

Recurrent Networks for Factor Models in Time Series

Student: Tim Hung Wu (CID: 01195701), Supervisor: Dr. Carlo Ciliberto, Second Marker: Professor Yiannis Demiris. Course: EIE3

Abstract

This project explores the effectiveness of certain recurrent neural network architectures with long short-term memory units (LSTM RNNs) in the forecasting of stock prices for companies in the STOXX Europe 600 Industrial Goods and Services Index (SXNP). The project focuses on attempting to identify whether certain attributes of a company's fundamentals data, such as book value, significantly influences its stock price. An emphasis of this project was to implement a tool that would provide all the functionalities required to take this machine learning problem from the initial raw dataset to a reasonable final forecast result. As such, the various processes required to develop a solution to a machine learning problem such as data preparation, network structuring etc. were studied. Attempts were also made to improve the performance of the model by evaluating hyperparameters and deepening the architecture. Finally, the returns that were predicted to be positive by the model were compared with the general distribution of stock returns. The results show some capability of forecasting, with the model returning approximately 0.7 in accuracy, precision and recall metrics for the test set.

Background

Overview of Recurrent Neural Networks (RNNs)

- RNNs first introduced into literature by Rumelhart et al.[1] in 1986 to model cognitive perception.
- In contrast to feedforward networks like the multilayer perceptron, RNNs have a memory component. Its state is modelled as: $h_t = f_W(h_{t-1}, x_t)$.
- Use cases: Sequential data tasks such as text generation, visual recognition and time series forecasting.

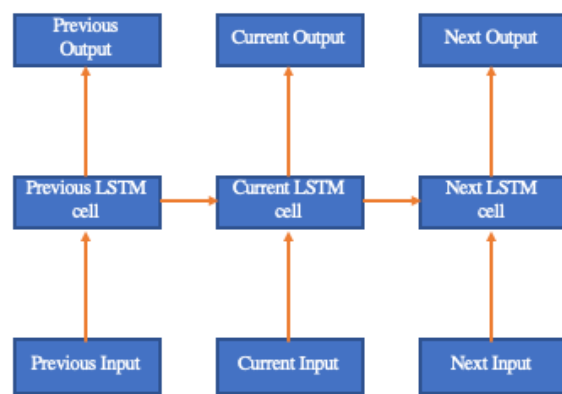


Figure 1: Unrolled architecture of RNN.

Vanishing Gradient Problem

- Repeated gradient signal multiplication across multiple cells during backpropagation causes small error gradients to tend towards 0 and vanish. [2]
- LSTMs were introduced by Hockreiter et al.[3] in 1997 to correct for this problem.
- LSTM units consist of three gates (forget, input and update) which process the flow of information through the cell and update its state, helping retain weak signals.

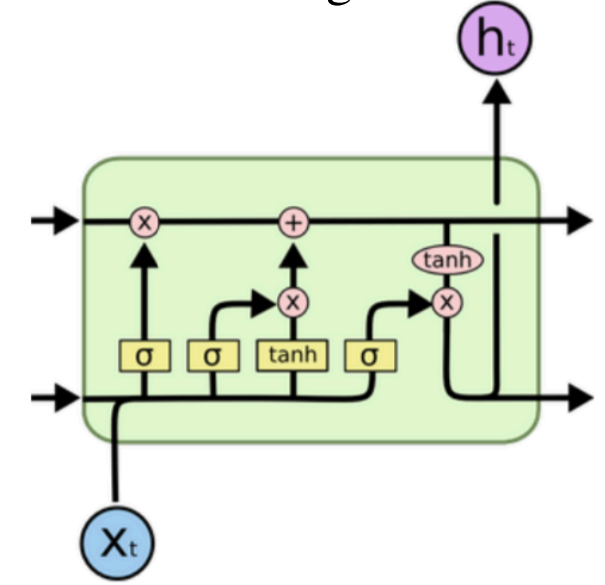


Figure 2: Component wise logic of LSTM cell.

Data Analysis

Data structure: Divided into 2 lists of features, *Fundamentals* and *Prices*.

- Fundamentals:** General data about the company, such as book value or sales. Subdivided into two categories: Last Twelve Months (LTM), the historical values for the last year, and Next Twelve Months (NTM), predictions for the next year.
- Prices:** Data on the behavioural characteristics of the stock trading on the exchange.
- Total number of features for each category: LTM: 16, NTM: 31, *Prices*: 14.
- There are 203 companies in the SXNP Index. Each company has an unique ticker.
- Each company feature contains 6313 time data points, starting from 3rd Jan 1995.

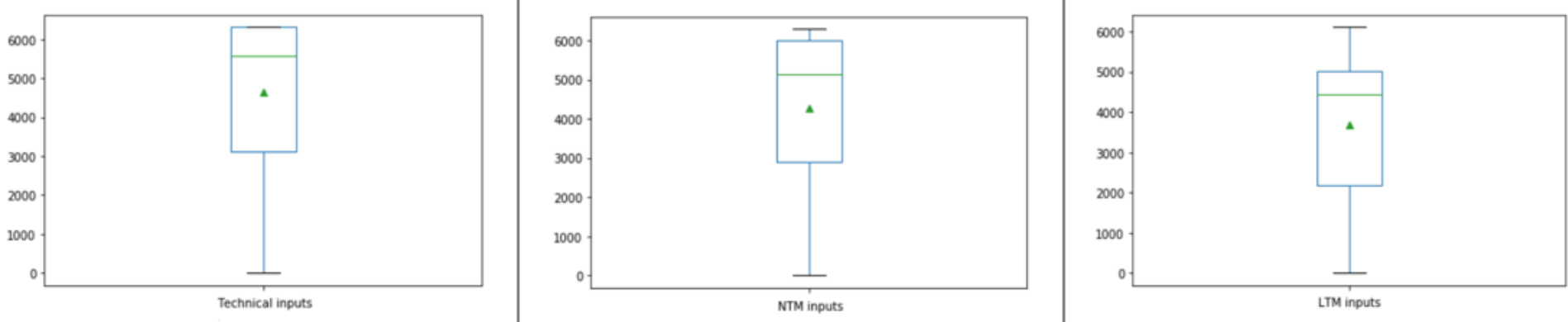


Figure 3: Boxplots indicating the approximate average underlying count numbers for each type of input. Green triangles indicate the mean counts.

Data sparsity problem: Solutions were considered about how to handle missing values.

- Three main methods: deleting, masking and generating values.
- Deletion: Resulted in a non standardised sequential input which caused very poor performance by the LSTM as the dataset lost its Markovian property.
- Masking: Caused a lot of repetitive data due to the low frequency of fundamental data updates. Produced extremely large datasets which were time consuming to train.
- Prediction: Required initially training on time series data with no missing values. Can amend small gaps but weak in larger data gaps due to compounding prediction errors.

Design and Implementation

The following figures describe the pipeline processes involved in setting up the ML experiment.

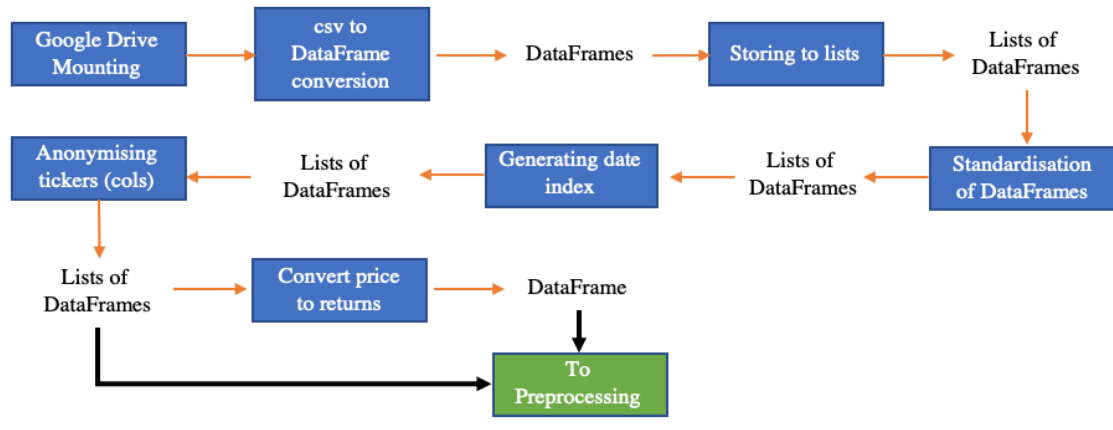


Figure 4: Program flow diagram of data structuring.

Step 2: Data Preprocessing

- Objective:** Analyse the properties of the data and determine a suitable method of handling data for the model input.
- Input attributes scaled between 0 and 1 using the min-max method.
- Target variable relabeled as binary values where +1 indicated positive return and 0 indicated negative return.
- Division into training, validation and test sets in the ratio of 60:20:20.

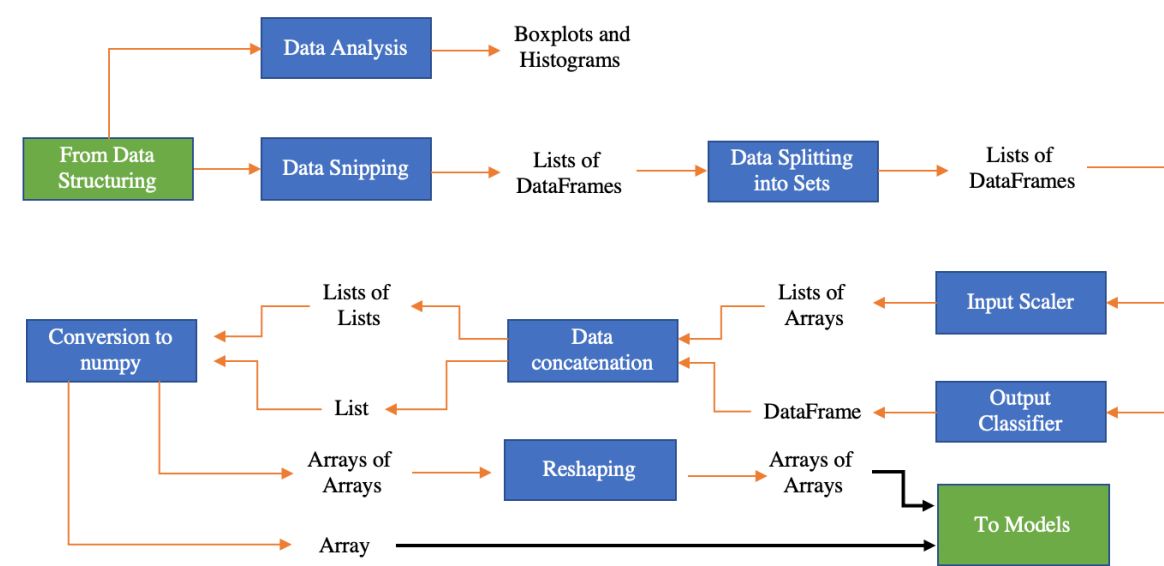


Figure 5: Program flow diagram of data preprocessing.

Step 3: Neural Network Architecture

- Objective:** Design a learning algorithm that outperforms the naïve diversification benchmark.
- Multi output architecture to provide predictions for both the next input and target variables.
- Inputs: 20x1 features array. Outputs: 20x1 features array and 1x1 binary digit.
- Stacked LSTM architecture for both branches consisting of 4 layers. Dropout rates of 20% used between layers to avoid overfitting.
- Deep architectures consistently outperformed shallow networks with the same total number of LSTM units.
- Loss functions: Binary cross-entropy and mean absolute error for output and input predictors respectively.
- Optimiser: Adaptive Moment Estimation (Adam).
- Batch size: 1024, Epochs: 30.

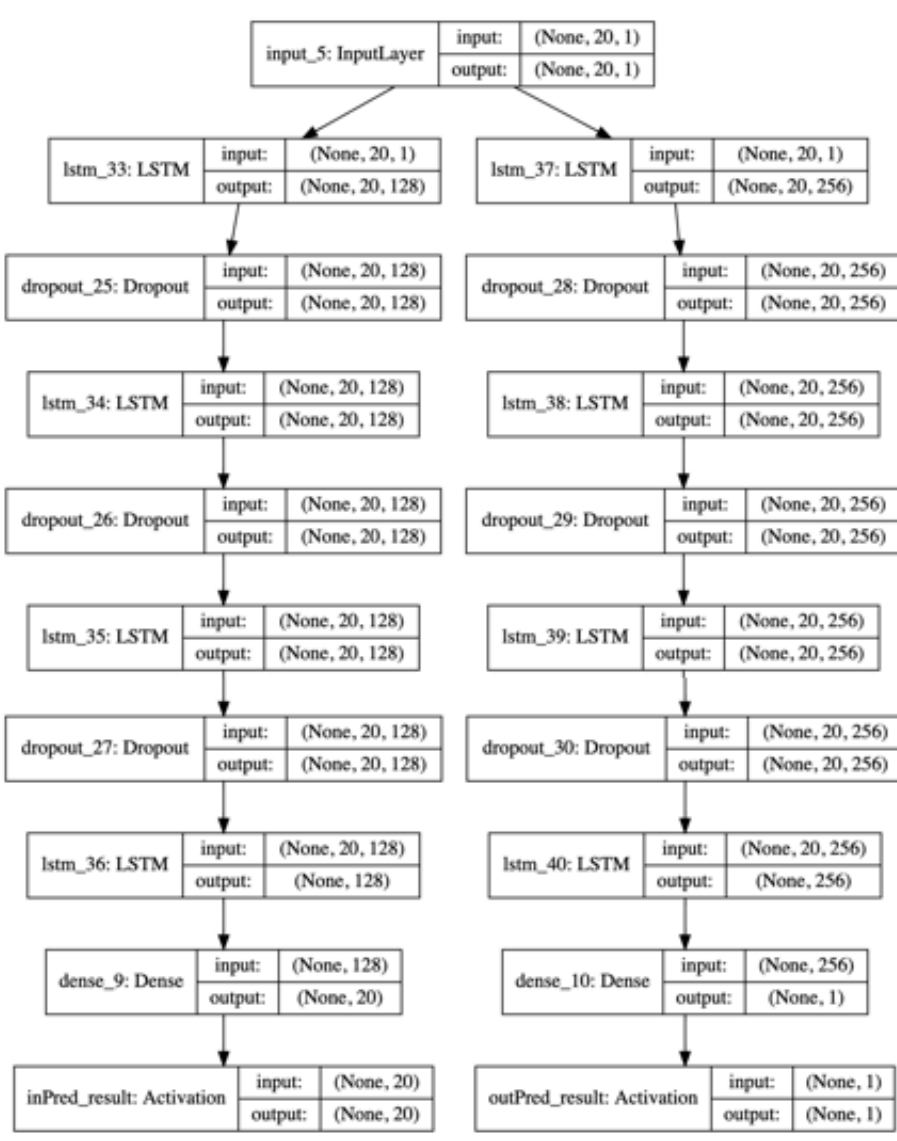


Figure 6: Architectural breakdown of multi output model.

Step 4: Evaluation Metrics

- Objective:** Predict using the model and assess performance against the benchmark.
- Selected all returns that were predicted to be +1 by the model in the test set and compared against the actual value of the returns.
- Visual plots and statistical summaries of distribution to compare against benchmark (the returns of the entire test set).

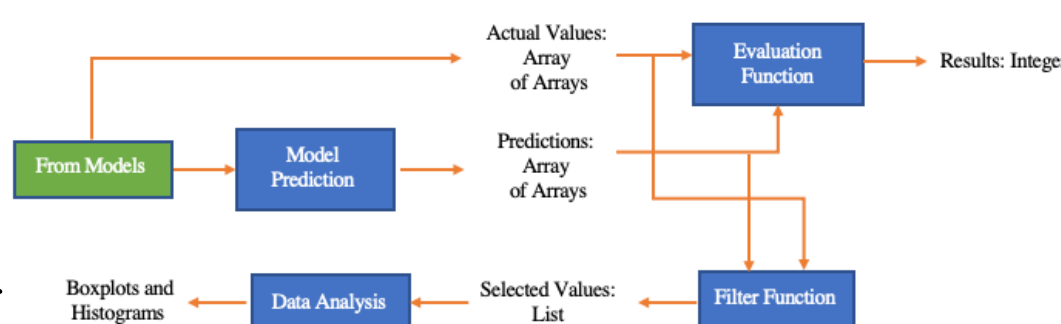


Figure 7: Program flow diagram of evaluation metrics.

Results

- Model predictions exhibited more preferable statistical properties than the test set benchmark. Accuracy plateaus at ~0.7 for training, with the same result in test data.
- Further hyperparameter optimisations such as decayed learning rate or alternate weight initialisation may have improved performance.

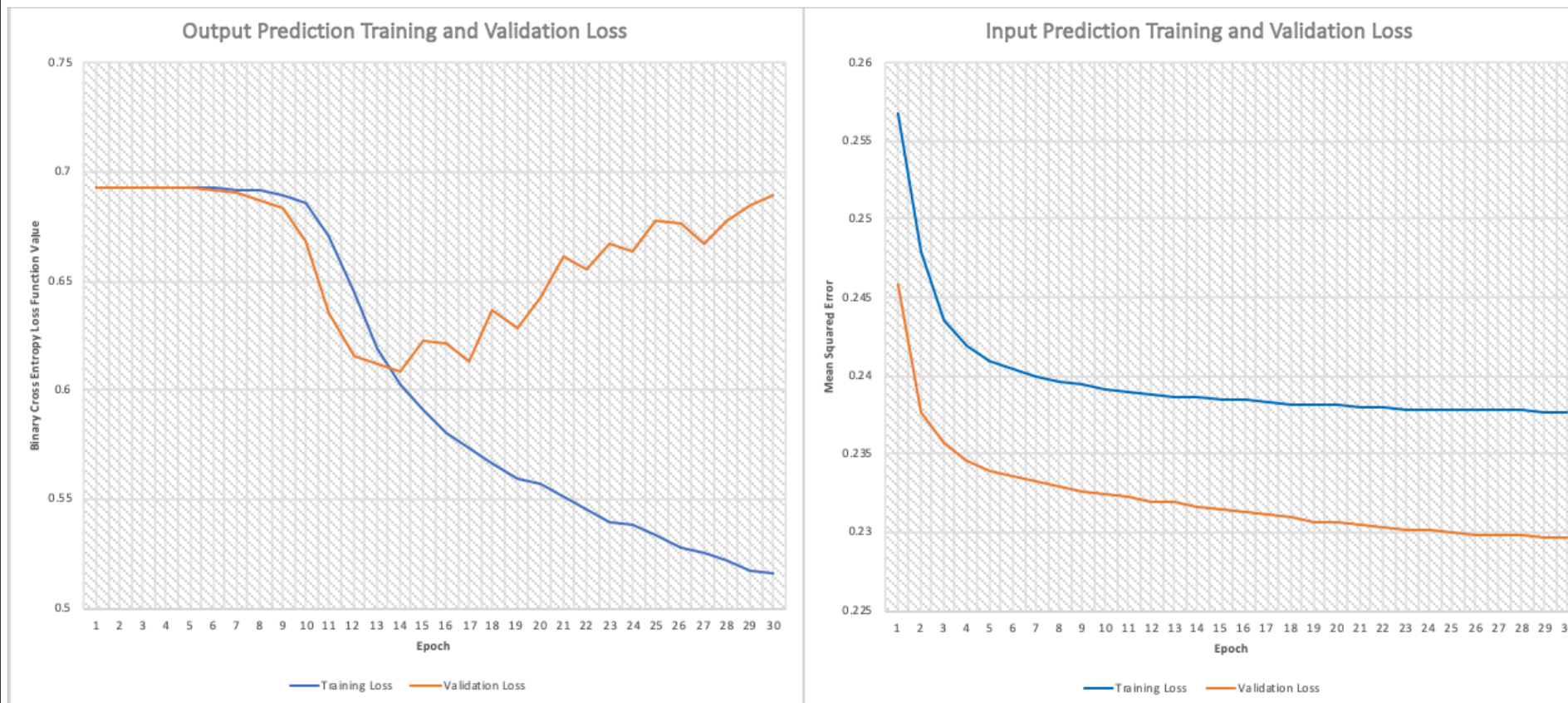


Figure 8: Training and Validation losses for next input and target variable prediction of the multi output model.

	Entire	Test	Selected
Mean	0.000389	-0.000147	0.00764
Variance	0.000546	0.000364	0.000269
Skew	64.114	-1.489	1.224
Kurtosis	18474.2	43.882	31.110

Accuracy	Precision	Recall
0.705	0.700	0.699

Table 1: Model performance metrics for holdout test data.

Table 2: Summary of returns data distributions for the entire, test and model predicted datasets.

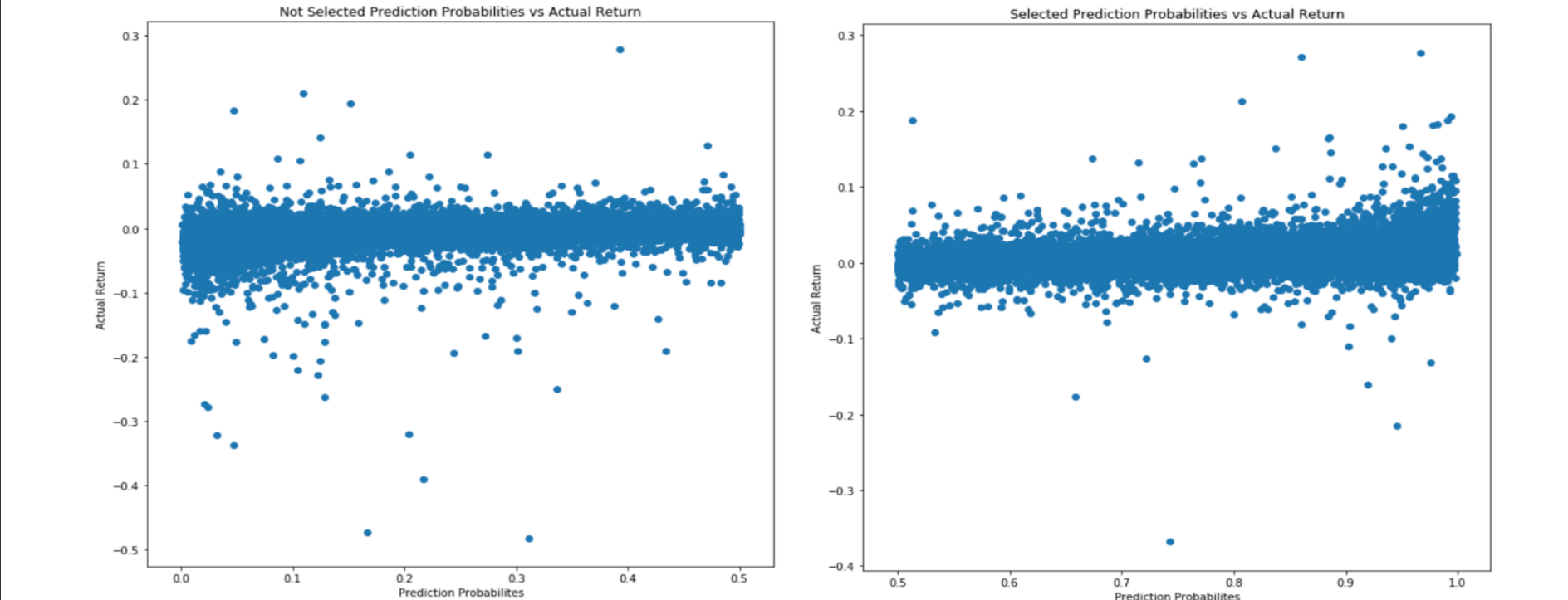


Figure 9: Scatter plots of the unselected (<0.5) and selected (>0.5) prediction probabilities against actual returns of the datapoint.

Conclusion

The project effectively evaluated a theoretical application of recurrent networks to the problem of predicting stock prices. One of the most significant achievements of this project was the implementation of a model which showed signs of outperformance in terms of prediction against the designated benchmark. Although the input data was not constructed solely from fundamental data as initially desired, the addition of technical analysis data was deemed vital for the success of the model. However, it would be difficult to translate any of the research generated into a practical investment application. For example, one of the issues arising from the problem is that the model takes the company metrics and predicts the price at that specific time step t . This does not translate into a viable long term investment plan as the objective in that is to evaluate the company metrics and judge the future price at a time step $t + c$ where c is the investment horizon period.

Future Work

- Data Feeds:** Add more types of data to see whether this would add any improvement. For example, sentiment data such as newsfeeds could be useful.
- Alternate learning algorithms:** Experiment with a reinforcement learning approach. An example framework would be to use the profit and loss of a portfolio as the reward, with buying and selling stocks being the decision and action processes.

References

- Project GitHub Repository: <https://github.com/twtutang/SXNP-Factor-Models>
- [1] D. E. Rumelhart, P. Smolensky, J. L. McClelland, and G. E. Hinton. *Schemata and Sequential Thought Processes in PDP Models*. Morgan Kaufmann Publishers, 1986.
 - [2] Y. Bengio, P. Simard, and P. Frasconi. *Learning Long-Term Dependencies with Gradient Descent is Difficult*. IEEE Transactions on Neural Networks, 1994.
 - [3] S. Hockreiter and J. Schmidhuber. Long Short Term Memory. MIT Press, 1997.