

## BIOS 667: Longitudinal Data Analysis

### Vectors and Matrices

Matrix notation is used in this class because it provides compact expressions that are easy to read and understand. The approach here is a practical one with very minimal theory involved.

We will only deal with vectors and matrices of real-values. The term *scalar* means one number such as 2.7.

All vectors will be column vectors. A set of real numbers such as  $a_1, \dots, a_n$  can be collected into a vector denoted  $a = (a_1, \dots, a_n)^\top$ . This vector has length  $n$ . The superscript  $^\top$  denotes the transpose. The notation  $(a_1, \dots, a_n)$  represents a row vector, while  $(a_1, \dots, a_n)^\top$  is a column vector.

A special vector is a vector of 1's, denoted  $1_n$  or  $1_{n \times 1}$  or just 1 provided there is no confusion with the scalar 1.

Another special vector is the zero vector, a vector of zeros,  $0_{n \times 1}$ .

Vectors of the same length can be added and subtracted elementwise,  $a = b + c, d = b - c$  mean that  $a_i = b_i + c_i, d_i = b_i - c_i$ , and  $a, b, c$  and  $d$  have the same length.

The *inner product* is an operation on two vectors of the same length  $n$ , defined as  $a^\top b = b^\top a = \sum_{i=1}^n a_i b_i$ . The result is a scalar (one number).

A matrix is a rectangular array of numbers. In matrix  $A$ , the entry in the  $i$ th row and  $j$ th column is  $a_{ij}$ .

A matrix  $A$  with 10 rows and 3 columns is a  $10 \times 3$  matrix. The pair of numbers  $(10, 3)$  is called the *dimension* or *dimensions* of the matrix. The transpose of  $A$  is  $A^\top$  which is a  $3 \times 10$  matrix with  $a_{ji}$  in the  $i$ th row and  $j$ th column;  $i$  goes from 1 to 3 while  $j$  goes from 1 to 10.

If the number of rows equals the number of columns the matrix is called a *square* matrix.

If  $A = A^\top$ , then  $A$  is said to be *symmetric*. Covariance matrices are symmetric.

Matrices of the same dimension can be added and subtracted elementwise,  $A = B + C, D = B - C$  mean that  $a_{ij} = b_{ij} + c_{ij}, d_{ij} = b_{ij} - c_{ij}$ , and  $A, B, C$  and  $D$  must have the same dimension.

The product of matrices  $A$  and  $B$  is denoted  $AB$  and is defined only if the number of columns in  $A$  is equal to the number of rows in  $B$ . If  $A$  is  $m \times n$  and  $B$  is  $n \times p$ , then the product  $C = AB$  is an  $m \times p$  matrix ( $m$  rows and  $p$  columns), and element  $c_{ij}$  in  $C$  is the inner product of the  $i$ th row of  $A$  and the  $j$ th column of  $B$ .

Order of matrix multiplication does not matter,  $ABC = A(BC) = (AB)C$ . Matrix multiplication is not commutative, generally  $AB \neq BA$ .

Note that if  $a_{m \times 1}$  and  $b_{n \times 1}$  are vectors then  $ab^\top$  is an  $m \times n$  matrix.

A special square matrix is the identity matrix, usually denoted  $I_{n \times n}$ ,  $I_n$  or just  $I$  if there is no

confusion about its dimension.

Another special matrix is a matrix of 1's, usually denoted  $J_{m \times n}$  and it can be represented by  $1_m 1_n^\top$ . Since  $J$  need not be square the notation  $J_n$  should be avoided.

If there is no linear dependence among the columns (or rows) of an  $n \times n$  matrix  $A$ , we say that  $A$  is nonsingular.

If  $A$  and  $B$  are  $n \times n$  matrices and  $AB = BA = I$ , we say that  $B$  is the inverse of  $A$  and express that by  $B = A^{-1}$ . The inverse exists only if  $A$  is nonsingular. The inverse is unique (when it exists).

Exercises:

Let  $a = (1, 2, 3, 4, 5, 6)^\top$ ,  $b = (2, -1, 4, -3, 6, -5)^\top$ .

Compute  $a^\top a, b^\top b, a^\top b, a 1_4^\top, 1^\top a, 1^\top (a a^\top) 1, J_{4 \times 6} a$ .

What is the inverse of  $A^{-1}$ ?

Random vectors and matrices are vectors and matrices whose elements are random variables. For example,  $Y = (Y_1, Y_2, Y_3, Y_4)^\top$  is a random vector. Its mean is  $E[Y] = (\mu_1, \mu_2, \mu_3, \mu_4)^\top$ . With multivariate observations  $Y_1, \dots, Y_n$ , each  $Y_i$  is itself a vector. In the TLC study each  $Y_i$  is a  $4 \times 1$  vector. The sample mean vector, as a random vector, is  $\bar{Y}$ , and its realized (observed) value is  $\bar{y}$ . The sample covariance matrix  $S$  is a  $4 \times 4$  matrix, and its realized value is  $s$ . Note that in the univariate case the common notation is different,  $S^2$  and  $s^2$ .

If the random vector  $Y_{n \times 1}$  has mean vector  $\mu_{n \times 1} = E[Y]$  and covariance matrix  $\Sigma_{n \times n} = \text{cov}(Y)$ , and  $A_{m \times n}$  is a matrix, then  $E[AY] = A\mu$  and  $\text{cov}(AY) = A\Sigma A^\top$ . It follows that if  $a$  is an  $n \times 1$  vector then the linear combination  $a^\top Y$  is a scalar random variable with mean  $E[a^\top Y] = a^\top \mu$  and variance  $\text{var}(a^\top Y) = a^\top \Sigma a$ .

Expressions of the type  $a^\top B a$  where  $B$  is a matrix are called *quadratic forms*. Examples include sums of squares in ANOVA and regression and many test statistics.

A square matrix  $A_{n \times n}$  is said to be *positive definite* if  $x^\top A x > 0$  for all non-zero vectors  $x$  (of length  $n$ ). If  $A$  is the covariance matrix of a random vector  $Y$ , positive definiteness of  $A$  guarantees that all non-zero linear combinations  $a^\top Y$  have strictly positive variance, i.e.  $\text{var}(a^\top Y)$  can't be negative and can't be zero unless  $a = 0$ .

A square matrix  $A_{n \times n}$  is said to be *positive semidefinite* if  $x^\top A x \geq 0$  for all non-zero vectors  $x$ .

If  $\Sigma$  is a positive definite  $n \times n$  covariance matrix, there exists a unique lower-triangular matrix  $L$  with positive diagonal elements such that  $\Sigma = LL^\top$ . Matrix  $L$  is known as the Choleski root of  $\Sigma$ . The Cholesky root of  $A$  can be computed by "chol(A)" in both SAS/IML and R.