

Return Oriented Programming on an Embedded System Using Code Injection

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Abstract—This paper describes the process of implementing a code injection attack on an ARM Cortex M4 through Return Oriented Programming. The paper will describe the process of selecting useful snippets of code found in the ROM of microcontroller. The paper will end by showing the injected program working on the microcontroller.

Index Terms—Return Oriented Programming (ROP), stack overflow, security, embedded system, canary.

I. INTRODUCTION

Every year, the amount of devices with embedded systems greatly increases. With the demand that every device connect to the internet (Internet of Things), in the near future almost all devices will have an embedded system. That being said, generally these embedded devices are not manufactured with security as the top priority.

Buffer overflow attacks have been widely demonstrated and used to allow a hacker to gain control over a system or program. Most of the buffer overflow techniques on x86-64 architectures have been well researched and defended against. However, this is not the case for embedded systems. Using more advanced buffer overflow techniques such as Return Oriented Programming (ROP), an attacker is able to utilize the manufacture's driver libraries and boot code found on the ROM to take over an embedded device. This vulnerability will become more threatening when most common, household items have embedded devices such as microcontrollers.

II. VULNERABILITY OVERVIEW

A. Overview of ROP

As stack based, buffer overflow attacks became more common, programmers and researchers came up with methods to defend against these attacks. A simple method of defense is to prohibit a section of memory to be both wrote to and executed from. If an attacker was able to accomplish a buffer overflow, the attacker would not be able to return and execute the malicious code on the stack. In response to this defense, attackers came up with ways to use the code already found on most systems, e.g. libraries such as libc. One of these more advanced methods of attack is Return Oriented Programming (ROP).

ROP allows the attacker to gain control flow over a program by using useful snippets of code found in drivers and/or libraries called "gadgets". After execution, each gadget needs

to end with a return command. The return command allows the attacker to return to another gadget or eventually to a malicious program.

In the case of an ARM architecture, there are no "return" commands so branches and pop instructions can be used instead to achieve the same result [1].

B. Buffer Overflow

The vulnerable function that will be exploited to allow a buffer overflow is the following:

```
void echo(void) {  
  
    char buffer[32];  
  
    UARTgets(buffer, sizeof(buffer));  
  
    UARTprintf("%s \n", buffer);  
  
}
```

The UARTgets() and UARTprintf() functions are provided from the TivaWare libraries from TI. In order to be able to overflow the character buffer of size 32, we had to remove the bounds checking done in the UARTgets() function. It is worth noting that for certain user-input obtaining functions, the function stops getting the input when it encounters the null character 0x00. This is not the case for UARTgets(), making the ROP attack easier to develop. The malicious code will be inserted onto the stack as the character buffer is overflowed.

C. Overcoming Canary Stack Protection

Another defense used to stop buffer overflow attacks is the use of a canary. The main objective of a buffer overflow is to overwrite the functions return address. A canary is placed in between the buffer and the return address. Before the program returns from the return address, it checks to see if the canary has been modified. If it has, it throws an exception and program execution is halted.

The IDE being used to program the echo() program onto the microcontroller is Keil uVision. In Keil, there are options available to turn on stack protection. For stack protection in kill, the canaries are defined by the programmers. A randomly generated canary is the best choice for increased security. However since the generation of random canaries

takes a toll on the overall performance of the microcontroller, often times a static canary is used. A common canary that is used is a 32-bit word containing nulls, e.g. 0x00000000 [2]. The authors chose to use the null canary and a later section in this paper will explain how the canary was overcome.

III. CODE INJECTION

In order to inject the attackers code, the microcontroller's flash memory needs to be erased and then reprogrammed. The microcontroller that will be used is the TM4C123G, more specifically, the Tiva C LaunchPad from Texas Instruments. The TM4C123G has a ARM Cortex M4 architecture that uses the Thumb-2 instruction set.

In order to erase the flash, the following must be performed:

- 1) Write the flash key and MERASE bit to the FMC register
- 2) Wait for flash erase routine to finish

In order to reprogram the flash, the following must be performed:

- 1) Write data to the FWBn registers
- 2) Write the start address of program into the FMA register
- 3) Write the flash key and WRBUF bit to the FMC2 register
- 4) Wait for flash write routine to finish

IV. GADGET SELECTION

V. IMPLEMENTATION

VI. RESULTS

A. Problems Encountered

VII. CONCLUSION

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