Navigation Based Pilot

Subsystem Technology Specific Specification (STSS)

Version 1.4
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Terms and Definitions

| Abbreviation | Description |
|--------------|------------------------|
| NBP | Navigation Based Pilot |
| ALC | Assisted Lane Change |
| TJA | Traffic Jam Assist |

1. Navigation Based Pilot

1.1 Functional Description

This STSS handles the functions associated with the Navigation Based Pilot feature, hereafter called NBP feature or NBP.

When a user is driving a vehicle with ALC, the user will be indicated by a lane change suggestion if it's determined to be helpful. Following a turn signal initiated by driver, the vehicle will perform a lane change.

Based on ALC, NBP will add the ability for vehicle to provide lane change suggestions according Navigation indication.

Currently, NBP scenarios are below:

- Highway Exit
- Y-shaped Road
- Lane End

It would support expanded scenarios in the future. Hence, the NBP indication signal is protected with 6-bit size.

Depending on the vehicle location relative to lane position and the distance to target road section and objects, this feature will:

- Signal to driver for a lane change suggestion
- Signal to driver for taking over steering control
- Signal to driver for a coming auto lane change maneuver if VLC (Vehicle-initiated Lane Change) is active

Starting with MY2024 CX771/CX821, Navigation Based Pilot (NBP) has been introduced to the suite of Highway Assist feature with the support of new introduced IPMB_EPC module. NBP enriches the capability providing lane change suggestion against additional scenarios (means Highway Exit) compared with that supported by ALC.

Navigation Based Pilot correlates the personalization signals from the IPMB, several signals from IPMB EPC and the Operation Mode to determine when to activate additional appropriate displays.

1.2 Interfaces

1.2.1 Interface Context Diagram (I/O Block Diagram)

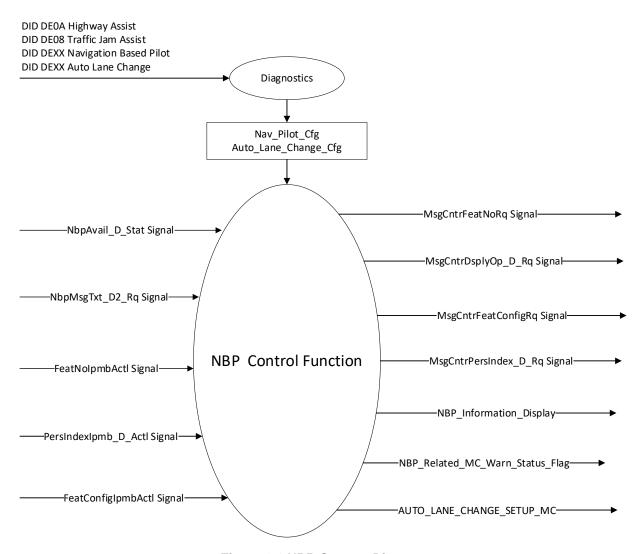


Figure 2.1 NBP Context Diagram

1.2.2 Inputs

1.2.2.1 Internal

- Hwy_Assist_Cfg Feature Cfg
- Traffic_Jam_Assist_Cfg Feature Cfg
- Nav_Piolot_Cfg
- Auto_Lane_Change_Cfg

1.2.2.2 MUX signals on the CAN Bus from IPMB (2nd ECU)

1.2.2.2.1 FeatConfigIpmbActl Signal

| Signal Name | Size (bits) | Detail | Units | Res. | Offset | State Encoded | Min | Max |
|--------------------|----------------|--------|-----------|------|--------|------------------|------------|-------------------|
| FeatConfigIpmbActl | 16 | - | Undefined | 1 | 0 | | 0 (0x0) | 65535 (0xFFFF) |

1.2.2.2.2 FeatNolpmbActl Signal

| Signal Name | Size (bits) | Detail | Units | Res. | Offset | State Encoded | Min | Max |
|----------------|----------------|--------|--------|------|--------|------------------|------------|-------------------|
| FeatNoIpmbActl | 16 | - | Number | 1 | 0 | | 0 (0x0) | 65535 (0xFFFF) |

1.2.2.2.3 PersIndexIpmb_D_Actl Signal

| TEELEG T CONTROCKIPHIS_D_ACT ORGINA | | | | | | | | |
|-------------------------------------|----------------|---------|-------|------|--------|------------------|--------|---------|
| Signal Name | Size (bits) | Detail | Units | Res. | Offset | State Encoded | Min | Max |
| PersIndexIpmb_D_Actl | 3 | | SED | 1 | 0 | | 0(0x0) | 7 (0x7) |
| | | PERS_1 | | | | 0x0 | | |
| | | PERS_2 | | | | 0x1 | | |
| | | PERS_3 | | | | 0x2 | | |
| | | PERS_4 | | | | 0x3 | | |
| | | Vehicle | | | | 0x4 | | |
| | | NotUsed | | | | 0x5 | | |
| | | NotUsed | | | | 0x6 | | |
| | | NotUsed | | | | 0x7 | | |

1.2.2.2.4 NbpAvail_D_Stat Signal

| Signal Name | Size (bits) | Detail | Units | Res. | Offset | State Encoded | Min | Max |
|---------------------|----------------|----------------------------|-------|------|--------|------------------|------------|------------|
| NbpAvail _D_Stat | 3 | | SED | 1 | 0 | | 0 (0x0) | 7 (0x7) |
| _D_Stat | | Off | | | | 0x0 | (070) | (0X1) |
| | | Standby | | | | 0x1 | | |
| | | AvailableLnChngSuggstnOnly | | | | 0x2 | | |
| | | AvailableDrvLnChng | | | | 0x3 | | |
| | | AvailableVehLnChng | | | | 0x4 | | |
| | | NbpFailure | | | | 0x5 | | |
| | | NotUsed | | | | 0x6 | | |
| | • | NotUsed | | | | 0x7 | | |

1.2.2.2.5 SIG-REQ-XXXXXX/A- NbpMsgTxt D2 Rq Signal

| Signal Name | Size (bits) | Detail | Uni ts | Res. | Offset | State Encoded | Min | Max |
|----------------|-------------|----------------------------|-----------|------|--------|------------------|-------|--------|
| NbpMsgTx | 6 | | SE | 1 | 0 | | 0 | 63 |
| t_D2_Rq | 6 | | D | 1 | 0 | | (0x0) | (0x3F) |
| | | NoMessage | | | | 0x00 | | |
| | | HandOver | | | | 0x01 | | |
| | | MissingExitAlert | | | | 0x02 | | |
| | | AlcOn | | | | 0x03 | | |
| | | AlcOff | | | | 0x04 | | |
| | | TurnOffIndicator | | | | 0x05 | | |
| | | SuggstnLeftExitManual | | | | 0x06 | | |
| | | SuggstnRightExitManual | | | | 0x07 | | |
| | | SuggstnLeftLnEndManual | | | | 0x08 | | |
| | | SuggstnRightLnEndManual | | | | 0x09 | | |
| | | SuggstnLeftYShapeManual | | | | 0x0A | | |
| | | SuggstnRightYShapeManual | | | | 0x0B | | |
| | | SuggstnLeftSlowVeh | | | | 0x0C | | |
| | | SuggstnRightSlowVeh | | | | 0x0D | | |
| | | SuggstnLeftExit | | | | 0x0E | | |
| | | SuggstnRightExit | | | | 0x0F | | |
| | | SuggstnLeftMergeIn | | | | 0x10 | | |
| | | SuggstnRightMergeIn | | | | 0x11 | | |
| | | SuggstnLeftUnintndExit | | | | 0x12 | | |
| | | SuggstnRightUnintndExit | | | | 0x13 | | |
| | | SuggstnLeftLnEnd | | | | 0x14 | | |
| | | SuggstnRightLnEnd | | | | 0x15 | | |
| | | SuggstnLeftYShape | | | | 0x16 | | |
| | | SuggstnRightYShape | | | | 0x17 | | |
| | | AutoLnChngLeftSlowVeh | | | | 0x18 | | |
| | | AutoLnChngRightSlowVeh | | | | 0x19 | | |
| | | AutoLnChngLeftOptmzedLn | | | | 0x1A | | |
| | | AutoLnChngRightOptmzedLn | | | | 0x1B | | |
| | | AutoLnChngLeftExit | | | | 0x1C | | |
| | | AutoLnChngRightExit | | | | 0x1D | | |
| | | AutoLnChngLeftMergeIn | | | | 0x1E | | |
| | | AutoLnChngRightMergeIn | | | | 0x1F | | |
| | | AutoLnChngLeftUnintndExit | | | | 0x20 | | |
| | | AutoLnChngRightUnintndExit | | | | 0x20 | | |
| | | AutoLnChngLeftLnEnd | | | | 0x21 | | |
| | | AutoLnChngRightLnEnd | | | | 0x23 | | |
| | | AutoLnChngLeftYShape | | | | 0x23 | | |
| | | AutoLnChngRightYShape | | | | 0x25 | | |
| | | NotUsed Notused | | | | 0x26~0x3F | | |

1.2.3 Outputs

1.2.3.1 Internal

- NBP_Information_Display displays the Navigation Based Pilot information in the ADAS metaphor.
- AUTO_LANE_CHANGE_SETUP_MC, controls the setting menu display output for Auto Lane Change.
- NBP_Related_MC_Warn_Status_Flag, which is used to control the state of the text warning message including those MC_Warn_Status_Flag below:
 - 1) Navigation_Pilot_Unavailable_MC_Warn_Status_Flag
 - 2) HandOver_MC_Warn_Status_Flag
 - 3) MissingExitAlert_MC_Warn_Status_Flag
 - 4) SuggstnLeftExitManual_MC_Warn_Status_Flag
 - 5) SuggstnRightExitManual_MC_Warn_Status_Flag
 - 6) SuggstnLeftLnEndManual_MC_Warn_Status_Flag
 - 7) SuggstnRightLnEndManual_MC Warn Status Flag
 - 8) SuggstnLeftYShapeManual_MC_Warn_Status_Flag
 - 9) SuggstnRightYShapeManual_MC_Warn_Status_Flag
 - 10) SuggstnLeftSlowVeh_MC_Warn_Status_Flag
 - 11) SuggstnRightSlowVeh_MC_Warn_Status_Flag
 - 12) SuggstnLeftExit_MC_Warn_Status_Flag
 - 13) SuggstnRightExit_MC_Warn_Status_Flag
 - 14) SuggstnLeftMergeIn_MC_Warn_Status_Flag
 - 15) SuggstnRightMergeIn_MC_Warn_Status_Flag
 - 16) SuggstnLeftUnintndExit_MC_Warn_Status_Flag
 - 17) SuggstnRightUnintndExit MC Warn Status Flag
 - 18) SuggstnLeftLnEnd_MC_Warn_Status_Flag
 - 19) SuggstnRightLnEnd_MC_Warn_Status_Flag
 - 20) SuggstnLeftYShape_MC_Warn_Status_Flag
 - 21) SuggstnRightYShape_MC_Warn_Status_Flag
 - 22) AutoLnChngLeftSlowVeh_MC_Warn_Status_Flag
 - 23) AutoLnChngRightSlowVeh_MC_Warn_Status_Flag
 - 24) AutoLnChngLeftOptmzedLn_MC_Warn_Status_Flag
 - 25) AutoLnChngRightOptmzedLn MC Warn Status Flag
 - 26) AutoLnChngLeftExit_MC_Warn_Status_Flag
 - 27) AutoLnChngRightExit_MC_Warn_Status_Flag
 - 28) AutoLnChngLeftMergeIn_MC_Warn_Status_Flag
 - 29) AutoLnChngRightMergeIn_MC_Warn_Status_Flag
 - 30) AutoLnChngLeftUnintndExit MC Warn Status Flag
 - 31) AutoLnChngRightUnintndExit MC Warn Status Flag
 - 32) AutoLnChngLeftLnEnd_MC_Warn_Status_Flag
 - 33) AutoLnChngRightLnEnd_MC_Warn_Status_Flag
 - 34) AutoLnChngLeftYShape_MC_Warn_Status_Flag
 - 35) AutoLnChngRightYShape_MC_Warn_Status_Flag

1.2.3.2 MUX signals on the CAN Bus to IPMB (2nd ECU)

1.2.3.2.1 MsgCntrFeatNoRq Signal

| Signal Name | Size (bits) | Detail | Units | Res. | Offset | State Encoded | Min | Max |
|-----------------|----------------|--------|--------|------|--------|------------------|------------|-------------------|
| MsgCntrFeatNoRq | 16 | - | Number | 1 | 0 | | 0 (0x0) | 65535 (0xFFFF) |

1.2.3.2.2 MsgCntrDsplyOp_D_Rq Signal

| Signal Name | Size (bits) | Detail | Units | Res. | Offset | State Encoded | Min | Max |
|---------------------|----------------|---------|-------|------|--------|------------------|------------|------------|
| MsgCntrDsplyOp_D_Rq | 3 | | SED | 1 | 0 | | 0 (0x0) | 7 (0x7) |
| | | NULL | | | | 0x0 | | - |
| | | QUERY | | | | 0x1 | | |
| | | SET | | | | 0x2 | | |
| | | UPLOAD | | | | 0x3 | | |
| | | RESTORE | | | | 0x4 | | |
| | | COPY | | | | 0x5 | | |
| | | Unused | | | | 0x6 | | |
| | | Unused | | | | 0x7 | | |

1.2.3.2.3 MsgCntrFeatConfigRq Signal

| Signal Name | Size (bits) | Detail | Units | Res. | Offset | State Encoded | Min | Max |
|---------------------|----------------|--------|-----------|------|--------|------------------|------------|-------------------|
| MsgCntrFeatConfigRq | 16 | - | Undefined | 1 | 0 | | 0 (0x0) | 65535 (0xFFFF) |

1.2.3.2.4 MsgCntrPersIndex D Rq Signal

| Signal Name | Size (bits) | Detail | Units | Res. | Offset | State Encoded | Min | Max |
|-----------------------|-------------|---------|-------|------|--------|------------------|------------|------------|
| MsgCntrPersIndex_D_Rq | 3 | | SED | 1 | 0 | | 0 (0x0) | 7 (0x7) |
| | | PERS_1 | | | | 0x0 | | |
| | | PERS_2 | | | | 0x1 | | |
| | | PERS_3 | | | | 0x2 | | |
| | | PERS_4 | | | | 0x3 | | |
| | | Vehicle | | | | 0x4 | | |
| | | Unused | | | | 0x5 | | |
| | | Unused | | | | 0x6 | | |
| | | Unused | | | | 0x7 | | |

1.3 Function/Performance

1.3.1 Operational Modes

| Mode Differentiating Vehicle Conditions | | | | | | |
|---|--|--|--|--|--|--|
| Sleep Mode | NBP Control Function Text Message Disabled | | | | | |
| Limited Mode | NBP Control Function Text Message Disabled | | | | | |
| Normal Mode | NBP Control Function Text Message Enabled / Disabled | | | | | |
| Crank Mode | NBP Control Function Text Message Enabled / Disabled | | | | | |

1.3.2 Voltage Levels

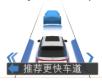
Refer to the Cluster Features table located in the Operational Modes and Voltage Range Strategies.

1.3.3 Human-Machine Interface

1.3.3.1 Visual

1.3.3.1.1 Indicator Graphics / Display Format

Example Graphic (final graphics to be provided by HMI wallpaper)



Message Center Text Warning Message as defined in section 1.3.3.5.12 of this document. Actual wording may vary based on Program Translation table.

Please refer to the program specific menu structure for exact graphics.

Example Menu Structure:

| Menu level 0 | Menu level 1 | Menu level 2 | Comments |
|---------------|----------------|--|---|
| Driver Assist | Cruise Control | With Lane Centering | Traffic_Jam_Assist_Cfg = 0x1 (Enabled) Hwy_Assist_Cfg = 0x0 (Disabled) Nav_Pilot_Cfg = X (Don't Care) Auto_Lane_Change_Cfg = X (Don't Care) |
| | | With Lane Centering (Blue Cruise) With Smart Offerings Lane Biasing Assist Lane Change | Hwy_Assist_Cfg = 0x1 (Enabled) Traffic_Jam_Assist_Cfg = X (Don't Care) Nav_Pilot_Cfg = X (Don't Care) Auto_Lane_Change_Cfg = 0x0 (Disabled) |
| | | With Lane Centering (Blue Cruise) With Smart Offerings Lane Biasing Assist Lane Change • Auto Lane Change | Hwy_Assist_Cfg = 0x1 (Enabled) Traffic_Jam_Assist_Cfg = X (Don't Care) Nav_Pilot_Cfg = X (Don't Care) Auto_Lane_Change_Cfg = 0x1 (Enabled) |

Nav_Pilot_Cfg affect Chinese name about With Lane Centering for distinguish different vehicles with different configurations like below.

| Menu level 0 | Menu level 1 | Menu level 2 | Comments |
|--------------|--------------|--------------|----------|

| Driver Assist | Cruise Control | With Lane Centering (Chinese name: ActiveGlide 智能辅助驾驶) With Smart Offerings Lane Biasing Assist Lane Change | Hwy_Assist_Cfg = 0x1 (Enabled) Traffic_Jam_Assist_Cfg = X (Don't Care) Nav_Pilot_Cfg = 0x0 (Disabled) Auto_Lane_Change_Cfg = X (Don't Care) |
|---------------|----------------|---|---|
| | | With Lane Centering (Chinese name: ActiveGlide 领航辅助驾驶) With Smart Offerings Lane Biasing Assist Lane Change | Hwy_Assist_Cfg = 0x1 (Enabled) Traffic_Jam_Assist_Cfg = X (Don't Care) Nav_Pilot_Cfg = 0x1 (Enabled) Auto_Lane_Change_Cfg = X (Don't Care) |

Menu display logic in above list:

1. About the menu of Lane Biasing and Assist Lane Change (Pre-condition: Hwy_Assist_Cfg = 0x1 (Enabled))

Menu display of Lane Biasing and Assisted Lane Change depends on the customer selection of Blue Cruise (Ford Brand)/Active Glide (Lincoln Brand) feature. There are two presentations. The final use of which will refer to HMI design. One case is that LB and ALC shall appear when Blue Cruise is selected on, while disappear when Blue Cruise is selected off. The other case is that LB and ALC show active and can be checked or unchecked when Blue Cruise is selected on, while LB and ALC show gray and cannot be checked or unchecked when Blue Cruise is selected off.

2. About the menu of Auto Lane Change (Pre-condition: Hwy_Assist_Cfg = 0x1 (Enabled) and Auto_Lane_Change_Cfg = 0x1(Enabled))

Menu display of Auto Lane Change depends on the customer selection of ALC feature. Auto Lane Change shall appear when ALC is selected on, while disappear when ALC is selected off.

3. IVI/SYNC+ should query Auto Lane Change menu every time after bootup and get response and display last remembered settings (follow HA menu strategy). Last remembered settings are saved on IPMB.

1.3.3.1.2 Indicator Color Coordinates

Refer to program specific HMI requirements for styling direction.

1.3.3.1.3 Indicator Characteristics

As per program specific HMI theme.

1.3.3.2 Switch Control Logic

Consumer access to NBP Module Configuration shall be as specified in the message center basic functionality display as specified in Message Center X Display_Y Button Interface Section, where X and Y are appropriate values in this document.

1.3.4 System Accuracy

Within 100 msec of receiving a message that results in a change of state the cluster will update the display to the proper state.

1.3.5 Operation: Performance and Functional

1.3.5.1 Subsystem Algorithm Flowchart / State Diagram

1.3.5.1.1 Highway Assist with Navigation Pilot Diagnostic Configuration Flowchart

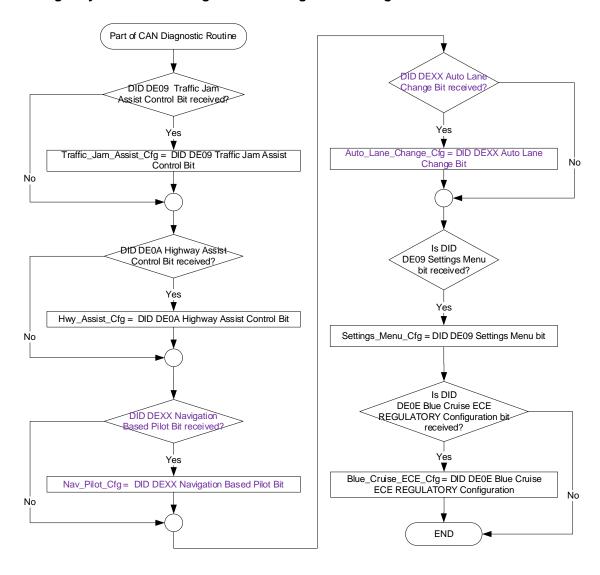


Figure 3.1 Diagnostic Configuration Flowchart

Figure 3.1 is based on F-REQ-343087/A-Highway Assist and Lane Centering Diagnostic Configuration Flowchart in < Highway Assist with Lane Centering Control Function and Warnings – FNV2.docm>. The purple content is added for NBP.

1.3.5.1.2 Highway Assist and Lane Centering and Auto Lane Change Menu Display Determination Matrix

| Hwy_Assist_Cf | Traffic_Jam_Assist_ Cfg | Auto_Lane_Change_Cfg | "With Lane Centering " Displayed in menu? | "With Smart Offering " Displaye d in menu? | "With Auto Lane Change" Displaye d in menu? |
|----------------|----------------------------|----------------------|--|--|---|
| Enabled (0x1) | Enabled (0x1) | Enabled (0x1) | Yes | Yes | Yes |
| Enabled (0x1) | Enabled (0x1) | Disabled (0x0) | Yes | Yes | No |
| Enabled (x1) | Disabled (0x0) | Enabled (0x1) | Yes | Yes | Yes |
| Enabled (0x1) | Disabled (0x0) | Disabled (0x0) | Yes | Yes | No |
| Disabled (0x0) | Enabled (0x1) | Enabled (0x1) | Yes | No | No |
| Disabled (0x0) | Enabled (0x1) | Disabled (0x0) | Yes | No | No |
| Disabled (0x0) | Disabled (0x0) | Enabled (0x1) | No | No | No |
| Disabled (0x0) | Disabled (0x0) | Disabled (0x0) | No | No | No |

1.3.5.1.3 Highway Assist with Navigation Pilot input request Flowchart

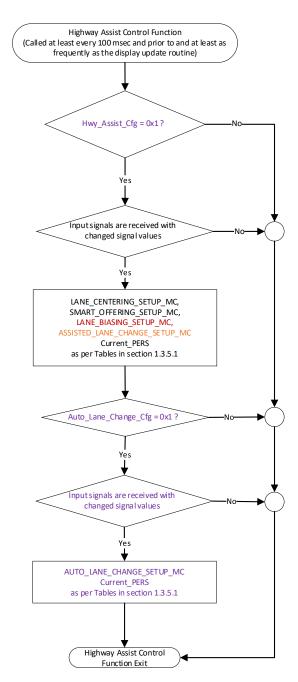


Figure 3.2 Input Request Flowchart

Figure 3.2 is based on F-REQ-343089/D-Highway Assist and Lane Centering input request Flowcharts in < Highway Assist with Lane Centering Control Function and Warnings – FNV2.docm>. The purple content is added or modified for NBP.

Input signals are received in a message from IPMB (2nd ECU), including FeatNoIpmbActl Signal, FeatConfigIpmbActl Signal, PersIndexIpmb_D_Actl Signal that is described in IO inputs.

1.3.5.1.4 Highway Assist with Navigation Pilot output SET request Flowchart

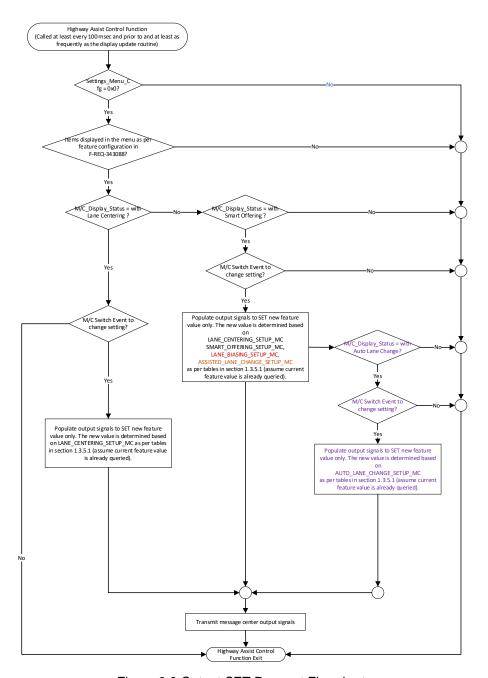


Figure 3.3 Output SET Request Flowchart

Figure 3.3 is based on F-REQ-343090/D-Highway Assist and Lane Centering Output SET request Flowchart in < Highway Assist with Lane Centering Control Function and Warnings – FNV2.docm>. The purple content is added for NBP.

Output signals are sent in a message to IPMB (2^{nd} ECU), including MsgCntrDsplyOp_D_Rq Signal, MsgCntrFeatNoRq Signal, MsgCntrFeatConfigRq Signal and MsgCntrPersIndex_D_Rq Signal that is described in Setup Request Messages.

1.3.5.1.5 Auto Lane Change Setup State Assignment

| FeatNoIpmbActl Signal | FeatConfigIpmbActl Signal | PersIndexIpmb_D_Actl Signal | NAVIGATION_PILOT_ SETUP_MC | Current_PERS (3) | |
|--------------------------|------------------------------|-----------------------------|-------------------------------|------------------|--|
| | 0x0000 (Off) $0x0 - 0x4$ | | 0x00 | 0x0 - 0x4 | |
| 0x0882 (1) | 0x0001 (On) | 0x0 - 0x4 | 0x01 | 0x0 - 0x4 | |
| | Oti | her ⁽²⁾ | Error | I V | |
| | Missing per Section 1.4. | 1 (2) | (0x2) | Last Known | |

1.3.5.1.6 Auto Lane Change Setup Request Messages based upon AUTO_LANE_CHANGE_SETUP_MC

| ASSISTED_ LANE_CHANGE_ SETUP_MC | Display Menu | M/C Switch Selection Event | MsgCntrDsplyOp_ D_Rq Signal | MsgCntrFeatNoRq Signal | MsgCntrFeatConfig Rq Signal | MsgCntrPersIndex_ D_Rq Signal |
|---------------------------------------|-----------------|-------------------------------|--------------------------------|---------------------------|--------------------------------|----------------------------------|
| 0x00 or 0x02 | (Off) | Up/Down + OK (Select On) | SET (0x2) | 0x0882 | 0x0001 (If On is selected) | Current_PERS |
| 0x01 | (On) | Up/Down + OK (Select Off) | SET (0x2) | 0x0882 | 0x0000 (If Off is selected) | Current_PERS |

1.3.5.1.7 State Matrix Update for Assisted Lane Change Information with NBP

Assisted Lane Change Information will be shown whenever Navigation Based Pilot is not available (either because Navigation Based Pilot is configured off or even if equipped but not activated due to driver deselection or without Navigation route).

| Operational_Mode | Feature Config | NbpAvail_D_Stat Signal | Blue_Cruise_ECE_ Cfg | TjaLc_D_Stat Signal | TjaLcWarn_D_Rq Signal | TjaLcMsgTxt_D_Rq | | ALC_Information_ Display (Example Graphics) | Chime Status Flag |
|-------------------|---|---|-------------------------|---------------------------------|--------------------------|----------------------|--------|---|-------------------|
| | | 0x0 (Off) Or 0x1 (Stan dby) Or 0x5 (Nbp Failur | | 0x1 (Standby) | X (Don't Care) | X (Don't Care) | | ((under speed threshold or no lanes detected) chevrons have less contrast and line thickness) | None |
| Nor mal or Cran k | led) (Don' t Care) | | X (Don't Care) | 0x2 (AvailableLeft) | | | Active | (Grey chevron on the left only) | None |
| | sist_Cfg = 0x1 (Enabl ane_Change_Cfg = X | | | 0x3 (AvailableRight) | | | | (Gray chevron on the right only) | None |
| | $\label{eq:continuity} Traffic_Jam_Assist_Cfg = 0x1 \ (Enabled) \\ AND \ Nav_Pilot_Cfg = X \ (Don' \ t Care) \ AND \ Auto_Lane_Change_Cfg = X \ (Don' \ t Care) \\$ | e) Or Missi ng | | 0x4 (AvailableLeftRigh t) | | | | (Grey Chevron on both sides, example graphic of HA in limited mode) | None |
| | Traffic_Jam_Assist_Cfg = AND Nav_Pilot_Cfg = X | | | 0x5 (PreparingLeft) | | | | (Blue Chevron on the Left, none Right, example graphic of HA in extended mode) | None |

| i | | ī | | | - | 1 | 11 | | |
|---|--|-------------------|-------------------|-------------------------|--------------------------------|----------------------|---|---|-------------|
| | | | | 0x6 (PreparingRight) | | | | Preparing Lane Change BLADY (Blue Chevron on the Right, none Left) | None |
| | | | | 0x7 (LcActiveLeft) | | | | (part of animation Indicating a lane change to the left, final static image is displayed as long as signal is active) | None |
| | | | | 0x8 (LcActiveRight) | | | | part of animation Indicating a lane change to the right, final static image is displayed as long as signal is active) | None |
| | | | 0x1 (Enabled) | | 0x1 (DriverCancel) | | | Canceled by Driver* (GML ID: A13) | |
| | | X (Don't Care) | | | 0x2 (SystemCancel) | X (Don't Care) | | Not Available (GML ID: A21) | ity_ Jag |
| | | | X (Don't Care) | 0x3 (CancelNoLane) | | Active | Not Available No Lane Seen* (GML ID: A15) | TJA_Low_Prionity_ Chime_Status_Flag | |
| | | | | | 0x4 (CancelLaneBusy) | | | Not Available Lane Busy* (GML ID: A14) | |
| | | | | | 0x5 (CancelSpeedToo Low) | | | Not Available Low Speed* (GML ID: A16) | |

| | _Cfg = 0x1 (Enabled) ne_Change_Cfg = X | 0x0 (Off) | | | | 0x1 (LcSugges tionLeft) | | Lane Change Suggested (above text or "Lane Change Possible, Use Left Turn Signal to make lane change" based on application HMI) | None |
|-------------------------------|--|-------------------|-------------------|--------------------------------|--------|---|--------------|--|------|
| Nor mal or Cran k | Cfg = 0x1 (Enabled) OR Hwy_Assist_Cfg = 0x1 (Enabled) Cfg = X (Don' t Care) AND Auto_Lane_Change_Cfg = X (Don, t Care) Ox0 Ox1 Ox1 Ox2 Ox1 Ox2 Ox4 Ox4 (Don't Care) Ax (Don't Care) Wissi Ox Ox2 (Don' t Care) | X (Don't Care) | X (Don't Care) | 0x2 (LcSugges tionRight) | Active | (above text or "Lane Change Possible, Use Left Turn Signal to make lane change" based on application HMI Example graphic of HA in Extended mode) | None | | |
| | Traffic_Jam_Assist_Cfg = AND Nav_Pilot_Cfg = | ng | | | | 0x5 (TurnOffIn dicator) | | Turn Signal Is Stil Active (Text: Turn Signal is Still Active) | None |
| | | | All | Other Cases | | | Inacti ve | (No indication) | None |

The ADAS controller will arbitrate and populate the 3 input signals above, cluster simply displays information based on signal states received.

Note *: The generic "Cancelation (GML ID: A1)" notification shall be displayed only if application display does not have space to display reason text.

For Assisted Lane Change, "Not Available" (GML ID: A21) notification shall be displayed only if an application display does not have space to display reason text.

Note: The Lane_Centering_Assist_Canceled_MC_Warn_Status_Flag shall have higher priority over any and all ALC cancelation messages.

Blue_Cruise_ECE_Cfg – Determines if certain notifications need to be displayed on the cluster per ECE regulations. Required to be enabled on ECE regions.

Above State Matrix for Assisted Lane Change Information is based on F-REQ-438184/B-State Matrix for Assisted Lane Change Information in < Highway Assist with Lane Centering Control Function and Warnings – FNV2.docm>. The purple content is added for NBP.

1.3.5.1.8 State Matrix for Navigation Based Pilot Information

Navigation Based Pilot Information will only be shown when the feature is active.

| Operational_Mode | Feature Config | NbpAvail_D_Stat Signal | Blue_Cruise_ECE_Cfg | TjaLc_D_Stat Signal | TjaLcWarn_D_Rq Signal | NbpLcMsgTxt_D_Rq | | NBP_Information_Display (Example Graphics) | Chime Status Flag |
|------------------|---|---|---|---------------------------------|--------------------------|-------------------|------------|---|-------------------|
| | = 0x1 (Enabled) Cfg = X (Don't Care) | | ChngSugg stnOnly) Or 0x3 (Available orvLnChng) Or 0x4 (Available | 0x1 (Standby) | X (Don't Care) | | | ((under speed threshold or no lanes detected) chevrons have less contrast and line thickness) | None |
| Nor mal | OR Hwy_Assist_Cfg Auto_Lane_Change_C | Grand Character (Available Lord Charges) Or (Charges) Or (Ox3) Or (Ox3) Or (Ox4) Or (Ox4) Or (Ox4) Or (Ox4) (Available DrvLnChng Or (Ox4) (Available DrvLnChng Ova (Available DrvLnChng Ova (Available VehLnChn | | 0x2 (AvailableLef t) | | X (Don't Care) | Activ e | (Grey chevron on the left only) | None |
| or Cran k | ssist_Cfg = $0x1$ (Enabled $y = X$ (Don't Care) ANL | | | 0x3 (AvailableRi ght) | | | | (Gray chevron on the right only) | None |
| | Traffic_Jam_A AND Nav_Pilot_Cf <u>i</u> | | | 0x4 (AvailableLef tRight) | | | | (Grey Chevron on both sides, example graphic of HA in limited mode) | None |

| | | | _ | | | | |
|--|-------------------|-----------------------------|--------------------|-------------------|-------|---|--|
| | | 0x5 (PreparingLef t) | | | | (Blue Chevron on the Left, none Right, example graphic of HA in extended mode) | None |
| | | 0x6 (PreparingRi ght) | | | | Preparing Lane Change (Blue Chevron on the Right, none Left) | None |
| | | 0x7 (LcActiveLef t) | | | | (part of animation Indicating a lane change to the left, final static image is displayed as long as signal is active) | None |
| | | 0x8 (LcActiveRig ht) | | | | part of animation Indicating a lane change to the right, final static image is displayed as long as signal is active) | None |
| | 0x1 (Enabled) | X | 0x1 (DriverCancel) | X (Don't Care) | Activ | Canceled by Driver* (GML ID: A13) | _Priority_ atus_Flag |
| | X (Don't Care) | (Don't Care) | 0x2 (SystemCancel) | | e | Not Available (GML ID: A21) | TJA_Low_Priority_ Chime_Status_Flag |

| ı | Ī | I | İ | 1 | Í | | ĺ | |] I |
|--|---|--|---|-------------------|--------------------------------|-------------------------------------|------------|--|--|
| | | | | | 0x3 (CancelNoLane) | | | Not Available No Lane Seen* (GML ID: A15) | |
| | | | | | 0x4 (CancelLaneBusy) | | | Not Available Lane Busy* (GML ID: A14) | |
| | | | | | 0x5 (CancelSpeedTooL ow) | | | Not Available Low Speed* (GML ID: A16) | |
| | X (Don't Care) ge_Cfg = X | | | | | 0x01 (HandOver) | | Handover | None |
| us a gen and and and and change a | R Traffic_Jam_Assist_Cfg = 3 bled) AND Auto_Lane_Chang | Hwy_Assist_Cfg = 0x1 (Enabled) OR Traffic_Jam_Assist_Cfg = X (Don' t Care) AND Nav_Pilot_Cfg = 0x1 (Enabled) AND Auto_Lane_Change_Cfg = X AND Nav_Pilot_Cfg = 0x1 (Enabled) AND Auto_Lane_Change_Cfg = X AND Nav_Pilot_Cfg = 0x1 (Enabled) AND Auto_Lane_Change_Cfg = X Ox O | AvailableL ChngSugg stnOnly) Or 0x3 Available | X (Don't Care) | X (Don't Care) | 0x02 (MissingExit Alert) | Activ e | Missing Exit Alert | TJA_Low_Priority_ Chime_Status_Flag |
| k | sist_Cfg = $0x1$ (Enabled) O Nav_Pilot_Cfg = $0x1$ (Ena | | Or Ox4 (Avaialble VehLnChn g) (Avaialble phonory of Care) | | | 0x05 (TurnOffIndic ator) | | Turn Signal is Still Active (Text: Turn Signal is Still Active) | None |
| | Hwy_As. AND | | | | | 0x06 (SuggstnLeft ExitManual) | | Approaching Exit change lane manually | None |

| | | | 0x07 (SuggstnRight ExitManual) | Approaching Exit change lane manually | None |
|--|--|--|--|---|------|
| | | | 0x08 (SuggstnLeft LnEndManual) | Approaching Lane End change lane manually | None |
| | | | 0x09 (SuggstnRight LnEndManual) | Approaching Lane End change lane manually | None |
| | | | 0x0A (SuggstnLeft YShapeManu al) | Approaching Y shape change lane manually | None |
| | | | 0x0B (SuggstnRight YShapeManu al) | Approaching Y shape change lane manually | None |
| | | | 0x0C (SuggstnLeftS lowVeh) | Slower vehicle change lane | None |
| | | | 0x0D (SuggstnRight SlowVeh) | To be added | None |

| | | | 0x0E (SuggstnLeft Exit) | Approaching Exit change lane | None |
|--|--|--|---------------------------------------|---|------|
| | | | 0x0F (SuggstnRight Exit) | Approaching Exit change lane | None |
| | | | 0x10 (SuggstnLeft MergeIn) | Approaching Merge in change lane | None |
| | | | 0x11 (SuggstnRight MergeIn) | Approaching Merge in change lane | None |
| | | | 0x12 (SuggstnLeft UnintndExit) | Approaching Unintended Exit change lane | None |
| | | | 0x13 (SuggstnRight UnintndExit) | Approaching Unintended Exit change lane | None |

| | | | 0x14 (SuggstnLeft LnEnd) | Approaching Lane End change lane | None |
|--|--|--|--|------------------------------------|------|
| | | | 0x15 (SuggstnRight LnEnd) | Approaching Lane End change lane | None |
| | | | 0x16 (SuggstnLeft YShape) | Approaching Y shape change lane | None |
| | | | 0x17 (SuggstnRight YShape) | Approaching Y shape change lane | None |
| | | | 0x18 (AutoLnChng LeftSlowVeh) | Slower vehicle Auto lane change | None |
| | | | 0x19 (AutoLnChng RightSlowVe h) | To be added | None |

| | | 0x1A (AutoLnChng LeftOptmzed Ln) | Optimized Lane Auto lane change | None |
|--|--|--|---------------------------------------|------|
| | | 0x1B (AutoLnChng RightOptmze dLn) | Optimized Lane Auto lane change | None |
| | | 0x1C (AutoLnChng LeftExit) | Approaching Exit Auto lane change | None |
| | | 0x1D (AutoLnChng RightExit) | Approaching Exit Auto lane change | None |
| | | 0x1E (AutoLnChng LeftMergeIn) | Approaching Merge in Auto lane change | None |
| | | 0x1F (AutoLnChng RightMergeIn | Approaching Merge in Auto lane change | None |

| | | | | | | A 151 | |
|---|-----|-------------|-----------|--|--------------|--|------|
| | | | | 0x20 atoLnChng itUnintndE xit) | | Approaching Unintended Exit Auto lane change | None |
| | | | | 0x21 atoLnChng ghtUnintnd Exit) | | Approaching Unintended Exit Auto lane change | None |
| | | | | 0x22 utoLnChng eftLnEnd) | | Approaching Lane End Auto lane change | None |
| | | | | 0x23 utoLnChng ghtLnEnd) | | Approaching Lane End Auto lane change | None |
| | | | (Au Le | 0x24 utoLnChng ftYShape) | | Approaching Y shape Auto lane change | None |
| | | | (Au | 00x25 utoLnChng htYShape) | | Approaching Y shape Auto lane change | None |
| • | All | Other Cases | • | | Inacti ve | (No indication) | None |

The ADAS controller will arbitrate and populate the 3 input signals above, cluster simply displays information based on signal states received.

Note *: The generic "Cancelation (GML ID: A1)" notification shall be displayed only if application display does not have space to display reason text.

For Assisted Lane Change, "Not Available" (GML ID: A21) notification shall be displayed only if an application display does not have space to display reason text.

Note: The Lane_Centering_Assist_Canceled_MC_Warn_Status_Flag shall have higher priority over any and all ALC cancelation messages.

Blue_Cruise_ECE_Cfg – Determines if certain notifications need to be displayed on the cluster per ECE regulations. Required to be enabled on ECE regions.

1.3.5.1.9 State Matrix Update for Highway Assist Information Warnings with NBP

| Operational_Mode | Feature Config | Driver Assist On- Demand Screen | TjaWarn_D_Rq Signal | TjaMsgTxt_D_Dsply Signal | NbpAvail_D_Stat Signal | Lane_Centering_Assis t Canceled MC War | Driver_Resume_Cont | Lane_Warning_Right | Lane_Warning_Left_ MC Worn Stotuc El | | Eyes_On_Road_Red_ | ote o b | Lane_Centering_Assis | Hwy_Assist_Unavaila | Hwy_Assist_On_ | Assist | Hwy_Assist_Press_Ac | Navigation_Pilot_Un |
|---------------------------|---|------------------------------------|--------------------------------------|---|---------------------------|---|--------------------|--------------------|---|------------------|-------------------|------------------|----------------------|---------------------|------------------|----------------------|---------------------|---------------------|
| | | Not Dis play ed | TrafficJamAs | X (Don't Care) | | Ac tiv e | In act ive | In act ive | In act ive | In act ive | In act ive | In act ive | In act ive | In act ive | In act ive | In act iv e | Ina cti ve | In act iv e |
| | | Acti vely Dis play ed | sistCancel (0x1) | | | Ina cti ve | In act ive | In act ive | In act ive | In act ive | In act ive | In act ive | In act ive | In act ive | In act ive | In act iv e | Ina cti ve | In act iv e |
| | abled $(0x1)$ Cfg = X | | HardTakeOv erLevel2 (0x3) | X (Don't Care) | | Ina ctiv e | A cti ve | In act ive | In act ive | In act ive | In act ive | In act ive | In act ive | In act ive | In act ive | In act iv e | Ina cti ve | In act iv e |
| | <pre>ffic_Jam_Assist_Cfg = Enabled (0x1) OR Hwy_Assist_Cfg = Enabled (0x1) AND Nav_Pilot_Cfg = 0x1 (Enabled) AND Auto_Lane_Change_Cfg = X</pre> | | HaLaneDept WarningRigh t (0x4) | | | Ina ctiv e | In act ive | A cti ve | In act ive | In act ive | In act ive | In act ive | In act ive | In act ive | In act ive | In act iv e | Ina cti ve | In act iv e |
| No rm | OR Hwy_Assi ND Auto_La | | HaLaneDept WarningLeft (0x5) | | X | Ina ctiv e | In act ive | In act ive | A cti ve | In act ive | In act ive | In act ive | In act ive | In act ive | In act ive | In act iv e | Ina cti ve | In act iv e |
| al or Cr an k | ubled (0x1) C (Enabled) A | X | SoftTakeOve rEyesOff (0x6) | | (Don' t Care) | Ina ctiv e | In act ive | In act ive | In act ive | A cti ve | In act ive | In act ive | In act ive | In act ive | In act ive | In act iv e | Ina cti ve | In act iv e |
| | II II | (Do n't Car e) | HardTakeOv erEyesOff (0x7) | | | Ina ctiv e | In act ive | In act ive | In act ive | In act ive | A cti ve | In act ive | In act ive | In act ive | In act ive | In act iv e | Ina cti ve | In act iv e |
| | Traffic_Jam_Assist_Cfg AND Nav_Pilot_Cfg | | | TrafficJamAs sistUnavailabl e (0x1) | | Ina ctiv e | In act ive | In act ive | In act ive | In act ive | In act ive | A cti ve | In act ive | In act ive | In act ive | In act iv e | Ina cti ve | In act iv e |
| | Traffi AN | | NoWarning (0x0) | TrafficJamAs sistSelected (0x2) | | Ina ctiv e | In act ive | In act ive | In act ive | In act ive | In act ive | In act ive | A cti ve | In act ive | In act ive | In act iv e | Ina cti ve | In act iv e |
| | | | (UXU) | HAUnavailab le (0x4) | | Ina ctiv e | In act ive | In act ive | In act ive | In act ive | In act ive | In act ive | In act ive | A cti ve | In act ive | In act iv e | Ina cti ve | In act iv e |
| | | | | HASelected (0x5) | | Ina ctiv e | In act ive | In act ive | In act ive | In act ive | In act ive | In act ive | In act ive | In act ive | A cti ve | In act iv e | Ina cti ve | In act iv e |

| Operational_Mode | Feature Config | Driver Assist On- Demand Screen | TjaWarn_D_Rq Signal | TjaMsgTxt_D_Dsply Signal | NbpAvail_D_Stat Signal | Lane_Centering_Assis t_Canceled_MC_War | Driver_Resume_Cont | Lane_Warning_Right | Lane_Warning_Left_ | On Ro | Eyes_On_Road_Red_ | Lane_Centering_Una | Lane_Centering_Assis | Hwy_Assist_Unavaila | Hwy_Assist_On_ | Hwy_Assist_Available | Hwy_Assist_Press_Ac | Navigation_Pilot_Un |
|------------------|-----------------|------------------------------------|--|--|---------------------------|---|--------------------|--------------------|--------------------|------------------|-------------------|--------------------|----------------------|---------------------|------------------|----------------------|---------------------|---------------------|
| | | | | SmartOfferin g (0x6) | | Ina ctiv e | In act ive | In act ive | In act ive | In act ive | In act ive | In act ive | In act ive | In act ive | In act ive | A cti ve | Ina cti ve | In act iv e |
| | | | | Disclaimer (0x7) | | Ina ctiv e | In act ive | In act ive | In act ive | In act ive | In act ive | In act ive | In act ive | In act ive | In act ive | In act iv e | Ac tiv e | In act iv e |
| | | | | Declared Missing as per Section 1.4.1 | | Ina ctiv e | In act ive | In act ive | In act ive | In act ive | In act ive | In act ive | In act ive | In act ive | In act ive | In act iv e | Ina cti ve | In act iv e |
| | | | X (Don't Care) | X (Don't Care) | NbpF ailure (0x5) | Ina ctiv e | In act ive | In act ive | In act ive | In act ive | In act ive | In act ive | In act ive | In act ive | In act ive | In act iv e | Ina cti ve | A cti ve |
| | | | Declared Missing as per Section 1.4.1 | X (Don't Care) | X (Don' t Care) | Ina ctiv e | In act ive | In act ive | In act ive | In act ive | In act ive | In act ive | In act ive | In act ive | In act ive | In act iv e | Ina cti ve | In act iv e |
| | All Other Cases | | | | | Ina ctiv e | In act ive | In act ive | In act ive | In act ive | In act ive | In act ive | In act ive | In act ive | In act ive | In act iv e | Ina cti ve | In act iv e |

Above State Matrix for Assisted Lane Change Information is based on F-REQ-343100/D-State Matrix for Highway Assist Information Warnings in < Highway Assist with Lane Centering Control Function and Warnings – FNV2.docm>. The purple content is added for NBP.

1.3.5.1.10 MC Status Flag to MC Warning Message

| MC Warn Status Flag | Reference Text or Graphic (see GML for exact wording) | MC Warning ID | Chime Status Flag |
|--|---|---------------|--|
| Navigation_Pilot_Unavailable_MC_Warn _Status_Flag | | | None |
| HandOver_MC_Warn_Status_Flag | Handover | | None |
| MissingExitAlert_MC_Warn_Status_Flag | Missing Exit Alert | | TJA_Low_Priority_ Chime_Status_Flag |
| SuggstnLeftExitManual_MC_Warn_Statu s_Flag | Approaching Exit change lane manually | | None |
| SuggstnRightExitManual_MC_Warn_Stat us_Flag | Approaching Exit change lane manually | | None |
| SuggstnLeftLnEndManual_MC_Warn_Sta tus_Flag | Approaching Lane End change lane manually | | None |
| SuggstnRightLnEndManual_MC_Warn_S tatus_Flag | Approaching Lane End change lane manually | | None |

| | | 1 | - |
|--|--|----------|------|
| SuggstnLeftYShapeManual_MC_Warn_St atus_Flag | Approaching Y shape change lane manually | | None |
| SuggstnRightYShapeManual_MC_Warn_ Status_Flag | Approaching Y shape change lane manually | | None |
| SuggstnLeftSlowVeh_MC_Warn_Status_ Flag | Slower vehicle change lane | | None |
| SuggstnRightSlowVeh_MC_Warn_Status _Flag | | | None |
| SuggstnLeftExit_MC_Warn_Status_Flag | Approaching Exit change lane | | None |
| SuggstnRightExit_MC_Warn_Status_Flag | Approaching Exit change lane | | None |
| SuggstnLeftMergeIn_MC_Warn_Status_F lag | Approaching Merge in change lane | | None |

| SuggstnRightMergeIn_MC_Warn_Status_ Flag | Approaching Merge in change lane | None |
|--|---|------|
| SuggstnLeftUnintndExit_MC_Warn_Status_Flag | Approaching Unintended Exit change lane | None |
| SuggstnRightUnintndExit_MC_Warn_Stat us_Flag | Approaching Unintended Exit change lane | None |
| SuggstnLeftLnEnd_MC_Warn_Status_Flag | Approaching Lane End change lane | None |
| SuggstnRightLnEnd_MC_Warn_Status_Fl | Approaching Lane End change lane | None |
| SuggstnLeftYShape_MC_Warn_Status_Fl ag | Approaching Y shape change lane | None |

| SuggstnRightYShape_MC_Warn_Status_Flag | Approaching Y shape change lane | None |
|--|------------------------------------|------|
| AutoLnChngLeftSlowVeh_MC_Warn_Status_Flag | Slower vehicle Auto lane change | None |
| AutoLnChngRightSlowVeh_MC_Warn_S tatus_Flag | | None |
| AutoLnChngLeftOptmzedLn_MC_Warn_Status_Flag | Optimized Lane Auto lane change | None |
| AutoLnChngRightOptmzedLn_MC_Warn _Status_Flag | Optimized Lane Auto lane change | None |
| AutoLnChngLeftExit_MC_Warn_Status_Flag | Approaching Exit Auto lane change | None |
| AutoLnChngRightExit_MC_Warn_Status _Flag | Approaching Exit Auto lane change | None |

| AutoLnChngLeftMergeIn_MC_Warn_Stat us_Flag | Approaching Merge in Auto lane change | None |
|---|--|------|
| AutoLnChngRightMergeIn_MC_Warn_St atus_Flag | Approaching Merge in Auto lane change | None |
| AutoLnChngLeftUnintndExit_MC_Warn_Status_Flag | Approaching Unintended Exit Auto lane change | None |
| AutoLnChngRightUnintndExit_MC_Warn _Status_Flag | Approaching Unintended Exit Auto lane change | None |
| AutoLnChngLeftLnEnd_MC_Warn_Status_Flag | Approaching Lane End Auto lane change | None |
| AutoLnChngRightLnEnd_MC_Warn_Status_Flag | Approaching Lane End Auto lane change | None |

| AutoLnChngLeftYShape_MC_Warn_Stat us_Flag | Approaching Y shape Auto lane change | None |
|---|--------------------------------------|------|
| AutoLnChngRightYShape_MC_Warn_Status_Flag | Approaching Y shape Auto lane change | None |

1.3.5.2 Operation Description (supports algorithm flow chart)

NBP settings are at IVI instead of cluster.

1.3.5.3 Personalization Feature Number Definition

None

1.3.5.4 Function Safety Classification (EMC)

Class B

1.3.5.6 Reconfigurable Telltale

None

1.3.5.5 Memory Storage

1.3.5.5.1 Memory Storage Parameters

| Parameter Name | Description | Value at Battery Connect | Value at Wake-up |
|---------------------------|--|--------------------------------|---------------------|
| Nav_Piolot_Cfg | Configures cluster to display items in the Settings menu (Set to "cluster" at cluster supplier manufacturer plant. | Use Stored Value | Use Stored Value |
| Auto_Lane_Change_Cfg | Configures cluster to display items in the Settings menu (Set to "cluster" at cluster supplier manufacturer plant. | Use Stored Value | Use Stored Value |
| FeatConfigIpmbActl signal | Input signal sent from IPMB to indicate current value of the feature setting for the feature that is being set or queried. | (0x0000) | Do Not Init |
| FeatNoIpmbActl | Input signal sent from IPMB to indicate Feature Number. | (0x0000) | Do Not Init |

| Parameter Name | Description | Value at Battery Connect | Value at Wake-up |
|---|--|--------------------------------|---------------------|
| PersIndexIpmb_D_Actl | Input signal from IPMB to indicate which personality profile is being reported. | Vehicle (0x4) | Do Not Init |
| Nbp_D_Stat | Input signal from IPMB to display current status of NBP system. | 0x0 | 0x0 |
| NbpMsgTxt_D2_Rq | Input signal from IPMB to display lane change assist notifications to the user. | 0x0 | 0x0 |
| NBP_Information_Display | Output signal to displays the Navigation Based Pilot information in the ADAS metaphor. | Inactive | Inactive |
| Navigation_Pilot_Unavailable_MC_Wa rn_Status_Flag | Output signal to control the state of the text warning message. | Inactive | Inactive |
| HandOver_MC_Warn_Status_Flag | Output signal to control the state of the text warning message. | Inactive | Inactive |
| MissingExitAlert_MC_Warn_Status_Fl ag | Output signal to control the state of the text warning message. | Inactive | Inactive |
| SuggstnLeftExitManual_MC_Warn_Status_Flag | Output signal to control the state of the text warning message. | Inactive | Inactive |
| SuggstnRightExitManual_MC_Warn_S tatus_Flag | Output signal to control the state of the text warning message. | Inactive | Inactive |
| SuggstnLeftLnEndManual_MC_Warn_ Status_Flag | Output signal to control the state of the text warning message. | Inactive | Inactive |
| SuggstnRightLnEndManual_MC_Warn _Status_Flag | Output signal to control the state of the text warning message. | Inactive | Inactive |
| SuggstnLeftYShapeManual_MC_Warn _Status_Flag | Output signal to control the state of the text warning message. | Inactive | Inactive |
| SuggstnRightYShapeManual_MC_War n_Status_Flag | Output signal to control the state of the text warning message. | Inactive | Inactive |
| SuggstnLeftSlowVeh_MC_Warn_Statu s_Flag | Output signal to control the state of the text warning message. | Inactive | Inactive |
| SuggstnRightSlowVeh_MC_Warn_Stat us_Flag | Output signal to control the state of the text warning message. | Inactive | Inactive |
| SuggstnLeftExit_MC_Warn_Status_Fla_g | Output signal to control the state of the text warning message. | Inactive | Inactive |
| SuggstnRightExit_MC_Warn_Status_Fl ag | Output signal to control the state of the text warning message. | Inactive | Inactive |
| SuggstnLeftMergeIn_MC_Warn_StatusFlag | Output signal to control the state of the text warning message. | Inactive | Inactive |
| SuggstnRightMergeIn_MC_Warn_Statu s_Flag | Output signal to control the state of the text warning message. | Inactive | Inactive |
| SuggstnLeftUnintndExit_MC_Warn_St atus_Flag | Output signal to control the state of the text warning message. | Inactive | Inactive |
| SuggstnRightUnintndExit_MC_Warn_S tatus_Flag | Output signal to control the state of the text warning message. | Inactive | Inactive |
| SuggstnLeftLnEnd_MC_Warn_Status_ Flag | Output signal to control the state of the text warning message. | Inactive | Inactive |
| SuggstnRightLnEnd_MC_Warn_Status _Flag | Output signal to control the state of the text warning message. | Inactive | Inactive |
| SuggstnLeftYShape_MC_Warn_Status _Flag | Output signal to control the state of the text warning message. | Inactive | Inactive |

| Parameter Name | Description | Value at Battery Connect | Value at Wake-up |
|----------------------------------|---------------------------------------|--------------------------------|---------------------|
| SuggstnRightYShape_MC_Warn_Statu | Output signal to control the state of | Inactive | Inactive |
| s_Flag | the text warning message. | mactive | mactive |
| AutoLnChngLeftSlowVeh_MC_Warn_ | Output signal to control the state of | Inactive | Inactive |
| Status_Flag | the text warning message. | mactive | mactive |
| AutoLnChngRightSlowVeh_MC_Warn | Output signal to control the state of | Inactive | Inactive |
| _Status_Flag | the text warning message. | mactive | mactive |
| AutoLnChngLeftOptmzedLn_MC_War | Output signal to control the state of | Inactive | Inactive |
| n_Status_Flag | the text warning message. | mactive | mactive |
| AutoLnChngRightOptmzedLn_MC_Wa | Output signal to control the state of | Inactive | Inactive |
| rn_Status_Flag | the text warning message. | mactive | mactive |
| AutoLnChngLeftExit_MC_Warn_Statu | Output signal to control the state of | Inactive | Inactive |
| s_Flag | the text warning message. | mactive | mactive |
| AutoLnChngRightExit_MC_Warn_Stat | Output signal to control the state of | Inactive | Inactive |
| us_Flag | the text warning message. | mactive | mactive |
| AutoLnChngLeftMergeIn_MC_Warn_S | Output signal to control the state of | Inactive | Inactive |
| tatus_Flag | the text warning message. | mactive | |
| AutoLnChngRightMergeIn_MC_Warn_ | Output signal to control the state of | Inactive | Inactive |
| Status_Flag | the text warning message. | mactive | mactive |
| AutoLnChngLeftUnintndExit_MC_War | Output signal to control the state of | Inactive | Inactive |
| n_Status_Flag | the text warning message. | mactive | mactive |
| AutoLnChngRightUnintndExit_MC_W | Output signal to control the state of | Inactive | Inactive |
| arn_Status_Flag | the text warning message. | mactive | mactive |
| AutoLnChngLeftLnEnd_MC_Warn_Sta | Output signal to control the state of | Inactive | Inactive |
| tus_Flag | the text warning message. | mactive | mactive |
| AutoLnChngRightLnEnd_MC_Warn_S | Output signal to control the state of | Inactive | Inactive |
| tatus_Flag | the text warning message. | mactive | mactive |
| AutoLnChngLeftYShape_MC_Warn_St | Output signal to control the state of | Inactive | Inactive |
| atus_Flag | the text warning message. | mactive | mactive |
| AutoLnChngRightYShape_MC_Warn_ | Output signal to control the state of | Inactive | Inactive |
| Status_Flag | the text warning message. | mactive | mactive |
| | Output signal to control the setting | | |
| AUTO_LANE_CHANGE_SETUP_MC | menu display output for Auto Lane | Inactive | Inactive |
| | Change. | | |

1.3.5.6 Prove Out

None

1.3.5.7 Message Center Msg

Refer to 1.3.3.5.14 MC Status Flag to MC Warning Message.

1.3.6 Electronic Horizon (EH) Message Handling

Electronic Horizon messages include ElecHorizon_Data1 (0x22E) and ElecHorizon_Data2 (0x22F) and they are originated from ADAS map which resides in In-Vehicle Infotainment System. With an alternative solution utilizing HD map for EH message creation, as it's stored outside of the IVI system, IVI has no responsibility broadcasting EH messages anymore. Neither does the ADAS map exist. Additionally, since HD map is highly linked with NBP feature, it makes sense to determine IVI EH messages broadcast based on NBP configuration.

- When Nav_Pilot_Cfg = 0x1 (Enabled), IVI should inhibit the broadcast of EH messages and disable any faults caused by ADAS map loss.
- When Nav_Pilot_Cfg = 0x0 (Disabled), IVI should broadcast EH messages based on ADAS map outputs.

*Note: please align with corresponding team who handles the ADAS map and EH message implementation.

1.4 Error Handling

1.4.1 Missing Message Strategy

Missing message DTC (TBD) shall be logged if signals NbpAvail_D_Stat or NbpMsgTxt_D_Rq is not received for continuous 5s.

If Nav_Pilot_Cfg = Disabled (0x0), the cluster shall never log a missing message DTC for NbpAvail_D_Stat and NbpMsgTxt_D_Rq signals for this feature.

1.5 Diagnostics

1.5.1 Self -Test

None

1.5.2 Engineering Test Mode

Reference section "Dealer / Engineering Test Mode (ETM)"

1.5.3 Part II Performance

1.5.3.1 DID Dexx

| - 1101011 | 1.3.3.1 DID DEXX | | | | | | | |
|---|-------------------------|----------------|------|---------------------------|----------|----------------|----------|---|
| Block | Block | D (() | 70. | State: | " | // 4.11 | 50.1 | Comments/ |
| Num | Description | Byte(s) | Bits | Description | "0" | "1" | Default | Information |
| PACKET | ED BLOCKS | | | | | | | |
| \$08 | Option Content (B&A) | * | 1 | Navigation Based Pilot | Disabled | Enabled | Disabled | This parameter allows the NBP related menu items and all information pertaining to the feature to be displayed in the vehicle. Disabled means NBP feature is not present in the vehicle. |
| \$08 | Option Content (B&A) | * | 1 | Auto Lane Change | Disabled | Enabled | Disabled | This parameter allows the Auto Lane Change settings menu and all pertaining information to be displayed in the cluster, as well as information. Disabled means Auto Lane Change (that is submenu of NBP) is not present in the vehicle. |
| *Byte and bit location to be identified in Part II Specification for this cluster | | | | | | | | |

1.5.3.2 Supported Diagnostic Trouble Codes (DTCs)

| DTC | Description |
|------|--|
| C23B | Lost Communication with IPMB (Image Processing Module "B") |

1.6 Reference Specification

< Highway Assist with Lane Centering Control Function and Warnings – FNV2.docm>

1.7 Revision History

| Version | Name | Change Description | Date |
|---------|---------------------------|---|------------------|
| 1.0 | Zhang Wayne Zheng Dong | Initial release | October 31/2022 |
| 1.1 | Zheng Dong | 1. According < Highway Assist with Lane Centering Control Function and Warnings – FNV2_v3.4_[VDOC075263_N]>, renaming assisted lane change "cancelation" notifications from "Canceled" to "Not Available". And add Blue_Cruise_ECE_Cfg condition in the chapter of State Matrix Update for Assisted Lane Change Information with NBP and State Matrix for Navigation Based Pilot Information. And add Blue_Cruise_ECE_Cfg condition in Diagnostic Configuration Flowchart. 2. Update DTC ID in 1.5.3.2 chapter 3. Update Highway Assist with Navigation Pilot input request Flowchart 4. Update Feature Config in State Matrix for Navigation Based Pilot Information | November 15/2022 |
| 1.2 | Zheng Dong | 1. Add output signals of MsgCntrDsplyOp_D_Rq, MsgCntrFeatNoRq, MsgCntrFeatConfigRq, MsgCntrPersIndex_D_Rq in I/O Block Diagram and description in outputs. 2. Add Hwy_Assist_Cfg and Traffic_Jam_Assist_Cfg in I/O Block Diagram. 3. Update for Menu display logic description. 4. Remove function ID such as F-REQ-XXXXXX/A. 5. Update Input Request Flowchart and Output SET Request Flowchart. 6. Delete the chapter of 1.3.5.5.2 Time Constants. | November 28/2022 |
| 1.3 | Zhang Wayne Zheng Dong | 1. Add 1.3.6 chapter for Electronic Horizon (EH) Message Handling. If this change implementation does not belong to NBP teams, please inform relevant responsible owner. | December 02/2022 |
| 1.4 | Zhang Wayne Zheng Dong | Update relative change for Setting menu change and NbpMsgTxt_D2_Rq replacing NbpMsgTxt_D_Rq. 1. update "1.1 Functional Description" 2. Add NbpMsgTxt_D2_Rq replacing NbpMsgTxt_D_Rq and remove NAVIGATION_PILOT_SETUP_MC and NAV_PILOT_AUDIO_SETUP_MC in I/O Block Diagram and descriptions in outputs. 3. Update Example Menu Structure and Menu display logic description in "1.3.3.1.1 Indicator Graphics / Display Format" 4. Remove 1.3.3.2 Audio-待修改 5. Update "1.3.5.1.2 Highway Assist and Lane Centering and Auto Lane Change Menu Display Determination Matrix" 6. Update "1.3.5.1.3 Highway Assist with Navigation Pilot input request Flowchart" | January 03/2023 |

| 7. Update "1.3.5.1.4 Highway Assist with Navigation | |
|---|--|
| Pilot output SET request Flowchart" | |
| 8. Remove "1.3.5.1.5 Navigation Based Pilot Setup | |
| State Assignment" | |
| 9. Remove "1.3.5.1.6 Navigation Based Pilot Setup | |
| Request Messages based upon | |
| NAVIGATION_PILOT_SETUP_M" | |
| 10. Remove "1.3.5.1.7 Navigation Pilot Audio Setup | |
| State Assignment" | |
| 11. Remove "1.3.5.1.8 Navigation Pilot Audio Setup | |
| Request Messages based upon | |
| NAV_PILOT_AUDIO_SETUP_MC" | |
| 12. Update "1.3.5.1.8 State Matrix for Navigation | |
| Based Pilot Information" | |
| 13. Update "1.3.5.1.10 MC Status Flag to MC | |
| Warning Message" | |
| 14. Update "1.3.5.5.1 Memory Storage Parameters" | |
| 15. Update block number for DID in 1.5.3.1 chapter | |