Terry Yu

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EDUCATION

University of California, Los Angeles

Expected June 2027

Bachelor of Science in Mechanical Engineering - GPA: 3.70

SKILLS

Design and Analysis: SolidWorks, Ansys Mechanical, Ansys Fluent, Altair Inspire, Fusion 360, HSMWorks, GD&T Manufacturing: CNC & Manual Mill/Lathe, FDM/SLA 3D Printing, Waterjet, Plasma/Laser Cutting, Soldering Software: Python, MATLAB, Java, C++, Arduino

Experience

Mechanical Engineering Intern

June 2025 - Present

DropletPharma Corp.

Los Angeles, CA

- Independently organized design and testing of innovative nozzle geometry to reliably dispense $1\,\mu\text{L}$ of various fluids; achieved variation below 5% across 100+ tests through 5+ iterations, refining design and manufacturing methods
- Engineered compact fume; extractor for toxic vapor removal in medical device; balanced airflow efficiency and serviceability within strict $30\,\mathrm{mm} \times 10\,\mathrm{mm} \times 5\,\mathrm{mm}$ packaging constraint
- CNC machined precision components from PEEK, PTFE, 6061 Aluminum, and 316 Stainless Steel to support R&D of chemical-handling systems

Drivetrain Lead

September 2023 – Present

Bruin Formula Racing

Los Angeles, CA

- Led rear driveline system design for FSAE EV, aligning geometry, materials, and integration with electrical and chassis teams to meet performance and reliability targets
- Programmed and machined components with ± 0.003 in tolerances and interference fits using HSMWorks and 3-axis CNC; reduced manufacturing costs by 20% through design improvements
- Performed FEA and topology optimization on sprockets, achieving a 42% weight reduction validated by physical testing, improving drivetrain efficiency and serviceability
- Pioneered custom CV boots and pouring process, iterating through 5 versions of mold with novel slider mechanism; ultimately replaced dysfunctional boots to enable reliable protection of joint while reducing cost by 50%

Mechatronics Research Intern

June 2024 – May 2025

Stanford University

Palo Alto, CA

- Designed and manufactured hardware components on computer vision-based Xenopus embryo sorter for the Beel Research Group, projected to sort 50 eggs per second with 99% accuracy
- Developed a PDMS-based microfluidics chip with a serpentine flow channel and quake valve sorter mechanism, ensuring quick and accurate imaging and sorting of millimeter-wide Xenopus embryo
- SLA printed mold and cast chip, FDM printed iterations of housing for chip and all electrical components

Projects

Pen Plotter | Project Link

September 2024

- Designed and 3D printed a custom CoreXY belt configuration pen plotter, featuring fully 3D printable recirculating ball bearing linear rails for precise, low-friction movement
- Developed custom bitmap to G-code slicer with image processing algorithms using Java, Python, and C++, enabling precise CoreXY motion control and real-time plotting communication with Arduino

Electric Go Kart | Project Link

May 2024

- Led team of 4 in design, analysis, manufacturing, and assembly of a three-wheeled go kart with speeds of 15 mph
- Used plasma cutter, band saw, drill press, mill, lathe, laser cutter, and 3D printer to manufacture parts from recycled scraps, reducing total cost to under \$100
- Invented a single wheel steering mechanism with bevel gear to achieve significant weight savings over competitors