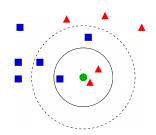


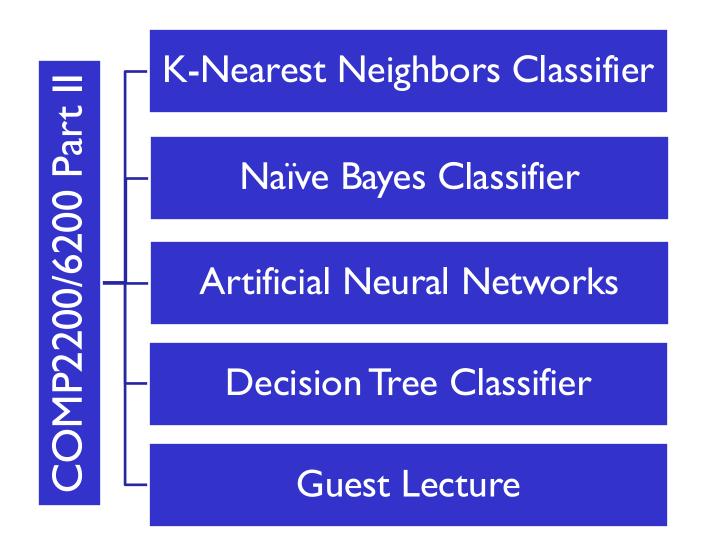
DATA SCIENCE COMP2200/6200

08 – K-Nearest Neighbors Classifier



Part II Scheduling





Lecture Outline



Machine Learning for Data Science

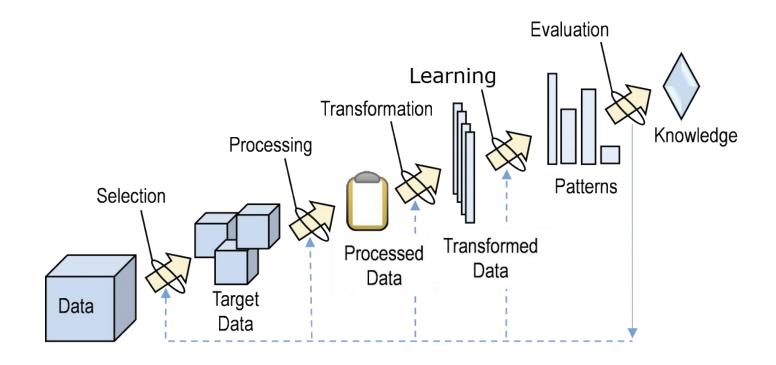
K-Nearest Neighbors Classifier

Model Selection

Data Mining and ML



- ❖ Data Mining ≈ Database + Machine Learning
 - Database: data management and pre-processing
 - Machine learning: data analysis & knowledge discovery



What is Learning?



- Given
 - Task T
 - **Performance** *P* of a computer program on task *T*
 - Experience E
- * If a computer program gains performance improvement on T by leveraging experience E, it can be said that the computer program learns from E with respect to T and P. [Mitchell, 1997]
- Experience is often embedded in the form of data
- Compared to no learning

Learning Example



- Task: predict if loan requests can be approved or not
- Performance: accuracy
- No learning: to randomly approve a future request
 - Accuracy (expectation): 50% (training accuracy)
- Experience (data): loan application data

ID	Age	Has_job	Own_house	Approved
1	young	yes	no	yes
2	middle	yes	yes	yes
3	old	no	yes	no

- * A simple learning: approve a future request with 'yes'
 - Accuracy: 66.7% (training accuracy) > 50%

What Is Machine Learning?

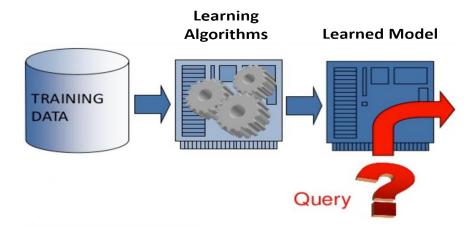


- A subset of artificial intelligence in the field of computer science
 - Gives computers the ability to "learn" (i.e., progressively improve performance on a specific task) with data
 - Without being explicitly programmed
- Ingredients
 - Model: to represent the form of learning result
 - Learning algorithm: how to generate a model from data
 - Data: input to ML algorithms
- Aims
 - to predict unseen data or to interpret existing data

Two Stages of Machine Learning



- Training stage
 - Training: to generate a model from observed data
- Testing stage
 - Testing: to use the learned model to predict unseen data



E.g., does a patient with coughing, running nose and fever suffer from COVID-19 or flu?

Data



- **Data set** D: a set of observed data instances
 - $D = \{d_1, d_2, \cdots, d_{|D|}\}$
 - Many types: numerical vectors, an image, a graph, ...
 - Assumption: i.i.d. (independent & identical distributed)
 - Instances in D follow a (unknown) distribution, from which each instance is independently sampled
- Training data: data used in the training stage
- Testing data: data used in the testing stage
- Validation data: used to select learning models
 - Part of training data

Data (Cont'd)

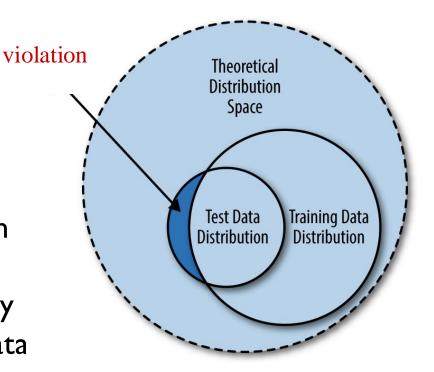


Assumption: the distribution of training examples is identical to the distribution of test examples (including future unseen examples)

 In practice, this is often violated to certain degree

 Strong violations will clearly result in poor performance

 To achieve good accuracy on the test data, training examples must be sufficiently representative of the test data



Data (Cont'd)

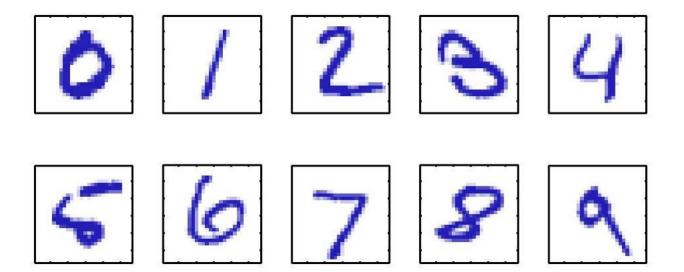


- Label/target of data
 - The interesting attribute(s) for prediction
 - Further, $d_i \equiv \langle x_i, y_i \rangle$
 - Supervised learning models
 - o Regression: y is continuous
 - Classification: y is discrete (binary or multi-class)
- No explicit label/target information
 - Then, $d_i \equiv \langle x_i, \cdot \rangle$
 - Unsupervised learning models
 - Clustering
- Semi-supervised learning (labeling is often costly)

Data Examples



- MINST data: handwritten digit recognition
 - http://yann.lecun.com/exdb/mnist/



Data Examples (Cont'd)

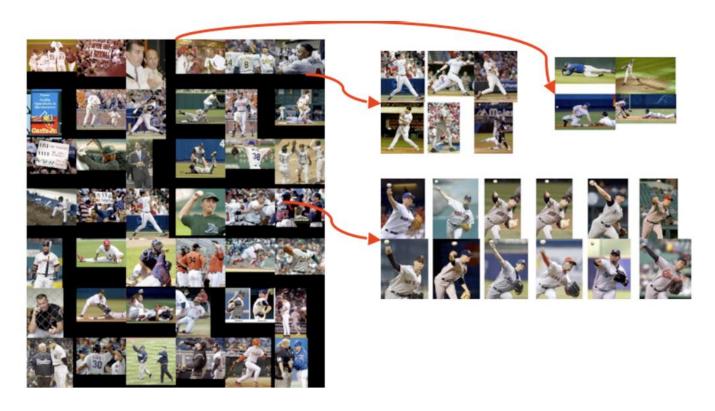


- **Represent input image as a vector** $x_i \in \mathbb{R}^{784}$
 - Feature extraction, a pre-processing step

- Label/target vector t_i
 - $t_i \in \{0,1\}^{10}$, a discrete, finite label set
 - $t_i = (0,0,1,0,0,0,0,0,0)$
- **Learning model** $y: \mathbb{R}^{784} \to \mathbb{R}^{10}$
 - Dataset: $\mathcal{D} = \{\langle x_1, t_1 \rangle, \cdots, \langle x_N, t_N \rangle\}$
 - Supervised learning
 - Classification problem

Data Examples (Cont'd)





- Finding similar images, image clustering, etc.
 - Unsupervised learning
 - Only $\mathcal{D} = \{x_i\}$ is available, no label information

Model



- * Model: a map from input space to output space
 - i.e., $f: \mathcal{X} \to \mathcal{Y}$
 - An infinite number of such maps
 - Input space: space spanned by feature attributes
 - Output space: space spanned by label/target attributes
- ❖ Hypothesis space H: space of all possible maps
 - Functional space: $\mathcal{H} \equiv \{f \mid \mathcal{X} \to \mathcal{Y}\}$
- Ground truth: underlying true mechanisms of generating the observed data
 - But never known in reality
 - The purpose of learning: to approximate the ground truth

Parameter Space



- What do we really learn from data for a model?
 - Hypothesis space is usually pre-specified in terms of problem domains
 - Different models are determined by parameters
 - Let θ denote the parameter vector, we have

$$\mathcal{H} \equiv \{ f \mid y = f_{\theta}(x) \}$$

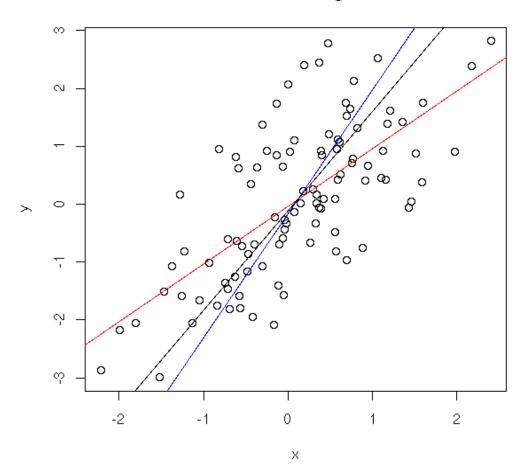
- Parameter space
 - Can be real value spaces, e.g., \mathbb{R}^n
 - Structure of a model (more implicit), e.g., tree or graph structures, as well as partitions of the input space

Parameter Space (Cont'd)



• E.g., linear regression models $y = w_0 + w_1 x$

three "regressions"



Lecture Outline



Machine Learning for Data Science

K-Nearest Neighbors Classifier

Nearest Neighbors Classification



- Idea: instance-based learning
 - Similar examples have similar labels
 - Classify new examples like similar training examples

Algorithm

- Given some new example x for which we need to predict its class y
- Find the most similar training examples
- Classify x "like" these most similar examples

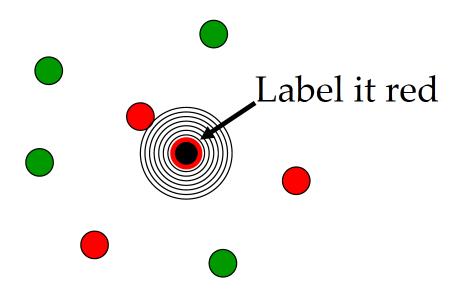
Questions:

- How to determine similarity?
- How many similar training examples to consider?

1-Nearest Neighbor



- One of the simplest classifiers
- Basic idea: label a new point the same as the closest known data instance
- ❖ E.g.,



1-Nearest Neighbor (Cont'd)

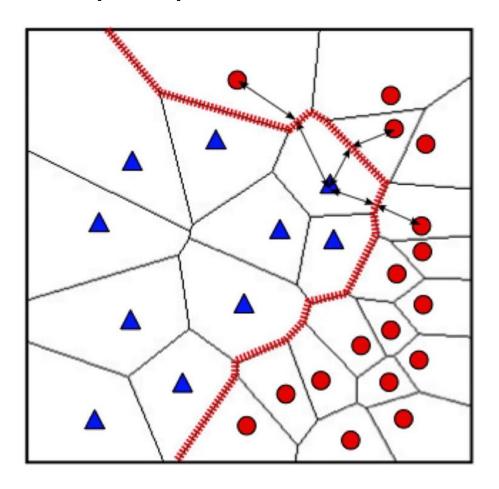


- A distance metric (to measure similarity)
 - Euclidean distance is commonly-used
 - When different units are used for each dimension
 - Standardization can apply
 - For categorical data, we can use hamming distance 0 $d(x_1, x_2) = \text{number of features on which } x_1 \text{ and } x_2 \text{ differ}$
 - Others (e.g., cosine, Manhattan)
- How many nearby neighbors to look at?
 - Only one
- How to fit with training data instances?
 - Just predict the same output as the nearest neighbor

1-Nearest Neighbor (Cont'd)



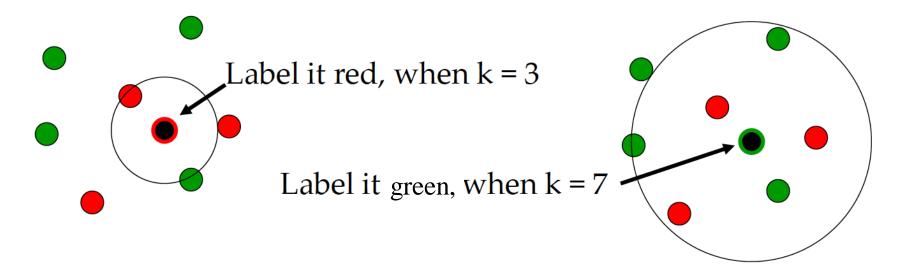
The resultant space partition is a voronoi diagram



K-Nearest Neighbor



- Generalizes 1 NN to smooth away noise in the labels
- ❖ A new data instance is now assigned the most frequent label of its k nearest neighbors
- E.g., k = 3, and k = 7



KNN Example



Training data

	Food	Chat	Fast	Price	Bar	BigTip
	(3)	(2)	(2)	(3)	(2)	
1	great	yes	yes	normal	no	yes
2	great	no	yes	normal	no	yes
3	mediocre	yes	no	high	no	no
4	great	yes	yes	normal	yes	yes

- Similarity metric: # of matching attributes (k = 2)
- New examples
 - Example 1 (great, no, no, normal, no)?
 - Example 2 (mediocre, yes, no, normal, no)?

KNN Example (Cont'd)



Pairwise similarity

Index	Instance 1	Instance 2	Instance 3	Instance 4
Example 1	3	4	2	1
Example 2	3	2	4	2

• Prediction (k = 2)

- Example 1 (great, no, no, normal, no)? 'yes'
 - \circ Most similar: instance 2 (1 mismatch, 4 match) \rightarrow yes
 - \circ 2nd most similar: instance 1 (2 mismatch, 3 match) \rightarrow yes
- Example 2 (mediocre, yes, no, normal, no)? 'yes'/'no'
 - o Most similar: instance 3 (1 mismatch, 4 match) \rightarrow no
 - \circ 2nd most similar: instance 1 (2 mismatch, 3 match) \rightarrow yes

KNN Limitations



- \bullet Each prediction takes O(n) computational complexity
 - Use fancy data structures such as KD-trees to accelerate the search of nearest neighbours
 - Or use locality-sensitive hashing to approximate nearest neighbours with constant computational complexity
- Prediction performance degrades when number of attributes grows
 - Curse of dimensionality: when the number of attributes is big, similarity/distance measures become less reliable
 - Remedy
 - Remove irrelevant attributes in pre-processing
 - Weight attributes differently

Lecture Outline



Machine Learning for Data Science

* K-Nearest Neighbors Classifier

Model Selection

How to Choose *K*?



- \bullet Question: can we learn K from training data?
 - No! K is a hyperparameter, rather than a model parameter
 - Then, what has been learned in KNN classifier?
 - A partition of the input space
- Usually, K should be determined by model users
 - Different K will produce different classifiers
 - Then, how to choose a value for K?

* Model Selection

- Multiple models generated by different algorithm parameter configurations
- Multiple models generated by different learning algorithms

Model Complexity



Model complexity

- Very generally, it refers to the number of degrees of freedom in a learned model
- Often measured as the number of adjustable weights or parameters in the architecture, e.g., weights in regression
- High complexity → stronger capability of capturing information from training data

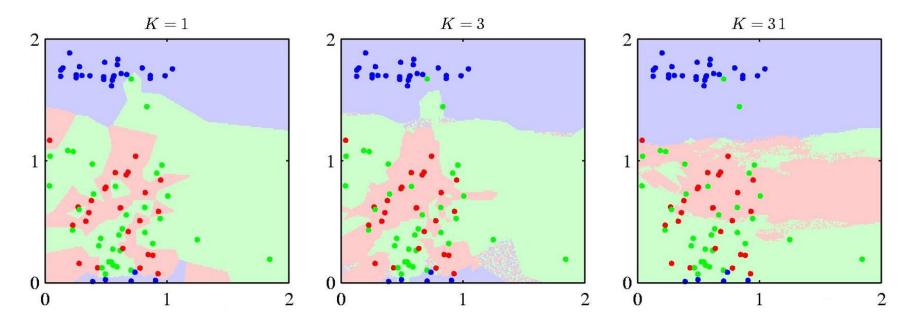
KNN classifier's complexity?

- No explicit model parameters
- Actually, the decision boundary formed from the input space partition is relevant to the model complexity
- The smoother the boundary is, the complexity is lower

Model Complexity (Cont'd)



* K acts as a smoother and controls model complexity



- $\star K = 1$ leads to the roughest decision boundaries
 - As 1-NN classifier has the highest complexity, can we just simply select this model as the best for model selection?

Training/Testing Errors



* Training error (or empirical error) of a trained model \hat{f} on a training data set of size N

$$E_{emp}(\hat{f}) = \frac{1}{N} \sum_{i=1}^{N} L(y_i, \hat{f}(x_i))$$

- Note that the loss function $L(\cdot,\cdot)$ requires instantiation for a specific model, e.g., the squared error in linear regression
- ❖ Testing error on a test data set with size N'

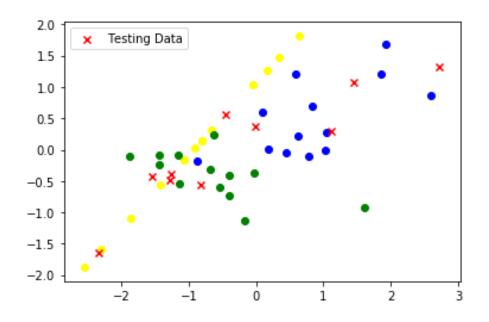
$$E_{test}(\hat{f}) = \frac{1}{N'} \sum_{i=1}^{N'} L(y_i, \hat{f}(x_i))$$

Indicating the generalisation capability of a learned model

Training/Testing Errors (Cont'd)



- Empirical study on KNN classifiers
 - 40 points for training, 10 points for testing
 - 3 classes
 - *Error* is calculated by 1.0 *accuracy*



Training/Testing Errors (Cont'd)



Observations

- Training error keeps going up when K increases
 - \circ 0 when K=1
- Testing error does not take lowest value at K=1



- \circ Testing error is minimized around K=9
- \bullet So, a paradox for K = 1 case! Why?
 - Overfitting: a model is too strong and captures the very details of training samples, lacking generalization capability
 - Data is noisy, and the model is fitted to noise
 - o Fighting against overfitting is important in machine learning!

Training/Testing Errors (Cont'd)



Observations

- Both errors are maximized when K = 40
 - All testing sample will be predicted as the same label. Why?



- This is the underfitting issue
 - It's easy to address by just increasing model complexity
- Insights
 - Model selection is a non-trivial job!
 - We need to use testing error as performance indicator to guide model selection for the generalization capability

How to select *K*?



- ❖ Increase K
 - Make KNN classifier less sensitive to noise
 - Avoid overfitting
- ❖ Decrease K
 - Allow capturing finer structure of space
 - Avoid underfitting
- Pick K not too large, but not too small
 - Data-specific
 - This is model selection by hyperparameter tuning
 - Cross validation can be used to find a suitable K
 - Theoretically, this is related to bias-variance tradeoff

How to Estimate Testing Error?



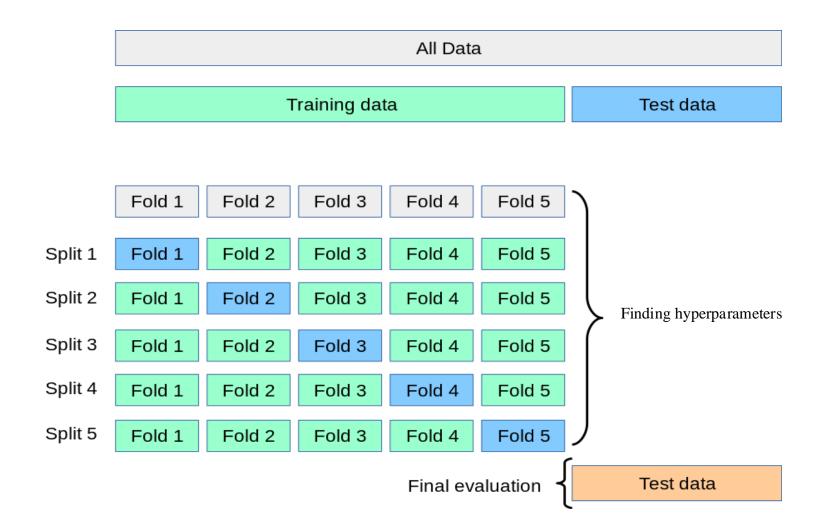
- Option 1: randomly divide the available set of samples into two parts: training data and validating data
 - Randomness will not give a robust testing error estimation
 - Wasting of data: the training data fail to contribute testing error while the validating data fail to contribute to training
 - We hope all data instances contribute to better model training and more robust testing error estimation

Option 2: k-fold cross validation

- Randomly partition data into k subsets (k is usually 5, 10)
- In each round, leave a subset out as the validating data
- Combined results from multiple rounds are reported as the robust testing error estimation

k-fold Cross Validation





Automatic Tuning



- Challenges in hyperparameter turning
 - Many hyperparameters are continuous
 - \circ E.g., complexity parameter α in Ridge regression
 - Search space is continuous
 - Need to tuning multiple hyperparameters simultaneously
- Automation strategies
 - Grid search
 - Exhaustive search over specified parameter values
 - Random search
 - A fixed number of parameter settings is sampled from the specified distributions

Summary



- Learning and machine learning
- Data, model, and parameter spaces
- Supervised learning vs unsupervised learning
- K-NN classifier
- Model selection and model complexity
- Training/testing error
- k-fold cross validation
- Automatic hyperparameter tuning