Matrix Operations and Multivariate Linear Regression

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R Lab 9: Matrix Operations and Multivariate Linear Regression

```
Define a matrix by entering its elements manually.
```

```
B \leftarrow matrix(c(1,2,3,4,5,6,7,8,9),3,3)
         [,1] [,2] [,3]
## [1,]
            1
            2
## [2,]
                  5
                       8
## [3,]
            3
This is an element-wise operation
B^2
         [,1] [,2] [,3]
## [1,]
            1
                 16
                      49
## [2,]
            4
                 25
                      64
## [3,]
            9
                      81
This is matrix multiplication, B^2 = B^*B
B %*% B
##
         [,1] [,2] [,3]
## [1,]
           30
                66
                     102
## [2,]
           36
                     126
## [3,]
           42
                     150
Transposed matrix
t(B)
         [,1] [,2] [,3]
##
## [1,]
## [2,]
            4
                  5
                       6
## [3,]
Joining two matrices side by side (as columns)
cbind(B, B)
         [,1] [,2] [,3] [,4] [,5] [,6]
```

Joining two matrices below each other (as rows)

7

8

1

2

4

5

7

8

4

5

1

2

[1,]

[2,]

[3,]

```
rbind(B, B)
         [,1] [,2] [,3]
## [1,]
            1
                 4
                       7
## [2,]
            2
                 5
                       8
## [3,]
            3
                       9
                 6
## [4,]
            1
                 4
                       7
## [5,]
            2
                 5
                       8
## [6,]
            3
                       9
Sub-matrix, a part of matrix B
B[1:3, 1:2]
##
         [,1] [,2]
## [1,]
                 4
            1
## [2,]
            2
                 5
## [3,]
            3
                 6
Inverting matrices is available in package "matlib"
# install.packages("matlib")
library(matlib)
## Warning in rgl.init(initValue, onlyNULL): RGL: unable to open X11 display
## Warning: 'rgl.init' failed, running with 'rgl.useNULL = TRUE'.
В
         [,1] [,2] [,3]
##
## [1,]
            1
                 4
                       7
## [2,]
            2
                 5
                       8
## [3,]
            3
                 6
                       9
inv(B)
## Error in Inverse(X, tol = sqrt(.Machine$double.eps), ...): X is numerically singular
This means there is a linear dependence among columns (and among rows) of matrix B. Such matrices are
not invertible, and they have a determinant equal \det(B)=0
make determinant equal det(B)=0
det(B)
## [1] 0
B[1,1]=100
В
##
         [,1] [,2] [,3]
## [1,]
         100
                       7
                 4
## [2,]
            2
                 5
                       8
            3
                 6
                       9
## [3,]
We changed the matrix by adding a "ridge", and now the inverse B^-1 exists
inv(B)
##
                [,1]
                              [,2]
                                           [,3]
## [1,] 0.01010101 -0.02020202 0.01010101
## [2,] -0.02020202 -2.95959596 2.64646465
```

Data practice - Multivariate Linear Regression

Define a matrix from the "mtcars" data set and build a regression model that predicts miles per gallon based on the number of cylinders, horsepower, axes ratio, weight, and acceleration time.

```
head(mtcars)
##
                                                wt qsec vs am gear carb
                      mpg cyl disp hp drat
## Mazda RX4
                                160 110 3.90 2.620 16.46
                     21.0
                                                           0
                                                              1
## Mazda RX4 Wag
                     21.0
                               160 110 3.90 2.875 17.02
                                                           0
                                                                        4
                                                              1
## Datsun 710
                     22.8
                             4 108 93 3.85 2.320 18.61
                                                                        1
## Hornet 4 Drive
                     21.4
                             6 258 110 3.08 3.215 19.44
                                                                   3
                                                                        1
                                                           1
## Hornet Sportabout 18.7
                             8
                               360 175 3.15 3.440 17.02
                                                           0
                                                                        2
## Valiant
                     18.1
                             6 225 105 2.76 3.460 20.22
                                                                        1
Extract X-matrix of predictors
X = data.matrix(mtcars[,c(2,4:7)])
head(X)
##
                     cyl hp drat
                                      wt qsec
## Mazda RX4
                       6 110 3.90 2.620 16.46
## Mazda RX4 Wag
                       6 110 3.90 2.875 17.02
## Datsun 710
                       4 93 3.85 2.320 18.61
## Hornet 4 Drive
                       6 110 3.08 3.215 19.44
## Hornet Sportabout
                       8 175 3.15 3.440 17.02
## Valiant
                       6 105 2.76 3.460 20.22
Find the vector of responses of Y
Y = data.matrix(mtcars[ ,1])
head(Y)
##
        [,1]
## [1,] 21.0
## [2,] 21.0
## [3,] 22.8
## [4,] 21.4
## [5,] 18.7
## [6,] 18.1
We also need a vector of 1s to include the intercept
n = length(Y)
one = matrix(1,n,1) #row 1, col n, values 1
```

```
##
          [,1]
##
   [1,]
             1
    [2,]
##
             1
##
  [3,]
             1
##
   [4,]
             1
  [5,]
##
             1
```

```
## [6,]
             1
##
    [7,]
             1
   [8,]
##
  [9,]
##
             1
## [10,]
             1
## [11,]
             1
## [12,]
             1
## [13,]
             1
## [14,]
             1
## [15,]
             1
## [16,]
             1
## [17,]
             1
## [18,]
             1
## [19,]
## [20,]
             1
## [21,]
             1
## [22,]
             1
## [23,]
## [24,]
             1
## [25,]
## [26,]
             1
## [27,]
## [28,]
             1
## [29.]
             1
## [30,]
             1
## [31,]
             1
## [32,]
             1
X = cbind(one,X)
Х
##
                           cyl hp drat
                                            wt qsec
## Mazda RX4
                             6 110 3.90 2.620 16.46
## Mazda RX4 Wag
                             6 110 3.90 2.875 17.02
```

```
## Datsun 710
                           4 93 3.85 2.320 18.61
                       1
## Hornet 4 Drive
                       1
                           6 110 3.08 3.215 19.44
## Hornet Sportabout
                           8 175 3.15 3.440 17.02
## Valiant
                           6 105 2.76 3.460 20.22
                       1
                           8 245 3.21 3.570 15.84
## Duster 360
                       1
## Merc 240D
                           4 62 3.69 3.190 20.00
                       1
## Merc 230
                           4 95 3.92 3.150 22.90
## Merc 280
                       1
                           6 123 3.92 3.440 18.30
## Merc 280C
                       1
                           6 123 3.92 3.440 18.90
## Merc 450SE
                       1
                           8 180 3.07 4.070 17.40
## Merc 450SL
                           8 180 3.07 3.730 17.60
                           8 180 3.07 3.780 18.00
## Merc 450SLC
                       1
## Cadillac Fleetwood 1
                           8 205 2.93 5.250 17.98
                           8 215 3.00 5.424 17.82
## Lincoln Continental 1
## Chrysler Imperial
                      1
                           8 230 3.23 5.345 17.42
## Fiat 128
                           4 66 4.08 2.200 19.47
                       1
## Honda Civic
                           4 52 4.93 1.615 18.52
                      1
## Toyota Corolla
                      1
                         4 65 4.22 1.835 19.90
## Toyota Corona
                       1
                           4 97 3.70 2.465 20.01
                           8 150 2.76 3.520 16.87
## Dodge Challenger
                       1
## AMC Javelin
                           8 150 3.15 3.435 17.30
                       1
```

```
## Camaro Z28 1 8 245 3.73 3.840 15.41
## Pontiac Firebird 1 8 175 3.08 3.845 17.05
## Fiat X1-9 1 4 66 4.08 1.935 18.90
                    1 4 91 4.43 2.140 16.70
## Porsche 914-2
## Lotus Europa
                     1
                        4 113 3.77 1.513 16.90
## Ford Pantera L
                    1 8 264 4.22 3.170 14.50
## Ferrari Dino
                     1 6 175 3.62 2.770 15.50
                     1 8 335 3.54 3.570 14.60
## Maserati Bora
## Volvo 142E
                         4 109 4.11 2.780 18.60
This is matrix X'X
t(X) %*% X
##
                      cyl
                                         drat
                                hp
                                                             qsec
         32.000
                                     115.0900
##
                  198.000
                           4694.00
                                                102.9520
                                                          571.160
## cyl
        198.000 1324.000 32204.00
                                     691.4000
                                                679.4040 3475.560
       4694.000 32204.000 834278.00 16372.2800 16471.7440 81092.160
## drat 115.090
                  691.400 16372.28
                                     422.7907
                                                358.7190
                                                         2056.914
## wt
        102.952
                  679.404 16471.74
                                     358.7190
                                                360.9011
                                                          1828.095
## qsec 571.160 3475.560 81092.16 2056.9140 1828.0946 10293.480
Slope \beta 1 = (X'X)-1X'Y
slope = inv(t(X) %*% X) %*% t(X) %*% Y
slope
##
              [,1]
## [1,] 25.94553598
## [2,] -0.48955421
## [3,] -0.01505188
## [4,] 1.13092435
## [5,] -3.38272539
## [6,] 0.34985343
```

Another method to get the same slope by using built-in function 1m

```
attach(mtcars)
## The following object is masked from package:ggplot2:
##
recheckReg <- lm(mpg ~ cyl + hp + drat + wt + qsec)</pre>
recheckReg
##
## lm(formula = mpg ~ cyl + hp + drat + wt + qsec)
## Coefficients:
                                                                                 qsec
## (Intercept)
                          cyl
                                        hp
                                                    drat
                                                                     wt.
      25.94521
                    -0.48967
                                  -0.01539
                                                 1.13077
                                                              -3.38279
                                                                             0.35011
Our estimated regression equation is mpg = 25.95 - 0.49 cyl - 0.015 hp + 1.13 drat - 3.38 wt +
0.35 \text{ qsec} + e
```