

Remember: Next week is Fall vacation

CHAPTER 14:

GRAPHICAL MODELS

Joint probabilities

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□ Recap from chapter 3

	Oranges	Apples	Peaches	$P(Y)$
Good	0.16	0.28	0.12	0.56
Bad	0.12	0.04	0.28	0.44
$P(X)$	0.28	0.32	0.40	

sum rule

$$p(X) = \sum_Y p(X, Y)$$

product rule

$$p(X, Y) = p(Y|X)p(X)$$

Joint probabilities

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□ Bayes' rule

$$\begin{aligned} P(Y|X) &= \frac{P(X, Y)}{P(X)} \\ &= \frac{P(X|Y)P(Y)}{P(X)} \\ &= \frac{P(X|Y)P(Y)}{\sum_Y P(X|Y)P(Y)} \end{aligned}$$

Graphical Models

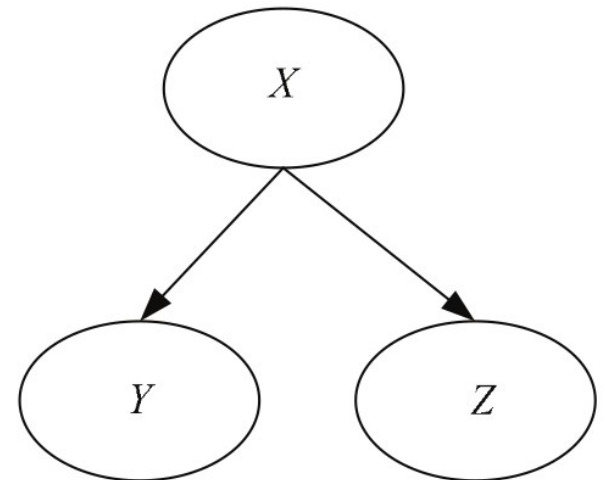
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- Aka Bayesian networks, probabilistic graphical models, probabilistic networks
- A graphical representation of joint probability distributions
 - Influences
 - Independences

Graphical Models

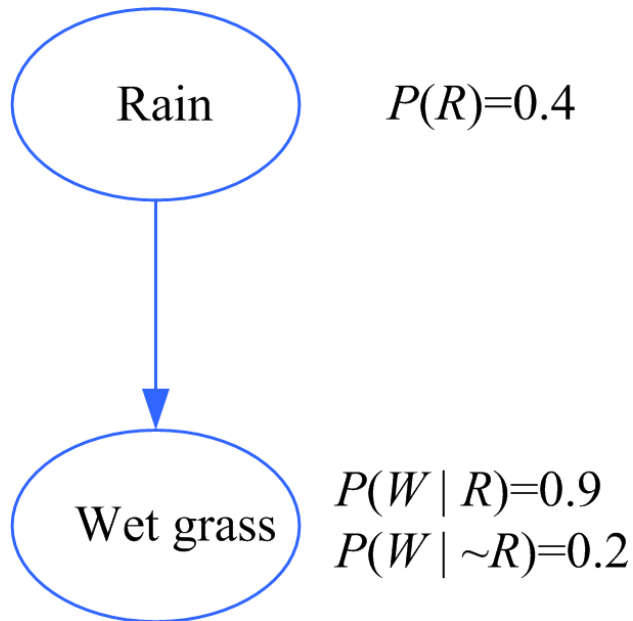
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- Nodes are random variables
- Arcs (edges) are direct influences between variables
- The structure is a directed acyclic graph (DAG)
- The parameters are the probability distributions



Simple example

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Two random variables:

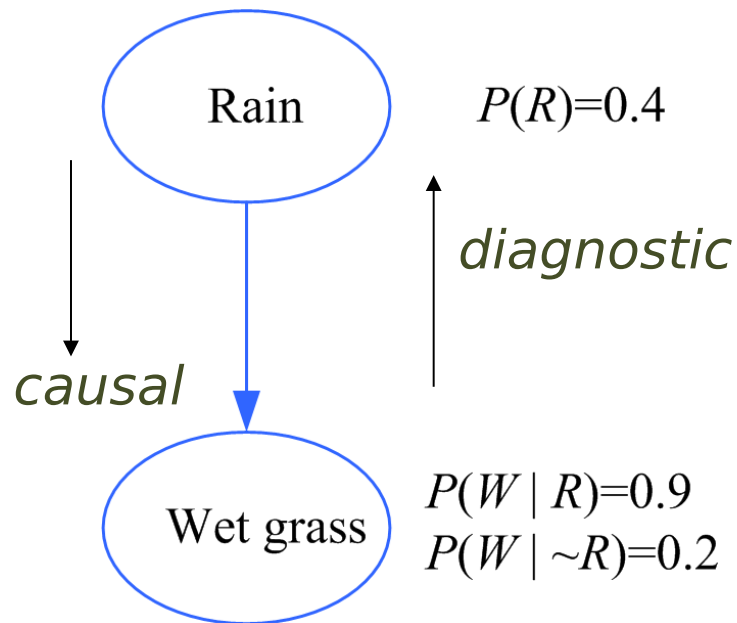
- *R : did it **Rain** last night?*
 - *W : is the grass **Wet**?*
- R “causes” W*

$$P(W,R) = P(W|R)P(R)$$

Note: the notation for binary variables in this chapter uses:
 $P(R)$ to mean $P(\text{Rain}=\text{True})$
 $P(\sim R)$ to mean $P(\text{Rain}=\text{False})$

Simple example

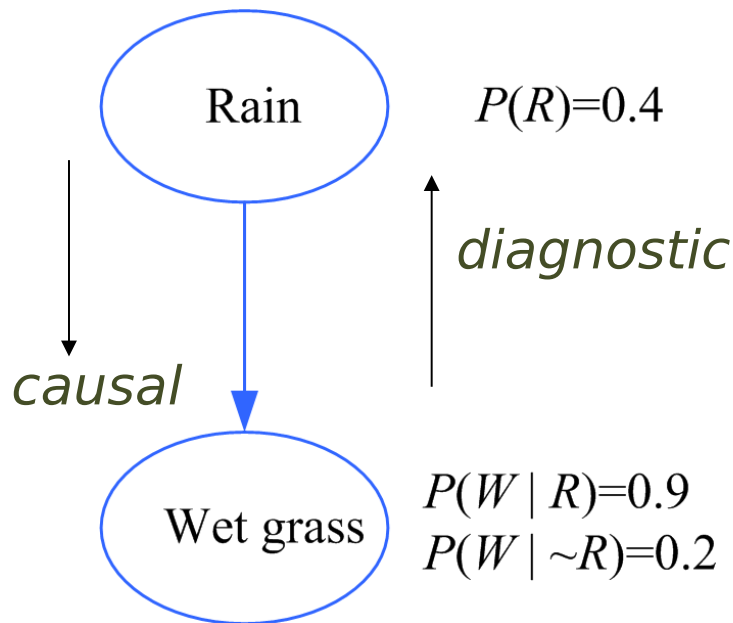
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*Diagnostic inference:
Knowing that the grass is wet,
what is the probability that rain is
the cause?*

Causes and Bayes' Rule

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*Diagnostic inference:
Knowing that the grass is wet,
what is the probability that rain is
the cause?*

$$\begin{aligned} P(R | W) &= \frac{P(W | R)P(R)}{P(W)} \\ &= \frac{P(W | R)P(R)}{P(W | R)P(R) + P(W | \sim R)P(\sim R)} \\ &= \frac{0.9 \times 0.4}{0.9 \times 0.4 + 0.2 \times 0.6} = 0.75 \end{aligned}$$

Conditional Independence

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- X and Y are independent if

$$P(X, Y) = P(X)P(Y)$$

Conditional Independence

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- X and Y are independent if

$$P(X, Y) = P(X)P(Y)$$

- X and Y are conditionally independent given Z if

$$P(X, Y|Z) = P(X|Z)P(Y|Z)$$

or

$$P(X|Y, Z) = P(X|Z)$$

Conditional Independence

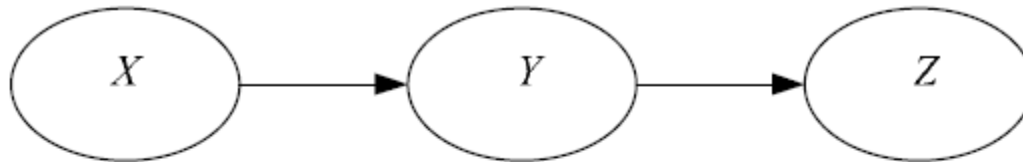
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- Graphical models show joint probability distributions
- Dependence and conditional independence can be seen directly from subgraphs of the model
- Three canonical cases: Head-to-tail, Tail-to-tail, head-to-head

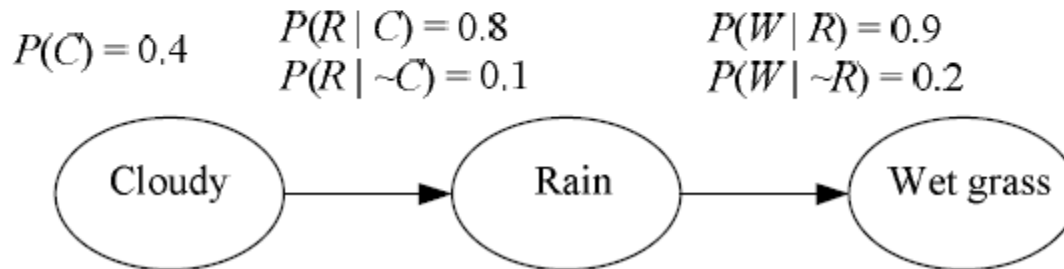
Case 1: Head-to-Head

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□ $P(X,Y,Z)=P(X)P(Y|X)P(Z|Y)$



(a) Model

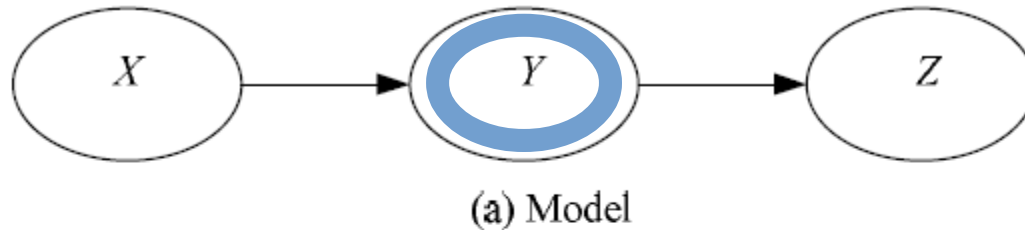


□ $P(W|C)=P(W|R)P(R|C)+P(W|\sim R)P(\sim R|C)$

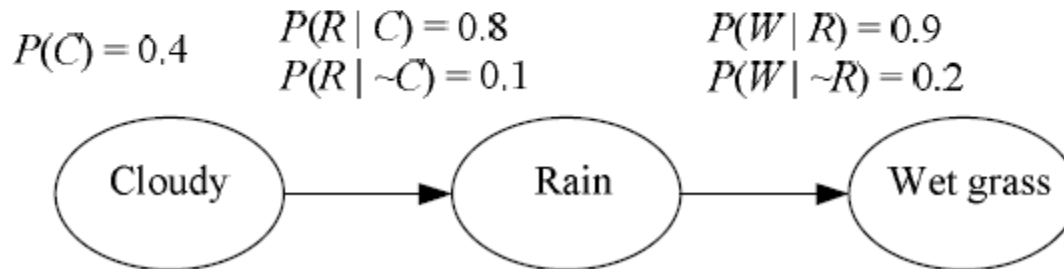
Case 1: Head-to-Head

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□ $P(X, Y, Z) = P(X)P(Y|X)P(Z|Y)$



Observing Y
blocks the path
between X and Z :
Makes X and Z
independent

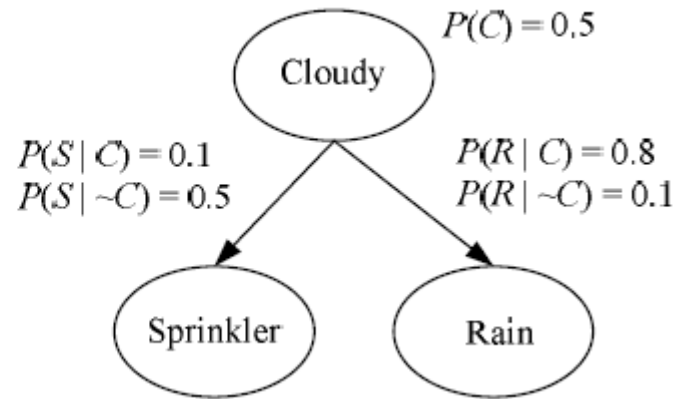
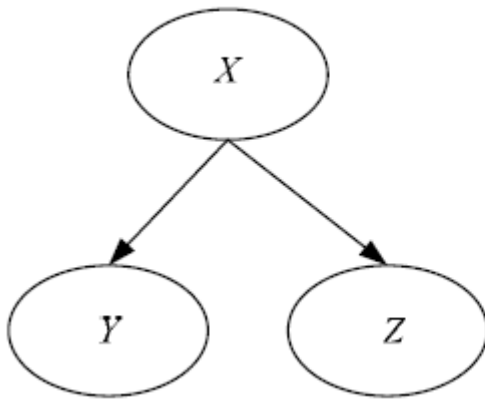


□ $P(W|C) = P(W|R)P(R|C) + P(W|\sim R)P(\sim R|C)$

Case 2: Tail-to-Tail

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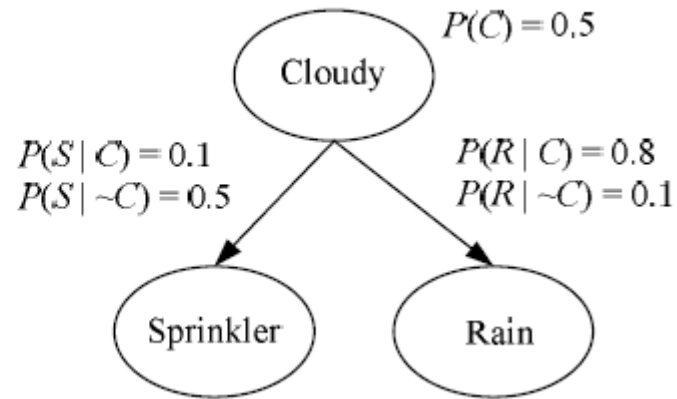
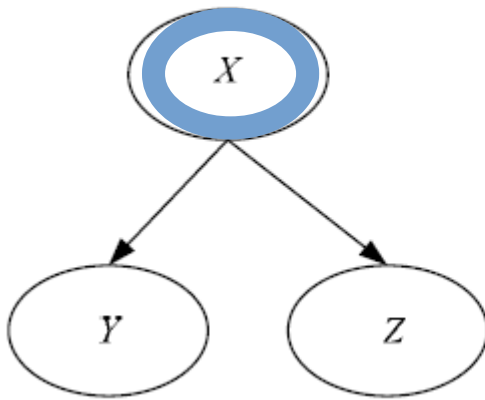
□ $P(X, Y, Z) = P(X)P(Y|X)P(Z|X)$



Case 2: Tail-to-Tail

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□ $P(X, Y, Z) = P(X)P(Y|X)P(Z|X)$

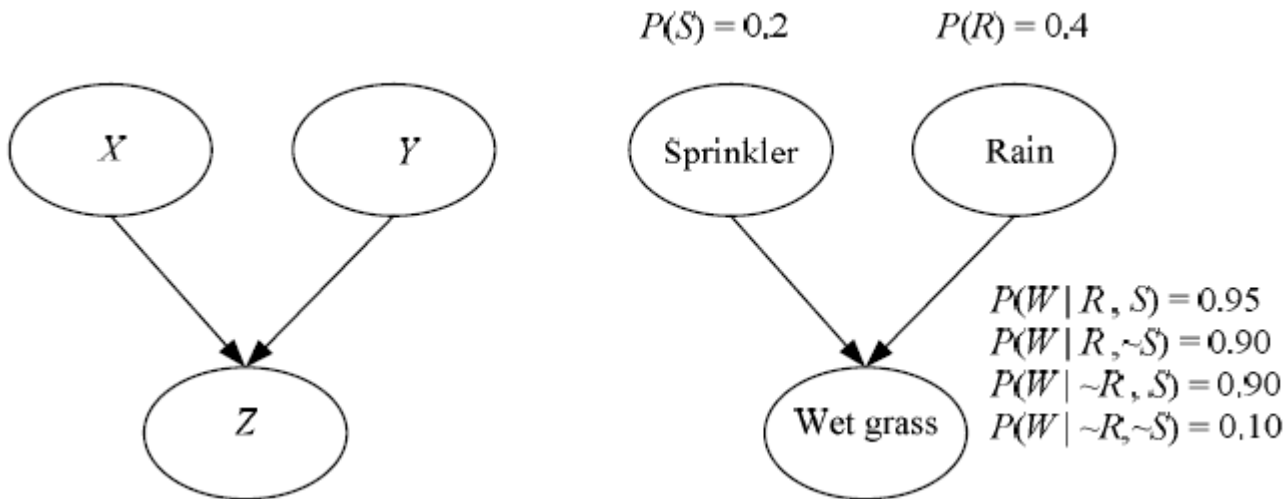


Observing X
makes Y and Z
independent

Case 3: Head-to-Head

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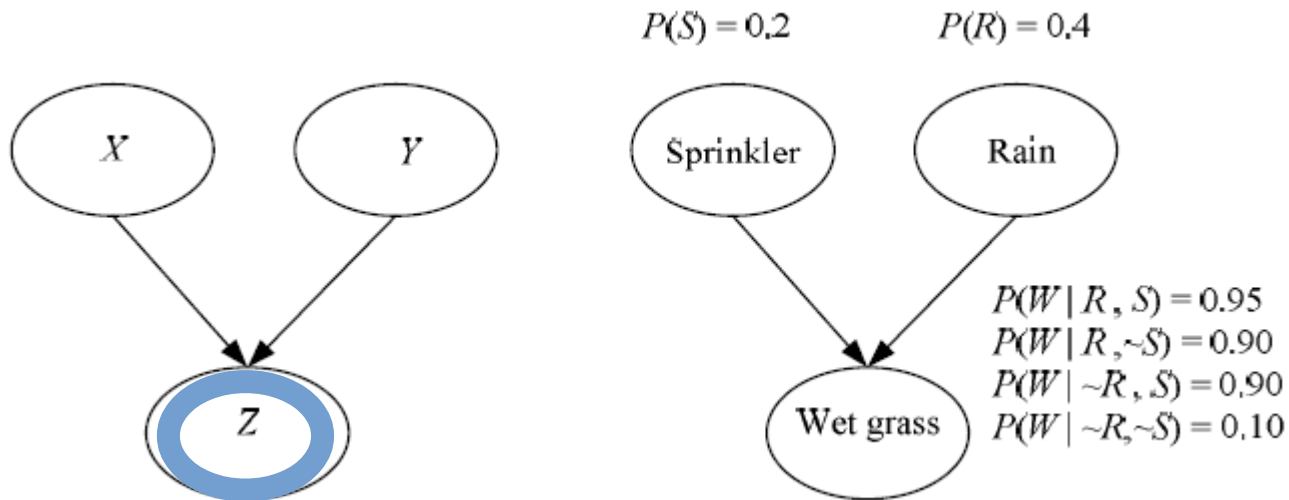
□ $P(X, Y, Z) = P(X)P(Y)P(Z|X, Y)$



Case 3: Head-to-Head

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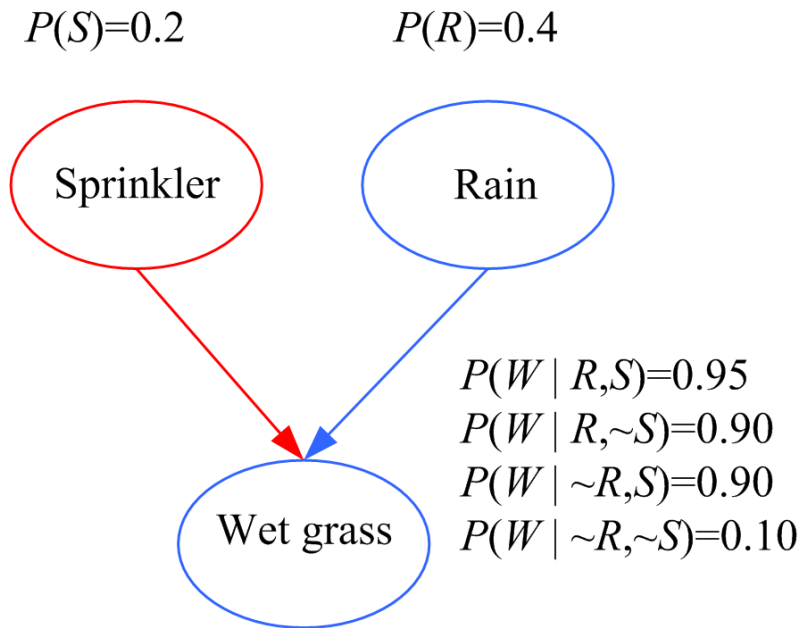
□ $P(X, Y, Z) = P(X)P(Y)P(Z|X, Y)$



X and Y are independent if Z is NOT observed!

Causal vs Diagnostic Inference

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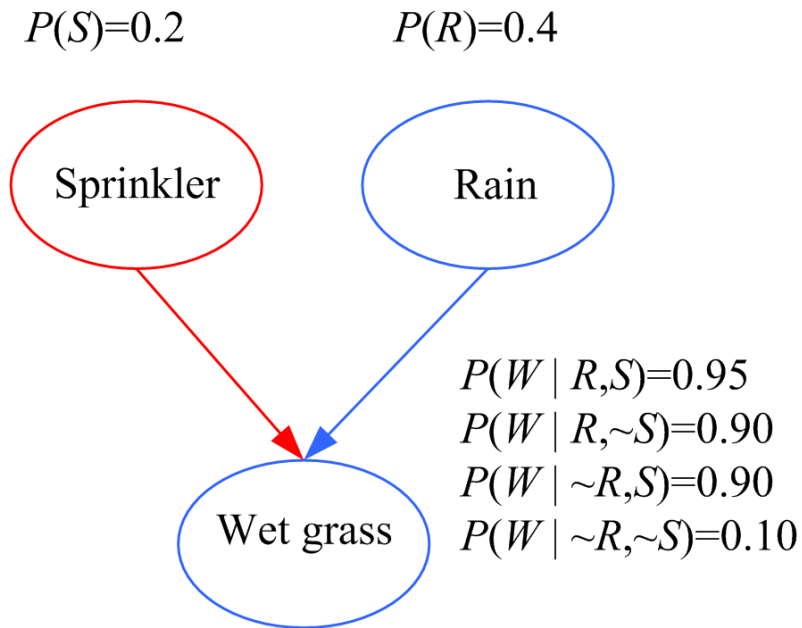


Causal inference: If the sprinkler is on, what is the probability that the grass is wet?

$$\begin{aligned} P(W|S) &= P(W|R,S) P(R|S) + \\ &\quad P(W|\sim R,S) P(\sim R|S) \\ &= P(W|R,S) P(R) + \\ &\quad P(W|\sim R,S) P(\sim R) \\ &= 0.95 \cdot 0.4 + 0.9 \cdot 0.6 = 0.92 \end{aligned}$$

Causal vs Diagnostic Inference

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Causal inference: If the sprinkler is on, what is the probability that the grass is wet?

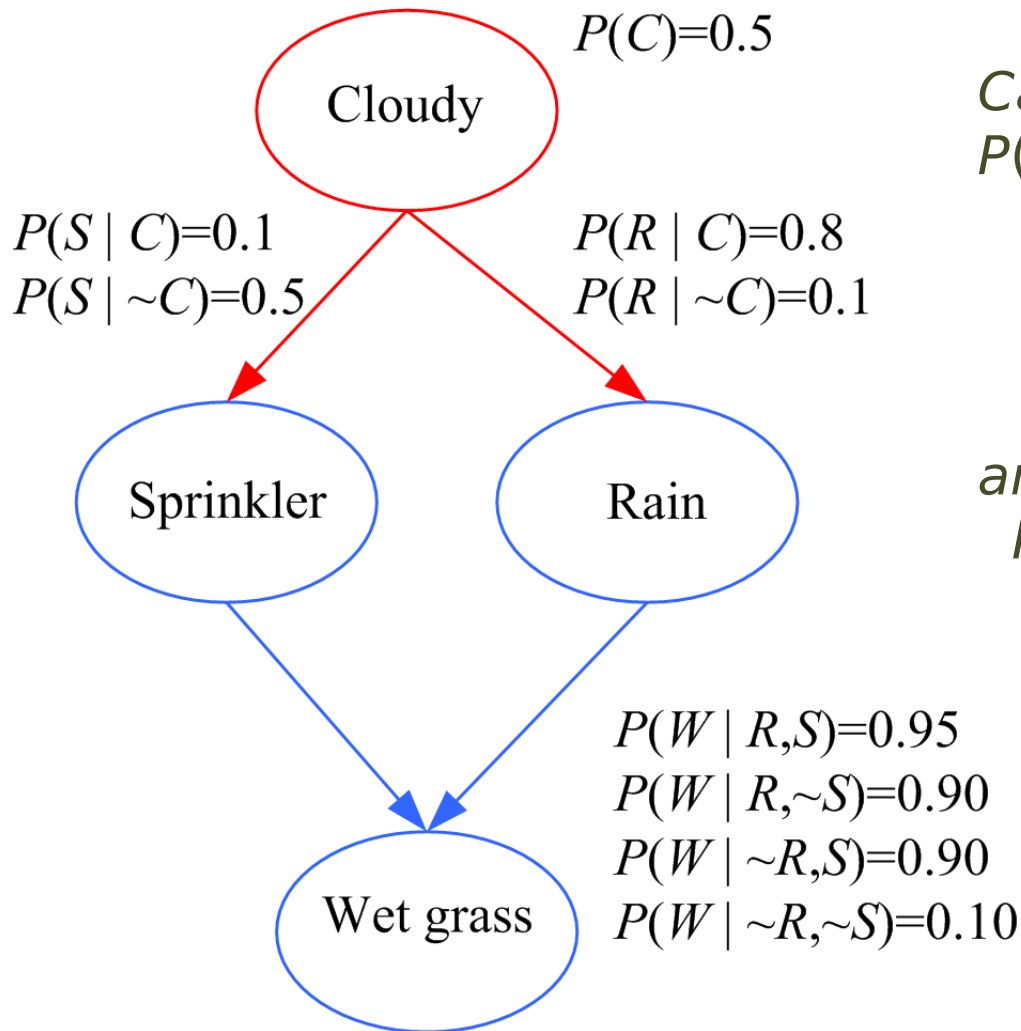
$$\begin{aligned} P(W|S) &= P(W|R,S) P(R|S) + P(W|\sim R,S) P(\sim R|S) \\ &= P(W|R,S) P(R) + P(W|\sim R,S) P(\sim R) \\ &= 0.95 \cdot 0.4 + 0.9 \cdot 0.6 = 0.92 \end{aligned}$$

Diagnostic inference: If the grass is wet, what is the probability that the sprinkler is on? $P(S|W) = 0.35 > 0.2 P(S)$

$P(S|R,W) = 0.21$ *Explaining away: Knowing that it has rained decreases the probability that the sprinkler is on.*

Combining graphs

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Causal inference:

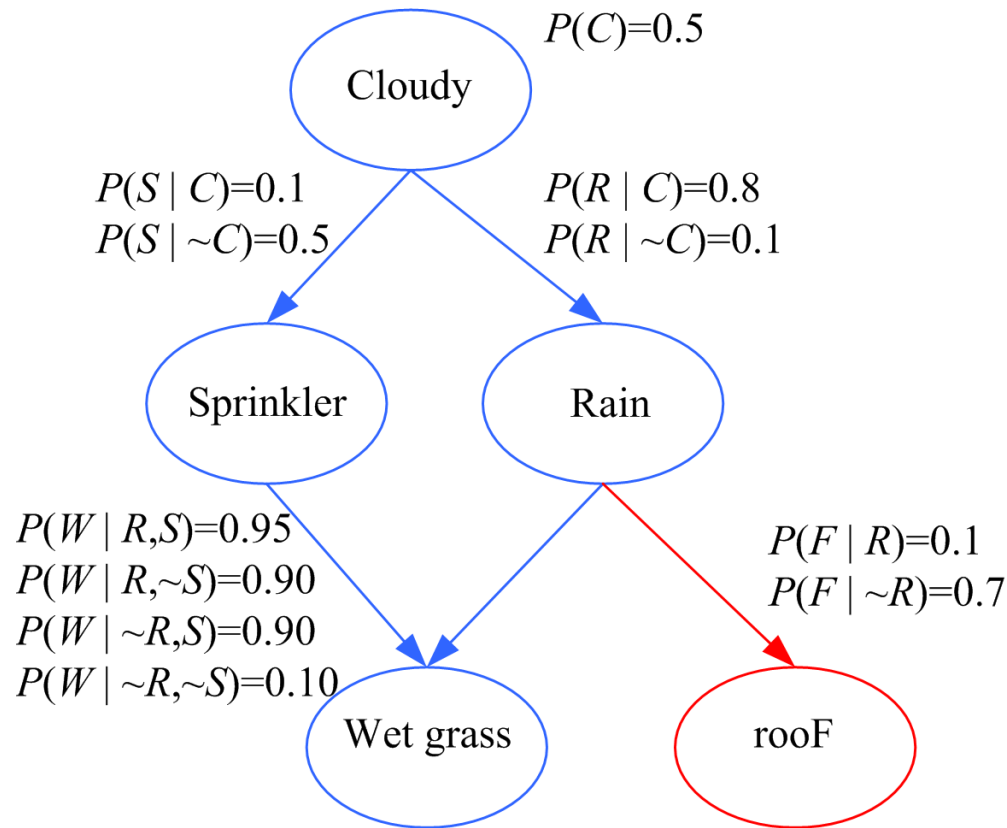
$$P(W|C) = P(W|R,S) P(R,S|C) + P(W|\sim R,S) P(\sim R,S|C) + P(W|R,\sim S) P(R,\sim S|C) + P(W|\sim R,\sim S) P(\sim R,\sim S|C)$$

and use the fact that

$$P(R,S|C) = P(R|C) P(S|C)$$

Exploiting the Local Structure

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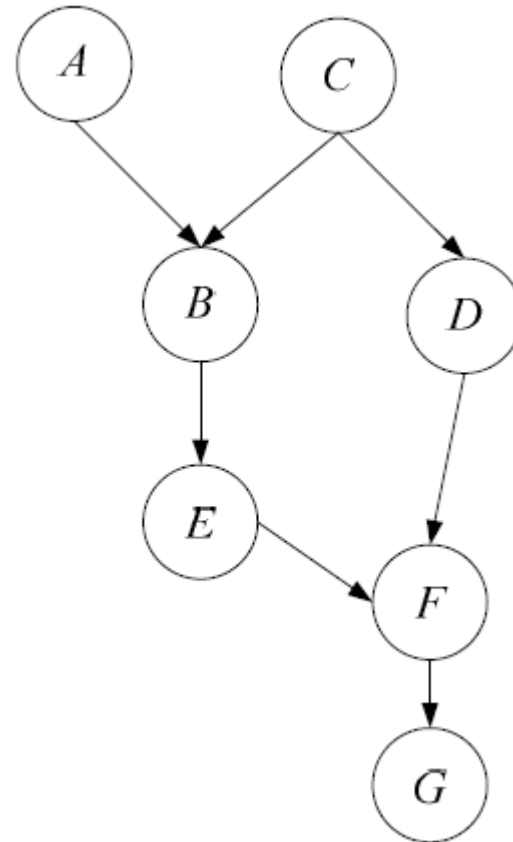
$$P(C, S, R, W, F) = P(C)P(S | C)P(R | C)P(W | S, R)P(F | R)$$

$$P(X_1, \dots, X_d) = \prod_{i=1}^d P(X_i | \text{parents}(X_i))$$

mini-exercise

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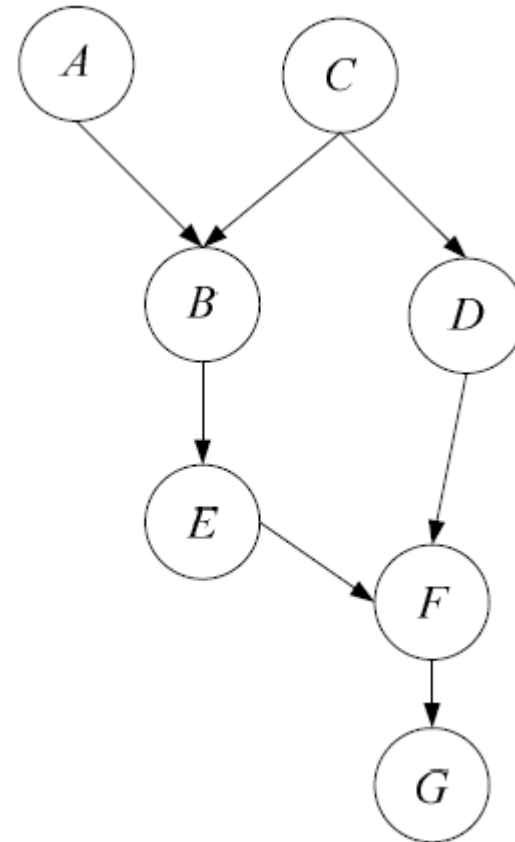
- Write the joint distribution for this model (DAG)



mini-exercise

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- Write the joint distribution for this model (DAG)



$$P(A)P(C)P(B|A,C)P(E|B)P(D|C)P(F|E,D)P(G|F)$$

mini-exercise

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$$p(x_1)p(x_2)p(x_3)p(x_4|x_1, x_2, x_3)p(x_5|x_1, x_3)p(x_6|x_4)p(x_7|x_4, x_5)$$

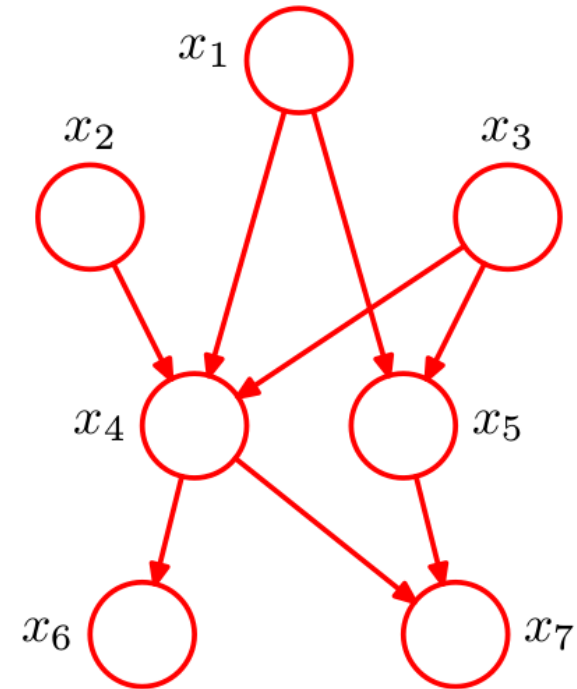
- Draw the model (DAG) that describes this joint distribution

mini-exercise

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$$p(x_1)p(x_2)p(x_3)p(x_4|x_1, x_2, x_3)p(x_5|x_1, x_3)p(x_6|x_4)p(x_7|x_4, x_5)$$

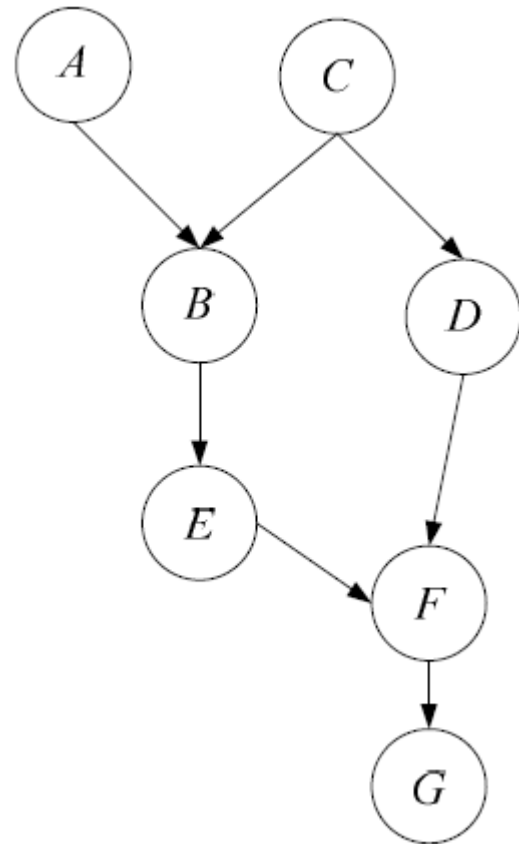
- Draw the model (DAG) that describes this joint distribution



d-Separation

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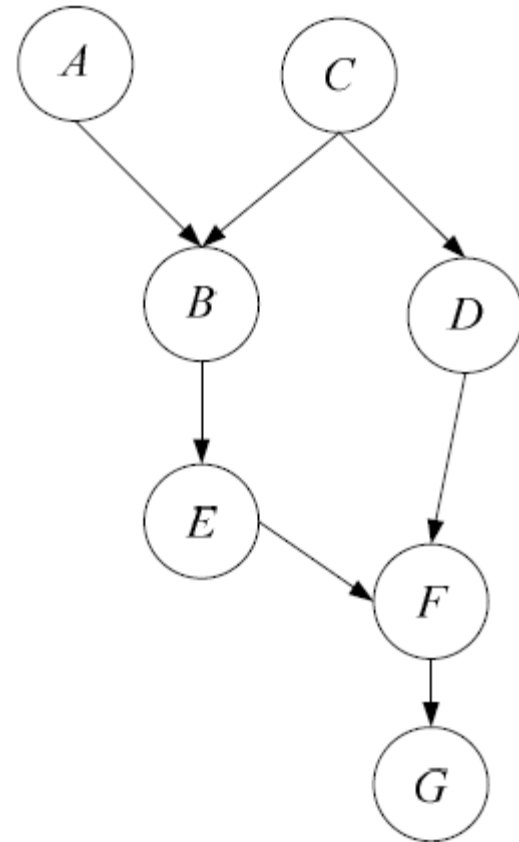
- A general way to describe if two (sets of) nodes are independent
- Two (sets of) nodes are d-separated if all paths between them are blocked



d-Separation

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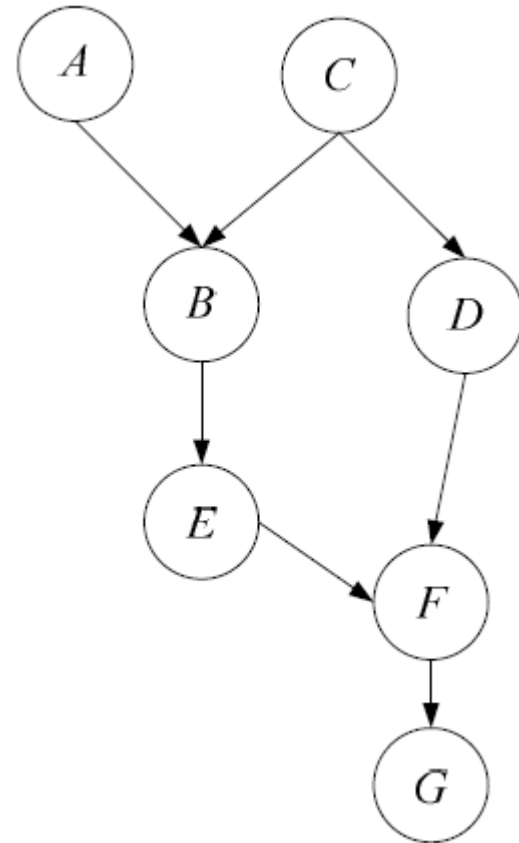
- A path from node X to node Y is **blocked** if
 - a) Edges on the path meet head-to-tail (case 1) or tail-to-tail (case 2) and the node between is observed
 - b) Edges on the path meet head-to-head (case 3) and neither that node nor any of its descendants are observed
- If all paths are blocked, X and Y are d-separated (conditionally independent) given the observations.



d-Separation: Are these paths blocked?

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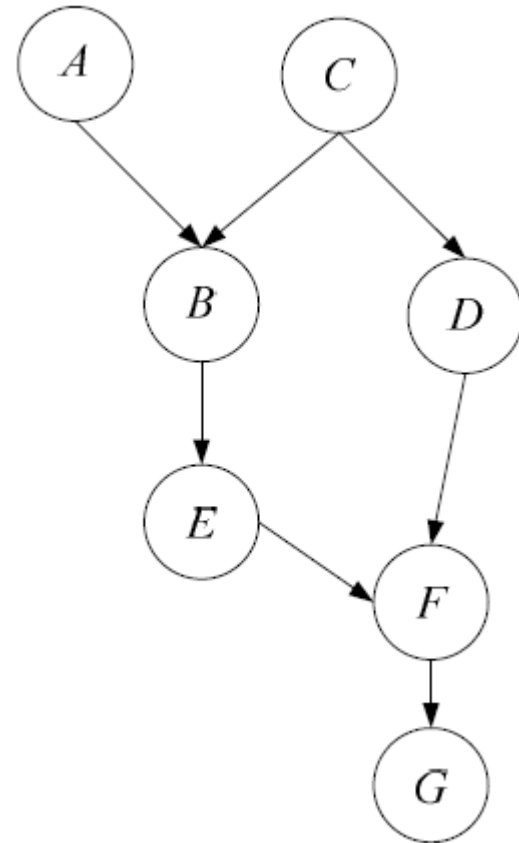
- BCDF given C?
- BEFG given F?
- BEFD given G?



d-Separation: Are these paths blocked?

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- BCDF given C?
-blocked
- BEFG given F?
-blocked
- BEFD given G?
-not blocked



Generative models

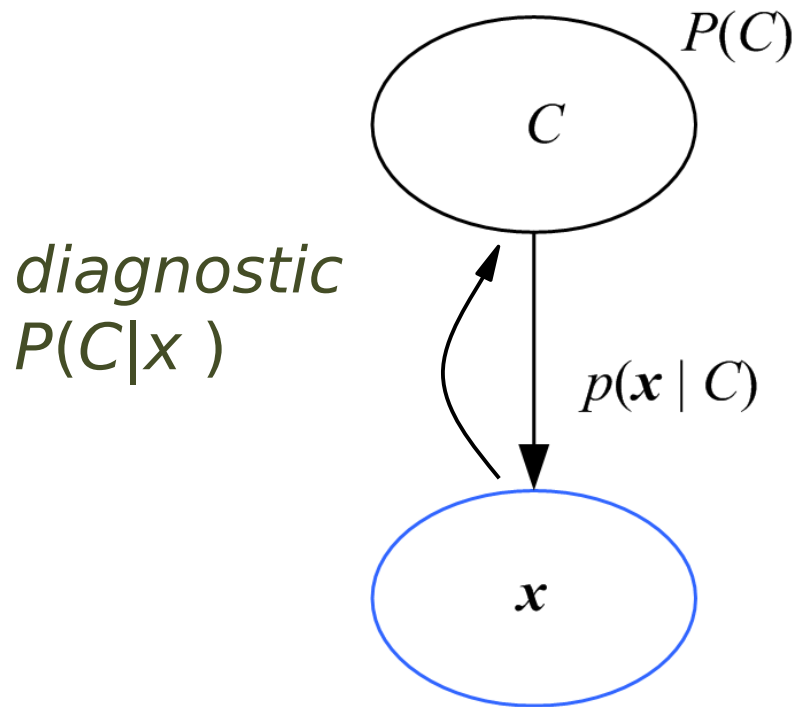
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- Graphical models can represent the processes that generate data
- Another way to look at
 - Classification
 - Regression
 - Etc

Classification

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Can be visualized as a graphical model:

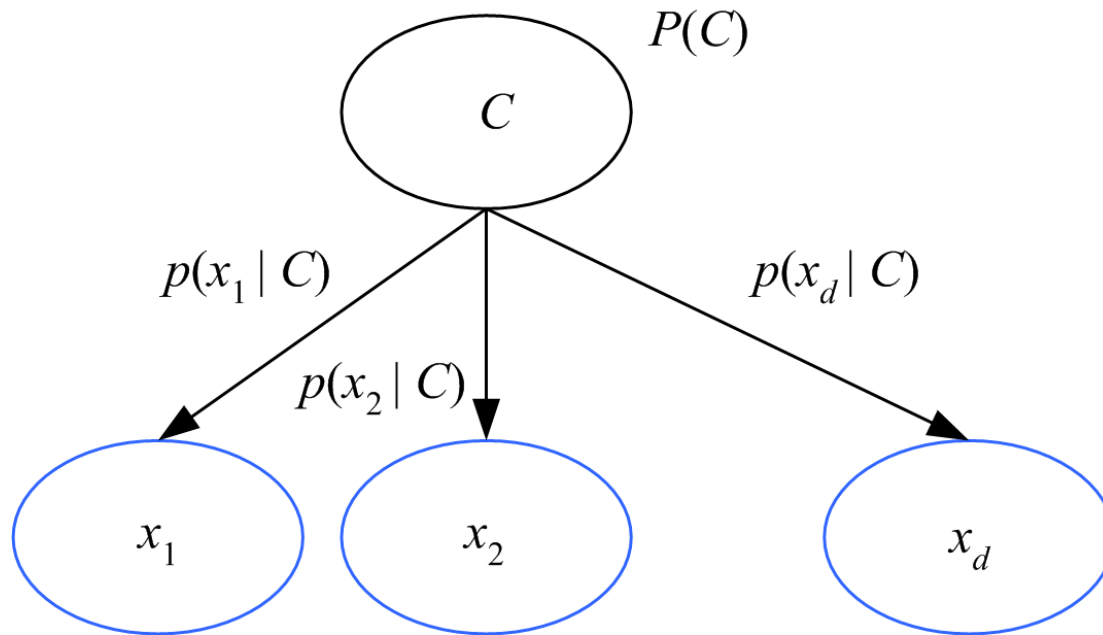


Bayes' rule inverts the arc:

$$P(C | \mathbf{x}) = \frac{p(\mathbf{x} | C)P(C)}{p(\mathbf{x})}$$

Naive Bayes' Classifier

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Given C , x_j are independent:

$$p(\mathbf{x}|C) = p(x_1|C) p(x_2|C) \dots p(x_d|C)$$

Linear Regression

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Linear regression as a graphical
(Bayesian) model

