Taewoong Kim

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Research Interests

Embodied AI, Multimodal learning, Few-shot/zero-shot learning, Reinforcement learning

Education

Yonsei University

Mar. 2023 - Aug. 2024

M.S. in Artificial Intelligence (Advisor: Prof. Jonghyun Choi)

- o Overall GPA: 4.04/4.3
- o Relevant Coursework: Multimodal Deep Learning, Machine Learning and Programming

Yonsei University

Mar. 2016 - Aug. 2023

B.S. in Mechanical Engineering

- o Major GPA: 4.16/4.3, Overall GPA: 3.83/4.3
- Relevant Coursework: Dynamics, Mechatronics, Mechanical System Control, Intelligent Control

Research Papers

A paper about zero-shot affordance grounding using GenAI

Under Review

B. Kim, T. Kim, J. Nam, J. Min, J. Kim, J. Kim, H. Kim, H. Jeon, J. Choi

Multi-Modal Grounded Planning and Efficient Replanning For

AAAI 2025

Learning Embodied Agents with A Few Examples

(to appear)

T. Kim, B. Kim, J. Choi

Realfred: An Embodied Instruction Following Benchmark in **Photo-Realistic Environments**

ECCV 2024

T. Kim*, C. Min*, B. Kim, J. Kim, W. Jeong, J. Choi

ECLAIR: Event-Cognizant Language Interaction Embodied Robots

Workshop on LA4IRA IEEE RO-MAN 2023

J. Kim, B. Kim, C. Min, Y. Kim, T. Kim, J. Choi

Research Experience

SNU Machine Perception and Reasoning Lab

Seoul National University

Sep. 2024 - Current

Research Assistant (Advisor: Prof. Jonghyun Choi)

- Zero-shot affordance grounding
 - Implemented image generation models to achieve zero-shot affordance grounding
 - Developed a framework that treats occlusions as interaction signals to identify affordance regions

Yonsei Vision & Learning Lab

Yonsei University

Graduate Research Assistant (Advisor: Prof. Jonghyun Choi)

Mar. 2023 - Aug. 2024

- Large language models (LLMs) as few-shot planners for embodied agents
 - Developed a multimodal planner with LLM for enhanced grounded planning capabilities
 - Designed an efficient replanning system that corrects partially misleading subgoals
- Bridging the reality gap
 - Proposed a photo-realistic benchmark with 3D-captured indoor scenes with interactive objects

Work Experience

Samsung Electronics

Suwon, Korea

Full-Time Engineer, Robot Business Team

Sep. 2022 - Jan. 2023

o Designed and developed mechanical components for exoskeleton robot

Samsung Electronics

Suwon, Korea

Intern, Mobile Experience Divison

July. 2021 - Aug. 2021

o Conducted personal project about foldable mobile devices

Q Honors and Awards

Outstanding Paper Award (Golden Prize), IPIU 2025	Feb. 2025
Innovative Graduate Thesis Award, Yonsei University	Feb. 2025
Outstanding Paper Award (Silver Prize), IPIU 2024	Feb. 2024
1st Place Award, CVPRW 2023 Embodied AI Workshop Challenge	June~2023
Academic High Honors Award, Yonsei University	Fall 2019, Fall 2020
Academic Honors Award, Yonsei University	Spring 2019
Academic Scholarship, Gwacheon City	Spring 2020 - Fall 2020
Volunteer Scholarship, Yonsei University	Spring 2019 - Fall 2019
Veritas (Academic) Scholarship, Yonsei University	Fall 2019,
	Spring 2019, 2020, 2021, 2022

School of Mechanical Engineering at Yonsei University

Dec. 2018 - Dec. 2019

56th Student President

o Organized, led, and made decisions for the department and student council

Military Service for Republic of Korea

Apr. 2017 - Jan. 2019

Sergeant

o Served as machine gun shooter at The 17th Infantry Division, Republic of Korea Army

Teaching Experience

Teaching Assistant, Seoul National University

Fall 2024

TA for graduate AI seminar

o Managed and addressed students' requests

Volunteer Experience

Korean University Mentors Union

Sept. 2020 - Feb. 2021

Mentor

o Conducted major-specific information sessions and addressed high school students' questions

✗ Academic Services

Reviewer: RO-MAN'24

Skills

Languages Korean (Native), English (Fluent)

Programming Python, C, MATLAB
CAD/CAE NX, Ansys, PTC Creo
General GitHub, LaTeX, PyTorch