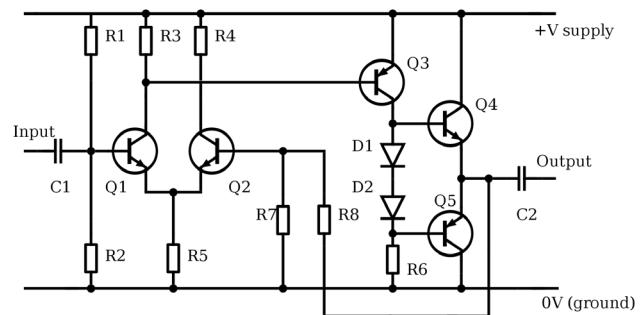


Lecture 7 – Microcontrollers

Andrés Faíña (anfv@itu.dk)



You can take an Arduino kit until March 25

- Sign up after the lab

- Practice different circuits at home

- Arduino Kit Guide is a recommended lecture

From March 25, take Arduinos boards, shields, sensors and hardware, but no Arduino kits

Add your project group to the Google docs document (LearnIT)

The auto-focus of the laser cutter is broken

- use manual focus, ask TAs

Preferably, use PMMA (acrylic) instead of POM

Startup programme presentation (Vlad)

Overview

DC/DC converters

Servos

Ultrasound sensors

Digital communications

Accelerometers / IMU (I2C)

Stable voltage

Issues

Input voltage can vary

Batteries

Noise

Load conditions (e.g., $I=0$ to $400mA$)

How can we have a fixed voltage output?

Linear regulators

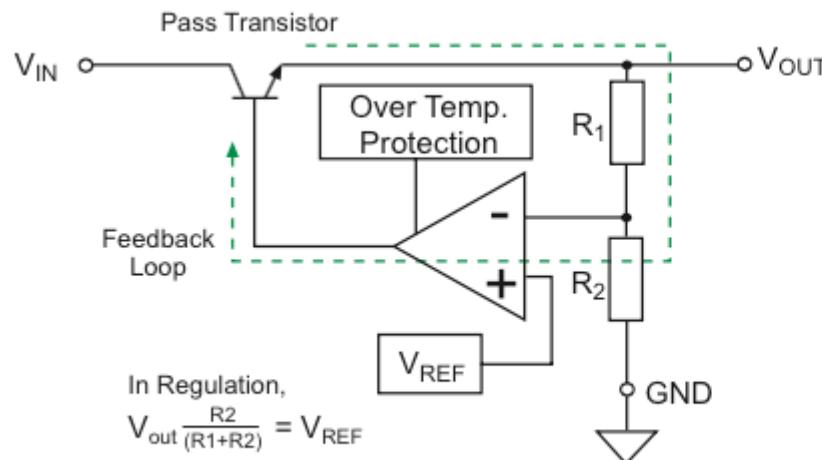
DC/DC converters

Linear regulators

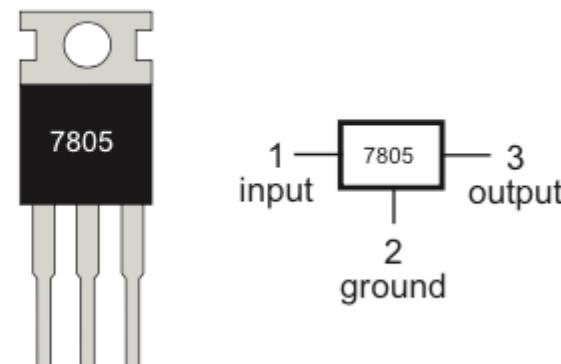
Use a transistor and a fixed voltage reference to keep constant the output voltage

Cons:

Generate heat, specially if $V_{IN} \gg V_{OUT}$ or I is high
Only decreases the voltage ($V_{OUT} < V_{IN}$)

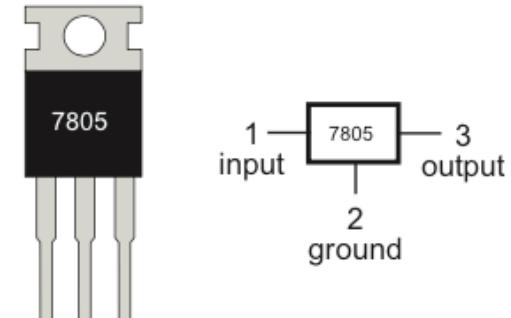


7805 PINOUT DIAGRAM

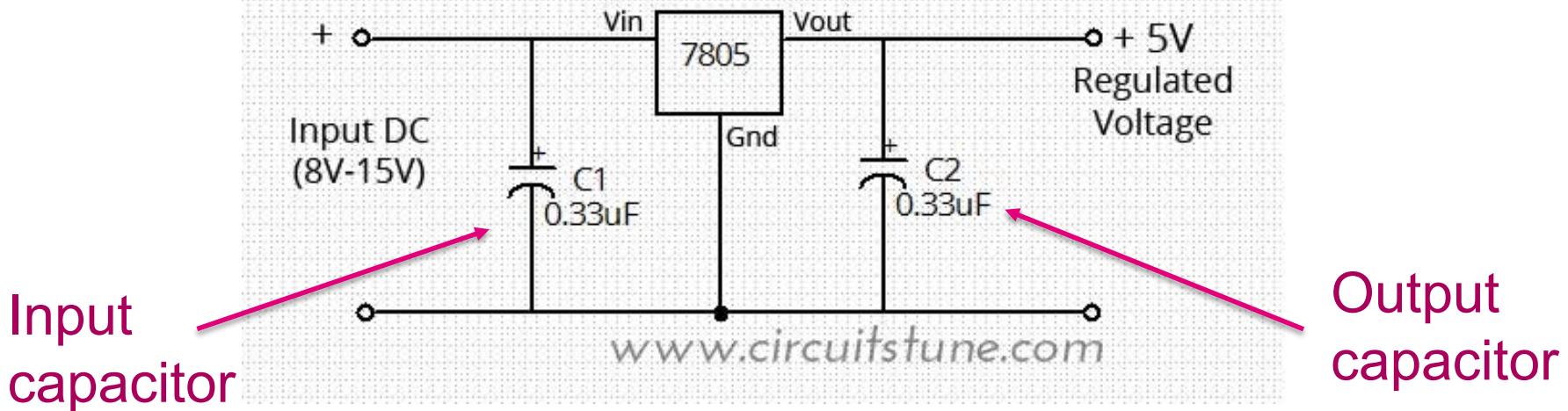


An example: 7805

7805 PINOUT DIAGRAM



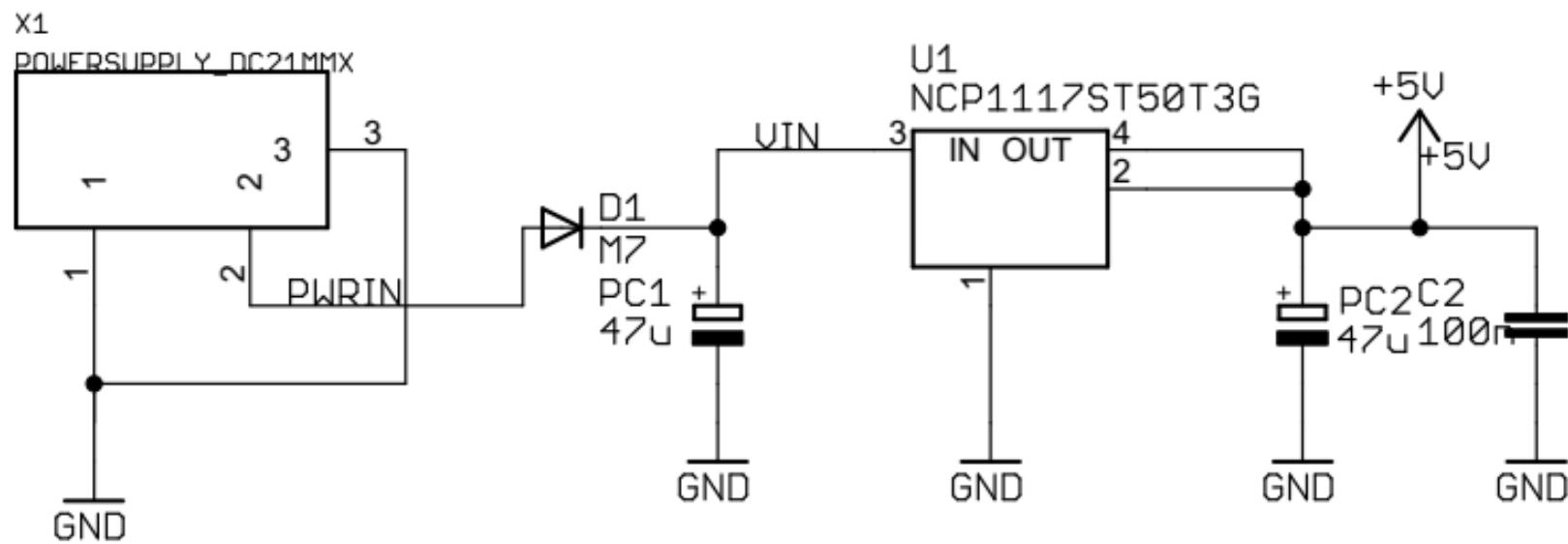
7805 Voltage Regulator Circuit



Always place two capacitors! (stability)

Where are the two resistors?

Example II: Arduino Uno schematics



DC / DC converters

Convert DC voltage to another voltage

Almost no losses of energy

Noisy (not suitable for precise analog measurements)

Different types

Boost:

Steps up voltage ($V_{in} < V_{out}$)

Buck:

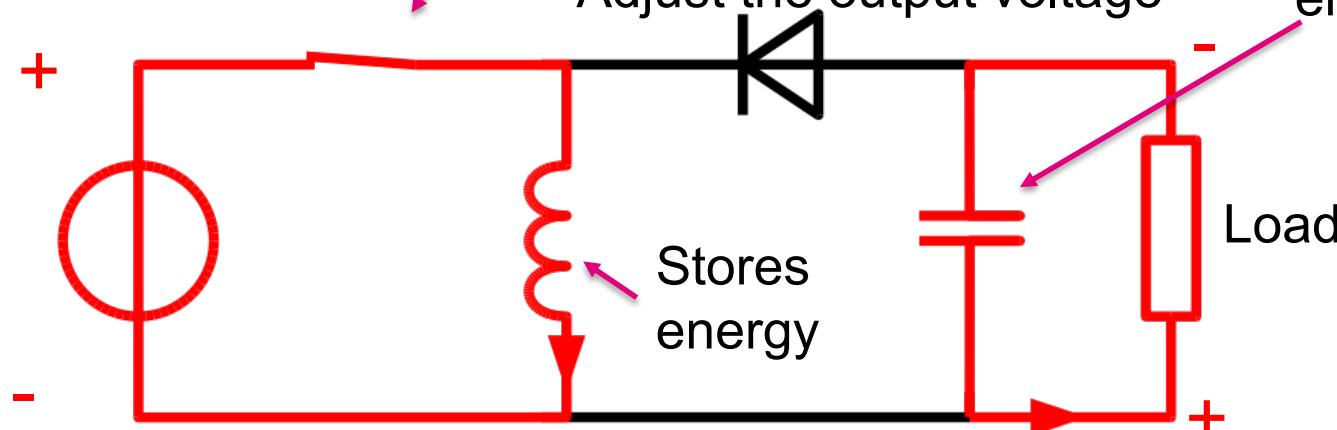
Steps down voltage ($V_{in} > V_{out}$)

Buck-boost:

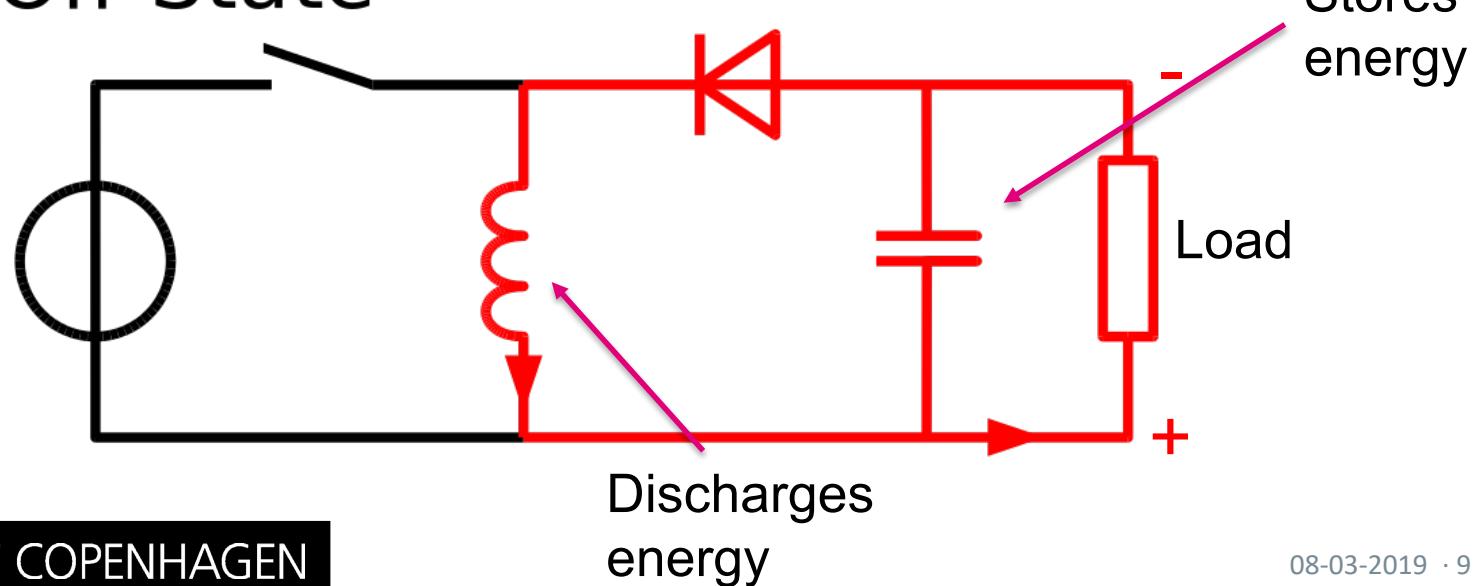
Output voltage is higher or smaller than the input

Buck-Boost converter

On-State



Off-State

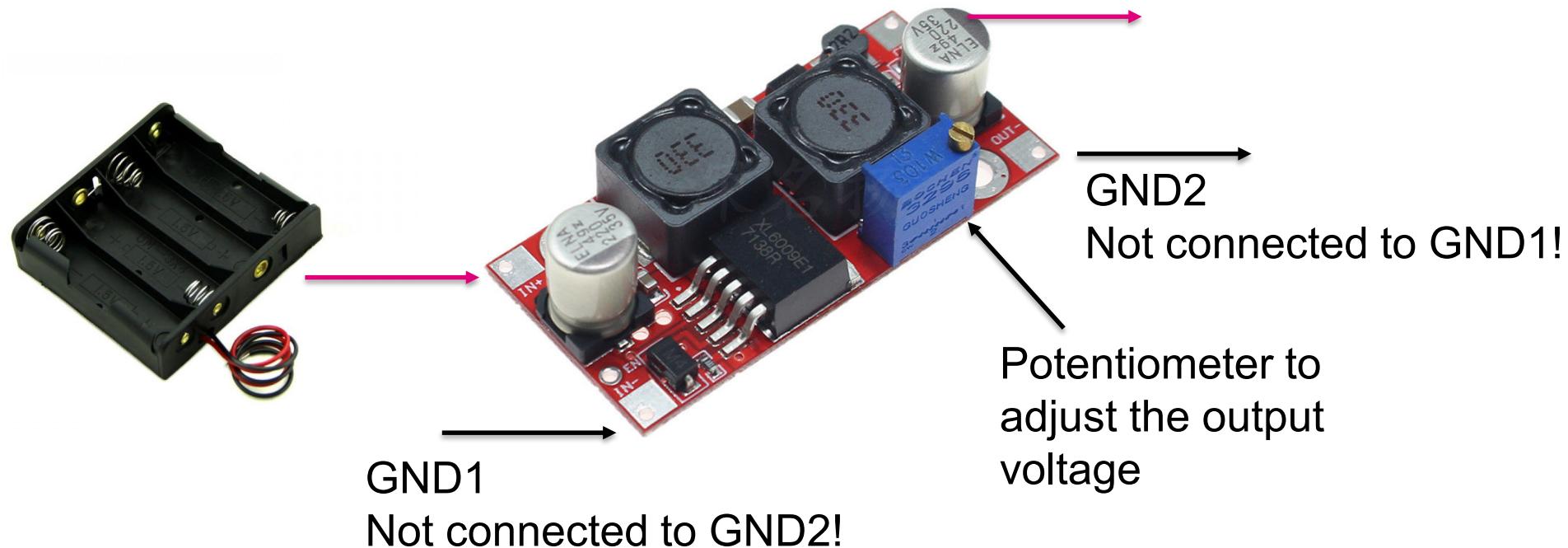


Buck-Boost available at REAL

5-6V

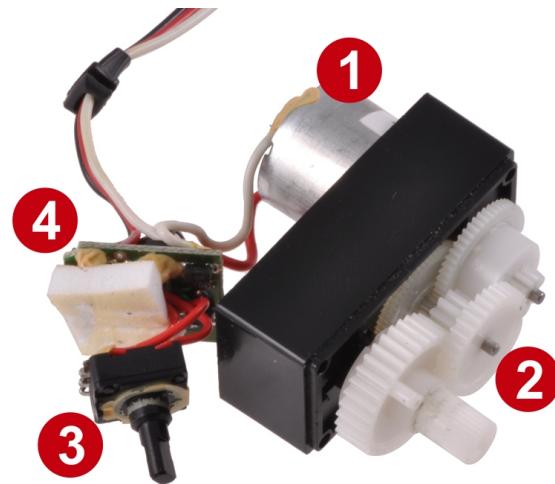
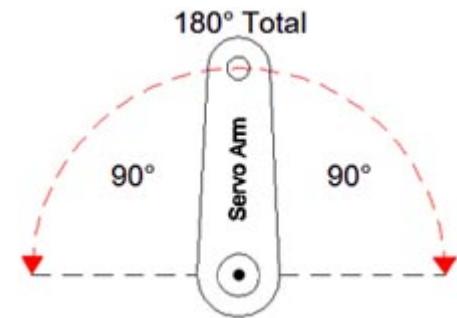
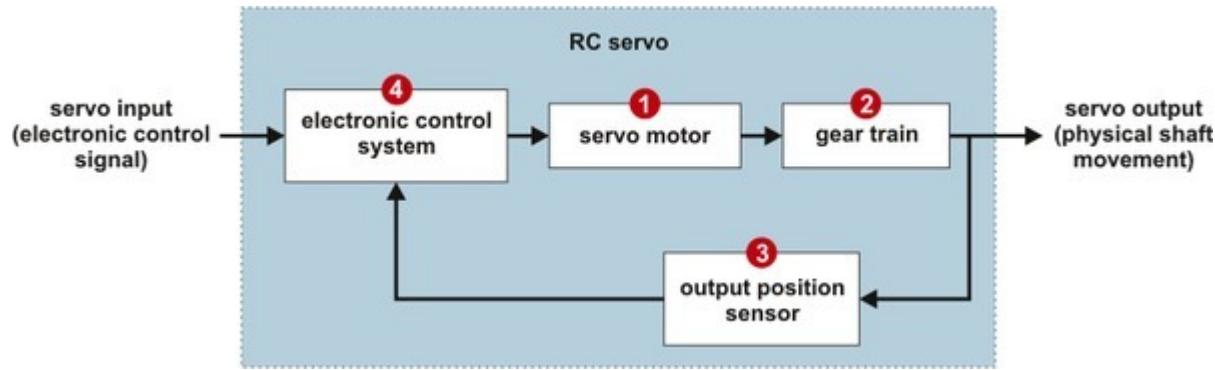
Buck-Boost

12V



How to reach a specific position with a DC motor?

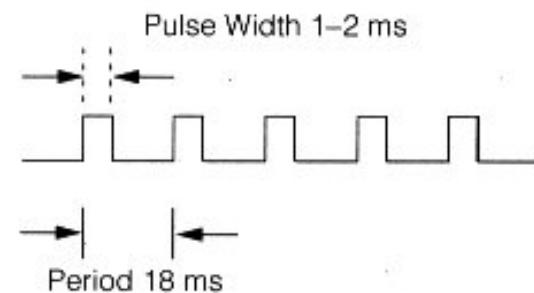
RC servos



RC Servos



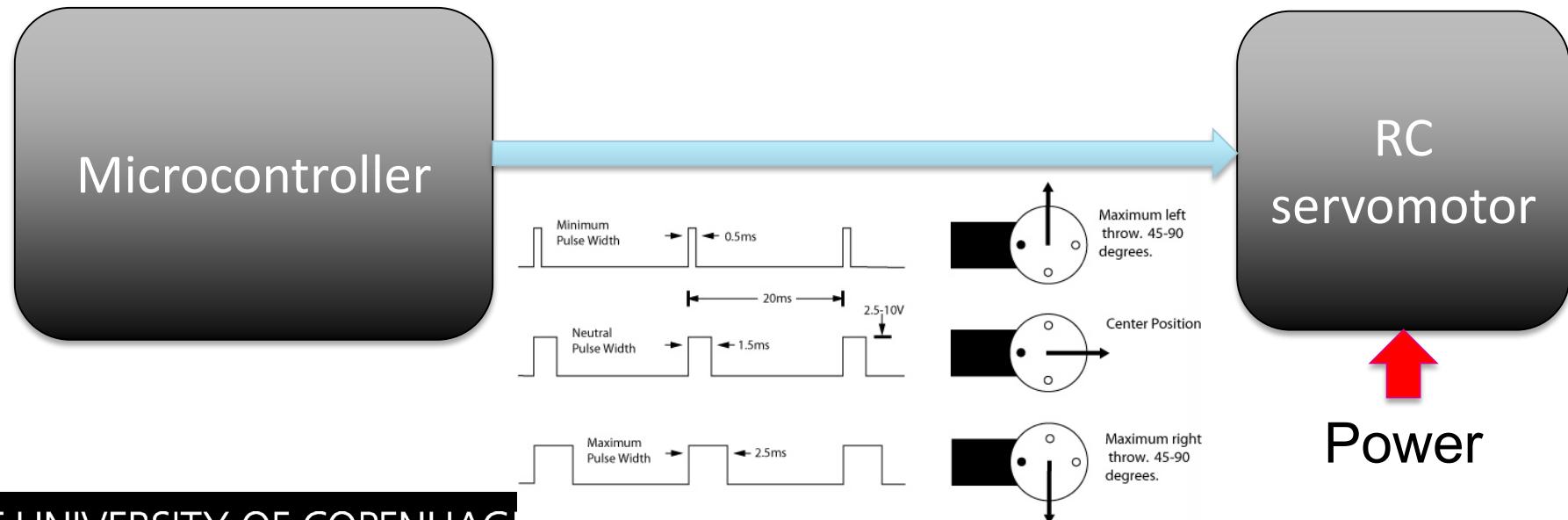
n



- 1 ms Pulse Train
Servo Motor Position
Left
- 1.5 ms Pulse Train
Servo Motor Position
Midrange
- 2 ms Pulse Train
Servo Motor Position
Right
-
- Four circular icons with arrows indicating the direction of rotation for each pulse train configuration:
- The first icon shows a counter-clockwise arrow and is associated with a 1 ms pulse train for the left position.
 - The second icon shows an upward arrow and is associated with a 1.5 ms pulse train for the midrange position.
 - The third icon shows a clockwise arrow and is associated with a 2 ms pulse train for the right position.
 - The fourth icon shows a clockwise arrow and is associated with a 2 ms pulse train for the right position (repeated entry).

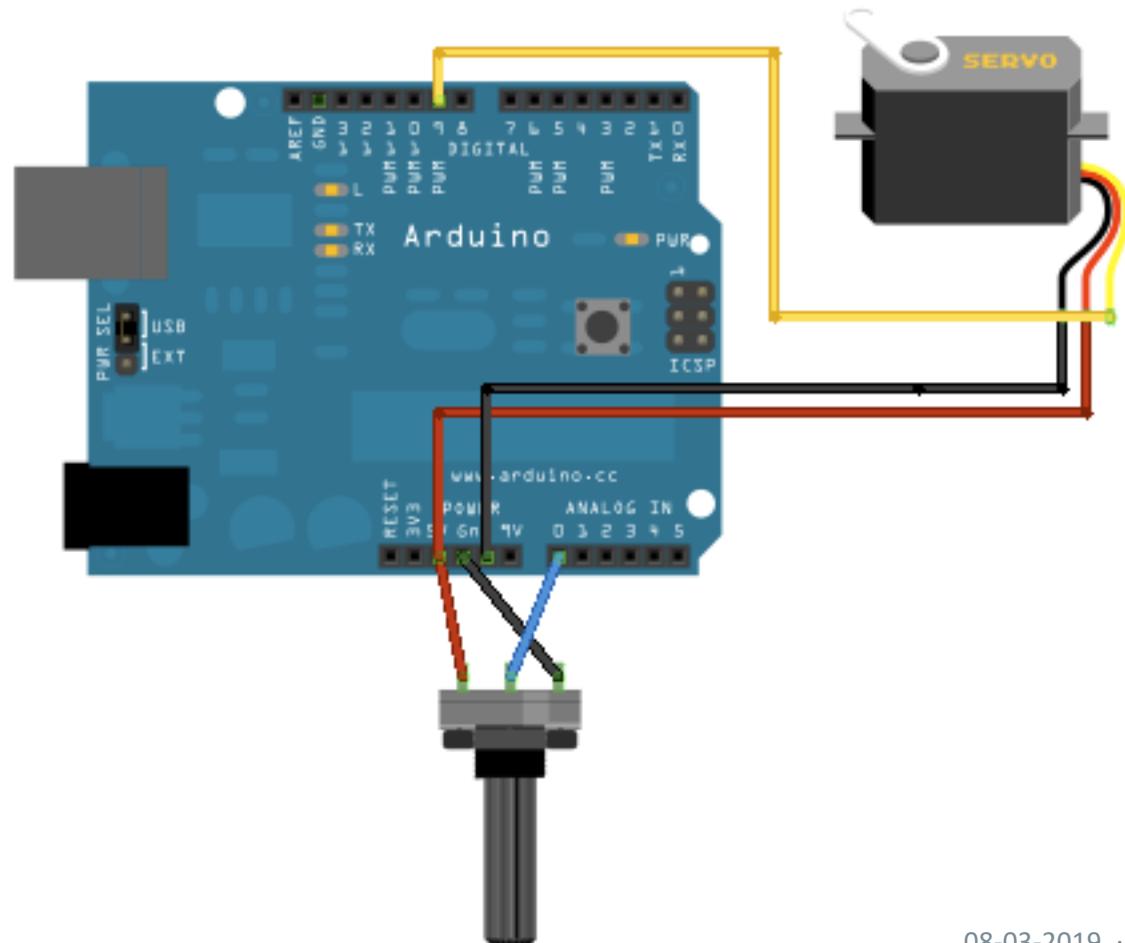
Servomotor- Control

- Microcontroller sets a target
- Servomotor tries to reach the target
 - Calculates the error
 - Calculates the output (voltage)
 - Applies the voltage to the motor



Exercise #1 - Moving a servo

Control the position la servo with a potentiometer
Use servo library



Questions? (Servos)

Connect a RC servo to an Arduino

Try to move it to different positions setting a target
with a potentiometer

Keep one position and apply a force to the shaft

Does the servo keep the position?

What happens if you remove the force?

What happens if you apply more force?

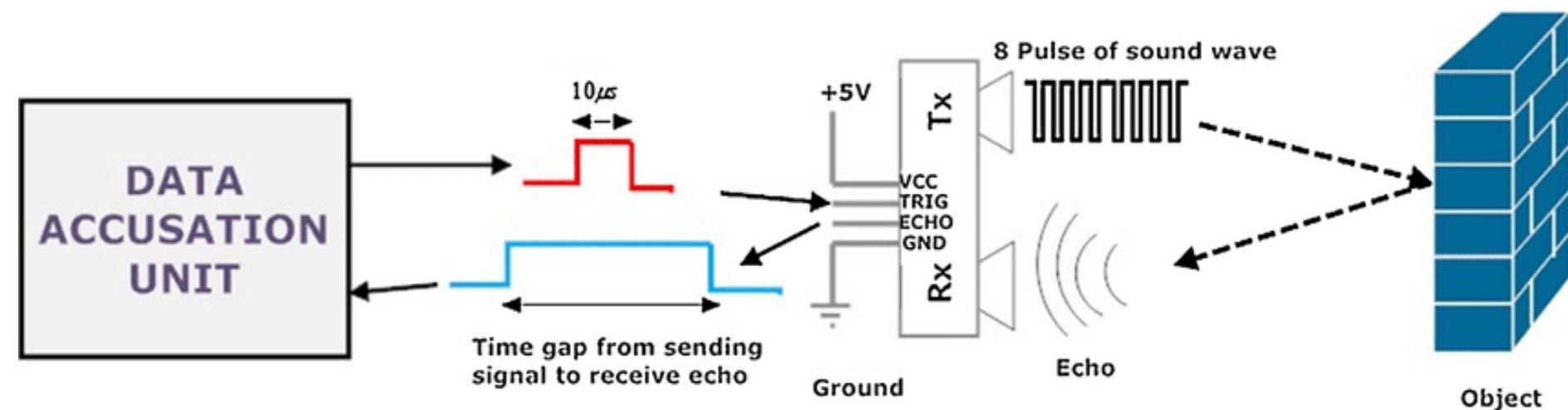
But be gentle when applying the force!

Ultrasound sensors

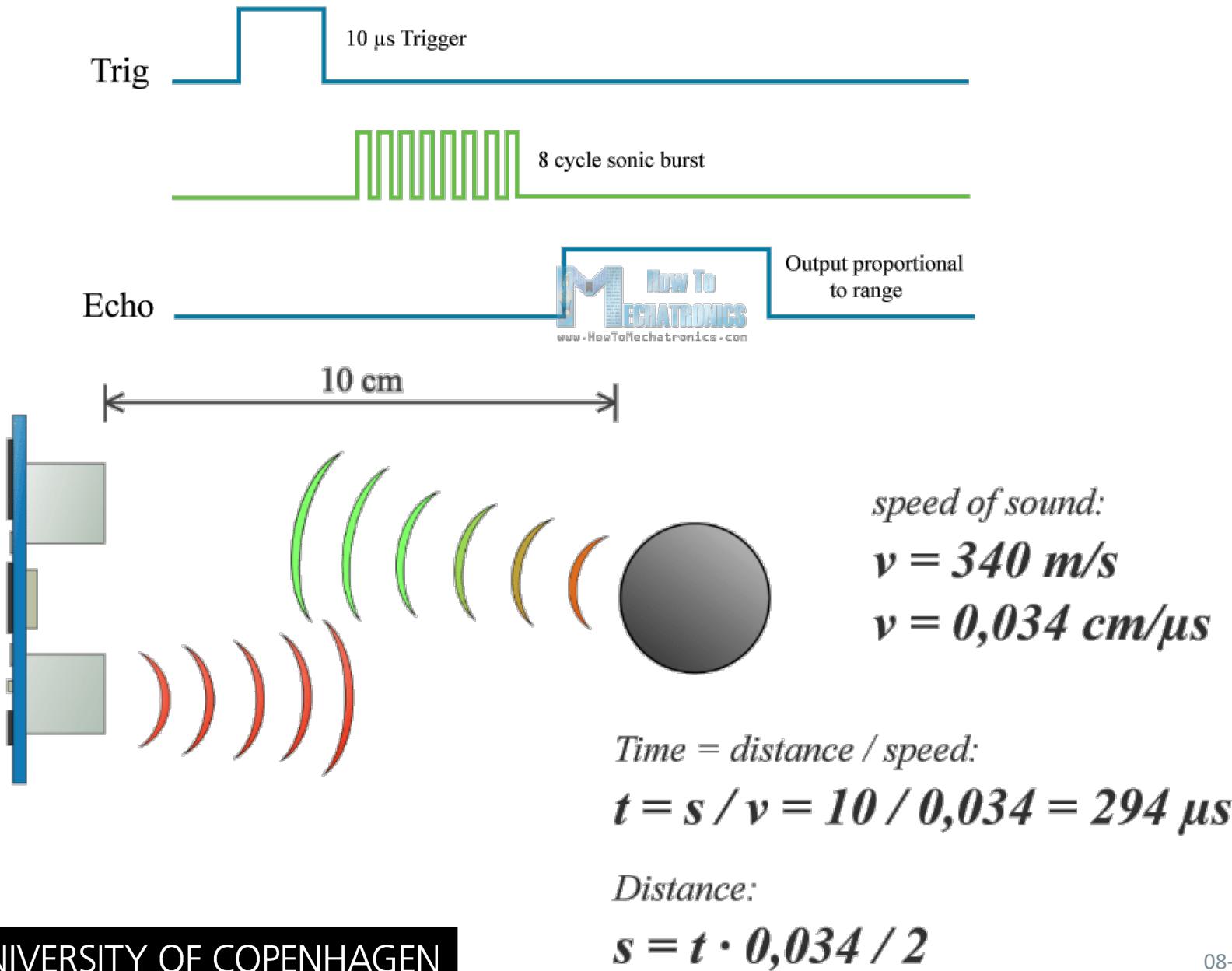
Similar to reflective optosensors

Use sound (instead of light)

Measure the time of flight (instead intensity of light)



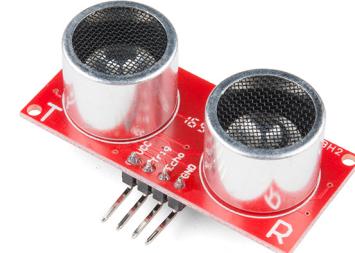
Working principle



Ultrasound sensor - HC-SR04

<https://www.sparkfun.com/products/13959>

<http://howtomechatronics.com/tutorials/arduino-ultrasonic-sensor-hc-sr04/>



Place the sensors in front of a white obstacle

Start with a distance of 0cm and note the value of the sensor, move the object (or the sensor) 10cm backwards at a time and note the values

Now plot the data (e.g. in Excel) and use it to answer the following questions:

Can you use the sensors to distinguish black from white?

Can you use the IR/US light sensors to measure distance?

Does the angle between sensor and object matter?

Does the material of the object matter?

Digital protocols

The ucontrollers can communicate with other devices through digital protocols

Features:

- Multi-master or 1master multi-slaves
- Easy to implement (low number of lines)
- Medium speeds (400kHz to 5MHz)

Types:

Uart (serial)

SPI

I2C

USB

CAN

USART - Universal Synchronous Asynchronous Receiver Transceiver (Serial)

We have a serial port between the Arduino and our computer

Try to print a message or a number

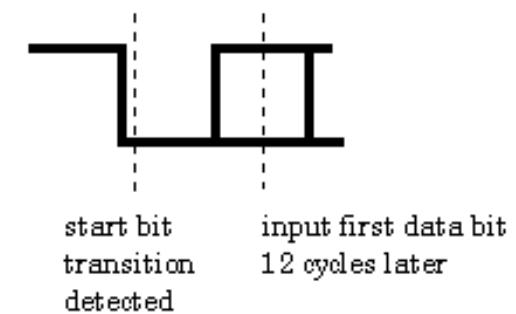
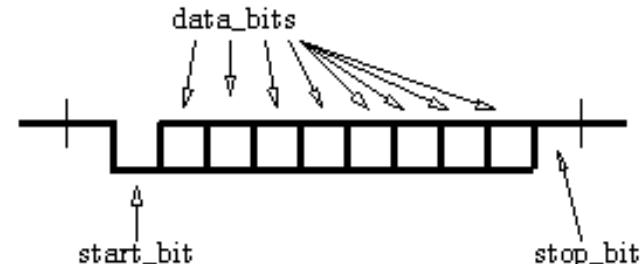
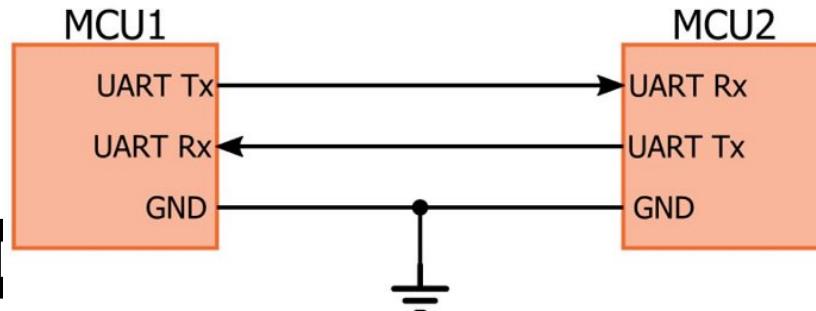
Open Serial monitor

2 lines:

Rx

Tx

TX are RX are crossed over!



SPI / I2C (Wire or TWI)

I2C

Only 2 lines (SDA, SCL)
with pull up resistors!

Slaves have addresses
up to 400kHz

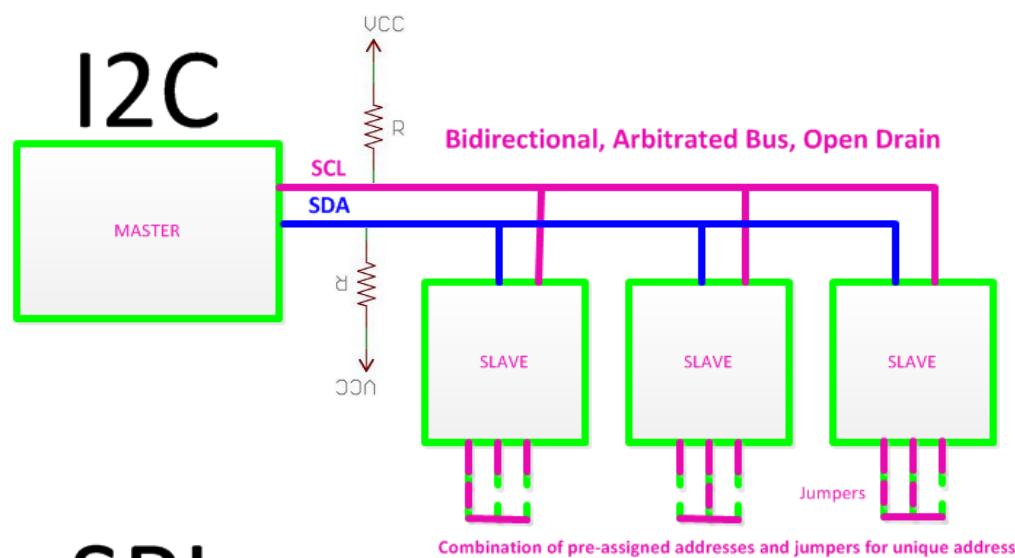
Multimaster

SPI

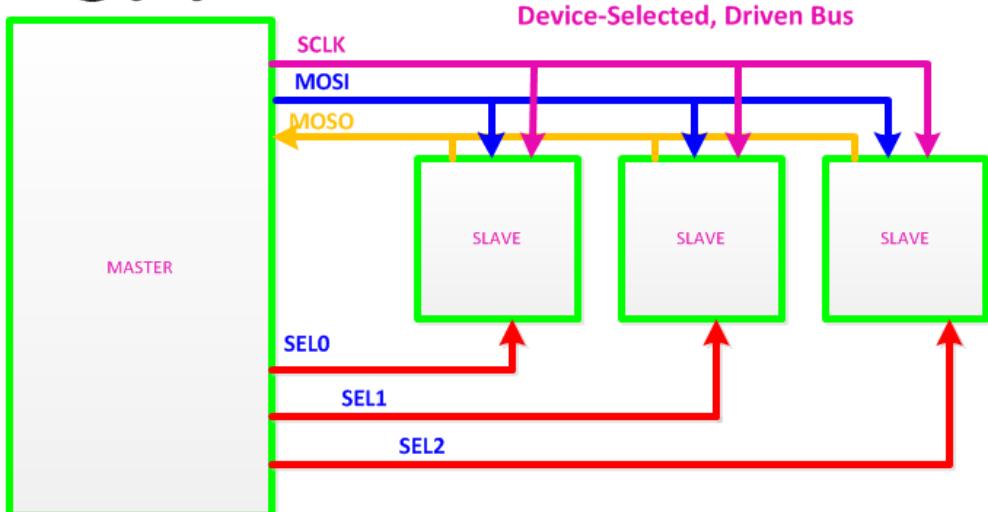
3 lines and 1 CS per slave
(MOSI, MISO, SCLK)

Slaves not need addresses
up to 14MHz

1 master

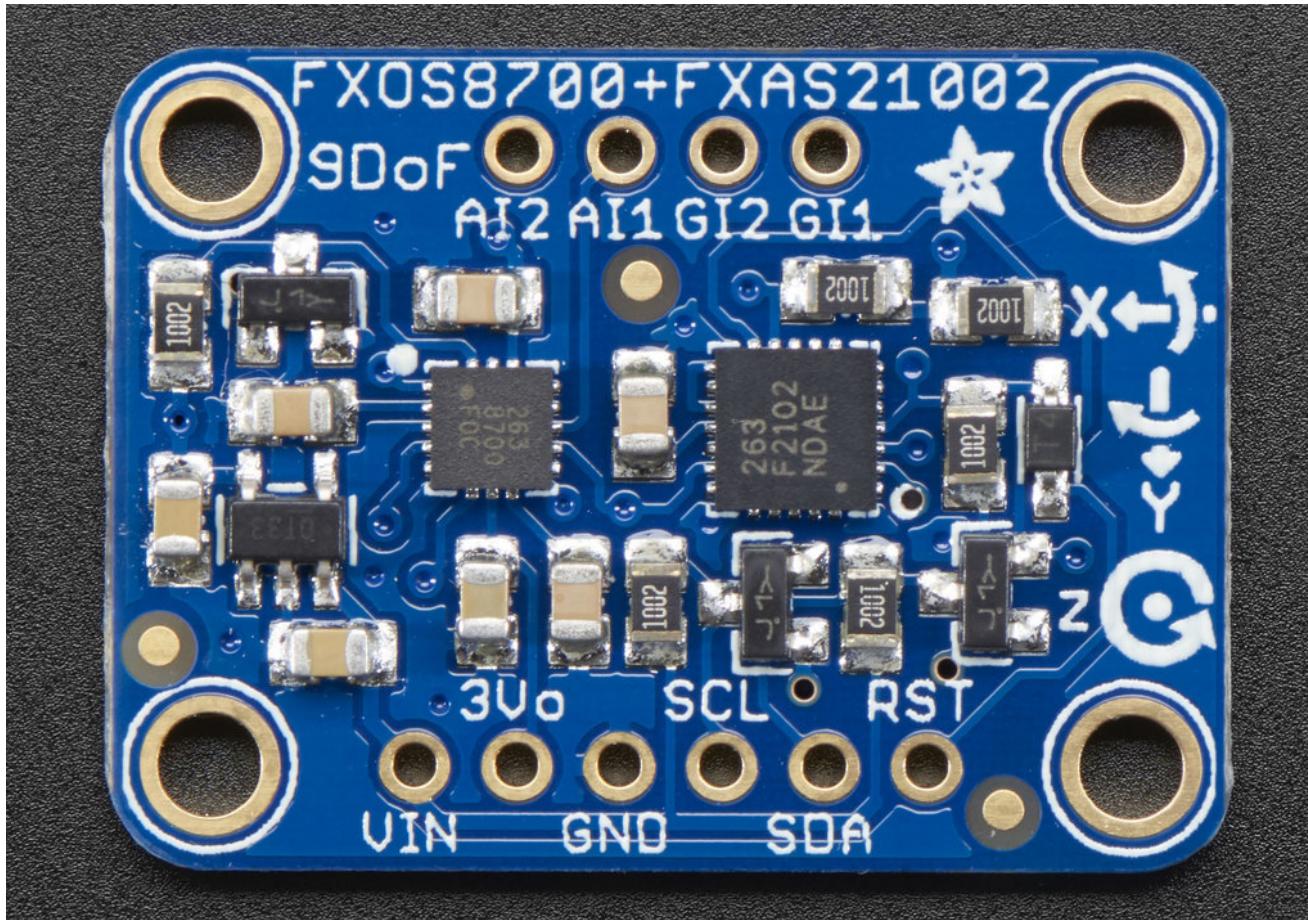


SPI

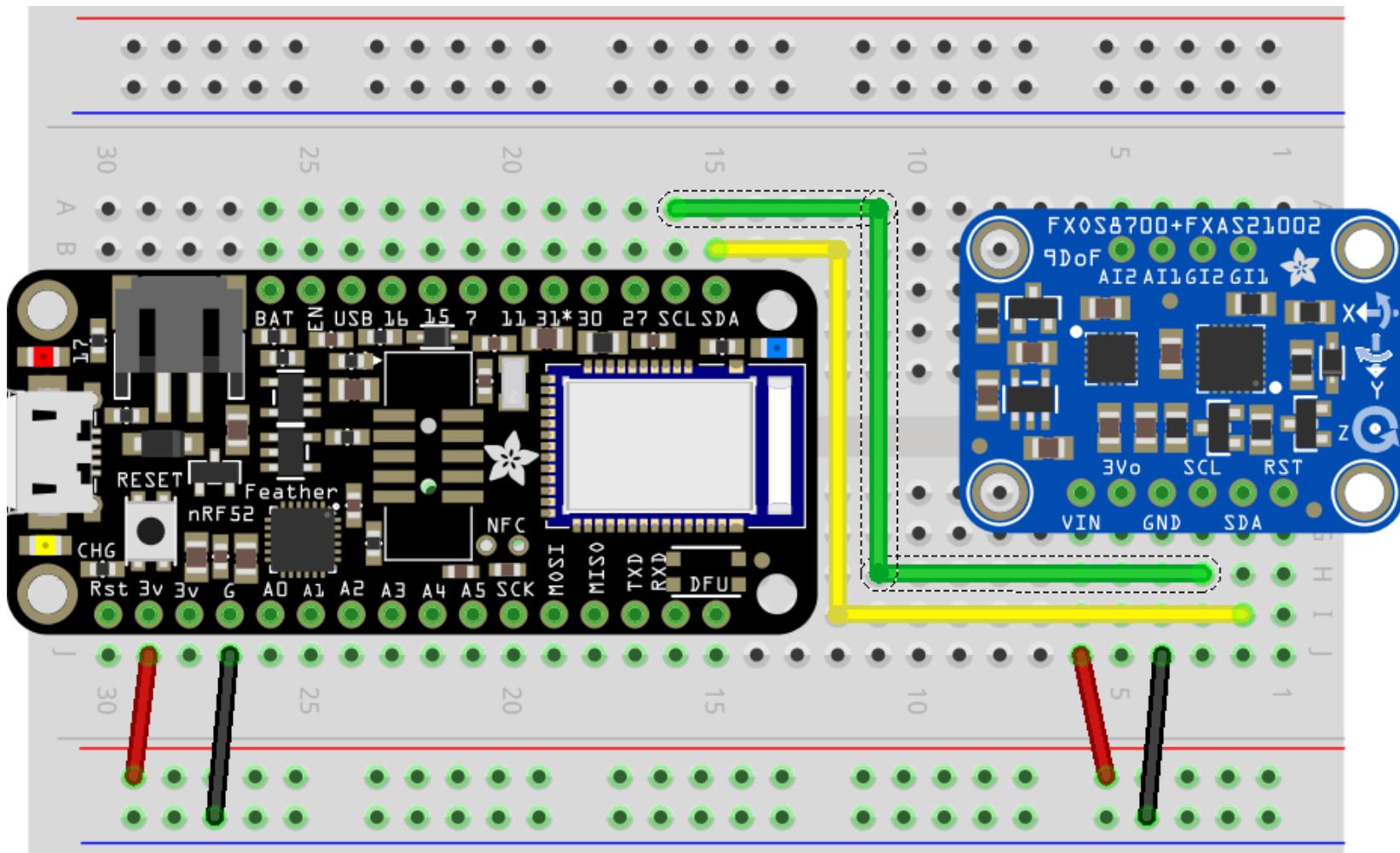


An example: FXOS8700

An 3-Axis accelerometer and magnetometer
What protocol does it employ?

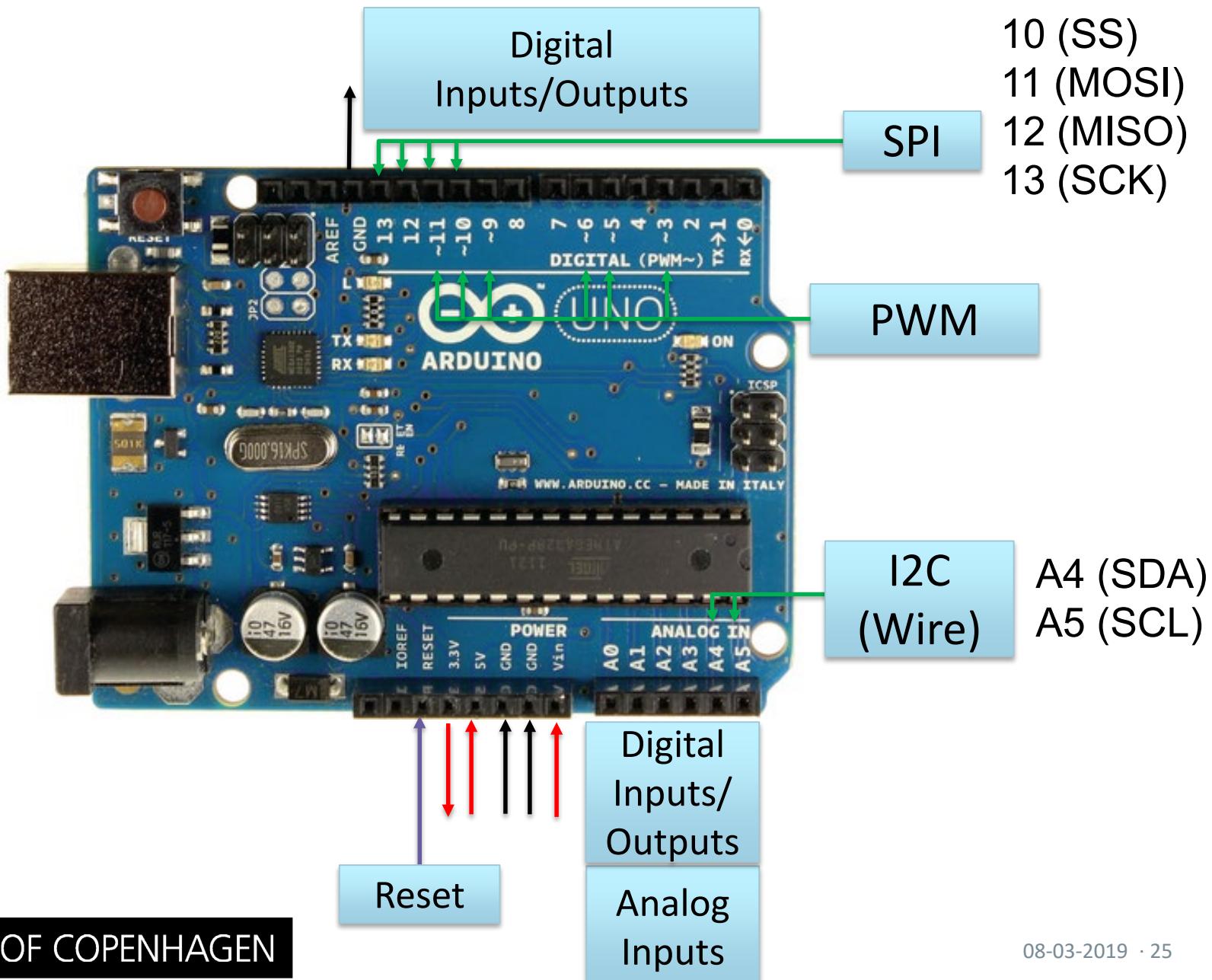


Wiring the FXOS8700



fritzing

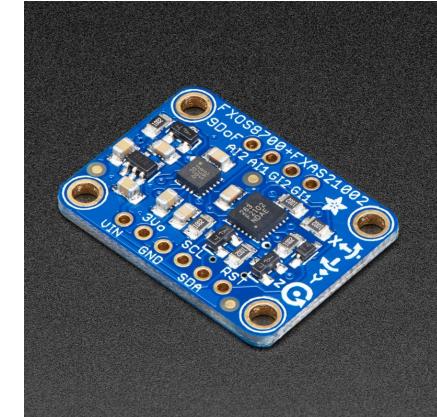
Arduino - Headers



9dof IMU: I2C communications

NXP Precision 9DoF Breakout

<https://learn.adafruit.com/nxp-precision-9dof-breakout?view=all>



Mandatory assignment

There is no MA today

Use the lab time to
ask questions
try buck-boost converters
explore advanced sensors/actuators
 Ultrasounds
 Accelerometers
 Pressure
 LCD
 Servos
 finish the previous MAs

Ready?

Let's program!

Andrés Faíña, 4D26
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Where to find electric components?

Components:

Sensors

Shields

Breakout boards

Distributors:

RS Components (www.rs-components.com/)

Mouser (www.mouser.dk/)

TME (<https://www.tme.eu/en/>)

DIY shops (with tutorials and libraries):

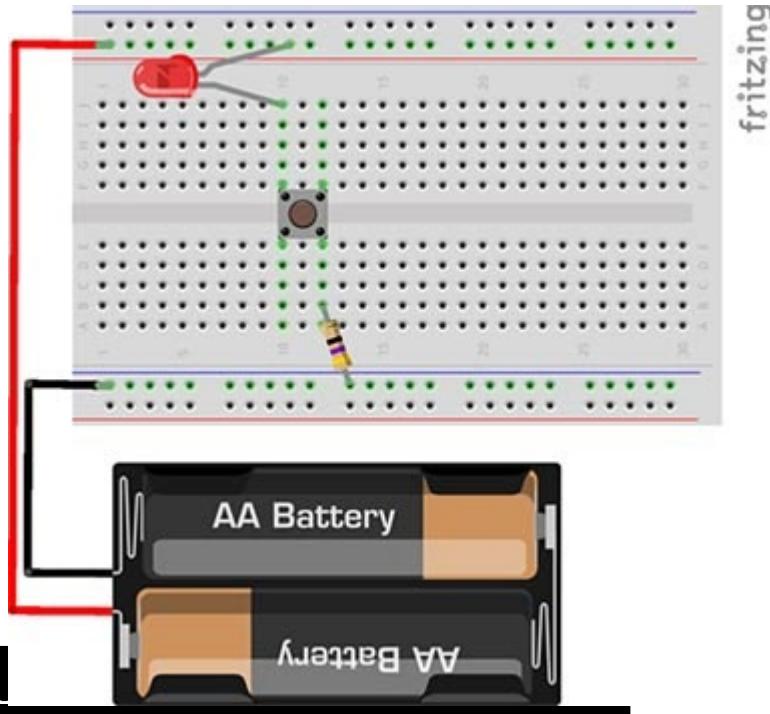
Adafruit (<https://www.adafruit.com/>)

Sparkfun (<https://www.sparkfun.com/>)

Breadboards

How to Use a Breadboard

<https://learn.sparkfun.com/tutorials/how-to-use-a-breadboard>



fritzing

