

## TASKS

### 1) Hardware and Initial setup

Main Task (Epic)	Subtasks (Action Items)	Dependencies	Notes	Man day
<b>HS-1: Project &amp; Peripherals Setup</b>	<b>HS-1.1:</b> Set up STM32CubeIDE project.	None	Use STM32F207 ZG target.	0.5
	<b>HS-1.2:</b> Configure clock tree (HSE, PLL).			0.5
	<b>HS-1.3:</b> Configure I2C/SPI for sensor communication (HAL).			0.5
	<b>HS-1.4:</b> Configure GPIO pins for LEDs (HAL).			0.5
	<b>HS-1.5:</b> Configure Ethernet MAC			1

	and related GPIOs (HAL).			
	<b>HS-1.6:</b> Initialize Timer (TIM) for system tick/RTOS (HAL).			1.5

## 2) Core Drivers and RTOS Integration

Main Task (Epic)	Subtasks (Action Items)	Dependencies	Notes	Man day
<b>DRV-1: Integrate FreeRTOS</b>	<b>DRV-1.1:</b> Integrate FreeRTOS into the project.	HS-1.6		1
	<b>DRV-1.2:</b> Create initialization task and start the scheduler.			1
<b>DRV-2: PAJ7660</b>	<b>DRV-2.1:</b> Implement sensor power-up and basic I2C/SPI	HS-1.3		1.5

<b>Sensor Driver</b>	initialization sequence.			
	<b>DRV-2.2:</b> Configure sensor to operate in the required Gesture Mode 5.			1
	<b>DRV-2.3:</b> Implement <code>read_gesture_id()</code> function (Layer 3 output).	DRV-2.2	Reads the classified integer.	1.5
<b>DRV-3: LED Driver</b>	<b>DRV-3.1:</b> Implement <code>set_led(pin, state)</code> utility function.	HS-1.4		0.5
	<b>DRV-3.2:</b> Implement <code>set_leds_by_count(int count)</code> using the utility.	DRV-3.1	Controls the 5-LED output.	0.5
<b>DRV-4: Networking Stack (LWIP)</b>	<b>DRV-4.1:</b> Integrate LWIP library with the Ethernet MAC HAL.	HS-1.5		1.5

	<b>DRV-4.2:</b> Configure LWIP for DHCP address acquisition.			1.5
	<b>DRV-4.3:</b> Implement a basic PING test to verify network connectivity.	DRV-4.2	Debugging check.	0.5

### 3) Application Logic and Feature Implementation

Main Task (Epic)	Subtasks (Action Items)	Dependencies	Notes	Man day
<b>APP-1: Sensing Task</b>	<b>APP-1.1:</b> Create RTOS task for continuous sensor polling	DRV-1, DRV-2.3		1
	<b>APP-1.2:</b> Map the sensor's raw IDs to the 5 standard system gestures	APP-1.1		1

	(e.g., ID 8 → Swipe Left).			
<b>APP-2: Local Feedback</b>	<b>APP-2.1:</b> Receive Gesture ID from APP-1.2.	APP-1.2		0.5
	<b>APP-2.2:</b> Call <b>DRV-3.2</b> to immediately display N LEDs for Gesture ID N.	DRV-3.2	Low-latency path.	0.5
<b>APP-3: MQTT Client &amp; Payload</b>	<b>APP-3.1:</b> Integrate lightweight MQTT client library	DRV-4.3		2
	<b>APP-3.2:</b> Implement MQTT connection and authentication logic.	APP-3.1	Handles reconnects.	1.5
	<b>APP-3.3:</b> Implement payload struct: Gesture_ID, Timestamp, Status.	APP-3.1		1

	<b>APP-3.4:</b> Implement QoS 1 publish logic (requires acknowledgement).	APP-3.3	PRD requireme nt for reliability.	2.5
<b>APP-4: Failsafe &amp; Monitori ng</b>	<b>APP-4.1:</b> Initialize and periodically feed the Watchdog Timer.	DRV-1	Ensures system restart on crash.	0.5
	<b>APP-4.2:</b> Monitor sensor read status and network connection status.	DRV-2.3, DRV-4.2		0.5
	<b>APP-4.3:</b> Implement the Failsafe Visual Alert (blink all 5 LEDs) if status check fails.	DRV-3.2, APP-4.2		0.5

#### 4) Quality Assurance and Documentation

Main Task (Epic)	Subtasks (Action Items)	Dependenci es	Notes	Man day
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<b>QA-1: Performance Testing</b>	<b>QA-1.1:</b> Set up timing hooks around sensor read and MQTT publish acknowledgment.	APP-2, APP-3.4		1.5
	<b>QA-1.2:</b> Execute 100 test gestures and calculate average latency.	QA-1.1	Verify $\leq 200 \text{ ms}$ cap.	1
<b>QA-2: Reliability Testing</b>	<b>QA-2.1:</b> Stress test MQTT QoS 1 delivery during simulated network disconnects.	APP-3.4, APP-4.3		1.5
	<b>QA-2.2:</b> Verify Emergency Stop (Closed Fist) response time.	APP-2.2	Needs defined priority.	0.5
<b>DOC-1: Finalizing Documentation</b>	<b>DOC-1.1:</b> Document the final MQTT topic structure and JSON/binary payload.	APP-3.3		0.5

	<b>DOC-1.2:</b> Update the architectural diagram and component descriptions to reflect the PAJ7660 integration.	Final QA		0.5
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