R Lab 7. Matrix Operations and Multivariate Linear Regression

Define a matrix by entering its elements manually.

Inverting matrices is available in package "matlib"

> install.packages("matlib")

> library(matlib)

```
> B = matrix(c(1,2,3,4,5,6,7,8,9),3,3)
> B
      [,1] [,2] [,3]
[1,]
        1
              4
[2,]
         2
               5
                     8
[3,]
         3
               6
                     9
> B^2
                           # This is an element-wise operation
      [,1] [,2] [,3]
[1,]
        1
              16
                    49
[2,]
         4
              25
                    64
[3,]
         9
              36
                    81
> B%*%B
                           # This is matrix multiplication, B^2 = B*B
      [,1] [,2] [,3]
        30
              66 102
[1,]
[2,]
        36
              81 126
[3,]
        42
              96 150
> t(B)
                           # Transposed matrix
      [,1] [,2] [,3]
[1,]
         1
               2
[2,]
         4
               5
                     6
         7
               8
                     9
[3,]
> cbind(B,B)
                           # Joining two matrices side by side (as <u>c</u>olumns)
       [,1] [,2] [,3] [,4] [,5] [,6]
[1,]
              4
                     7
                                 4
         1
                           1
                                 5
                                       8
         2
               5
                     8
                           2
[2,]
               6
                           3
                                 6
[3,]
         3
                     9
> rbind(B,B)
                           # Joining two matrices below each other (as rows)
     [,1] [,2] [,3]
[1,]
        1
               4
[2,]
         2
               5
                     8
[3,]
         3
               6
                     9
[4,]
         1
               4
                     7
         2
               5
[5,]
         3
[6,]
> B[1:2,1:3]
                           # Sub-matrix, a part of matrix B
      [,1] [,2] [,3]
[1,]
         1
               4
               5
[2,]
         2
```

```
> inv(B)
Error in Inverse(X, tol = sqrt(.Machine$double.eps), ...) :
   X is numerically singular
```

This means there is a linear dependence among columns (and among rows) of matrix B. Such matrices are not invertible, and they have a determinant equal det(B)=0

```
> det(B)
[1] 0
> B[1,1]=100
> B
     [,1] [,2] [,3]
[1,] 100
              4
              5
                   8
[2,]
        2
[3,]
        3
              6
> inv(B)
            # We changed the matrix by adding a "ridge", and now the inverse B-1 exists
                          [,2]
                                       [,3]
[1,] 0.01010101 -0.02020202 0.01010101
[2,] -0.02020202 -2.95959596 2.64646465
[3,] 0.01010101 1.97979798 -1.65656566
```

Define a matrix from the "mtcars" data set and build a regression model that predicts miles per gallon based on the number of cylinders, horsepower, axel ratio, weight, and acceleration time.

```
> head(mtcars)
                   mpg cyl disp hp drat
                                            wt qsec vs am gear carb
                  21.0 6 160 110 3.90 2.620 16.46 0
Mazda RX4
                                                        1
Mazda RX4 Wag
                  21.0 6 160 110 3.90 2.875 17.02 0
                                                        1
Datsun 710
                  22.8 4 108 93 3.85 2.320 18.61
                                                      1
                                                        1
                                                                   1
Hornet 4 Drive
                  21.4
                         6 258 110 3.08 3.215 19.44
                                                      1
                                                         0
                                                              3
                                                                   1
Hornet Sportabout 18.7 8 360 175 3.15 3.440 17.02
                                                      0
                                                         \cap
                                                              3
                                                                   2
Valiant
                  18.1
                         6 225 105 2.76 3.460 20.22
                                                              3
                                                                   1
> X = data.matrix(mtcars[,c(2,4:7)])
                                        #X-matrix of predictors
> head(X)
                  cyl hp drat
                                  wt qsec
Mazda RX4
                    6 110 3.90 2.620 16.46
Mazda RX4 Waq
                    6 110 3.90 2.875 17.02
Datsun 710
                   4 93 3.85 2.320 18.61
Hornet 4 Drive
                    6 110 3.08 3.215 19.44
Hornet Sportabout 8 175 3.15 3.440 17.02
                    6 105 2.76 3.460 20.22
> Y = data.matrix(mtcars[,1])
                                        # Vector of responses
> n = length(Y)
> one = matrix(1,n,1) # We also need a vector of 1s to include the intercept
```

> X = cbind(one, X)

```
> t(X) %*% X
                  # This is matrix X'X
                      cyl
                                 hp
                                           drat
                                                         wt
                                                                 qsec
                198.000
                           4694.00
                                      115.0900
       32.000
                                                 102.9520
                                                             571.160
      198.000 1324.000 32204.00
                                      691.4000
                                                 679.4040 3475.560
cyl
     4694.000 32204.000 834278.00 16372.2800 16471.7440 81092.160
hp
drat 115.090
               691.400
                         16372.28
                                      422.7907
                                                 358.7190 2056.914
                 679.404
      102.952
                          16471.74
                                      358.7190
                                                 360.9011 1828.095
qsec 571.160 3475.560 81092.16 2056.9140 1828.0946 10293.480
                                                # Slope \beta = (X'X)^{-1}X'Y
> slope = inv(t(X) %*% X) %*% t(X) %*% Y
> slope
            [,1]
[1,] 25.94553598
[2,] -0.48955421
[3,] -0.01505188
[4,] 1.13092435
[5,] -3.38272539
[6,] 0.34985343
# We can certainly get the same slopes by the usual regression command "lm"
> lm( mpg ~ cyl + hp + drat + wt + qsec )
lm(formula = mpg ~ cyl + hp + drat + wt + qsec)
Coefficients:
                                                drat
(Intercept)
                      cyl
                                    hp
                                                                wt
qsec
                              -0.01539
   25.94521
                -0.48967
                                             1.13077
                                                          -3.38279
```

Our estimated regression equation is # mpg = 25.95 – 0.49 cyl – 0.015 hp + 1.13 drat – 3.38 wt + 0.35 qsec + ϵ

0.35011