

# Learning Invariant Weights in Neural Networks

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# Invariances in Deep Learning

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# Symmetries in Deep Learning

Embedding symmetries into architectures leads to better models!



(a) Convolutions embed  
translation equivariance. \*

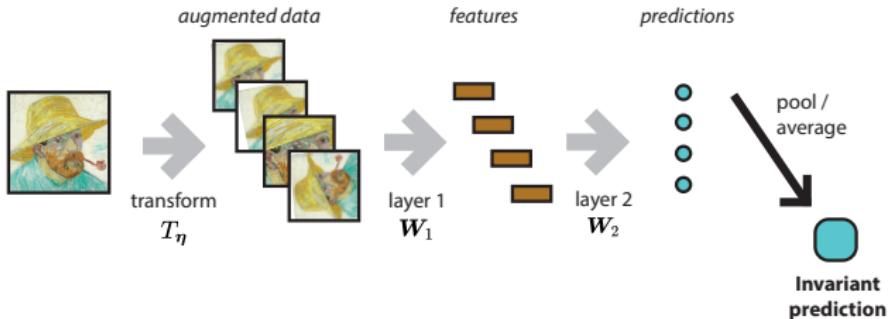
(b) Can be extended to other groups,  
such as rotation.

Symmetries need to be chosen or selected with cross-validation.

Can we *learn* the right invariances with gradients?

\* Animation by: Vincent Dumoulin, Francesco Visin - A guide to convolution arithmetic

# Constructing an invariant neural network



Consider a shallow network

$$g_{\theta}(T(x)) = \sigma(W_2 \circ \phi(W_1 \circ T \circ x))$$

integrated over a set of transformations

$$f_{\theta}(x; \eta) = \int g_{\theta}(T(x)) p_{\eta}(T) dT$$

We can apply transformations to the input or the weights first:

$$W_1 \circ (T \circ x) = (W_1 \circ T) \circ x$$

# Parameterizing invariance

General parameterization of invariance

$$T = \exp \left( \sum_i \epsilon_i \eta_i \mathbf{G}_i \right), \quad \epsilon \sim U[-1, 1]^k$$

use set of affine generators

$\mathbf{G}_1$  : translation x

$\mathbf{G}_2$  : translation y

$\mathbf{G}_3$  : rotation

$\mathbf{G}_4$  : scale x

$\mathbf{G}_5$  : scale y

$\mathbf{G}_6$  : shear

## Stochastic or deterministic sampling

The invariant predictor is described by an integral, which is intractable.

However, we can predict with an approximation from MC samples:

$$\hat{f}_{\theta}(x; \eta) = \frac{1}{S} \sum_{i=1}^S g_{\theta}(T_i(x))$$

to get an unbiased estimate

$$f_{\theta}(x; \eta) = \mathbb{E}_T [\hat{f}_{\theta}(x; \eta)]$$

Normally, we would use cross-validation to learn hyperparameters.

Finding optimal hyper-parameters  $\eta$  with Bayesian model selection

$$p(\theta, \eta | \mathcal{D}) = \frac{p(\mathcal{D}|\theta, \eta)p(\theta|\eta)p(\eta)}{p(\mathcal{D}|\eta)} \quad (\text{Full Bayes})$$

$$\hat{\eta} = \arg \max_{\eta} \int p(\mathcal{D}|\theta, \eta)p(\theta|\eta)d\theta \quad (\text{Empirical Bayes})$$

Well known procedure (Empirical Bayes, Type-II ML).

Used to learning invariances in GPs [van der Wilk; 2018].

# Variational Inference

Marginal likelihood is intractable for neural networks.

We derive a lower bound using multi-sample Jensen's inequality:

$$\log p(\mathcal{D}) \geq \mathbb{E}_{q(\boldsymbol{\theta})} \left[ \mathbb{E}_{\prod_{i=1}^N p_{\boldsymbol{\eta}}(T_i)} \left[ \log p(y | \hat{f}_{\boldsymbol{\eta}}(\mathbf{x}, \boldsymbol{\eta})) \right] \right] - \text{KL}(q(\boldsymbol{\theta} | \boldsymbol{\mu}, \boldsymbol{\Sigma}) || p(\boldsymbol{\theta}))$$

Similar to Nabarro et al., 2022 and Schwöbel et al., 2022.

# Results

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# Learning affine invariances



Figure 1: Visualisation of filter banks trained on rotated CIFAR-10 data.



(a) Trained on regular MNIST.

(b) Trained on rotated MNIST.



(c) Trained on scaled MNIST.

(d) Trained on translated MNIST.

Figure 2: The same model capable of learning affine invariances learns filter banks with different invariances corresponding the data it was trained on.

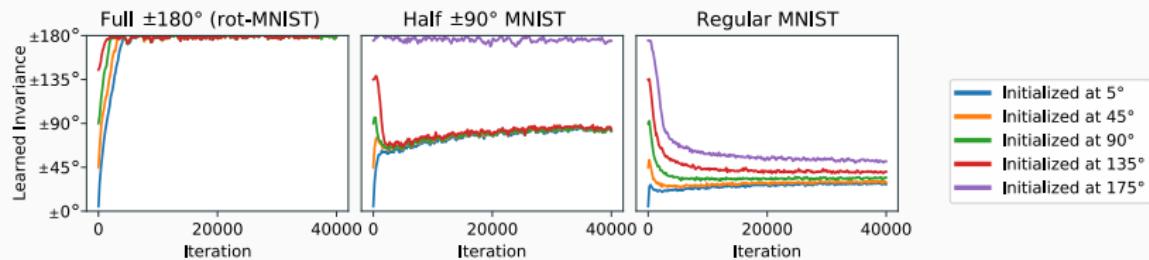
# Learned invariant filter banks

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# Recovering invariances

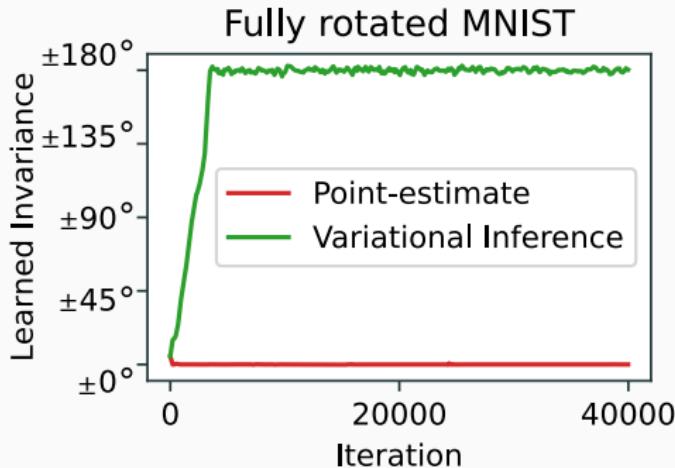
Relaxed invariance is not limited by the 'closure' axiom of groups.

We can learn the right amount of invariance from training data.



# The necessity of the Bayesian approach

The marginal likelihood balances data fit and model complexity.



This proves to be very useful beyond predictive uncertainty.

## Conclusion

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# Conclusion

We can learn invariant weights from data!

*But, only in shallow networks*

Exciting work in progress...

- Scaling the objective to deep networks

*"Invariance Learning in Deep Neural Networks with Differentiable Laplace Approximations",*

*A Immer, TFA van der Ouderaa, V Fortuin, G Rätsch, M van der Wilk (2022)*

- Parameterization of learnable layer-wise equivariance

*"Relaxing Equivariance Constraints with Non-stationary Continuous Filters",*

*TFA van der Ouderaa, M van der Wilk (2022)*

Very happy to engage in discussions on the topic!

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