

Unsupervised Hierarchical Semantic Segmentation with Multiview Cosegmentation and Clustering Transformers



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Stella X. Yu

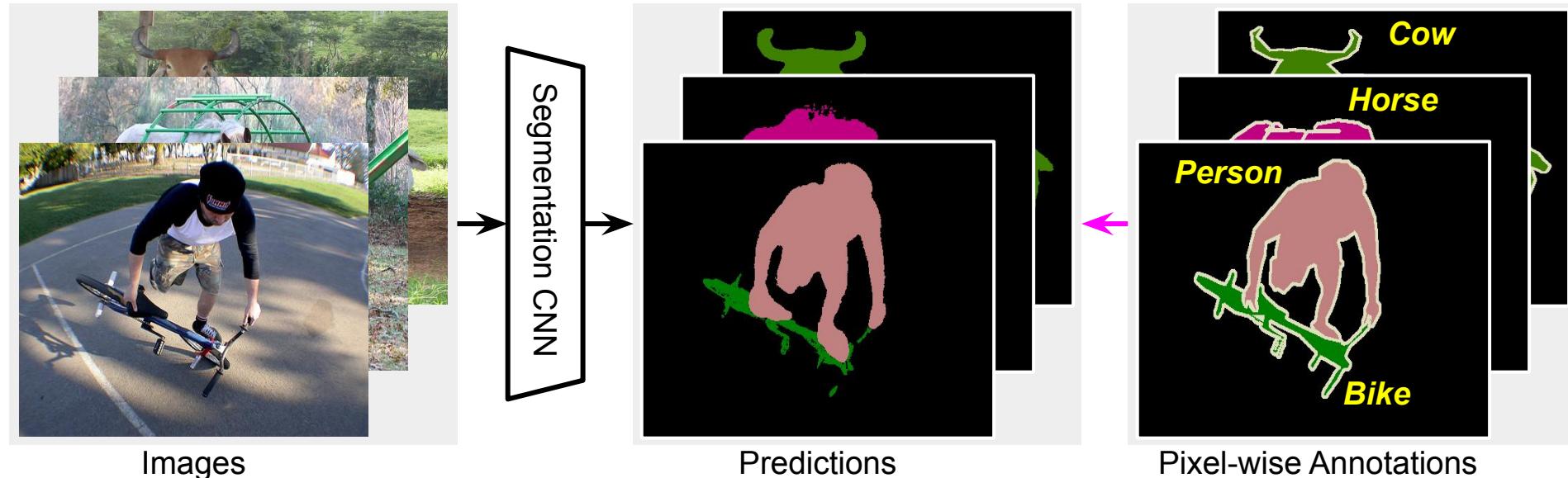


Berkeley
UNIVERSITY OF CALIFORNIA



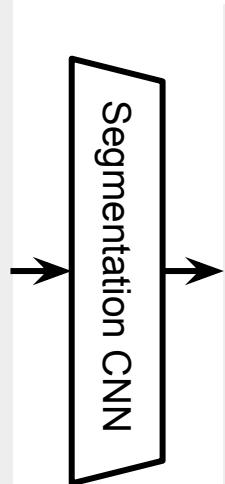
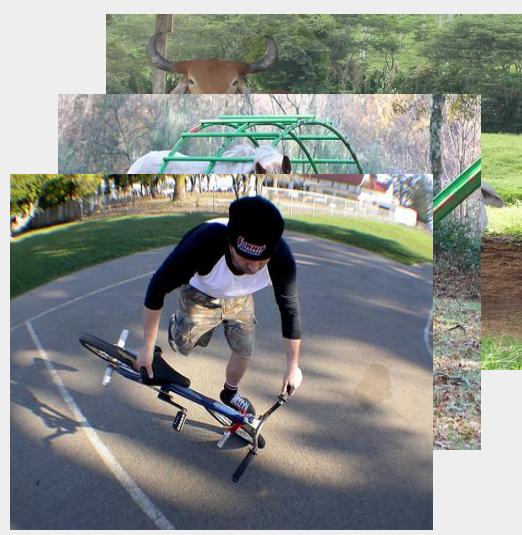
Task of Semantic Segmentation:

Put Pixels into Semantic Categories

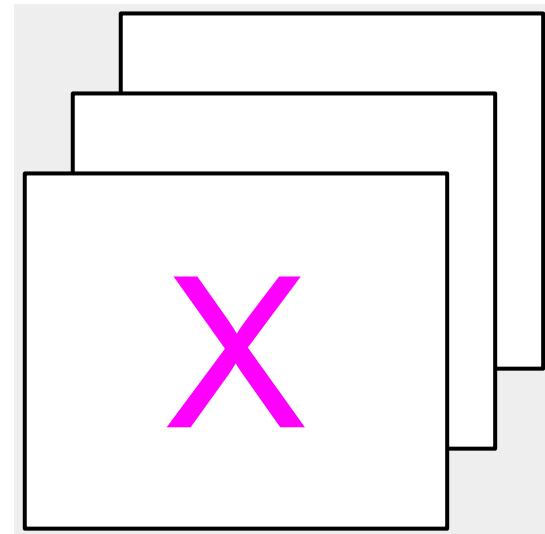


Task of Unsupervised Semantic Segmentation:

Put Pixels into Groups without Any Labeled Supervision

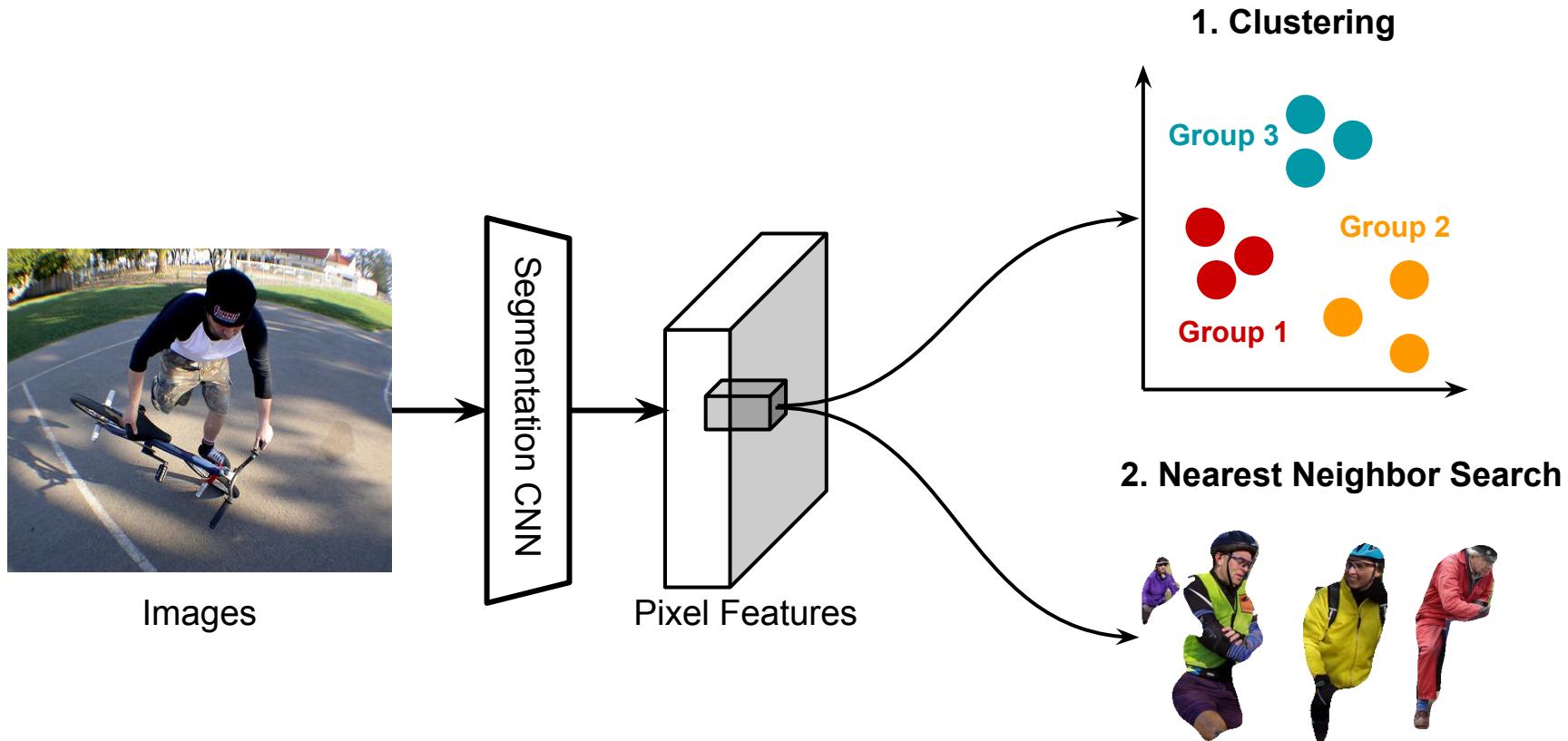


Predictions



No labeled supervision

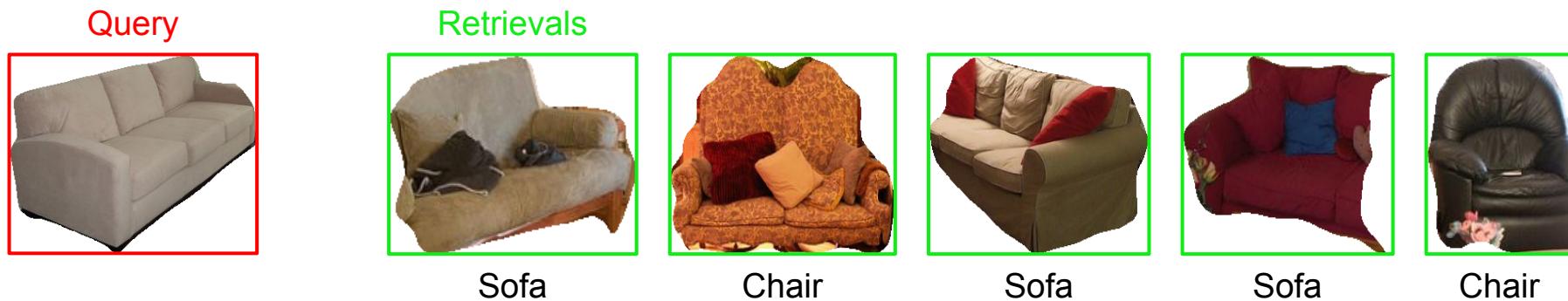
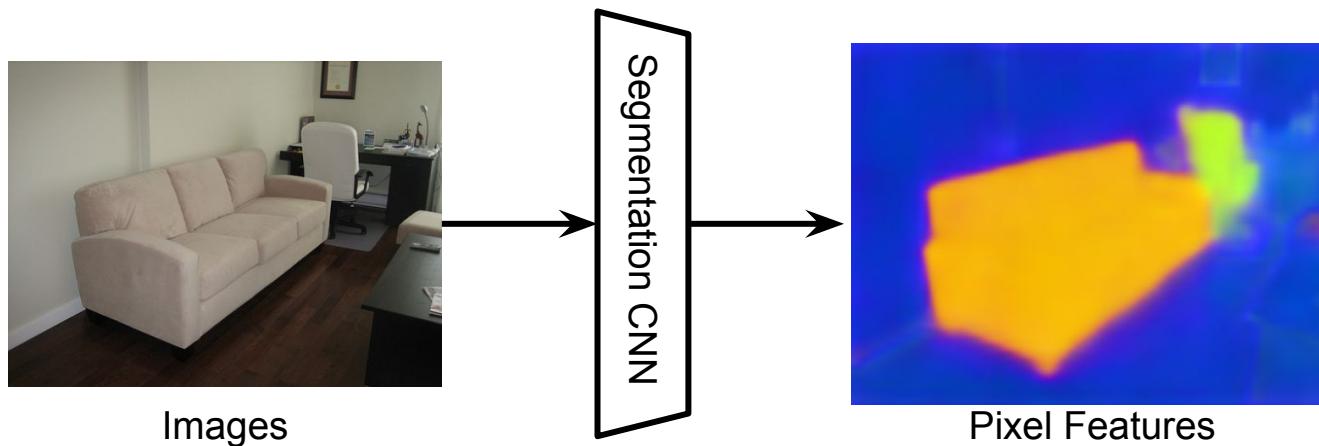
Two Approaches to Predict Pixel Labels from Groupings



1. Invariant Information Clustering for Unsupervised Image Classification and Segmentation. Ji et al. ICCV 2019.

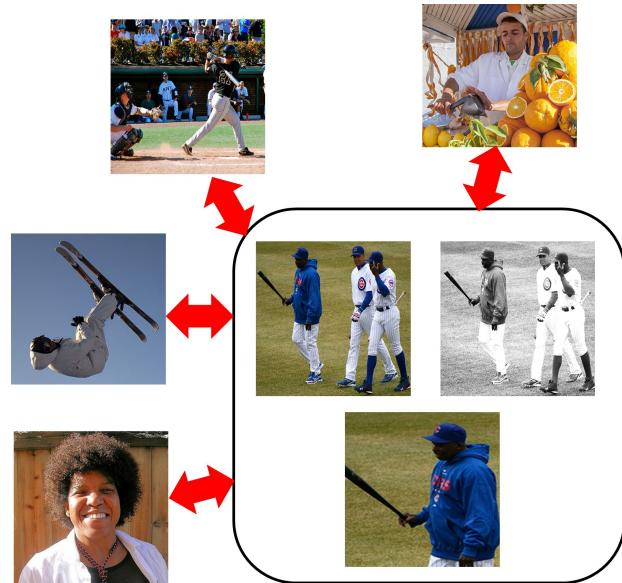
2. SegSort: Segmentation by Discriminative Sorting of Segments. Hwang et al. ICCV 2019.

Our Model by Feature Learning: Predict Labels from Retrieved Segments



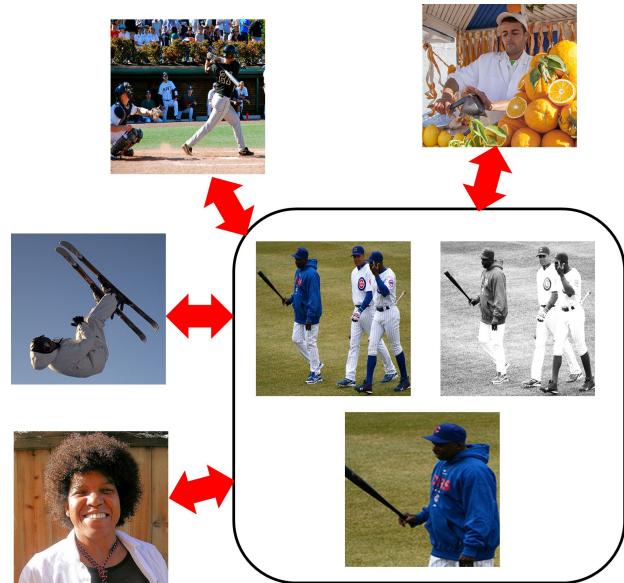
Current Feature Learning Methods: Contrast Image-Image vs. Pixel-Segment

Contrast **images** disregarding visual change

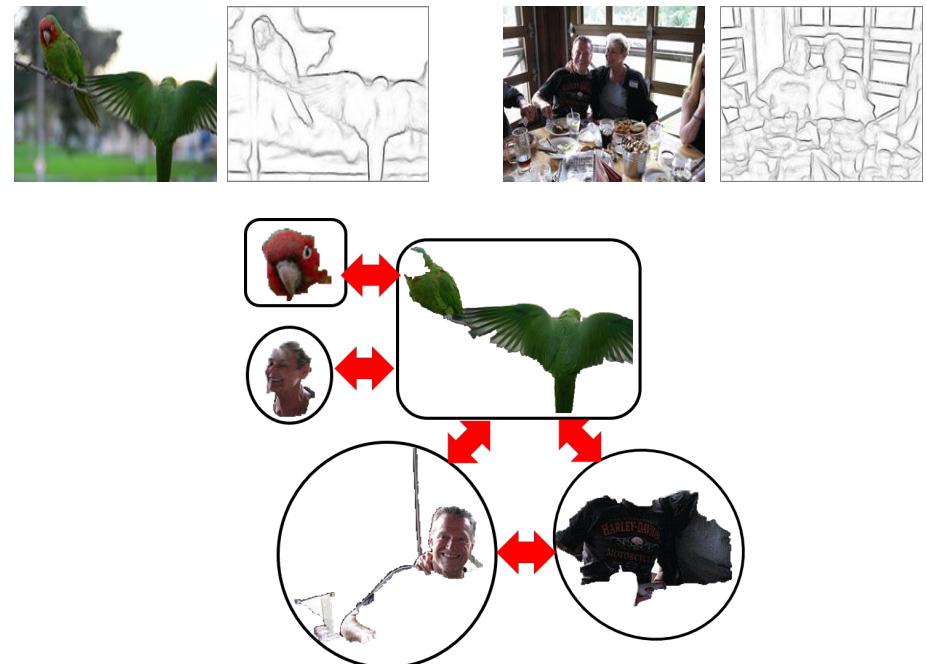


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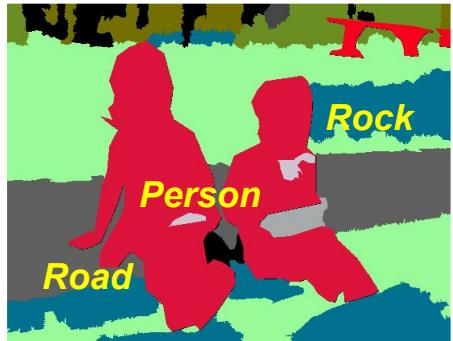
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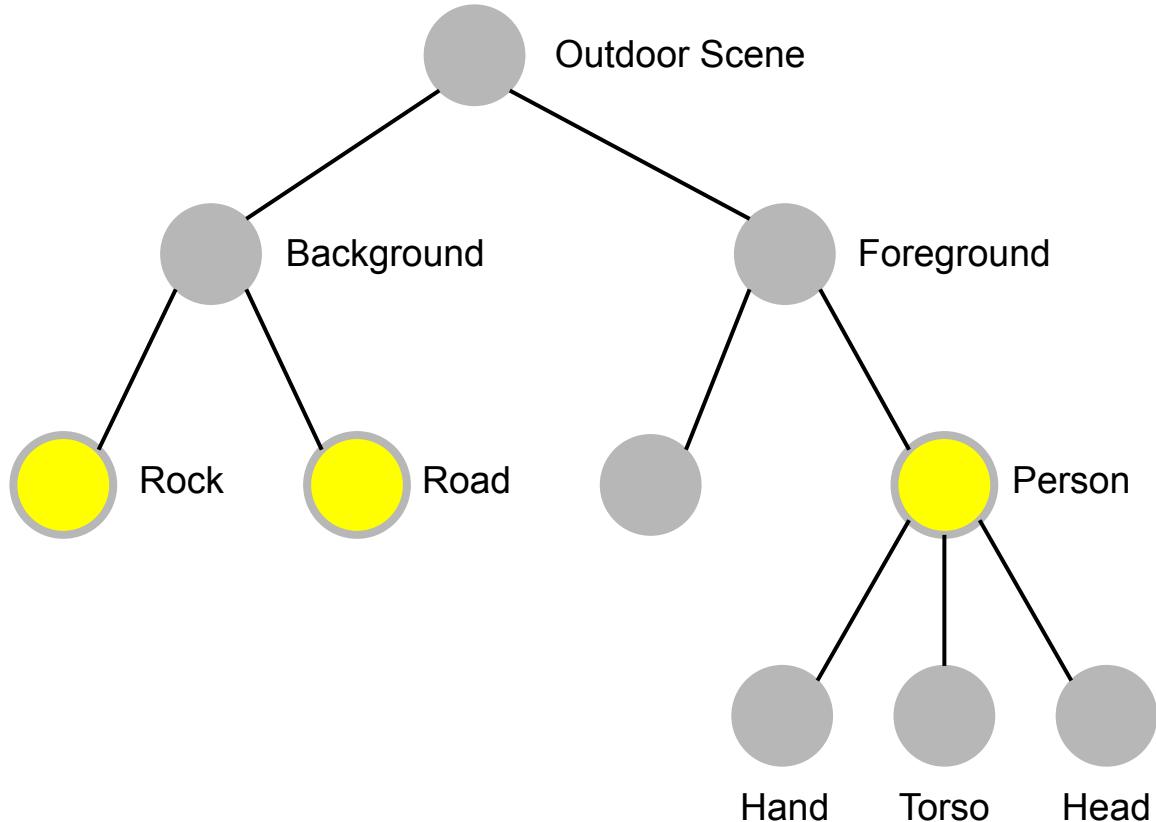
Contrast pixels with **regions** w.r.t low-level visual cues



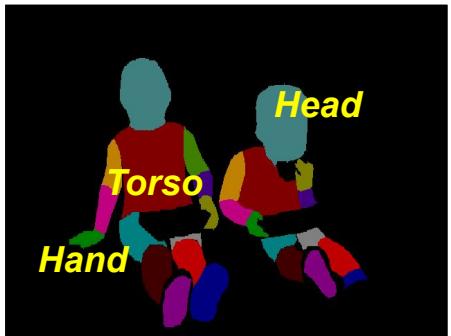
Semantics Intrinsically Has Multiple Levels of Granularity



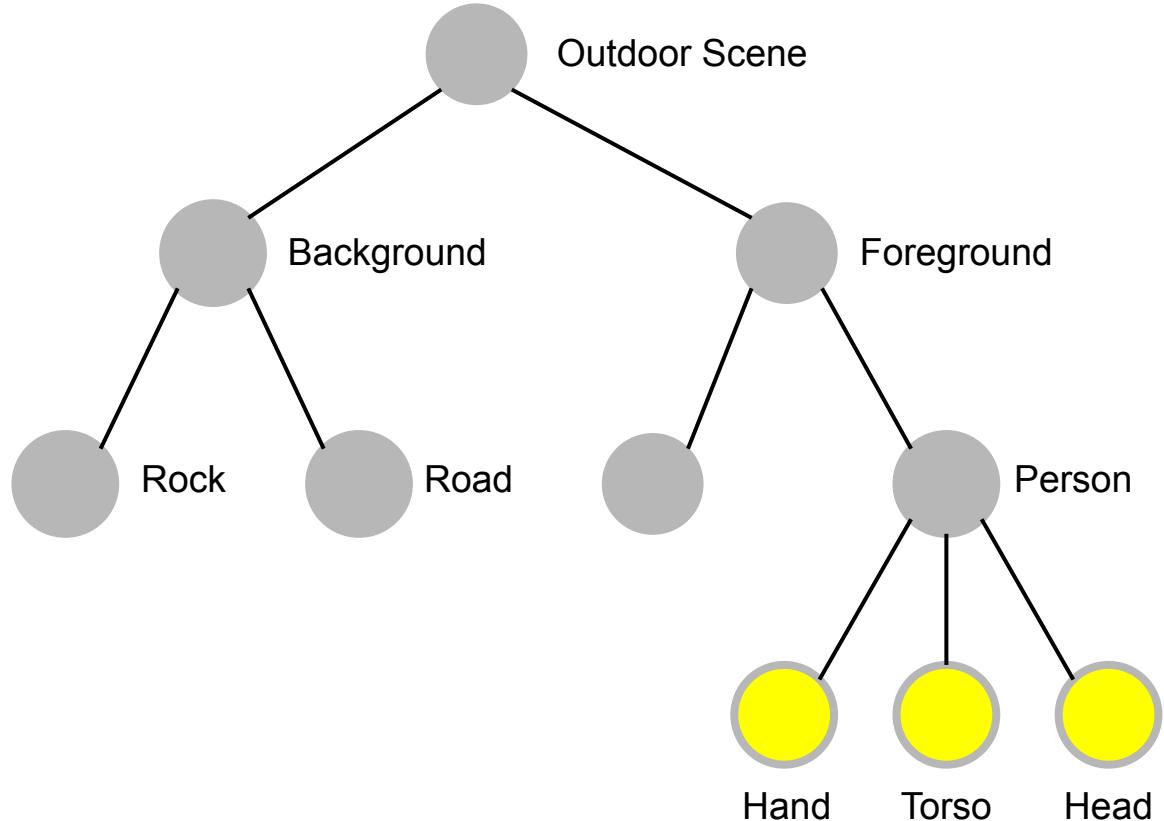
Coarse-grained Categories



Semantics Intrinsically Has Multiple Levels of Granularity

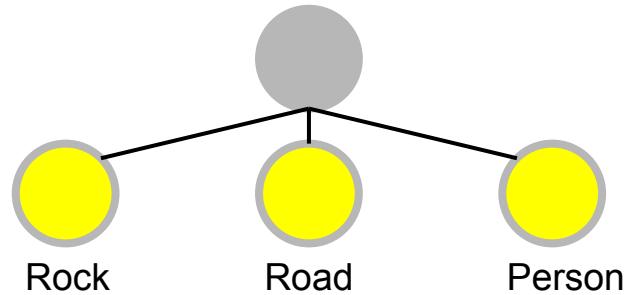


Fine-grained Categories

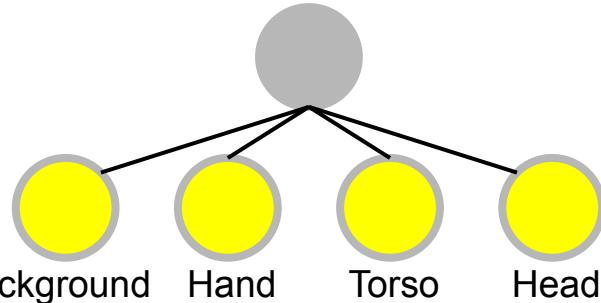


Semantics Intrinsically Has Multiple Levels of Granularity

Most existing methods:
avoid ambiguity / presume a granularity

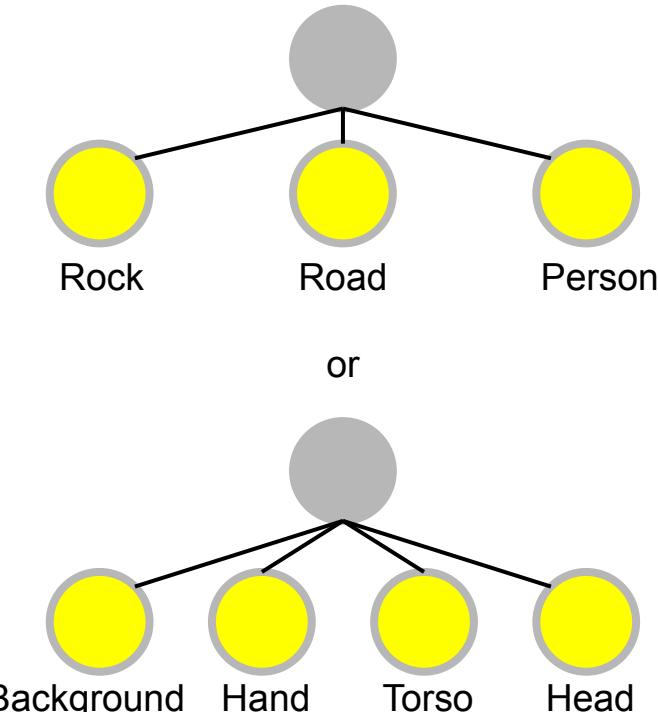


or

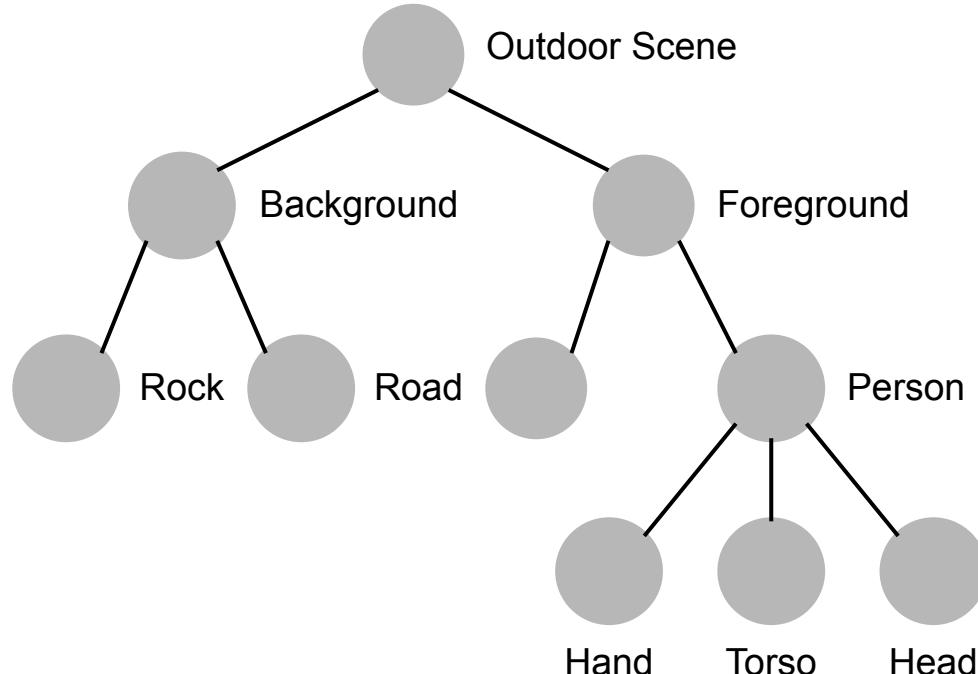


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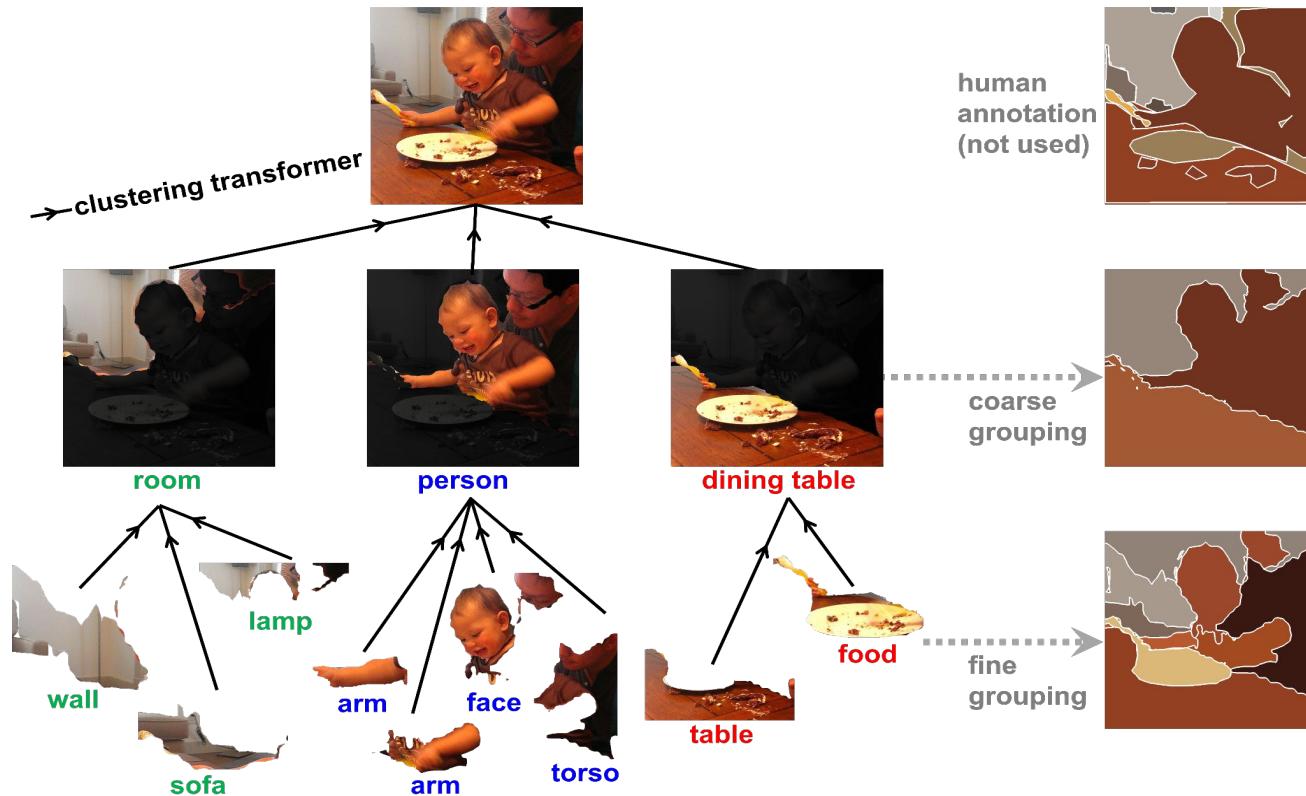
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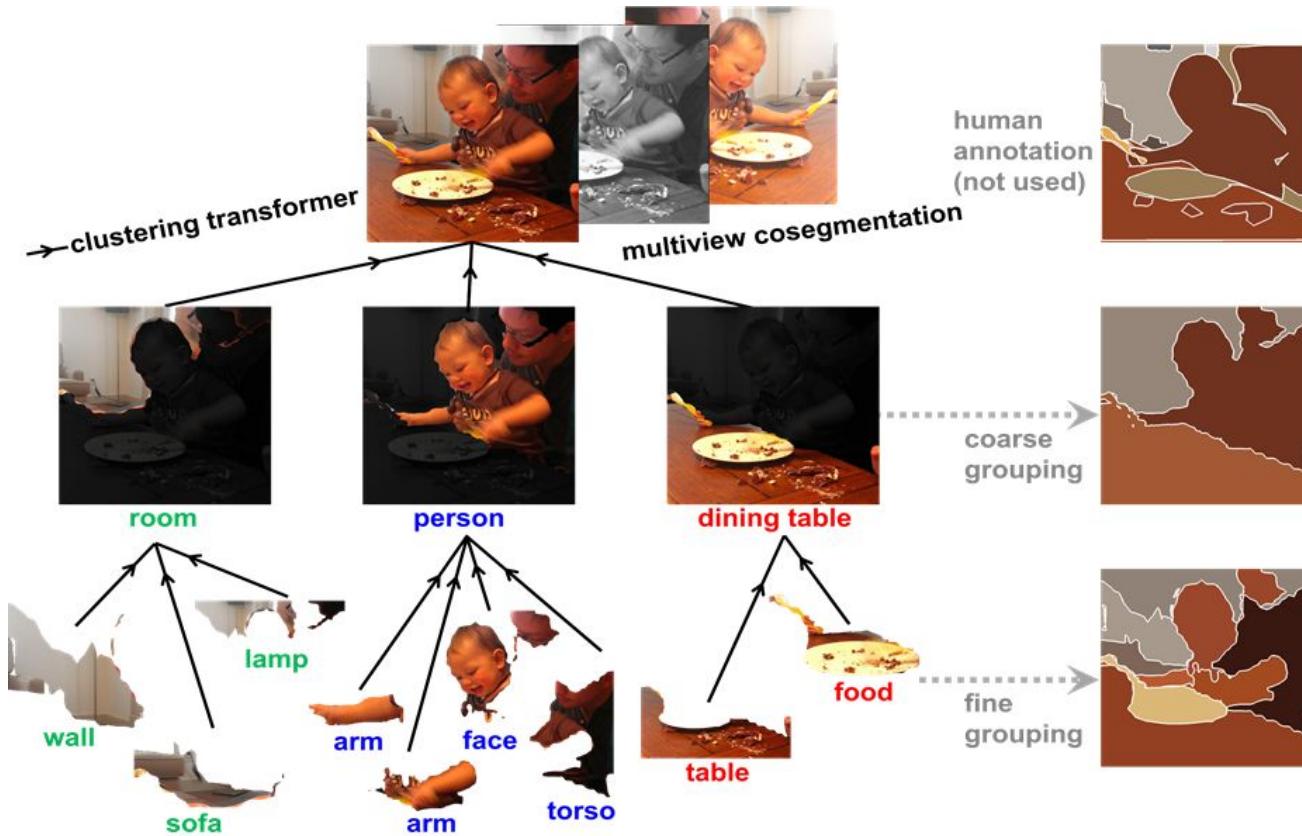
Our idea: embrace multiple levels of granularity



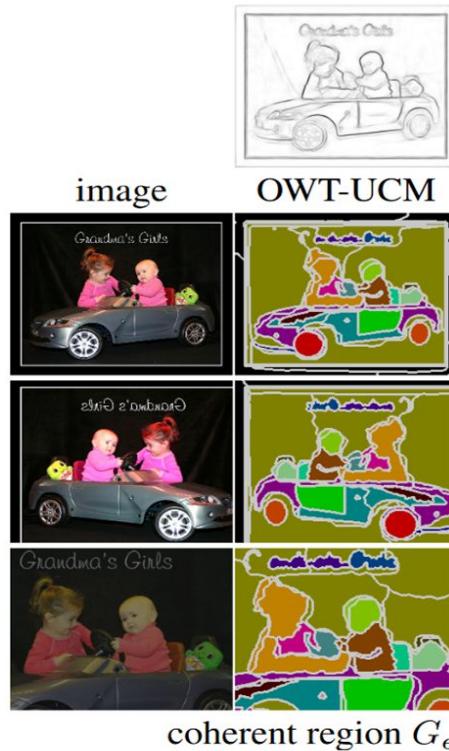
Face and Body are Parts of a Whole in the Visual Scene



Babies Appear Different but Have the Same Semantics

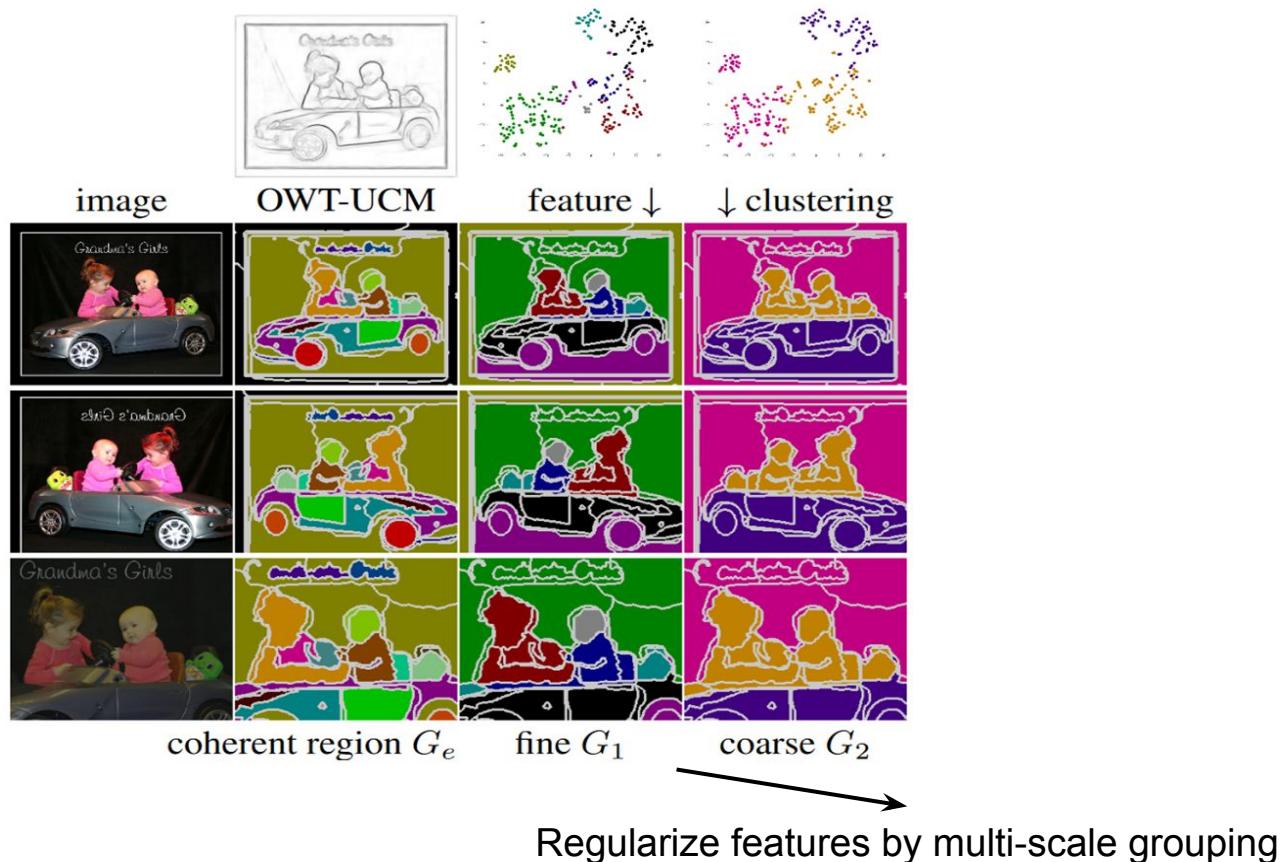


Invariance: Multiview Cosegmentation

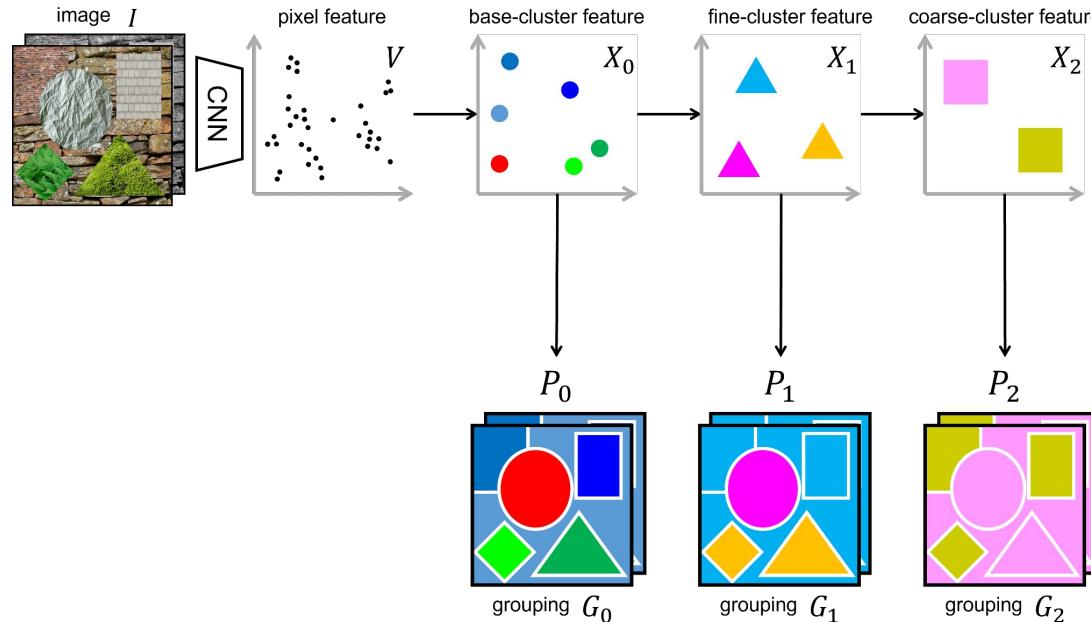


Ground features by visual appearance and correspondence

Invariance: Multiview Cosegmentation



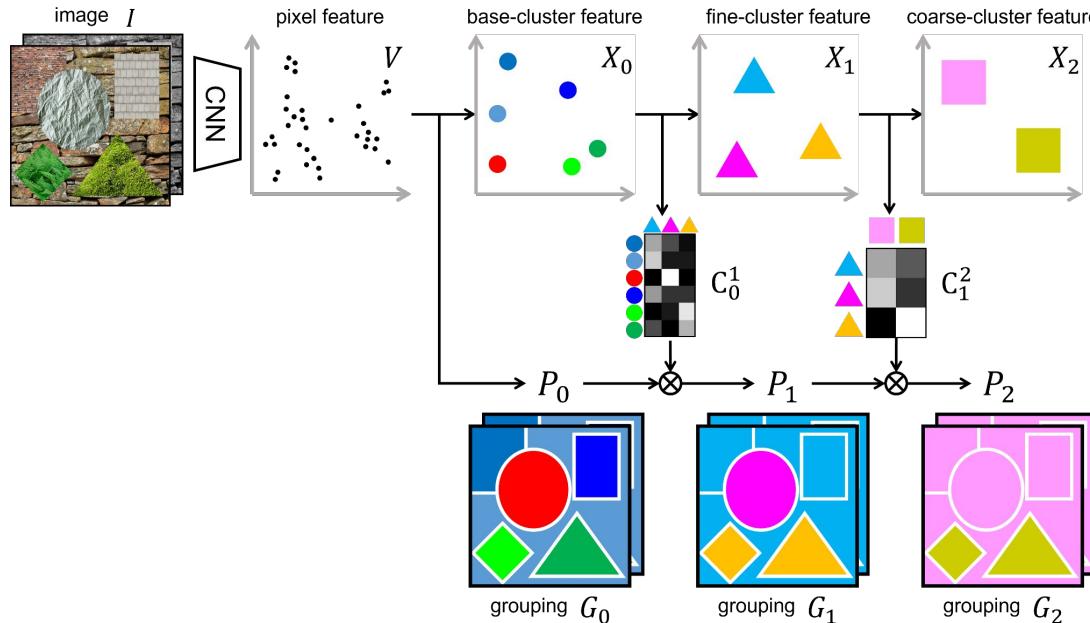
Multi-scale Grouping: Consistency is Not Guaranteed



Grouping Probability at Level l :

$$P_l(a) = \text{Prob}(G_l = a|x)$$

Multi-scale Consistency: Clustering Transformer



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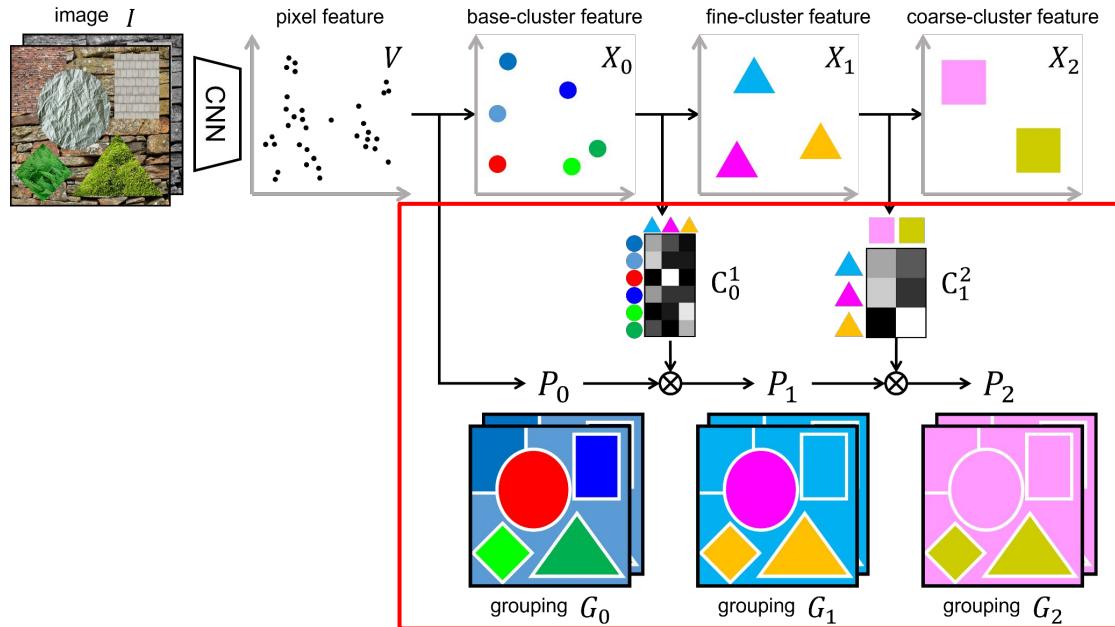
Transition Probability to Level $l+1$:

$$C_l^{l+1}(a, b) = \text{Prob}(G_{l+1} = b|G_l = a)$$

Grouping Assignment at Level $l+1$:

$$P_{l+1} = P_l \times C_l^{l+1} = P_0 \times C_0^1 \times \cdots \times C_l^{l+1}$$

Multi-scale Consistency: Clustering Transformer



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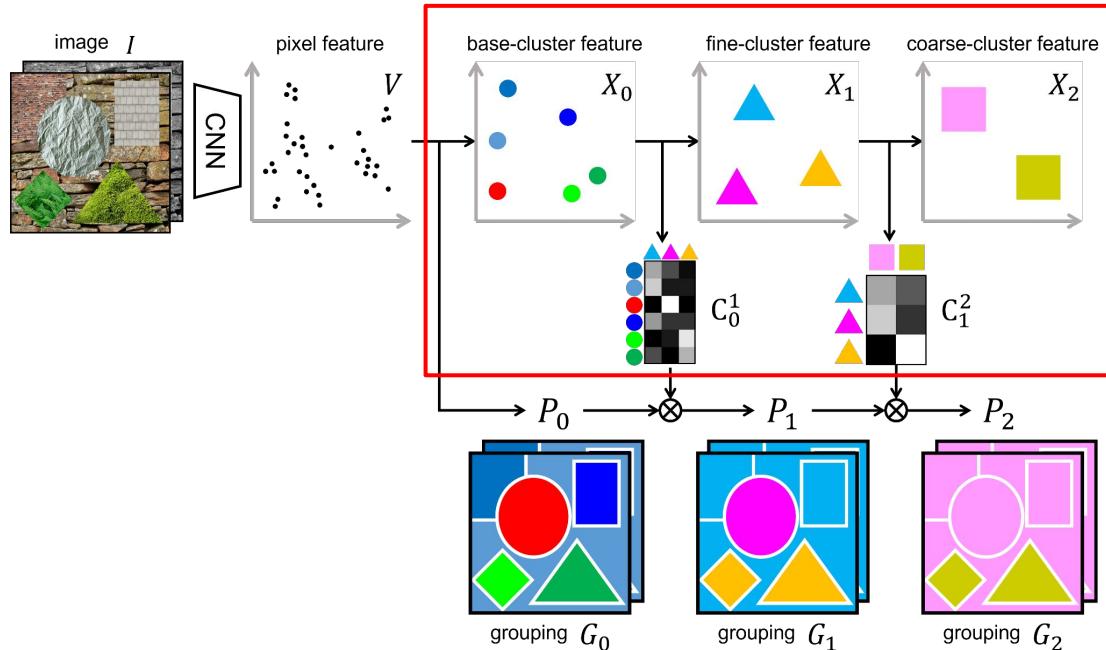
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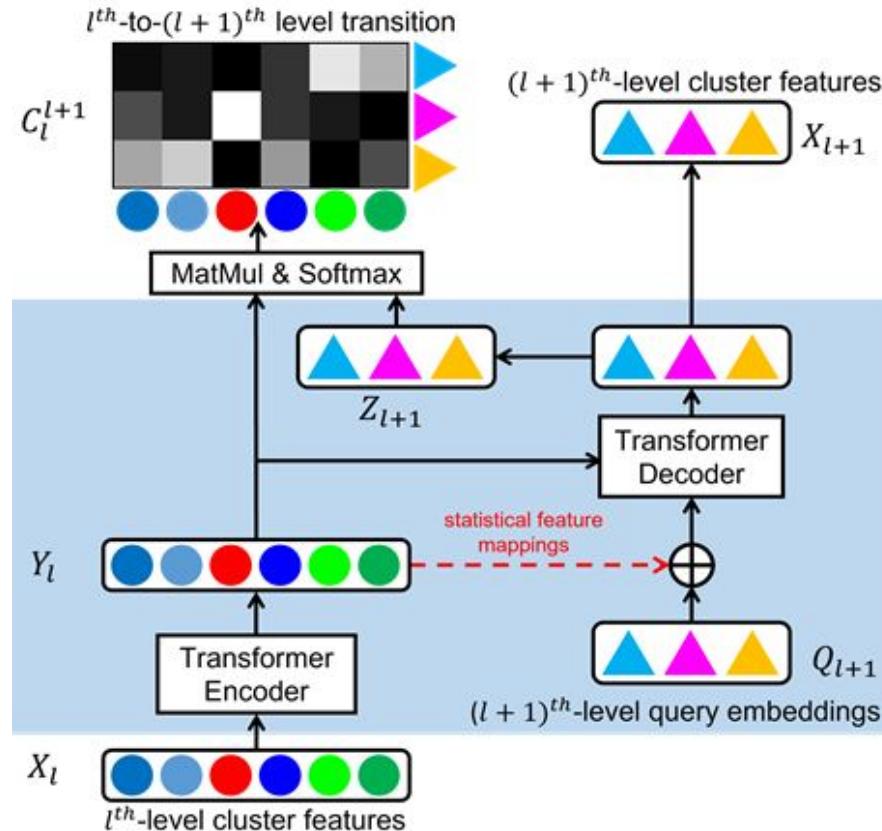
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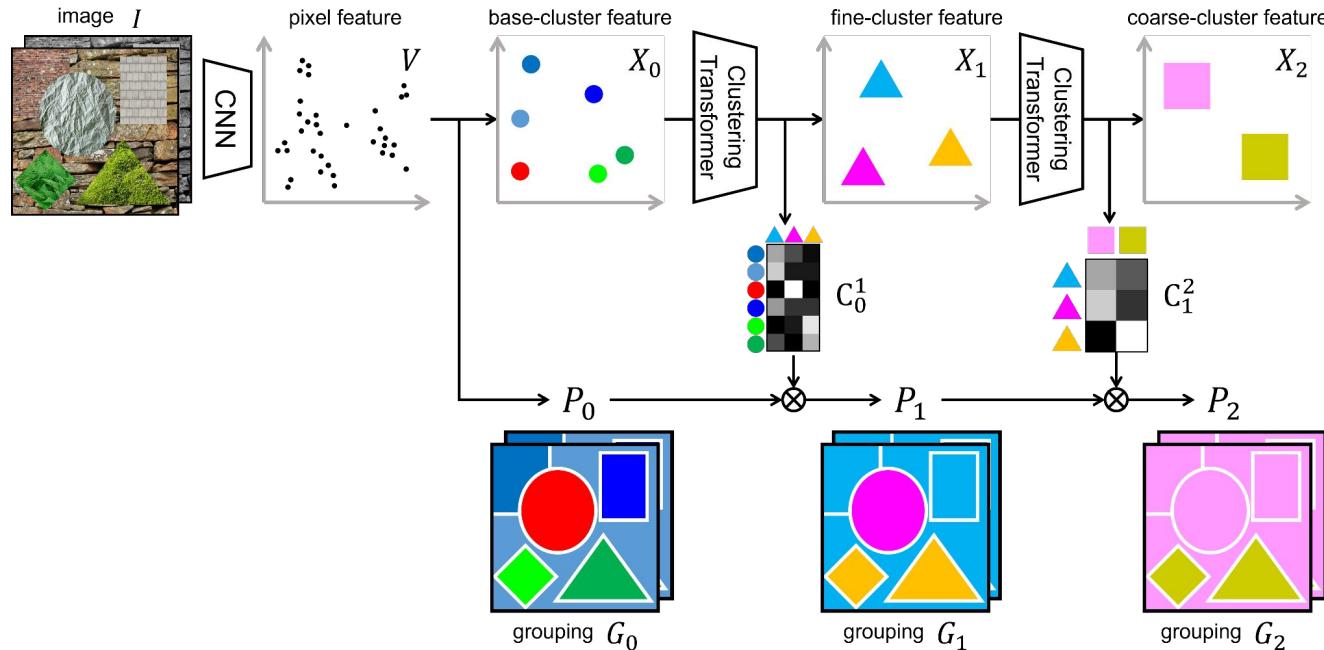
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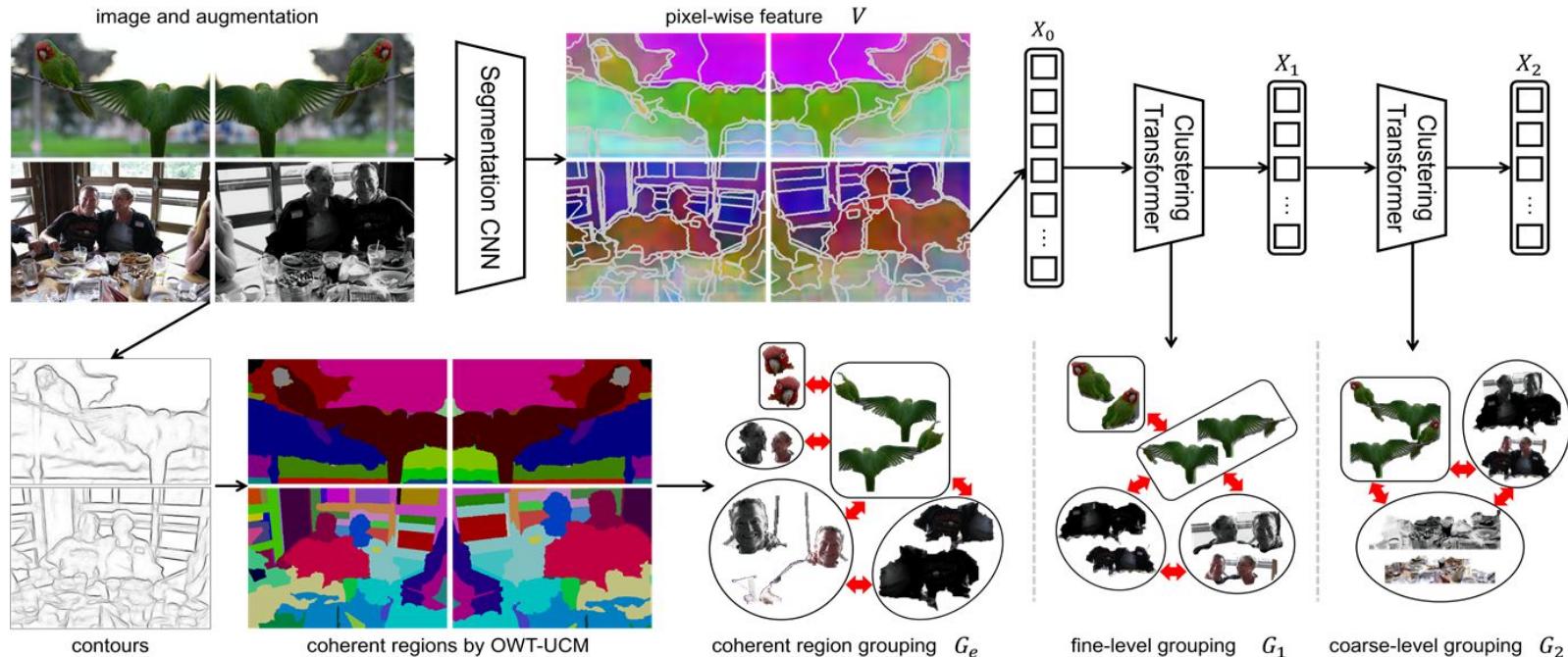
Multi-scale Consistency: Clustering Transformer



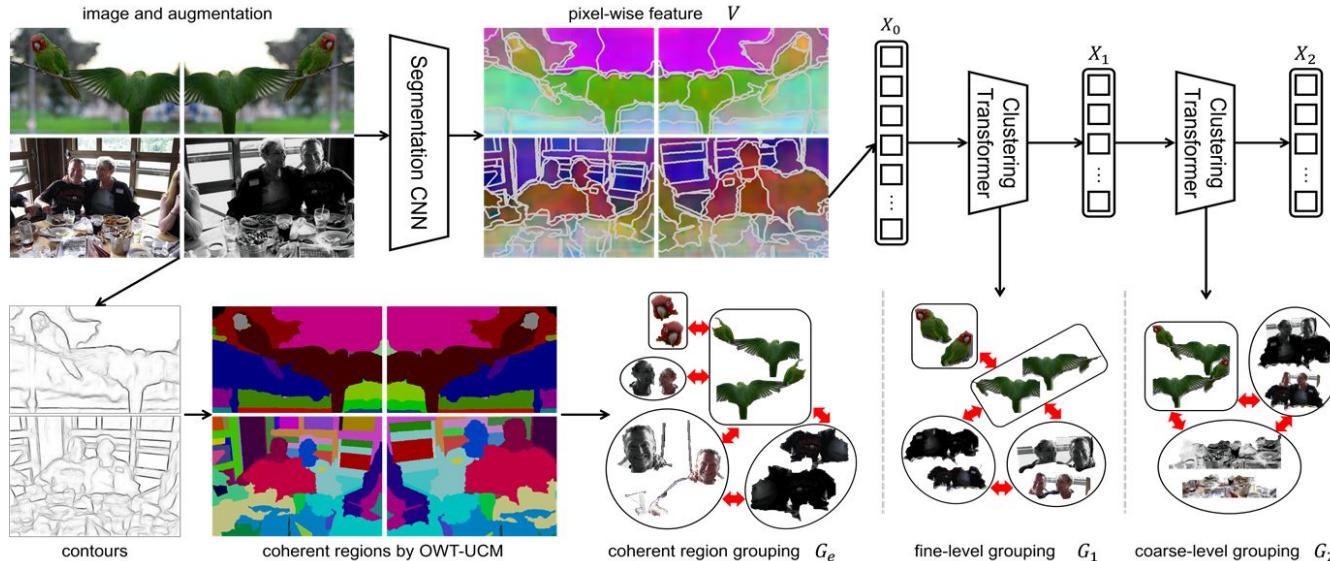
Multi-scale Consistency: Clustering Transformer



Our Hierarchical Segment Grouping Model



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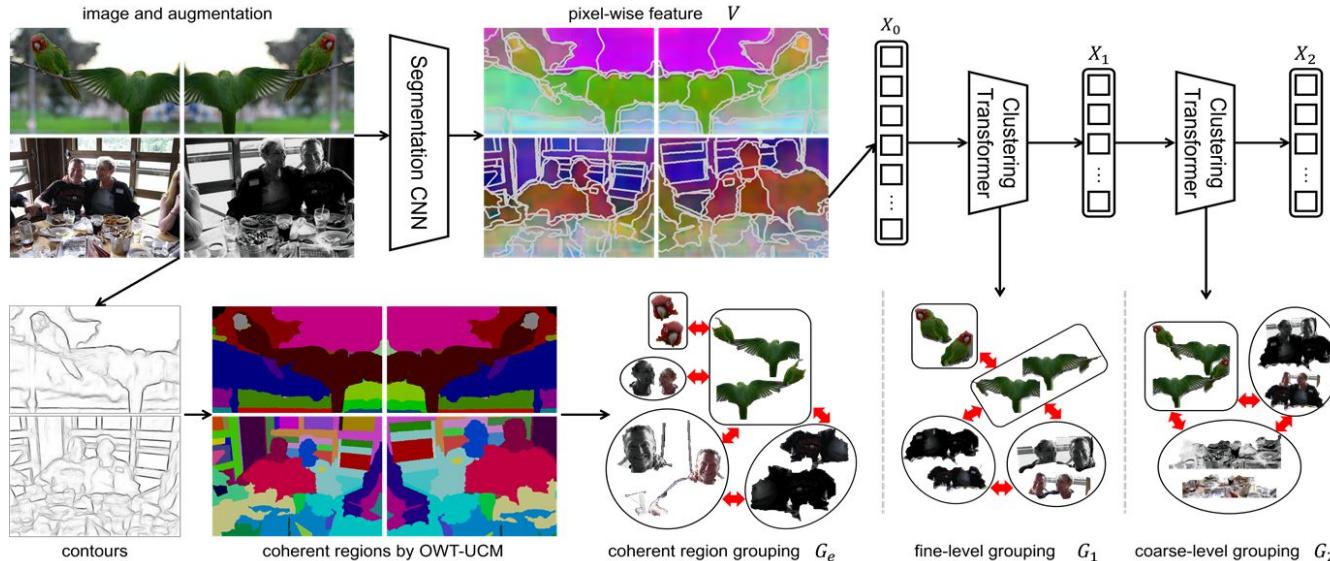


$$L(f) = \boxed{\lambda_E L_f(G_e)} + \lambda_F \sum_{l \geq 1} L_f(G_l) + \lambda_G L_g$$

Pixel-segment contrast loss:

1. Ground features by visual appearance
2. Enforce correspondence across views

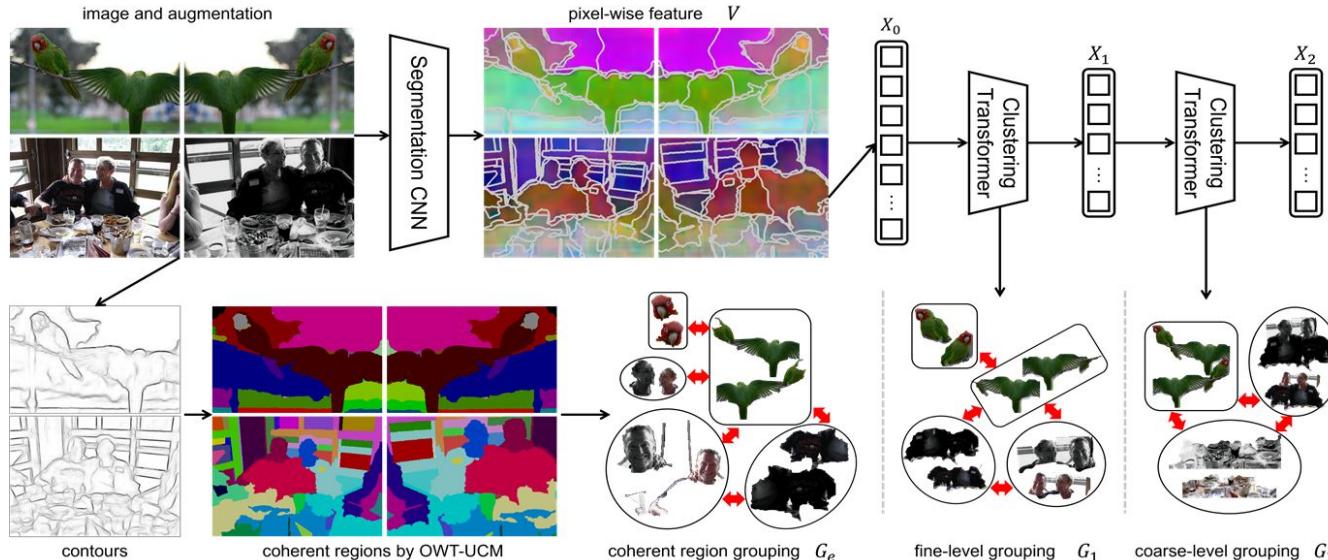
Our Hierarchical Segment Grouping Model



$$L(f) = \lambda_E L_f(G_e) + \lambda_F \sum_{l \geq 1} L_f(G_l) + \lambda_G L_g$$

Pixel-segment contrast loss:
Regularize features by consistent hierarchy

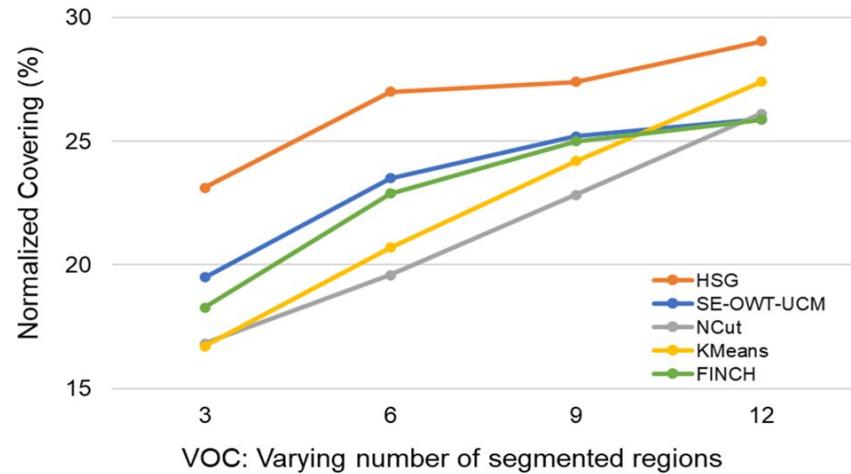
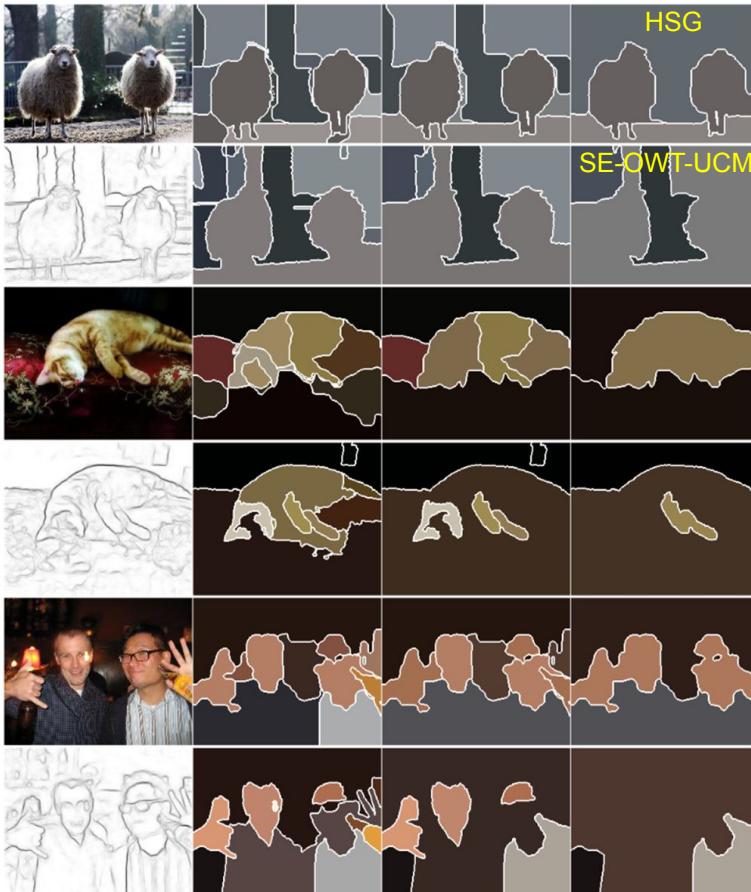
Our Hierarchical Segment Grouping Model



$$L(f) = \lambda_E L_f(G_e) + \lambda_F \sum_{l \geq 1} L_f(G_l) + \boxed{\lambda_G L_g}$$

Goodness of Grouping:
Desire balanced, compact, distinctive clusters

1. First Unsupervised Hierarchical Semantic Segmentation



$$\text{NFCovering}(S' \rightarrow S_{fg}) = \frac{1}{|S_{fg}|} \sum_{R \in S_{fg}} \max_{R' \in S'} \frac{|R \cap R'|}{|R \cup R'|}$$

2. SOTA on Unsupervised Semantic Segmentation



Training set	MSCOCO		Cityscapes		KITTI-STEP	
Validation set	VOC		Cityscapes		KITTI-STEP	
Method	mIoU	Acc.	mIoU	Acc.	mIoU	Acc.
Moco [20]	28.1	-	15.3	69.5	13.7	60.3
DenseCL [60]	35.1	-	12.7	64.2	9.3	47.6
Revisit [56]	35.1	-	17.1	71.7	17.0	65.0
SegSort [26]	11.7	75.1	24.6	81.9	19.2	69.8
Our HSG	41.9	85.7	32.5	86.0	21.7	73.8

3. Unsupervised Visual Context Retrievals across Granularity Levels



Code available at <https://github.com/twke18/HSG>

