

Intelligent Systems Programming

Lecture 8: Constraint Programming



Today's Program

- [10:00-10:50]
 - Constraint Satisfaction Problems (CSPs)
 - Constraint Propagation
 - Backtracking
- [11:00-12:00]
 - Variable and value selection
 - Forward Checking
 - Maintaining arc consistency (MAC) algorithm
 - Global constraints
 - Modern constraint propagation systems



Constraint Satisfaction Problems (CSPs)

	1	2	3	4	5	6	7	8	9
A			3		2		6		
B	9			3		5			1
C			1	8		6	4		
D			8	1		2	9		
E	7								8
F			6	7		8	2		
G			2	6		9	5		
H	8			2		3			9
I			5		1		3		

Container Vessel Slot Planning



Definition of CSPs

A **CSP** is a triple $\langle X, D, C \rangle$, where:

$X = \{X_1, \dots, X_n\}$ is a finite set of **variables**.

$D = \{D_1, \dots, D_n\}$ is a set of **domains** of possible values for each variable, where $D_i = \{v_1, \dots, v_{k_i}\}$

$C = \{C_1, \dots, C_m\}$ is a set of **constraints**, where $C_i = \langle \text{scope}, \text{relation} \rangle$

e.g. $X_1 \in \{A, B\}, X_2 \in \{A, B\}$

Implicit constraint representation: $\langle (X_1, X_2), X_1 \neq X_2 \rangle$

Explicit constraint representation: $\langle (X_1, X_2), [(A, B), (B, A)] \rangle$

Typical short notation: $X_1 \neq X_2$

CSP Solutions

- **Partial Assignment** : Values assigned to only some of the variables.
- **Complete Assignment** : Each variable has a value assigned.
- **Consistent Assignment** : Each constraint, where all variables in its scope are assigned, is satisfied.
- **Solution** : Complete consistent assignment.

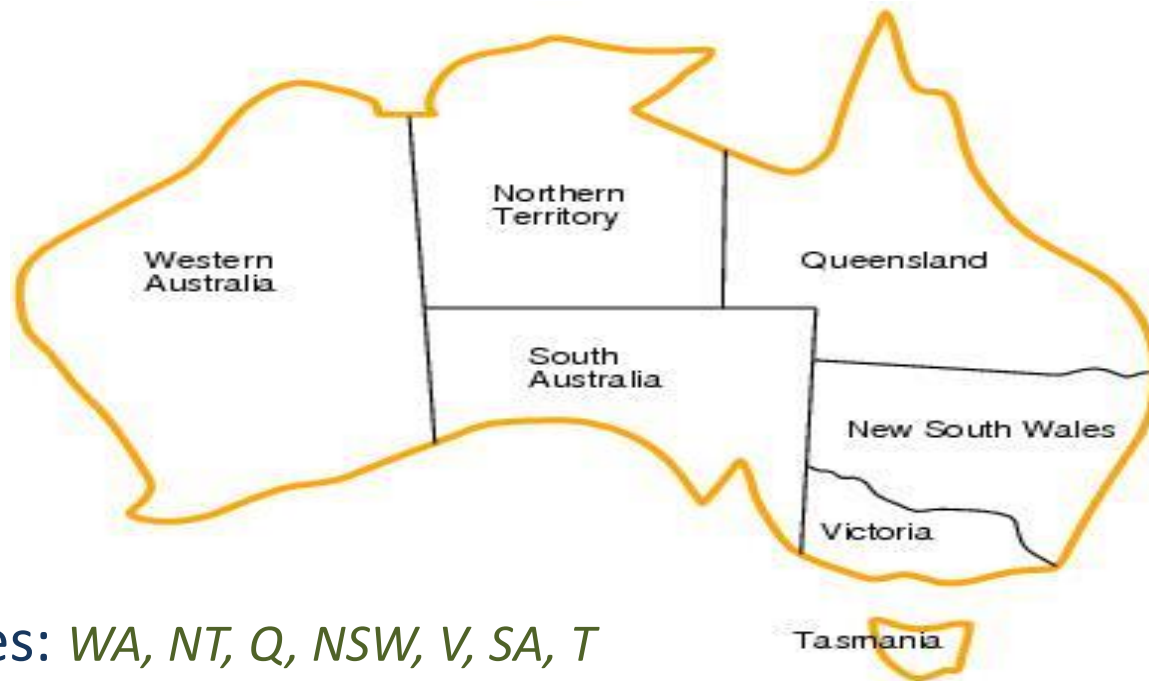
Types of Constraints

Different Arity

- **Unary constraints** involve a single variable.
 - e.g. $X \neq 12$
- **Binary constraints** involve pairs of variables.
 - e.g. $X > Y$, $P = MIB \wedge C = Black$
- **Global constraints** involve arbitrary number of variables.
 - e.g. *AllDifferent*

This lecture: all* algorithms assume **binary constraints**

CSP Example: Map Coloring

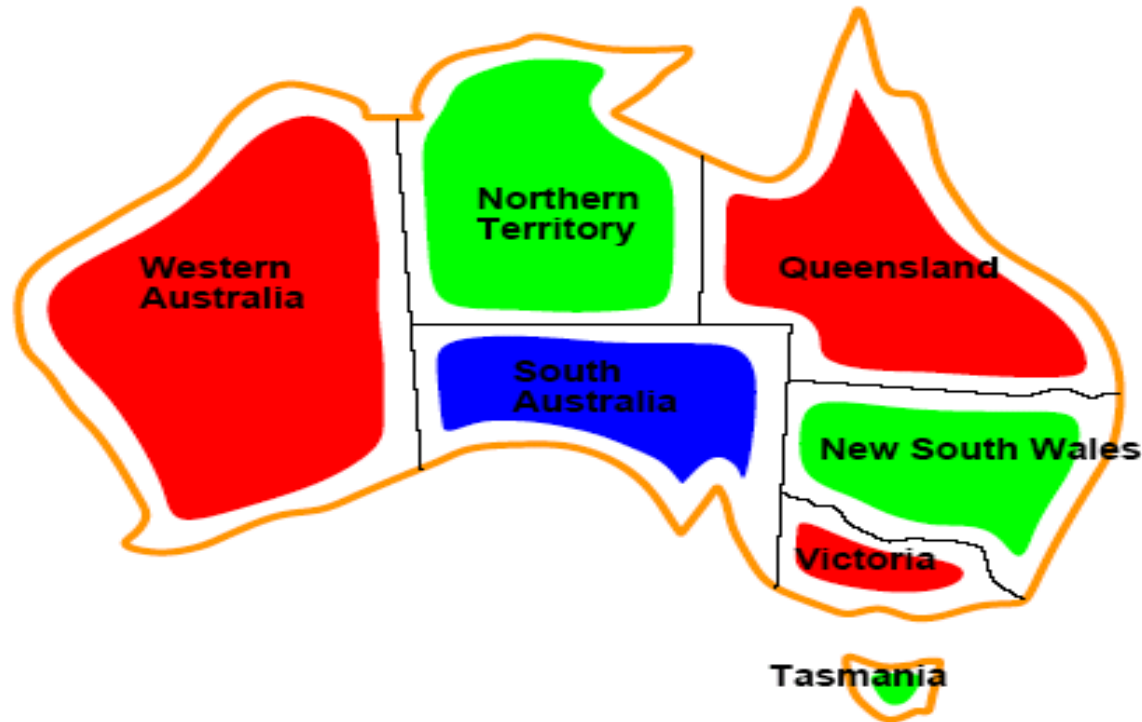


- Variables: WA, NT, Q, NSW, V, SA, T
- Domains: $D_i = \{red, green, blue\}$
- Constraints: adjacent regions must have different colors.

e.g. $\langle (WA, NT), WA \neq NT \rangle$

$\langle (WA, NT), [(red, green), (red, blue), (green, red), \dots] \rangle$

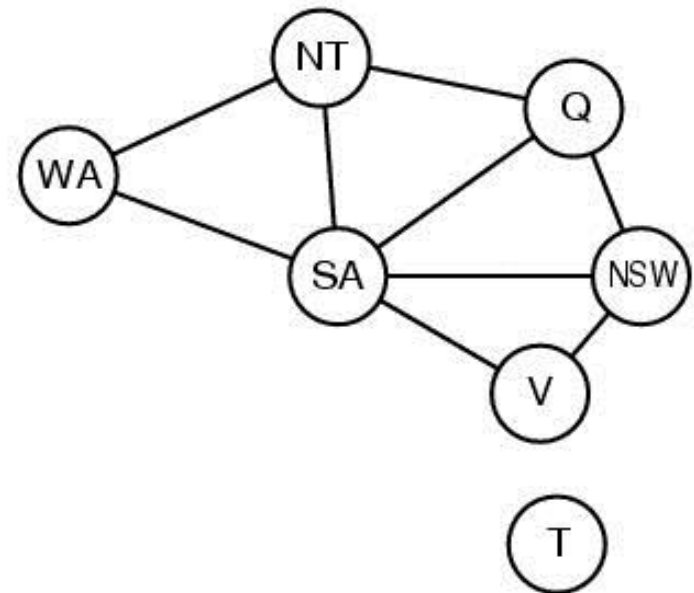
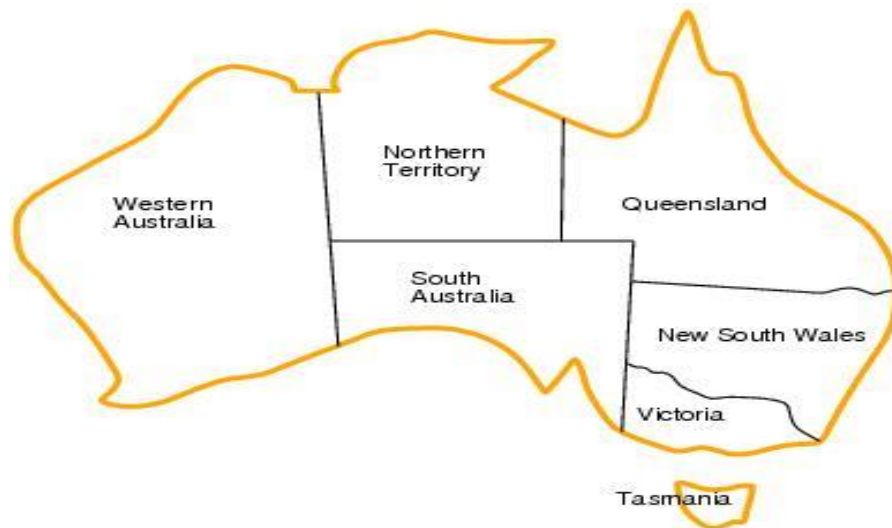
CSP Example: Map Coloring



- Solutions are assignments satisfying all constraints, e.g.
 $\{WA=red, NT=green, Q=red, NSW=green, V=red, SA=blue, T=green\}$

Constraint Graph Representation of CSP

- Nodes are variables
- Edges are **binary constraints**



Constraint Propagation (Rule Inference)

CSPs are solved combining **search**
and **constraint propagation**

Constraint Propagation

- **Node consistency** : for every value v_i of variable X , all unary constraints of X are satisfied.

Example

$SA \in \{red, green, blue\}, SA \neq \{green\}$

$SA \in \{red, blue\}$

- **Arc consistency**: for every $X \rightarrow Y$ arc, every value v_i in X has a support value u_j in Y .

Arc Consistency Examples

1) $SA \in \{red, green, blue\}, NT \in \{blue\}, SA \neq NT$
 $SA \rightarrow NT$ arc-consistent: $SA \in \{red, green\}$

2) $X, Y \in \{0, 1, \dots, 9\}, Y = X^2$

$X \rightarrow Y$ arc-consistent : $X \in \{0, 1, 2, 3\}, Y \in \{0, 1, \dots, 9\}$

$Y \rightarrow X$ arc-consistent: $X \in \{0, 1, \dots, 9\}, Y \in \{0, 1, 4, 9\}$

3) $SA \in \{red, green, blue\}, WA \in \{red, green, blue\}, SA \neq WA$

$SA \rightarrow WA / WA \rightarrow SA$ arc-consistent: can we prune any values?

Arc Consistency Algorithm AC-3

function AC-3(*csp*) **returns** false if an inconsistency is found and true otherwise (+ updated CSP)

inputs: *csp*, a binary CSP with components (X , D , C)

local variables: *queue*, a queue of arcs, initially all the arcs in *csp*

while *queue* is not empty **do**

$(X_i, X_j) \leftarrow \text{REMOVE-FIRST}(\text{queue})$

if REVISE(*csp*, X_i , X_j) **then**

if size of $D_i = 0$ **then return** false

for each X_k **in** $X_i.\text{NEIGHBORS} - \{X_j\}$ **do**

 add (X_k, X_i) to *queue*

return true

Obs: two arcs for
each binary
constraint!

function REVISE(*csp*, X_i , X_j) **returns** true iff we revise the domain of X_i

revised \leftarrow false

for each x **in** D_i **do**

if no value y in D_j allows (x, y) to satisfy the constraint between X_i and X_j **then**

 delete x from D_i

revised \leftarrow true

return *revised*

Complexity of AC-3

Assume

- n variables,
- at most d values in domains
- c binary constraints

Observations

- An arc can at most be added to Q d times
- An arc can be revised in d^2
- Thus, worst case runtime is $O(cd^3)$

CSP Solving



Search in CSP

- Inference is not enough
- Apply depth-first search:
 - State: Partial assignment
 - Action: $var = value$
- Complexity
 - Branching factor b at the top level is nd
 - $b = (n-l)d$ at depth l , hence $n!d^n$ leaves
 - But only d^n complete assignments?!

Backtracking Search

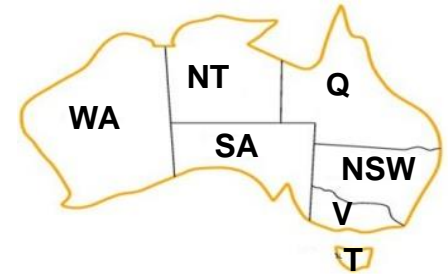
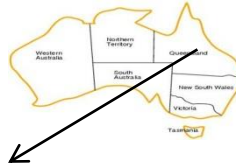
- **Insight:**

- If we assign the first k variables to values, it does not matter in what order we did it in.
- Thus, after choosing which variable to assign in a node, do not change it.

- **Backtracking Algorithm:**

- Choose values for one variable at the time.
- Backtrack when a variable has no legal values left.

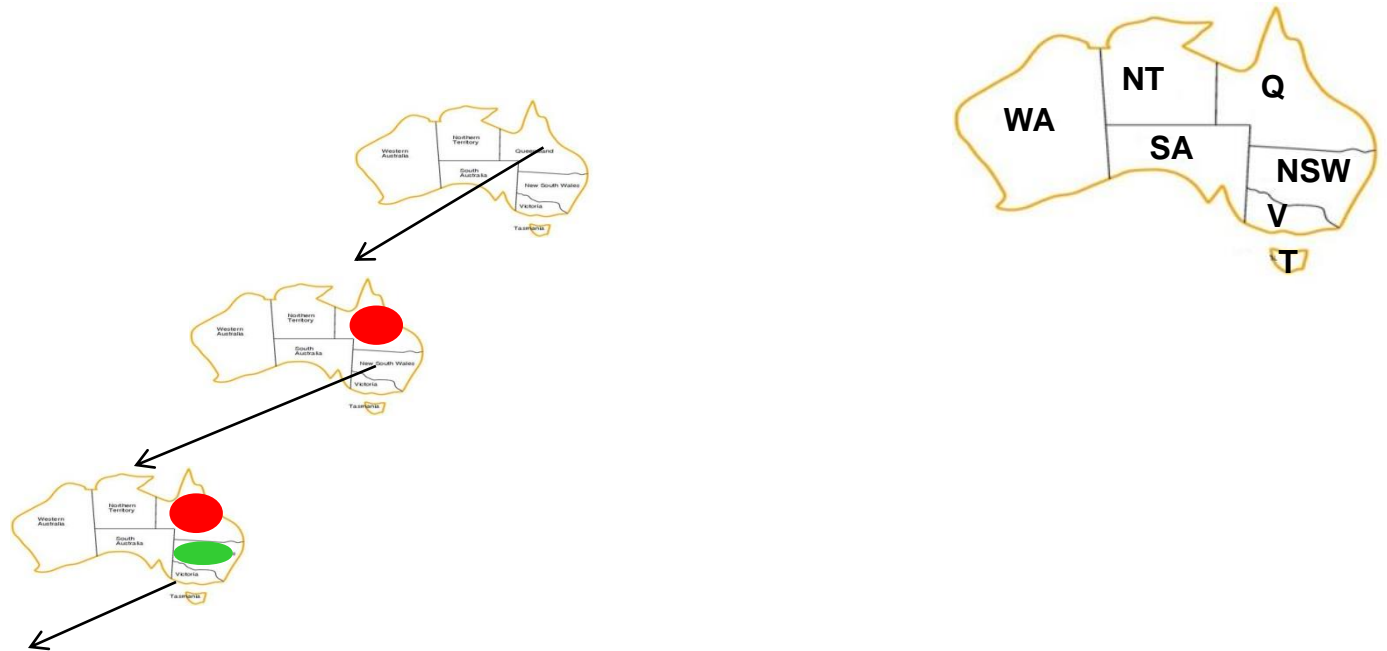
Backtracking Example



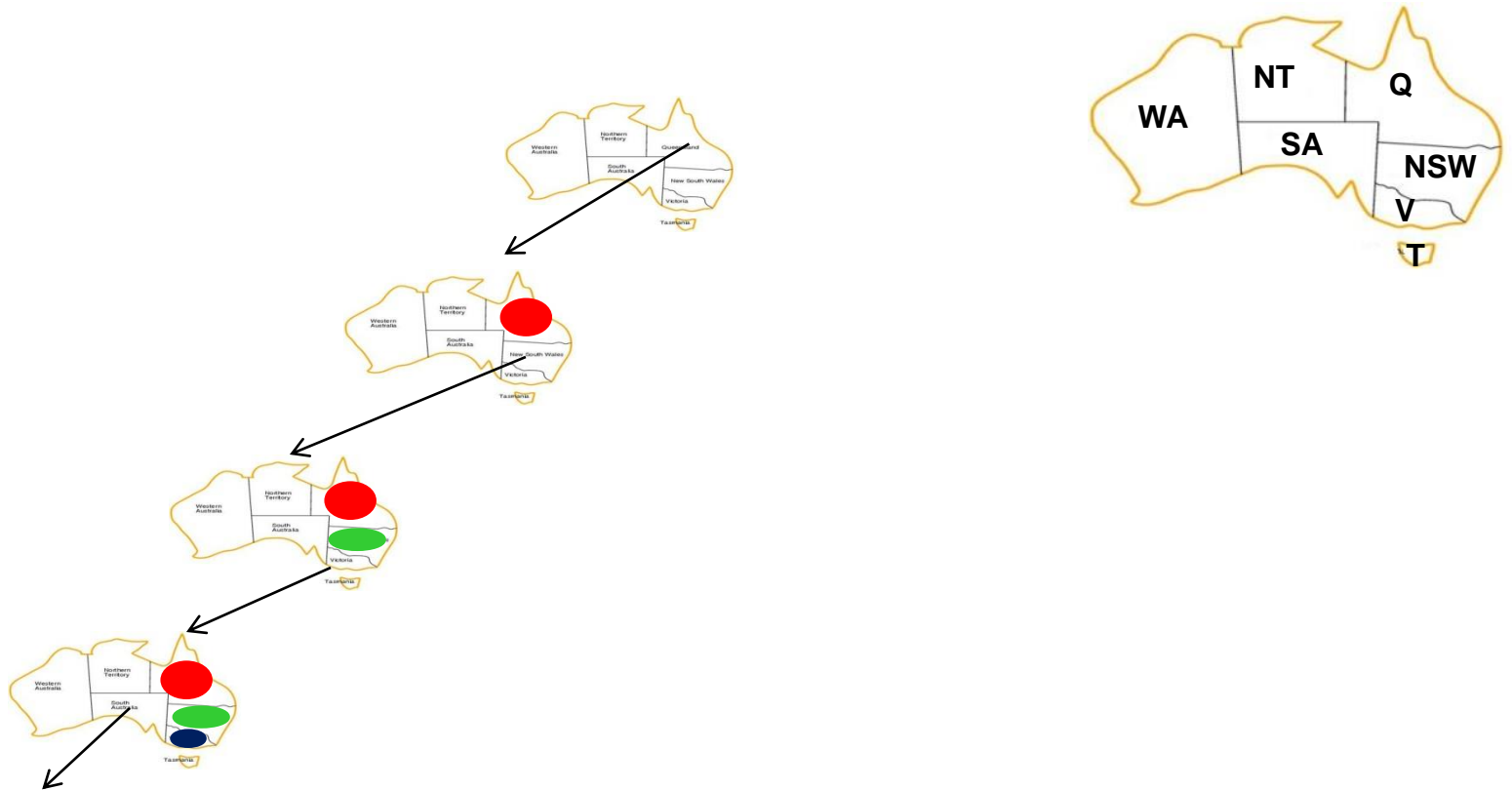
Backtracking Example



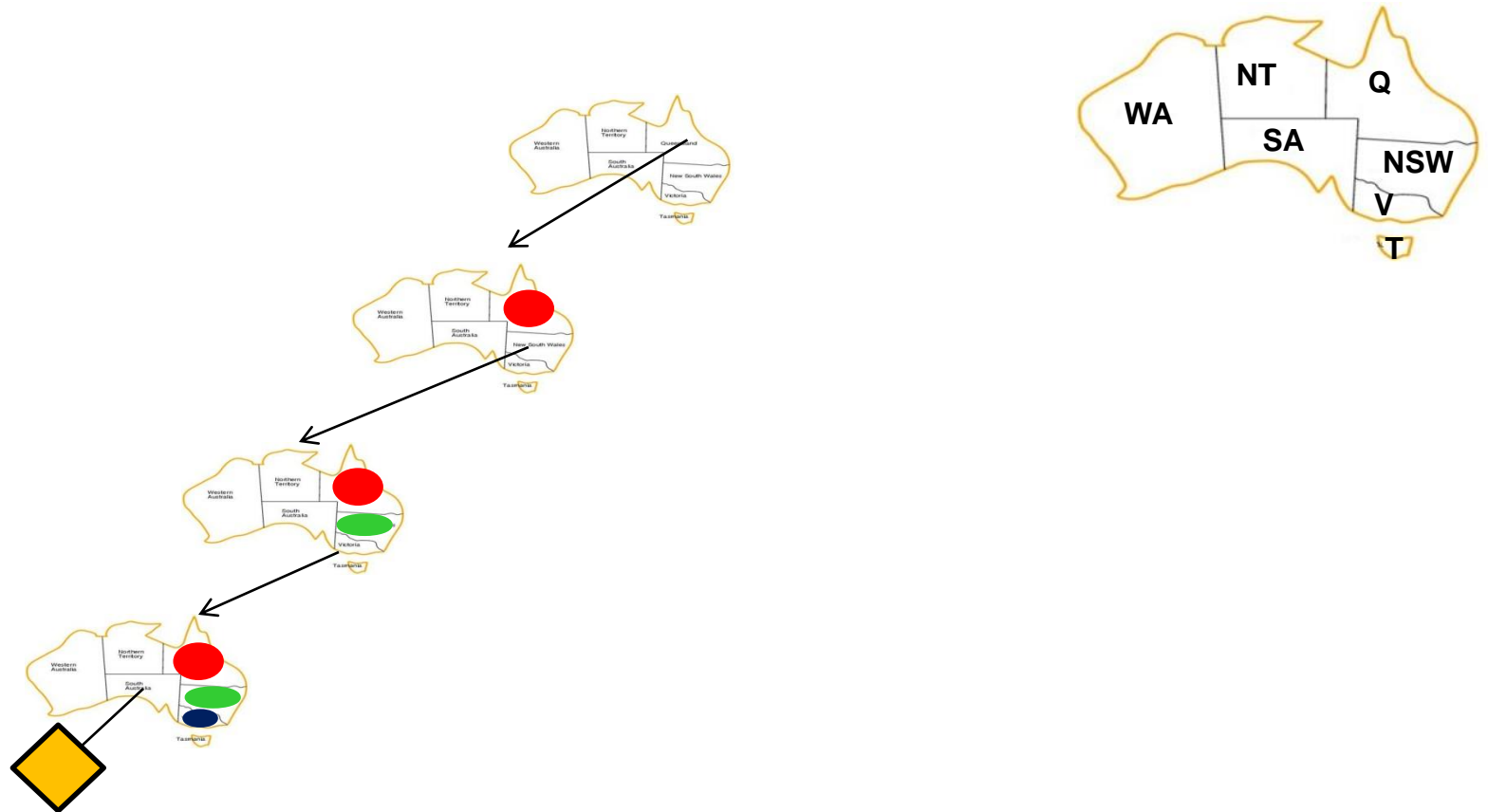
Backtracking Example



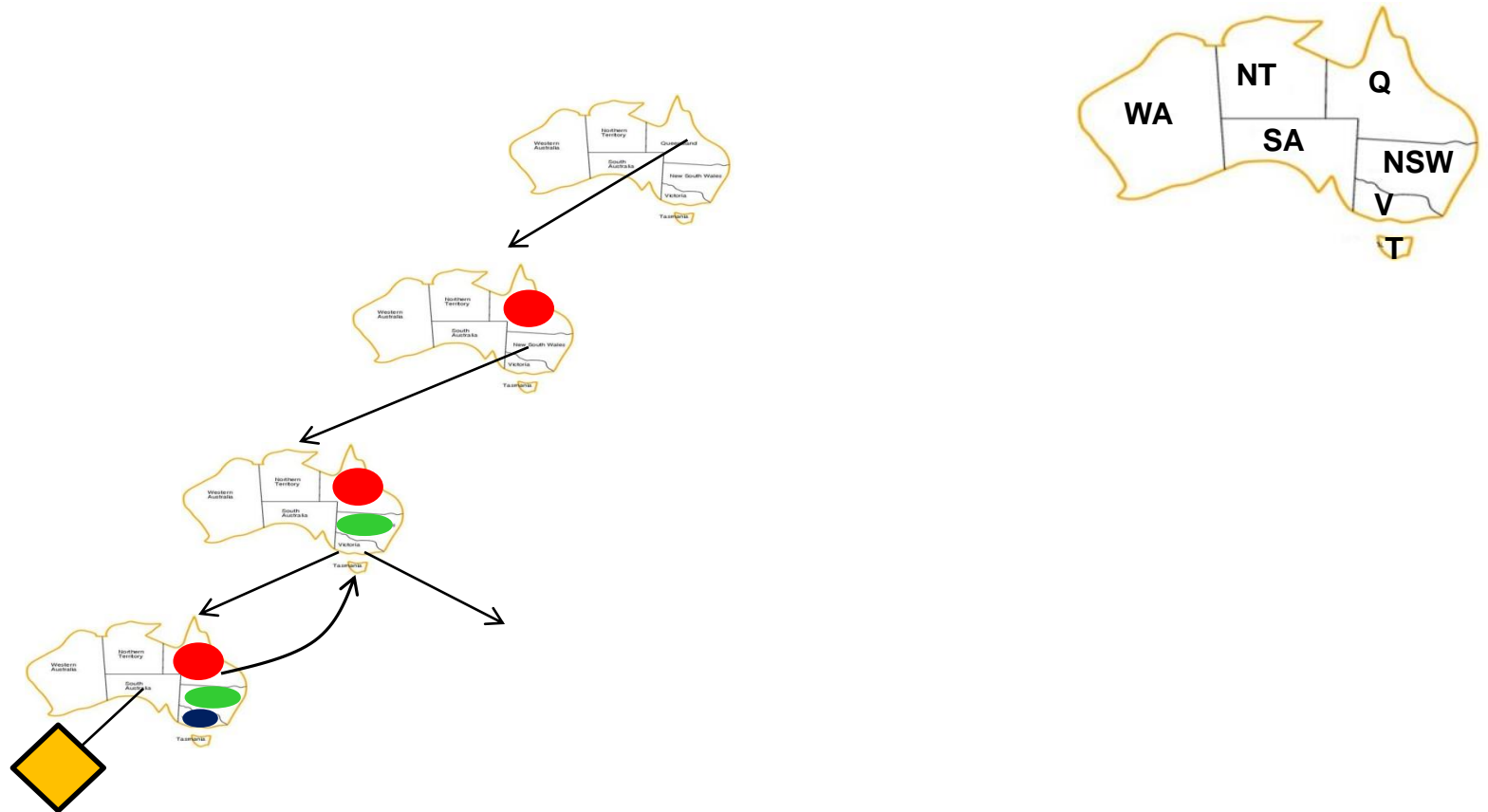
Backtracking Example



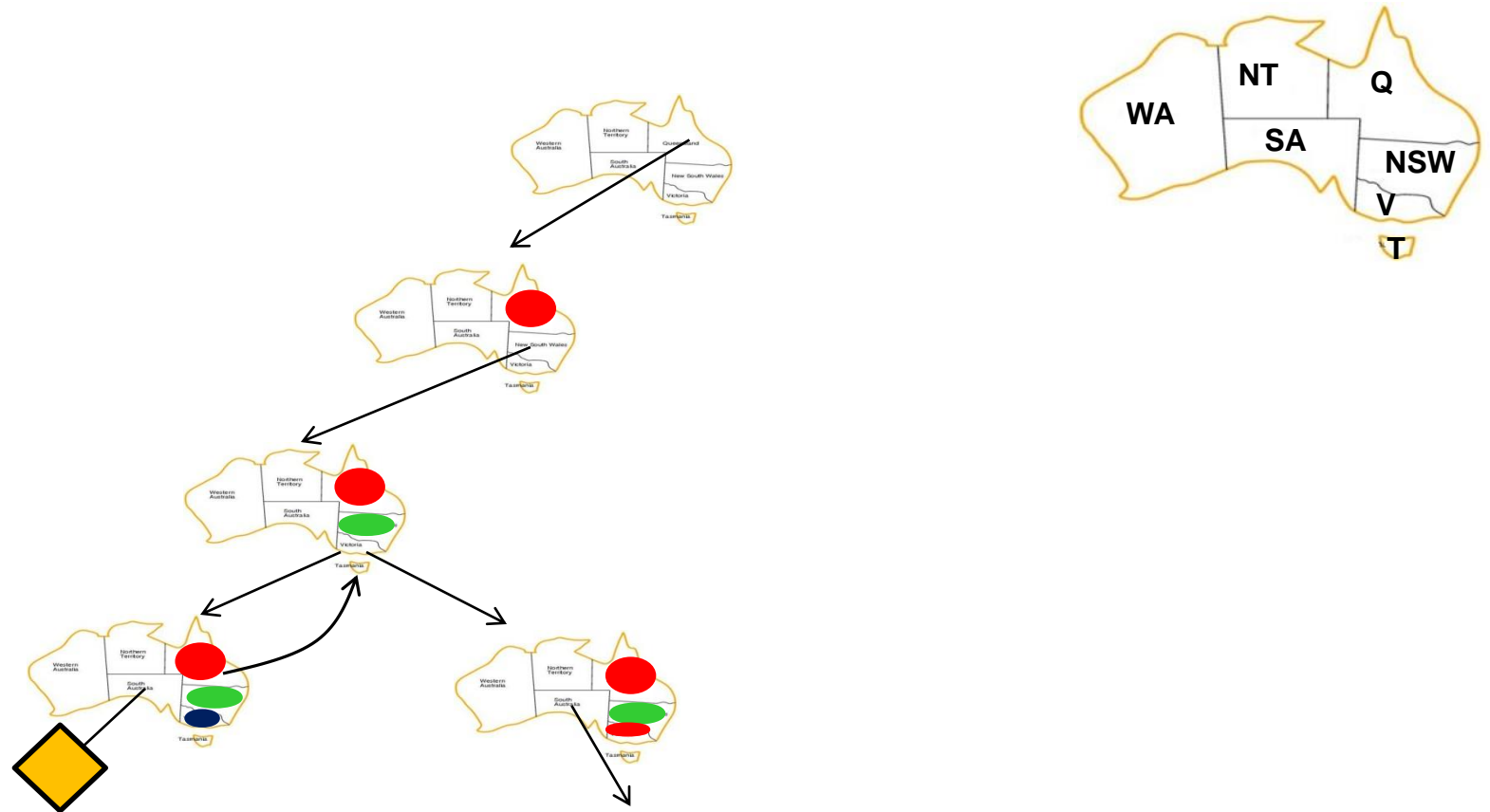
Backtracking Example



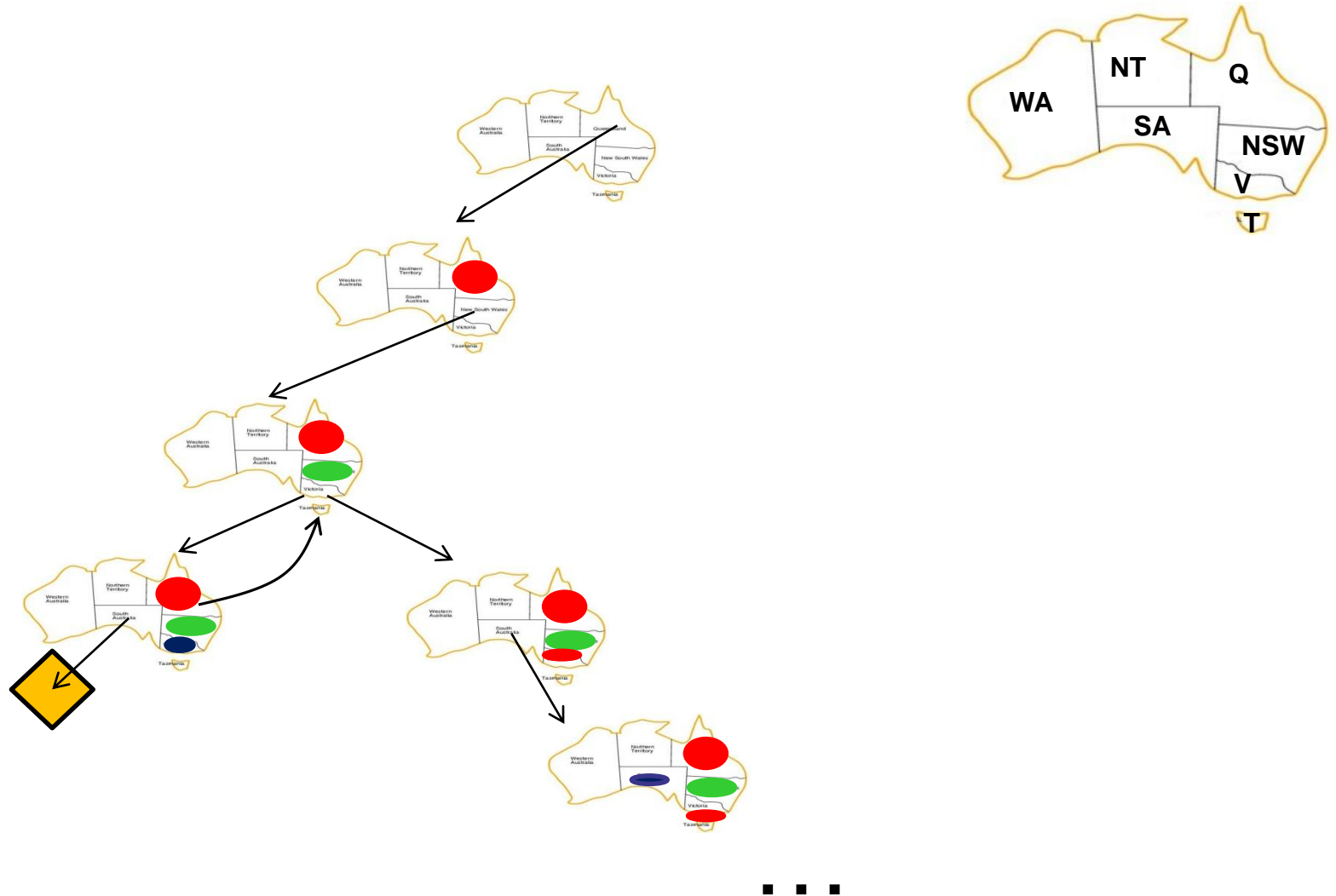
Backtracking Example



Backtracking Example



Backtracking Example

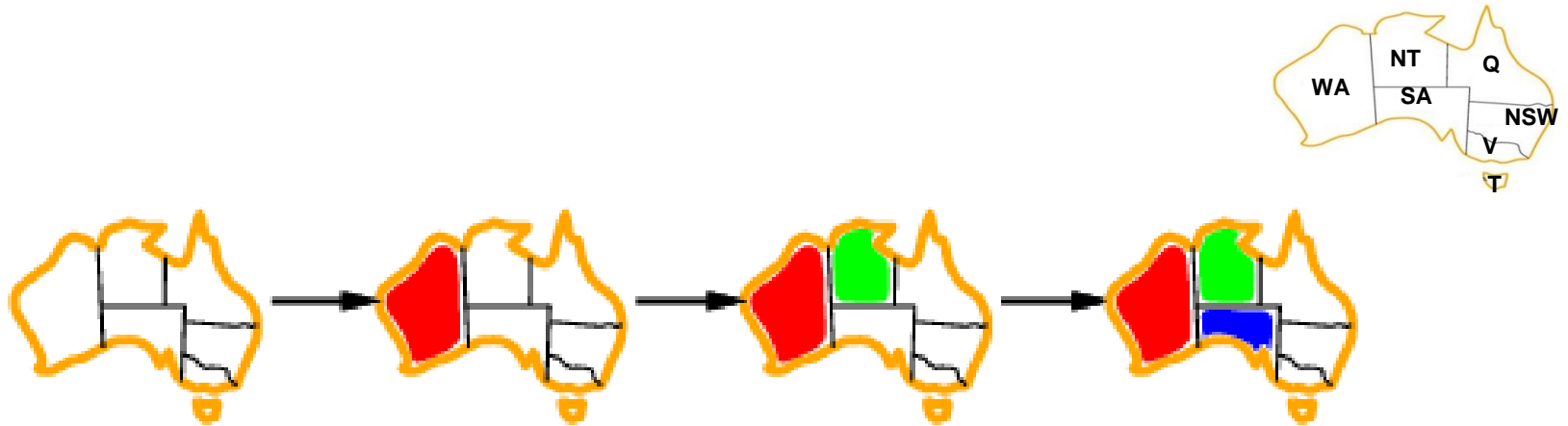


Backtracking Algorithm

function BACKTRACKING-SEARCH(*csp*) **returns** a solution, or failure
 return BACKTRACK({ }, *csp*)

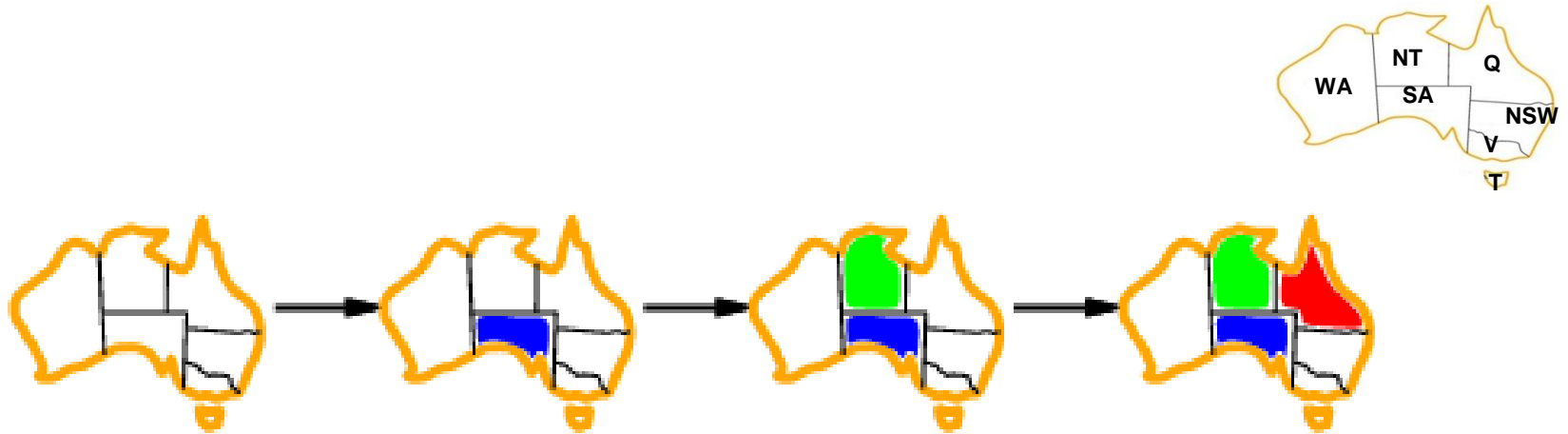
function BACKTRACK(*assignment*, *csp*) **returns** a solution, or failure
 if *assignment* is complete **then return** *assignment*
 var \leftarrow SELECT-UNASSIGNED-VARIABLE(*csp*)
 for each *value* **in** ORDER-DOMAIN-VALUES(*var*, *assignment*, *csp*) **do**
 if *value* is consistent with *assignment* **then**
 add { *var* = *value* } to *assignment*
 inferences \leftarrow INFERENCE(*csp*, *var*, *value*)
 if *inferences* \neq failure **then**
 add *inferences* to *assignment*
 result \leftarrow BACKTRACK(*assignment*, *csp*)
 if *result* \neq failure **then**
 return *result*
 remove { *var* = *value* } and *inferences* from *assignment*
 return failure

Select-Unassigned-Variable



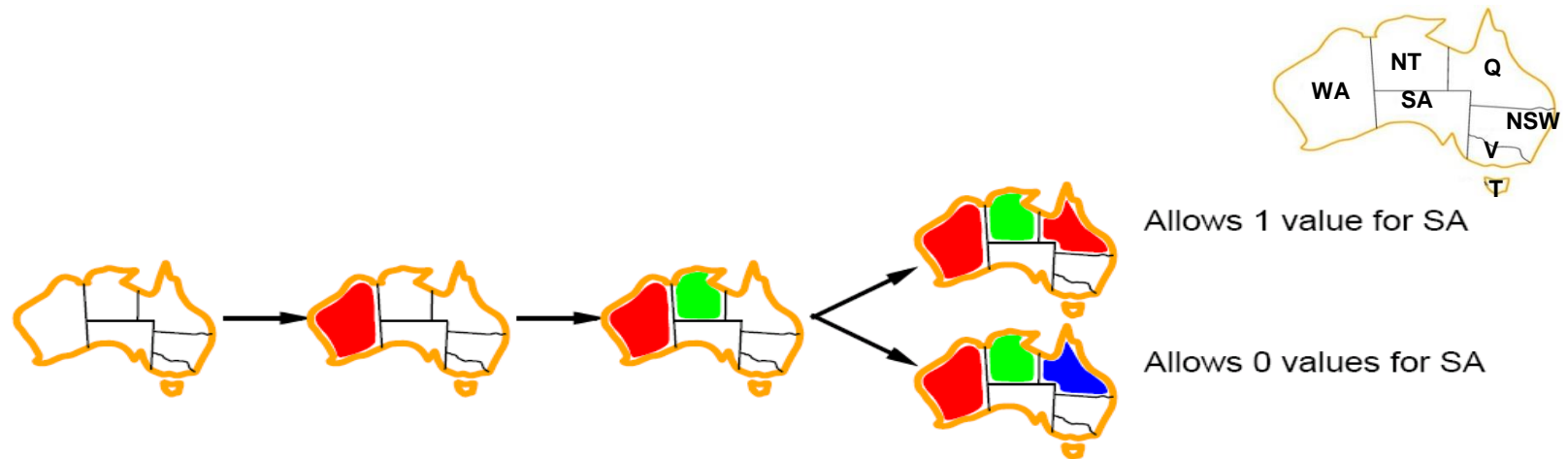
- Minimum remaining values (MRV)
- Rule: choose variable with the **fewest legal values**

Select-Unassigned-Variable



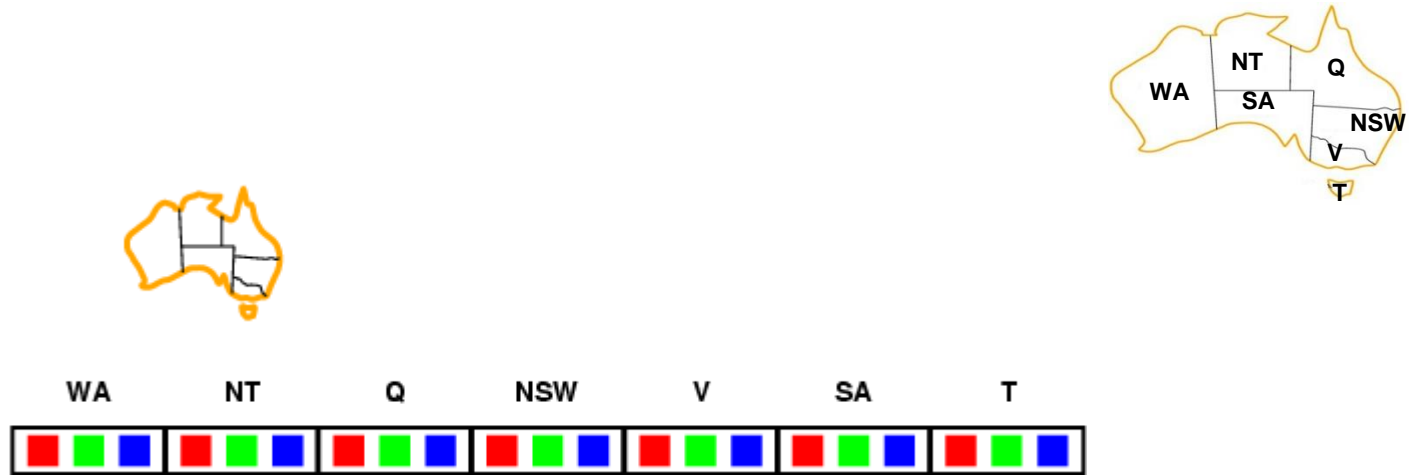
- Degree heuristic
- Rule: select variable that is involved in the largest number of constraints on other unassigned variables.
- Degree heuristic is very useful as a tie breaker

Order-Domain-Values



- Least constraining value heuristic
- Rule: given a variable choose the least constraining value i.e., the one that leaves the maximum flexibility for subsequent variable assignments.

Forward Checking



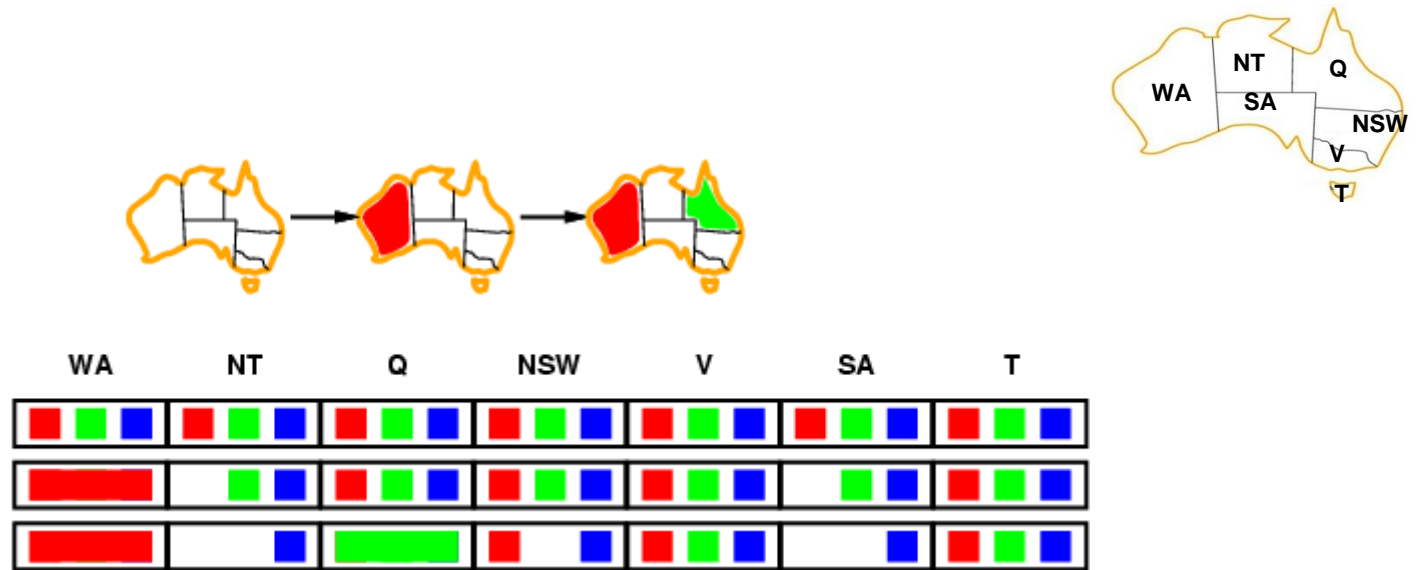
- **Forward checking:** Whenever a value v is assigned to a variable X_i , make all variables **consistent** with **this** assignment.
- Terminates search when any variable has no legal values.

Forward Checking



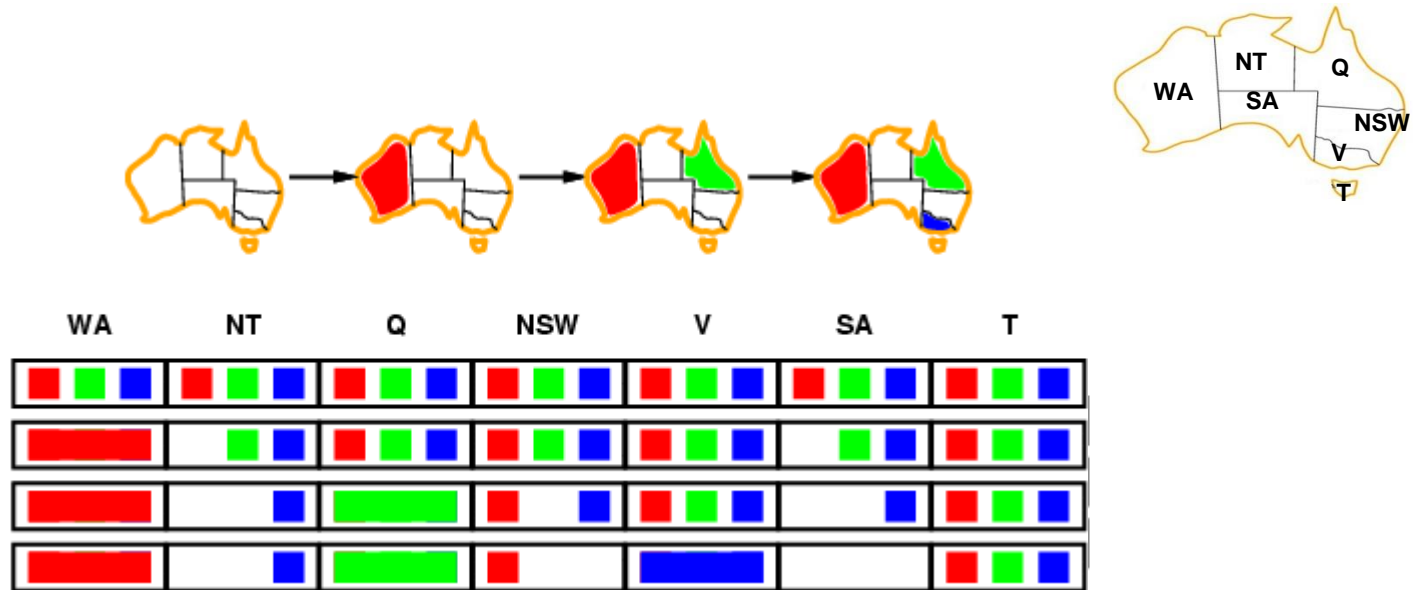
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Forward Checking



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Forward Checking Algorithm

function FORWARD-CHECKING-SEARCH(*csp*) **returns** a solution or failure
 return RECURSIVE-FORWARD-CHECKING({ },*csp*)

function RECURSIVE-FORWARD-CHECKING(*assignment*,*csp*) **returns** a solution or failure

if *assignment* is complete **then return** *assignment*

 var \leftarrow SELECT-UNASSIGNED-VARIABLE(VARIABLES[*csp*],*assignment*,*csp*)

for each *value* **in** ORDER-DOMAIN-VALUES(*var*, *assignment*, *csp*) **do**

if *value* is consistent with *assignment* **do**

 add {*var*=*value*} to *assignment*

***inferences* \leftarrow remove all domain values of remaining variables
 inconsistent with {*var* = *value*}**

if *inferences* \neq failure **then**

add *inferences* to *assignment* and **update** *csp*

result \leftarrow RECURSIVE-FORWARD-CHECKING(*assignment*, *csp*)

if *result* \neq failure **then**

result *result*

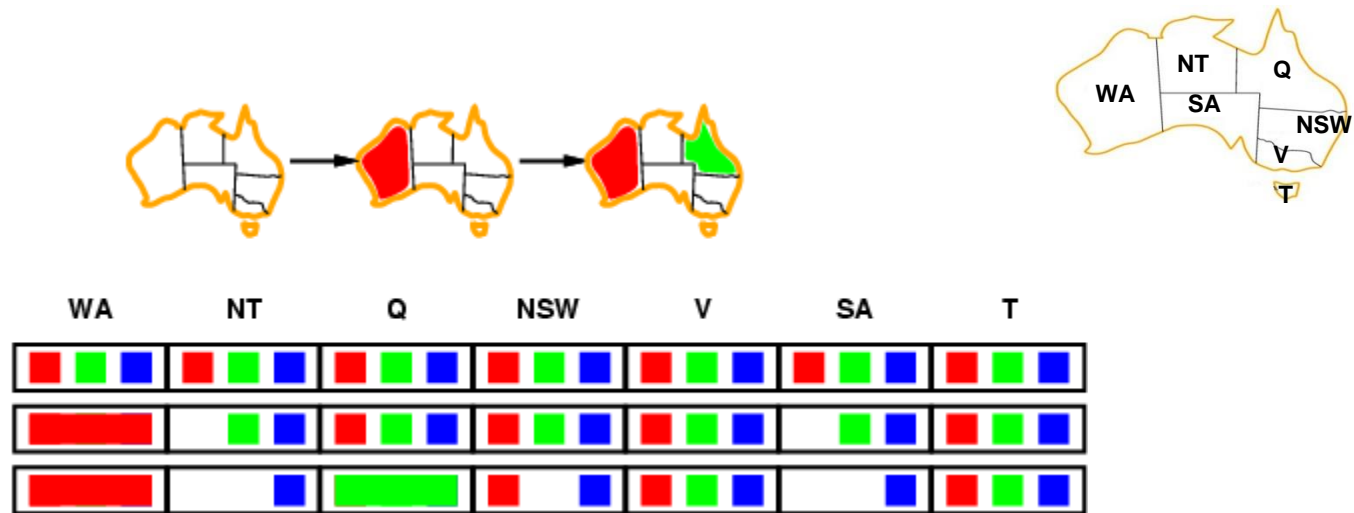
 remove {*var*=*value*} and *inferences* from *assignment* and *csp*

return failure



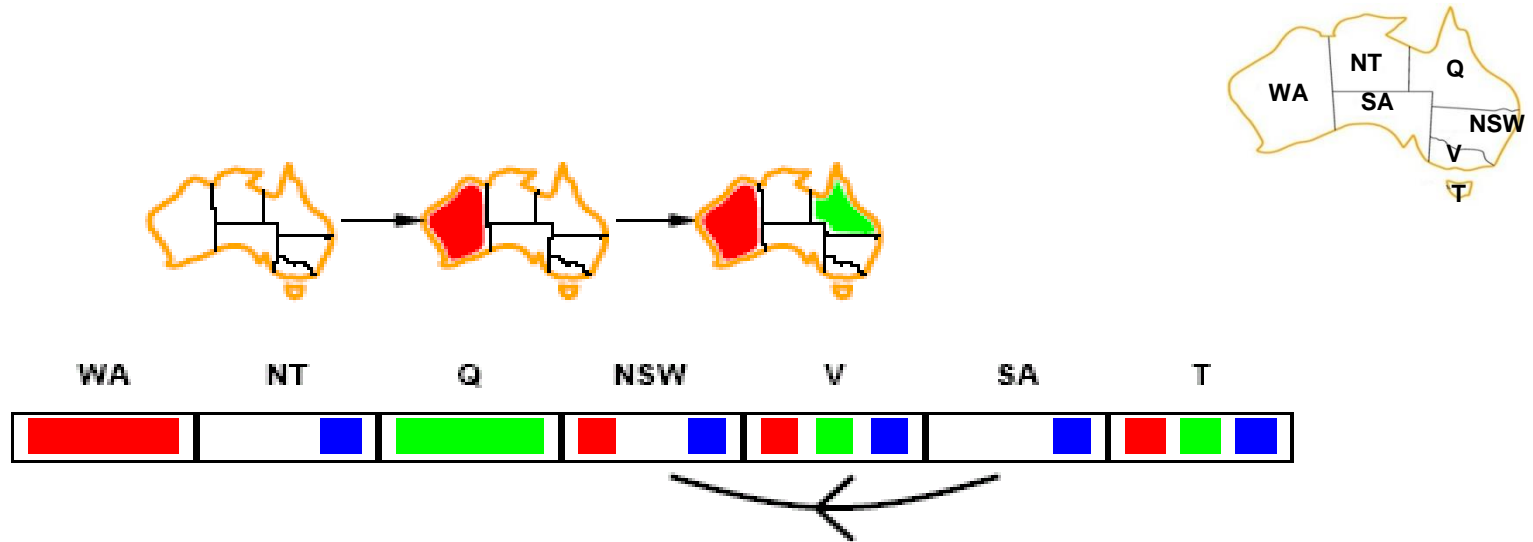
Forward Checking

- **Forward checking** propagates information from assigned to unassigned variables, but doesn't provide early detection for all failures:



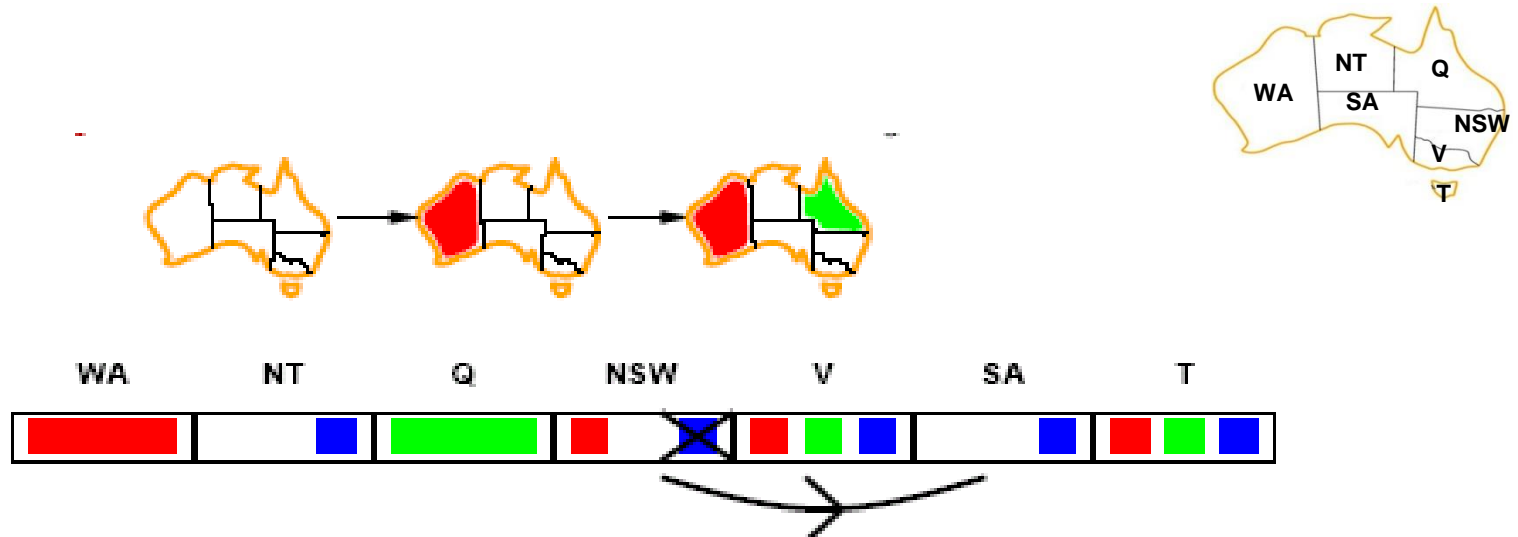
NT and SA cannot both be blue!

Arc Consistency



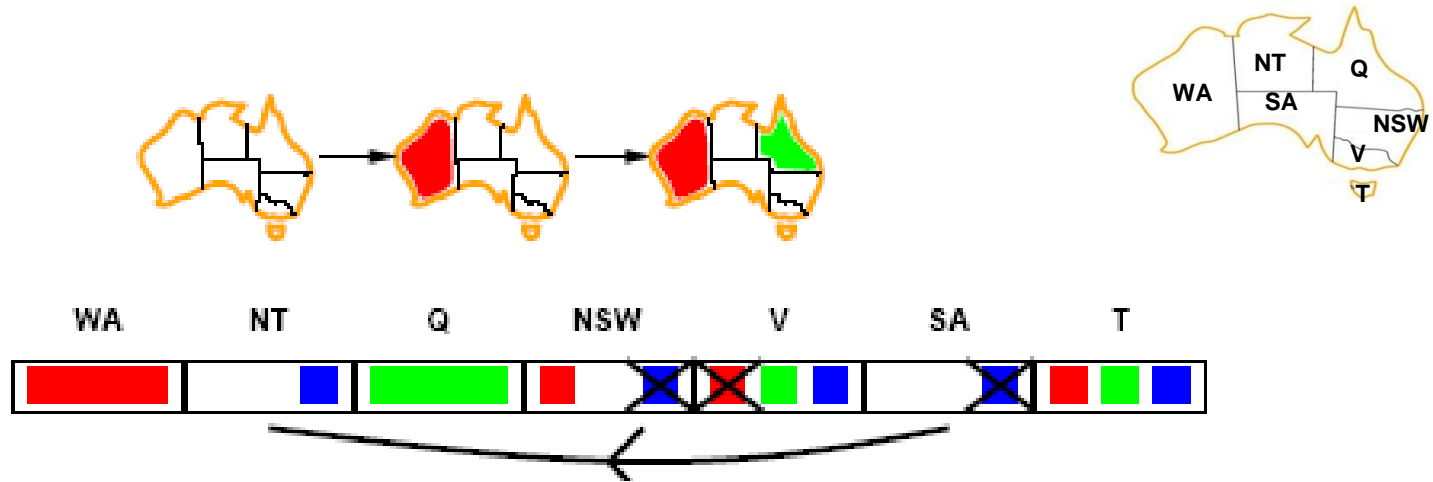
- $X \rightarrow Y$ is consistent iff for **every** value u_i of X there is some allowed v_j value in Y

Arc Consistency



- $X \rightarrow Y$ is consistent iff for **every** value u_i of X there is some allowed v_j value in Y

Arc Consistency



- $X \rightarrow Y$ is consistent iff for **every** value u_i of X there is some allowed v_j value in Y .
- Arc consistency detects failure earlier than FC

MAC

function MAC-SEARCH(*csp*) **returns** a solution or failure
 run **AC-3**(*csp*)
 return RECURSIVE-MAC({},*csp*)

function RECURSIVE-MAC(*assignment*,*csp*) **returns** a solution or failure
 if *assignment* is complete **then return** *assignment*
 var ← SELECT-UNASSIGNED-VARIABLE(VARIABLES[*csp*],*assignment*,*csp*)
 for each *value* **in** ORDER-DOMAIN-VALUES(var, *assignment*, *csp*) **do**
 if *value* is consistent with *assignment* **do**
 add {var=*value*} to *assignment*
 ***inferences* ← AC-3(*csp*)**
 if *inferences* ≠ failure **then**
 add *inferences* to *assignment* and update *csp*
 result ← RECURSIVE-MAC(*assignment*, *csp*)
 if *result* ≠ failure **then**
 result *result*
 remove {var=*value*} and *inferences* from *assignment* and *csp*
 return failure

Global Constraints

Definition

- Depends on arbitrary number of variables

Generalized Arc Consistency (GAC)

- For each value in domain of X_i , there exists a valid assignment for all the remaining variables in the constraint
- $x, y, z \in \{1, 2, 3\}$, $[x > y \wedge y = z]$: $\{(3, 2, 2), (3, 1, 1), (2, 1, 1)\}$
GAC : $x \in \{2, 3\}$, $y \in \{1, 2\}$, $z \in \{1, 2\}$

Alldifferent

- Alldifferent: all $X_i \in \text{scope}$ of constraint are assigned to different values.

e.g. $X_1, \dots, X_4 \in \{0, 1, 2, 3, 4\}$ ***Alldiff***(X_1, X_2, X_3, X_4)

$X_1=0, X_2=1, X_3=2, X_4=3$ ✓

$X_1=0, X_2=1, X_3=1, X_4=2$ ✗

- How to represent Alldifferent with binary \neq constraints?

Simple approximation to AllDiff GAC

1. If $\#values < \#vars$ then return failure

$$X_1=0, X_2 \in \{1, 2\}, X_3 \in \{1, 2\}, X_4=3 \quad \checkmark$$

$$X_1 \in \{1, 2\}, X_2 \in \{1, 2\}, X_3 \in \{1, 2\}, X_4=3 \quad \times$$

2. Remove all vars with singleton domains

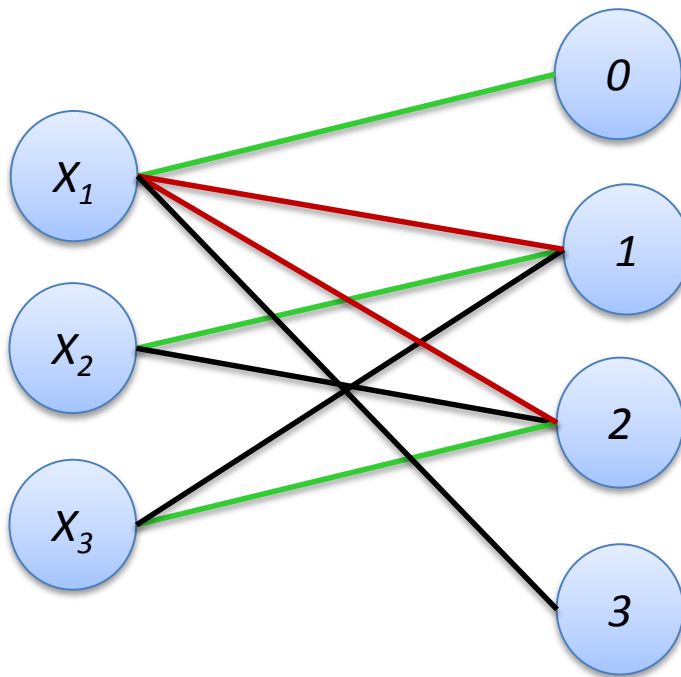
3. Remove singleton values from remaining domains

4. Goto 1

Fast Computation of AllDiff GAC

– GAC = Find all max matchings in a bipartite graph

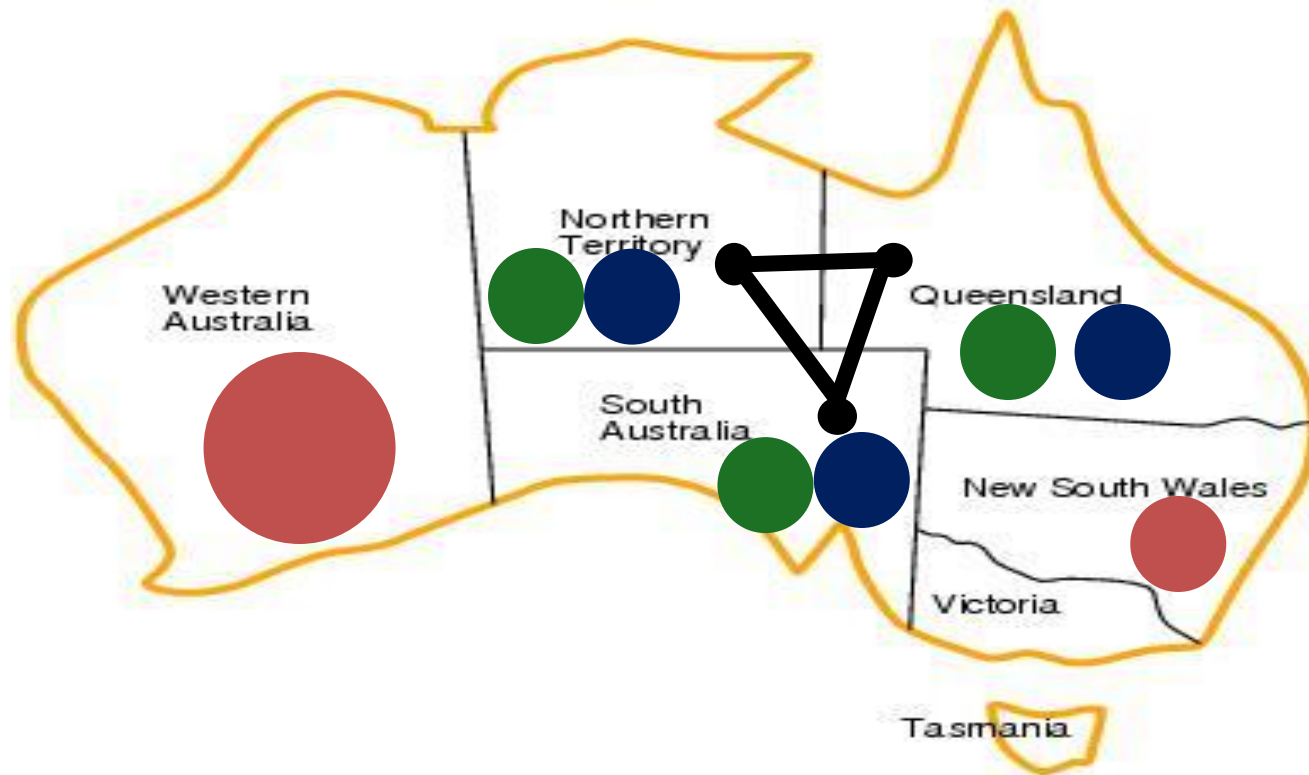
e.g. $X_1 \in \{0, 1, 2, 3\}$, $X_2 \in \{1, 2\}$, $X_3 \in \{1, 2\}$



Can be shown to be possible in $O(d\sqrt{n})$

Where AC-3 on $O(d^2)$ not equal constraints takes $O(d^5)$

AllDiff Stronger than binary constraints



Inconsistency detected by AllDiff GAC,
but not by AC-3!

Constraint propagation systems

World's best 08-12 **Gecode** (link on ISP learnit page)

- Constraint Store
- Propagators
- Propagator Loop
- Search

Constraint store

$x \in \{3,4,5\} \quad y \in \{3,4,5\}$

- Maps variables to possible values

Constraint store

finite domains

$x \in \{3,4,5\} \quad y \in \{3,4,5\}$

- Maps variables to possible values
- Others: finite sets, continuous domains, trees, ...

Constraints and Propagators

- Extensive use of global constraints
- Propagators **implement** constraints!
 - prune values in conflict with constraint
- Constraint propagation drives propagators for several constraints

Propagators

$$x \geq y$$

$$y > 3$$

$$x \in \{3, 4, 5\} \quad y \in \{3, 4, 5\}$$

- Amplify store by constraint propagation

Propagators

$x \geq y$

$y > 3$

$x \in \{3, 4, 5\} \quad y \in \{3, 4, 5\}$

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Propagators

$$x \geq y$$

$$y > 3$$

$$x \in \{3, 4, 5\} \quad y \in \{4, 5\}$$

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Propagators

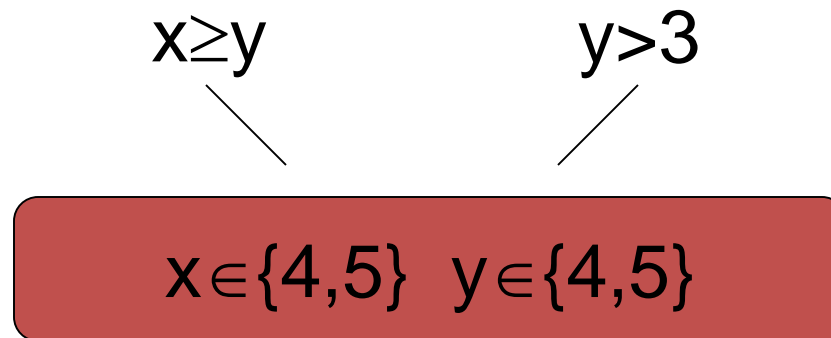
$$x \geq y$$

$$y > 3$$

$$x \in \{3, 4, 5\} \quad y \in \{4, 5\}$$

- Amplify store by constraint propagation

Propagators



- Amplify store by constraint propagation
- Disappear when done (subsumed, entailed)
 - no more propagation possible

Propagators

$x \geq y$

$x \in \{4,5\} \quad y \in \{4,5\}$

- Amplify store by constraint propagation
- Disappear when done (subsumed, entailed)
 - no more propagation possible

Propagation loop

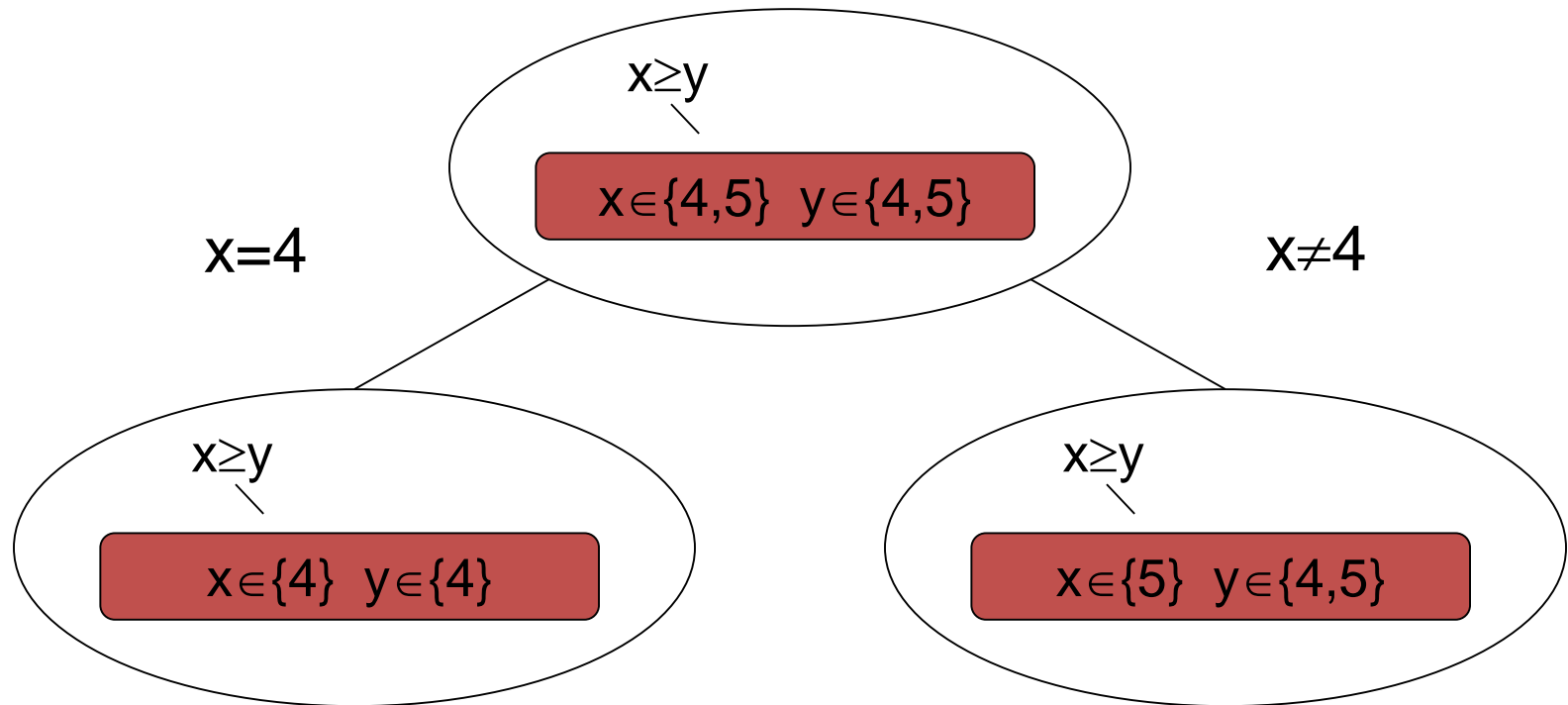
function PROPAGATE(*csp*)

```
     $Q \leftarrow \{c_1, c_2, \dots, c_n\}$  // Queue of propagators from csp  
    while  $Q \neq \{\}$  do  
         $c \leftarrow \text{REMOVE-FIRST}(Q)$   
        EXECUTE(c) // run propagator, prune domains of variables  
        if any domain in csp is empty then  
            return false  
        for each  $X_i \in \text{SCOPE}(c)$  s.t.  $D_i$  was narrowed do  
            ADD(GET-PROPS( $X_i$ ) - c) to  $Q$  //Add new propagators  
        end for  
    end while // Fixed point reached!!  
    return true
```


Search

- Propagation **alone** is not enough!
- Search: Explore search tree for solutions (Backtracking)
- Branching: Select variable and value (define search tree)
 - Minimum remaining values
 - Degree
 - Least constraining value

Search: Branching



- Create subproblems with additional information
- Enable further constraint propagation

Constraint propagation systems

- Each node in the search tree has different information.
- Constraint store and propagators are encapsulated in a **Space**.
- Manipulate spaces: Copy , add new constraints, ask for solutions, etc.

Search algorithm

function SEARCH(*csp*) **returns** solution or failure

csp \leftarrow PROPAGATE(*csp*)

if *csp* is failure **then return** failure

if *csp* is solved **then return** SOL(*csp*)

csp' \leftarrow *csp*

ADD(*csp*' , BRANCH(*csp*' ,1))

csp'' \leftarrow *csp*

ADD(*csp*'', BRANCH(*csp*'',2))

solution \leftarrow SEARCH(*csp*')

if *solution* is valid **then return** *solution*

else return SEARCH(*csp*'')

function BRANCH(*csp*, *nbranch*)

return the constraint representing the *nbranch* according to variable and value heuristic selection.