

x1	x2	$\theta$	w1	w2	$f(\cdot)$
0	0	0	0.5	0.5	$G(z-T)$
0	1	0	0.5	0.5	$G(z-T)$
1	0	0	0.5	0.5	$G(z-T)$
1	1	0	0.5	0.5	$G(z-T)$
$z=w_1x_1+w_2x_2+\theta$			Output $y=G(z)$		A AND B
$0*0.5+0*0.5 = 0$			0		0
$0*0.5+1*0.5 = 0.5$			0		0
$1*0.5+0*0.5 = 0.5$			0		0
$1*0.5+1*0.5 = 1$			1		1

$$T = 1$$

$$g(z-T) = \begin{cases} 1 & , \quad z \geq T \\ 0 & , \quad z < T \end{cases}$$