

#1) $\vec{y}_i = \vec{x}_i + \vec{v}_i$, $\langle \vec{v}_i, \vec{v}_j \rangle = R_i \delta_{ij}$, $\langle \vec{v}_i, \vec{x}_j \rangle = 0$ for $i > j$
 $\langle \vec{v}_i, \vec{x}_i \rangle = D_i$

all random variables are 0-mean

let $\{\vec{e}_i\}$ denote the innovation of $\{\vec{y}_i\}$, $\underbrace{\|\vec{e}_i\|^2}_{\text{variance of innovation } \vec{e}_i} = R_{e,i}$

Goal: use innovations wisely to analyze $\vec{x}_{i|i-1}$

(i.e. LMS of \vec{x}_i given $\{\vec{y}_j\}_{j=0}^{i-1}$)

Note: problem requires few calculations if done right

1-Q1) Show: $\langle \vec{v}_i, \hat{y}_{i|i-1} \rangle = 0$ where $\hat{y}_{i|i-1}$ is the LMS of \vec{y}_i given $\{\vec{y}_j\}_{j=0}^{i-1}$

Note: $\hat{y}_{i|i-1} = \sum_{j=0}^{i-1} \langle \vec{y}_i, \vec{e}_j \rangle \|\vec{e}_j\|^{-2} \vec{e}_j$, $e_0 = y_0$

also: $\hat{y}_{i|i-1} = \vec{x}_{i|i-1} + \sum_{j=0}^{i-1} \vec{v}_{i|i-1}^j$ (per $\vec{y}_i = \vec{x}_i + \vec{v}_i$)

$\vec{v}_{i|i-1}^j = 0$ b/c noise at \vec{v}_i is uncorrelated with noise at all other times

$\hat{x}_{i|i-1} = ?? = \sum_{j=0}^{i-1} k_{i,j} \vec{y}_j$ (per linear modeling assumptions)

$$= \sum_{j=0}^{i-1} k_{i,j} (\vec{x}_j + \vec{v}_j)$$

$\Rightarrow \langle \vec{v}_i, \hat{y}_{i|i-1} \rangle = \langle \vec{v}_i, \sum_{j=0}^{i-1} k_{i,j} (\vec{x}_j + \vec{v}_j) \rangle$

Note: example from Lee 10, pg 7:

$$\hat{x}_m = \sum_{j=0}^{m-1} \langle \vec{x}_m, \vec{e}_j \rangle \|\vec{e}_j\|^{-2} \vec{e}_j$$

need to prove

$$= \underbrace{\langle \vec{v}_i, \sum_{j=0}^{i-1} k_{i,j} \vec{x}_j \rangle}_{=0} + \underbrace{\langle \vec{v}_i, \sum_{j=0}^{i-1} k_{i,j} \vec{v}_j \rangle}_{=0 \text{ per } \langle \vec{v}_i, \vec{v}_j \rangle = 0 \forall i \neq j}$$

per $\langle \vec{v}_i, \vec{x}_j \rangle = 0 \forall i > j$

$\Rightarrow \boxed{\langle \vec{v}_i, \hat{y}_{i|i-1} \rangle = 0}$

□

#1-Q2) Show $\langle \vec{v}_i, \vec{e}_i \rangle = D_i + R_{e,i}$

$$\vec{e}_i = \vec{y}_i - \hat{y}_{i|i-1} \quad , \quad \hat{y}_{i|i-1} = \left[\sum_{j=0}^{i-1} \langle \vec{y}_i, \vec{e}_j \rangle \|\vec{e}_j\|^{-2} \vec{e}_j \right] = \hat{x}_{i|i-1} + \hat{v}_{i|i-1}$$

$$\vec{y}_i = \vec{x}_i + \vec{v}_i$$

$$\Rightarrow \vec{e}_i = \vec{x}_i + \vec{v}_i - \cancel{\hat{x}_{i|i-1}} \hat{y}_{i|i-1}$$

$$\Rightarrow \langle \vec{v}_i, \vec{e}_i \rangle = \langle \vec{v}_i, \vec{x}_i + \vec{v}_i - \hat{y}_{i|i-1} \rangle$$

$$= \langle \vec{v}_i, \vec{x}_i \rangle + \langle \vec{v}_i, \vec{v}_i \rangle - \cancel{\langle \vec{v}_i, \hat{y}_{i|i-1} \rangle}^0 \text{ for (Q1-Q2)}$$

$$\boxed{= D_i + R_{e,i}}$$

□

#1-Q3)

$$\text{Show } \hat{x}_{i|i} = \vec{y}_i - (D_i + R_{e,i}) R_{e,i}^{-1} \vec{e}_i$$

~~we have that~~ $\hat{y}_{i|i-1} = \sum_{j=0}^{i-1} \langle \vec{y}_i, \vec{e}_j \rangle \|\vec{e}_j\|^{-2} \vec{e}_j$

Linear modeling assumption:

$$\hat{x}_{i|i} = \sum_{j=0}^i \kappa_{ij} \hat{y}_j$$

~~$\vec{y}_i = \vec{x}_i + \vec{v}_i (= \vec{e}_i + \hat{y}_{i|i-1})$~~

~~$\hat{y}_{i|i-1} = \sum_{j=0}^{i-1} \langle \vec{x}_i + \vec{v}_i, \vec{e}_j \rangle R_{e,j}^{-1} \vec{e}_j = \hat{x}_{i|i-1} + \hat{v}_{i|i-1}$~~

~~project \vec{y}_i onto \vec{e}_i gives us $\hat{y}_{i|i} = \langle \vec{y}_i, \vec{e}_i \rangle$
(orthogonal components drop out)~~

~~$$\hat{x}_{i|i} = (\vec{e}_i + \hat{y}_{i|i-1}) - (\langle \vec{v}_i, \vec{e}_i \rangle + \langle \vec{e}_i, \vec{e}_i \rangle) \|\vec{e}_i\|^{-2} \vec{e}_i$$~~

→

$$\begin{aligned}
 \hat{x}_{i|i} &= (\vec{e}_i + \hat{y}_{i|i-1}) - (\langle \vec{v}_i, \vec{e}_i \rangle + \|\vec{e}_i\|^2) \|\vec{e}_i\|^2 \vec{e}_i \\
 &= (\vec{e}_i + \hat{y}_{i|i-1}) - (\langle \vec{v}_i, \vec{e}_i \rangle \|\vec{e}_i\|^2 \vec{e}_i + \vec{x}_i) \\
 &= \hat{y}_{i|i-1} - \langle \vec{v}_i, \vec{e}_i \rangle \|\vec{e}_i\|^2 \vec{e}_i
 \end{aligned}$$

$$(y_i) = \hat{y}_{i|i} = \sum_{j=0}^i \langle \hat{y}_i, \vec{e}_j \rangle \|\vec{e}_j\|^2 \vec{e}_j$$

$$= \sum_{j=0}^i \langle \hat{x}_i, \vec{e}_j \rangle \|\vec{e}_j\|^2 \vec{e}_j + \sum_{j=0}^i \langle \vec{v}_i, \vec{e}_j \rangle \|\vec{e}_j\|^2 \vec{e}_j$$

$$y_i = \hat{x}_{i|i} + \underbrace{\langle \vec{v}_i, \vec{e}_i \rangle R_{e,i}^{-1} \vec{e}_i}_{= (D_i + R_{i|i}) R_{e,i}^{-1} \vec{e}_i} + \underbrace{\sum_{j=0}^{i-1} \langle \vec{v}_i, \vec{e}_j \rangle \|\vec{e}_j\|^2 \vec{e}_j}$$

$$\vec{e}_j \in \text{Span}(y_0, y_1, \dots, y_j) \subset \text{Span}(x_0, x_1, \dots, x_j, v_0, v_1, \dots, v_j)$$

$$\langle \vec{v}_i, \vec{x}_j \rangle = \langle \vec{v}_i, \vec{v}_j \rangle = 0 \quad \forall i > j$$

$$\Rightarrow \langle \vec{v}_i, \vec{e}_j \rangle = 0 \quad \forall i > j$$

$$\Rightarrow \sum_{j=0}^{i-1} \langle \vec{v}_i, \vec{e}_j \rangle \|\vec{e}_j\|^2 \vec{e}_j = 0$$

(can also re-use arguments from #1-Q1 and #1-Q2)

$$\Rightarrow \boxed{\hat{x}_{i|i} = \hat{y}_i - (D_i + R_i) R_{e,i}^{-1} \vec{e}_i}$$

1-Q4]

$$\underline{\text{show}} \quad \|\vec{x}_i - \hat{x}_{\text{all}}\|^2 = R_i + (D_i + R_i) R_{e,i}^{-1} (D_i + R_i)^T$$

$$\begin{aligned} \|\vec{x}_i - \hat{x}_{\text{all}}\|^2 &= \langle \vec{x}_i - \hat{x}_{\text{all}}, \vec{x}_i - \hat{x}_{\text{all}} \rangle \\ &= \langle \vec{x}_i, \vec{x}_i \rangle - \langle \vec{x}_i, \hat{x}_{\text{all}} \rangle - \langle \hat{x}_{\text{all}}, \vec{x}_i \rangle + \langle \hat{x}_{\text{all}}, \hat{x}_{\text{all}} \rangle \end{aligned}$$

$$\left[\begin{aligned} \vec{x}_i - \hat{x}_{\text{all}} &= (\vec{y}_i - \vec{v}_i) - (\vec{y}_i - (D_i + R_i) R_{e,i}^{-1} \vec{e}_i) \\ &= -\vec{v}_i + (D_i + R_i) R_{e,i}^{-1} \vec{e}_i \end{aligned} \right]$$

$$\begin{aligned} \Rightarrow \|\vec{x}_i - \hat{x}_{\text{all}}\|^2 &= \|-\vec{v}_i + (D_i + R_i) R_{e,i}^{-1} \vec{e}_i\|^2 \\ &= \langle \vec{v}_i, \vec{v}_i \rangle - \langle \vec{v}_i, (D_i + R_i) R_{e,i}^{-1} \vec{e}_i \rangle - \langle (D_i + R_i) R_{e,i}^{-1} \vec{e}_i, \vec{v}_i \rangle \\ &\quad + \langle (D_i + R_i) R_{e,i}^{-1} \vec{e}_i, (D_i + R_i) R_{e,i}^{-1} \vec{e}_i \rangle \end{aligned}$$

$$\langle \vec{v}_i, \vec{v}_i \rangle = R_i$$

$$\langle \vec{v}_i, (D_i + R_i) R_{e,i}^{-1} \vec{e}_i \rangle = \langle \vec{v}_i, \vec{e}_i \rangle R_{e,i}^{-1} (D_i + R_i)^T = (D_i + R_i) R_{e,i}^{-1} (D_i + R_i)^T$$

$$\langle (D_i + R_i) R_{e,i}^{-1} \vec{e}_i, \vec{v}_i \rangle = (D_i + R_i) R_{e,i}^{-1} (D_i + R_i)^T$$

$$\begin{aligned} \langle (D_i + R_i) R_{e,i}^{-1} \vec{e}_i, (D_i + R_i) R_{e,i}^{-1} \vec{e}_i \rangle &= (D_i + R_i) R_{e,i}^{-1} \langle \vec{e}_i, \vec{e}_i \rangle R_{e,i}^{-1} (D_i + R_i)^T \\ &= (D_i + R_i) R_{e,i}^{-1} (D_i + R_i)^T \end{aligned}$$

$$R_{e,i} = \begin{bmatrix} R(e_0, e_0)(i) & R(e_0, e_1)(i) & \dots \\ R(e_0, e_1)(i) & \ddots & \\ \vdots & & \\ R(e_m, e_m)(i) & & \end{bmatrix}$$

$$= \begin{bmatrix} R(e_0, e_0)_i & & \\ & \ddots & \\ & & R(e_m, e_m)_i \end{bmatrix} \xrightarrow{\text{due to orthogonalizing of } e_0, e_1, \dots, e_{m-1}} \Rightarrow R_{e,i} = R_{e,i}^T$$

→

1-4

$$R_{e,i} = R_{e,i}^T$$

$$\Rightarrow \langle \vec{v}_i, (D_i + R_i) R_{e,i}^{-1} \vec{e}_i \rangle = (D_i + R_i) R_{e,i}^{-1} (D_i + R_i)^T = (D_i + R_i) R_{e,i}^{-1} (D_i + R_i)^+$$

$$\langle (D_i + R_i) R_{e,i}^{-1} \vec{e}_i, \vec{v}_i \rangle = (D_i + R_i) R_{e,i}^{-1} (D_i + R_i)^T$$

$$\langle (D_i + R_i) R_{e,i}^{-1} \vec{e}_i, (D_i + R_i) R_{e,i}^{-1} \vec{e}_i \rangle = (D_i + R_i) R_{e,i}^{-1} (D_i + R_i)^T$$

$$\boxed{\Rightarrow \| \vec{x}_i - \hat{x}_i \|_2^2 = R_i - (D_i + R_i) R_{e,i}^{-1} (D_i + R_i)^T}$$

#2] Innovation for simple process

$$y_n = v_n + v_{n-1}, n \geq 0 \Rightarrow \{v_i\}_{i=1}^{\infty}, \sum v_i = 0 \\ \sum v_i = 1$$

$$\#2-02] \text{ Show } e_j = v_j + \frac{(-1)^{j-1}}{j+1} \left(\sum_{k=-1}^{j-1} (-1)^k v_k \right) \quad \& \quad \|e_j\|^2 = \frac{j+2}{j+1}$$

by inspection show true for $j=0, 1$:

$$e_0 = v_0 + \frac{(-1)^0}{1} \sum_{k=-1}^0 (-1)^k v_k = v_0 + -1(-1)v_{-1} = v_0 + v_{-1} \quad \checkmark \\ (y_0 = v_0 + v_{-1}) = e_0$$

$$e_1 = v_1 + \frac{(-1)^0}{1+1} \sum_{k=-1}^0 (-1)^k v_k = v_1 + \frac{1}{2}(-v_{-1} + v_0) \quad (\text{eq 2.1})$$

$$= y_1 - \hat{y}_{1|0} = v_1 + v_0 - \left(\sum_{i=0}^0 \langle y_i, e_i \rangle \|e_i\|^{-2} e_i \right)$$

$$= v_1 + v_0 - \left(\langle y_1, e_0 \rangle \|e_0\|^{-2} e_0 \right) ; \quad \langle y_1, e_0 \rangle = \langle v_1 + v_0, v_0 + v_{-1} \rangle$$

$$= v_1 + v_0 - \left(\left(\frac{1}{2} \right) (v_0 + v_{-1}) \right) \quad \|e_0\|^2 = \langle e_0, e_0 \rangle = \langle v_0 + v_{-1}, v_0 + v_{-1} \rangle = 2 \\ \Rightarrow \|e_0\|^{-2} = \frac{1}{2}$$

$$= v_1 - \frac{1}{2} v_{-1} + v_0 - \frac{1}{2} v_0$$

$$= v_1 + \frac{1}{2}(-v_{-1} + v_0) \quad \checkmark \quad (\text{eq 2.2})$$

equation (2.1) equals equation (2.2) \checkmark



Now assume holds true for ~~e_{j-1}~~ e_{j-1}

$$\text{then: } e_j = v_j - \hat{y}_{j-1} = v_j + v_{j-1} - \sum_{i=0}^{j-1} \langle y_i, e_i \rangle \|e_i\|^2 e_i \quad (2.3)$$

$$\begin{aligned} \sum_{i=0}^{j-1} \langle v_i + v_{j-1}, e_i \rangle \|e_i\|^2 e_i &= \sum_{i=0}^{j-1} (\underbrace{\langle v_i, e_i \rangle}_0 + \underbrace{\langle v_{j-1}, e_i \rangle}_0) \|e_i\|^2 e_i \\ &= \stackrel{\textcircled{1}}{=} \quad \stackrel{\textcircled{2}}{=} \quad \stackrel{\textcircled{3}}{=} \end{aligned} \quad (2.4)$$

for $i < j-1$
for $j-1 = i'$

$$\Rightarrow = (1) \|e_{j-1}\|^2 e_{j-1}$$

$$e_{j-1} \text{ is given: } e_{j-1} = v_{j-1} + \frac{(-1)^{j-2}}{j} \sum_{i=1}^{j-2} (-1)^i v_i$$

$$\|e_{j-1}\|^2 = \langle v_{j-1}, v_{j-1} \rangle + \underbrace{0}_{\langle v_{j-1}, v_i \rangle, i \leq j-2 \text{ (white noise)}} + \frac{(-1)^{j-2} (-1)^{j-2}}{j^2} \underbrace{\left\langle \sum_{i=1}^{j-2} (-1)^i v_i, \sum_{n=1}^{j-2} (-1)^n v_n \right\rangle}_{\langle v_i, v_n \rangle = \delta_{in}, \prod_{i=n}^j (-1)^i (-1)^{j-i} = (-1)^{2j}} \\ \Rightarrow = \textcircled{4}$$

$$= 1 + \frac{1}{j} = \frac{j+1}{j} \quad \boxed{\left(\Rightarrow \|e_j\|^2 = \frac{j+1}{j+2} \right)} \quad \boxed{\left(\|e_j\| = \frac{j+2}{j+1} \right)}$$

$$\Rightarrow (2.4) = \|e_{j-1}\|^2 e_{j-1} = \frac{j}{j+1} \left(v_{j-1} + \frac{(-1)^{j-2}}{j} \sum_{i=1}^{j-2} (-1)^i v_i \right)$$

$$\Rightarrow (2.3) \Rightarrow e_j = v_j + v_{j-1} - \frac{j}{j+1} \left(v_{j-1} \right) - \frac{(-1)^{j+2}}{j+1} \sum_{i=1}^{j-2} (-1)^i v_i$$

$$= v_j + v_{j-1} \left(1 - \frac{j}{j+1} \right) - \dots \rightarrow$$

$$\rightarrow e_j = v_j + v_{j-1} \left(\frac{1}{j+1} \right) \underbrace{\sum_{l=1}^{j-2} (-1)^l v_l}_{\cancel{(-1)^{j-2}} \sum_{l=1}^{j-2} (-1)^l v_l} \quad \cancel{(-1)^{j-1}}$$

Note: $(-1)^{j-1} (-1)^{j-1} = 1 \quad \checkmark$

$$\Rightarrow e_j = v_j + v_{j-1} \left(\frac{(-1)^{j-1} (-1)^{j-1}}{j+1} \right) + \frac{(-1)^{j-1}}{j+1} \sum_{l=1}^{j-2} (-1)^l v_l$$

$$\Rightarrow \boxed{e_j = v_j + \frac{(-1)^{j-1}}{j+1} \sum_{l=1}^{j-1} (-1)^l v_l \quad \checkmark}$$

Then by induction, we have proven

$$e_j = v_j + \frac{(-1)^{j-1}}{j+1} \sum_{l=1}^{j-1} (-1)^l v_l \quad \text{and} \quad \|e_j\|^2 = \frac{j+2}{j+1}$$

□

#2-Q2 Prove that $\hat{y}_{n+k} = \frac{n+1}{k+2} e_n$

by inspection: $\hat{y}_{1|0} = \sum_{i=0}^0 \langle y_1, e_i \rangle \|e_i\|^{-2} e_i = \langle y_1, e_0 \rangle \|e_0\|^{-2} e_0 \quad (\text{from } \#2-Q1)$

$$= \frac{1}{2} (v_0 + v_{-1}) = \frac{1}{2} e_0$$

and $\hat{y}_{1|0} = \frac{0+1}{0+2} e_0 = \frac{1}{2} e_0 \quad \checkmark$

assume holds for $\hat{y}_{n|n-1}$, then check $\hat{y}_{n+1|n}$

$$\Rightarrow \hat{y}_{n+1|n} = \sum_{i=0}^n \langle y_{n+1}, e_i \rangle \|e_i\|^{-2} e_i$$

$$= \sum_{i=0}^n \left(\langle v_{n+1}, e_i \rangle + \langle v_n, e_i \rangle \right) \|e_i\|^{-2} e_i$$

$$\Rightarrow \hat{y}_{n+1|n} = (1) \|e_n\|^{-2} e_n = \frac{n+1}{k+2} e_n \quad \text{by induction}$$

□

#3-A1) A Useful Relation with Innovations

$\{\vec{y}_i\}_{i=0}^n$, innovation = $\{\vec{e}_i\}_{i=0}^n$ Let $\vec{y} \stackrel{?}{=} \begin{bmatrix} \vec{y}_0 \\ \vdots \\ \vec{y}_{n-1} \end{bmatrix}$

$$\text{Show: } \vec{y}^T R_y^{-1} \vec{y} = \sum_{i=0}^{n-1} \vec{e}_i^T \vec{e}_i$$

Note: assume R_y non-singular. (Recall $\vec{y} = L\vec{e}$ for some well-chosen lower triangular matrix L w/ unit diagonal.)

$$\vec{e}_i = \vec{y}_i - \hat{y}_{i|i-1} \Rightarrow \vec{y}_i = \vec{e}_i + \hat{y}_{i|i-1}, \quad \hat{y}_{i|i-1} = \sum_{j=0}^{i-1} \langle \vec{y}_j, \vec{e}_i \rangle \vec{e}_j$$

$$\vec{y}^T R_y^{-1} \vec{y} = \vec{e}^T L^T R_y^{-1} L \vec{e}$$

$$R_y^{-1} = (\mathbb{E}[yy^T])^{-1} = (\langle \vec{y}, \vec{y} \rangle)^{-1}$$

$$\langle \vec{y}, \vec{y} \rangle = \langle \vec{e}, \vec{e} \rangle$$

$$\vec{y} = \begin{bmatrix} \vec{y}_0 \\ \vdots \\ \vec{y}_{n-1} \end{bmatrix} = \begin{bmatrix} \vec{e}_0 + \hat{y}_{0|0} \\ \vec{e}_1 + \hat{y}_{1|0} \\ \vdots \\ \vec{e}_{n-1} + \hat{y}_{n-1|n-2} \end{bmatrix} = \vec{e} + \begin{bmatrix} \hat{y}_{0|0} \\ \vdots \\ \hat{y}_{n-1|n-2} \end{bmatrix}$$

$$\begin{aligned} \langle \vec{y}, \vec{y} \rangle &= \langle \vec{e} + \Sigma, \vec{e} + \Sigma \rangle \\ &= \langle \vec{e}, \vec{e} \rangle + \langle \vec{e}, \Sigma \rangle + \langle \Sigma, \vec{e} \rangle + \langle \Sigma, \Sigma \rangle \end{aligned}$$

$$\langle \vec{e}, \Sigma \rangle = \mathbb{E}(\vec{e} \Sigma^T) = \mathbb{E}(\vec{e} \mathbb{E}[\hat{y}_{0|0}^T \cdots \hat{y}_{n-1|n-2}^T])$$

$$= \mathbb{E} \left[\begin{array}{cccc} 0 & \vec{e}_0 \hat{y}_{0|0}^T & \cdots & \vec{e}_0 \hat{y}_{n-1|n-2}^T \\ 0 & \vec{e}_1 \hat{y}_{0|0}^T & \ddots & \vdots \\ \vdots & \vdots & \ddots & \vdots \\ 0 & \vec{e}_{n-1} \hat{y}_{0|0}^T & \cdots & \vec{e}_{n-1} \hat{y}_{n-1|n-2}^T \end{array} \right]$$

$$\text{by definition, } \mathbb{E}(\vec{e}_i \hat{y}_{i|i-1}^T) = \langle \vec{e}_i, \hat{y}_{i|i-1} \rangle = 0 \text{ (orthogonal)}$$

$$\hat{y}_{110} = \langle \hat{y}_1, \vec{e}_0 \rangle \|\vec{e}_0\|^{-2} \vec{e}_0$$

$$\Rightarrow \langle \vec{e}_0, \hat{y}_{110} \rangle = \langle \vec{e}_0, \langle \hat{y}_1, \vec{e}_0 \rangle \|\vec{e}_0\|^{-2} \vec{e}_0 \rangle = \langle \vec{e}_0, \vec{e}_0 \rangle (\langle \hat{y}_1, \vec{e}_0 \rangle \|\vec{e}_0\|^{-2})^+$$

(orthogonal)

$$\Rightarrow [\langle \hat{e}_j, \hat{y}_{11i-1} \rangle = 0 \vee j = i]$$

$$\langle \vec{e}_0, \hat{y}_{110} \rangle = \langle \vec{e}_0, \langle \hat{y}_1, \vec{e}_0 \rangle \|\vec{e}_0\|^{-2} \vec{e}_0 \rangle = \langle \vec{e}_0, \vec{e}_0 \rangle (\langle \hat{y}_1, \vec{e}_0 \rangle \|\vec{e}_0\|^{-2})^+$$

$$\langle \vec{e}_0, \hat{y}_{n-1|n-2} \rangle = \langle \vec{e}_0, \sum_{j=0}^{n-1} \langle \hat{y}_{n-1}, \vec{e}_j \rangle \|\vec{e}_j\|^{-2} \vec{e}_j \rangle = \langle \vec{e}_0, \vec{e}_0 \rangle (\langle \hat{y}_{n-1}, \vec{e}_0 \rangle \|\vec{e}_0\|^{-2})^+$$

by orthogonality.

$$\Rightarrow [\langle \vec{e}_j, \hat{y}_{11i-1} \rangle = \langle \vec{e}_j, \vec{e}_j \rangle (\langle \hat{y}_{11i}, \vec{e}_j \rangle \|\vec{e}_j\|^{-2})^+ \vee i > j]$$

$$\langle \Sigma, \vec{e} \rangle = \mathbb{E}[\Sigma \vec{e}^+] = \mathbb{E}[\Sigma [\vec{e}_0^+ \vec{e}_1^+ \dots \vec{e}_{n-1}^+]]$$

$$= \mathbb{E} \left[\begin{matrix} 0 & 0 & \dots & 0 \\ \hat{y}_{110} \vec{e}_0 & \hat{y}_{110} \vec{e}_1 & \dots & \hat{y}_{110} \vec{e}_{n-1} \\ \vdots & & & \\ \hat{y}_{n-1|n-2} \vec{e}_0 & \dots & \hat{y}_{n-1|n-2} \vec{e}_{n-1} \end{matrix} \right]$$

$$\hat{y}_{11i-1} = \sum_{j=0}^{i-1} \langle \hat{y}_{11i}, \vec{e}_j \rangle \|\vec{e}_j\|^{-2} \vec{e}_j$$

$$\Rightarrow \langle \hat{y}_{11i-1}, \vec{e}_k \rangle = 0 \quad \forall k > i-1 \quad \Rightarrow \mathbb{E}[\Sigma \vec{e}^+] \text{ upper triangle} = 0$$

$$\langle \hat{y}_{110}, \vec{e}_0 \rangle = \langle \hat{y}_1, \vec{e}_0 \rangle \|\vec{e}_0\|^{-2} \langle \vec{e}_0, \vec{e}_0 \rangle = \langle \hat{y}_1, \vec{e}_0 \rangle \|\vec{e}_0\|^{-2} \langle \vec{e}_0, \vec{e}_0 \rangle$$

$$\begin{aligned} \langle \hat{y}_{n-1|n-2}, \vec{e}_0 \rangle &= \langle \sum_{j=0}^{n-2} \langle \hat{y}_{n-1}, \vec{e}_j \rangle \|\vec{e}_j\|^{-2} \vec{e}_j, \vec{e}_0 \rangle \\ &= \langle \langle \hat{y}_{n-1}, \vec{e}_0 \rangle \|\vec{e}_0\|^{-2} \vec{e}_0, \vec{e}_0 \rangle \quad \text{by orthogonality} \end{aligned}$$

$$\text{try: } R_y^{-1} = (\langle \vec{y}, \vec{y} \rangle)^{-1} = (\langle L\vec{e}, L\vec{e} \rangle)^{-1} \\ = (\mathbb{E}(L\vec{e}\vec{e}^T L^+))^{-1} = \cancel{\mathbb{E}(L^+ \vec{e}^+ \vec{e} L^{-1})}$$

$L = ?$

$$\vec{y} = \begin{bmatrix} \vec{y}_0 \\ \vec{y}_1 \\ \vdots \\ \vec{y}_{n-1} \end{bmatrix}$$

$$\vec{y}_i = \vec{e}_i + \sum_{j=0}^{i-1} \langle \vec{y}_i, \vec{e}_j \rangle \| \vec{e}_j \|^2 \vec{e}_j, \quad \vec{e}_0 = \vec{y}_0 \\ \Rightarrow \vec{y} = \left[\begin{array}{l} \vec{y}_0 = \vec{e}_0 \\ \vec{e}_1 + \langle \vec{y}_1, \vec{e}_0 \rangle \| \vec{e}_0 \|^2 \vec{e}_0 \\ \vec{e}_2 + \langle \vec{y}_2, \vec{e}_0 \rangle \| \vec{e}_0 \|^2 \vec{e}_0 + \langle \vec{y}_2, \vec{e}_1 \rangle \| \vec{e}_1 \|^2 \vec{e}_1 \\ \vdots \\ \vec{e}_{n-1} + \sum_{j=0}^{n-2} \langle \vec{y}_{n-1}, \vec{e}_j \rangle \| \vec{e}_j \|^2 \vec{e}_j \end{array} \right]$$

$$= L\vec{e}$$

$$= \left[\begin{array}{cccccc} 1 & & & & & \\ \langle \vec{y}_1, \vec{e}_0 \rangle \| \vec{e}_0 \|^2 & 1 & & & & \\ \langle \vec{y}_2, \vec{e}_0 \rangle \| \vec{e}_0 \|^2 & \langle \vec{y}_2, \vec{e}_1 \rangle \| \vec{e}_1 \|^2 & 1 & & & \\ \vdots & & & & & \\ \langle \vec{y}_{n-1}, \vec{e}_0 \rangle \| \vec{e}_0 \|^2 & \langle \vec{y}_{n-1}, \vec{e}_1 \rangle \| \vec{e}_1 \|^2 & \dots & \langle \vec{y}_{n-1}, \vec{e}_{n-2} \rangle \| \vec{e}_{n-2} \|^2 & 1 & \end{array} \right] \begin{bmatrix} \vec{e}_0 \\ \vec{e}_1 \\ \vdots \\ \vec{e}_{n-1} \end{bmatrix}$$

$\Rightarrow L$ is constant

$$\Rightarrow R_y^{-1} = \cancel{\mathbb{E}(L^+ \vec{e}^+ \vec{e} L^{-1})} = L^+ \mathbb{E}(\vec{e} \vec{e}^T) \\ = \mathbb{E}(L \vec{e} \vec{e}^T L^+)^{-1} = [L \mathbb{E}(\vec{e} \vec{e}^T) L^+]^{-1} = L^+ \mathbb{E}(\vec{e} \vec{e}^T)^{-1} L^{-1}$$

$$\Rightarrow \vec{y}^+ R_y^{-1} \vec{y} = \vec{e}^+ L^+ \cancel{I} \mathbb{E}(\vec{e} \vec{e}^T)^{-1} L^{-1} \cancel{I} \vec{e} \\ = \vec{e}^+ \| \vec{e} \|^2 \vec{e}$$



$$\vec{e}^+ \|\vec{e}\|^{-2} \vec{e} = ?$$

$$\|\vec{e}\|^2 = (\vec{e}, \vec{e})^{-1} = \mathbb{E}(\vec{e} \vec{e}^+)^{-1} = \left[\mathbb{E} \begin{bmatrix} \vec{e}_0 \vec{e}_0 & \vec{e}_0 \vec{e}_1 & \cdots & \vec{e}_0 \vec{e}_{n-1} \\ \vec{e}_1 \vec{e}_0 & \ddots & & \vdots \\ \vdots & & \ddots & \vdots \\ \vec{e}_{n-1} \vec{e}_0 & & & \vec{e}_{n-1} \vec{e}_{n-1} \end{bmatrix} \right]^{-1}$$

$$= \begin{bmatrix} \|\vec{e}_0\|^2 & & 0 \\ & \|\vec{e}_1\|^2 & \ddots \\ & 0 & \|\vec{e}_{n-1}\|^2 \end{bmatrix} \quad \text{by orthogonality}$$

i.e. $\mathbb{E}[\vec{e}_j \vec{e}_i^+] = \langle \vec{e}_j, \vec{e}_i \rangle^{-1} \delta_{ij}$

$$\Rightarrow \|\vec{e}\|^{-2} \vec{e} = \begin{bmatrix} \|\vec{e}_0\|^{-2} \vec{e}_0 \\ \|\vec{e}_1\|^{-2} \vec{e}_1 \\ \vdots \\ \|\vec{e}_{n-1}\|^{-2} \vec{e}_{n-1} \end{bmatrix}$$

$$\Rightarrow \vec{e}^+ \|\vec{e}\|^{-2} \vec{e} = \vec{e}_0^+ \|\vec{e}_0\|^{-2} \vec{e}_0 + \vec{e}_1^+ \|\vec{e}_1\|^{-2} \vec{e}_1 + \dots + \vec{e}_{n-1}^+ \|\vec{e}_{n-1}\|^{-2} \vec{e}_{n-1}$$

$$= \sum_{i=0}^{n-1} \vec{e}_i^+ \|\vec{e}_i\|^{-2} \vec{e}_i$$

$$\Rightarrow \boxed{\text{thus, } \vec{y}^+ R_y^{-1} \vec{y} = \sum_{i=0}^{n-1} \vec{e}_i^+ \|\vec{e}_i\|^{-2} \vec{e}_i}$$

□