1. a.
$$A = \begin{bmatrix} 1 & 1 & 1 \\ 1 & 0 & 2 \\ 1 & 8 & -6 \\ 4 & 1 & 7 \end{bmatrix}$$

solve for
$$C_{1}\begin{pmatrix} 1\\ 1\\ 4 \end{pmatrix} + C_{2}\begin{pmatrix} 1\\ 8\\ 1 \end{pmatrix} + C_{3}\begin{pmatrix} 1\\ 2\\ -6\\ 7 \end{pmatrix} = \begin{pmatrix} 0\\ 0\\ 0 \end{pmatrix}$$

$$\Rightarrow \begin{cases} C_{1} + C_{2} + C_{3} = 0\\ C_{1} = -2C_{3} \end{cases} \Rightarrow \Rightarrow C_{2} = C_{3} = -\frac{1}{2}C_{1}$$
and this could solve
$$\begin{cases} C_{1} + 8C_{2} + -6C_{3} = 0\\ 4C_{1} + C_{2} + 7C_{3} = 0 \end{cases}$$

i. Not linearly independent

$$\alpha(\text{trauy}, \quad A \cdot \begin{pmatrix} 2 \\ -1 \\ -1 \end{pmatrix} = \begin{pmatrix} 0 \\ 0 \\ 0 \end{pmatrix}$$

Solve for
$$C_1\begin{bmatrix}1\\4\\4\end{bmatrix} + C_2\begin{bmatrix}0\\8\\1\end{bmatrix} + C_3\begin{bmatrix}1\\2\\0\\2\end{bmatrix} = 0$$
first two equations
$$= C_3 = -\frac{1}{2}C_1$$

plug into the 3rd & 4th equations $\Rightarrow 3C_1 = 0 \Rightarrow C_1 = C_2 = C_3 = 0$

$$\begin{vmatrix} \begin{bmatrix} 2-\lambda & 1 \\ 2 & 4-\lambda \end{vmatrix} \end{vmatrix} = 0$$

$$\Rightarrow \lambda = 3 \pm \sqrt{3}$$

$$\Rightarrow v_1 = C \left(\frac{\sqrt{3} - 1}{2} \right)$$

similarly, for
$$\lambda_1 = 3-\overline{13} \Rightarrow \nu_1 = c \begin{pmatrix} (\overline{13} + 1) \\ 2 \end{pmatrix}$$

linear combination of formal r.v.'s is still normal; what remains to derive is the mean & variance of that normal distribution

$$E \left[3x_1 + x_2 + x_3 \right]$$

$$= 3E[x_1] + E[x_2] + E[x_3] = 0$$

2.b. Define
$$y_1 = {X_1 \choose X_2}$$
, $y_2 = {X_3}$

Then ${Y_1 \choose y_2} \sim N({M_1 \choose M_1}, {\Xi_{11} \subseteq Z_{12} \choose Z_{21} \subseteq Z_{22}})$

where $M_1 = {0 \choose 0}$, $M_2 = {0}$
 $Z_{11} = {2 \choose 0}$, $Z_{12} = {0 \choose 0.5}$, $Z_{21} = Z_{12}^T$, $Z_{22} = {1}$

Using the formula

 $Y_1 \mid Y_2 = b \sim N(M_1 + Z_{12} \cdot Z_{22}^T \mid b - M_2)$, $Z_{11} - Z_{12} \sum_{22}^T \mid Z_{21}$)

with $b = 3$
 $\Rightarrow Y_1 \mid Y_2 = 3 \sim N({0 \choose 1} + {0 \choose 0.5} \mid 1)^T \mid (3) - (0)$,

 $\begin{bmatrix} 2 & 0 \\ 0 & 2 \end{bmatrix} - \begin{bmatrix} 0 & b \\ 0 & 5 \end{bmatrix} \mid 1 \mid 1^T \mid 0.6 \mid 0.5 \mid 0$

$$\begin{array}{rcl}
2.C. & (ov (X_1 + 2X_2, 3X_2 + X_3)) \\
&= (ov (X_1, 3X_2) + (ov (2X_1, 3X_2) + (ov (2X_2, X_3) + (ov (X_1, X_3)) \\
&= 3 \cdot 0 + 6 \cdot 2 + 2 \cdot 0.5 + 0.6
\end{array}$$

$$= 13.6$$

3. Any linear combination of multi-normal v.v.rs is still normal with the mean

$$E[Y] = E[\sum_{i=1}^{k} a_i \times i]$$

$$= \sum_{i=1}^{k} a_i E[x_i]$$

$$= \sum_{i=1}^{k} a_i u_i$$

and variance

=
$$\sum_{i=1}^{k} Var [ai Xi] + \sum_{i=1}^{k} \sum_{j\neq i}^{k} \sum_{j=1}^{k} [ai Xi, aj Xj]$$

$$= \sum_{i=1}^{k} \alpha_i^2 > Var(X_i) + 2\sum_{i=1}^{k} \sum_{j=1}^{k} \sum_{i,j\neq i}^{k} \alpha_i^2 \alpha_j^2 (ov(X_i,X_j))$$

$$\Sigma = \sum_{i=1}^{k} \sum_{j=1,j\neq i}^{k} \alpha_i \alpha_j \sum_{i=1}^{k} \sum_{j=1,j\neq i}^{k} \alpha_i \alpha_j \sum_{j=1,j\neq i}^{k} \alpha_i \alpha_i \alpha_j \sum$$

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4. (a)
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$$E[\hat{\beta}w]$$

$$= E[(X^{T}V^{T}X)^{T}X^{T}V^{T}Y]$$

$$= (X^{T}V^{T}X)^{T}X^{T}V^{T}E[Y]$$

$$= (X^{T}V^{T}X)^{T}X^{T}V^{T}X\beta$$

$$= X\beta + E(\xi)$$

$$= X\beta$$

(b)
$$(ov (\beta w))$$

= $(ov ((X^{T}V^{T}X)^{T}X^{T}V^{T}Y^{T})$
= $(X^{T}V^{T}X)^{T}X^{T}V^{T}$ $(ov (Y) V^{T}X (X^{T}V^{T}X)^{T})$
($(ov (Y) = Var (X\beta + \Sigma) = Var (\Sigma) = 6^{2}V)$
= $(X^{T}V^{T}X)^{T}X^{T}V^{T}(6^{2}V)V^{T}X (X^{T}V^{T}X)^{T}$
= $6^{2} (X^{T}V^{T}X)^{T}$

(c) If & is multi-normal, then we immediately know that $\hat{\beta}_{W} \sim N(\beta, 6^{1}(xTV-1X)T)$ Otherwise, only the mean & variance don't give enough information on the exact distribution of $\hat{\beta}_{W}$

$$Var(yi) = Var(\sum_{i=1}^{mi} xi / mi)$$

$$= (\frac{1}{mi})^2 \sum_{i=1}^{mi} 6^2$$

$$= \frac{6^2}{mi}$$

Therefore the covariance matrix
$$Cov(y) = 6$$
 V

Where $V = \begin{bmatrix} \frac{1}{m_1} & 0 \\ 0 & \frac{1}{m_1} \end{bmatrix}$

In other words

assume the observations are independent Diagonal terms are inverse - weighted by the number of observations as more observations mean more information on that y: => less variable