

Mandatory 3

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Assignment 1

For the matrix A, compute the following:

- The rank
- The dimension of the row space
- The dimensions of the column space
- A basis for the nullspace (not just the dimension of the nullspace)

$$A = \begin{pmatrix} 1 & 2 & 3 & 3 & 2 \\ 4 & 6 & 4 & 8 & 9 \\ 3 & 4 & 1 & 4 & 8 \end{pmatrix}$$

Computing the rank

The rank of a matrix represents the maximum number of linearly independent vectors in a matrix which is equal to the number of non-zero rows in its row echelon form.

Thus to find the rank of A we can reduce A to row echelon form.
Thereafter the number of nonzero rows represents the rank of A

$$A = \begin{pmatrix} 1 & 2 & 3 & 3 & 2 \\ 4 & 6 & 4 & 8 & 9 \\ 3 & 4 & 1 & 4 & 8 \end{pmatrix}$$

$$R_2 + (-4)R_1 \Rightarrow R_2$$
$$\begin{pmatrix} 1 & 2 & 3 & 3 & 2 \\ 0 & -2 & -8 & -4 & 1 \\ 3 & 4 & 1 & 4 & 8 \end{pmatrix}$$

$$(-\frac{1}{2})R_2 \Rightarrow R_2$$
$$\begin{pmatrix} 1 & 2 & 3 & 3 & 2 \\ 0 & 1 & 4 & 2 & -\frac{1}{2} \\ 3 & 4 & 1 & 4 & 8 \end{pmatrix}$$

$$R_3 + (-3)R_1 \Rightarrow R_3$$
$$\begin{pmatrix} 1 & 2 & 3 & 3 & 2 \\ 0 & 1 & 4 & 2 & -\frac{1}{2} \\ 0 & -2 & -8 & -5 & 2 \end{pmatrix}$$

$$R_3 - (-2)R_2 \Rightarrow R_3$$
$$\begin{pmatrix} 1 & 2 & 3 & 3 & 2 \\ 0 & 1 & 4 & 2 & -\frac{1}{2} \\ 0 & 0 & 0 & -1 & 1 \end{pmatrix}$$

$$\begin{array}{ccccc}
 (-1)R_3 \Rightarrow R_3 & & & & \\
 1 & 2 & 3 & 3 & 2 \\
 0 & 1 & 4 & 2 & -\frac{1}{2} \\
 0 & 0 & 0 & 1 & -1
 \end{array}$$

Since A in echelon form has 3 nonzero rows then
 $\text{rank}(A) = 3$

Computing dimension of the row space and column space

We know that the dimension of the row/column space of Matrix A is equal to the rank of A.
 Thus the dimension of the column/row space is 3 as we know that the rank of matrix A is 3

$$A = \begin{array}{ccccc}
 1 & 2 & 3 & 3 & 2 \\
 0 & 1 & 4 & 2 & -\frac{1}{2} \\
 0 & 0 & 0 & 1 & -1
 \end{array}$$

Computing the basis for the nullspace

The nullspace of A is the solution space of the homogenous space
 $Ax = \mathbf{0}$

To solve this we can write the augmented matrix $[A \ \mathbf{0}]$ in reduced echelon row echelon form

We can reuse the row echelon form from the previous assignment

$$A = \begin{array}{ccccc}
 1 & 2 & 3 & 3 & 2 \\
 0 & 1 & 4 & 2 & -\frac{1}{2} \\
 0 & 0 & 0 & 1 & 2
 \end{array}$$

The system of equations corresponding to the reduced row-echelon form is

$$x_1 + 2x_2 + 3x_3 + 3x_4 + 2x_5 = 0$$

$$x_2 + 4x_3 + 2x_4 - \frac{1}{2}x_5 = 0$$

$$x_4 - x_5 = 0$$

let x_3 and x_5 be the free variables to present the solutions in parametric form

$$\begin{aligned}
 x_1 &= -2x_2 - 3x_3 - 3x_4 - 2x_5 \\
 &= -2\left(-4s + \frac{3}{2}t\right) - 3s - 3x_4 - 2t \\
 &= 5s + \frac{6}{2}t - \frac{10}{2}t \\
 &= 5s - \frac{4}{2}t \\
 &= 5s - 2t
 \end{aligned}$$

$$x_2 = -4s - 2t + \frac{1}{2}x_5 = -4s - 2t + \frac{1}{2}t = -4s + \frac{3}{2}t$$

$$x_3 = s$$

$$x_4 = t$$

$$x_5 = t$$

This means that the solution space of $Ax = \mathbf{0}$ consists of all solution vectors of the form

$$\mathbf{x} = \begin{pmatrix} x_1 \\ x_2 \\ x_3 \\ x_4 \\ x_5 \end{pmatrix} = \begin{pmatrix} 5s - 2t \\ -4s + \frac{3}{2}t \\ s \\ t \\ t \end{pmatrix} = s \begin{pmatrix} 5 \\ -4 \\ 1 \\ 0 \\ 0 \end{pmatrix} + t \begin{pmatrix} -2 \\ \frac{3}{2} \\ 0 \\ 1 \\ 1 \end{pmatrix}$$

So a basis for the null space of A consists of the vectors:

$$\begin{pmatrix} 5 \\ -4 \\ 1 \\ 0 \\ 0 \end{pmatrix} \text{ and } \begin{pmatrix} -2 \\ \frac{3}{2} \\ 0 \\ 1 \\ 1 \end{pmatrix}$$

In other words these two vectors are solutions for $A\mathbf{x} = \mathbf{0}$ and all linear combinations of these two vectors are also solutions.

Assignment 2

Consider the following vectors in \mathbb{R}^3

$$\mathbf{v} = \begin{bmatrix} 1 \\ 0 \\ 3 \end{bmatrix} \quad \mathbf{w} = \begin{bmatrix} 0 \\ 1 \\ 2 \end{bmatrix} \quad \mathbf{u} = \begin{bmatrix} -2 \\ 2 \\ 5 \end{bmatrix}$$

Compute the projection of \mathbf{u} onto the subspace spanned by \mathbf{v} and \mathbf{w} .

Find the coordinates a, b such that the projection can be written as

$$a\mathbf{v} + b\mathbf{w}$$

Computing the projection of \mathbf{u} onto subspace spanned by \mathbf{v} and \mathbf{w}

Recall that a set of vectors $S = \{\mathbf{v}_1, \mathbf{v}_2, \dots, \mathbf{v}_n\}$ in a vector space V is a basis for V when

- S spans V
- S is linearly independent

In our case we know that

$$S = \{\mathbf{v}, \mathbf{w}\}$$

Given in the assignment we know that S spans \mathbb{R}^3

And we know S is linearly independent because the vector equation

$$c_1\mathbf{v} + c_2\mathbf{w} = \mathbf{0}$$

Where $c_1 = 0$, and $c_2 = 0$ is the only trivial solution to the vector equation above

Hence the basis A can be found by adjoining \mathbf{v} and $\mathbf{w} \Rightarrow [\mathbf{v} \quad \mathbf{w}]$

$$A = \begin{pmatrix} 1 & 0 \\ 0 & 1 \\ 3 & 2 \end{pmatrix}$$

By theorem 1 from the lecture notes we know that the projection of a vector \mathbf{u} in \mathbb{R}^3 to S can be computed as

$$P\mathbf{u} \text{ where } P = A(A^T A)^{-1} A^T$$

And so

$$\begin{aligned}
 A^T A &= \begin{bmatrix} 1 & 0 & 3 \\ 0 & 1 & 2 \end{bmatrix} \begin{bmatrix} 1 & 0 \\ 0 & 1 \\ 3 & 2 \end{bmatrix} \\
 &= \begin{bmatrix} 1*1 + 0*0 + 3*3 & 1*0 + 0*1 + 3*2 \\ 0*1 + 1*0 + 2*3 & 0*0 + 1*1 + 2*2 \end{bmatrix} \\
 &= \begin{bmatrix} 10 & 6 \\ 6 & 5 \end{bmatrix}
 \end{aligned}$$

Since $A^T A$ is a 2×2 matrix recall that we can find the inverse of a 2×2 matrix with the following formula

$$\begin{bmatrix} a & b \\ c & d \end{bmatrix}^{-1} = \frac{1}{ad - bc} \begin{bmatrix} d & -b \\ -c & a \end{bmatrix}$$

$$(A^T A)^{-1} = \frac{1}{10*5 - 6*6} \begin{bmatrix} 5 & -6 \\ 6 & 10 \end{bmatrix}$$

$$(A^T A)^{-1} = \frac{1}{50 - 36} \begin{bmatrix} 5 & -6 \\ 6 & 10 \end{bmatrix}$$

$$(A^T A)^{-1} = \frac{1}{14} \begin{bmatrix} 5 & -6 \\ 6 & 10 \end{bmatrix}$$

$$(A^T A)^{-1} = \begin{bmatrix} \frac{5}{14} & -\frac{6}{14} \\ \frac{6}{14} & \frac{10}{14} \end{bmatrix}$$

Then we can calculate

$$A(A^T A)^{-1} = \frac{1}{14} * \begin{pmatrix} 1 & 0 \\ 0 & 1 \\ 3 & 2 \end{pmatrix} \begin{bmatrix} 5 & -6 \\ 6 & 10 \end{bmatrix}$$

$$A(A^T A)^{-1} = \frac{1}{14} * \begin{bmatrix} 5 & -6 \\ 6 & 10 \\ 27 & 2 \end{bmatrix}$$

Finally we can combine our previous calculations to compute the projection matrix P

$$P = A(A^T A)^{-1} A^T$$

$$P = \frac{1}{14} * \left(\begin{bmatrix} 5 & -6 \\ 6 & 10 \\ 27 & 2 \end{bmatrix} * \begin{bmatrix} 1 & 0 & 3 \\ 0 & 1 & 2 \end{bmatrix} \right)$$

$$P = \frac{1}{14} * \begin{bmatrix} 5 & -6 & 3 \\ 6 & 10 & 38 \\ 27 & 2 & 85 \end{bmatrix}$$

And so we can compute the projection of vector u onto to S with the computed Projection matrix P

$$Pu = \frac{1}{14} * \left(\begin{bmatrix} 5 & -6 & 3 \\ 6 & 10 & 38 \\ 27 & 2 & 85 \end{bmatrix} * \begin{bmatrix} -2 \\ 2 \\ 5 \end{bmatrix} \right)$$

$$Pu = \frac{1}{14} * \begin{bmatrix} -7 \\ 198 \\ 375 \end{bmatrix}$$

$$Pu = \begin{bmatrix} -\frac{7}{14} \\ \frac{198}{14} \\ \frac{375}{14} \end{bmatrix}$$

$$Pu = \begin{bmatrix} -\frac{1}{2} \\ \frac{99}{7} \\ \frac{375}{14} \end{bmatrix}$$

This implies that the projection of vector u onto S results in the following vector

$$\begin{bmatrix} -\frac{1}{2} \\ \frac{99}{7} \\ \frac{375}{14} \end{bmatrix}$$

Finally we can compute the coordinates a and b to show that $av + bw = Pu$

$$a * \begin{bmatrix} 1 \\ 0 \\ 3 \end{bmatrix} + b * \begin{bmatrix} 0 \\ 1 \\ 2 \end{bmatrix} = \begin{bmatrix} -\frac{1}{2} \\ \frac{99}{7} \\ \frac{375}{14} \end{bmatrix}$$

Which corresponds to the following system of linear equations

$$a = -\frac{1}{2}$$

$$b = \frac{99}{7}$$

$$3a + 2b = \frac{375}{14}$$

We can solve the system with Gauss Jordan elimination on the augmented matrix

$$\begin{bmatrix} 1 & 0 & -\frac{1}{2} \\ 0 & 1 & \frac{99}{7} \\ 3 & 2 & \frac{375}{14} \end{bmatrix} \Rightarrow \begin{bmatrix} 1 & 0 & -\frac{1}{2} \\ 0 & 1 & \frac{99}{7} \\ 0 & 0 & 0 \end{bmatrix}$$

Hence the coordinate a and b are

$$a = -\frac{1}{2}, \quad b = \frac{99}{7}$$

We can test if this solution is correct by plotting it in our equation :

$$a\mathbf{v} + b\mathbf{w} = P\mathbf{u}$$

$$-\frac{1}{2} * \begin{bmatrix} 1 \\ 0 \\ 3 \end{bmatrix} + \frac{99}{7} * \begin{bmatrix} 0 \\ 1 \\ 2 \end{bmatrix} = \begin{bmatrix} -\frac{1}{2} \\ \frac{99}{7} \\ \frac{375}{14} \end{bmatrix}$$

And solve the left side of the equation

$$\begin{bmatrix} -\frac{1}{2} \\ 0 \\ 3 \\ -\frac{3}{2} \end{bmatrix} + \frac{99}{7} * \begin{bmatrix} 0 \\ 1 \\ 2 \end{bmatrix} = \begin{bmatrix} -\frac{1}{2} \\ \frac{99}{7} \\ \frac{375}{14} \end{bmatrix}$$

$$\begin{bmatrix} -\frac{1}{2} \\ 0 \\ 3 \\ -\frac{3}{2} \end{bmatrix} + \begin{bmatrix} 0 \\ \frac{99}{7} \\ \frac{198}{7} \\ \frac{375}{14} \end{bmatrix} = \begin{bmatrix} -\frac{1}{2} \\ \frac{99}{7} \\ \frac{375}{14} \end{bmatrix}$$

$$\begin{bmatrix} 0 - \frac{1}{2} \\ \frac{99}{7} + 0 \\ \frac{198}{7} + -\frac{3}{2} \end{bmatrix} = \begin{bmatrix} -\frac{1}{2} \\ \frac{99}{7} \\ \frac{375}{14} \end{bmatrix}$$

$$\begin{bmatrix} -\frac{1}{2} \\ \frac{99}{7} \\ \frac{396}{14} - \frac{21}{14} \end{bmatrix} = \begin{bmatrix} -\frac{1}{2} \\ \frac{99}{7} \\ \frac{375}{14} \end{bmatrix}$$

$$\begin{bmatrix} 1 \\ -\frac{1}{2} \\ \frac{99}{7} \\ \frac{375}{14} \end{bmatrix} = \begin{bmatrix} 1 \\ -\frac{1}{2} \\ \frac{99}{7} \\ \frac{375}{14} \end{bmatrix}$$

Which implies

$$a\mathbf{v} + b\mathbf{w} = P\mathbf{u}$$

And so we can conclude that the projection of \mathbf{u} onto the subspace spanned by \mathbf{v} and \mathbf{w} results in the vector

$$P\mathbf{u} = \begin{bmatrix} 1 \\ -\frac{1}{2} \\ \frac{99}{7} \\ \frac{375}{14} \end{bmatrix}$$

Where P is the projection matrix

And also that the same projection can be written with the coordinates a and b in the equation $a\mathbf{v} + b\mathbf{w}$

Since we have shown that

$$P\mathbf{u} = a\mathbf{v} + b\mathbf{w} = \begin{bmatrix} 1 \\ -\frac{1}{2} \\ \frac{99}{7} \\ \frac{375}{14} \end{bmatrix}$$

Assignment 3

Find linear combination of the functions

$$f(x) = 2x^2 + x$$

$$g(x) = x + 1$$

That best fits the observation points

$$\{(-1, -2), (0, 2), (1, 5)\}$$

In other words find numbers a, b such that

$$h(x) = a f(x) + b g(x) \text{ minimises the sum } (h(-1) + 2)^2 + (h(0) - 2)^2 + (h(1) - 5)^2$$

We can substitute the points into the function

$$h(x) = a f(x) + b g(x)$$

Such that we get a system of 3 linear equations

$$-2 = a ((2(-1)^2 - 1) + b * (-1 + 1))$$

$$2 = a (2(0)^2 + 0) + b (0 + 1)$$

$$5 = a(2(1)^2 + 1) + b (1 + 1)$$

We can expand the linear equations

$$-2 = a(1) + b(0)$$

$$2 = a(0) + b(1)$$

$$5 = a(3) + b(2)$$

$$-2 = a$$

$$2 = b$$

$$5 = 3a + 2b$$

Plotting the equations into a coefficient matrix we get

$$\begin{bmatrix} 1 & 0 \\ 0 & 1 \\ 3 & 2 \end{bmatrix} * \begin{bmatrix} a \\ b \end{bmatrix} = \begin{bmatrix} -2 \\ 2 \\ 5 \end{bmatrix}$$

And so we can define the following vectors v' , w' and u' based on matrix above such that $v', w', u' \in \mathbb{R}^3$

$$v' = \begin{bmatrix} 1 \\ 0 \\ 3 \end{bmatrix} \quad w' = \begin{bmatrix} 0 \\ 1 \\ 2 \end{bmatrix} \quad u' = \begin{bmatrix} -2 \\ 2 \\ 5 \end{bmatrix}$$

Recall that in exercise two we have the following vectors we used to solve the least square problem

$$v = \begin{bmatrix} 1 \\ 0 \\ 3 \end{bmatrix} \quad w = \begin{bmatrix} 0 \\ 1 \\ 2 \end{bmatrix} \quad u = \begin{bmatrix} -2 \\ 2 \\ 5 \end{bmatrix}$$

As it can be seen, this least square problem is the same as in exercise 2 and therefore the calculations and solution to this least square problem is exactly the same as In exercise 2