\_Cfg = X AND Nav\_Pilot\_Cfg = 0x1 (Enabled) AND Auto\_Lane\_Change\_Cfg = X AND Nav\_Pilot\_Cfg = 0x1 (Enabled) AND Auto\_Lane\_Change\_Cfg = X AND Nav\_Pilot\_Cfg = 0x1 (Enabled) AND Auto\_Lane\_Change\_Cfg = X AND Nav\_Pilot\_Cfg = 0x1 (Enabled) AND Auto\_Lane\_Change\_Cfg = X AND Nav\_Pilot\_Cfg = 0x1 (Enabled) AND Auto\_Lane\_Change\_Cfg = X AND Nav\_Pilot\_Cfg = 0x1 (Enabled) AND Auto\_Lane\_Change\_Cfg = X AND Nav\_Pilot\_Cfg = 0x1 (Enabled) AND Auto\_Lane\_Change\_Cfg = X AND Nav\_Pilot\_Cfg = 0x1 (Enabled) AND Auto\_Lane\_Change\_Cfg = X AND Nav\_Pilot\_Cfg = 0x1 (Enabled) AND Auto\_Lane\_Change\_Cfg = 0x1 (Enabled) AND Auto\_Cfg = 0x1 (Enabled) And Auto\_C$		HaLaneDept WarningRigh t (0x4)			Ina ctiv e	In act ive	A cti ve	In act ive	In act ive	In act ive	In act ive	In act ive	In act ive	In act ive	In act iv e	Ina cti ve	In act iv e
No rm	nR Hwy_Assi ND Auto_La		HaLaneDept WarningLeft (0x5)		X	Ina ctiv e	In act ive	In act ive	A cti ve	In act ive	In act ive	In act ive	In act ive	In act ive	In act ive	In act iv e	Ina cti ve	In act iv e
al or Cr an k	bled (0x1) O (Enabled) A	X	SoftTakeOve rEyesOff (0x6)		(Don' t Care)	Ina ctiv e	In act ive	In act ive	In act ive	A cti ve	In act ive	In act ive	In act ive	In act ive	In act ive	In act iv e	Ina cti ve	In act iv e
	$t_{\text{C}}$ Cfg = Ena $t_{\text{C}}$ Cfg = 0x1	(Do n't Car e)	HardTakeOv erEyesOff (0x7)			Ina ctiv e	In act ive	In act ive	In act ive	In act ive	A cti ve	In act ive	In act ive	In act ive	In act ive	In act iv e	Ina cti ve	In act iv e
	Traffic_Jam_Assist_Cfg AND Nav_Pilot_Cfg			TrafficJamAs sistUnavailabl e (0x1)		Ina ctiv e	In act ive	In act ive	In act ive	In act ive	In act ive	A cti ve	In act ive	In act ive	In act ive	In act iv e	Ina cti ve	In act iv e
	Traffi AN		NoWarning (0x0)	TrafficJamAs sistSelected (0x2)		Ina ctiv e	In act ive	In act ive	In act ive	In act ive	In act ive	In act ive	A cti ve	In act ive	In act ive	In act iv e	Ina cti ve	In act iv e
			(UXU)	HAUnavailab le (0x4)		Ina ctiv e	In act ive	In act ive	In act ive	In act ive	In act ive	In act ive	In act ive	A cti ve	In act ive	In act iv e	Ina cti ve	In act iv e
				HASelected (0x5)		Ina ctiv e	In act ive	In act ive	In act ive	In act ive	In act ive	In act ive	In act ive	In act ive	A cti ve	In act iv e	Ina cti ve	In act iv e

Operational_Mode	Feature Config	Driver Assist On- Demand Screen	TjaWarn_D_Rq Signal	TjaMsgTxt_D_Dsply Signal	NbpAvail_D_Stat Signal	Lane_Centering_Assis t_Canceled_MC_War	Driver_Resume_Cont	Lane_Warning_Right	Lane_Warning_Left_	On Ro	Eyes_On_Road_Red_	Lane_Centering_Una	Lane_Centering_Assis	Hwy_Assist_Unavaila	Hwy_Assist_On_	Hwy_Assist_Available	Hwy_Assist_Press_Ac	Navigation_Pilot_Un
				SmartOfferin g (0x6)		Ina ctiv e	In act ive	In act ive	In act ive	In act ive	In act ive	In act ive	In act ive	In act ive	In act ive	A cti ve	Ina cti ve	In act iv e
				Disclaimer (0x7)		Ina ctiv e	In act ive	In act ive	In act ive	In act ive	In act ive	In act ive	In act ive	In act ive	In act ive	In act iv e	Ac tiv e	In act iv e
				Declared Missing as per Section 1.4.1		Ina ctiv e	In act ive	In act ive	In act ive	In act ive	In act ive	In act ive	In act ive	In act ive	In act ive	In act iv e	Ina cti ve	In act iv e
			X (Don't Care)	X (Don't Care)	NbpF ailure (0x5)	Ina ctiv e	In act ive	In act ive	In act ive	In act ive	In act ive	In act ive	In act ive	In act ive	In act ive	In act iv e	Ina cti ve	A cti ve
			Declared Missing as per Section 1.4.1	X (Don't Care)	X (Don' t Care)	Ina ctiv e	In act ive	In act ive	In act ive	In act ive	In act ive	In act ive	In act ive	In act ive	In act ive	In act iv e	Ina cti ve	In act iv e
	All Other Cases					Ina ctiv e	In act ive	In act ive	In act ive	In act ive	In act ive	In act ive	In act ive	In act ive	In act ive	In act iv e	Ina cti ve	In act iv e

Above State Matrix for Assisted Lane Change Information is based on F-REQ-343100/D-State Matrix for Highway Assist Information Warnings in < Highway Assist with Lane Centering Control Function and Warnings - FNV2.docm>. The purple content is added for NBP.

# 1.3.3.5.14 MC Status Flag to MC Warning Message

MC Warn Status Flag	Reference Text or Graphic (see GML for exact wording)	MC Warning ID	Chime Status Flag
Navigation_Pilot_Unavailable_MC_Warn _Status_Flag			None
Lane_Change_Suggested_For_Faster_Lan e_Left_MC_Warn_Status_Flag	Lane Change Suggested For Faster Lane		None
Lane_Change_Suggested_For_Faster_Lan e_Right_MC_Warn_Status_Flag	Lane Change Suggested For Faster Lane		None
Lane_Change_Suggested_Following Navigation Left_MC_Warn_Status_Flag	Lane Change Suggested Following Navigation		None
Lane_Change_Suggested_Following Navigation Right_MC_Warn_Status_Flag	Lane Change Suggested Following Navigation		None
HandOver_MC_Warn_Status_Flag	Handover		None
Missing_Exit_Alert_MC_Warn_Status_Fl ag	Missing Exit Alert		TJA_Low_Priority_ Chime_Status_Flag
LnChngSuggstnLeftManual_MC_Warn_S tatus_Flag			None
LnChngSuggstnRightManual _MC_Warn_Status_Flag			None

# 1.3.5.2 Operation Description (supports algorithm flow chart)

NBP settings are at IVI instead of cluster.

# 1.3.5.3 Personalization Feature Number Definition

None

# **1.3.5.4** Function Safety Classification (EMC)

Class B

# **1.3.5.5** Memory Storage

# 1.3.5.5.1 Memory Storage Parameters

Parameter Name	Description	Value at Battery Connect	Value at Wake-up
Nav_Piolot_Cfg	Configures cluster to display items in the Settings menu (Set to "cluster" at cluster supplier manufacturer plant.	Use Stored Value	Use Stored Value
Auto_Lane_Change_Cfg	Configures cluster to display items in the Settings menu (Set to "cluster" at cluster supplier manufacturer plant.	Use Stored Value	Use Stored Value
FeatConfigIpmbActl signal	Input signal sent from IPMB to indicate current value of the feature setting for the feature that is being set or queried.	(0x0000)	Do Not Init
FeatNoIpmbActl	Input signal sent from IPMB to indicate Feature Number.	(0x0000)	Do Not Init
PersIndexIpmb_D_Actl	Input signal from IPMB to indicate which personality profile is being reported.	Vehicle (0x4)	Do Not Init
Nbp_D_Stat	Input signal from IPMB to display current status of NBP system.	0x0	0x0
NbpMsgTxt_D_Rq	Input signal from IPMB to display lane change assist notifications to the user.	0x0	0x0
NBP_Information_Display	Output signal to displays the Navigation Based Pilot information in the ADAS metaphor.	Inactive	Inactive
Navigation_Pilot_Unavailable_MC_Wa rn_Status_Flag	Output signal to control the state of the text warning message.	Inactive	Inactive
Lane_Change_Suggested_For_Faster_L ane_Left_MC_Warn_Status_Flag	Output signal to control the state of the text warning message.	Inactive	Inactive
Lane_Change_Suggested_For_Faster_L ane_Right_MC_Warn_Status_Flag	Output signal to control the state of the text warning message.	Inactive	Inactive
Lane_Change_Suggested_Following Navigation Left_MC_Warn_Status_Flag	Output signal to control the state of the text warning message.	Inactive	Inactive
Lane_Change_Suggested_Following Navigation Right_MC_Warn_Status_Flag	Output signal to control the state of the text warning message.	Inactive	Inactive

Parameter Name	Description	Value at Battery Connect	Value at Wake-up
HandOver_MC_Warn_Status_Flag	Output signal to control the state of the text warning message.	Inactive	Inactive
Missing_Exit_Alert_MC_Warn_Status_Flag	Output signal to control the state of the text warning message.	Inactive	Inactive
LnChngSuggstnRightManua_Status_Fla	Output signal to control the state of the text warning message.	Inactive	Inactive
LnChngSuggstnRightManual_Status_Fl ag	Output signal to control the state of the text warning message.	Inactive	Inactive
NAVIGATION_PILOT_SETUP_MC	Output signal to control the setting menu display output for Navigation Based Pilot	Inactive	Inactive
NAV_PILOT_AUDIO_SETUP_MC	Output signal to control the setting menu display output for Navigation Based Pilot audio selection.	Inactive	Use Stored Value?
AUTO_LANE_CHANGE_SETUP_MC	Output signal to control the setting menu display output for Auto Lane Change.	Inactive	Inactive

# **1.3.5.6** Reconfigurable Telltale

None

## **1.3.5.6** Prove Out

None

# 1.3.5.7 Message Center Msg

Refer to 1.3.3.5.14 MC Status Flag to MC Warning Message.

# 1.4 Error Handling

#### 1.4.1 Missing Message Strategy

Missing message DTC (TBD) shall be logged if signals NbpAvail\_D\_Stat or NbpMsgTxt\_D\_Rq is not received for continuous 5s.

If Nav\_Pilot\_Cfg = Disabled (0x0), the cluster shall never log a missing message DTC for NbpAvail\_D\_Stat and NbpMsgTxt\_D\_Rq signals for this feature.

## 1.5 Diagnostics

#### 1.5.1 Self -Test

None

#### 1.5.2 Engineering Test Mode

Reference section "Dealer / Engineering Test Mode (ETM)"

#### 1.5.3 Part II Performance

#### 1.5.3.1 DID DExx

Block Num	Block Description	Byte(s)	Bits	State: Description	"0"	"1"	Default	Comments/ Information		
PACKET	ED BLOCKS	-								
\$01	Option Content (B&A)	*	1	Navigation Based Pilot	Disabled	Enabled	Disabled	This parameter allows the NBP related menu items and all information pertaining to the feature to be displayed in the vehicle.  Disabled means NBP feature is not present in the vehicle.		
\$02	Option Content (B&A)	*	1	Auto Lane Change	Disabled	Enabled	Disabled	This parameter allows the Auto Lane Change settings menu and all pertaining information to be displayed in the cluster, as well as information. Disabled means Auto Lane Change (that is submenu of NBP) is not present in the vehicle.		
	*Byte and bit location to be identified in Part II Specification for this cluster									

# 1.5.3.2 Supported Diagnostic Trouble Codes (DTCs)

DTC	Description
C23B	Lost Communication with IPMB (Image Processing Module "B")

#### 1.6 Reference Specification

< Highway Assist with Lane Centering Control Function and Warnings - FNV2.docm>

# 1.7 Revision History

Version	Name	Change Description	Date
1.0	Zhang Wayne Zheng Dong	Initial release	October 31/2022
1.1	Zheng Dong	According < Highway Assist with Lane Centering Control Function and Warnings - FNV2_v3.4_[VDOC075263_N]>, renaming assisted lane change "cancelation" notifications from "Canceled" to "Not Available". And add Blue_Cruise_ECE_Cfg condition in the chapter of State Matrix Update for Assisted Lane Change Information with NBP and State Matrix for Navigation Based Pilot Information. And add Blue_Cruise_ECE_Cfg condition in Diagnostic Configuration Flowchart.  Update DTC ID in 1.5.3.2 chapter  Update Highway Assist with Navigation Pilot input request Flowchart	November 15/2022
		Update Feature Config in State Matrix for Navigation Based Pilot Information	
1.2	Zheng Dong	Add output signals of MsgCntrDsplyOp_D_Rq, MsgCntrFeatNoRq, MsgCntrFeatConfigRq, MsgCntrPersIndex_D_Rq in I/O Block Diagram and description in outputs. Add Hwy_Assist_Cfg and Traffic_Jam_Assist_Cfg in I/O Block Diagram. Update for Menu display logic description. Remove function ID such as F-REQ-XXXXXX/A. Update Input Request Flowchart and Output SET Request Flowchart. Delete the chapter of 1.3.5.5.2 Time Constants.	